

Linear Algebra & Convex Optimization – Lecture 1

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Course Outline

Lecture Topics (14 Lectures) :

- Vector Operations,, Norms, Distances
- Clustering, Linear Dependence, Basis, Orthogonality
- Matrices, Matrix -Vector Product, Matrix Applications
- Matrix Inverses , Solving Linear Equations, Projection Spaces
- Least Squares, Data Fitting, Classification
- Eigen Analysis, PCA, Positive/Negative Definiteness
- Singular Value Decomposition and Applications
- Introduction to Functions, Derivatives and Matrix Calculus
- Convex Functions and Optimization Problems
- Optimality Criteria, Equivalent Convex Problems
- Lagrange Duality, Complementary Slackness, KKT conditions
- Constrained Optimization , Application to PCA
- Un-constrained Optimization, Gradient Descent Methods

Tutorials (2 Lectures):

Python Exercises (Vectors, Matrices, Least Squares)

Texts:

1. Introduction to Applied Linear Algebra, *Stephen Boyd & Lieven Vandenberghe*
2. Convex Optimization, *Stephen Boyd*

Evaluation Scheme – Part 1

Total (50)	
25 Marks	Mid-term Exam (Multiple Choice, 25 Questions of 1 mark each)
10 Marks	Assignment 1 (Pen and Paper)
10 Marks	Assignment 2 (Pen and Paper)
5 Marks	Attendance + Class Participation(Polls)

Outline

- Vector Representation
- Vector Operations
- Norms, Distances
- Vector Standardization

Textbook: Introduction to Applied Linear Algebra, S. Boyd: Chapters 1,2,3.

Vector Representation : Algebraic

Vector : Ordered set of numbers

$$\begin{bmatrix} -1.1 \\ 0.0 \\ 3.6 \\ -7.2 \end{bmatrix} \quad \text{or} \quad \begin{pmatrix} -1.1 \\ 0.0 \\ 3.6 \\ -7.2 \end{pmatrix} \quad \text{or} \quad (-1.1, 0.0, 3.6, -7.2).$$

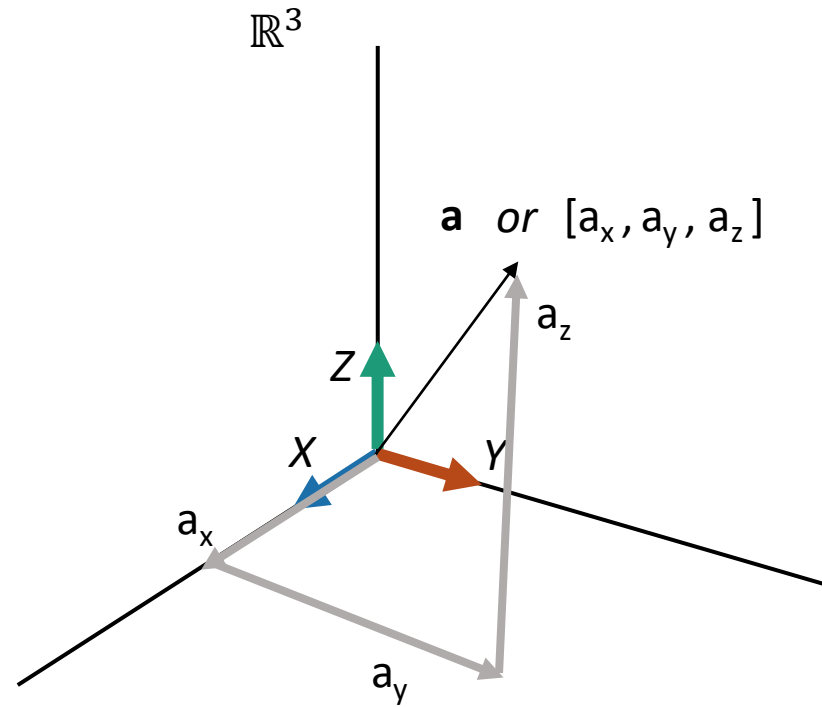
Indexing:

n dimensional vector indexed from $i = 1$ to $i = n$

elements in a single vector : $a = [a_1, a_2, \dots, a_n]$

elements in a group of vectors: j^{th} element in i^{th} vector : $(a_i)_j$

Vector Representation : Geometric



$$\mathbf{a} \in \mathbb{R}^3$$

$[a_x, a_y, a_z]$ \Rightarrow Point in 3- dimensional Space /
3-dimensional Vector / **Data**

Vector Representations

Stacked Vectors :

$$a = \begin{bmatrix} b \\ c \\ d \end{bmatrix}$$

$b \in \mathbb{R}^m$ $c \in \mathbb{R}^n$ $d \in \mathbb{R}^p$

$$a \in \mathbb{R}^{(m+n+p)}$$

$$b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$
$$m \times 1$$

$$c = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$$
$$n \times 1$$

$$d = \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_p \end{bmatrix}$$
$$p \times 1$$

$$a = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \\ c_1 \\ \vdots \\ c_n \\ d_1 \\ \vdots \\ d_p \end{bmatrix}$$
$$(m+n+p) \times 1$$

Transpose of Stacked Vectors :

$$a^T = [b^T \ c^T \ d^T]$$

$$a^T = [b_1 \ b_2 \ \dots \ b_m \ c_1 \ \dots \ c_n \ d_1 \ \dots \ d_p]$$
$$1 \times (m+n+p)$$

Slicing Vectors :

$a_{r:s} = (a_r, \dots, a_s)$

$b = a_{1:m}$

$c = a_{(m+1):(m+n)}$

$d = a_{(m+n+1):(m+n+p)}$

Unit Vectors

Unit Vector : All elements equal to zero except one element equal to one

$$e_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad e_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad e_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

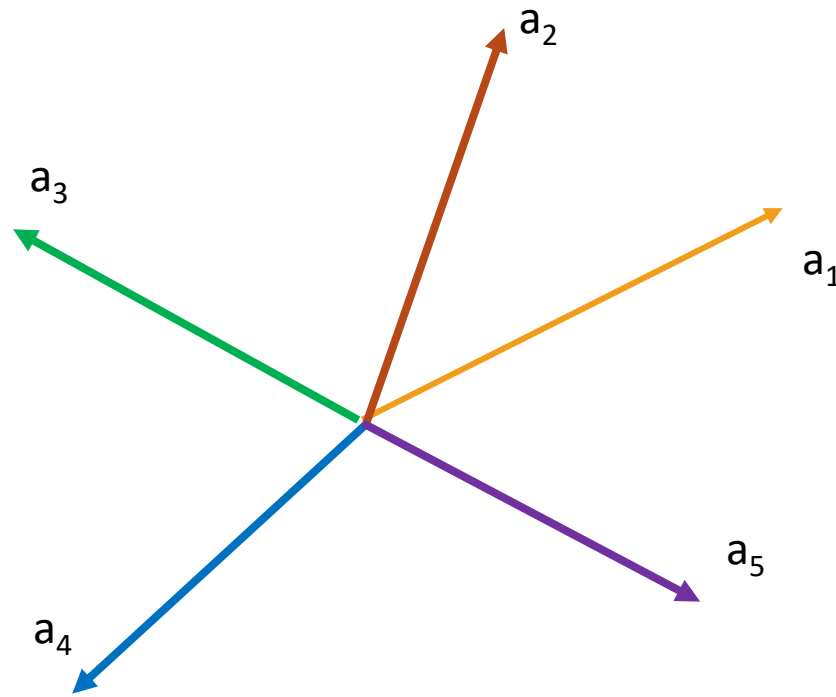
j^{th} element in i^{th} unit vector :

$$(e_i)_j = \begin{cases} 1 & j = i \\ 0 & j \neq i \end{cases}$$

Examples : Data in Multi-Dimensional Space

5 –Dimensional Space (\mathbb{R}^5)

(Do not bother to Imagine !
Look only Algebraic way)



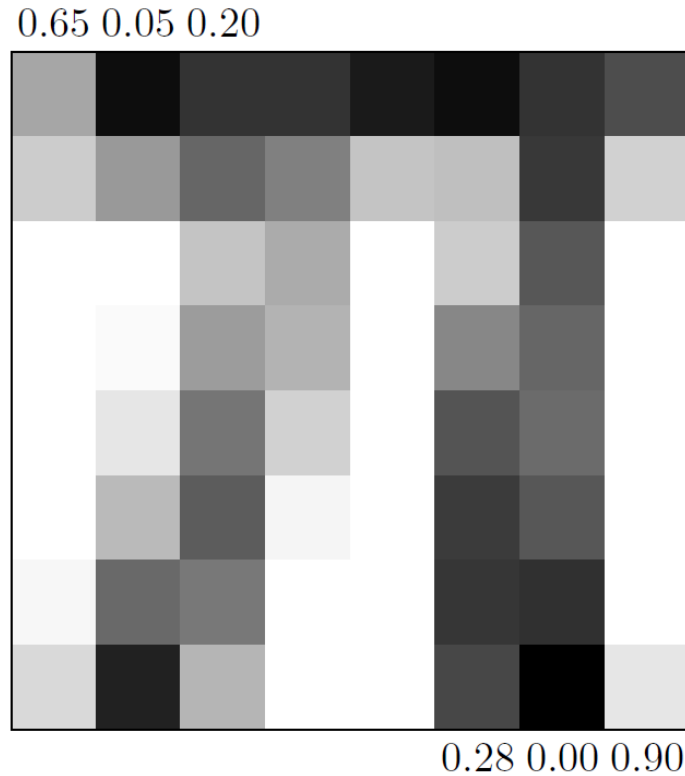
$$a_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad a_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad a_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$a_4 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} \quad a_5 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

Dimension	Meaning	Value
a_1	Height (ft)	6
a_2	Age	30
a_3	Weight (kg)	70
a_4	Waist-Size(in)	32
a_5	Gender	1

$$\mathbf{a} = [6 , 30 , 70 , 32 , 1] \quad \Rightarrow \quad \mathbf{a} = 6\mathbf{a}_1 + 30\mathbf{a}_2 + 70\mathbf{a}_3 + 32\mathbf{a}_4 + \mathbf{a}_5$$

Example : Image Representation



8 × 8 image

8 × 8 image can be represented as 64 dimensional vector

$$x = [0.65 \ 0.05 \ 0.20 \ \dots \ 0.28 \ 0.00 \ 0.90]$$

x is a point in 64-dimension space, $x \in \mathbb{R}^{64}$

Videos:

k frames in a video of resolution $m \times n$ can be represented as
as $m \times n \times k$ vector

$$x \in \mathbb{R}^{m \times n \times k}$$

Poll : $x \in \mathbb{R}^{m \times n \times k}$ & $x \in \mathbb{R}^{m \times k \times n}$
represents the same video ?

Example : Document Representation

Word Count Histogram:

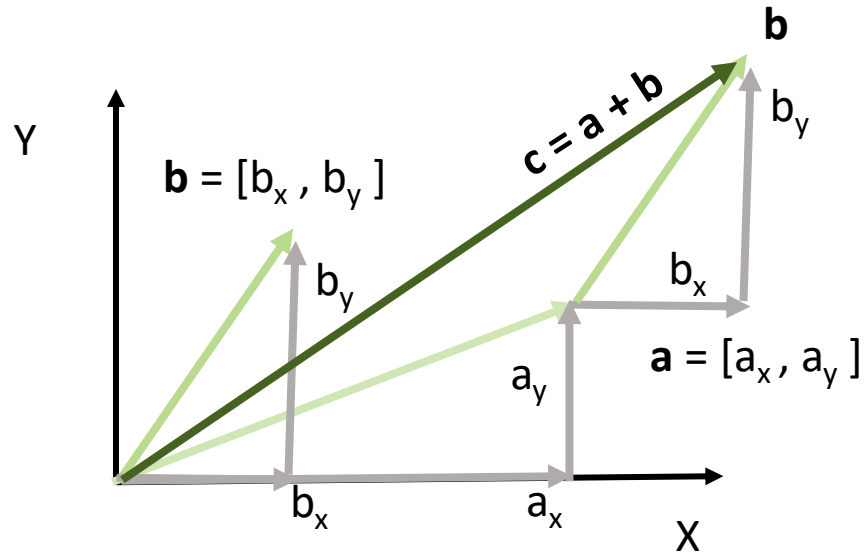
word	3
in	2
number	1
horse	0
the	4
document	2

Word –Preprocessing:

- 1) Tokenization
- 2) Normalization
- 3) Stop-word removal
- 4) Lemmatization

Vector Addition

How Vector Addition Looks Geometrically ?



For any 2D vectors \mathbf{a} , \mathbf{b}

$$\mathbf{a} + \mathbf{b} = [a_x + b_x, a_y + b_y]$$

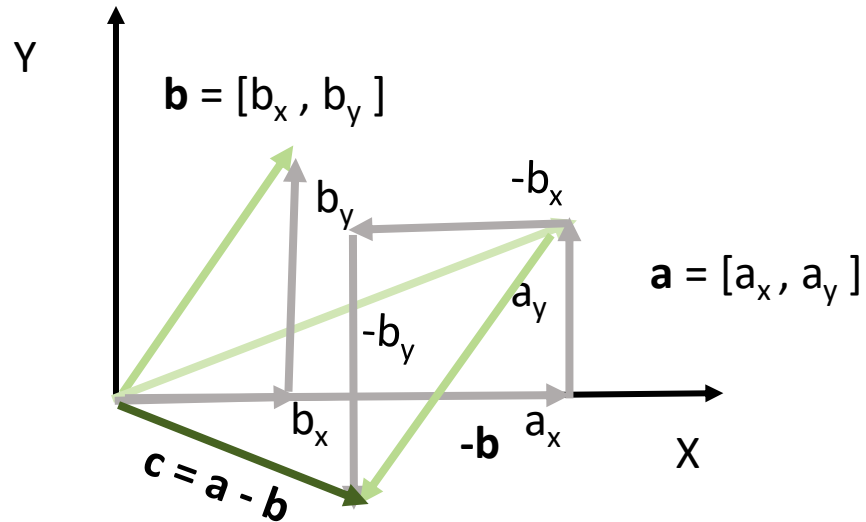
Algebraic Definition

For Multi-dimensional vectors $\mathbf{a} = [a_1, a_2, \dots, a_n]$ & $\mathbf{b} = [b_1, b_2, \dots, b_n]$

$$\mathbf{a} + \mathbf{b} = [a_1 + b_1, a_2 + b_2, \dots, a_n + b_n]$$

Vector Subtraction

How Vector Subtraction Looks Geometrically ?



For any 2D vectors \mathbf{a} , \mathbf{b}

$$\mathbf{a} - \mathbf{b} = [a_x - b_x, a_y - b_y]$$

Algebraic Definition

For Multi-dimensional vectors $\mathbf{a} = [a_1, a_2, \dots, a_n]$ & $\mathbf{b} = [b_1, b_2, \dots, b_n]$

$$\mathbf{a} - \mathbf{b} = [a_1 - b_1, a_2 - b_2, \dots, a_n - b_n]$$

Vector Addition -Examples

1. Document Addition

x : word histogram of Document 1

y : word histogram of Document 2

$x + y$: word histogram of combined Document (Using Same Dictionary)

2. Audio Addition

x : recording of voice between t_1 to t_2

y : recording of music between t_1 to t_2

$x + y$: Recording of Music and Voice together in same time

3. Image Addition

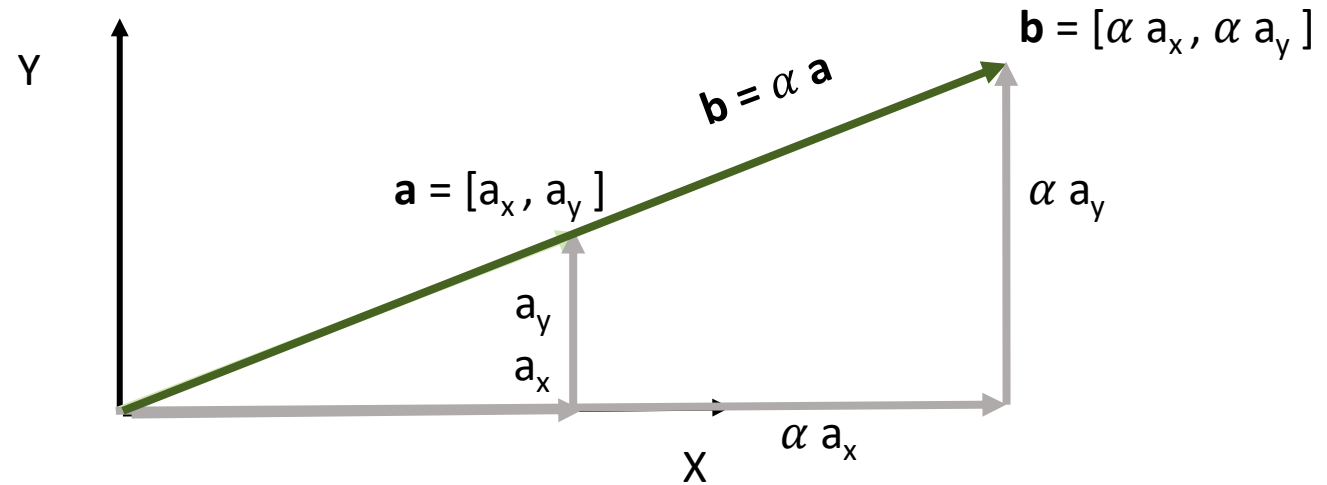
x : 1D representation of image I_1

y : 1D representation of image I_2

$x + y$: I_2 overlaid on I_1

Vector Scaling

$$(-2) \begin{bmatrix} 1 \\ 9 \\ 6 \end{bmatrix} = \begin{bmatrix} -2 \\ -18 \\ -12 \end{bmatrix}$$



Linear Combination of unit vectors :

$$\mathbf{b} = b_1 \mathbf{e}_1 + \cdots + b_n \mathbf{e}_n$$

$$\begin{bmatrix} -1 \\ 3 \\ 5 \end{bmatrix} = (-1) \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 5 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Special Linear Combinations:

Sum

$$\beta_1 = \cdots = \beta_m = 1 \Rightarrow a_1 + \cdots + a_m$$

Average

$$\beta_1 = \cdots = \beta_m = 1/m \Rightarrow (1/m)(a_1 + \cdots + a_m)$$

Affine

$$\beta_1 + \cdots + \beta_m = 1$$

Linear Combination: Examples

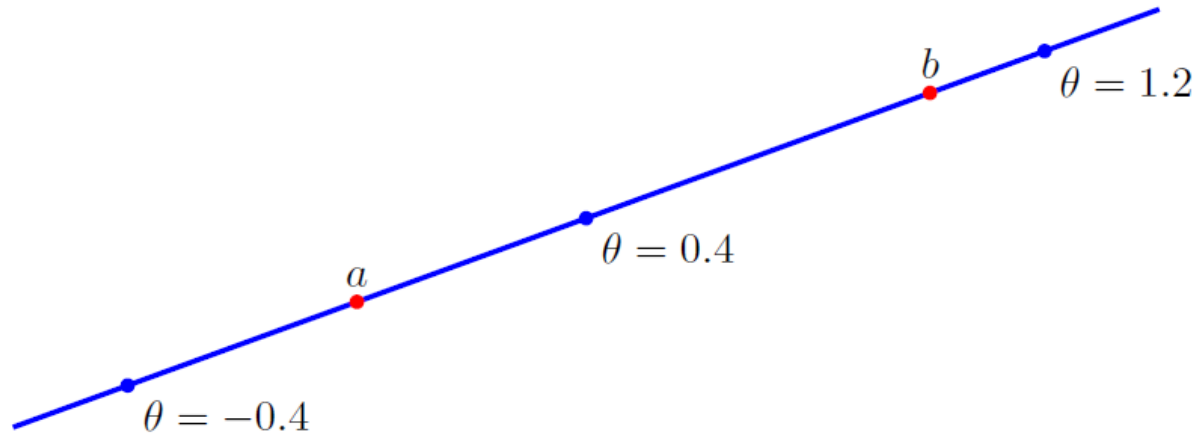
Audio Mixing:

x_1, x_2, \dots, x_n : n audio tracks $\beta_1, \beta_2, \dots, \beta_n$: mixing ratio

$\beta_1 x_1 + \beta_2 x_2 + \dots + \beta_n x_n$: mixed audio signal

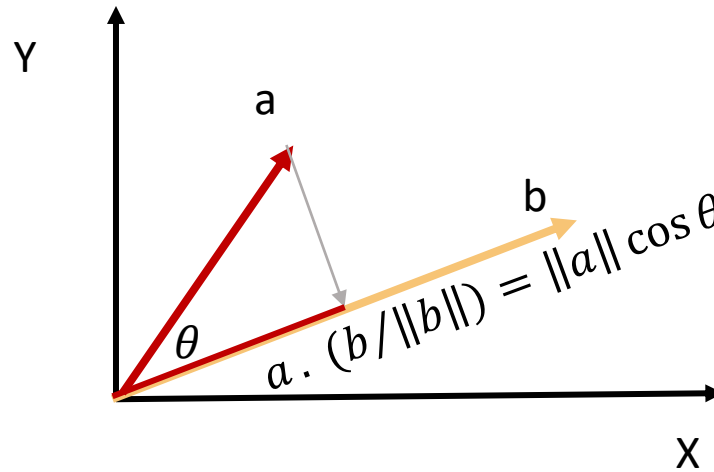
Line and Segment:

$$c = \theta a + (1 - \theta)b$$



Dot Product : Geometric Definition

$\mathbf{a} \cdot \mathbf{u}$: Amount of \mathbf{a} in the direction of unit vector $\mathbf{u} = \mathbf{b}/\|\mathbf{b}\|$



For any 2D vectors \mathbf{a} , \mathbf{b}

$$\mathbf{a} \cdot \mathbf{b} = \|\mathbf{a}\| \|\mathbf{b}\| \cos \theta$$

$\mathbf{a} \cdot \mathbf{b}$: Amount of \mathbf{a} in the direction of \mathbf{b} scaled by the value of \mathbf{b}

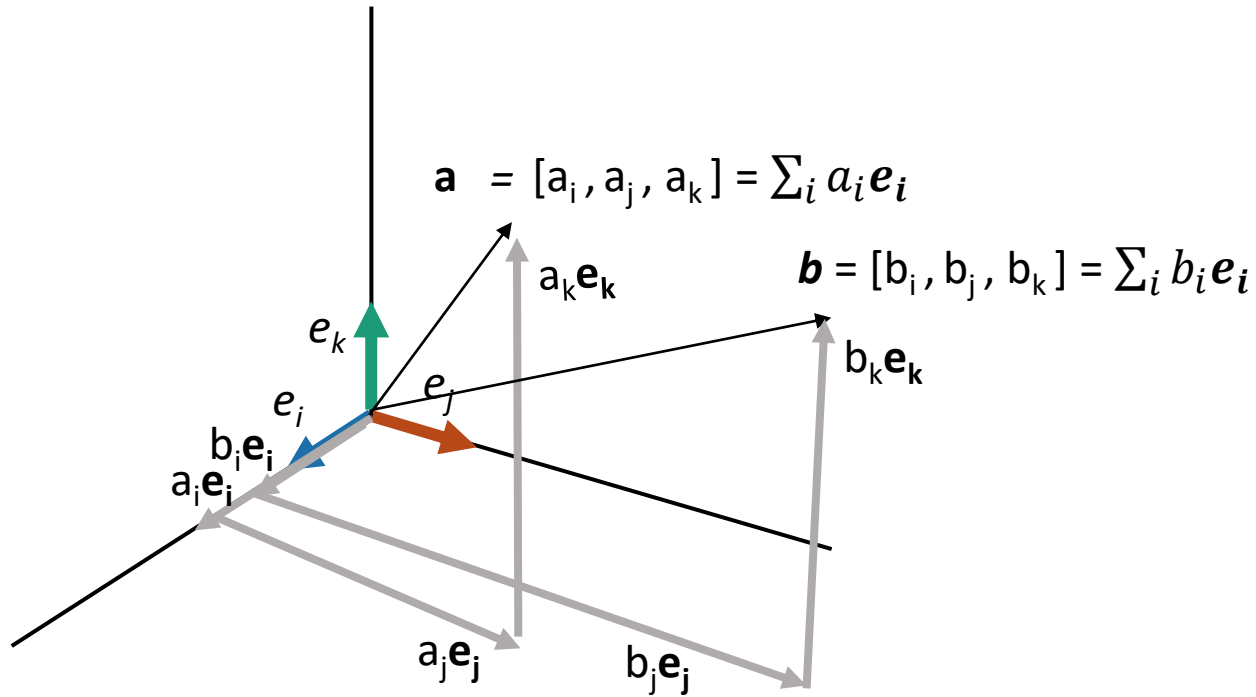
OR

Amount of \mathbf{b} in the direction of \mathbf{a} scaled by the value of \mathbf{a}

Dot Product (Inner Product) : Algebraic Definition

[Amount of \mathbf{a} in the direction of unit vector]

$$\mathbf{a} \cdot \mathbf{e}_i = a_i \quad \mathbf{a} \cdot \mathbf{e}_j = a_j$$



$$\begin{aligned} \mathbf{a} \cdot \mathbf{b} &= \mathbf{a} \cdot \sum_i b_i \mathbf{e}_i \\ &= \sum_i b_i (\mathbf{a} \cdot \mathbf{e}_i) \\ &= \sum_i b_i a_i = \sum_i a_i b_i \end{aligned}$$

Poll:

If a_1, b_1, a_2, b_2 are **any** 4 n -vectors, $a_1^T b_1 = a_2^T b_2$ implies the angle between a_1 & b_1 is same as a_2 & b_2 ?

No

Representations:

- | | |
|--------------------------|---------------------------|
| 1. $a^T b$ | 2. $\langle a, b \rangle$ |
| 3. $\langle a b \rangle$ | 4. $a \cdot b$ |

Inner Product : Examples

1. Unit Vector : $e_i^T a = a_i$

2. Sum : $\mathbf{1}^T a = a_1 + a_2 + \cdots a_n$ where $\mathbf{1} = [1, 1 \cdots, 1]$

3. Average : $(\mathbf{1}/n)^T a = (a_1 + a_2 + \cdots a_n)/n$ where $\mathbf{1}/n = [1/n, 1/n \cdots, 1/n]$

4. Sum of Squares : $a^T a = a_1^2 + a_2^2 + \cdots a_n^2$

5. Block Vectors:

$$a^T b = \begin{bmatrix} a_1 \\ \vdots \\ a_k \end{bmatrix}^T \begin{bmatrix} b_1 \\ \vdots \\ b_k \end{bmatrix} = a_1^T b_1 + \cdots + a_k^T b_k$$

Inner Product : Applications

1. Co-occurrence:

a : indicates membership, Set A

b : indicates membership, Set B

$a^T b$: # of elements in $A \cap B$

$$a = (0, 1, 1, 1, 1, 1, 1) \quad b = (1, 0, 1, 0, 1, 0, 0) \quad a^T b = 2$$

2. Score:

f : set of features of an object

w : weight of each feature

Example: *Document Sentiment Analysis*

f : histogram from vocabulary of size n

$w^T f$: score for the object based on the importance of each feature

$w: \{-1, 0, 1\}^n$

3. Polynomial Evaluation:

$$p(x) = c_1 + c_2x + \cdots + c_{n-1}x^{n-2} + c_nx^{n-1}$$

c : coefficients of the polynomial

$$c^T z = p(t)$$

$$z = (1, t, t^2, \dots, t^{n-1})$$