

In [1]:

```
def astar(startnode, stopnode):
    open_set=set(startnode)
    closed_set=set()
    g={}
    parents={}
    parents[startnode]= startnode
    g[startnode]=0
    while len(open_set) > 0:
        n= None
        for v in open_set:
            if n==None or g[v]+heuristic(v)<g[n]+heuristic(n):
                n=v
        if n==stopnode or Graph_nodes[n]==None:
            pass
        else:
            for (m,weight) in get_neighbors(n):
                if m not in open_set and m not in closed_set:
                    open_set.add(m)
                    parents[m]=n
                    g[m]=g[n]+weight
                else:
                    if g[m]>g[n]+weight:
                        g[m]=g[n]+weight
                        parents[m]=n

                    if m in closed_set:
                        closed_set.remove(m)
                        open_set.add(m)

            if n==None:
                print("Path does not exist")
                return None
        if n==stopnode:
            path=[]
            while (parents[n]!=n):
                path.append(n)
                n= parents[n]
            path.append(startnode)
            path.reverse()
            print("Path found {}".format(path))
            return path
        open_set.remove(n)
        closed_set.add(n)
    print("Path does not exist")
    return None

def get_neighbors(n):
    if n in Graph_nodes:
        return Graph_nodes[n]
    else:
        return None

def heuristic(n):
    H_dist = {
        'S': 5,
        'A': 3,
        'B': 4,
        'C': 2,
        'D': 6,
        'G': 0,
    }

    return H_dist[n]
```

```
Graph_nodes = {
    'S': [('A', 1), ('G', 10)],
    'A': [('B', 2), ('C', 1)],
    'B': [('D', 5)],
    'C': [('D', 3), ('G', 4)],
    'D': [('G', 2)],
}

astar('S', 'G')
```

```
Path found ['S', 'A', 'C', 'G']
['S', 'A', 'C', 'G']
```

Out[1]:

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In [1]:

```
class Graph:
    def __init__(self, g, heuristic, startnode):
        self.graph = g
        self.H=heuristic
        self.start = startnode
        self.solution={}
        self.parents={}
        self.status={}

    def applyAO(self):
        self.aostar(self.start, False)

    def getHeuristic(self,n):
        return self.H.get(n,0)
    def getStatus(self,n):
        return self.status.get(n,0)
    def getNeighbor(self,n):
        return self.graph.get(n, '')
    def setHeuristic(self,n,v):
        self.H[n]=v
    def setStatus(self,n,v):
        self.status[n]=v

    def mincost(self,v):
        minimumcost=0
        costtochildnodelist={}
        costtochildnodelist[minimumcost]=[]
        flag=True
        for nodeval in self.getNeighbor(v):
            cost=0
            nodelist=[]
            for c, weight in nodeval:
                cost=cost + self.getHeuristic(c) + weight
                nodelist.append(c)
            if flag==True:
                minimumcost=cost
                costtochildnodelist[minimumcost]=nodelist
                flag=False
            else:
                if minimumcost>cost:
                    minimumcost=cost
                    costtochildnodelist[minimumcost]=nodelist
        return minimumcost, costtochildnodelist[minimumcost]

    def printsol(self):
        print("The start node is" , self.start)
        print("-----")
        print("The solution graph is")
        print(self.solution)

    def aostar(self, v, backtracking):
        print("HEURISTIC VALUES" ,self.H)
        print("Solution Graph", self.solution)
        print("Processing Node" ,v)
        print("-----")

        if self.getStatus(v)>=0:
            minimumCost, childnodelist = self.mincost(v)
            self.setHeuristic(v,minimumCost)
            self.setStatus(v, len(childnodelist))
```

```

        solved==True
    for childnode in childnodelist:
        self.parents[childnode]=v
        if self.getStatus(childnode)!=-1:
            solved =solved & False
    if solved==True:
        self.setStatus(v,-1)
        self.solution[v]=childnodelist

    if v!=self.start:

        self.aostar(self.parents[v], True)

    if backtracking==False:
        for childnode in childnodelist:
            self.setStatus(childnode,0)
            self.aostar(childnode, False)

h1 = {'A': 1, 'B': 6, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 5, 'H': 7, 'I': 7, 'J': 1, 'K': 1}

graph = {
    'A' : [[('B',1), ('C',1)], [('D',1)]],
    'B' : [[('G',1)], [('H',1)]],
    'C' : [[('J',1)]],
    'D' : [[('E',1)], [('F',1)]],
    'G' : [[('I',1)]]
}

g1= Graph(graph,h1,'A')
g1.applyAO()
g1.printsol()

```

```
HEURISTIC VALUES {'A': 1, 'B': 6, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 5, 'H': 7, 'I':  
7, 'J': 1, 'T': '3'}  
Solution Graph {}  
Processing Node A  
-----  
-  
HEURISTIC VALUES {'A': 10, 'B': 6, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 5, 'H': 7, 'I':  
7, 'J': 1, 'T': '3'}  
Solution Graph {}  
Processing Node B  
-----  
-  
HEURISTIC VALUES {'A': 10, 'B': 6, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 5, 'H': 7, 'I':  
7, 'J': 1, 'T': '3'}  
Solution Graph {}  
Processing Node A  
-----  
-  
HEURISTIC VALUES {'A': 10, 'B': 6, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 5, 'H': 7, 'I':  
7, 'J': 1, 'T': '3'}  
Solution Graph {}  
Processing Node G  
-----  
-  
HEURISTIC VALUES {'A': 10, 'B': 6, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 8, 'H': 7, 'I':  
7, 'J': 1, 'T': '3'}  
Solution Graph {}  
Processing Node B  
-----  
-  
HEURISTIC VALUES {'A': 10, 'B': 8, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 8, 'H': 7, 'I':  
7, 'J': 1, 'T': '3'}  
Solution Graph {}  
Processing Node A  
-----  
-  
HEURISTIC VALUES {'A': 12, 'B': 8, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 8, 'H': 7, 'I':  
7, 'J': 1, 'T': '3'}  
Solution Graph {}  
Processing Node I  
-----  
-  
HEURISTIC VALUES {'A': 12, 'B': 8, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 8, 'H': 7, 'I':  
0, 'J': 1, 'T': '3'}  
Solution Graph {'I': []}  
Processing Node G  
-----  
-  
HEURISTIC VALUES {'A': 12, 'B': 8, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 1, 'H': 7, 'I':  
0, 'J': 1, 'T': '3'}  
Solution Graph {'I': [], 'G': ['I']}  
Processing Node B  
-----  
-  
HEURISTIC VALUES {'A': 12, 'B': 2, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 1, 'H': 7, 'I':  
0, 'J': 1, 'T': '3'}  
Solution Graph {'I': [], 'G': ['I'], 'B': ['G']}  
Processing Node A  
-----  
-  
HEURISTIC VALUES {'A': 6, 'B': 2, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 1, 'H': 7, 'I':  
0, 'J': 1, 'T': '3'}  
Solution Graph {'I': [], 'G': ['I'], 'B': ['G']}  
Processing Node C  
-----  
-
```

```
HEURISTIC VALUES {'A': 6, 'B': 2, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 1, 'H': 7, 'I':
0, 'J': 1, 'T': '3'}
Solution Graph {'I': [], 'G': ['I'], 'B': ['G']}
Processing Node A
-----
-
HEURISTIC VALUES {'A': 6, 'B': 2, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 1, 'H': 7, 'I':
0, 'J': 1, 'T': '3'}
Solution Graph {'I': [], 'G': ['I'], 'B': ['G']}
Processing Node J
-----
-
HEURISTIC VALUES {'A': 6, 'B': 2, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 1, 'H': 7, 'I':
0, 'J': 0, 'T': '3'}
Solution Graph {'I': [], 'G': ['I'], 'B': ['G'], 'J': []}
Processing Node C
-----
-
HEURISTIC VALUES {'A': 6, 'B': 2, 'C': 1, 'D': 12, 'E': 2, 'F': 1, 'G': 1, 'H': 7, 'I':
0, 'J': 0, 'T': '3'}
Solution Graph {'I': [], 'G': ['I'], 'B': ['G'], 'J': [], 'C': ['J']}
Processing Node A
-----
-
The start node is A
-----
The solution graph is
{'I': [], 'G': ['I'], 'B': ['G'], 'J': [], 'C': ['J'], 'A': ['B', 'C']}
```

In []:

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In [23]:

```
import csv
a=[]
with open('../labprog/c2.csv') as csvfile:
    fdata= csv.reader(csvfile)
    for row in fdata:
        a.append(row)
        print(row)

['sunny', 'warm', 'normal', 'strong', 'warm', 'same', 'Y']
['sunny', 'warm', 'high', 'strong', 'warm', 'same', 'Y']
['rainy', 'cold', 'high', 'strong', 'warm', 'change', 'N']
['sunny', 'warm', 'high', 'strong', 'cool', 'change', 'Y']
```

In [24]:

```
num_att = len(a[0])-1
S=['0']*num_att
G=['?']*num_att
print(S)
print(G)
temp=[]

['0', '0', '0', '0', '0', '0']
['?', '?', '?', '?', '?', '?']
```

In [25]:

```
for i in range(0,num_att):
    S[i]=a[0][i]
print("-----")
```

In [27]:

```
for i in range(0, len(a)):
    if a[i][num_att]=='Y':
        for j in range(0,num_att):
            if S[j]!=a[i][j]:
                S[j]='?'
        for j in range(0,num_att):
            for k in range(0, len(temp)):
                if temp[k][j]!=S[j] and temp[k][j]!='?':
                    del temp[k]
    if a[i][num_att]=='N':
        for j in range(0,num_att):
            if S[j]!=a[i][j] and S[j]!='?':
                G[j]= S[j]
                temp.append(G)
                G =['?']*num_att
```

In [29]:

```
print(S)
if len(temp)==0:
    print(G)
else:
    print(temp)

['sunny', 'warm', '?', 'strong', '?', '?']
[['sunny', '?', '?', '?', '?', '?'], ['?', 'warm', '?', '?', '?', '?'], ['sunny', '?',
 '?', '?', '?', '?'], ['?', 'warm', '?', '?', '?', '?']]
```

In []:


```
In [28]: from collections import Counter
        from pprint import pprint
        import pandas as pd
        import math
```

```
In [36]: data = pd.read_csv('tennis.csv')
        attr = list(data.columns[1:])
        attr.remove('PlayTennis')
```

```
In [41]: def entropy(x):
        c = Counter(i for i in x)
        n = len(x) * 1.0
        prob= [i/n for i in c.values()]
        return sum(-i*math.log(i,2) for i in prob)
```

```
In [45]: def information_gain(df,split,target):
        dfs= df.groupby(split)
        n= len(df)*1.0
        dfa = dfs.agg({target: [entropy, lambda x: len(x)/n]})[target]
        dfa.columns = ['entropy', 'prob']
        new = sum(dfa['entropy'] * dfa['prob'])
        old = entropy(df[target])
        return old-new
```

```
In [50]: def id3(df,attr,target, default=None):
        c = Counter(i for i in df[target])
        if len(c)==1:
            return next(iter(c))
        elif df.empty or (not attr):
            return default
        else:
            default = max(c.keys())
            gain = [information_gain(df,att,target) for att in attr]
            best = attr[gain.index(max(gain))]
            tree= {best:{}}
            remain = [ i for i in attr if i!=best]
            for at, dfs in df.groupby(best):
                subtree= id3(dfs,remain,target,default)
                tree[best][at]= subtree
            return tree
```

```
In [51]: tree = id3(data,attr,'PlayTennis')
        pprint(tree)
```

```
{'Outlook': {'Overcast': 'Yes',
             'Rain': {'Wind': {'Strong': 'No', 'Weak': 'Yes'}},
             'Sunny': {'Humidity': {'High': 'No', 'Normal': 'Yes'}}}}
```

```
In [ ]:
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```
In [ ]:
```

```
In [3]: import numpy as np
X=np.array([[1,2],[3,6],[2,5]],dtype=float)
Y =np.array([[92],[86],[89]],dtype=float)
X= X/np.amax(X,axis=0)
Y= Y/100
```

```
In [8]: epooch = 500
lr =0.1
inputlay=2
hidden=3
output=1

def sigmoid(x):
    return (1 / 1 + np.exp(-x))
def derivative_sigmoid(x):
    return (x* (1-x))
```

```
In [9]: wh = np.random.uniform(size=(inputlay,hidden))
bh = np.random.uniform(size=(1,hidden))
wout = np.random.uniform(size=(hidden, output))
bout = np.random.uniform(size=(1, output))
```

```
In [13]: for i in range(epooch):
    hinpl = np.dot(X,wh)
    hinp = hinpl + bh
    hlayer_act = sigmoid(hinp)
    outinp1 = np.dot(hlayer_act, wout)
    outinp = outinp1 + bout
    output = sigmoid(outinp)
```

```
In [15]: EO = Y - output
outgrad = derivative_sigmoid(output)
d_output = EO * outgrad
EH = d_output.dot(wout.T)
hgrad=derivative_sigmoid(hlayer_act)
h_output = EH * hgrad
```

```
In [17]: wout+= hlayer_act.T.dot(d_output) *lr
wh += X.T.dot(h_output) *lr
```

```
In [18]: print("Expected outcome", str(Y))
print("Output", output)
print("Input", str(X))
```

```
Expected outcome [[0.92]
 [0.86]
 [0.89]]
Output [[1.05127091]
 [1.07260753]
 [1.06511096]]
Input [[0.33333333 0.33333333]
 [1.          1.          ]
 [0.66666667 0.83333333]]
```



```
In [5]: import math
import csv
def safe_div(x,y):
    if y==0:
        return 0
    return x/y
def mean(numbers):
    return(safe_div(sum(numbers) , float(len(numbers))))
def stdev(numbers):
    avg=mean(numbers)
    variance = safe_div(sum([pow(x-avg, 2) for x in numbers ]), float(len(numbers)-1))
    return math.sqrt(variance)
```

```
In [4]: def calculateprob(x, mean,stdev):
    expo= math.exp( -safe_div( math.pow(x-mean,2), (2 * math.pow(stdev,2)) ))
    final = safe_div(expo, math.sqrt(2*math.pi)* stdev)
    return final
```

```
In [5]: testset=dataset =[list(map(float,i)) for i in [x for x in list(csv.reader(open("ConceptLearning.csv")))]
trainset = [testset.pop(0) for x in range(int(len(dataset)*0.9))]
print(*testset ,sep="\n")
print(*trainset ,sep="\n")
```

```
-----
NameError                                Traceback (most recent call last)
Input In [5], in <module>
----> 1 testset=dataset =[list(map(float,i)) for i in [x for x in list(csv.reader(open("
ConceptLearning.csv")))]
      2 trainset = [testset.pop(0) for x in range(int(len(dataset)*0.9))]
      3 print(*testset ,sep="\n")

NameError: name 'csv' is not defined
```

```
In [6]: separated= {}
for i in trainset:
    if i[-1] not in separated:
        separated[i[-1]]=[]
        separated[i[-1]].append(i)
```

```
-----
NameError                                Traceback (most recent call last)
Input In [6], in <module>
      1 separated= {}
----> 2 for i in trainset:
      3     if i[-1] not in separated:
      4         separated[i[-1]]=[]

NameError: name 'trainset' is not defined
```

```
In [7]: summaries = {}
for classvalue, instances in separated.items():
    summaries[classvalue] = [(mean(att), stdev(att)) for att in zip(*instances)]
    [i.pop() for i in summaries.values()]
print("Summaries attributes by class")
for i, j in summaries.items():
    print(i, ":", j)
```

```
In [8]: prediction = []
        for i in range(len(testset)):
            probab = {}
            for clv, classum in summaries.items():
                probab[clv]=1
            for j in range(len(classum)):
                mean, stdev = classum[j]
                x = testset[i][j]
                probab[clv]*= calculateprob(x, mean,stdev)
            bestLabel, bestProb = None, -1
            for cv, prob in probab.items():
                if bestLabel is None or prob>bestProb:
                    bestProb = prob
                    bestLabel = cv
            prediction.append(bestLabel)
```

```
-----
NameError                                Traceback (most recent call last)
Input In [8], in <module>
      1 prediction = []
----> 2 for i in range(len(testset)):
      3     probab = {}
      4     for clv, classum in summaries.items():

NameError: name 'testset' is not defined
```

```
In [9]: actual = [i[-1] for i in testset]
        count = 0
        for (i,j) in zip(actual,prediction):
            if i==j:
                count+=1
        accuracy = safe_div(count, float(len(actual))) *100
        print("ACTUAL", actual)
        print("PREDICTION", prediction)
        print("Accuracy", accuracy)
```

```
-----
NameError                                Traceback (most recent call last)
Input In [9], in <module>
----> 1 actual = [i[-1] for i in testset]
      2 count = 0
      3 for (i,j) in zip(actual,prediction):

NameError: name 'testset' is not defined
```

In []:

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```
In [59]: from sklearn.cluster import KMeans
import sklearn.metrics as sm
import matplotlib.pyplot as plt
from sklearn.mixture import GaussianMixture
from sklearn.datasets import load_iris
from sklearn import preprocessing
import pandas as pd
import numpy as np
```

```
In [60]: iris= load_iris()
X= pd.DataFrame(iris.data)
Y= pd.DataFrame(iris.target)

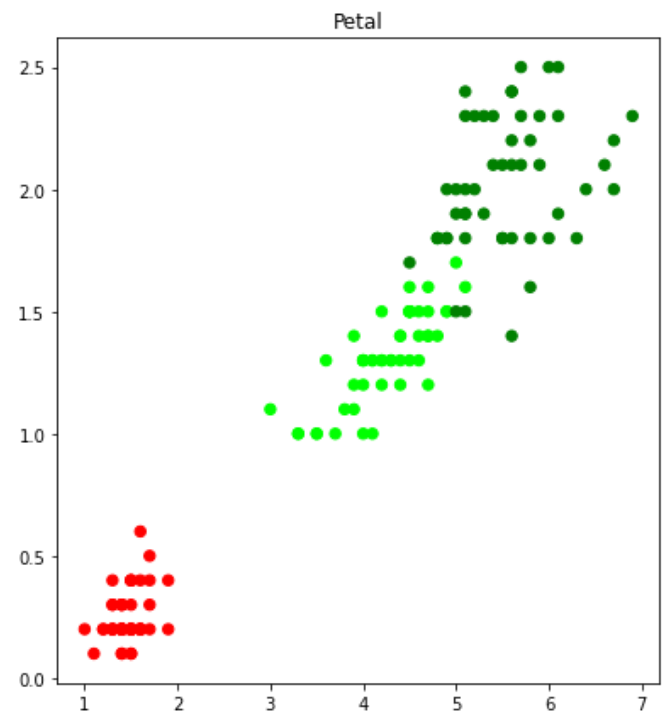
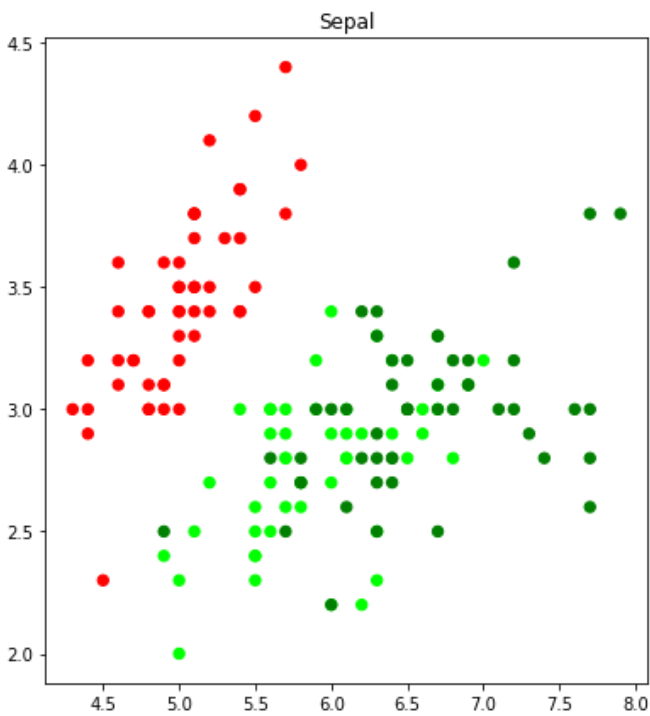
l1 = [0,1,2]
def rename(s):
    l2=[]
    for i in s:
        if i not in l2:
            l2.append(i)
    for i in range(len(s)):
        pos= l2.index(s[i])
        s[i]=l1[pos]
    return s
```

```
In [61]: X.columns= ['Sep_L', 'Sep_W', 'Pet_L', 'Pet_W']
Y.columns = ['Targets']
```

```
In [62]: plt.figure(figsize=(14,7))
color = np.array(['red', 'lime', 'green'])

plt.subplot(1,2,1)
plt.scatter(X.Sep_L, X.Sep_W, c=color[Y.Targets], s=40)
plt.title("Sepal")

plt.subplot(1,2,2)
plt.scatter(X.Pet_L, X.Pet_W, c=color[Y.Targets], s=40)
plt.title("Petal")
plt.show()
```



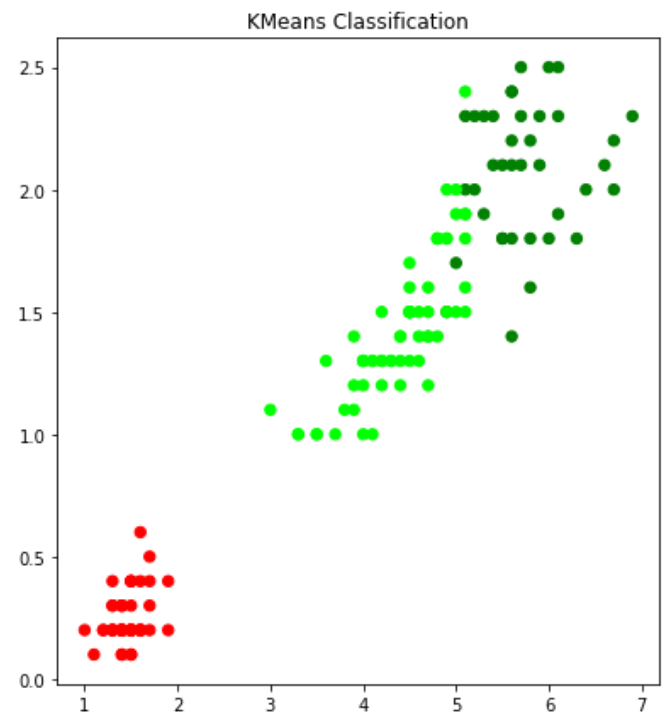
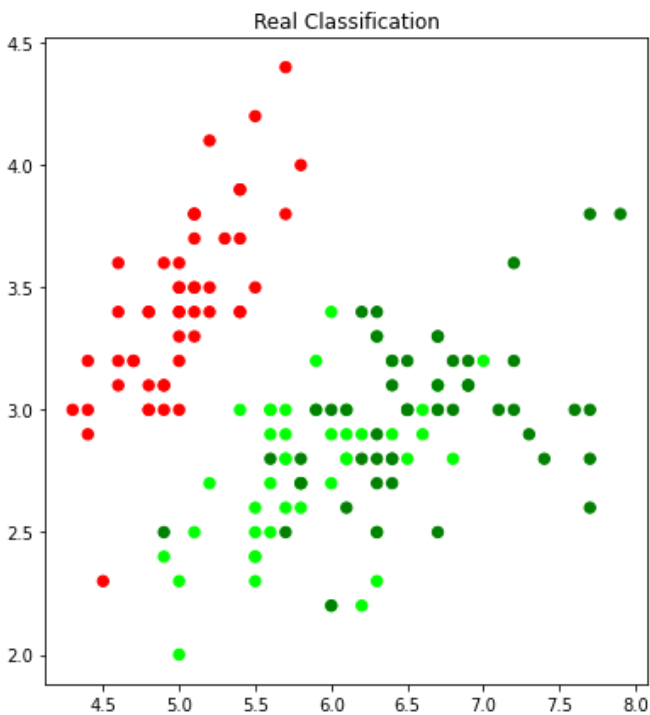
```
In [63]: model = KMeans(n_clusters= 3)
model.fit(X)
```

```
Out[63]: KMeans(n_clusters=3)
```

```
In [64]: plt.figure(figsize=(14,7))
color = np.array(['red', 'lime', 'green'])

plt.subplot(1,2,1)
plt.scatter(X.Sep_L, X.Sep_W, c=color[Y.Targets], s=40)
plt.title("Real Classification")

plt.subplot(1,2,2)
plt.scatter(X.Pet_L, X.Pet_W, c=color[model.labels_], s=40)
plt.title("KMeans Classification")
plt.show()
```



```
In [65]: km = rename(model.labels_)
print("What KMEANS THOUGHT", km)
print("What is accuracy score", sm.accuracy_score(Y, km))
print("What is confusion matrix \n", sm.confusion_matrix(Y, km))
```

[illegible]

```
scaler = preprocessing.StandardScaler()
```

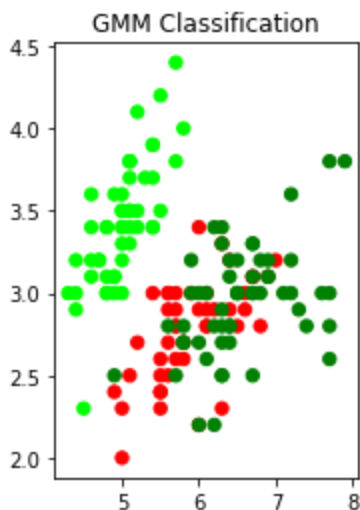
```
In [67]: scaler.fit(X)
          xsa= scaler.transform(X)
          xs= pd.DataFrame(xsa, columns= X.columns)
          print("xs is", xs.sample(5))
```

xs	is	Sep_L	Sep_W	Pet_L	Pet_W
142	-0.052506	-0.822570	0.762758	0.922303	
46	-0.900681	1.709595	-1.226552	-1.315444	
130	1.886180	-0.592373	1.331133	0.922303	
122	2.249683	-0.592373	1.672157	1.053935	
20	-0.537178	0.788808	-1.169714	-1.315444	

```
In [74]: gmm = GaussianMixture(n_components=3)

gmm.fit(xs)
y_cluster_gmm = gmm.predict(xs)

plt.subplot(1,2,1)
plt.scatter(X.Sep_L, X.Sep_W, c=color[y_cluster_gmm], s=40)
plt.title("GMM Classification")
plt.show()
```



```
In [75]: em = rename(y cluster gmm)
```


[illegible]

```
In [6]: from sklearn.datasets import load_iris
        from sklearn.neighbors import KNeighborsClassifier
        from sklearn.model_selection import train_test_split
        import numpy as np
```

```
In [9]: iris_data = load_iris()
```

```
In [10]: X_train, X_test, y_train, y_test= train_test_split(iris_data['data'], iris_data['target']
```

```
In [11]: print("IRIS DATASET", iris_data['data'])
        print("X Test", X_test)
        print("X_train", X_train)
```

IRIS DATASET [[5.1 3.5 1.4 0.2]

[4.9 3. 1.4 0.2]

[4.7 3.2 1.3 0.2]

[4.6 3.1 1.5 0.2]

[5. 3.6 1.4 0.2]

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[4.6 3.2 1.4 0.2]]

```

```

In [13]: kn = KNeighborsClassifier(n_neighbors=5)
         kn.fit(X_train, y_train)

```

```

Out[13]: KNeighborsClassifier()

```

```

In [30]: x_new = np.array([[5, 2.9, 1, 0.2]])
         prediction = kn.predict(x_new)

```

```

In [31]: print("Prediction value is: {} ".format(prediction))
         print("predicted feature name is ", iris_data["target_names"][prediction])

```

```

Prediction value is: [0]
predicted feature name is  ['setosa']

```

```

In [41]: i = 1
         x = X_test[i]
         x_new = np.array([x])
         for i in range(len(X_test)):
             x = X_test[i]
             x_new = np.array([x])
             prediction = kn.predict(x_new)
             print("\nACTUAL : {0} {1}, PREDICTED: {2}{3}" .format(y_test[i], iris_data["target_names"][y_test[i]],
                                                                     iris_data["target_names"][prediction], prediction))
         print("\nAccuracy score [ACCURACY] ", kn.score(X_test, y_test) )

```


ACTUAL : 2 virginica, PREDICTED: [2]['virginica']

ACTUAL : 1 versicolor, PREDICTED: [1]['versicolor']

ACTUAL : 0 setosa, PREDICTED: [0]['setosa']

ACTUAL : 2 virginica, PREDICTED: [2]['virginica']

ACTUAL : 0 setosa, PREDICTED: [0]['setosa']

ACTUAL : 2 virginica, PREDICTED: [2]['virginica']

ACTUAL : 0 setosa, PREDICTED: [0]['setosa']

ACTUAL : 1 versicolor, PREDICTED: [1]['versicolor']

ACTUAL : 1 versicolor, PREDICTED: [1]['versicolor']

ACTUAL : 1 versicolor, PREDICTED: [1]['versicolor']

ACTUAL : 2 virginica, PREDICTED: [2]['virginica']

ACTUAL : 1 versicolor, PREDICTED: [1]['versicolor']

ACTUAL : 1 versicolor, PREDICTED: [1]['versicolor']

ACTUAL : 1 versicolor, PREDICTED: [1]['versicolor']

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ACTUAL : 0 setosa, PREDICTED: [0]['setosa']

ACTUAL : 0 setosa, PREDICTED: [0]['setosa']

ACTUAL : 2 virginica, PREDICTED: [2]['virginica']

ACTUAL : 1 versicolor, PREDICTED: [1]['versicolor']

ACTUAL : 0 setosa, PREDICTED: [0]['setosa']

ACTUAL : 0 setosa, PREDICTED: [0]['setosa']

ACTUAL : 2 virginica, PREDICTED: [2]['virginica']

ACTUAL : 0 setosa, PREDICTED: [0]['setosa']

ACTUAL : 0 setosa, PREDICTED: [0]['setosa']

ACTUAL : 1 versicolor, PREDICTED: [1]['versicolor']

ACTUAL : 1 versicolor, PREDICTED: [1]['versicolor']

ACTUAL : 0 setosa, PREDICTED: [0]['setosa']

ACTUAL : 2 virginica, PREDICTED: [2]['virginica']

ACTUAL : 1 versicolor, PREDICTED: [1]['versicolor']

ACTUAL : 0 setosa, PREDICTED: [0]['setosa']

ACTUAL : 2 virginica, PREDICTED: [2]['virginica']

ACTUAL : 2 virginica, PREDICTED: [2]['virginica']

ACTUAL : 1 versicolor, PREDICTED: [1]['versicolor']

ACTUAL : 0 setosa, PREDICTED: [0]['setosa']

ACTUAL : 1 versicolor, PREDICTED: [2]['virginica']

Accuracy score [ACCURACY] 0.9736842105263158

In []:

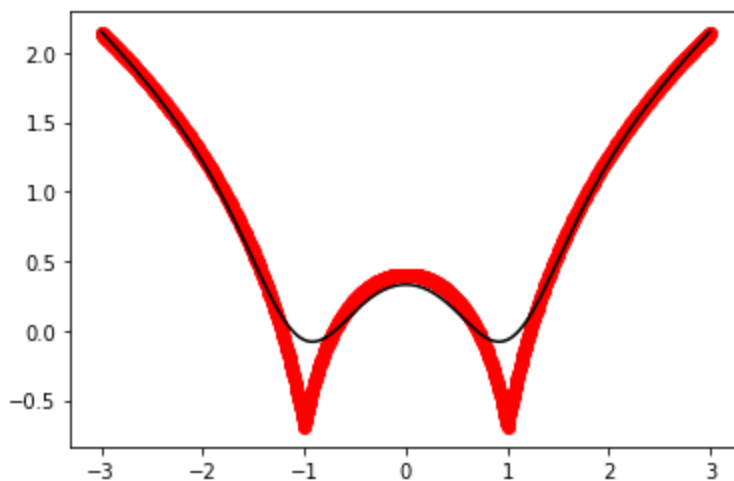
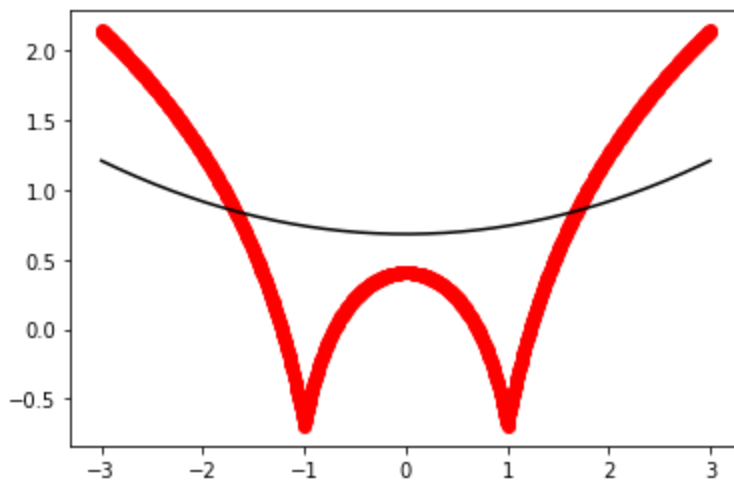
In []:

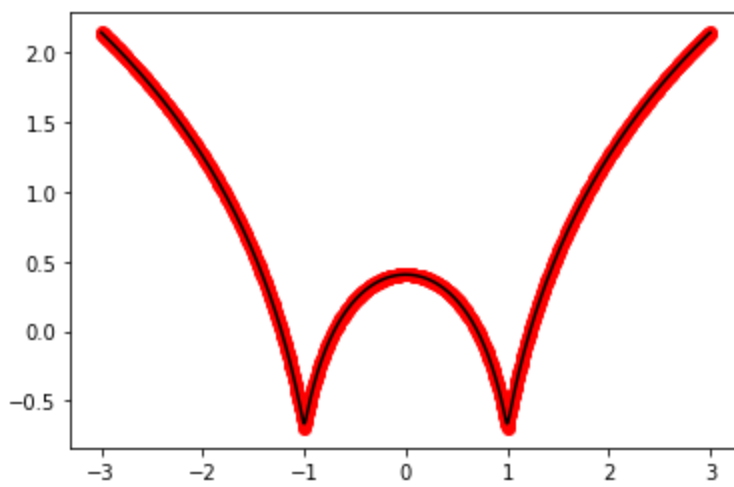
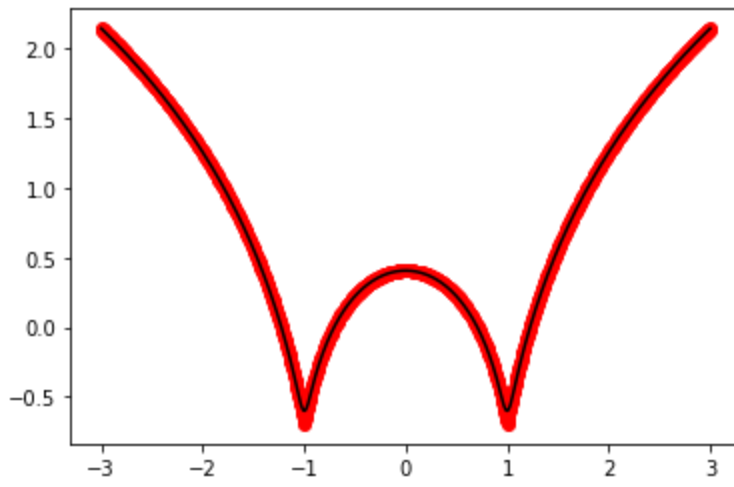
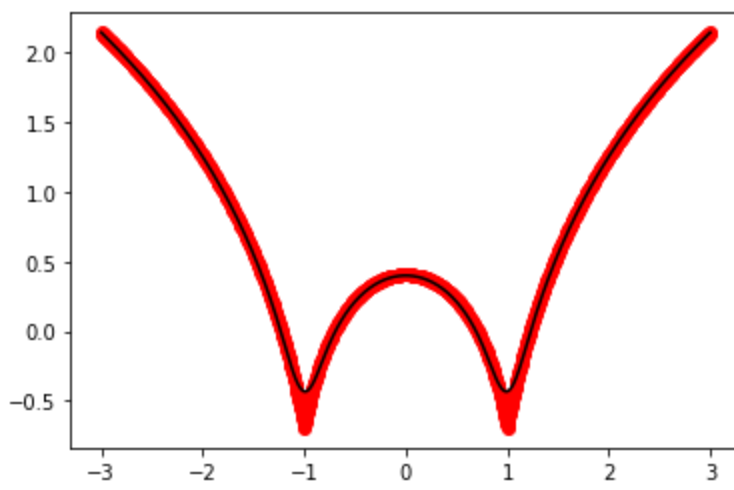
```
In [2]: import numpy as np
import matplotlib.pyplot as plt

def local_reg(x0,X,Y,tau):
    x0 =[1,x0]
    X=[[1,i] for i in X]
    X= np.asarray(X)
    xw = X.T * np.exp(np.sum((X-x0)**2 ,axis=1)/ (-2*tau))
    beta= np.linalg.pinv(xw @ X) @ xw @ Y @ x0
    return beta
```

```
In [5]: def draw(tau):
    prediction = [local_reg(x0,X,Y,tau) for x0 in domain]
    plt.plot(X,Y, 'o', color='red')
    plt.plot(domain, prediction, color='black')
    plt.show()
```

```
In [6]: X= np.linspace(-3,3,num=1000)
domain = X
Y= np.log(np.abs(X**2 -1) +0.5)
draw(10)
draw(0.1)
draw(0.01)
draw(0.001)
draw(0.0001)
```





In []:

7