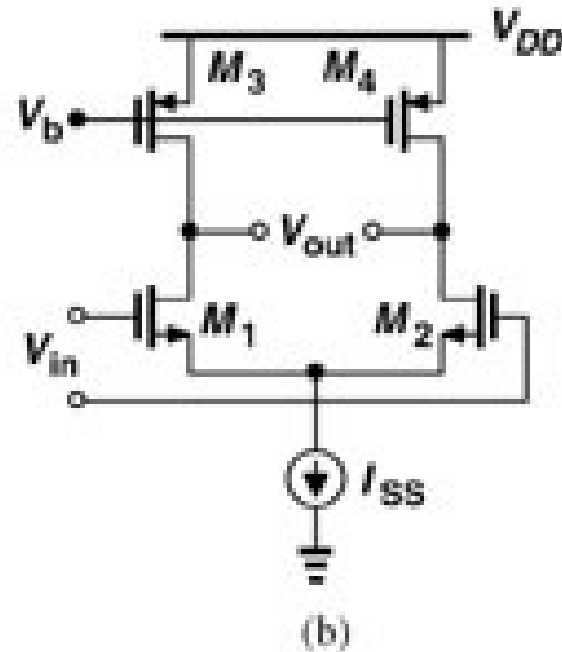
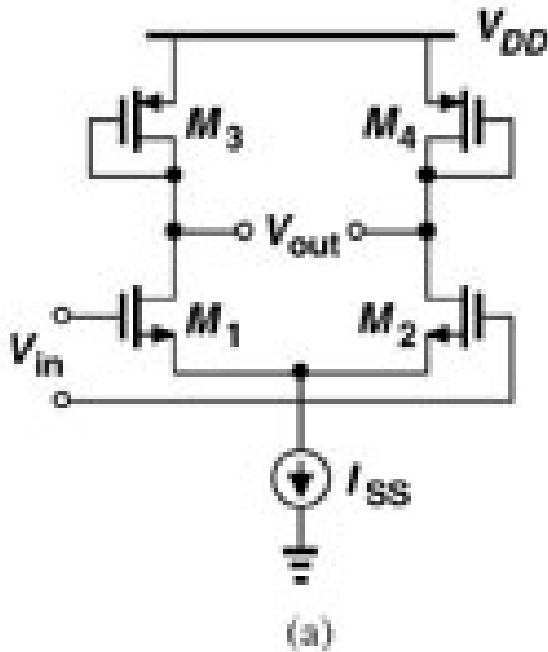


Differential Pair with MOS Loads

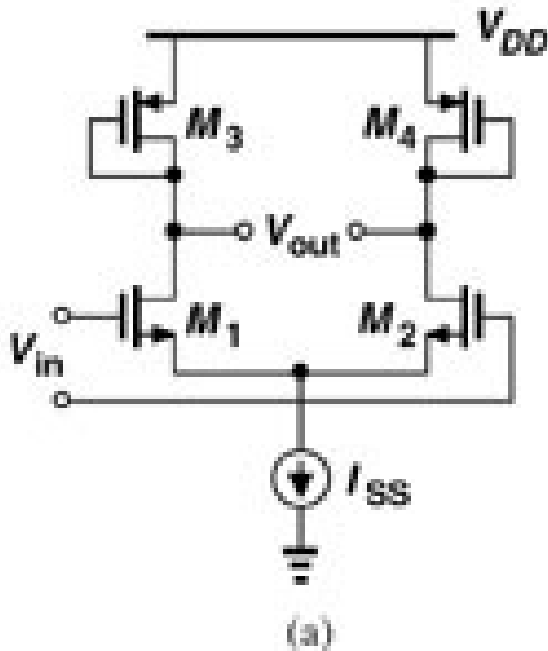
- The load of a differential pair need not be implemented by linear resistors.
- Differential pairs can employed diode-connected or current-source load.

MOS Loads

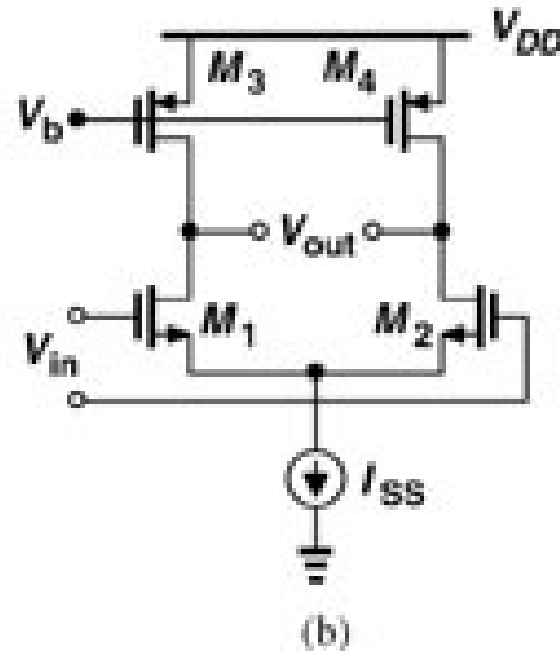


- (a) Diode-connected load
- (b) Current-Source load

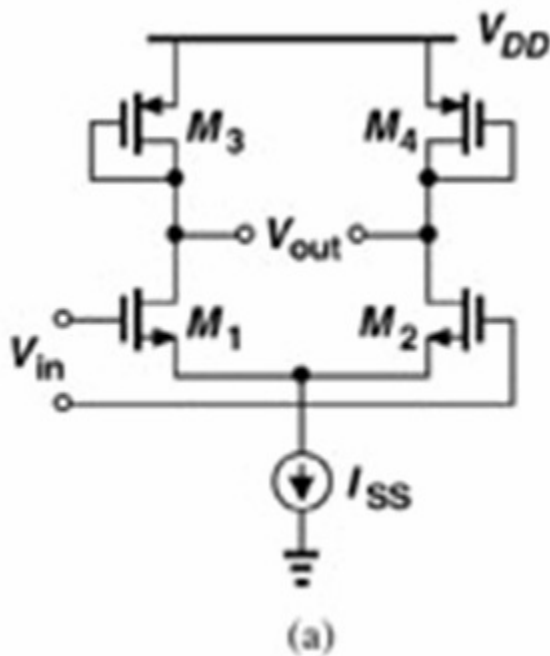
MOS Loads: Differential Gain Formulas



$$\begin{aligned}
 A_{V,diff} &= -g_{mN} (g_{mP}^{-1} \parallel r_{oN} \parallel r_{oP}) \\
 &\approx -\frac{g_{mN}}{g_{mP}} \\
 &= -\sqrt{\frac{\mu_n (W/L)_N}{\mu_p (W/L)_P}} \quad \text{A}
 \end{aligned}$$



$$A_{V,diff} = -g_{mN} (r_{oN} \parallel r_{oP}) \quad \text{B}$$



- The diode-connected loads consume voltage headroom, thus creating a trade-off between:
 - the output voltage swings,
 - the voltage gain, and
 - the input CM range.
- To achieve higher gain, $(W/L)_p$ must be decreased (from A)

Problem with this approach:

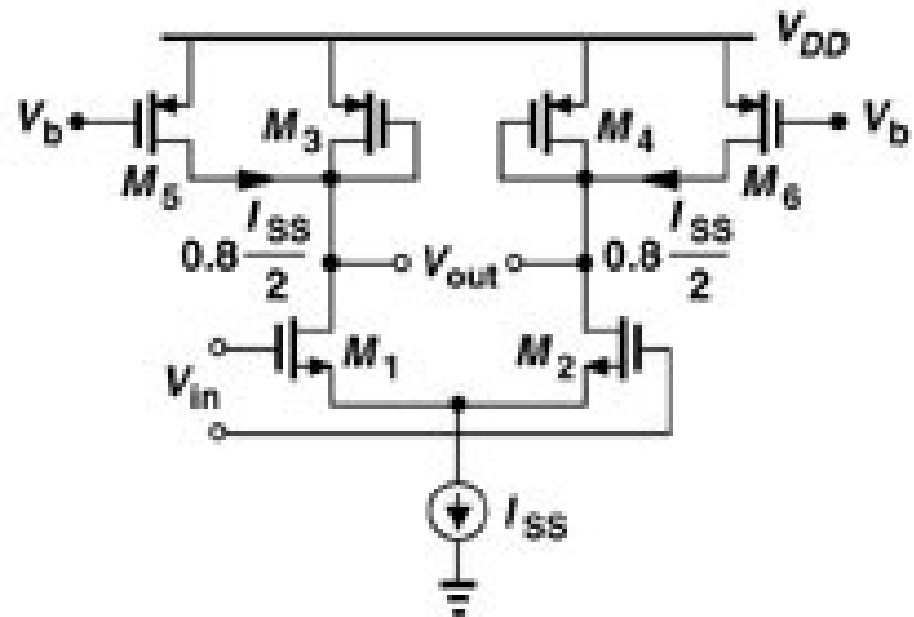
- This increases $|V_{GSP} - V_{THP}|$ and lowers the CM level at nodes X and Y (since more voltage drop across the PMOS).

Overcoming Diode-connected Load swing problem for higher gains:

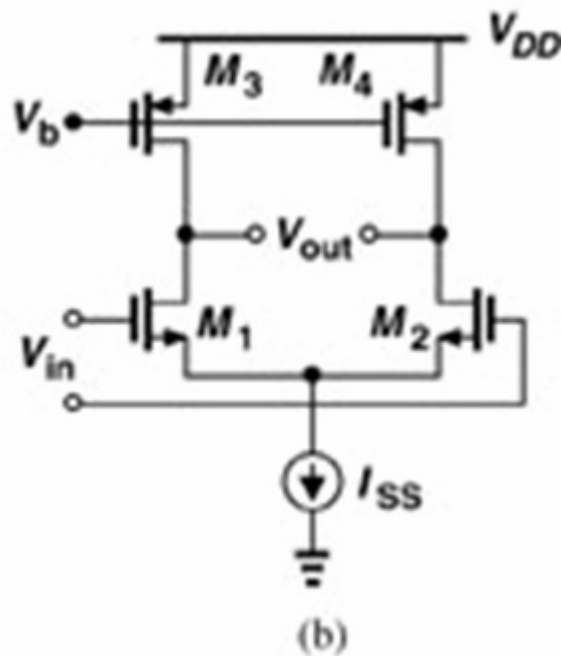
- The idea is to lower the g_m of the diode-connected MOS, instead of lowering $(W/L)_P$ of load.

Solution:

- If M_5 and M_6 carry 80% of the drain current of M_1 and M_2 , the current through M_3 and M_4 is reduced by a factor of 5.
 - reduce g_m for M_3 & M_4 (instead of lowering $(W/L)_p$)
 - gain increase by 5



Problems with Current-Source MOS Loads



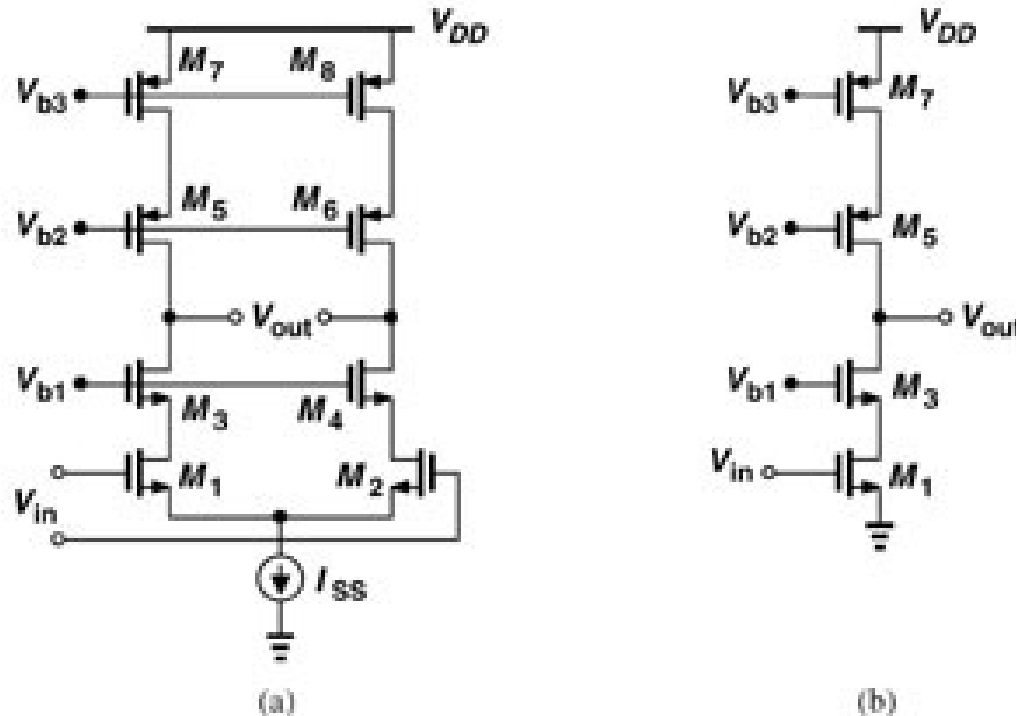
- In sub-micron technologies, it's hard to obtain differential gains higher than 10-20.

Problem: How to increase the gain for current-source MOS load?

Solution:

- From B, increase the gain by increase the output impedance.

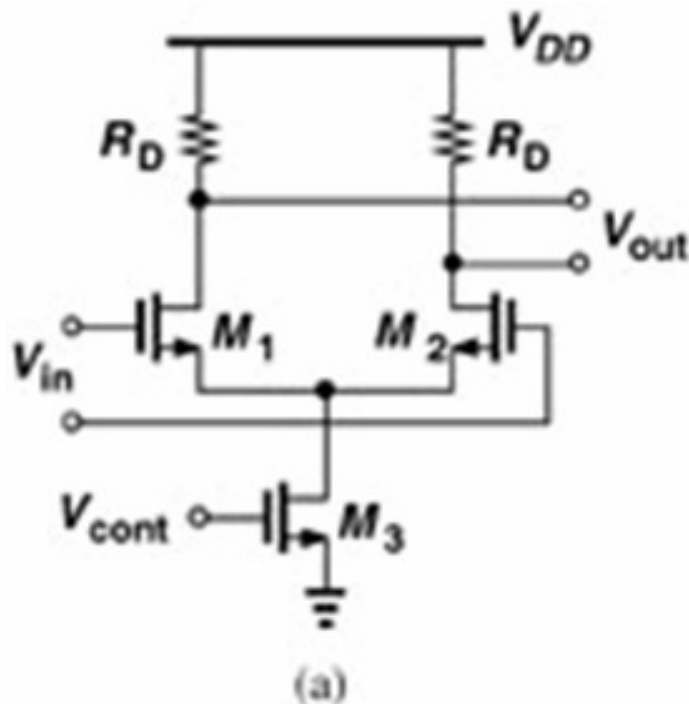
Solution to low-gain problem: Cascoding



$$A_{V,diff} \approx g_{m1}[(g_{m3}r_{o3}r_{o1}) \parallel (g_{m5}r_{o5}r_{o7})]$$

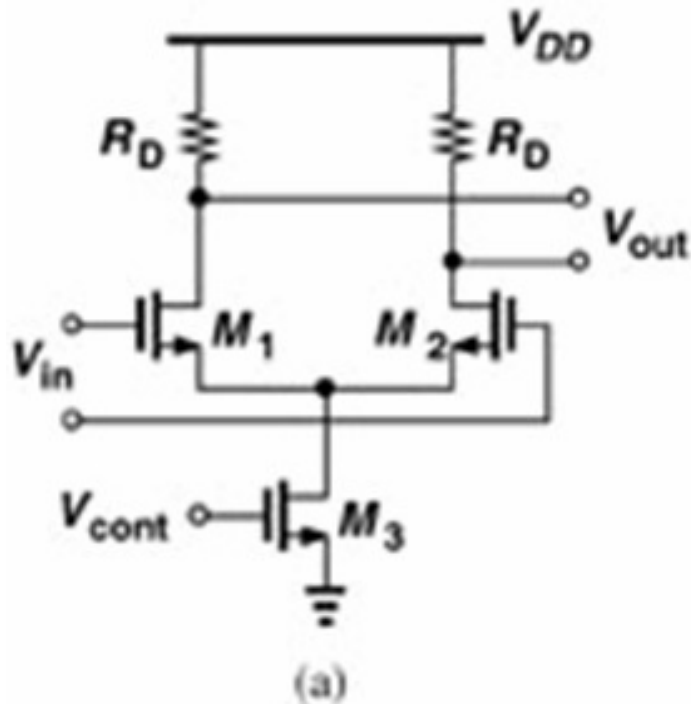
- We can increase the output impedance of both PMOS and NMOS devices by cascoding.
- Cascoding increases the differential gain substantially but at the cost of consuming more voltage headroom.

Gilbert Cell



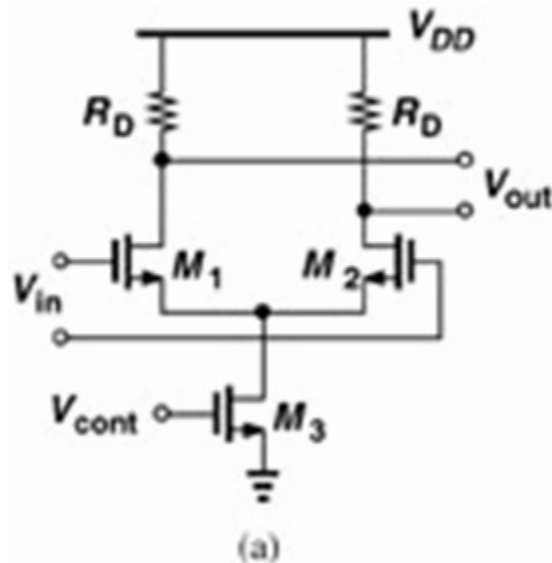
- Our study of differential pairs reveals two important aspects of their operations:
 - The small-signal gain of the circuit is a function of the tail current
 - The two transistors in a differential pair provide a simple means of steering the tail current to one of two destinations
- By combining these two properties, we can develop a versatile building block.

Gilbert Cell (contd ...)

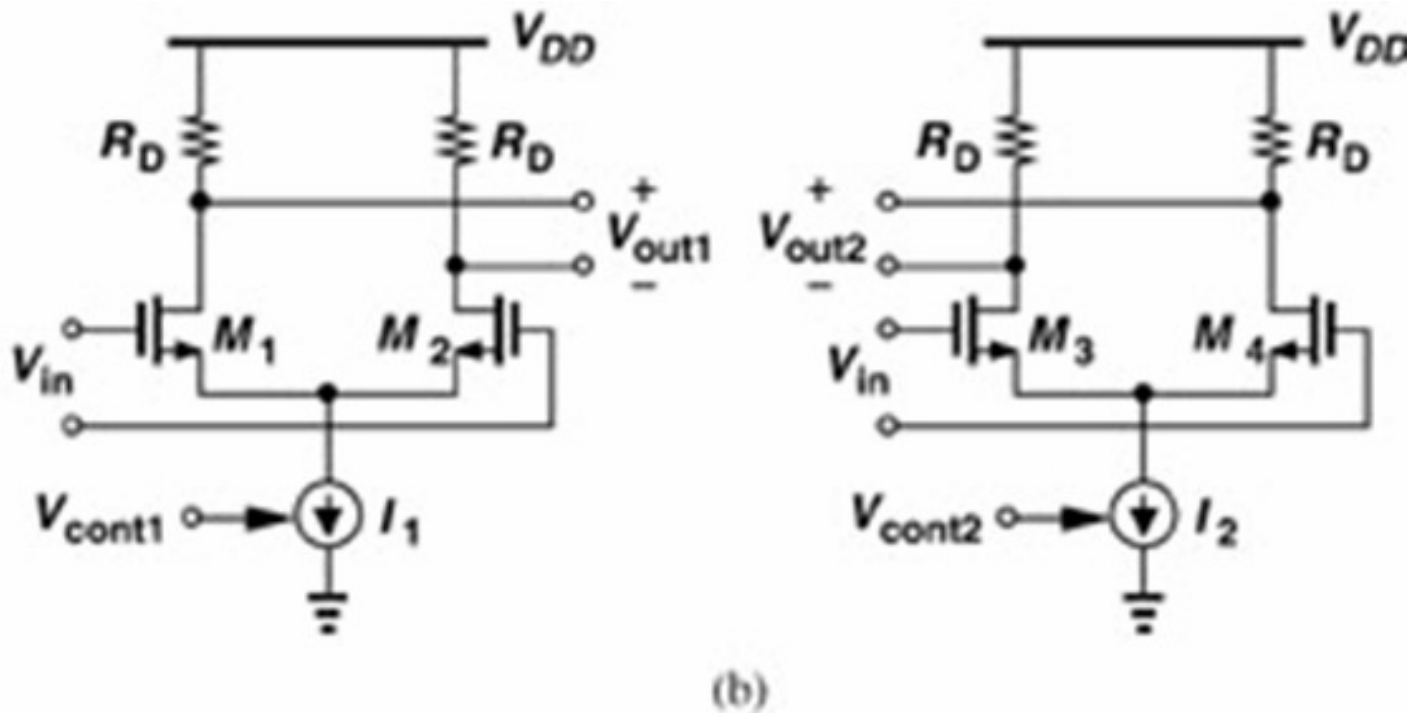


- In other word: vary $V_{cont} \rightarrow$ vary $I_{ss} \rightarrow$ vary gain
- Thus we can vary the gain by vary the input voltage.
- This is useful when input signal amplitude experience large variation and hence require inverse change in gain.
- V_{cont} define the tail current (I_{ss}) thus the gain.
- Max gain is given by:
 - Voltage headroom
 - Device dimension

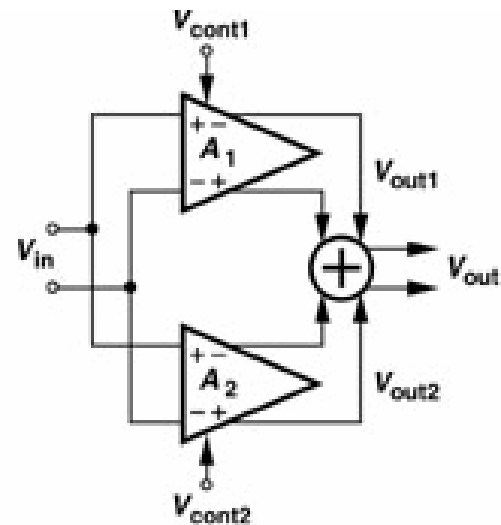
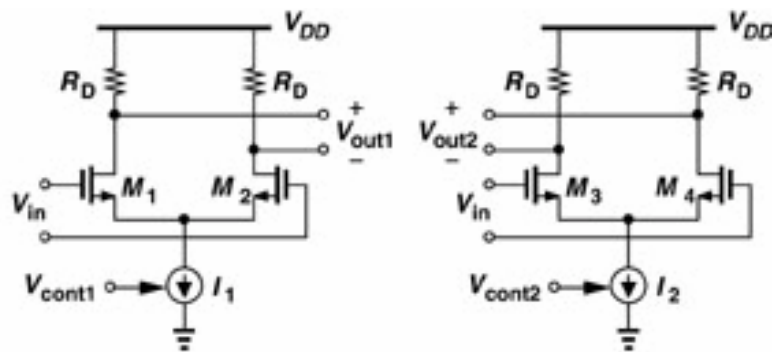
Voltage-controlled differential gain



- We can create a differential pair whose gain is varied by control voltage (Fig a).
- The control voltage defines the tail current and hence the gain.
- In this topology, $A_v = V_{out}/V_{in}$ varies from zero (if $I_{D3}=0$) to a maximum value given by voltage headroom limitations and device dimensions.
- This circuit is a simple example of a “variable-gain amplifier (VGA).
- VGAs can be used in application where the signal amplitude may experience large variation and hence require inverse changes in the gain.



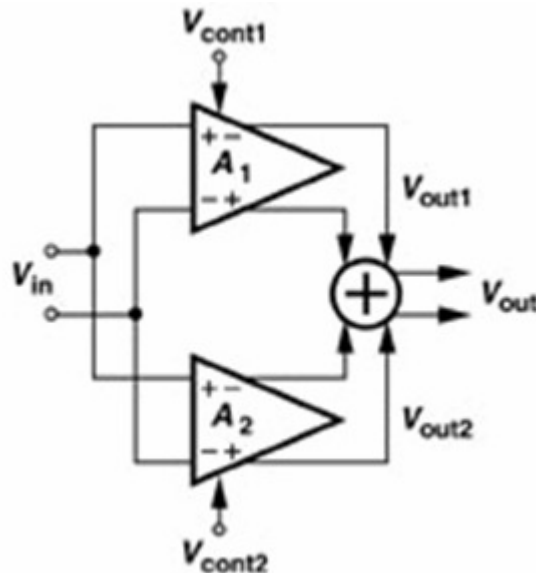
- Suppose we want an amplifier whose gain can be continuously varied from a negative value to a positive value.
- Fig (b) shows two differential pair that amplify the input by opposite gains.
- We have $V_{out1}/V_{in} = -g_m R_D$ and $V_{out2}/V_{in} = +g_m R_D$
- If I_1 and I_2 vary in opposite direction, so do $|V_{out1}/V_{in}|$ and $|V_{out2}/V_{in}|$.



(a)

- But how V_{out1} and V_{out2} can be combined into a single output?
- As shown in Fig (a), the two voltage can be summed, producing $V_{out} = V_{out1} + V_{out2} = A_1 V_{in} + A_2 V_{in}$, where A_1 and A_2 are controlled by V_{cont1} and V_{cont2} , respectively

The actual implementation is quite simple: since

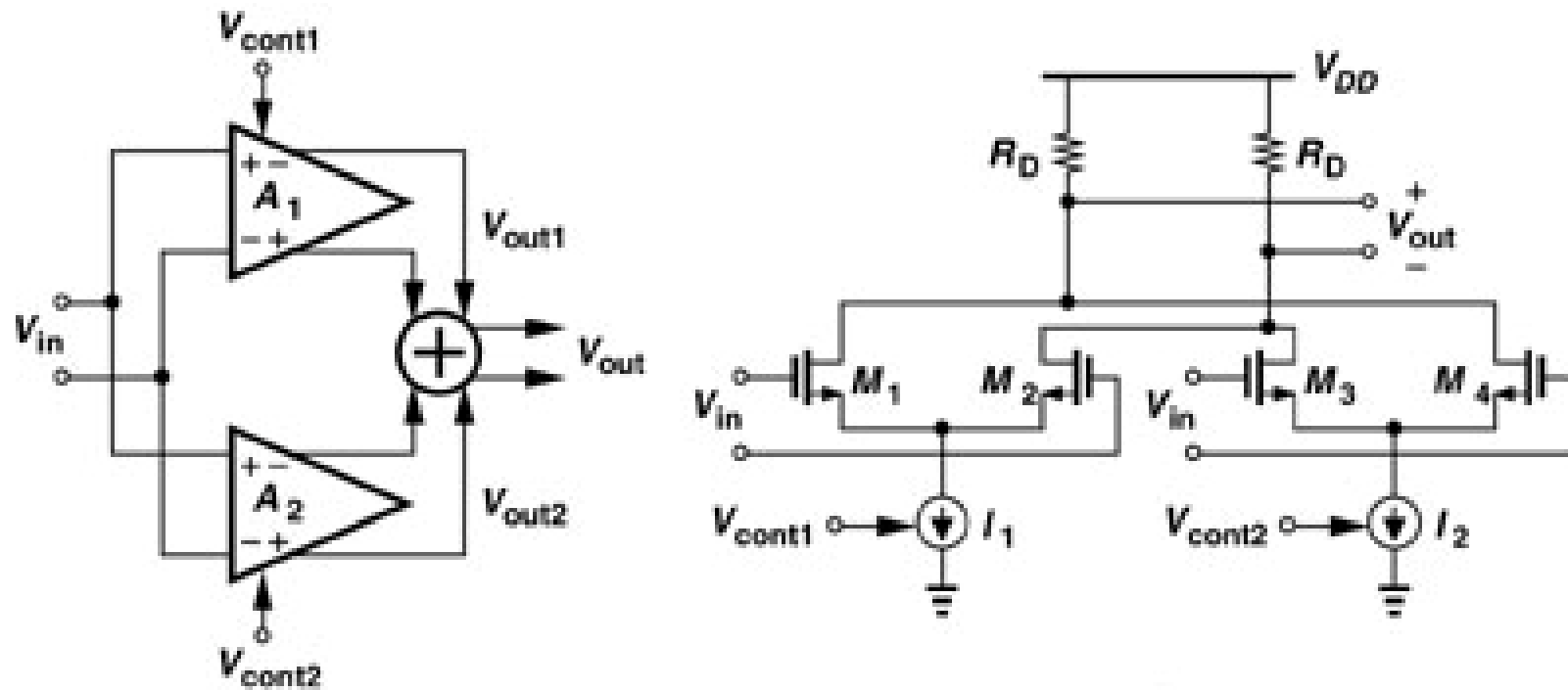


$$V_{out1} = R_D I_{D1} - R_D I_{D2} \text{ and}$$

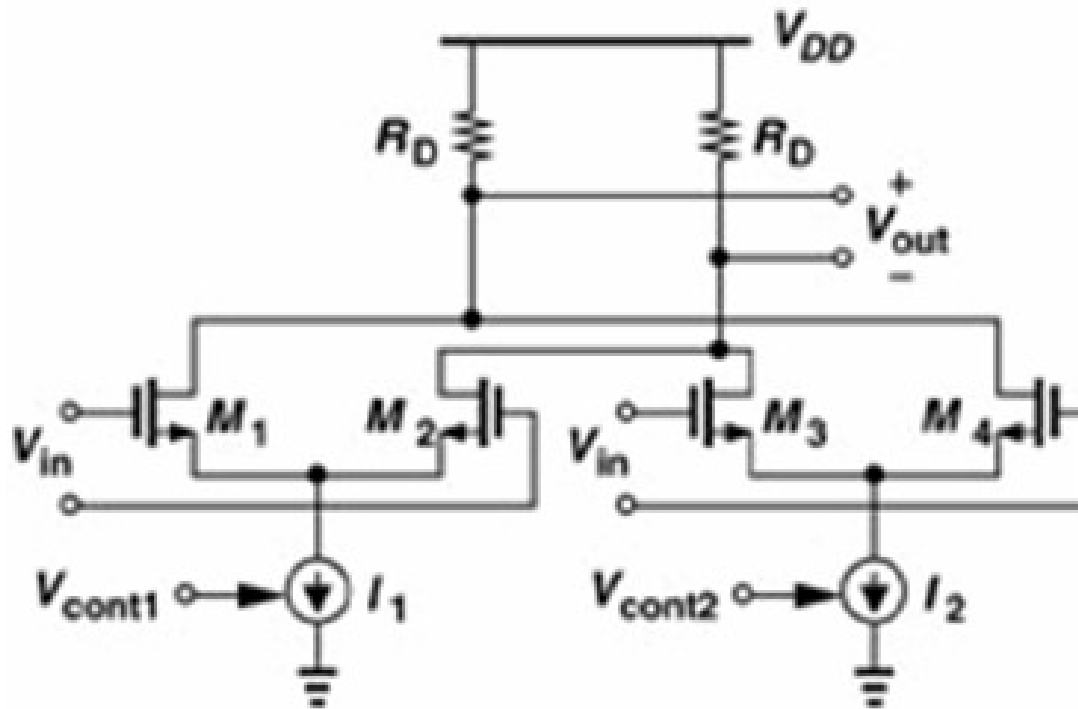
$$V_{out2} = R_D I_{D4} - R_D I_{D3},$$

we have:

$$V_{out1} + V_{out2} = R_D (I_{D1} + I_{D4}) - R_D (I_{D2} + I_{D3})$$

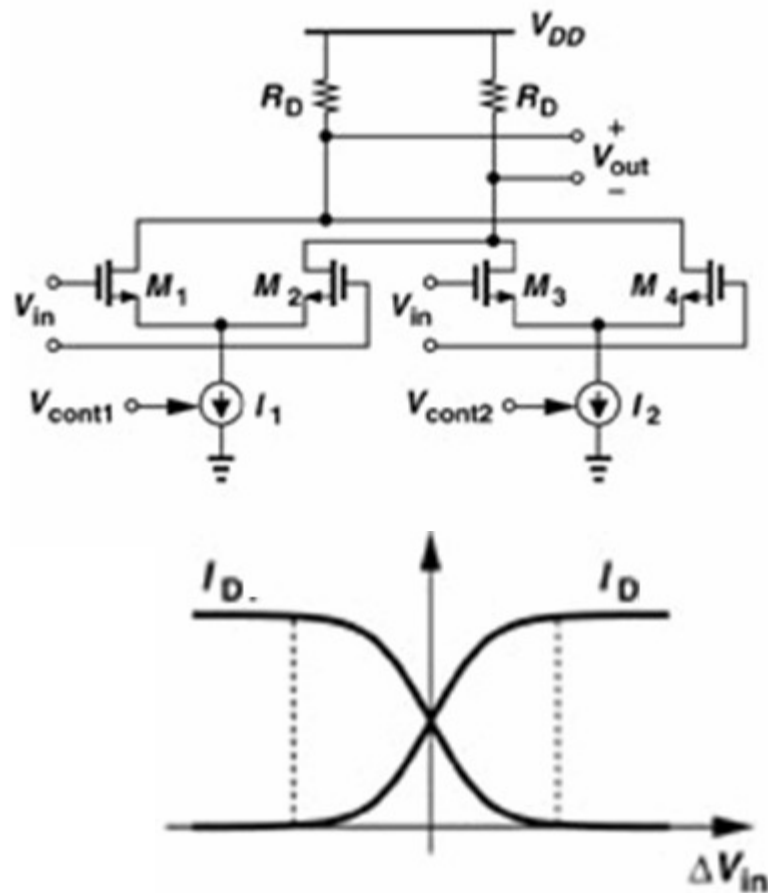


Thus, rather than add the voltage V_{out1} and V_{out2} , we add the current by simply short the corresponding drain terminals to sum the currents (and subsequently generate the output voltage).

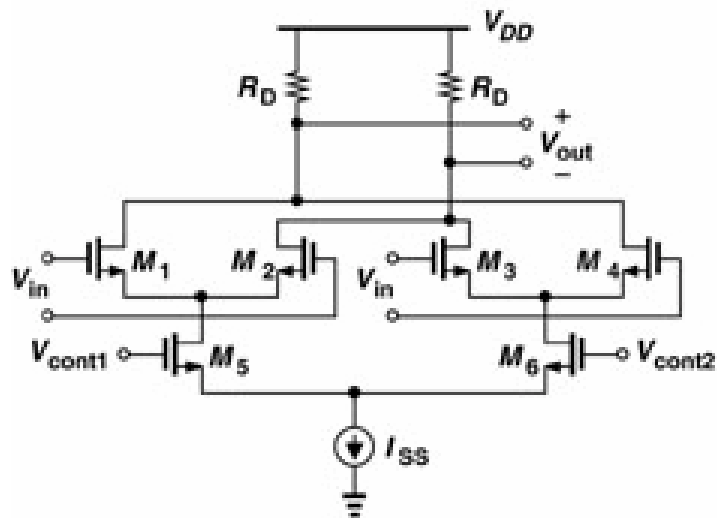
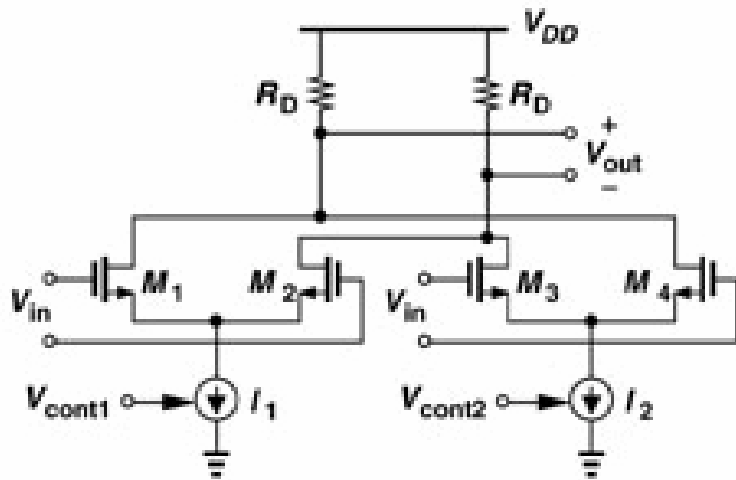


Note that:

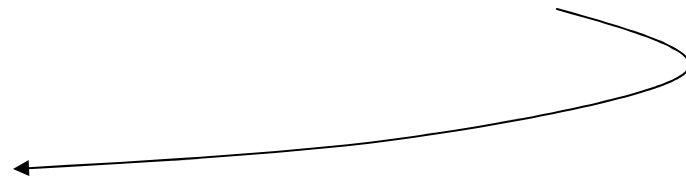
- If $I_1=0$, then $V_{out}=+g_m R_D V_{in}$ and
- If $I_2=0$, then $V_{out}=-g_m R_D V_{in}$.
- For $I_1=I_2$, the gain drop to zero.

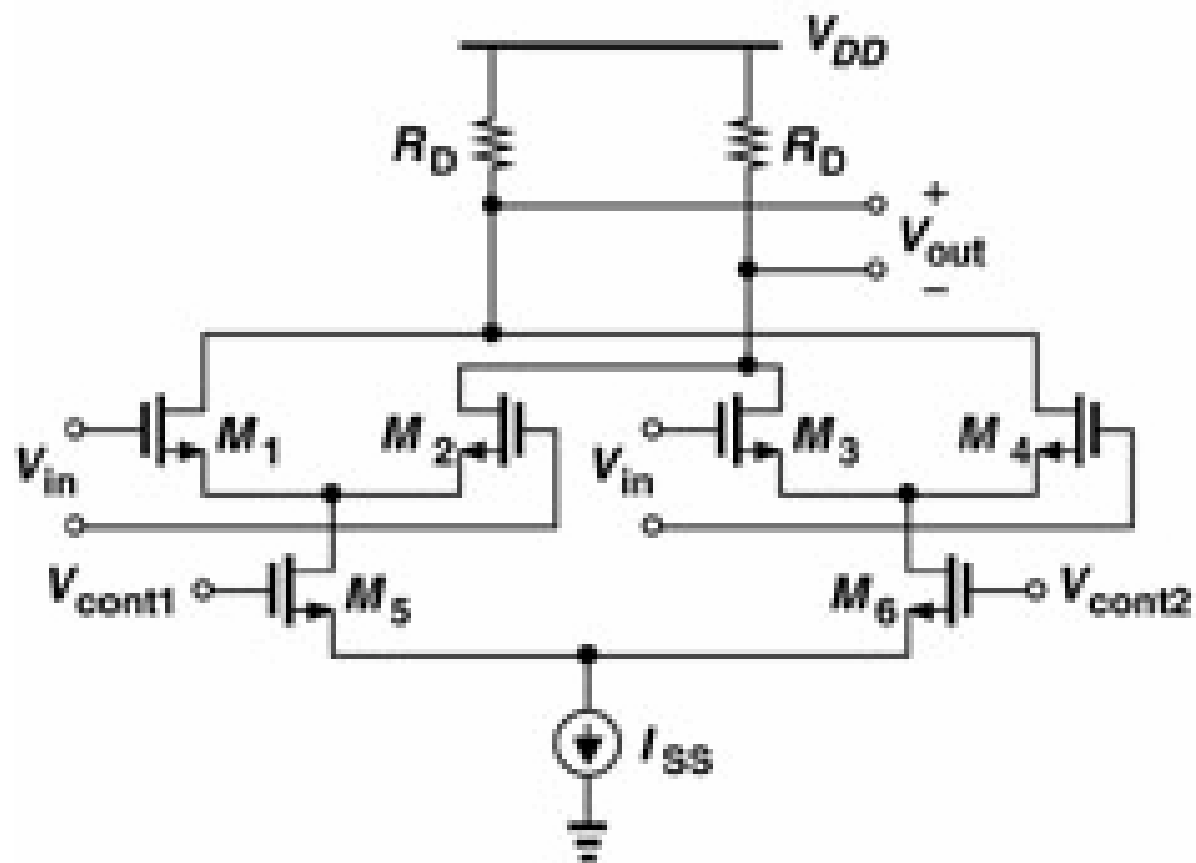


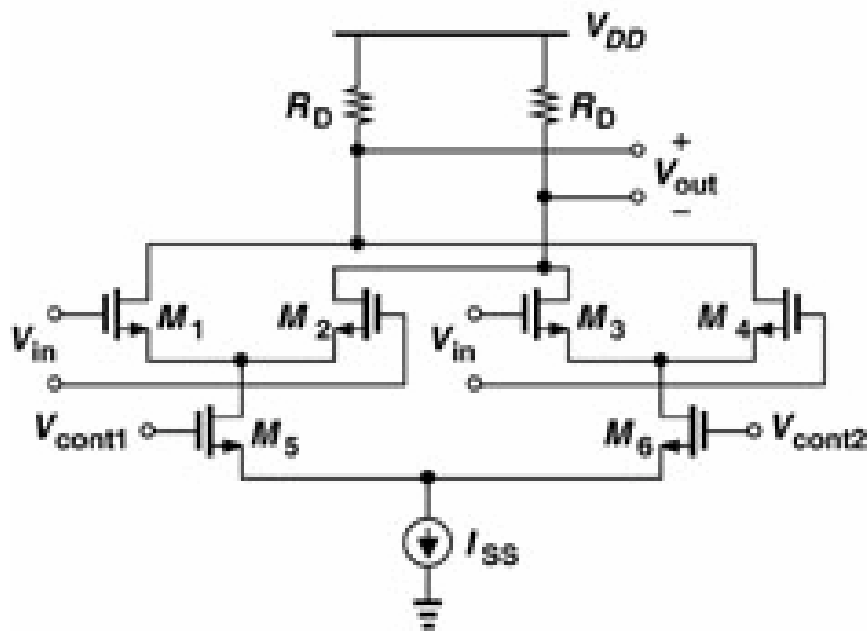
- Note that V_{cont1} and V_{cont2} must vary I_1 and I_2 in opposite directions such that the gain of the amplifier changes monotonically.
- What circuit can vary two currents in opposite direction?



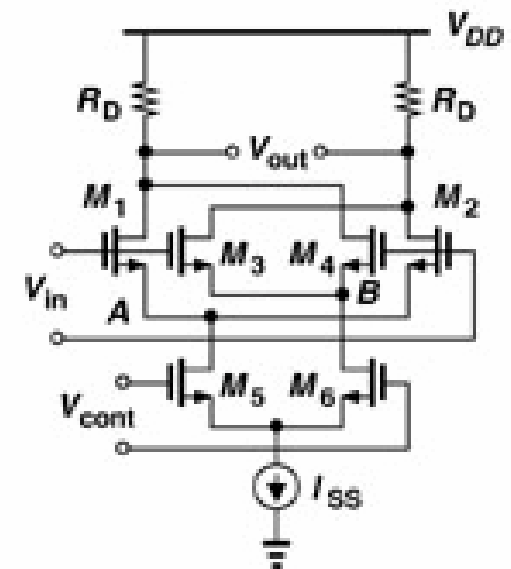
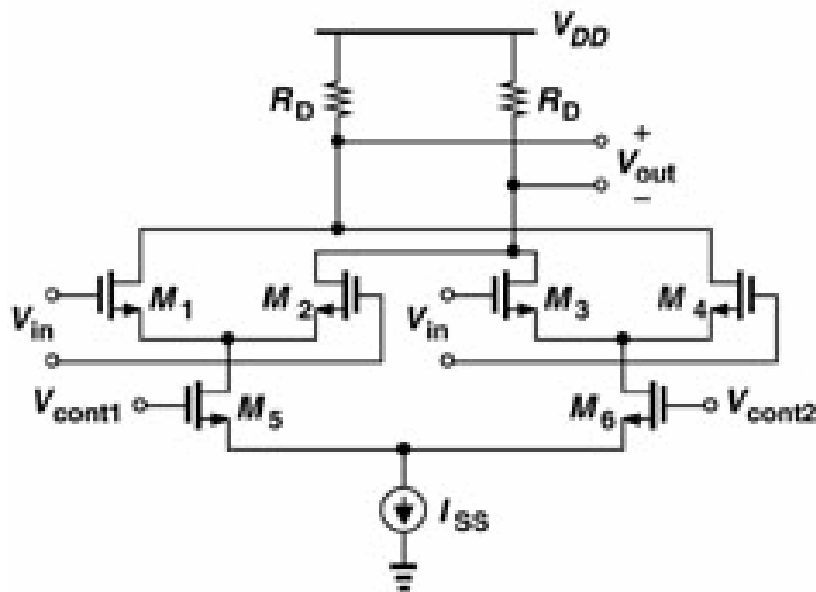
- What circuit can vary two currents in opposite direction? → A differential pair provides such a characteristic, leading to the topology shown in the figure







- Note that for a large $|V_{cont1} - V_{cont2}|$, all of the tail current is steered to one of the top differential pairs and the gain from V_{in} to V_{out} is at its most positive or most negative values.
- For $|V_{cont1} = V_{cont2}|$, the gain is zero.



- For simplicity, the circuit is redraw.
- This circuit is called “Gilbert Cell”, this circuit is widely used in many analog and communication systems.
- In typical design, M_1 - M_4 are identical and so M_5 and M_6 .