4/4/2019 pg08

Contents

- Experiment 8 : Time Response specifications of second order systems.
- Plot step response of second order system
- Conclusion :

Experiment 8: Time Response specifications of second order systems.

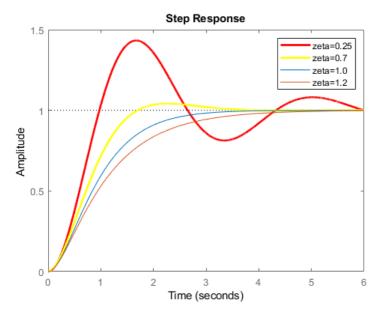
```
%Name : Shruti Mandaokar
%PRN : 17070123102
%Batch : Entc EB2

clc;
clear all;
close all;
```

Plot step response of second order system

```
t=0:0.001:20;
w_n=2;
% For zeta = 0.25
zeta=0.25:
theta=atan(sqrt(1-zeta^2)/zeta);
w_d=w_n*sqrt(1-zeta^2);
C=1-((exp(-zeta.*w_n.*t).*(sin(sqrt(1-zeta^2)*w_d.*t+theta)))./sqrt(1-zeta^2));
plot(t,C,'r','LineWidth',2); hold on;
%For zeta = 0.7
zeta=0.7;
theta=atan(sqrt(1-zeta^2)/zeta);
D=1-((exp(-zeta.*w_n.*t).*(sin(sqrt(1-zeta^2)*w_d.*t+theta)))/sqrt(1-zeta^2));
plot(t,D,'y','LineWidth',2); hold on;
% For zeta = 1.0
zeta=1.0;
N1=[(w_n)^2];
D1=[1 (2*zeta*w_n) (w_n*w_n)];
M1=tf(N1,D1)
stepplot(M1); hold on;
% For zeta = 1.2
zeta=1.2;
N2=[(w_n)^2];
D2=[1 (2*zeta*w_n) (w_n*w_n)];
M2=tf(N2,D2)
stepplot(M2); hold on;
legend('zeta=0.25','zeta=0.7','zeta=1.0','zeta=1.2');
```

4/4/2019 pg08



```
stepinfo(C)
stepinfo(D)
figure()

b = imread('exp0801.PNG');
imshow(b)

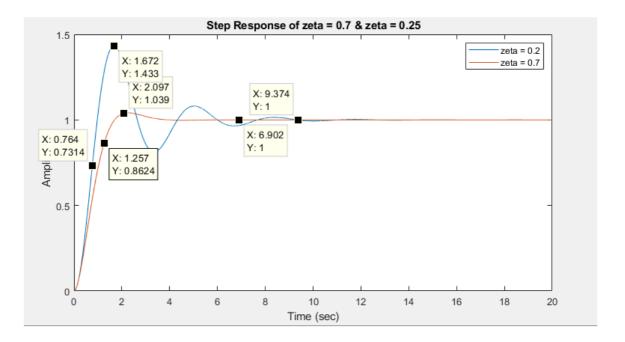
%plot(t,C);
%titlehold on
%plot(t,D);
```

```
ans =
  struct with fields:
    RiseTime: 653.7972
  SettlingTime: 7.2429e+03
    SettlingMin: 0.8128
    SettlingMax: 1.4327
    Overshoot: 43.2754
    Undershoot: 0
        Peak: 1.4327
        PeakTime: 1672

ans =
  struct with fields:
    RiseTime: 1.0981e+03
```

SettlingTime: 3.0134e+03
SettlingMin: 0.9001
SettlingMax: 1.0416
Overshoot: 4.1581
Undershoot: 0
Peak: 1.0416
PeakTime: 2261

4/4/2019 pg08



Conclusion:

%In this experiment I plotted the step response of second order system with %given parameters using step function and further calculated characteristics %of system. Further, I used stepinfo to verify the results.

% 1. When 0<zeta<1, the system is underdamped.

% 2. When zeta>1, system is overdamped.

 $\ensuremath{\text{\%}}$ 3. As zeta increases, the response becomes progressively less

% oscillatory till it becomes critically damped for zeta = 1, and becomes

% overdamped for zeta > 1.

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