

# ShritejShrikant\_Chavan\_HW\_4

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## 1 Load Libraries/Install Software

[ ]:

```
[39]: if 'google.colab' in str(get_ipython()):
      from google.colab import drive
      drive.mount('/content/drive')

      !pip install torchtext --upgrade -qq
      !pip install torchmetrics -qq
      !pip install torchinfo -qq
      !pip install fast_ml -qq
      !pip install joblib -qq
      !pip install sklearn -qq
      !pip install pandas -qq
      !pip install numpy -qq
      !pip install scikit-multilearn -qq
      !pip install transformers evaluate wandb accelerate -U -qq

      basepath = '/content/drive/MyDrive/NLP'

  else:
      basepath = '/home/harpreet/Insync/google_drive_shaanloor/data'
```

Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", force\_remount=True).

```
7.6/7.6 MB
71.2 MB/s eta 0:00:00
81.4/81.4 kB
10.9 MB/s eta 0:00:00
2.1/2.1 MB
87.9 MB/s eta 0:00:00
258.1/258.1 kB
28.9 MB/s eta 0:00:00
294.9/294.9 kB
32.3 MB/s eta 0:00:00
7.8/7.8 MB
111.4 MB/s eta 0:00:00
```

```

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46.4 MB/s eta 0:00:00
115.3/115.3 kB
15.8 MB/s eta 0:00:00
194.1/194.1 kB
21.3 MB/s eta 0:00:00
134.8/134.8 kB
18.1 MB/s eta 0:00:00
190.0/190.0 kB
24.4 MB/s eta 0:00:00
224.8/224.8 kB
24.3 MB/s eta 0:00:00
Preparing metadata (setup.py) ... done
62.7/62.7 kB
8.8 MB/s eta 0:00:00
Building wheel for pathtools (setup.py) ... done

```

```

[133]: # Importing PyTorch library for tensor computations and neural network modules
import torch
import torch.nn as nn
import torch.nn.functional as F

# For working with textual data vocabularies and for displaying model summaries
from torchtext.vocab import vocab
from torchinfo import summary

# General-purpose Python libraries for random number generation and numerical
↳operations
import random
import numpy as np

# Utilities for efficient serialization/deserialization of Python objects and
↳for element tallying
import joblib
from collections import Counter

# For creating lightweight attribute classes and for partial function
↳application
from types import SimpleNamespace
from functools import partial

# For filesystem path handling, generating and displaying confusion matrices,
↳and date-time manipulations
from pathlib import Path
from sklearn.metrics import confusion_matrix, ConfusionMatrixDisplay

```

```

from datetime import datetime

# For plotting and visualization
import matplotlib.pyplot as plt

import ast
from sklearn.preprocessing import MultiLabelBinarizer
from fast_ml.model_development import train_valid_test_split
from skmultilearn.model_selection import iterative_train_test_split
import pandas as pd

# For creating lightweight attribute classes and for partial function
↳ application
from types import SimpleNamespace
from functools import partial

# Import HammingDistance from torchmetrics
# HammingDistance is useful for evaluating multi-label classification problems.
from torchmetrics import HammingDistance

from torch.nn.utils import clip_grad_value_

from sklearn.metrics import accuracy_score, multilabel_confusion_matrix,
↳ classification_report

```

## 2 Specify Project Folders

```

[134]: base_folder = Path(basepath)
data_folder = base_folder / 'datasets/hw4'
model_folder = base_folder / 'models/nlp_spring_2023/hw4'
custom_functions = base_folder / 'custom-functions'

```

## 3 Load Dataset

```

[135]: X_train_cleaned_file = data_folder / 'df_multilabel_hw_cleaned.joblib'

data = joblib.load(X_train_cleaned_file)

```

```

[136]: type(data)

```

```

[136]: pandas.core.frame.DataFrame

```

```

[137]: data.head()

```

```
[137]:
```

	cleaned_text	Tags \
0	asp query stre dropdown webpage follow control...	c# asp.net
1	run javascript code server java code want run ...	java javascript
2	linq sql throw exception row find change hi li...	c# asp.net
3	run python script php server run nginx web ser...	php python
4	advice write function m try write function res...	javascript jquery

```

Tag_Number
0      [0, 9]
1      [1, 3]
2      [0, 9]
3      [2, 7]
4      [3, 5]

```

```
[138]: data.shape
```

```
[138]: (47427, 3)
```

```
[139]: data.info()
```

```

<class 'pandas.core.frame.DataFrame'>
RangeIndex: 47427 entries, 0 to 47426
Data columns (total 3 columns):
#   Column          Non-Null Count  Dtype
---  -
0   cleaned_text    47427 non-null  object
1   Tags            47427 non-null  object
2   Tag_Number      47427 non-null  object
dtypes: object(3)
memory usage: 1.1+ MB

```

```
[140]: data.describe()
```

```
[140]:
```

	cleaned_text	Tags \
count	47427	47427
unique	36481	176
top	cause error targetcontrolid valid value null...	javascript jquery
freq	3	19989

```

Tag_Number
count      47427
unique      176
top         [3, 5]
freq       19989

```

```
[141]: data.dtypes
```

```
[141]: cleaned_text    object
      Tags            object
      Tag_Number      object
      dtype: object
```

```
[142]: data.isna().sum()
```

```
[142]: cleaned_text    0
      Tags            0
      Tag_Number      0
      dtype: int64
```

```
[143]: type(data['cleaned_text'][3])
```

```
[143]: str
```

```
[144]: arr = []

      x = []

      for i in range(data.shape[0]):
          arr.append(ast.literal_eval(data['Tag_Number'][i]))
          x.append(str(data['cleaned_text'][i]))

      x = np.array(x).reshape(-1,1)
```

```
[145]: x[1]
```

```
[145]: array(['run javascript code server java code want run javascript code server
      want manipulate result return javascript inside java code'],
      dtype='<U30141')
```

```
[146]: mlb = MultiLabelBinarizer()

      y = mlb.fit_transform(arr)

      print(type(y) , y.shape)
      print(type(x) , x.shape)
```

```
<class 'numpy.ndarray'> (47427, 10)
<class 'numpy.ndarray'> (47427, 1)
```

## 4 Data Split

iterative-stratification iterative-stratification is a project that provides scikit-learn compatible cross validators with stratification for multilabel data.

Presently scikit-learn provides several cross validators with stratification. However, these cross validators do not offer the ability to stratify multilabel data. This iterative-stratification project offers implementations of MultilabelStratifiedKFold, MultilabelRepeatedStratifiedKFold, and MultilabelStratifiedShuffleSplit with a base algorithm for stratifying multilabel data described in the following paper:

Sechidis K., Tsoumakas G., Vlahavas I. (2011) On the Stratification of Multi-Label Data. In: Gunopulos D., Hofmann T., Malerba D., Vazirgiannis M. (eds) Machine Learning and Knowledge Discovery in Databases. ECML PKDD 2011. Lecture Notes in Computer Science, vol 6913. Springer, Berlin, Heidelberg.

```
[147]: X_train, y_train, X_test, y_test = iterative_train_test_split(X = x, y = y ,  
    ↪test_size = 0.4)  
  
X_valid, y_valid, X_test, y_test = iterative_train_test_split(X_test, y_test ,  
    ↪test_size = 0.5)  
  
# X_train, y_train, X_valid, y_valid, X_test, y_test =  
    ↪train_valid_test_split(data['cleaned_text'], y ,  
#  
    ↪train_size=0.6, valid_size=0.2, test_size=0.2, random_state=42,  
#  
    ↪shuffle=True, stratify=y)
```

## 5 Custom Dataset Class

```
[148]: class CustomDataset(torch.utils.data.Dataset):  
    """  
    Custom Dataset class for loading IMDB reviews and labels.  
  
    Attributes:  
        X (numpy.ndarray): Feature data, an array of texts.  
        y (list or array-like): Target labels.  
    """  
  
    def __init__(self, X, y):  
        """  
        Initialize the dataset with feature and target data.  
  
        Args:  
            X (list or array-like): The feature data (texts).  
            y (list or array-like): The target labels.
```

```

        """
        # Converting the feature data to a NumPy array for consistency
        self.X = np.array(X)

        # Storing the target labels
        self.y = y

    def __len__(self):
        """
        Return the number of samples in the dataset.

        Returns:
            int: The total number of samples.
        """
        return len(self.X)

    def __getitem__(self, idx):
        """
        Fetch and return a single sample from the dataset at the given index.

        Args:
            idx (int): Index of the sample to fetch.

        Returns:
            tuple: A tuple containing the label and the text for the sample.
        """
        # Retrieve the text and corresponding label from the dataset using the
        ↪ index
        texts = self.X[idx][0]
        labels = self.y[idx]

        # Packing them into a tuple before returning
        sample = (labels, texts)

        return sample

```

```

[149]: trainset = CustomDataset(X_train, y_train)
       validset = CustomDataset(X_valid, y_valid)
       testset = CustomDataset(X_test, y_test)

```

```

[150]: trainset[3][1]

```

```

[150]: 'php page redirect operation page php grid subpages(<<1,2,3,4 > > operation page
take $ get[\`prd_p $ request[\`prd_p give page number want user stay page
operation mean use redirect < form name="frmsearchme action="<?php echo $
page_name > method="post > < tr > < input class=\'form_button type=\'submit
name=\'btnsubmit value= save onclick=\'return checkerrors /></td > < /tr >

```

```
//php code < /form > '
```

## 5.1 Create Vocab

```
[151]: def get_vocab(dataset, min_freq=1):  
        """  
        Generate a vocabulary from a dataset.  
  
        Args:  
            dataset (list of tuple): List of tuples where each tuple contains a  
            ↪label and a text.  
            min_freq (int): The minimum frequency for a token to be included in the  
            ↪vocabulary.  
  
        Returns:  
            torchtext.vocab.Vocab: Vocabulary object.  
        """  
        # Initialize a counter object to hold token frequencies  
        counter = Counter()  
  
        # Update the counter with tokens from each text in the dataset  
        for (l_, text) in dataset:  
            counter.update(str(text).split())  
  
        # Create a vocabulary using the counter object  
        # Tokens that appear fewer times than `min_freq` are excluded  
        my_vocab = vocab(counter, min_freq=min_freq)  
  
        # Insert a '<unk>' token at index 0 to represent unknown words  
        my_vocab.insert_token('<unk>', 0)  
  
        # Set the default index to 0  
        # This ensures that any unknown word will be mapped to '<unk>'  
        my_vocab.set_default_index(0)  
  
        return my_vocab
```

```
[152]: lang_vocab = get_vocab(trainset, min_freq=2)
```

```
[153]: len(lang_vocab)
```

```
[153]: 90146
```

```
[154]: lang_vocab.get_itos()[0:5]
```

```
[154]: ['<unk>', 'asp', 'query', 'stre', 'dropdown']
```



[154]:

## 5.2 Collate\_fn for Data Loaders

```
[155]: # Creating a function that will be used to get the indices of words from vocab
def text_pipeline(x, vocab):
    """Converts text to a list of indices using a vocabulary dictionary"""
    return [vocab[token] for token in str(x).split()]
```

```
[156]: def collate_batch(batch, my_vocab):
    """
    Collates a batch of samples into tensors of labels, texts, and offsets.

    Parameters:
        batch (list): A list of tuples, each containing a label and a text.

    Returns:
        tuple: A tuple containing three tensors:
            - Labels tensor
            - Concatenated texts tensor
            - Offsets tensor indicating the start positions of each text in
↳the concatenated tensor
    """
    # Unpack the batch into separate lists for labels and texts
    labels, texts = zip(*batch)

    # Convert the list of labels into a tensor of dtype int32
    labels = torch.tensor(labels, dtype=torch.float32)

    # Convert the list of texts into a list of lists; each inner list contains
↳the vocabulary indices for a text
    list_of_list_of_indices = [text_pipeline(text, my_vocab) for text in texts]

    # Compute the offsets for each text in the concatenated tensor
    offsets = [0] + [len(i) for i in list_of_list_of_indices]
    offsets = torch.tensor(offsets[:-1]).cumsum(dim=0)

    # Concatenate all text indices into a single tensor
    texts = torch.cat([torch.tensor(i, dtype=torch.int64) for i in
↳list_of_list_of_indices])

    return (texts, offsets), labels
```

## 5.3 Check Data Loaders

Let us check if our collate function is working by creating a dataloader

```
[157]: batch_size = 2
check_loader = torch.utils.data.DataLoader(dataset=trainset,
                                             batch_size=batch_size,
                                             shuffle=True,
                                             collate_fn=partial(collate_batch,
↪my_vocab = lang_vocab),
                                             )
```

```
[158]: torch.manual_seed(22)
for (text, offset), label in check_loader:
    print(text, offset, label)
    break
```

```
tensor([ 158,  100,  494,  123,  915,  949,   60, 1098, 2381,   53,
         6,  100,  301,   29,  495,   34,   29,  682, 3798,   34,
        29,  450,   0,   34,   29,  450, 60285,   34,   29, 2340,
        34,   29,  682, 3798,   34,   29,  450,   0,   34,   29,
       450,   0,   34,   29, 2340,   34,   29,  682, 3798,   34,
        29,  450,   0,   34,   29,  450,   0,   34,   29, 2340,
        34,   29,  682, 3798,   34,   29,  450,   0,   34,   29,
       450, 60285,   34,   29, 2340,   34,   29,  685,   34,   19,
       682,  123,  915, 3495, 1098,   53,  230,   26,  235, 8413,
        50,  486,   47,  873,  388,  542,  826,  102,  388,  858,
       259, 9392, 2746,  542,  388,  542, 1565,  388,  858, 1172,
      8902, 3127, 1524,  387,    0, 35886,  387,  594,    0,  496,
       570, 1109,   51,    0, 35886,  704, 1565,  858,  551,  388,
      219]) tensor([ 0, 91]) tensor([[0., 0., 0., 1., 0., 1., 0., 0., 0.,
0.],
      [1., 1., 0., 0., 0., 0., 0., 0., 0., 0.]])
```

## 6 Model

embedding\_layer->linear-> ReLU ->dropout -> batch norm -> linear->ReLU->Dropout->  
batchnorm -> linear layer

```
[159]: from transformers.modeling_outputs import SequenceClassifierOutput
from transformers import PreTrainedModel, PretrainedConfig
import torch
import torch.nn as nn
```

```
[160]: class CustomConfig(PretrainedConfig):
    def __init__(self, vocab_size=0, embedding_dim=0, hidden_dim1=0,
↪hidden_dim2=0, num_labels=0, **kwargs):
        super().__init__()
        self.vocab_size = vocab_size
        self.embedding_dim = embedding_dim
        self.hidden_dim1 = hidden_dim1
```

```

self.hidden_dim2 = hidden_dim2
self.num_labels = num_labels

```

```

[161]: class CustomMLP(PreTrainedModel):
        # config_class = CustomConfig

        def __init__(self, config):
            super().__init__(config)

            self.embedding_bag = nn.EmbeddingBag(config.vocab_size, config.
↪embedding_dim)

            self.layers = nn.Sequential(
                nn.Linear(config.embedding_dim, config.hidden_dim1),
                nn.BatchNorm1d(num_features=config.hidden_dim1),
                nn.ReLU(),
                nn.Dropout(p=0.5),
                nn.Linear(config.hidden_dim1, config.hidden_dim2),
                nn.BatchNorm1d(num_features=config.hidden_dim2),
                nn.ReLU(),
                nn.Dropout(p=0.5),
                nn.Linear(config.hidden_dim2, config.num_labels)
            )

        def forward(self, input_ids, offsets, labels=None):
            embed_out = self.embedding_bag(input_ids, offsets)
            logits = self.layers(embed_out)

            loss = None
            if labels is not None:
                loss_fct = nn.BCEWithoutLogitsLoss()
                loss = loss_fct(logits.view(-1, self.config.num_labels), labels.
↪view(-1))

            return SequenceClassifierOutput(
                loss=loss,
                logits=logits
            )

```

## 7 Hyperparameters

```

[162]: hyperparameters = SimpleNamespace(
        # model Parameters
        EMBED_DIM=300,
        VOCAB_SIZE=len(lang_vocab),
        OUTPUT_DIM=10,
        HIDDEN_DIM1=200,

```

```

HIDDEN_DIM2=100,

# training
EPOCHS=5,
BATCH_SIZE=128,
LEARNING_RATE=0.001,
WEIGHT_DECAY=0.0001,
CLIP_TYPE='value',
CLIP_VALUE=10,
PATIENCE=5,

# data
)

collate_fn = partial(collate_batch, my_vocab=lang_vocab)

```

```

[163]: class CustomBlock(nn.Module):
        def __init__(self, input_dim, output_dim, drop_prob):

            super().__init__()

            self.layers = nn.Sequential(
                nn.Linear(input_dim, output_dim),
                nn.BatchNorm1d(num_features=output_dim),
                nn.ReLU(),
                nn.Dropout(p=drop_prob),

            )

        def forward(self, x):
            return self.layers(x)

```

```

[164]: class EmbeddingBagWrapper(nn.Module):
        def __init__(self, vocab_size, embedding_dim):
            super().__init__()
            self.embedding_bag = nn.EmbeddingBag(vocab_size, embedding_dim)

        def forward(self, input_tuple):
            data, offsets = input_tuple
            return self.embedding_bag(data, offsets)

# Define the sequential model
vocab_size = len(lang_vocab)
embed_dim = hyperparameters.EMBED_DIM
model_embedding_1 = nn.Sequential(
    EmbeddingBagWrapper(vocab_size, embed_dim ),
    CustomBlock(embed_dim , hyperparameters.HIDDEN_DIM1, 0.5),
    CustomBlock(hyperparameters.HIDDEN_DIM1, hyperparameters.HIDDEN_DIM2, 0.5),

```

```
nn.Linear(hyperparameters.HIDDEN_DIM2, hyperparameters.OUTPUT_DIM)
)
```

```
[165]: # Define the device
device = torch.device('cuda:0' if torch.cuda.is_available() else 'cpu')

# Move the model to the device
model_embedding_1 = model_embedding_1.to(device)

# Generate some dummy input data and offsets, and move them to the device
data = torch.LongTensor([1, 2, 4, 5, 4]).to(device)
offsets = torch.LongTensor([0, 2, 4]).to(device)

# Generate summary
summary(model_embedding_1, input_data=[(data, offsets)], device=device)
```

```
[165]: =====
=====
Layer (type:depth-idx)                Output Shape                Param #
=====
=====
Sequential                            [3, 10]                     --
  EmbeddingBagWrapper: 1-1             [3, 300]                    --
    EmbeddingBag: 2-1                 [3, 300]                    27,043,800
  CustomBlock: 1-2                    [3, 200]                    --
    Sequential: 2-2                   [3, 200]                    --
      Linear: 3-1                     [3, 200]                    60,200
      BatchNorm1d: 3-2                [3, 200]                    400
      ReLU: 3-3                      [3, 200]                    --
      Dropout: 3-4                   [3, 200]                    --
  CustomBlock: 1-3                    [3, 100]                    --
    Sequential: 2-3                   [3, 100]                    --
      Linear: 3-5                     [3, 100]                    20,100
      BatchNorm1d: 3-6                [3, 100]                    200
      ReLU: 3-7                      [3, 100]                    --
      Dropout: 3-8                   [3, 100]                    --
  Linear: 1-4                         [3, 10]                     1,010
=====
=====
Total params: 27,125,710
Trainable params: 27,125,710
Non-trainable params: 0
Total mult-adds (M): 81.38
=====
=====
Input size (MB): 0.00
Forward/backward pass size (MB): 0.02
```

Params size (MB): 108.50  
Estimated Total Size (MB): 108.52

=====  
=====

```
[166]: # Test the model
# Move the model to the device
model_embedding_1 = model_embedding_1.to(device)

# Generate some dummy input data and offsets, and move them to the device
# we will pass text as input, collate function will create data and offsets
data = torch.LongTensor([1, 2, 4, 5, 4]).to(device)
offsets = torch.LongTensor([0, 2, 4]).to(device)

# Since nn.Sequential expects a single input, we pack data and offsets into a
↳tuple
output = model_embedding_1((data, offsets))

print(output)
```

```
tensor([[ 1.0477, -0.3162, -1.4045, -0.2548, -0.9364, -0.3623, -0.2632, -0.2217,
         -0.3958,  0.9847],
        [ 0.5110,  0.2843,  0.4339, -0.7888,  0.2140,  0.1882,  0.2605,  0.0651,
         -0.4568,  0.4220],
        [-0.0763,  1.2264, -0.7943, -0.1306,  1.3449,  0.7397, -0.8203, -2.4401,
          0.0569, -0.0226]], device='cuda:0', grad_fn=<AddmmBackward0>)
```

## 7.1 Step Function

```
[168]: def step(inputs, targets, model, device, loss_function=None, optimizer=None):
        """
        Performs a forward and backward pass for a given batch of inputs and
        ↳targets.

        Parameters:
        - inputs (torch.Tensor): The input data for the model.
        - targets (torch.Tensor): The true labels for the input data.
        - model (torch.nn.Module): The neural network model.
        - device (torch.device): The computing device (CPU or GPU).
        - loss_function (torch.nn.Module, optional): The loss function to use.
        - optimizer (torch.optim.Optimizer, optional): The optimizer to update
        ↳model parameters.

        Returns:
        - loss (float): The computed loss value (only if loss_function is not None).
        - outputs (torch.Tensor): The predictions from the model.
        - correct (int): The number of correctly classified samples in the batch.
```

```

"""
# Move the model and data to the device

train_hamming_distance = HammingDistance(task="multilabel", num_labels=10).
↳to(device)

model = model.to(device)
inputs = tuple(input_tensor.to(device)
                for input_tensor in inputs)

targets = targets.to(device)

# Step 1: Forward pass to get the model's predictions
outputs = model(inputs)

# Step 2: Compute the loss using the provided loss function
if loss_function:
    loss = loss_function(outputs, targets)

with torch.no_grad():
    # Correct prediction using thresholding
    y_pred = (outputs.data>0.5).float()

    # Update Hamming Distance metric
    train_hamming_distance.update(y_pred, targets)

# Step 3 and 4: Perform backward pass and update model parameters if an
↳optimizer is provided
if optimizer:
    optimizer.zero_grad()
    loss.backward()
    clip_grad_value_(model.parameters(), clip_value = hyperparameters.
↳CLIP_VALUE)
    optimizer.step()

# Return relevant metrics
if loss_function:
    return loss, outputs, train_hamming_distance
else:
    return outputs, train_hamming_distance

```

## 7.2 Train\_Epoch Function

```
[169]: def train_epoch(train_loader, model, device, loss_function, optimizer):  
    """  
    Trains the model for one epoch using the provided data loader and updates  
    ↪ the model parameters.  
  
    Parameters:  
    - train_loader (torch.utils.data.DataLoader): DataLoader object for the  
    ↪ training set.  
    - model (torch.nn.Module): The neural network model to be trained.  
    - device (torch.device): The computing device (CPU or GPU).  
    - loss_function (torch.nn.Module): The loss function to use for training.  
    - optimizer (torch.optim.Optimizer): The optimizer to update model  
    ↪ parameters.  
  
    Returns:  
    - train_loss (float): Average training loss for the epoch.  
    - train_acc (float): Training accuracy for the epoch.  
    """  
    # Set the model to training mode  
  
    model.train()  
  
    # Initialize variables to track running training loss and correct  
    ↪ predictions  
    running_train_loss = 0.0  
    running_train_correct = 0  
  
    # Iterate over all batches in the training data  
    for inputs, targets in train_loader:  
        # Perform a forward and backward pass, updating model parameters  
        loss, _, hamming = step(inputs, targets, model, device, loss_function,  
    ↪ optimizer)  
  
        # Update running loss and correct predictions counter  
        running_train_loss += loss.item()  
  
        # Compute Hamming Distance for the epoch  
        epoch_hamming_distance = hamming.compute()  
  
    # Compute average loss and accuracy for the entire training set  
    train_loss = running_train_loss / len(train_loader)
```



```
return train_loss, epoch_hamming_distance
```

### 7.3 Val\_Epoch Function

```
[170]: def val_epoch(valid_loader, model, device, loss_function):  
    """  
    Validates the model for one epoch using the provided data loader.  
  
    Parameters:  
    - valid_loader (torch.utils.data.DataLoader): DataLoader object for the  
    ↪ validation set.  
    - model (torch.nn.Module): The neural network model to be validated.  
    - device (torch.device): The computing device (CPU or GPU).  
    - loss_function (torch.nn.Module): The loss function to evaluate the model.  
  
    Returns:  
    - val_loss (float): Average validation loss for the epoch.  
    - val_acc (float): Validation accuracy for the epoch.  
    """  
    # Set the model to evaluation mode  
    model.eval()  
  
    # Initialize variables to track running validation loss and correct  
    ↪ predictions  
    running_val_loss = 0.0  
    running_val_correct = 0  
  
    # Disable gradient computation  
    with torch.no_grad():  
        # Iterate over all batches in the validation data  
        for inputs, targets in valid_loader:  
            # Perform a forward pass to get loss and number of correct  
            ↪ predictions  
            loss, _, hamming = step(inputs, targets, model, device, ↪  
            ↪ loss_function, optimizer=None)  
  
            # Update running loss and correct predictions counter  
            running_val_loss += loss.item()  
            # Compute Hamming Distance for the epoch  
            epoch_hamming_distance = hamming.compute()  
  
    # Compute average loss and accuracy for the entire validation set  
    val_loss = running_val_loss / len(valid_loader)  
    # val_acc = running_val_correct / len(valid_loader.dataset)
```

```
return val_loss, epoch_hamming_distance
```

```
[171]: def train(train_loader, valid_loader, model, optimizer, loss_function, epochs, device):  
    """  
    Trains and validates the model, and returns history of train and validation metrics.  
  
    Parameters:  
    - train_loader (torch.utils.data.DataLoader): DataLoader for the training set.  
    - valid_loader (torch.utils.data.DataLoader): DataLoader for the validation set.  
    - model (torch.nn.Module): Neural network model to train.  
    - optimizer (torch.optim.Optimizer): Optimizer algorithm.  
    - loss_function (torch.nn.Module): Loss function to evaluate the model.  
    - epochs (int): Number of epochs to train the model.  
    - device (torch.device): The computing device (CPU or GPU).  
  
    Returns:  
    - train_loss_history (list): History of training loss for each epoch.  
    - train_acc_history (list): History of training accuracy for each epoch.  
    - valid_loss_history (list): History of validation loss for each epoch.  
    - valid_acc_history (list): History of validation accuracy for each epoch.  
    """  
  
    # Initialize lists to store metrics for each epoch  
    train_loss_history = []  
    valid_loss_history = []  
    train_hamm_history = []  
    valid_hamm_history = []  
  
    # Loop over the number of specified epochs  
    for epoch in range(epochs):  
        # Train model on training data and capture metrics  
        train_loss, train_hamm = train_epoch(  
            train_loader, model, device, loss_function, optimizer)  
  
        # Validate model on validation data and capture metrics  
        valid_loss, valid_hamm = val_epoch(  
            valid_loader, model, device, loss_function)  
  
        # Store metrics for this epoch  
        train_loss_history.append(train_loss)  
        train_hamm_history.append(train_hamm.to('cpu').numpy())  
        valid_loss_history.append(valid_loss)  
        valid_hamm_history.append(valid_hamm.to('cpu').numpy())
```

```

        # Output epoch-level summary
        print(f"Epoch {epoch+1}/{epochs}")
        print(f"Train Loss: {train_loss:.4f} | Train Hamming Distance:␣
↪{train_hamm:.4f}")
        print(f"Valid Loss: {valid_loss:.4f} | Valid Hamming Distance:␣
↪{valid_hamm:.4f}")
        print()

    return train_loss_history, train_hamm_history, valid_loss_history,␣
↪valid_hamm_history

```

[171]:

## 8 Training Configuration

[171]:

```

[172]: # Fix seed value
SEED = 2345
random.seed(SEED)
np.random.seed(SEED)
torch.manual_seed(SEED)
torch.cuda.manual_seed(SEED)
torch.backends.cudnn.deterministic = True

collate_fn = partial(collate_batch, my_vocab=lang_vocab)

# Data Loader
train_loader = torch.utils.data.DataLoader(trainset, batch_size=hyperparameters.
↪BATCH_SIZE, shuffle=True,
                                         collate_fn=collate_fn, num_workers=4)
valid_loader = torch.utils.data.DataLoader(validset, batch_size=hyperparameters.
↪BATCH_SIZE, shuffle=False,
                                         collate_fn=collate_fn, ␣
↪num_workers=4)
test_loader = torch.utils.data.DataLoader(testset, batch_size=hyperparameters.
↪BATCH_SIZE, shuffle=False,
                                         collate_fn=collate_fn, num_workers=4)

# cross entropy loss function
loss_function = nn.BCEWithLogitsLoss()

# model

```

```

model_lang = nn.Sequential(
    EmbeddingBagWrapper(vocab_size, embed_dim ),
    CustomBlock(embed_dim , hyperparameters.HIDDEN_DIM1, 0.5),
    CustomBlock(hyperparameters.HIDDEN_DIM1, hyperparameters.HIDDEN_DIM2, 0.5),
    nn.Linear(hyperparameters.HIDDEN_DIM2, hyperparameters.OUTPUT_DIM)
)

def init_weights(m):
    if type(m) == nn.Linear:
        torch.nn.init.kaiming_normal_(m.weight)
        torch.nn.init.zeros_(m.bias)

# apply initialization recursively to all modules
model_lang.apply(init_weights)

# Intialize stochastic gradient descent optimizer
optimizer = torch.optim.AdamW(model_lang.parameters(),
                                lr=hyperparameters.LEARNING_RATE,

                                )

device = torch.device('cuda:0' if torch.cuda.is_available() else 'cpu')

```

## 9 Sanity Check

- Check the loss without any training. For Cross entropy the expected value will be log(number of classes)

```

[173]: batch_size = 2
check_loader = torch.utils.data.DataLoader(dataset=trainset,
                                             batch_size=batch_size,
                                             shuffle=True,
                                             collate_fn=partial(collate_batch,
↪my_vocab = lang_vocab),
                                             )

```

```

[174]: for input_ , targets in train_loader:

    # move inputs and outputs to GPUs
    model_lang = model_lang.to(device)

    input_ = tuple(input_tensor.to(device)
                   for input_tensor in input_)
    targets = targets.to(device)

```

```

model_lang.eval()
# Forward pass
output = model_lang(input_)
loss = loss_function(output, targets)
print(f'Actual loss: {loss}')
break

print(f'Expected Theoretical loss: {np.log(2)}')

```

Actual loss: 0.6807318925857544

Expected Theoretical loss: 0.6931471805599453

## 10 Training Model

```

[175]: # Call the train function to train the model
train_losses, train_hamm, valid_losses, valid_hamm = train(
    train_loader, valid_loader, model_lang
    , optimizer, loss_function, hyperparameters.EPOCHS, device
)

```

Epoch 1/5

Train Loss: 0.3519 | Train Hamming Distance: 0.0636

Valid Loss: 0.1972 | Valid Hamming Distance: 0.1973

Epoch 2/5

Train Loss: 0.1908 | Train Hamming Distance: 0.0750

Valid Loss: 0.1572 | Valid Hamming Distance: 0.2000

Epoch 3/5

Train Loss: 0.1556 | Train Hamming Distance: 0.0568

Valid Loss: 0.1364 | Valid Hamming Distance: 0.1757

Epoch 4/5

Train Loss: 0.1345 | Train Hamming Distance: 0.0545

Valid Loss: 0.1254 | Valid Hamming Distance: 0.1595

Epoch 5/5

Train Loss: 0.1194 | Train Hamming Distance: 0.0295

Valid Loss: 0.1166 | Valid Hamming Distance: 0.1486

## 11 Plot Losses Metrics

```
[176]: def plot_history(train_losses, train_metrics, val_losses=None,
    ↪ val_metrics=None):
    """
    Plot training and validation loss and metrics over epochs.

    Args:
        train_losses (list): List of training losses for each epoch.
        train_metrics (list): List of training metrics (e.g., accuracy) for
    ↪ each epoch.
        val_losses (list, optional): List of validation losses for each epoch.
        val_metrics (list, optional): List of validation metrics for each epoch.

    Returns:
        None
    """
    epochs = range(1, len(train_losses) + 1)

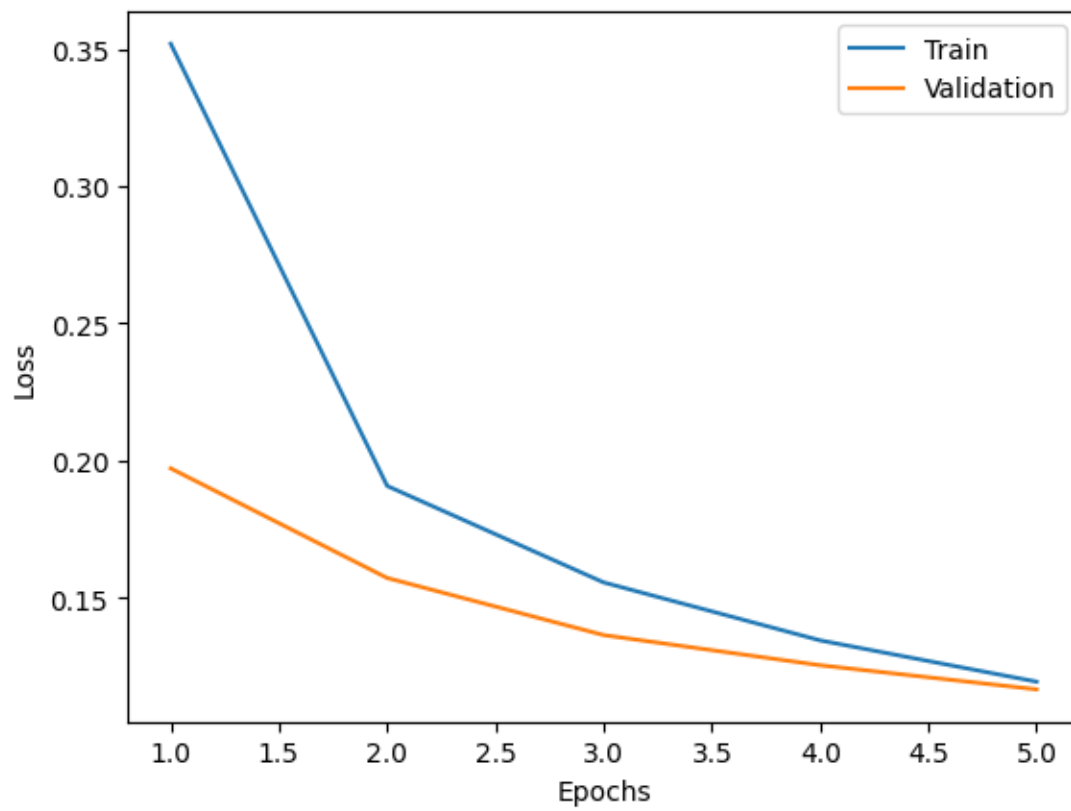
    # Plot training and validation losses
    plt.figure()
    plt.plot(epochs, train_losses, label="Train")
    if val_losses:
        plt.plot(epochs, val_losses, label="Validation")
    plt.xlabel("Epochs")
    plt.ylabel("Loss")
    plt.legend()
    plt.show()

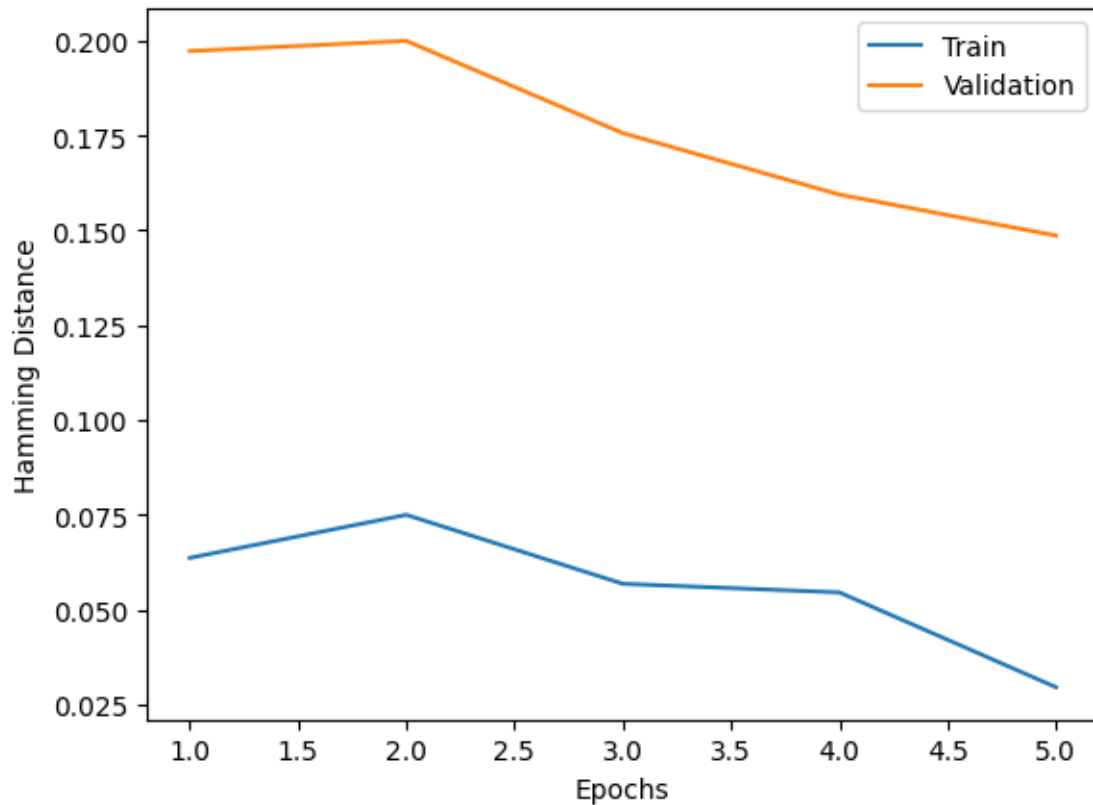
    # Plot training and validation metrics (if available)
    if train_metrics[0] is not None:
        plt.figure()
        plt.plot(epochs, train_metrics, label="Train")
        if val_metrics:
            plt.plot(epochs, val_metrics, label="Validation")
        plt.xlabel("Epochs")
        plt.ylabel("Hamming Distance")
        plt.legend()
        plt.show()
```

```
[177]: train_hamm
```

```
[177]: [array(0.06363636, dtype=float32),
    array(0.07499999, dtype=float32),
    array(0.05681819, dtype=float32),
    array(0.05454546, dtype=float32),
    array(0.02954543, dtype=float32)]
```

```
[178]: plot_history(train_losses, train_hamm, valid_losses, valid_hamm)
```





## 12 Model Checkpointing

```
[179]: # Get the current timestamp in the format "YYYY-MM-DD_HH-MM-SS"
timestamp = datetime.now().strftime("%Y-%m-%d_%H-%M-%S")
```

```
# Define a suffix for the file name
suffix = 'hw4'
```

```
# Combine the timestamp and suffix to create the file path
path = model_folder / f'{timestamp}_{suffix}.pt'
path
```

```
[179]: PosixPath('/content/drive/MyDrive/NLP/models/nlp_spring_2023/hw4/2023-09-25_01-43-13_hw4.pt')
```

```
[180]: # Save the model's state dictionary to the specified file path
torch.save(model_lang.state_dict(), path)
```

```
[181]: # model
my_model = nn.Sequential(
```



```

EmbeddingBagWrapper(vocab_size, embed_dim ),
CustomBlock(embed_dim , hyperparameters.HIDDEN_DIM1, 0.5),
CustomBlock(hyperparameters.HIDDEN_DIM1, hyperparameters.HIDDEN_DIM2, 0.5),
nn.Linear(hyperparameters.HIDDEN_DIM2, hyperparameters.OUTPUT_DIM)
)

# Load the model's state dictionary from the specified checkpoint file
checkpoint = torch.load(path)

# Load the saved state dictionary into the model
my_model.load_state_dict(checkpoint)

```

[181]: <All keys matched successfully>

[181]:

## 13 Get Accuracy, Predictions

```

[182]: def get_acc_pred(data_loader, model, device):
        """
        Function to get predictions and accuracy for a given data using a trained_
        ↪ model
        Input: data iterator, model, device
        Output: predictions and accuracy for the given dataset
        """
        model = model.to(device)
        # Set model to evaluation mode
        model.eval()

        # Create empty tensors to store predictions and actual labels
        predictions = torch.Tensor().to(device)
        y = torch.Tensor().to(device)

        # Iterate over batches from data iterator
        with torch.no_grad():
            for inputs, targets in data_loader:
                # Process the batch to get the loss, outputs, and correct_
                ↪ predictions
                outputs, _ = step(inputs, targets, model,
                                   device, loss_function=None, optimizer=None)

                # Choose the label with maximum probability
                # Correct prediction using thresholding
                y_pred = (outputs.data>0.5).float()

```

```

        # Add the predicted labels and actual labels to their respective
        ↪ tensors
        predictions = torch.cat((predictions, y_pred))
        y = torch.cat((y, targets.to(device)))

        # Calculate accuracy by comparing the predicted and actual labels
        accuracy = (predictions == y).float().mean()

        # Return tuple containing predictions and accuracy
        return predictions, accuracy, y

```

```

[183]: # Get the prediction and accuracy
predictions_test, acc_test, y_test = get_acc_pred(test_loader, my_model, device)
predictions_train, acc_train, y_train = get_acc_pred(train_loader, my_model, ↪
        ↪ device)
predictions_valid, acc_valid, y_valid = get_acc_pred(valid_loader, my_model, ↪
        ↪ device)

```

```

[184]: # Print Test Accuracy
print('Test accuracy', acc_test * 100)
print('Train accuracy', acc_train * 100)
print('Valid accuracy', acc_valid * 100)

```

```

Test accuracy tensor(95.7285, device='cuda:0')
Train accuracy tensor(96.7632, device='cuda:0')
Valid accuracy tensor(95.6536, device='cuda:0')

```

## 14 Get Multi-Label Confusion Matrix

```

[185]: multilabel_confusion_matrix(y_true=y_test.cpu(), y_pred=predictions_test.cpu())

```

```

[185]: array([[[[7182,  186],
               [ 418, 1672]],

               [[7691,  114],
               [ 173, 1480]],

               [[8257,   52],
               [ 473,  676]],

               [[3588,  399],
               [ 467, 5004]],

               [[7856,   74],
               [ 139, 1389]]],

```

```

[[4246, 234],
 [ 415, 4563]],

[[9295, 8],
 [ 98, 57]],

[[9335, 2],
 [ 98, 23]],

[[9396, 0],
 [ 62, 0]],

[[6811, 154],
 [ 474, 2019]]])

```

## 15 Get Test Data Hamming Distance

```

[196]: test_hamming_distance = HammingDistance(task="multilabel", num_labels=10).
      ↪to(device)
      test_hamming_distance.update(y_test, predictions_test)

```

```

[197]: test_hamming_distance.compute()

```

```

[197]: tensor(0.0427, device='cuda:0')

```

```

[ ]:

```