

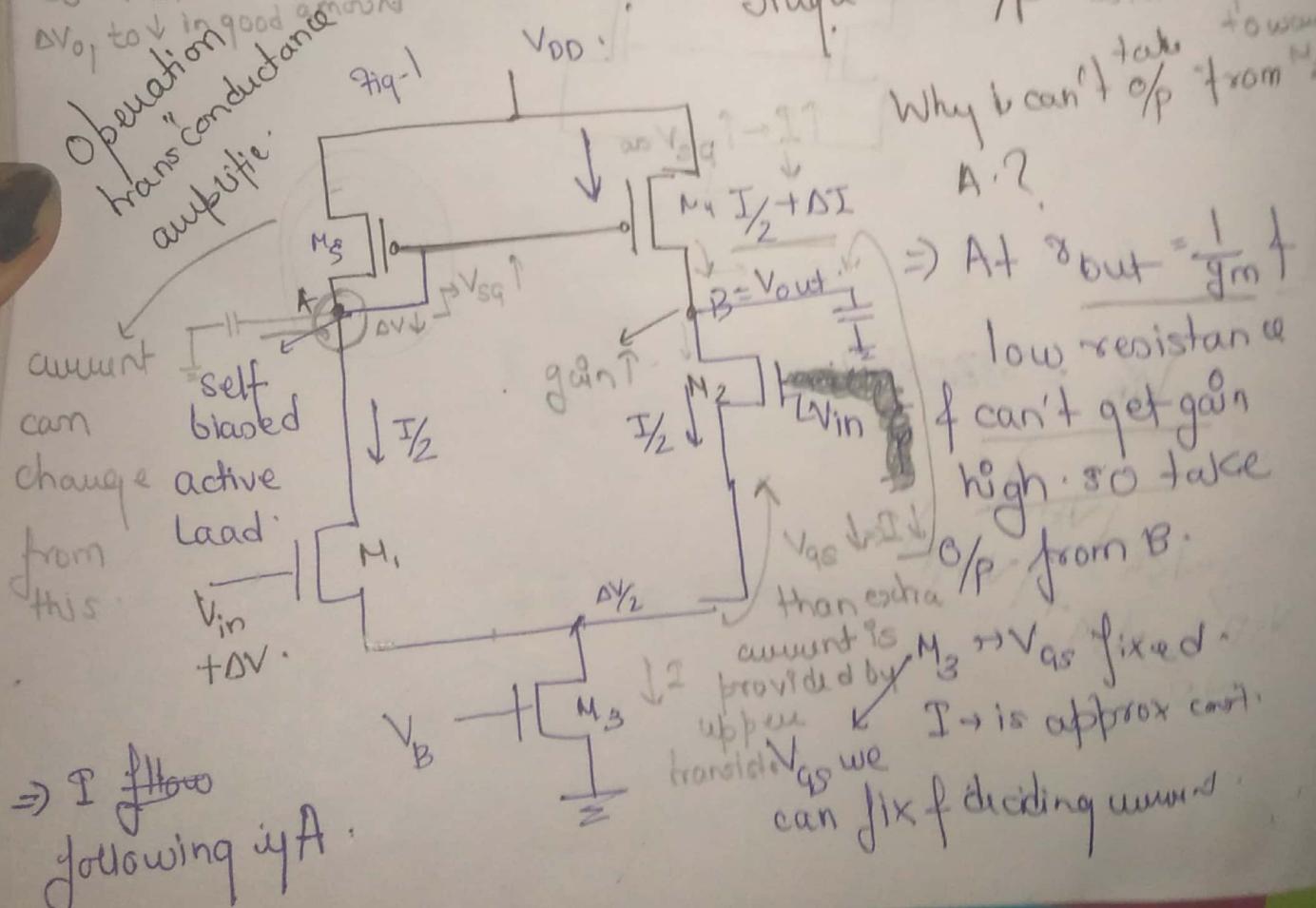
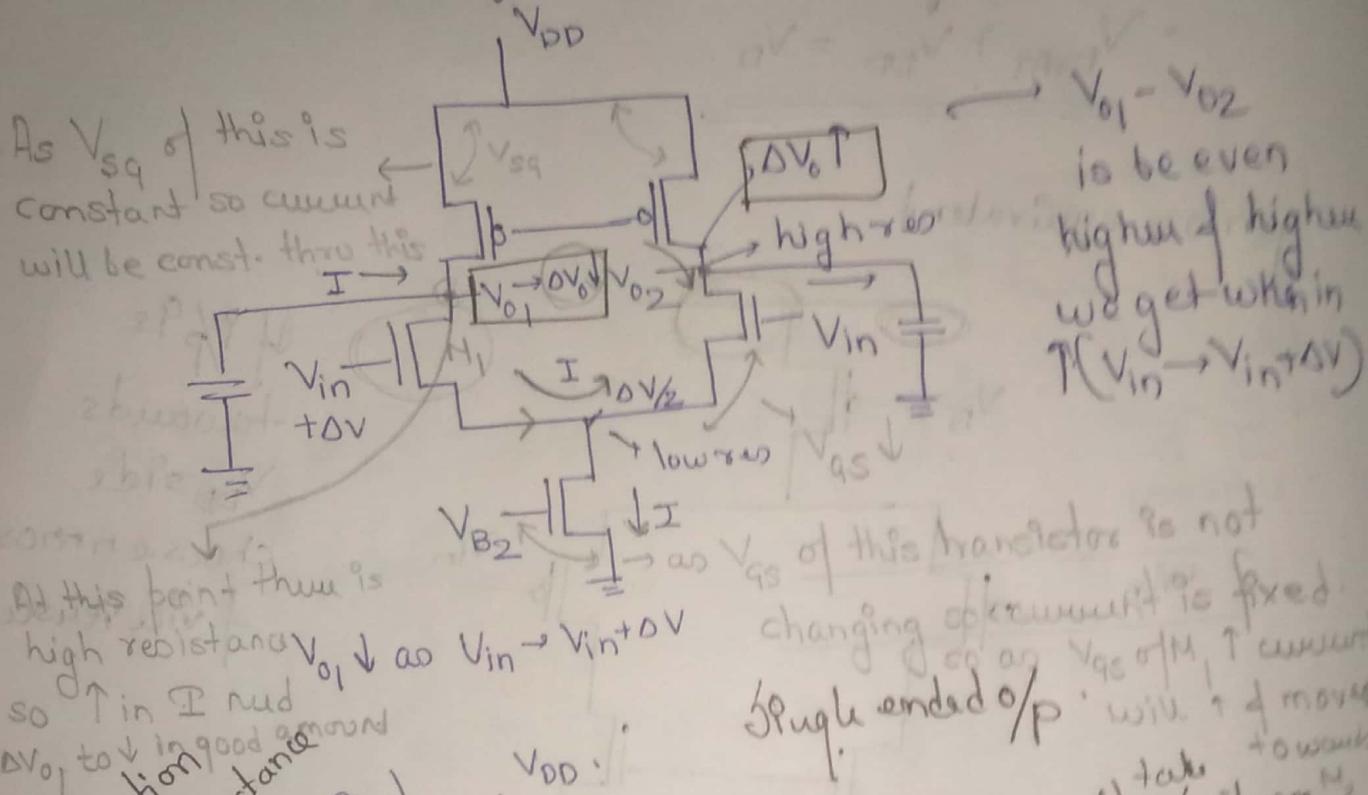
7/01/19

Multi-Stage Amplifier

Multiple amplifier connected in cascade.

Differential i/p } Direct o/p → I^{st stage}

(Balanced structure)



When V_{in} is fixed as V_{GS}/V_{SG} of all transistors is fixed. ($V_{GS} = V_{SG}$) M_1, N_2 + $(V_{SG} = V_{SD}) M_4, M_5$.
 $V_{in} \rightarrow V_{in+AV}$, $I_{M_1} \rightarrow \text{will } \uparrow$, $V_A \downarrow \rightarrow I_{M_5} \text{ will } \uparrow$ ($V_{SG} \uparrow$) $\rightarrow V_A \downarrow$.
 $M_4 \rightarrow V_{SG} = V_{SD} |_{M_5}$.

Current through M_4 will \uparrow .

~~At B~~ At B higher gain (I came from M_4 & N_2 both)
so Current basically \uparrow .

\Rightarrow As V_{in} is same - As V_{GS} is same than current is slightly same (V_{DS} change) know $[M_1, N_2]$

\Rightarrow V_{SG} same - Current approx same.
transconductance $A_m (I/V)$ ($0/p$ current) \Rightarrow if Res. low it will support current change.

$(R \rightarrow \infty)$

Voltage amplifier -

i/p imp - higher.

o/p imp - lower.

$V_{out} \rightarrow \text{low imp.}$

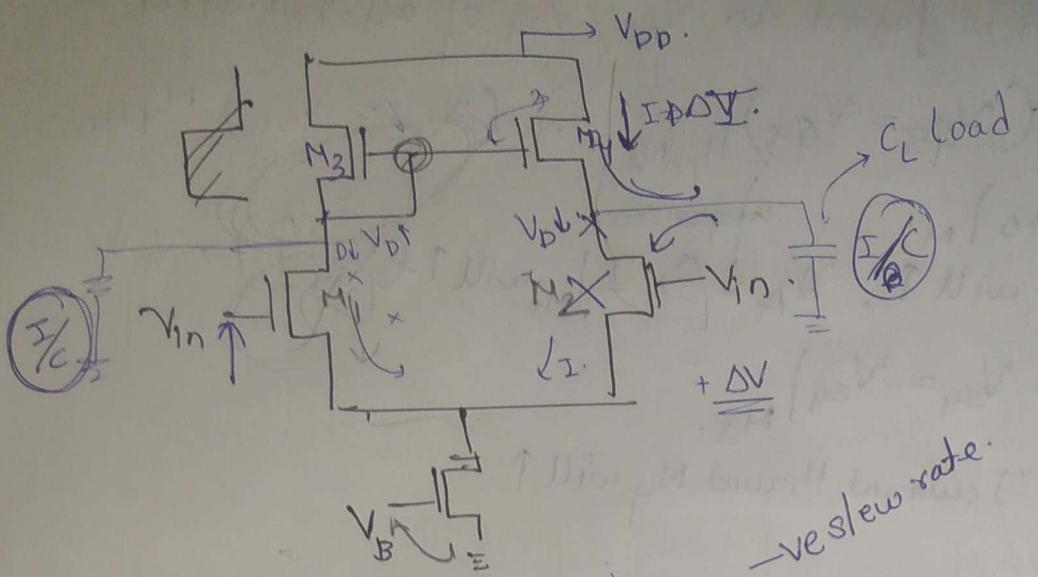
$V_{out} \rightarrow \text{high imp.}$ as V_{out} has huge impedance in Fig-1 it will be followed by

Source follower.

Source follower.

\Rightarrow i/p. imp. higher, o/p impedance high.

$\Rightarrow (V-I)$ Amp.



$$\left(\frac{dV_{out}}{dt} \right)_{max} = +\frac{I}{C} \quad \left(\frac{dV_{out}}{dt} \right)_{min} = -\frac{I}{C}$$

$$V_{SG} = V_{SD}$$

$$V_Q = V_{Q'} = V_D$$

$N_D > N_Q - V_{th}, V_{GS} > V_{th}$
 $\rightarrow V_{GS} < V_{th} \rightarrow V_{GS} = 0$

In here we are taking single opamp so (no add of subtraction)

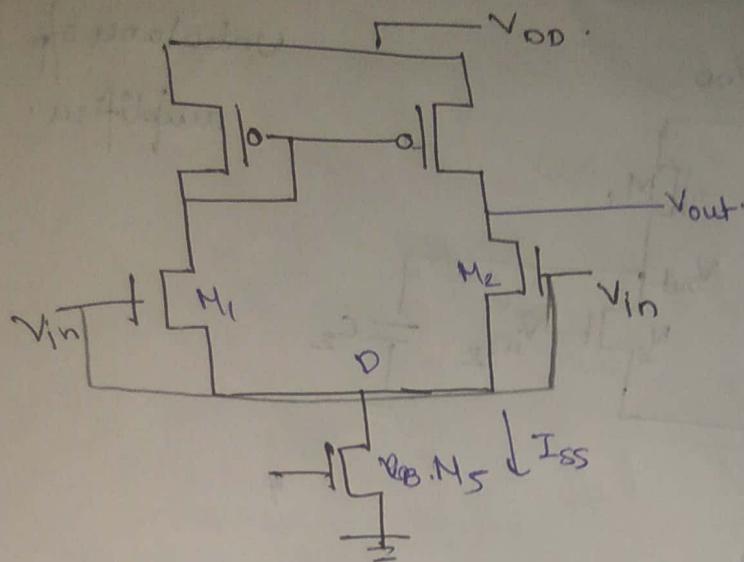
\Rightarrow As $V_{in} \uparrow \Rightarrow M_2$ got turn off.

\Rightarrow than I amount of current will flow through M_3

& M_1 and V_{SG} of M_3 & M_4 are same so

I amount of current will also flow thru

M_4 \therefore slew rate $= +\frac{I}{C}$



Calculate I_{CMR} .

for corresponding
 I_{SS} we will
see V_{in} :

$$V_{in} \rightarrow V_{in} + \Delta V \Rightarrow V_{GS} \uparrow$$

When V_{in} is same.

$$\underline{V_{in} \uparrow \rightarrow V_{GS} \text{ const.}}$$

$$\underline{V_D > V_G - V_{th}}$$

$$V_{GS} = V_{in} - V_D$$

$$\underline{V_{GS}|_{in \text{ osat}}} = V_{in}$$

$$\left[\begin{array}{l} V_{in} = V_{osat} + V_{th} \\ \min \end{array} \right]$$

$$+ V_{osat}$$

$$= \sqrt{\frac{I_{SS}}{B_1}} + V_{th}$$

$$+ \sqrt{\frac{2I_{SS}}{B_5}}$$

$V_{in} + \Delta V \rightarrow M_1, M_2 \text{ can come out of sat}$

$$V_{in} - \Delta V \rightarrow M_3$$

$$V_{in|_{max}}$$

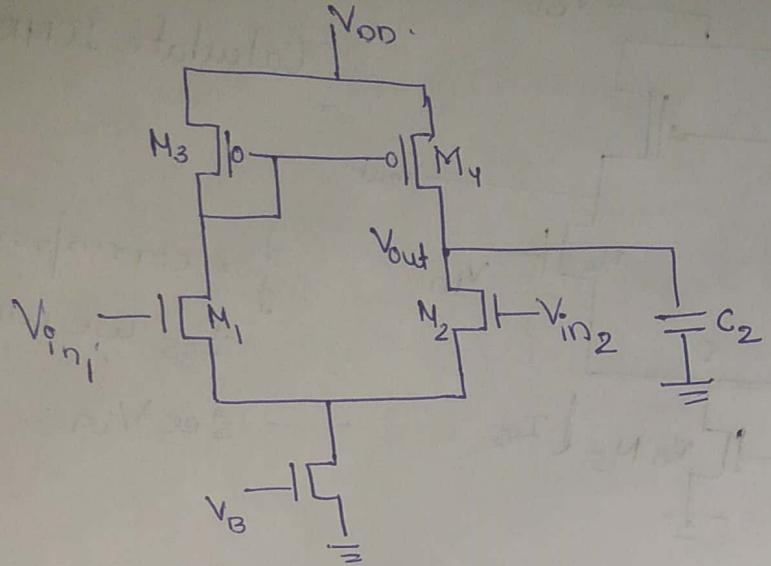
$$V_{SG} = V_{DD} - V_D$$

$$V_D = V_{DD} - V_{SG}$$

$$= V_{DD} - (V_{osat} + V_{th,P})$$

$$V_D > V_G - V_{th,12}$$

$$\begin{aligned} & V_{DD} - (V_{osat} + V_{th,12}) \\ & + V_{th,12} > V_{in} \end{aligned}$$



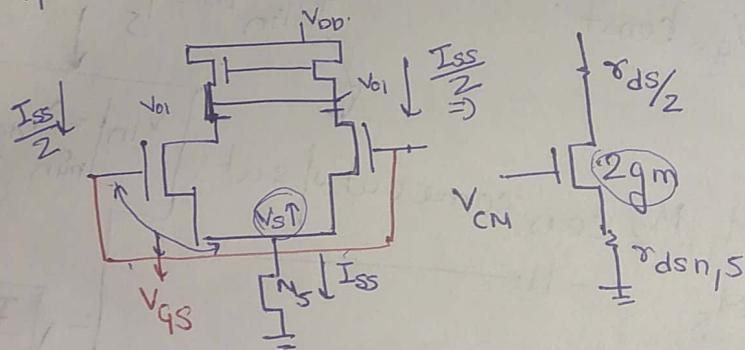
Unbalance o/p
- amplifier

\Rightarrow can't make half circuit like the previous one

$$A_{cm} \rightarrow \frac{\%}{p} \text{ same} \Rightarrow V_{out} = \text{same}$$

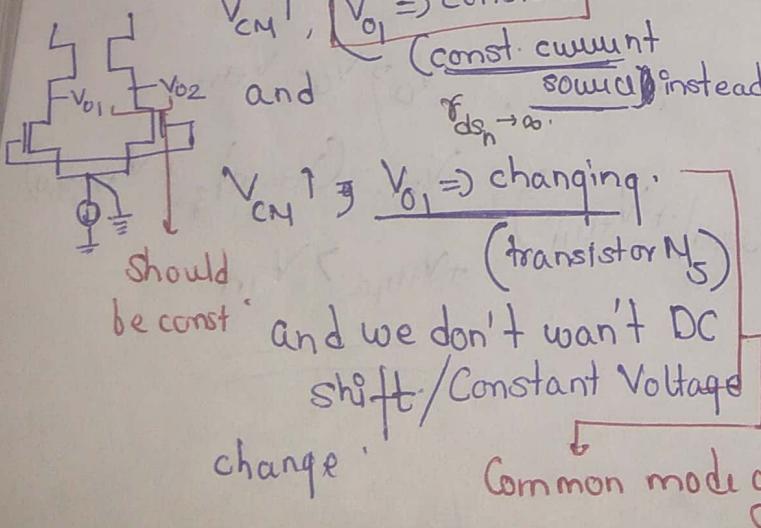
$$V_{GS} \rightarrow \text{constant}$$

$$V_q \uparrow \rightarrow V_S \uparrow$$

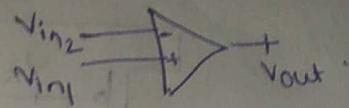
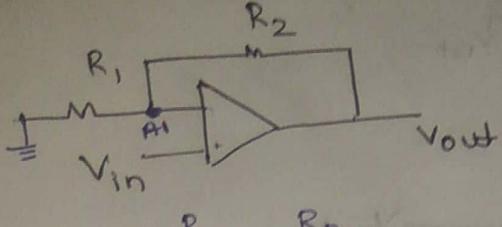


Q Common mode gain significance?
⇒ & why we calculate

$$\frac{V_o}{V_{in}} = \frac{-\gamma_{ds,p}/2}{\frac{1}{2g_m} + \frac{\gamma_{dsm}}{V_o}} \xrightarrow[V_o \rightarrow \infty]{\gamma_{ds,n}}$$



of N_S) [$\int \int$ Iss amount of current
 flow thru ~~both~~ trans.
 current src. than
 Differential
~~parallel~~ → Common mode.
 Iss will $\frac{1}{2}$ flow thru
 both ~~trans.~~
 trans. as
 they are
 mirror image]



$$V_{out} = A(V_{in_1} - V_{in_2})$$

Ideal case
 $A = \infty$

$$\frac{V_{in} - 0}{R_1} = \frac{V_{out} - V_{in}}{R_2}$$

$$V_{in} \left(\frac{1}{R_1} + \frac{R_2}{R_2} \right) = \frac{V_{out}}{R_2}$$

$$\frac{R_1 + R_2}{R_1 R_2} = \frac{V_{out}}{V_{in}}$$

$$\frac{R_1}{R_1 + R_2} = \frac{V_{out}}{V_{in}}$$

$$R_1 = R_2$$

$$2 = \frac{V_{out}}{V_{in}}$$

$$\frac{V_{out} R_1}{R_1 + R_2} \Rightarrow A \left[\frac{V_{in} - V_{out} R_1}{R_1 + R_2} \right]$$

$$V = V_{out}$$

$$V_{out} \left[1 + \frac{AR_1}{R_1 + R_2} \right] = AV_{in}$$

$$V_{out} = A V_{in} \frac{R_1 + R_2}{R_1 (1+A) + R_2}$$

$$R_1 = R_2, A = 10$$

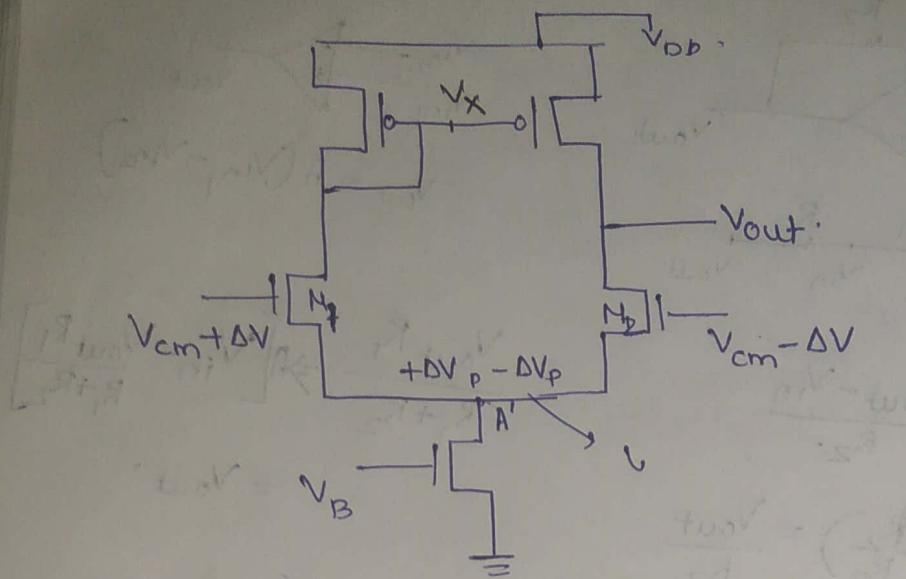
$$\frac{V_{out}}{V_{in}} = 1.66$$

error $\leftarrow 20\%$

$$\frac{0.2}{0.64 \times 10^6} \approx 0.2 \text{ pF}$$

\Rightarrow We can't consider always A as virtual short, we can only consider that when A is ∞ .

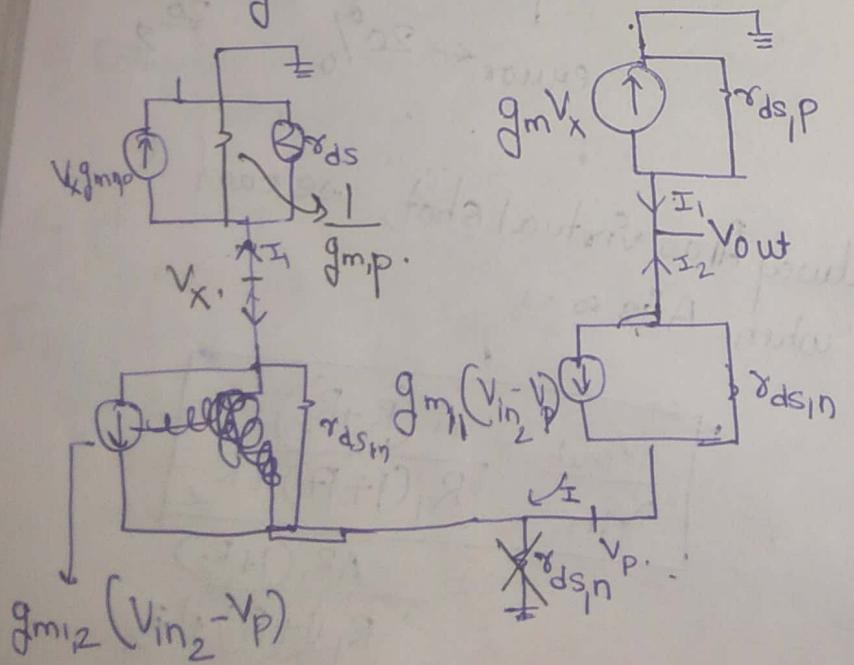
$$\begin{aligned} \frac{V_{out}}{V_{in}} &= \frac{A(R_1 + R_2)}{R_1(1+A) + R_2} \\ &= \frac{AR_1(1 + \frac{R_2}{R_1})}{R_1(1+A) + R_2} \end{aligned}$$



As we don't have mirror images so effect by N_2 & M_1 will not be same & for this we can't consider this as virtually grd.

$$V_{out} \rightarrow V_{in_1} \text{ & } V_{in_2}$$

AC analysis.



$$g_m (\emptyset - V_x)$$

$$V_x$$

$$I_1 = -g_m V_x - \frac{V_{out}}{r_{ds,p}}$$

$$I_2 = -g_{m,n} (V_{in_2} - V_p) - \left(\frac{V_{out} - V_p}{r_{ds,n}} \right)$$

~~$$g_m \cancel{V_x} \quad I_1 + I_2 = 0$$~~

$$g_m V_x - \frac{V_{out}}{r_{ds,p}} = +g_{m,n} (V_{in_2} - V_p) + \left(\frac{V_{out} - V_p}{r_{ds,n}} \right)$$

$$\frac{V_x - 0}{\frac{1}{g_{m,p}}} = I_1 = -g_m V_x = \frac{V_{out}}{r_{ds,p}}$$

$$V_x \left(\frac{1}{g_{m,p}} + g_{m,p} \right) = -\frac{V_{out}}{r_{ds,p}}$$

$$V_x (2g_{m,p}) r_{ds,p} = -V_{out}$$

$$V_x = \frac{-V_{out}}{2g_{m,p} r_{ds,p}}$$

$$\frac{V_{out}}{r_{ds,p}} - \frac{V_{out} g_{m,p}}{(2g_{m,p} r_{ds,p})} + g_{m,n} (V_{in_2} - V_p) + \left(\frac{V_{out} - V_p}{r_{ds,n}} \right) = 0$$

$$-\frac{V_{out}}{2r_{ds,p}} + \dots = 0$$

$$V_{out} \left(\frac{1}{r_{ds,p}} + \frac{1}{r_{ds,n}} \right) - \frac{V_{out}}{2r_{ds,p}} + V_{in,2} g_{m,1,2} - V_p g_{m,1,n} - \frac{V_p}{r_{ds,n}} = 0$$

$$\left(\frac{V_{out}}{g_{mn}} \left(\frac{1}{r_{ds,p}} + \frac{1}{r_{ds,n}} \right) - \frac{V_{out} + V_{in,2}}{2r_{ds,p}g_{m,p}} \right) = V_p$$

$$V_x(g_{m,p}) + (V_{in,1} - V_p) g_{m,p,2} + \frac{V_x - V_p}{r_{ds,n}} = 0$$

$$-\frac{V_{out}}{2(g_{m,p})r_{ds,p}} (g_{m,p}) + (V_{in,1} - V_p) g_{m,1,2} + -\frac{V_{out}}{2r_{ds,p}g_{m,n}} - \frac{V_p}{r_{ds,n}} = 0$$

$$V_{out} \left[-\frac{1}{2r_{ds,p}} - \frac{1}{2r_{ds,p}g_{m,n}r_{ds,n}} \right] + \frac{V_p}{r_{ds,n}} \left[-\frac{1}{r_{ds,n}} - g_{m,p} \right] + V_{in,1} g_{m,1,2} = 0$$

$$V_p = V_{in,1} g_{m,1,2} - \frac{V_{out}}{2r_{ds,p}g_{m,p,2}} + V_{in,1}$$

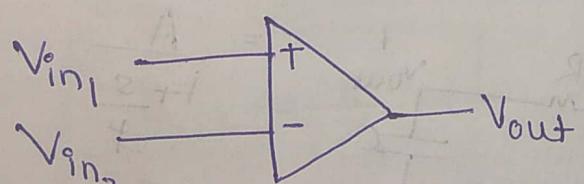
$$\frac{-V_{out}}{2 \gamma_{ds,p} g_{m1,2}} + V_{in_1} = \frac{V_{out}}{g_{m_{n1,2}}} \left(\frac{1}{\gamma_{ds,p}} + \frac{1}{\gamma_{ds,n}} \right)$$

$$\frac{-V_{out}}{2 \gamma_{ds,gm}} + V_{in_2}$$

$$\frac{V_{in_1} - V_{in_2}}{\left(\frac{1}{\gamma_{ds,p}} + \frac{1}{\gamma_{ds,n}} \right)} = \frac{V_{out}}{g_{m_{n1,2}}}$$

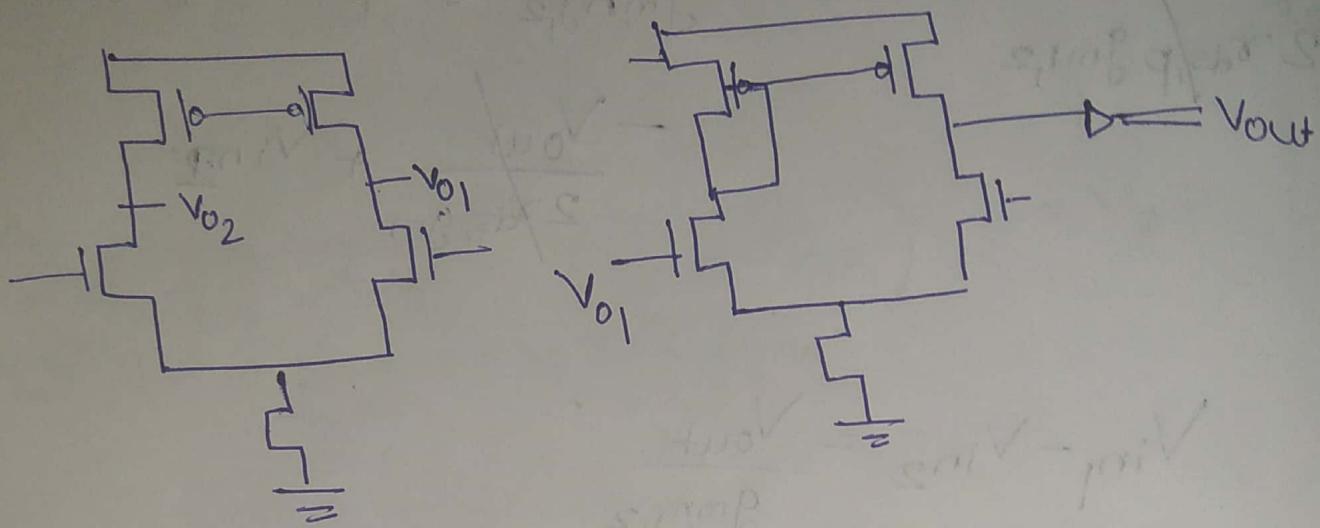
$$\frac{g_{m_{n1,2}} (V_{in_1} - V_{in_2})}{\left(\frac{1}{\gamma_{ds,p}} + \frac{1}{\gamma_{ds,n}} \right)} = V_{out}$$

$$g_{m_{n1,2}} (\gamma_{ds,p} || \gamma_{ds,n}) = \frac{V_{out}}{V_{in_1} - V_{in_2}}$$



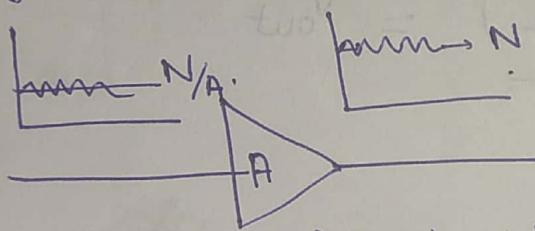
\Rightarrow In previous circuit from only one node gain was coms half of
here calculated one node gain. So basically this is

more beneficial.



⇒ We use that in amplification

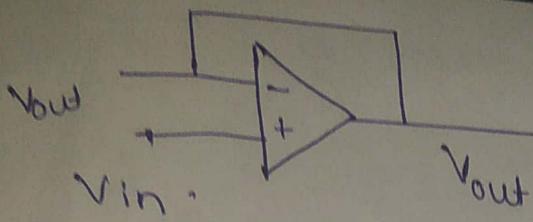
⇒ With high amplification Noise $V_{min}(inf)$ ↓.



⇒ At $N/A \downarrow$ and as V_{in} should be greater than N/A for detection of s/g it decides V_{min} .

⇒ If $s/g(V_{out}) < N$ we can't detect s/g.

$$V_{out} = \frac{A}{1 + \frac{s}{P}} V_{in}$$
$$V_{out}' = \frac{V_{out}}{1 + \omega RC}$$



$$\frac{A}{1+s/BW} = A_{\text{open-loop}}$$

(P) $\rightarrow 3\text{dB B.W.}$

$$V_{\text{out}} = \frac{A}{1+s/BW} [V_{\text{in}} - V_{\text{out}}]$$

$$V_{\text{out}} = \frac{A}{1+j\omega P} = A_0$$

$$V_{\text{out}} \left[1 + \frac{A}{1+s/BW} \right] + V_{\text{in}} \left(\frac{A}{1+s/BW} \right)$$

$$\frac{V_{\text{out}}}{V_{\text{in}}} = \frac{A}{A+1+s/BW}$$

$$\frac{V_{\text{out}}}{V_{\text{in}}} = \frac{A}{1+A}$$

$$1 + \frac{s}{BW(1+A)}$$

When $B.W. = 0$

$$A_{\text{open}} = A$$

$$\frac{V_{\text{out}}}{V_{\text{in}}} = \frac{A}{1+A}$$

"We need very high open-loop amplifier"

high open-loop amplifier

amplifier

11/03/18

Frequency Response.

- 1) Magnitude 2) Phase

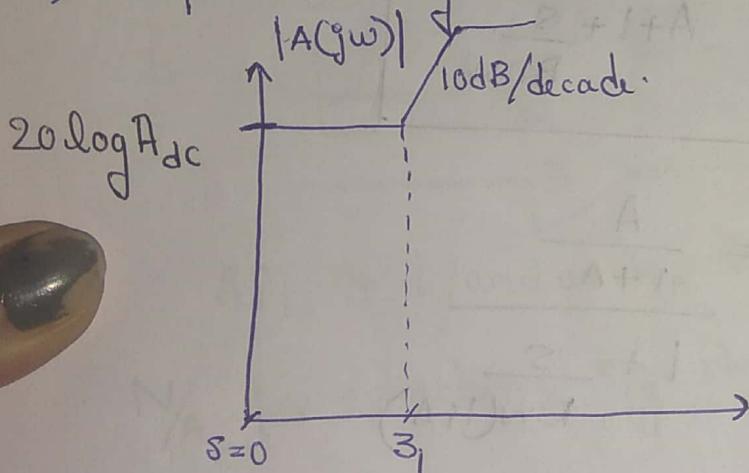
At time domain, we have huge analysis.

Why we use freq. analysis? b/c cap. react. is $\propto \omega$.

$$\Rightarrow A(j\omega) = A_{dc} \frac{(1 + \frac{s}{z_1})(1 + \frac{s}{z_2})}{(1 + \frac{s}{p_1})(1 + \frac{s}{p_2})}$$

\Rightarrow 3 poles \rightarrow extra path come.

\Rightarrow Pole provide delay.



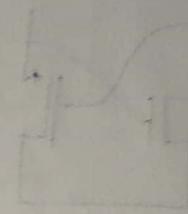
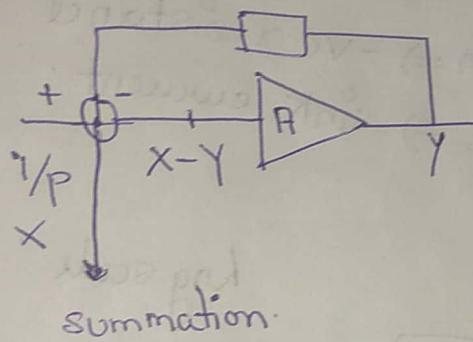
Assuming $z_1 < z_2 < p_1 < p_2 \dots$

$$|A(j\omega)| = 20 \log A_{dc} + 10 \log \left(1 + \frac{\omega^2}{z_1^2} \right) + 10 \log \left(1 + \frac{\omega^2}{z_2^2} \right) \\ - 10 \log \left(1 + \frac{\omega^2}{p_1^2} \right) - 10 \log \left(1 + \frac{\omega^2}{p_2^2} \right)$$

$$\angle A(j\omega) = \tan^{-1} \left(\frac{\omega}{z_1} \right) + \tan^{-1} \left(\frac{\omega}{z_2} \right) - \tan^{-1} \left(\frac{\omega}{p_1} \right) - \tan^{-1} \left(\frac{\omega}{p_2} \right)$$

What is physical significance?
 ⇒ stability of S/S

⇒ closed loop → -ve feedback component.
 → S/S not stable due to w component.



When w component come:

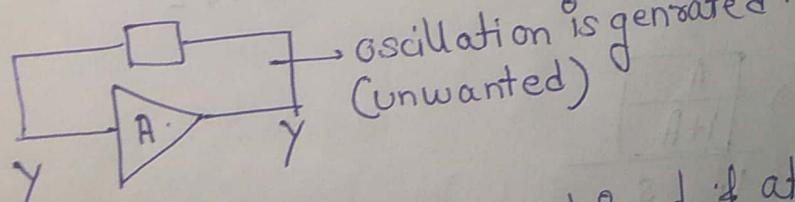
⇒ Phase shift is not dependent only on A_{dc} and depend on w & can change.

Like Common source.

$$\Rightarrow A_{dc} = -g_m R_{out} \rightarrow 180^\circ$$

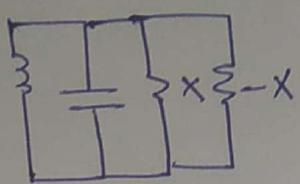
- $180^\circ + \dots +$ → phase at one pt. will be 0° .
 and it will become $X+Y$ & will increase.

A Negative f/b S/S may oscillate at $\approx w$ if the phase shift around the loop is more -ve than 180° .



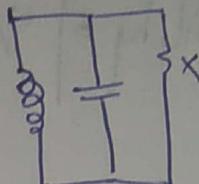
$\text{an}^{-1}\left(\frac{w}{P_s}\right)$ At a particular frequency it will get sustained if at

Other frequency there will be damping. (from)

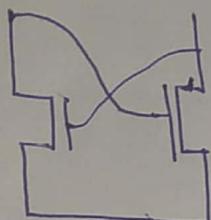


$$\sin \omega t$$

no damping,



$$e^{-x} \sin(\omega t)$$



$\rightarrow -\frac{V}{gm} \Rightarrow -ve$ resistance
 $\Rightarrow \sin K$ current.

$$A(j\omega) = \frac{A}{(s+a)}$$

$$q_{in} \times B.W = \text{const.}$$

B.W \uparrow gain \downarrow .

$$\omega_{UGB} \times | = \omega_{3dB} \times A_{dc}$$

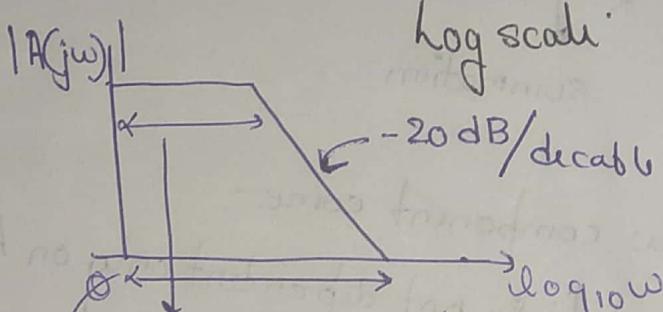
Minimum gain

Maximum freq.

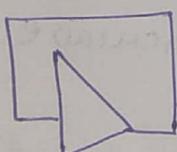
Eq. \Rightarrow

$$\frac{A}{1+A}$$

$$1 + \frac{s}{B.W(1+A)}$$

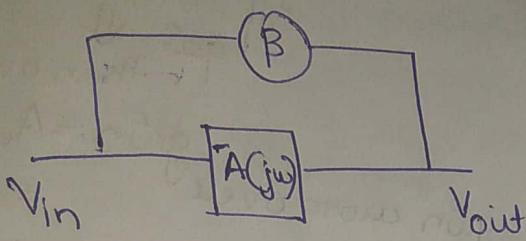


We want this particular to maximize otherwise S/S will become Unity gain B.W non-linear.



\rightarrow overall gain = 1

$$B.W =$$



$$= \frac{A(j\omega)}{1 - \beta A(j\omega)} \rightarrow \frac{-A(j\omega)}{1 + \beta A(j\omega)} = A_{cl}(j\omega)$$

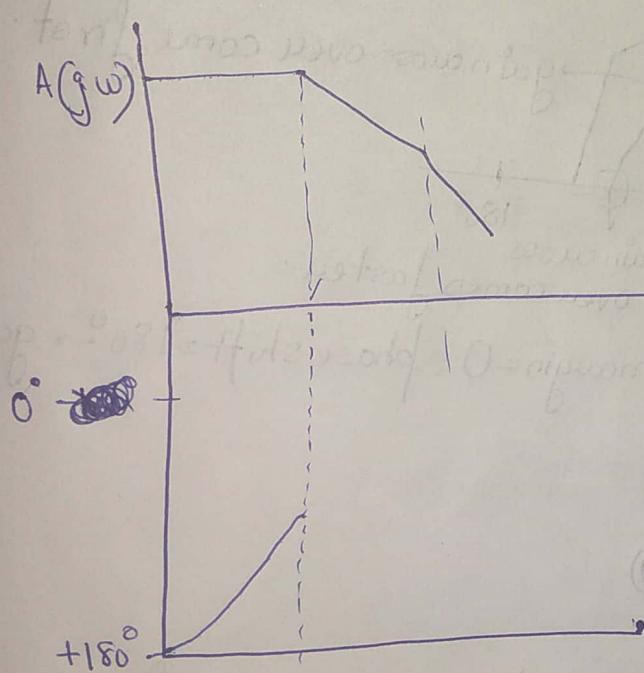
if $A(j\omega)$ has pole

$$= \frac{a+jb}{c+jb}$$

$$\Rightarrow A(j\omega) = -\frac{1}{\beta} \quad \text{We don't want that.}$$

$$\Rightarrow A_{cl}(j\omega) = \infty$$

left half phase shift
zero
 $s+j\omega$



RHP → add extra phase shift.

Right half phase shift

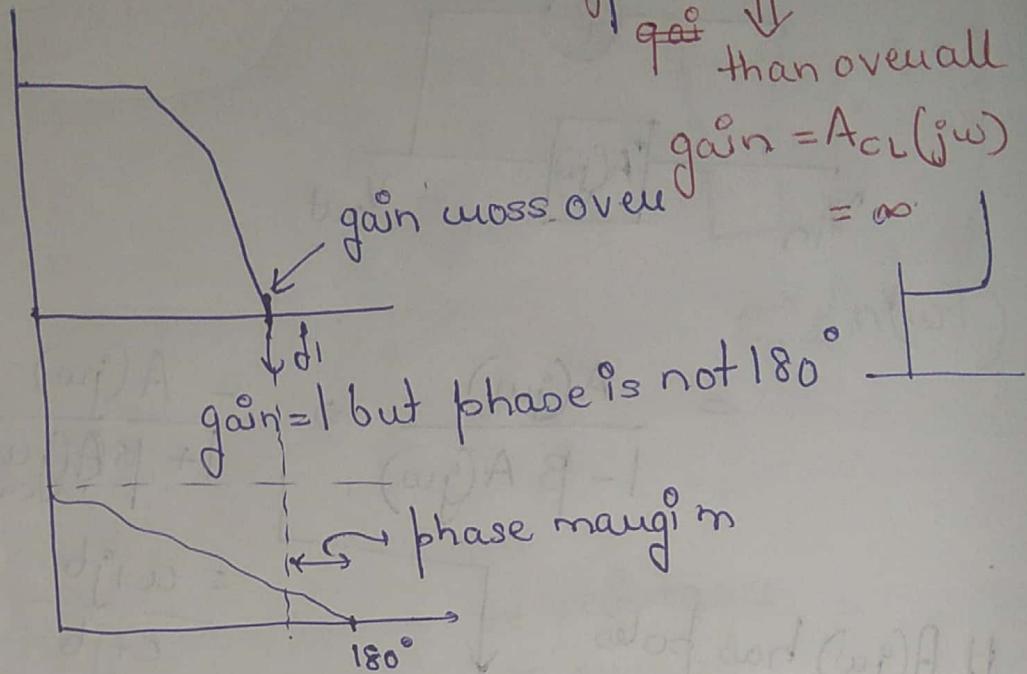
pole
zero
 $s-j\omega$

$$\begin{aligned} & -\tan^{-1}\left(\frac{\omega}{\zeta}\right) \\ & = 180^\circ - \tan^{-1}\left(\frac{\omega}{\zeta}\right) \\ & \quad \left. \begin{array}{l} \downarrow \\ -\tan^{-1}(\zeta) \end{array} \right. \\ & = -180^\circ \end{aligned}$$

⇒ we don't want RHP zero
⇒ we want LHP pole ($e^{j\omega} \rightarrow \infty$)

$= 0^\circ$
we don't want that.

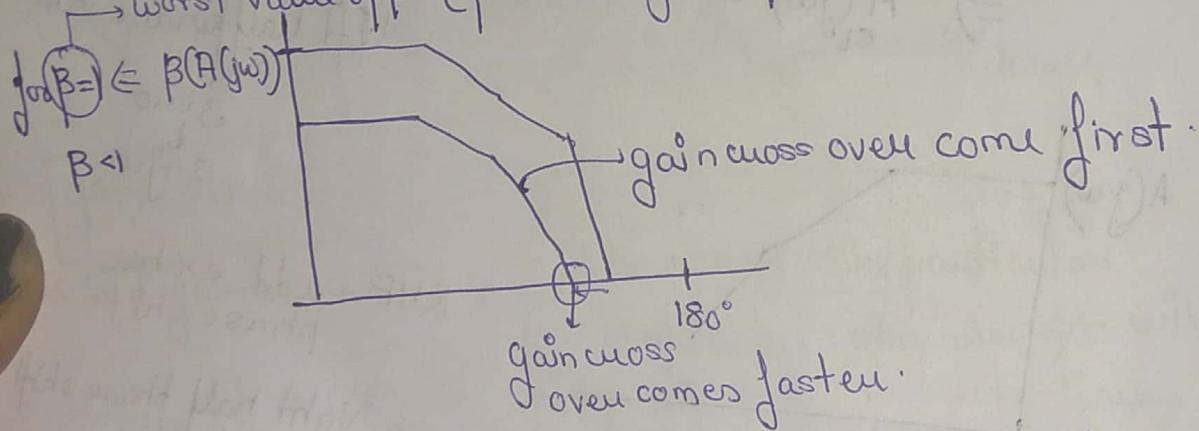
12/03/19



\Rightarrow gain cross over should come before phase cross over.

Q How much phase margin one should have?

worst value of β . [feedback gain, $\beta < 1$]



$\beta A(j\omega) = 1 \rightarrow \text{phase margin} = 0^\circ, \text{phase shift} = 180^\circ \rightarrow \text{gain will be } \infty$

$$\beta = \frac{A(j\omega)}{1 + \beta A(j\omega)}$$

$$\beta A(j\omega) = -1 \quad \text{so phase margin} = 30^\circ$$

$$\beta A(j\omega) = |H(j\omega)| e^{j\theta}$$

$\beta \leq 1$ considering worst case scenario of β . [$\beta=1$].

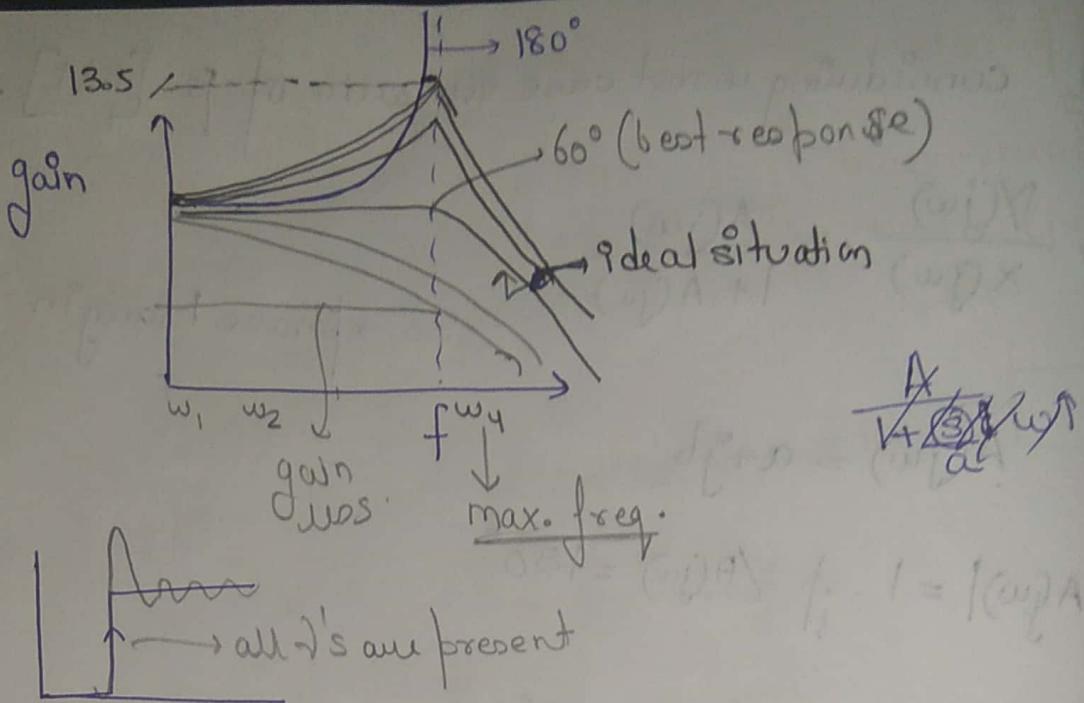
$$\Rightarrow \frac{Y(j\omega)}{X(j\omega)} = \frac{A(j\omega)}{1 + A(j\omega)}, \quad 30^\circ \rightarrow \text{phase Margin}.$$

$$A(j\omega) = a + jb.$$

$$|A(j\omega)| = 1 \quad \angle A(j\omega) = 150^\circ$$

$$\Rightarrow A(j\omega) = 0.66 - 0.38j$$

$$\begin{aligned} \therefore \frac{Y(\omega)}{X(j\omega)} &= \frac{0.66 - 0.38j}{1 + 0.66 - 0.38j} \\ &= \frac{0.66 - 0.38j}{1.66 - 0.38j} \\ &= \frac{(0.66 - 0.38j)(1.66 + 0.38j)}{2.9} \\ &= 1.0958 = \frac{0.9512 - [0.2508 + 0.6308]}{2.9} \\ &= \frac{0.9512}{2.9} \\ &= \frac{0.9512 - 0.8816j}{2.9} \\ &= \frac{1}{2.9} \sqrt{(0.9041) + 0.772} \\ &= \frac{1}{2.9} \times (1.6819) \\ &= 0.447 \end{aligned}$$



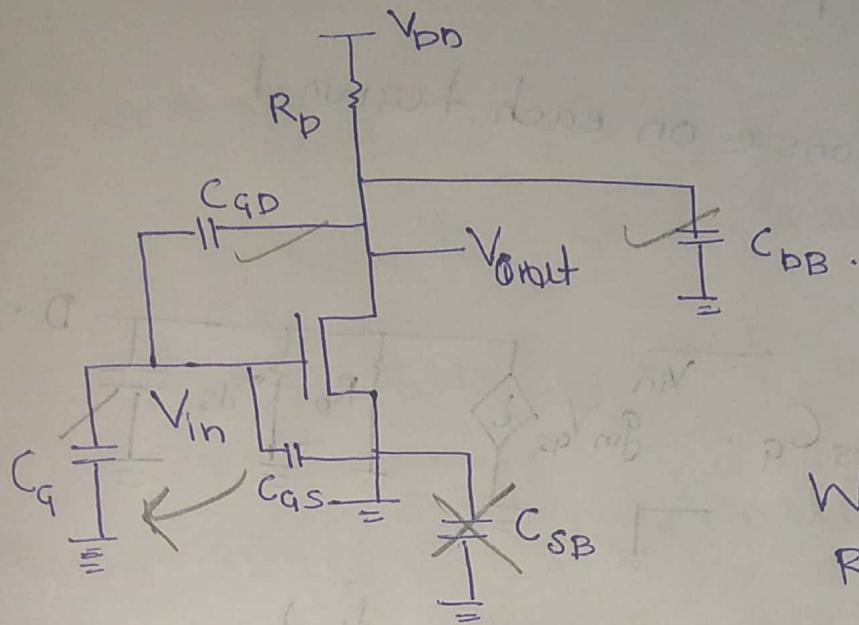
→ when gain is ∞ undamped, $180^\circ - 22.5^\circ = 157.5^\circ$ phase margin

→ underdamped. $180^\circ - 22.5^\circ = 157.5^\circ$ phase margin

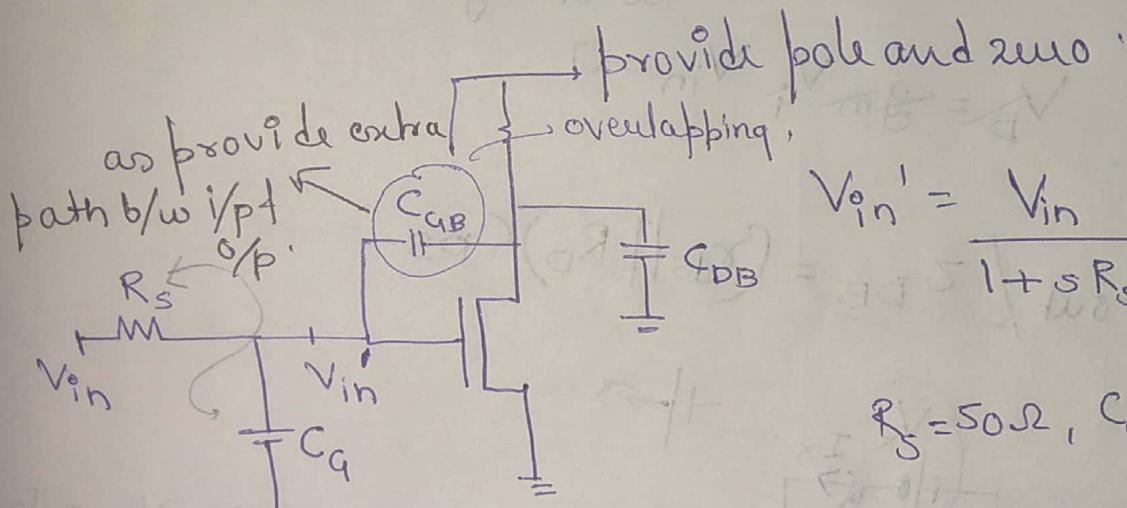
→ overdamped. $180^\circ - 30^\circ = 150^\circ$ phase margin

→ critical $180^\circ - 45^\circ = 135^\circ$ phase margin (best response)

$$\frac{A \left(1 + \frac{s}{\omega_1}\right)}{\left(1 + \frac{s}{P_1}\right) \left(1 + \frac{s}{P_2}\right)} \cdot \frac{(s+1)(s+1)(s+1)}{(s+1)(s+1)(s+1)}$$



We are safe if
Rf & C are less

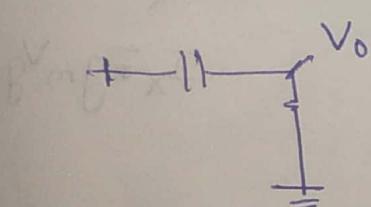


$$V_{in}' = \frac{V_{in}}{1 + s R_S C_G}$$

$$R_S = 50\Omega, C_G = 100 \text{ fF} \quad 10^{15}$$

$$P = \frac{1}{R_S C_G} = \frac{50}{100 \times 1}$$

$C_{GB} \rightarrow$ provides zero



$$V'_o = \frac{V_o R_S C}{1 + R_S C} \rightarrow \text{provides one pole zero}$$

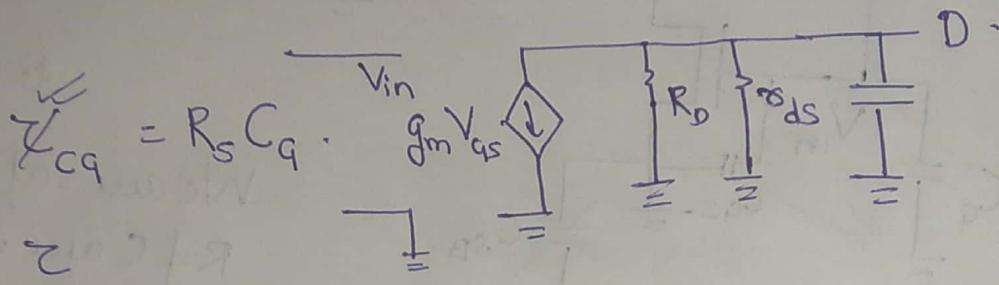
we need to see poles will have dominant effect

B.W. if R_S \rightarrow pole location large.

$$= -g_m R_D \left(1 + \frac{s}{P_1}\right)$$

$$\frac{\left(1 + \frac{s}{P_1}\right)\left(1 + \frac{s}{P_2}\right)\left(1 + \frac{s}{P_3}\right)}{R_D}$$

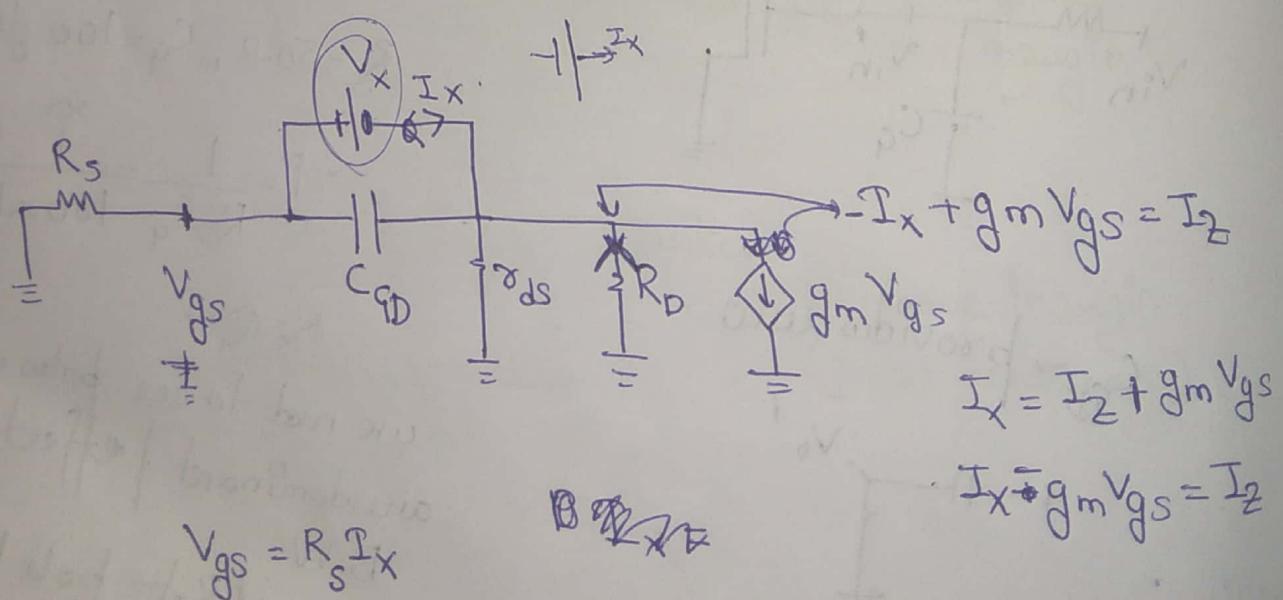
\Rightarrow We see 3 response on each terminal



when find

$$V_D = g_m K_q V_{in} = 0$$

$$Z_{out} / Z_{DB} = (\gamma_{ds} || R_D) C_{PS}$$



$$(-I_x + g_m I_x R_S) R_o - V_x = -I_x R_S.$$

$$(R_s + R_o + g_m R_s R_o) = \frac{V_x}{I_x}$$

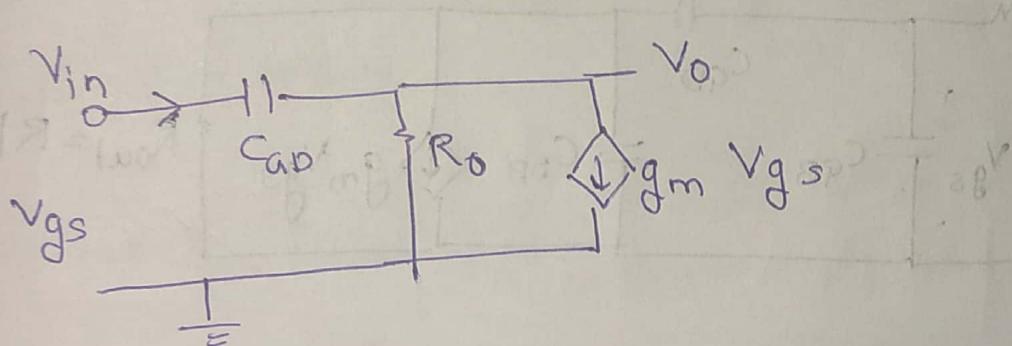
$$\tau_{C_D} = \text{large}$$

$\Rightarrow 3R_i C_i \rightarrow$ have to find dominant pole

$$P_1 = [C_g R_s + C_{DB} (\infty_d || R_D) + C_{GD} g_m R_s (\infty_s || R_D)]$$

Like wise other pole f zero as well

At first pole \rightarrow gain \downarrow by 3dB \rightarrow 3dB

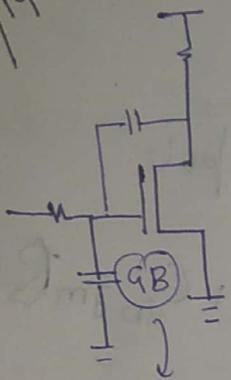


$$\begin{aligned} \frac{(V_{in} - V_o) s C_{GD}}{1 + s C_{GD} R_o} &= \frac{V_o}{R_o} + g_m V_{in} \\ V_{in} (s C_{GD} - g_m) &= V_o \left(\frac{1}{R_o} + s C_{GD} \right) \\ \frac{\cancel{R_o} + s C_{GD}}{\cancel{s C_{GD}} - g_m} &= \frac{V_o}{V_{in}} \\ \frac{1}{R_o} + s C_{GD} & \end{aligned}$$

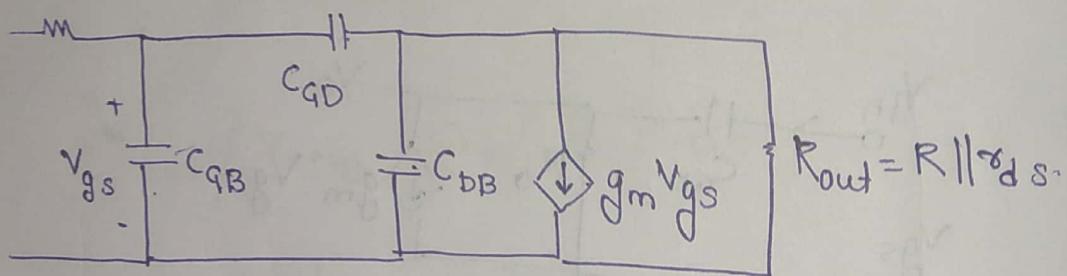
Zero \rightarrow Right half.

\downarrow
supporting \uparrow in phase shift of instability.

13/03/19



biggest cap.



$$\frac{V_o}{V_{in}} = -g_m R_{out} \left(1 - \frac{s C_{GD}}{g_m} \right)$$

$$\begin{aligned} & \frac{s^2 (C_{GD} C_{PB} + C_{DB} C_{GB} + C_{GB} C_{GD}) R_{out} R_S}{(C_1 C_2 + C_2 C_3 + C_3 C_1)} \\ & + s (C_{GB} R_S + C_{DB} R_{out} + C_{GD} (R_{out} + R_S + R_{out} R_S g_m)) + 1 \end{aligned}$$

$$= \frac{A_0 \left(1 + \frac{s}{\beta_1}\right)}{\left(\frac{s}{P_1} + 1\right) \left(\frac{s}{P_2} + 1\right)} = \frac{A_0 \left(1 + \frac{s}{\beta_1}\right)}{\frac{s^2}{P_1 P_2} + s \left(\frac{1}{P_1} + \frac{1}{P_2}\right) + 1}$$

\Rightarrow Poles should be at distance - possibility will be to reach 180° ($P_2 = 10P_1$)

\Rightarrow gain slope changes gradually but phase decreases in higher amount so 180° will come fast.

$$PM = 180^\circ - \tan^{-1} \frac{\omega_{QGB}}{P_1} - \tan^{-1} \frac{\omega_{QGB}}{P_2} - \tan^{-1} \frac{\omega_{QGB}}{\beta_1}$$

$$\text{gain} = 1 \rightarrow \omega_{QGB}$$

$$\boxed{\text{We take } \cancel{\frac{\omega_{QGB}}{P_1} \leq \beta_1}}$$

$$\boxed{10\omega_{QGB} \leq \beta_1}$$

$$U_{QGB} \times 1 = P_1 \times A_{dc}$$

$$\frac{U_{QGB} \times 1}{P_1} = A_{dc} \cdot (\Rightarrow \tan^{-1}(A_{dc}))$$

$$60^\circ = 180^\circ - 89^\circ - \tan^{-1} \left(\frac{U_{QGB}}{P_2} \right) - 5^\circ$$

$$\tan^{-1} \left(\frac{U_{QGB}}{P_2} \right) = 35^\circ \quad \left[P_2 = 2.12 U_{QGB} \right]$$

$$\frac{U_{QGB}}{P_2} = 0.47$$

$\Rightarrow P_1 \ll P_2$ [Pole location should be away from each other]
 \Rightarrow if UGB should come much less earlier than P_2 .

$$\text{So } \frac{1}{P_2} \ll \frac{1}{P_1}$$

$$\frac{P_1}{P_2} = \frac{1}{C_{GB} R_s C_{DB} R_{out} + C_{GD} g_m R_{out} R_s} \quad (1)$$

\downarrow ~~2dB less BW~~
 \downarrow BW will become less.

huge value.

$$\frac{1}{P_1 P_2} = R_{out} R_s (C_{GB} \dots)$$

$$\frac{C_{GD} - C_{DB} R_{out} + C_{GD} g_m R_{out} R_s}{R_{out} R_s (C_{GD} C_{GB} + C_{GB} C_{DB})} = P_2$$

GB \rightarrow high capacitance.

\Rightarrow All pole location in left half.

if heavy load not there.

$$P_2 = \frac{-g_m C_{GD}}{C_{GB} (C_{GD} + C_{DB})}$$

$$Z = \frac{g_m}{C_{GD}}$$

$Z \rightarrow 0 \rightarrow$ right half.

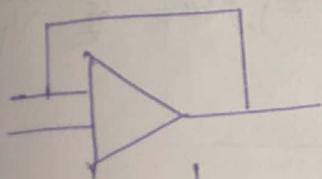
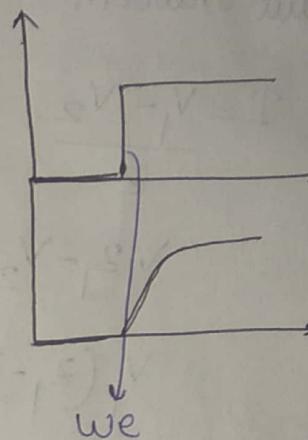
→ Common
Source
Amplifier

$$P_I = -\frac{1}{g_m R_{out} R_S C_{GD}}$$

$$A_{dc} = -g_m R_{out}$$

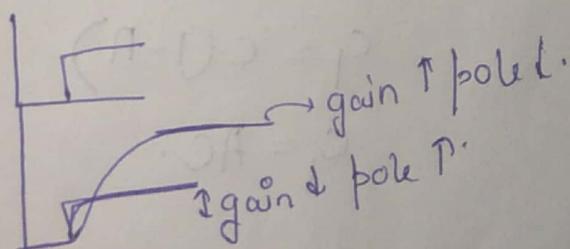
$$U_{GB} = P_I \times A_{dc}$$

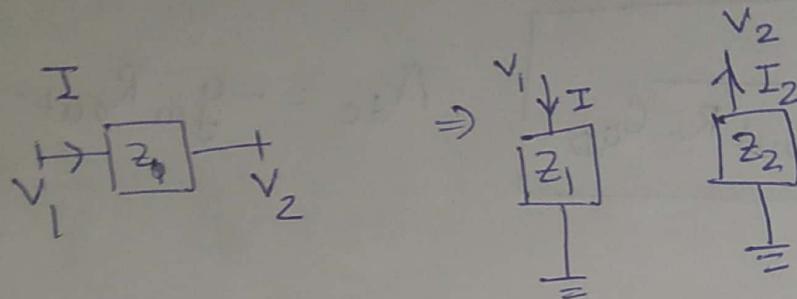
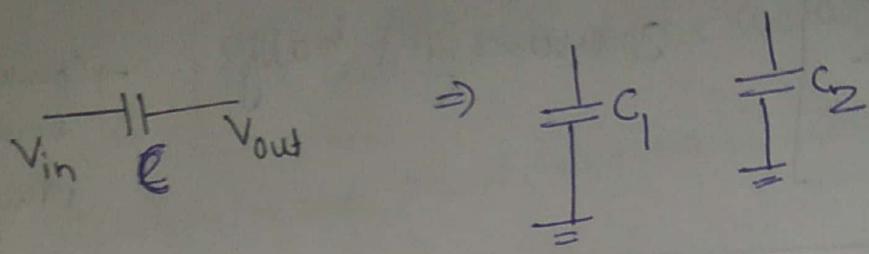
$$U_{GB} = \frac{1}{R_S C_{GD}}$$



$$\frac{\frac{A}{1+A}}{1 + \frac{1}{a(1+A)}}$$

if we multiply gain divide gain by $1+A$, a gets multiply by same amount.





Millman's theorem

$$I = \frac{V_1 - V_2}{Z} = \frac{V_1}{Z_1}$$

$$V_1 Z_1 - V_2 Z_1 = V_1 Z$$

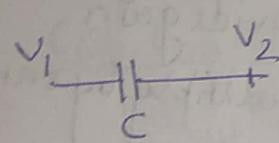
$$\frac{V_1 - V_2}{Z} = -\frac{V_2}{Z_1}$$

$$\frac{V_1}{Z_1} = V_2 \left(\frac{1}{Z} + \frac{1}{Z_1} \right)$$

$$V_1 (Z_1 - Z) = V_2 Z_1$$

$$\frac{V_1}{Z_1} + \frac{1}{Z_1} = \frac{V_2}{Z} = \frac{V_2}{Z_1}$$

$$\frac{V_1}{Z_1} = V_2$$



$$\frac{1}{\underline{I}} C$$

$$\frac{1}{\underline{I} C} = \frac{1}{1 - A}$$

$$C_1 = C(1 - A)$$

$$C_1 = AC$$

~~$$\frac{V_1}{Z_1}$$~~

$$Z_2 = \frac{2}{1 - \frac{1}{A}}$$

$$\frac{1}{Z_1} = A \left(\frac{Z_1 + Z}{Z_1} \right)$$

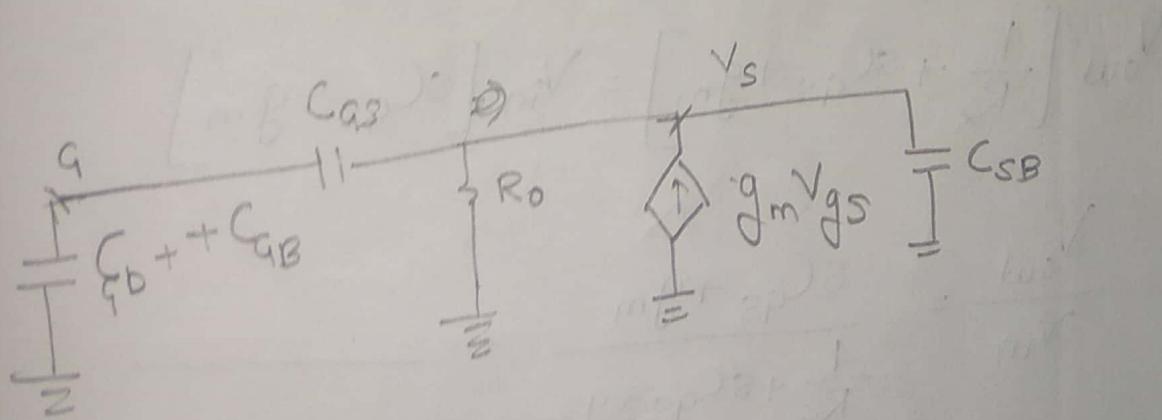
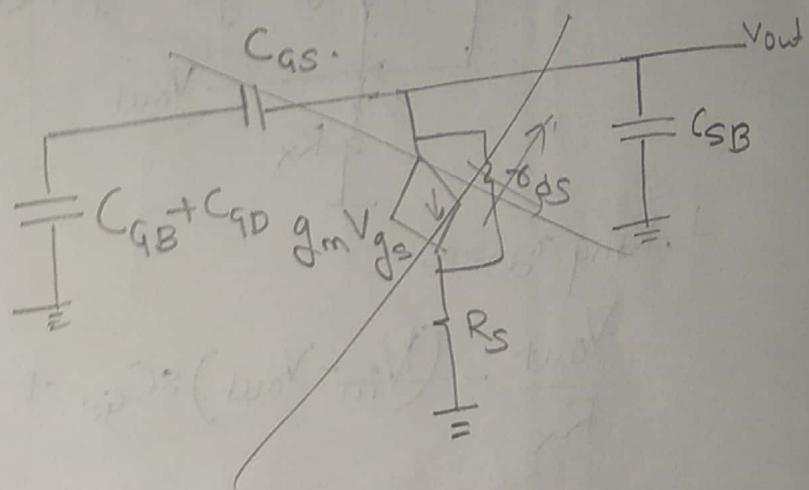
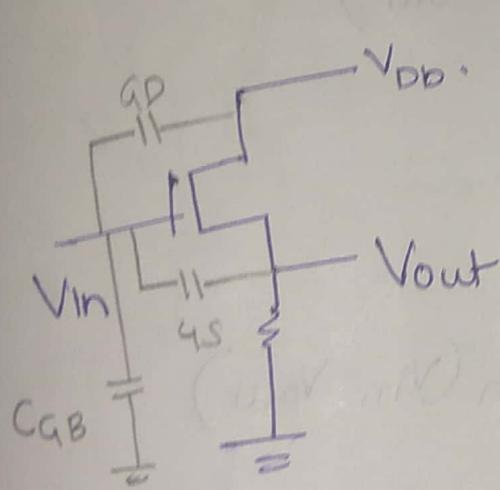
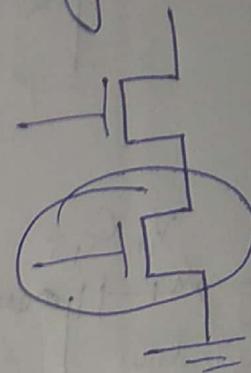
$$Z = A$$

$$Z(1 - A) = A^2 Z$$

$$\boxed{Z_2 = \frac{Z}{1 - \frac{1}{A}}}$$

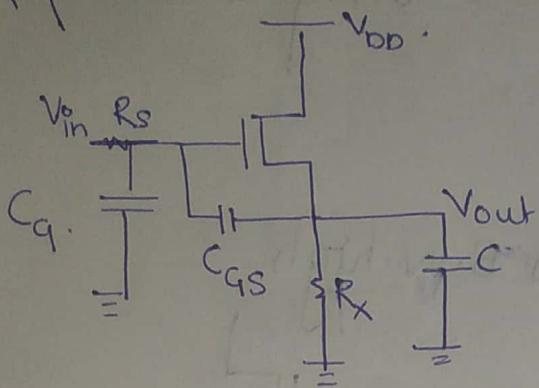
\Rightarrow When gain is finite constant only we can apply Miller.

\Rightarrow Cascode one has Miller Block. B.W high

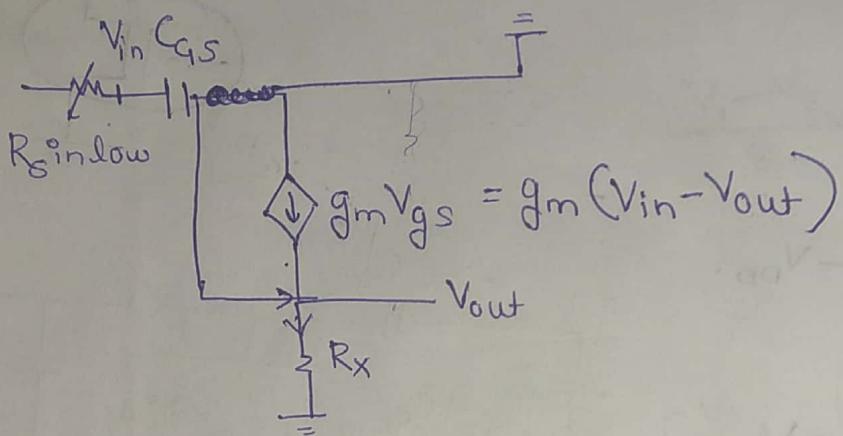


C_{SB}

14/03/19



To find zero location
of the circuit



taking $\infty_{DS} = \infty$.

$$\frac{V_{out}}{R_X} = (V_{in} - V_{out}) sC_{QS} + g_m (V_{in} - V_{out})$$

$$V_{out} \left[\frac{1}{R_X} + sC_{QS} + g_m \right] = V_{in} \left[sC_{QS} + g_m \right]$$

$$\frac{V_{out}}{V_{in}} = \frac{sC_{QS} + g_m}{\frac{1}{R_X} + sC_{QS} + g_m} = \frac{\dots}{\dots}$$

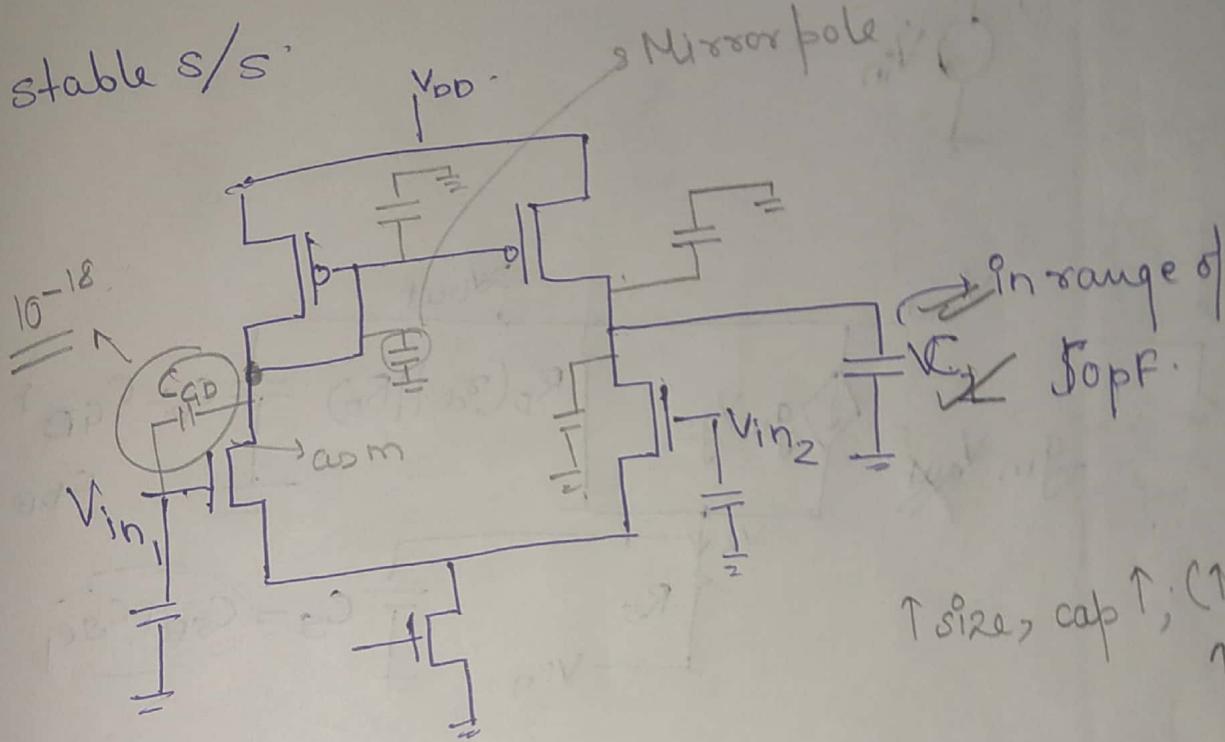
$$\begin{aligned} \text{D.E.gain} &= A_d = -g_m \times \left[\frac{1}{g_m} || R_X \right] \\ &= g_m \times \left[\frac{1}{g_m R_X} \right] = \frac{g_m R_X}{1 + R_X g_m} \end{aligned}$$

$$z = -\frac{g_m}{C_{GS}}$$

left half zero phase shift
change.

$$\text{Phase} = \tan^{-1}\left(\frac{C_{GS}}{g_m C_{GS}}\right)$$

\Rightarrow stable s/s



\uparrow size, cap \uparrow ; (\uparrow gain,
 \uparrow gm)

\Rightarrow Cap lower, zero at higher ω

$$R = 100 \text{ k}\Omega$$

$$= 10^2 \times 10^3$$

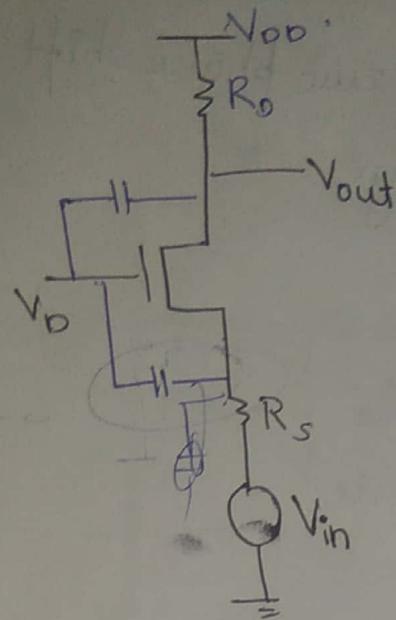
$$= 10^5$$

$$C = 10^{-12}$$

$$w = \frac{1}{10^{-12} \times 10^5}$$

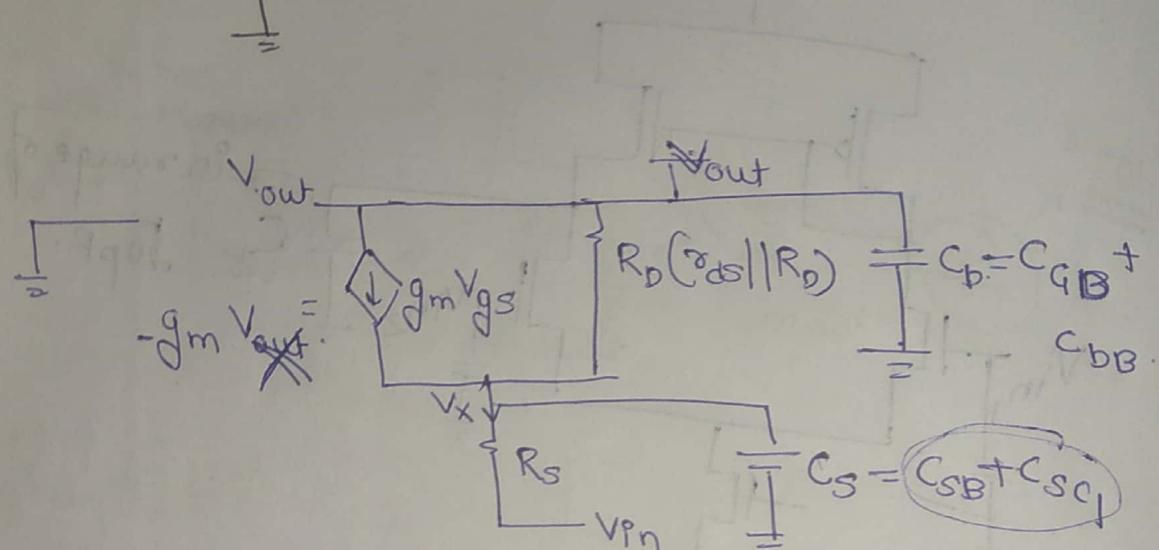
$$w = \frac{1}{10^{-7}}$$

$$W = \frac{N \cdot H_B}{\text{form}}$$



No zero is here.

B.W is higher as there is no zero.



$$\frac{V_x - V_{in}}{R_s} + (V_x - V_{in}) s C_s$$

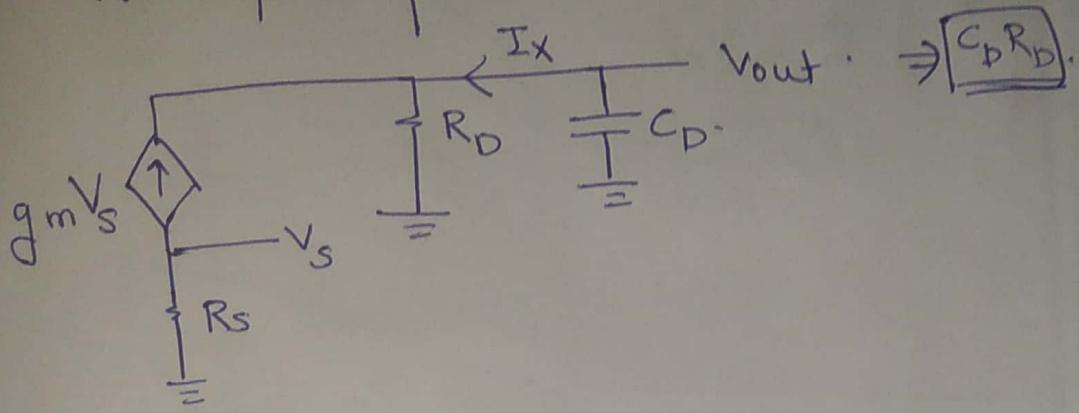
$$= -g_m V_{\cancel{x}} + \frac{(V_{out} - V_x)}{R_D} + (V_{out} - V_x) C_b$$

$$-g_m V_x = (V_{out} - V_x) R \quad \boxed{P_i = \frac{1}{C_s R}}$$

$$\frac{-g_m V_x}{V_o - V_x} = R$$

$$\frac{V_x - V_{in}}{R_s} =$$

When finding C_D



$$\cancel{\frac{g_m V_s}{R}} = \cancel{\frac{V_s}{R_s}}$$

$$R_s = \cancel{\frac{1}{g_m}}$$

$$(g_m V_s) R = V_o - V_s$$

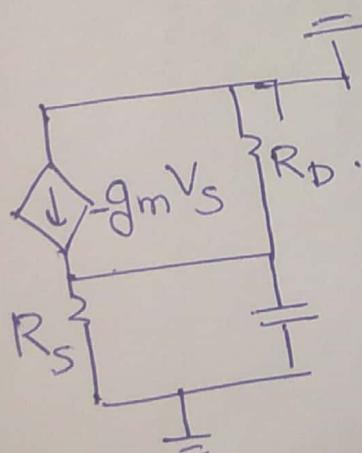
$$R' = \left(\frac{V_o - V_s}{g_m V_s} \right)$$

$$R' = \frac{V_s - V_o}{g_m V_s}$$

$$R_D \parallel \cancel{\frac{1}{g_m}}$$

$$(g_m V_s) R =$$

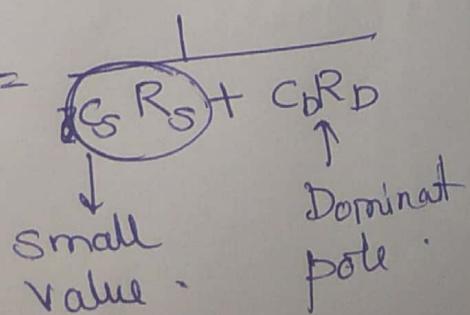
$$V_s = 0 \quad g_m + \frac{1}{R_s} = 0$$

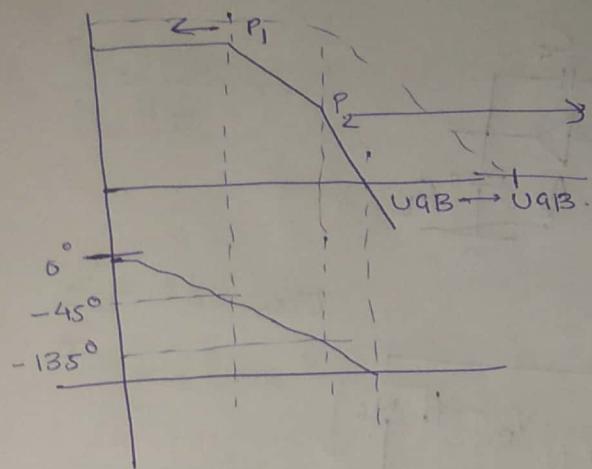


$$\frac{R_D}{1 + g_m R_s} \parallel R_s$$

$$\Rightarrow R_s$$

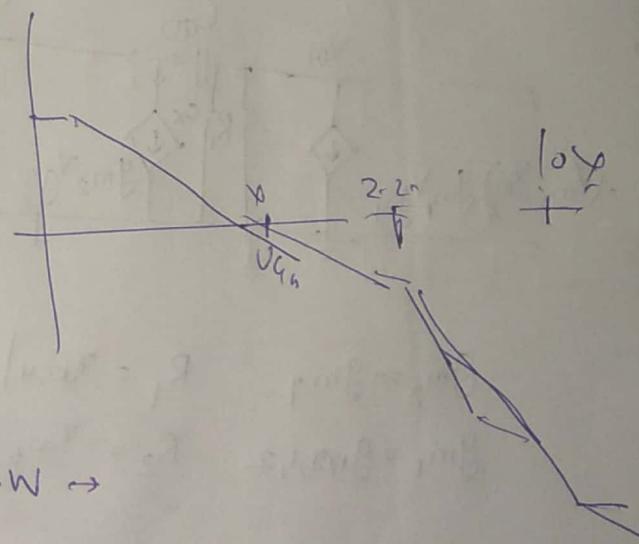
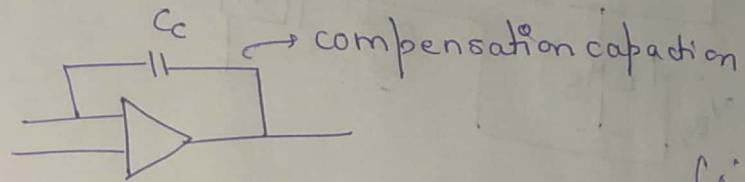
= Dominant pole



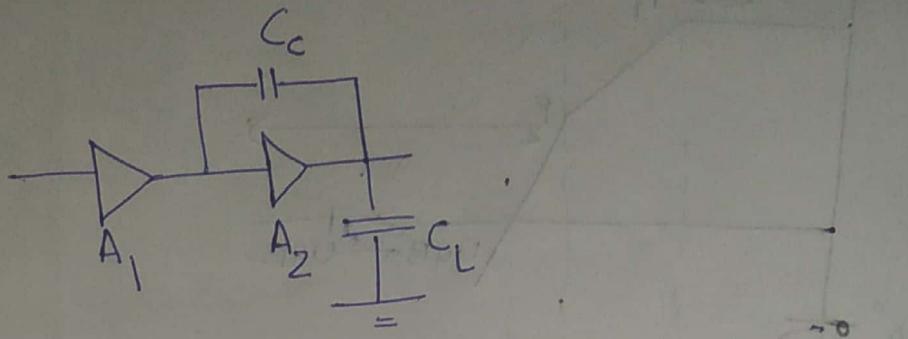


$$\frac{A}{1 + \frac{S}{P_r}} = \frac{A}{1 + \frac{S}{PC + A}}$$

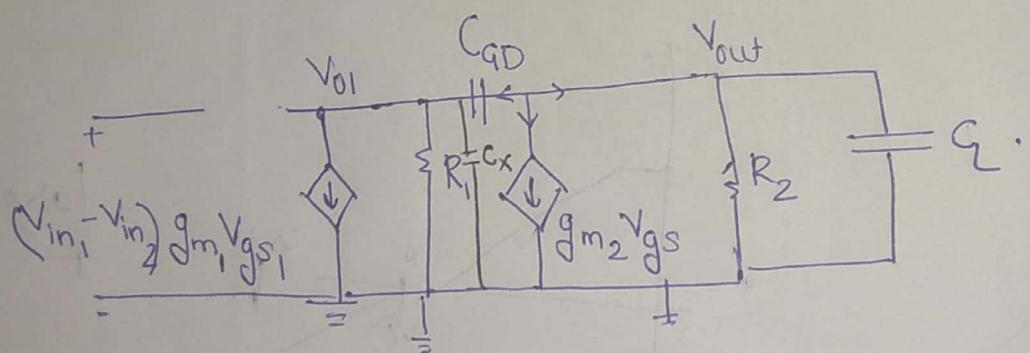
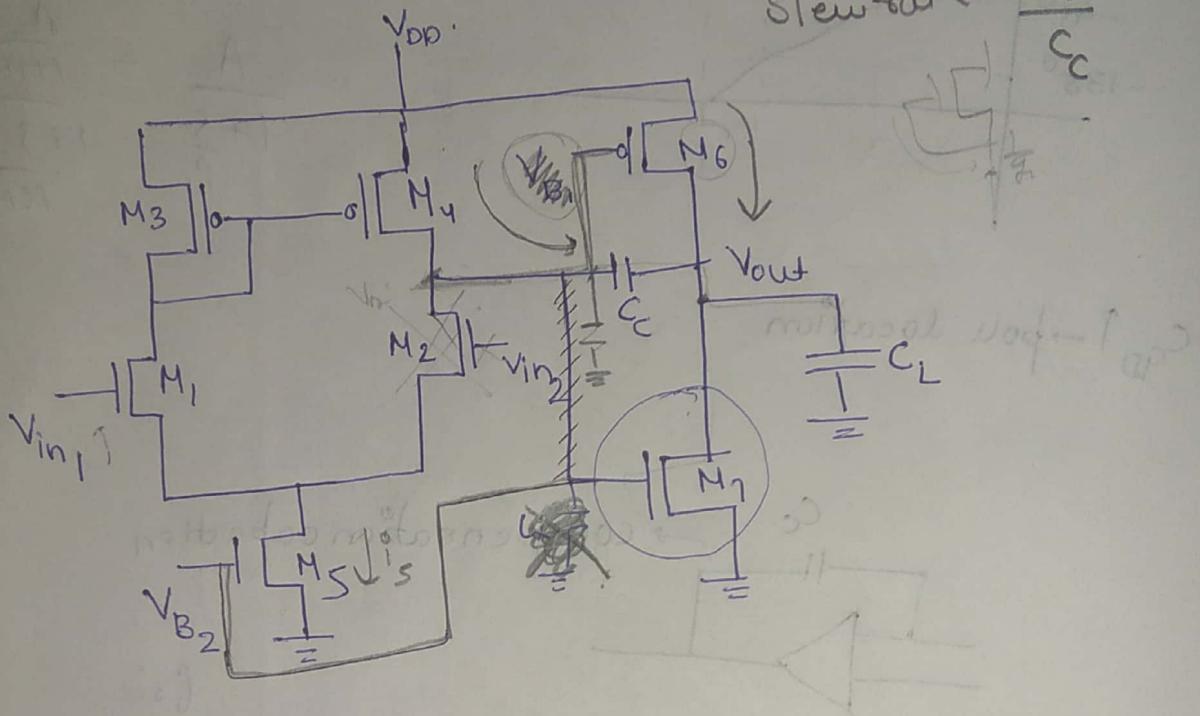
$C_{QD} \uparrow \rightarrow$ pole location



We are ↑ stability not B.W. \rightarrow



$$\text{Slew-rate} = \frac{1}{2\pi f_c C_c}$$



$$g_{m_2} = g_{m_7} \quad R_1 = r_{ds,4} \parallel r_{ds,2}$$

$$g_{m_1} = g_{m_2,1,2} \quad R_2 = r_{ds,6} \parallel r_{ds,7}$$

W.B. for didots!

$$\frac{V_{out} - 0}{R_2 \parallel Z_L} + g_{m_2} V_{gs} +$$

$V_{in} - V_{out}$
 → single cap f
 V_{in} & V_{out} same
 than left half zero
 & op. R_{in} &

$$\frac{V_{out}}{V_{in}} = -g_{m_I} g_{m_{II}} R_I R_{II} \left(1 - \frac{s C_c}{g_{m_2}} \right) \xrightarrow{\text{right half}}$$

$$\frac{s^2 R_I R_{II} (C_c C_x + C_x C_L + C_L C_c)}{s (C_c g_{m_{II}} R_I R_{II} + C_x R_I + C_L R_{II}) + 1} \xrightarrow{\substack{C_x \rightarrow \text{femto farad} \\ \text{can be neglected.}}}$$

$$P_1 = \frac{-1}{C_c g_{m_2} R_I R_2}$$

$$P_2 = \frac{-g_{m_I} R_I R_{II} C_c}{R_L R_{II} C_c C_L} = \frac{-g_{m_I}}{C_L}$$

⇒ All pole are left hand side.

$$U_{QB} * \frac{g_{m_I} g_{m_{II}} R_I R_{II}}{g_{m_2} R_I R_{II} C_c} = \frac{g_{m_I}}{C_c}$$

$$Z_{\text{emo}} = \frac{g_{m_2}}{c_c}$$

$Z_{\text{emo}} > 10V_{GB} \rightarrow 60^\circ \text{ phase margin}$

$$\frac{g_{m_{II}}}{c_c} > 10 \frac{g_{m_I}}{c_c}$$

$$\boxed{g_{m_{II}} > 10 g_{m_I}}$$

$$P_2 > 2.12 V_{GB}$$

~~$$\frac{g_{m_{III}}}{c_L} > 2.2$$~~

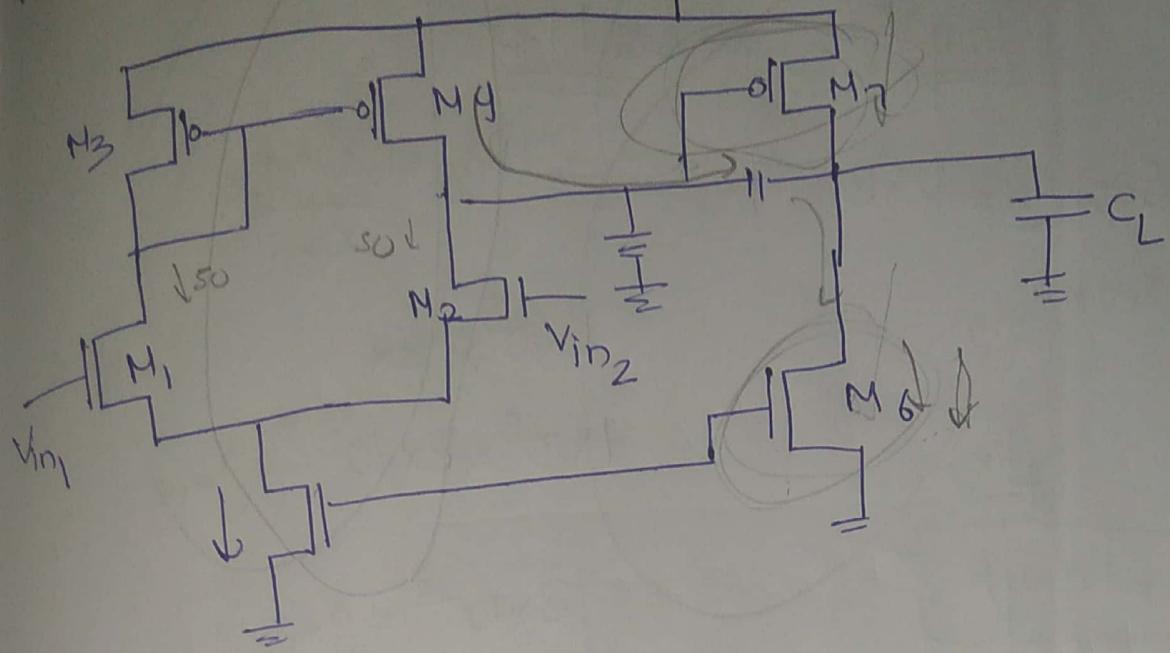
$$\frac{g_{m_2}}{c_L} > 2.2 \frac{g_{m_I}}{c_c}$$

$$\frac{10}{c_L} > \frac{2.2}{c_c}$$

$$\boxed{c_c > 0.22 c_L}$$

For slew rate = $\frac{V_{GS}}{\tau}$

Hen Hallberg



$$g_m = \beta V_{GS}$$

$$\frac{g_{m1}}{g_{m2}} = \frac{\beta_1 V_{GS1}}{\beta_2 V_{GS2}}$$

$$V_{out} = \frac{1}{\lambda I_D} s$$

if V_{GS} are same

$$\frac{g_{m1}}{g_{m2}} = \frac{I_{D1}}{I_{D2}}$$

$$V_{DD} = 3V, \lambda = 0.05V^{-1}, |V_{TH}| = 0.6V, \text{ gain} = 5000V/V, \text{ slew rate} = 10V/\mu s, P_D = 10mW, C_L = 10pF$$

$$\mu_n C_{ox} = 300 \mu A/V^2, \mu_p C_{ox} = 100 \mu A/V^2, N_{DD}, N_{AS}$$

$$ICMR = 1 - 2.6V, B.W = 500KHz$$

$$C_C = 30pF, C_L = 3pF$$

$$V_{dsat} = \sqrt{\frac{2I_D}{\beta}}$$

~~$$\frac{i_{SS}}{C_C} = 10$$~~

~~$$\frac{i_{SS}}{C_C} = 10 \times 10 \times 10^{-6}$$~~

$$(i_{SS})_S = 10 \times 10^6 \times 3 \times 10^{-12} = 30 \mu A$$

~~$$\frac{i_S}{C_C} = 10^{-4}$$~~

$$P.D = (30 \times 3) \mu W$$

$$= \cancel{90 \mu W}, \text{ We can } \cancel{\uparrow P.D}$$

$$IMH_3 = \frac{g_{m1,2}}{C_C}$$

$$500K4_3 = UGB$$

$$500K4_3$$

$$1 \times 10^6 \times 3 \times 10^{-12}$$

$$1 \times 10^6 \times 3 \times 10^{-12} = g_{m1,2}$$

~~$I_s = 100 \mu A$~~

$$\boxed{3 \times 10^{-6} = g_{m1,2}}$$

$$g_m = \sqrt{QB I_D}$$

$$\beta_{1,2} = \frac{g_m^2}{2I_D} = \frac{9 \times 10^{12}}{2 \times 100 \times 10^{-6}} = \frac{9 \times 10^{-6}}{2} \times 10^2$$

$$\begin{aligned} ICNR &\rightarrow \min \\ I &= V_{dsat1,2} \\ &\hookrightarrow \beta_{1,2} \end{aligned}$$

$$ICNR \rightarrow \max, \frac{W_n C_{ox} N}{B_S} = 4.7 \times 10^{-8}$$

$$B_S \beta_2 / (A_P C_{ox}) = 4.7 \times 10^{-6} \times 10^{-2}$$

$$\text{size} \times \frac{V_D}{W_m} = 0.047 \times 10^{-6}$$

$$\boxed{g_{m2} \geq 10 g_{m1}}$$