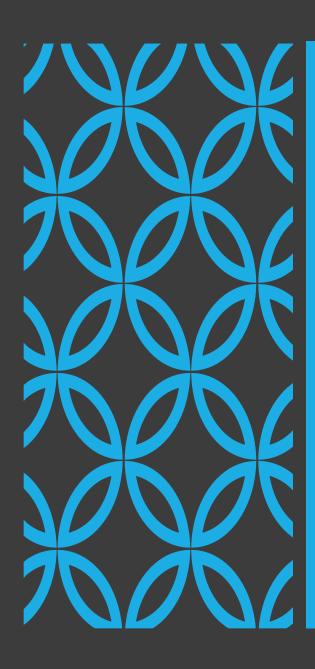
# UNIT 1 ARTIFICIAL INTELLIGENCE

Introduction



### DISCLAIMER

Some contents in this presentation are retrieved from the following original sources:

- 1. Washington State University: Artificial Intelligence Course
- 2. Introduction to Articial Intelligence by Prof. Bojana Dalbelo Basic and Assoc. Prof. Jan Snajder, University of Zagreb, Faculty of Electrical Engineering and Computing
- 3. <a href="https://www.educba.com/intelligent-agents/">https://www.educba.com/intelligent-agents/</a>
- ,

https://www.geeksforgeeks.org/artificial-intelligence-an-introduction/

## WHY STUDY AI?

Turning theory into working programs forces us to work out the details

AI yields good results for Computer Science

AI yields good results for other fields

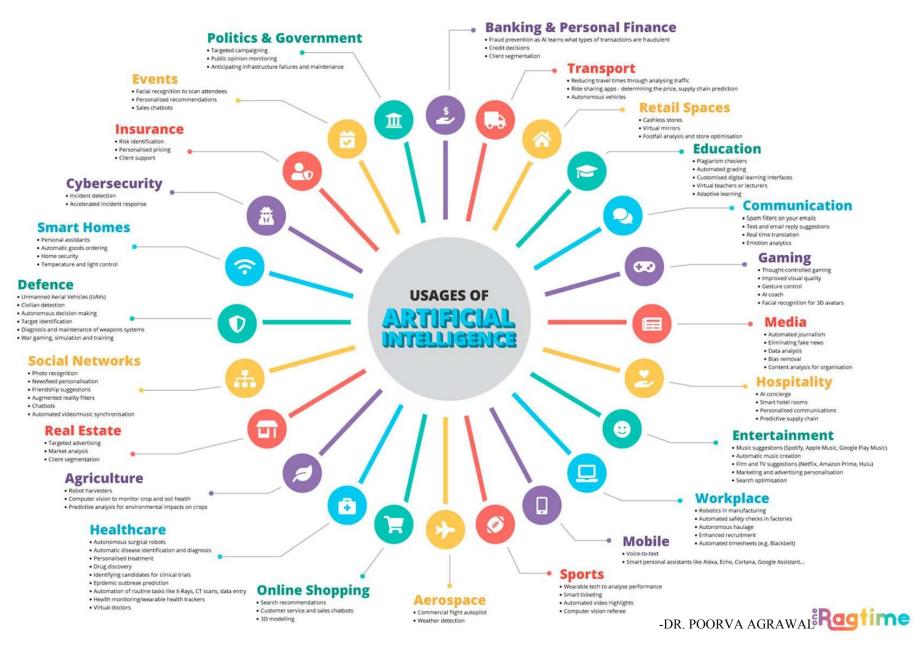
Computers make good experimental subjects

Personal motivation: mystery



A survey states that there is a huge possibility that AI is going to create about **58 million jobs by 2022.** 

### APPLICATIONS OF AI





### INTELLIGENT CAPABILITIES

Problem solving: Search, Adversarial search, Optimization

Knowledge management: Knowledge retrieval and extraction, Knowledge representation, Filtering

Reasoning: Logical reasoning, Uncertain reasoning

Interaction: Human-computer interaction, Real world interaction

## COMPONENTS OF INTELLIGENCE

Intelligence is an intangible entity that is composed of:

Reasoning
Learning
Problem solving
Perception
Linguistic Intelligence
Learning

Perception

Learning

Perception

Learning

Perception

Problem Solving

### HISTORY OF AI

A.I. TIMELINE











1950

#### **TURING TEST**

Computer scientist Alan Turing proposes a test for machine intelligence. If a machine can trick humans into thinking it is human, then it has intelligence

1955

#### A.I. BORN

Term 'artificial intelligence' is coined by computer scientist, John McCarthy to describe "the science and engineering of making intelligent machines"

1961

#### UNIMATE

First industrial robot. Unimate, goes to work at GM replacing humans on the assembly line

1964

#### ELIZA

Pioneering chatbot developed by Joseph Weizenbaum at MIT holds conversations with humans

1966

#### SHAKEY

The 'first electronic person' from Stanford, Shakey is a generalpurpose mobile robot that reasons about its own actions

A.I.

#### WINTER

Many false starts and dead-ends leave A.I. out in the cold

1997

#### DEEP BLUE

Deep Blue, a chessplaying computer from IBM defeats world chess emotionally intelligent champion Garry Kasparov

1998

#### KISMET

Cynthia Breazeal at MIT introduces KISmet, an robot insofar as it detects and responds to people's feelings



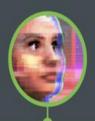














1999

#### AIBO

Sony launches first consumer robot pet dog autonomous robotic AiBO (Al robot) with skills and personality that develop over time

2002

#### ROOMBA

First mass produced vacuum cleaner from iRobot learns to navigate interface, into the and clean homes

2011

Apple integrates Siri, an intelligent virtual assistant with a voice iPhone 4S

2011

#### WATSON

IBM's question answering computer Watson wins first place on popular \$1M prize television quiz show Jeopardy

2014

Eugene Goostman, a chatbot passes the Turing Test with a third of judges believing Eugene is human

2014

#### ALEXA

Amazon launches Alexa, Microsoft's chatbot Tay an intelligent virtual assistant with a voice interface that completes inflammatory and shopping tasks

2016

#### TAY

goes roque on social media making offensive racist comments

-DR. POORVA AGRAWsAle positions

2017

#### ALPHAGO

Google's A.I. AlphaGo beats world champion Ke Jie in the complex board game of Go, notable for its vast number (2170) of

What do you think?

	Systems that think rationally
Systems that act like humans	Systems that act rationally

#### Bellman,

"[The automation of] activities that we associate with human thinking, activities such as decision making, problem solving, learning"

#### Haugeland,

The exciting new effort to make computers think *machines with minds*, in the full and literal sense"

#### Schalkoff, 1990

"A field of study that seeks to explain and emulate intelligent behavior in terms of computational processes"

## Luger & Stubblefield, 1993

"The branch of computer science that is concerned with the automation of intelligent behavior"

#### **Dean et al., 1995**

"A field of study that seeks to explain and emulate intelligent behavior in terms of computational processes"

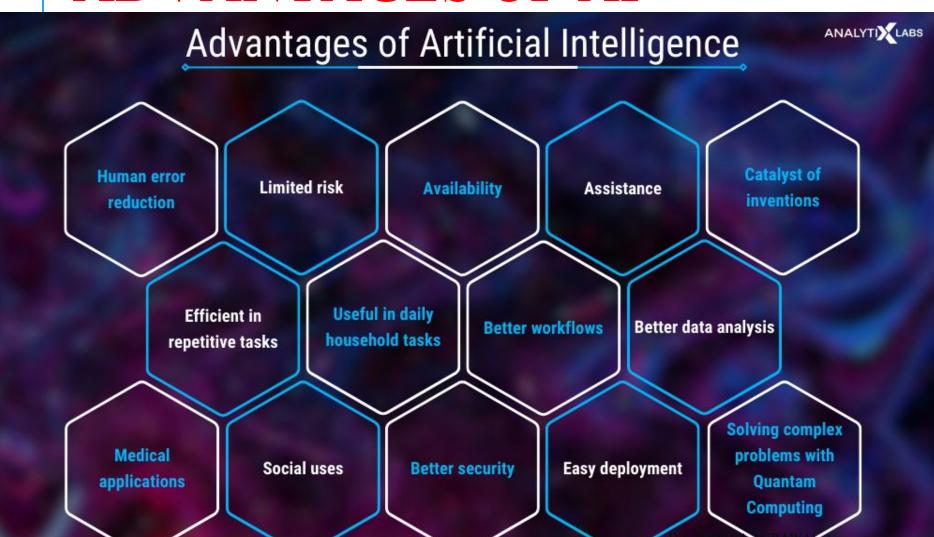
#### Nilsson, 1998

"Many human mental activities such as writing computer programs, doing mathematics, engaging in common sense reasoning, understanding language, and even driving an automobile, are said to demand intelligence. We might say that [these systems] exhibit artificial intelligence"

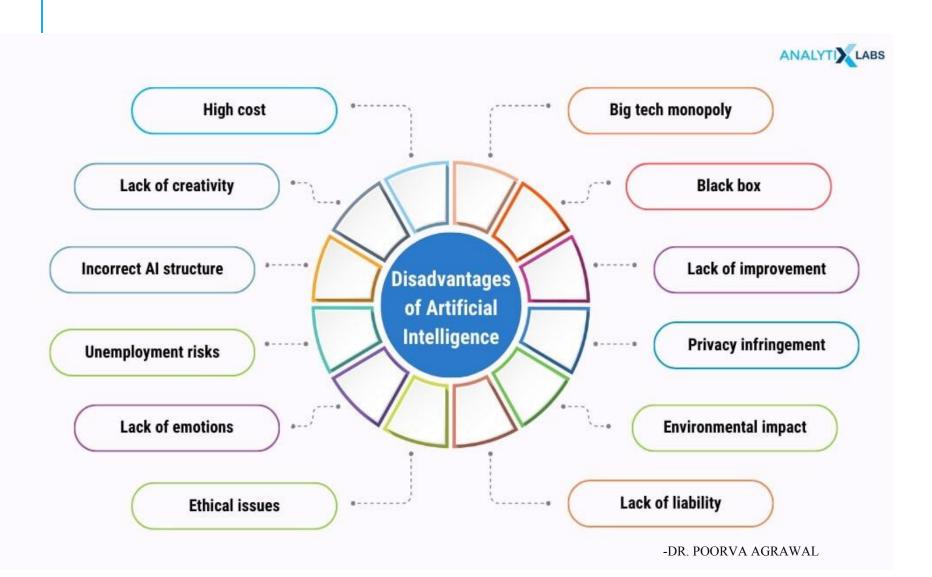
### NITI Aayog, 2015

AI refers to the ability of machines to perform cognitive tasks like thinking, perceiving, learning, problem solving and decision making.

### ADVANTAGES OF AI



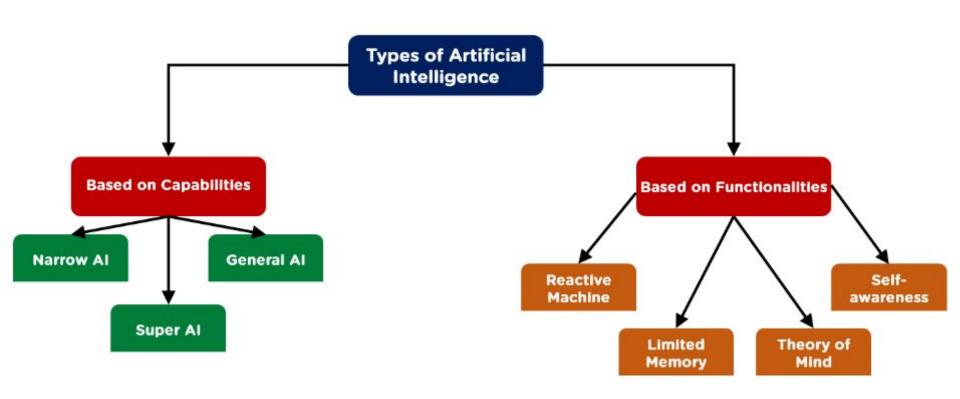
### DISADVANTAGES OF AI



### GOALS OF AI



### TYPES OF AI



## BASED ON CAPABILITIES

Types of AI

Weak AI- which has a narrow range of abilities

General AI- which is on par with human capabilities;

Strong AI-which is more capable than a human.

## BASED ON FUNCTIONALITIES

**Reactive Machines -** AI systems that has no memory and are task specific.

**Limited Memory -** ability to look into the past and improve over time.

**Theory of Mind -** a term from psychology that describes an individual's capacity for empathy and understanding of others

**Self- Awaren**ess- It is hypothetical type of AI that form representations of themselves and perceive their own emotions and menta state.

### APPROACH 1: ACTING HUMANLY

Turing test: ultimate test for acting humanly

Computer and human both interrogated by judge

Computer passes test if judge can't tell the

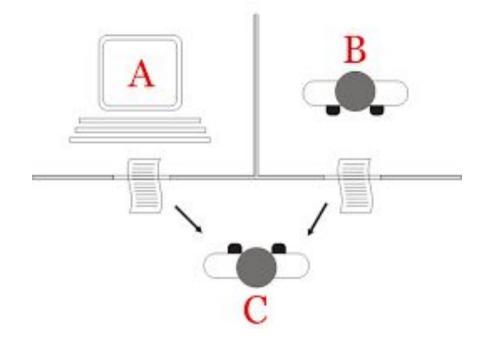
difference

**Natural Language Processing:** The machine needs this to communicate with the interrogator.

**Knowledge Representation:** The machine needs to store the information provided before the interrogation.

**Reasoning:** It's important for the machine to understand how to interpret the information that gets stored..

**Machine Learning:** This is needed so that the machine can adapt to new conditions in real time.



## APPROACH 2: THINKING HUMANLY

Requires knowledge of brain function

What level of abstraction?

How can we validate this

This is the focus of Cognitive Science

## APPROACH 3: THINKING RATIONALLY

Aristotle attempted this

What are correct arguments or thought processes?

Provided foundation of much of AI

Not all intelligent behavior controlled by logic

What is our goal? What is the purpose of thinking?

## APPROACH 4: ACTING RATIONALLY

Act to achieve goals, given set of beliefs

Rational behavior is doing the "right thing"

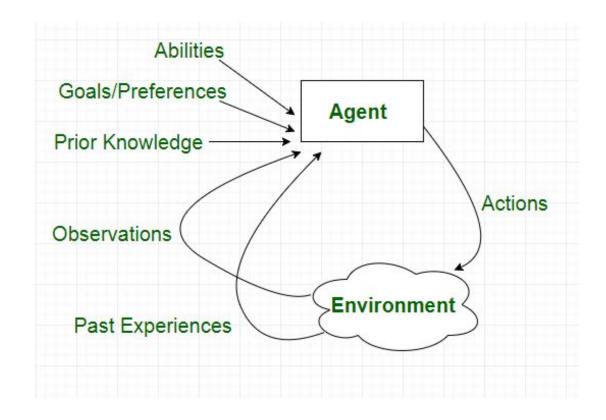
☐ Thing which expects to maximize goal achievement

This is approach adopted by Russell & Norvig

#### RATIONA LITY

A rational agent does the right thing (what is this?)

A fixed performance measure evaluates the sequence of observed action effects on the environment



Source: https://www.geeksforgeeks.org/agents-artificial-intelligence/?ref=gcse

### **PEAS**

Use PEAS to describe task environment

- ☐ Performance measure
- Environment
- Actuators
- Sensors

#### Example: Autonomous driving

- Performance measure: safe, fast, comfortable (maximize profits)
- ☐ Environment: roads, other traffic, pedestrians, customers
- Actuators: steering, accelerator, brake, signal, horn
- ☐ Sensors: cameras, sonar, speedometer, GPS, odometer, accelerometer, engine sensors



### ENVIRON MENT PROPERT IES

Fully observable vs. partially observable

Deterministic vs. stochastic / strategic

Episodic vs. sequential

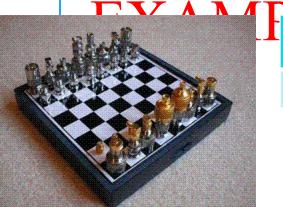
Static vs. dynamic

Discrete vs. continuous

Single agent vs. multiagent

	si.	ell.		
2				
1	44		16	5
	**	*4		
	X			
		Y	4	

Environment	Determi nistic	Episodic	Stati c	Discrete	Agents
Chess with a clock					
Chess without a clock					



	Obser vable		Episodic	Stati c	Discrete	Agents
Chess with a clock	Fully	Strategic	Sequential	Semi	Discrete	Multi

<u> </u>	Environment		Determi nistic	Episodic	Stati c	Discrete	Agents
	Chess with a clock	Fully	Strategic	Sequential	Semi	Discrete	Multi
	Poker						

1	Environment	Obser vable	Determi nistic	Episodic	Stati c	Discrete	Agents
	Chess with a clock	Fully	Strategic	Sequential	Semi	Discrete	Multi
	Chess without a clock	Fully	Strategic	Sequential	Static	Discrete	Multi
	Poker	Partial	Strategic	Sequential	Static	Discrete	Multi

Taxi driving

EXAMI	Environment	Obser vable	Determi nistic	Episodic	Stati c	Discrete	Agent
	Chess with a clock	Fully	Strategic	Sequential	Semi	Discrete	Multi
	Chess without a clock	Fully	Strategic	Sequential	Static	Discrete	Multi
6	Poker	Partial	Strategic	Sequential	Static	Discrete	Multi

Partial

Stochasti

c

Dyna

mic

Continu

ous

Multi

Sequential

EVAMPLES

	Environment	Obser vable	Determi nistic	Episodic	Stati c	Discrete	Agents
	Chess with a clock	Fully	Strategic	Sequential	Semi	Discrete	Multi
	Chess without a clock	Fully	Strategic	Sequential	Static	Discrete	Multi
	Poker	Partial	Strategic	Sequential	Static	Discrete	Multi
	Backgammon	Fully	Stochasti c	Sequential	Static	Discrete	Multi
	Taxi driving	Partial	Stochasti c	Sequential	Dyna mic	Continu ous	Multi
	Medical diagnosis						

EVA PL C

6	i ,	
THE STATE OF		
	I	17
		-

Environment	Obser vable	Determi nistic	Episodic	Stati c	Discrete	Agents
Chess with a clock	Fully	Strategic	Sequential	Semi	Discrete	Multi
Chess without a clock	Fully	Strategic	Sequential	Static	Discrete	Multi
Poker	Partial	Strategic	Sequential	Static	Discrete	Multi
Backgammon	Fully	Stochasti c	Sequential	Static	Discrete	Multi
Taxi driving	Partial	Stochasti c	Sequential	Dyna mic	Continu ous	Multi
Medical diagnosis	Partial	Stochasti c	Episodic	Static	Continu ous	Single

Medical diagnosis

Image analysis

	T TC						
EAAMI	Environment	Obser vable	Determi nistic	Episodic	Stati c	Discrete	
	Chess with a clock	Fully	Strategic	Sequential	Semi	Discrete	]
	Chess without a clock	Fully	Strategic	Sequential	Static	Discrete	]
	Poker	Partial	Strategic	Sequential	Static	Discrete	]
dimension of the second	Backgammon	Fully	Stochasti c	Sequential	Static	Discrete	]
	Taxi driving	Partial	Stochasti c	Sequential	Dyna mic	Continu ous	]

Partial

Stochasti

c

Episodic

Static

Continu

ous

Agents

Multi

Multi

Multi

Multi

Multi

Single

	T TC			
EAAMI	Environment	Obser vable	Determi nistic	Episodic
	Chess with a clock	Fully	Strategic	Sequentia
	Chess without a clock	Fully	Strategic	Sequentia
	Poker	Partial	Strategic	Sequentia
	Backgammon	Fully	Stochasti c	Sequentia
	Taxi driving	Partial	Stochasti	Sequentia

Environment	vable	nistic	Episouic	c	Discrete	Agents
Chess with a clock	Fully	Strategic	Sequential	Semi	Discrete	Multi
Chess without a clock	Fully	Strategic	Sequential	Static	Discrete	Multi
Poker	Partial	Strategic	Sequential	Static	Discrete	Multi
Backgammon	Fully	Stochasti c	Sequential	Static	Discrete	Multi
Taxi driving	Partial	Stochasti c	Sequential	Dyna mic	Continu ous	Multi
Medical diagnosis	Partial	Stochasti c	Episodic	Static	Continu ous	Single
Image analysis	Fully	Determi nistic	Episodic	Semi	Discrete	Single

## ENVIRONMENT EXAMPLES Environment Observed



Environment	Obser vable	Determi nistic	Episodic	Stati c	Discrete	Agents
Chess with a clock	Fully	Strategic	Sequential	Semi	Discrete	Multi
Chess without a clock	Fully	Strategic	Sequential	Static	Discrete	Multi
Poker	Partial	Strategic	Sequential	Static	Discrete	Multi
Backgammon	Fully	Stochasti c	Sequential	Static	Discrete	Multi
Taxi driving	Partial	Stochasti c	Sequential	Dyna mic	Continu ous	Multi
Medical diagnosis	Partial	Stochasti c	Episodic	Static	Continu ous	Single
Image analysis	Fully	Determi nistic	Episodic	Semi	Discrete	Single
Robot part picking						

## ENVIRONMENT EXAMPLES Observed Observed Environment Observed O



Environment	Obser vable	Determi nistic	<b>Episodic</b>	Stati c	Discrete	Agents
Chess with a clock	Fully	Strategic	Sequential	Semi	Discrete	Multi
Chess without a clock	Fully	Strategic	Sequential	Static	Discrete	Multi
Poker	Partial	Strategic	Sequential	Static	Discrete	Multi
Backgammon	Fully	Stochasti c	Sequential	Static	Discrete	Multi
Taxi driving	Partial	Stochasti c	Sequential	Dyna mic	Continu ous	Multi
Medical diagnosis	Partial	Stochasti c	Episodic	Static	Continu ous	Single
Image analysis	Fully	Determi nistic	Episodic	Semi	Discrete	Single
Robot part picking	Fully	Determi nistic	Episodic	Semi	Discrete	Single

FXAMI	Environment
	Chess with a clo
	Chess without a
	Poker
	Backgammon

Environment	Obser vable	Determi nistic	Episodic	Stati c	Discrete	Agents
Chess with a clock	Fully	Strategic	Sequential	Semi	Discrete	Multi
Chess without a clock	Fully	Strategic	Sequential	Static	Discrete	Multi
Poker	Partial	Strategic	Sequential	Static	Discrete	Multi
Backgammon	Fully	Stochasti c	Sequential	Static	Discrete	Multi
Taxi driving	Partial	Stochasti c	Sequential	Dyna mic	Continu ous	Multi
Medical diagnosis	Partial	Stochasti c	Episodic	Static	Continu ous	Single
Image analysis	Fully	Determi nistic	Episodic	Semi	Discrete	Single
Robot part picking	Fully	Determi nistic	Episodic	Semi	Discrete	Single
Interactive English tutor						

	H	X	A	\/	1
Siè	46	1		4.	
		W.	5		
	CA .		VIII C		
				-	

Environment	Obser vable	Determi nistic	Episodic	Stati c	Discrete	Agents
Chess with a clock	Fully	Strategic	Sequential	Semi	Discrete	Multi
Chess without a clock	Fully	Strategic	Sequential	Static	Discrete	Multi
Poker	Partial	Strategic	Sequential	Static	Discrete	Multi
Backgammon	Fully	Stochasti c	Sequential	Static	Discrete	Multi
Taxi driving	Partial	Stochasti c	Sequential	Dyna mic	Continu ous	Multi
Medical diagnosis	Partial	Stochasti c	Episodic	Static	Continu ous	Single
Image analysis	Fully	Determi nistic	Episodic	Semi	Discrete	Single
Robot part picking	Fully	Determi nistic	Episodic	Semi	Discrete	Single
Interactive English tutor	Partial	Stochasti c	Sequential	Dyna mic	Discrete	Multi

## AGENT TYPES

Types of agents (increasing in generality and ability to handle complex environments)

- Simple reflex agents
- Reflex agents with state
- ☐ Goal-based agents
- ☐ Utility-based agents
- Learning agent

Source: https://www.oec.uzh.ch/en/studies/master/it/ai.htm



## OTHER EXAMPLE AI SYSTEMS





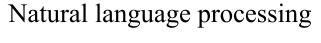
Knowledge Representation Search



Problem solving



Planning



Uncertainty reasoning

Computer Vision

**Robotics** 



Machine learning

### THANK YOU!