Linear Algebra & Convex Optimization – Lecture 13

Lagrange Method

Convex Optimization Formulation

General Optimization Formulation:

minimize
$$f_0(x)$$

subject to $f_i(x) \leq 0, \quad i = 1, \dots, m$
 $h_i(x) = 0, \quad i = 1, \dots, p$

Convex Optimization Formulation:

minimize
$$f_0(x)$$

subject to $f_i(x) \leq 0, \quad i = 1, \dots, m$
 $a_i^T x = b_i, \quad i = 1, \dots, p$

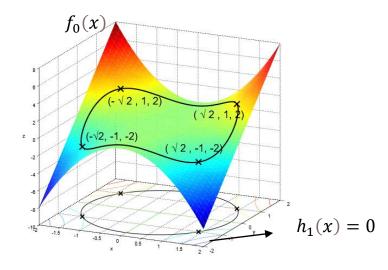
 f_0 , f_1 , . . . , f_m are convex; equality constraints are affine

Feasible region of a convex optimization problem is convex

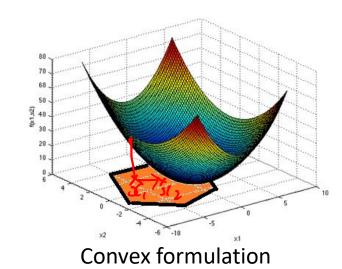
Alternative way of writing:

minimize
$$f_0(x)$$

subject to $f_i(x) \le 0, \quad i = 1, \dots, m$
 $Ax = b$



Poll: Suppose we consider $f_0(x)$ that is convex, will the above formulation convex ? Yes/No



Lagrangian Function

$$Solution J(\alpha) = P^{\ddagger}$$

standard form problem (not necessarily convex):

$$\begin{array}{ll} \text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0, \quad i=1,\ldots,m \\ & h_i(x)=0, \quad i=1,\ldots,p \end{array}$$

$$\underline{x} \in \underline{\mathbf{R}^n}$$

$$\mathcal{D} = \bigcap_{i=0}^m \mathrm{dom}\, f_i \ \cap \ \bigcap_{i=1}^p \mathrm{dom}\, h_i$$
 optimal value p^\star

Lagrangian: $L: \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^p \to \mathbb{R}$, with $\operatorname{dom} L = \mathcal{D} \times \mathbb{R}^m \times \mathbb{R}^p$,

$$L(\underline{x}, \underline{\lambda}, \underline{\nu}) = f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \nu_i h_i(x)$$

weighted sum of objective and constraint functions

 λ_i is Lagrange multiplier associated with $f_i(x) \leq 0$

 ν_i is Lagrange multiplier associated with $h_i(x) = 0$

Lagrange Dual Function

Lagrange dual function: $g: \mathbb{R}^m \times \mathbb{R}^p \to \mathbb{R}$,

$$g(\underline{\lambda}, \underline{\nu}) = \inf_{x \in \mathcal{D}} L(\underline{x}, \lambda, \underline{\nu})$$

$$= \inf_{x \in \mathcal{D}} \left(f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \nu_i h_i(x) \right)$$

g is concave as it is point-wise infimum of family of affine functions in (λ, v)

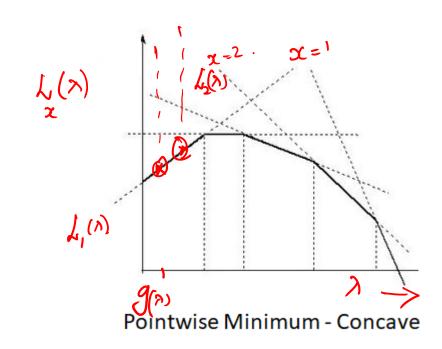
Proof:

Consider a slight change of notation
$$L_x(\xi) = L(x, \lambda, \nu)$$
 where $\xi = (\lambda, \nu)$

For a fixed x, $L_x(\xi)$ is affine in $\xi \implies \{L_x(\xi): x \in D\}$ is a family of affine functions

 $g(\xi) = \inf_{x} \{ L_{x}(\xi) : x \in D \}$ is point-wise infimum on a family of affine functions

Hence $g(\xi) = g(\lambda, v)$ is concave



Lagrange dual function in Lagrange variables is concave irrespective of the original functions

Lagrange Dual Function: Lower Bound Property

Standard Form Problem (optimal value p*):

minimize
$$f_0(x)$$
 subject to $f_i(x) \leq 0, \quad i=1,\ldots,m$
$$h_i(x) = 0, \quad i=1,\ldots,p$$

$$\text{problem}$$

if $\lambda \succeq 0$, then $g(\lambda, \nu) \leq p^*$

Proof:

$$\tilde{x}$$
 is a feasible point \Box

$$f_i(\tilde{x}) \le 0$$

$$h_i(\tilde{x}) = 0$$

Lagrange Dual Function:

$$g(\lambda, \nu) = \inf_{x \in \mathcal{D}} \left(f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \nu_i h_i(x) \right)$$

$$N \geq 0$$

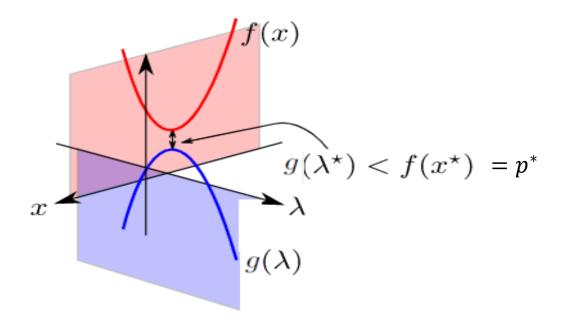
$$\tilde{x}$$
 is a feasible point \Rightarrow $f_i(\tilde{x}) \leq 0$ $h_i(\tilde{x}) = 0$ \Rightarrow $\sum_{i=1}^m \lambda_i f_i(\tilde{x}) + \sum_{i=1}^p \nu_i h_i(\tilde{x}) \leq 0$,

$$L(\tilde{x}, \lambda, \nu) = f_0(\tilde{x}) + \sum_{i=1}^{m} \lambda_i f_i(\tilde{x}) + \sum_{i=1}^{p} \nu_i h_i(\tilde{x}) \le f_0(\tilde{x})$$

$$g(\lambda, \nu) = \inf_{x \in \mathcal{D}} L(x, \lambda, \nu) \le L(\tilde{x}, \lambda, \nu) \le f_0(\tilde{x})$$

Lagrange Dual Function: Illustration

Combined graph depiction of Dual and Original Problems



Lagrange Dual Optimization Problem

$$\begin{array}{ll} \text{maximize} & g(\lambda,\nu) \\ \text{subject to} & \lambda \succeq 0 \end{array}$$

Dual problem is a convex optimization problem

Dual problem has a global maximum, $\,d^*$, even if original problem is non-convex

Dual problem find best lower bound on primal problem's optimal value, p^*

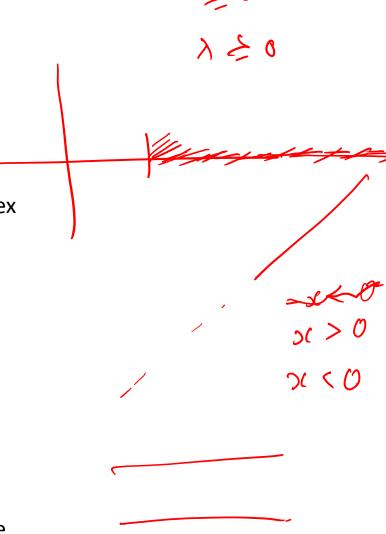
 λ, v are dual feasible if , $\lambda \geq 0$, $(\lambda, v) \in \operatorname{dom} g$

Weak Duality:

$$d^{\star} \leq p^{\star}$$

$$p^\star = -\infty \implies d^\star = -\infty \implies \text{Lagrangian dual problem is infeasible}$$

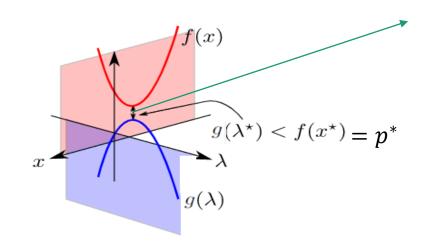
$$d^\star = \infty$$
 \Longrightarrow $p^\star = \infty$ \Longrightarrow Primal problem is infeasible



Strong Duality

Strong duality: $d^* = p^*$

Does not hold in general; holds for convex problems



Primal – Dual Gap

Primal & Dual Problems

Primal – Dual Gap is zero for strong duality

Complementary Slackness

YER"

Assume strong duality holds for the given problem ::

minimize
$$f_0(x)$$

subject to $f_i(x) \leq 0, \quad i = 1, \dots, m$
 $h_i(x) = 0, \quad i = 1, \dots, p$

$$x^{\star}$$
 is primal optimal

$$x^{\star}$$
 is primal optimal $(\lambda^{\star}, \nu^{\star})$ is dual optimal

$$\mathcal{L}(x,\lambda^*,v^*)$$

$$f_0(x^*) = g(\lambda^*, \nu^*) = \inf_x \left(f_0(x) + \sum_{i=1}^m \lambda_i^* f_i(x) + \sum_{i=1}^p \nu_i^* h_i(x) \right)$$

$$f_0(x^\star) + \sum_{i=1}^m \lambda_i^\star f_i(x^\star) + \sum_{i=1}^p \nu_i^\star h_i(x^\star)$$

$$f_0(x^\star) \qquad \text{The 2 inequalities can be replaced with equalities}$$

This Implies:

- x^* minimizes $L(x, \lambda^*, \nu^*)$
 - $\lambda_i^{\star} f_i(x^{\star}) = 0$ for $i = 1, \dots, m$ (known as complementary slackness)

$$\lambda_i^{\star} > 0 \Longrightarrow f_i(x^{\star}) = 0, \ f_i(x^{\star}) < 0 \Longrightarrow \lambda_i^{\star} = 0$$

Gradient of $L(x, \lambda^*, \nu^*)$ evaluated at x^* is zero, $\nabla L(x^*, \lambda^*, \nu^*) = 0$.

KKT (Karush-Kuhn-Tucker) Conditions

minimize $f_0(x)$ subject to $f_i(x) \leq 0, \quad i = 1, \dots, m$ $h_i(x) = 0, \quad i = 1, \dots, p$

For Convex Problems: KKT conditions are sufficient for strong duality

Any pair of primal & dual points that satisfy KKT conditions are optimal points and have zero duality gap

$$f_i(x^*) \leq 0, \quad i = 1, \dots, m$$

$$h_i(x^*) = 0, \quad i = 1, \dots, p$$

$$\lambda_i^* \geq 0, \quad i = 1, \dots, m$$

$$\lambda_i^* f_i(x^*) = 0, \quad i = 1, \dots, m$$

$$\nabla f_0(x^*) + \sum_{i=1}^m \lambda_i^* \nabla f_i(x^*) + \sum_{i=1}^p \nu_i^* \nabla h_i(x^*) = 0.$$

In a few special cases, KKT conditions can be solved analytically to obtain the solution.

Lagrange Method: Least Norm

Least Norm solution with Constraints:

minimize
$$x^Tx$$
 $A \in \mathbf{R}^{p \times n}$ subject to $Ax = b$ $\{ \ x \mid Ax = b \ \} = \{ \ x_p + z \mid z \in \mathcal{N}(A) \ \}$

Lagrangian: $L(x,\nu) = x^T x + \nu^T (Ax - b)$ Domain: $\mathbf{R}^n \times \mathbf{R}^p$

$$\nabla_{x}L(x, v^*) = 2x + \underline{A^Tv^*}$$

$$\nabla_{x}L(x, v^{*}) = 0$$
 at $x = x^{*}$

$$2x^* + A^T v^* = 0 \implies x^* = (-1/2)A^T v^*$$

KKT conditions:
$$\nabla_{x}L(x, v^{*}) = 2x + \underline{A^{T}v^{*}}$$

$$\nabla_{x}L(x, v^{*}) = 0 \text{ at } x = x^{*}$$

$$rac{\partial \mathbf{x}^{ op} \mathbf{A} \mathbf{x}}{\partial \mathbf{x}} = \left(\mathbf{A} + \mathbf{A}^{ op}
ight) \mathbf{x}$$

$$\frac{\partial \mathbf{A} \mathbf{x}}{\partial \mathbf{x}} = \mathbf{A}^{\top}$$

Solution:

Solve for $Ax^* = b$ & $x^* = (-1/2)A^T\underline{v}^*$ together

$$-\frac{1}{2}AA^{T}v^{*} = b$$
 $v^{*} = -2(AA^{T})^{-1}b$

This gives,
$$x^* = A^T (AA^T)^{-1}b$$

 $x = (A^T A)^{-1} A^T b$ is the least square solution (For Tall A)

Lagrange Method: Constrained Least Squares

Least Squares solution of linear equations:

minimize
$$||Ax - b||^2$$

subject to $Cx = d$. $(Lx, \sqrt{)} = J((x^TA^T - b^T)(Ax - b))$
 $J(Lx, \sqrt{)} = J((x^TA^T - b^T)(Ax - b))$

Lagrangian: $L(x, v) = (Ax - b)^T (Ax - b) + v^T (Cx - d)$

KKT conditions:

$$\nabla_{x}(L(x,v^*)) = 2A^TAx - 2A^Tb + C^Tv^*$$

$$\nabla_{\mathbf{x}} L(\mathbf{x}, \mathbf{v}^*) = 0$$
 at $\mathbf{x} = \mathbf{x}^*$

$$2A^TAx^* - 2A^Tb + C^Tv^* = 0 \quad - \bigcirc$$

Solution:

Solve for
$$x^* \& v^*$$
 together as $\begin{bmatrix} x^* \\ v^* \end{bmatrix} = \begin{bmatrix} 2A^TA & C^T \\ C & 0 \end{bmatrix}^{-1} \begin{bmatrix} 2A^Tb \\ d \end{bmatrix}$

KKT Matrix

KKT Matrix is square and is invertible, if solution exists

Constrained Least Squares: Advertising Purchase Example

- *m* demographic groups of audiences
- *n* number channels to advertise
- $m \times n$ Matrix R represents the 'Available Data' on Ad views per dollar spent
- v^{des} is the desired viewership from each channel
- n vector s is the dollars invested in each channel for advertisement
- m vector Rs = v gives the total viewership from each demographic group

Unconstrained Objective:

Find
$$\hat{s}$$
 that minimizes $\|Rs - v^{des}\|^2$

$$\hat{s} = \begin{bmatrix} 62\\100\\1443 \end{bmatrix}$$

Total Dollars to be spent is 1605

Constrained Objective:

minimize
$$||Rs - v^{\text{des}}||^2$$

subject to $\mathbf{1}^T s = B$.

B is the total budget available

Actual budget available is 20% less i.e. B = 1284

Solving constrained least squares, we get

$$\hat{s} = \begin{bmatrix} 315 \\ 110 \\ 859 \end{bmatrix}$$

