

# Vidyavardhini's College of Engineering and Technology Department of Artificial Intelligence & Data Science

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Class/Sem:	SE/IV
<b>Experiment No.:</b>	11
Title:	15 Puzzle.
<b>Date of Performance:</b>	
Date of Submission:	
Marks:	
Sign of Faculty:	



# Vidyavardhini's College of Engineering and Technology

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#### **Experiment No. 11**

Title: 15 Puzzle.

Aim: To study and implement 15 puzzle problem

Objective: To introduce Backtracking and Branch-Bound methods

#### Theory:

The 15 puzzle problem is invented by sam loyd in 1878.

- In this problem there are 15 tiles, which are numbered from 0 15.
- The objective of this problem is to transform the arrangement of tiles from initial arrangement to a goal arrangement.
- The initial and goal arrangement is shown by following figure.

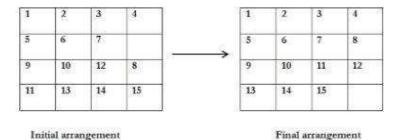


Figure 12

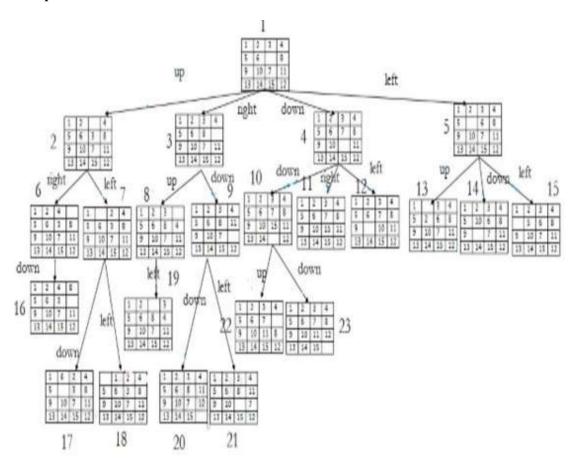
- There is always an empty slot in the initial arrangement.
- The legal moves are the moves in which the tiles adjacent to ES are moved to either left, right, up or down.
- Each move creates a new arrangement in a tile.
- These arrangements are called as states of the puzzle.
- The initial arrangement is called as initial state and goal arrangement is called as goal state.
- The state space tree for 15 puzzle is very large because there can be 16! Different arrangements.
- A partial state space tree can be shown in figure.



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- In state space tree, the nodes are numbered as per the level.
- Each next move is generated based on empty slot positions.
- Edges are label according to the direction in which the empty space moves.
- The root node becomes the E- node.
- The child node 2, 3, 4 and 5 of this E node get generated.
- Out of which node 4 becomes an E node. For this node the live nodes 10, 11, 12 gets generated.
- Then the node 10 becomes the E node for which the child nodes 22 and 23 gets generated.
- Finally we get a goal state at node 23.
- We can decide which node to become an E node based on estimation formula.

#### **Example:**





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#### **Implementation:**

```
#include <stdio.h>
#include <stdlib.h>
#define N 4 // Size of the puzzle grid (N x N)
#define EMPTY TILE 0
void printPuzzle(int puzzle[N][N]) {
int i,j;
    for (i = 0; i < N; i++) {
    for (j = 0; j < N; j++) {
            if (puzzle[i][j] == EMPTY_TILE) {
                printf(" "); // Print empty tile
                printf("%2d ", puzzle[i][j]);
        printf("\n");
int isSolved(int puzzle[N][N]) {
    int count = 1;
    int i,j;
    for (i = 0; i < N; i++) {
    for (j = 0; j < N; j++) {
        if (puzzle[i][j] != count && (i != N - 1 || j != N - 1)) {
                return 0; // Puzzle is not solved
            count++;
    return 1; // Puzzle is solved
// Function to move the empty tile in the puzzle
void moveTile(int puzzle[N][N], int moveX, int moveY) {
    int emptyX, emptyY,i,j;
```



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```
// Find the position of the empty tile
   for (i = 0; i < N; i++) {
    for (j = 0; j < N; j++) {
            if (puzzle[i][j] == EMPTY_TILE) {
                emptyX = i;
                emptyY = j;
                break;
    // Swap the empty tile with the tile to be moved
   puzzle[emptyX][emptyY] = puzzle[emptyX + moveX][emptyY + moveY];
   puzzle[emptyX + moveX][emptyY + moveY] = EMPTY_TILE;
int main() {
    int puzzle[N][N] = {
       {1, 2, 3, 4},
       \{5, 6, 7, 8\},\
       {9, 10, 11, 12},
        {13, 14, 15, EMPTY_TILE}
   };
   printf("Initial Puzzle State:\n");
   printPuzzle(puzzle);
   // Example move: Move the empty tile up
   moveTile(puzzle, -1, 0);
   printf("\nPuzzle State After Move:\n");
   printPuzzle(puzzle);
   if (isSolved(puzzle)) {
        printf("\nPuzzle Solved!\n");
    } else {
        printf("\nPuzzle Not Solved Yet.\n");
   return 0;
```



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#### **Output:**

```
C:\TURBOC3\BIN\TC
Initial Puzzle State:
1 2 3 4
5 6 7 8
9 10 11 12
13 14 15

Puzzle State After Move:
1 2 3 4
5 6 7 8
9 10 11
13 14 15 12
```

**Conclusion:** The implementation of the 15 puzzle problem in C demonstrated the fundamental mechanics of puzzle manipulation and state checking. While the provided code offers a basic framework, further extensions could include implementing solving algorithms such as A\* search to find optimal solutions efficiently.