## 4. 8 puzzle Missing tiles heuristic

```
def mistil(state, goal):
  count = 0
  for i in range(3):
    for j in range(3):
       if state[i][j] != goal[i][j]:
         count += 1
  return count
def findmin(open_list, goal):
  minv = float('inf')
  best_state = None
  for state in open_list:
    h = mistil(state['state'], goal)
    f = state['g'] + h
    if f < minv:
       minv = f
       best_state = state
  open_list.remove(best_state)
  return best_state
def operation(state):
  next_states = []
  blank_pos = find_blank_position(state['state'])
```

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for move in ['up', 'down', 'left', 'right']:
    new_state = apply_move(state['state'], blank_pos, move)
    if new_state:
       next_states.append({
         'state': new_state,
         'parent': state,
         'move': move,
         'g': state['g'] + 1
      })
  return next_states
def find_blank_position(state):
  for i in range(3):
    for j in range(3):
      if state[i][j] == 0:
         return i, j
  return None
def apply_move(state, blank_pos, move):
  i, j = blank_pos
  new_state = [row[:] for row in state]
  if move == 'up' and i > 0:
    new_state[i][j], new_state[i - 1][j] = new_state[i - 1][j], new_state[i][j]
  elif move == 'down' and i < 2:
```

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new_state[i][j], new_state[i + 1][j] = new_state[i + 1][j], new_state[i][j]
  elif move == 'left' and j > 0:
    new_state[i][j], new_state[i][j - 1] = new_state[i][j - 1], new_state[i][j]
  elif move == 'right' and j < 2:
    new_state[i][j], new_state[i][j + 1] = new_state[i][j + 1], new_state[i][j]
  else:
    return None
  return new_state
def print_state(state):
  for row in state:
    print(' '.join(map(str, row)))
initial_state = [[2,8,3], [1,6,4], [7,0,5]]
goal_state = [[1,2,3], [8,0,4], [7,6,5]]
open_list = [{'state': initial_state, 'parent': None, 'move': None, 'g': 0}]
visited_states = []
while open_list:
  best_state = findmin(open_list, goal_state)
  print("Current state:")
  print_state(best_state['state'])
  h = mistil(best_state['state'], goal_state)
```

```
f = best_state['g'] + h
  print(f"g(n): {best_state['g']}, h(n): {h}, f(n): {f}")
  if best_state['move'] is not None:
    print(f"Move: {best_state['move']}")
  print()
  if mistil(best_state['state'], goal_state) == 0:
    goal_state_reached = best_state
    break
  visited_states.append(best_state['state'])
  next_states = operation(best_state)
  for state in next_states:
    if state['state'] not in visited_states:
      open_list.append(state)
moves = []
while goal_state_reached['move'] is not None:
  moves.append(goal_state_reached['move'])
  goal_state_reached = goal_state_reached['parent']
moves.reverse()
print("\nMoves to reach the goal state:", moves)
print("\nGoal state reached:")
print_state(goal_state)
```

```
Current state:
7 0 5
g(n): 0, h(n): 5, f(n): 5
Current state:
7 6 5
g(n): 1, h(n): 3, f(n): 4
Current state:
2 0 3
184
7 6 5
g(n): 2, h(n): 4, f(n): 6
Current state:
283
7 6 5
g(n): 2, h(n): 4, f(n): 6
Move: left
023
184
7 6 5
g(n): 3, h(n): 3, f(n): 6
Move: left
Current state:
084
7 6 5
g(n): 4, h(n): 2, f(n): 6
Move: down
```

```
Current state:
1 2 3
8 0 4
7 6 5
g(n): 5, h(n): 0, f(n): 5
Move: right

Moves to reach the goal state: ['up', 'up', 'left', 'down', 'right']

Goal state reached:
1 2 3
8 0 4
7 6 5
```