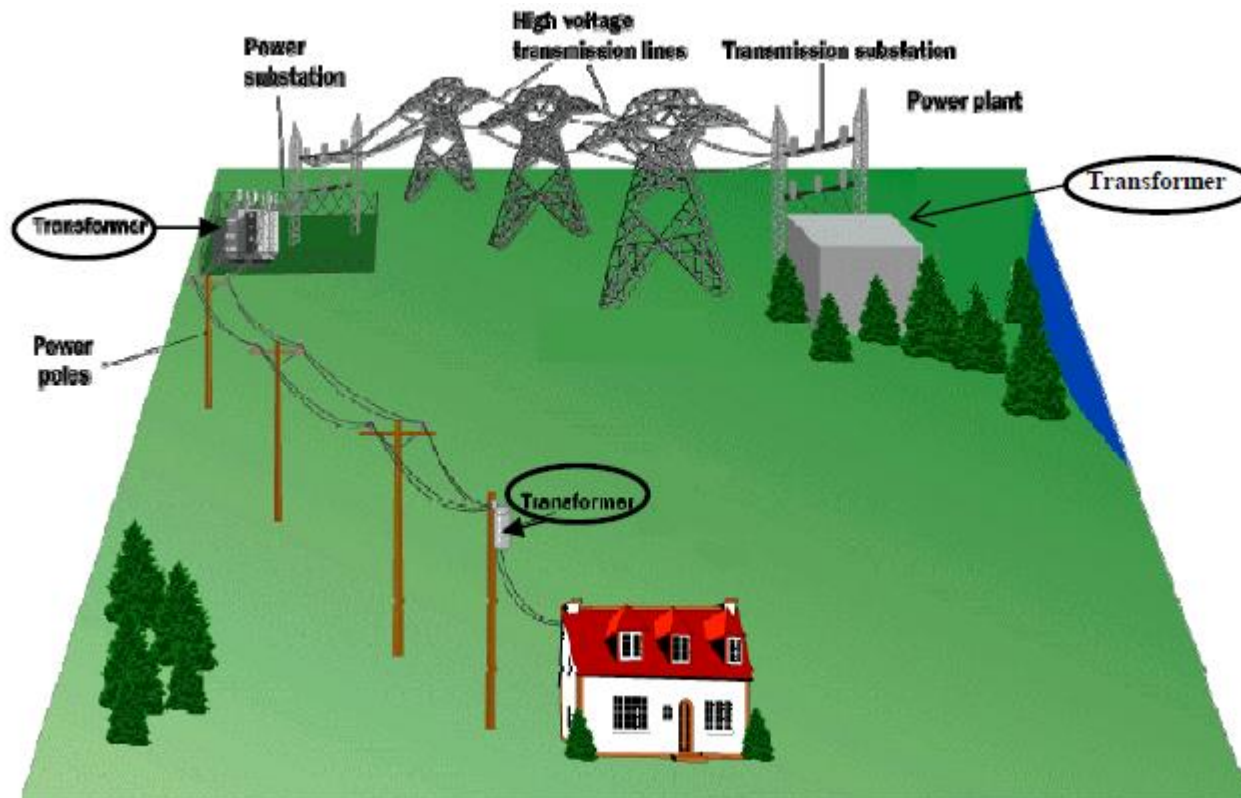
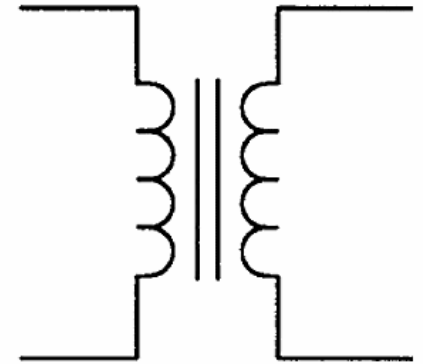




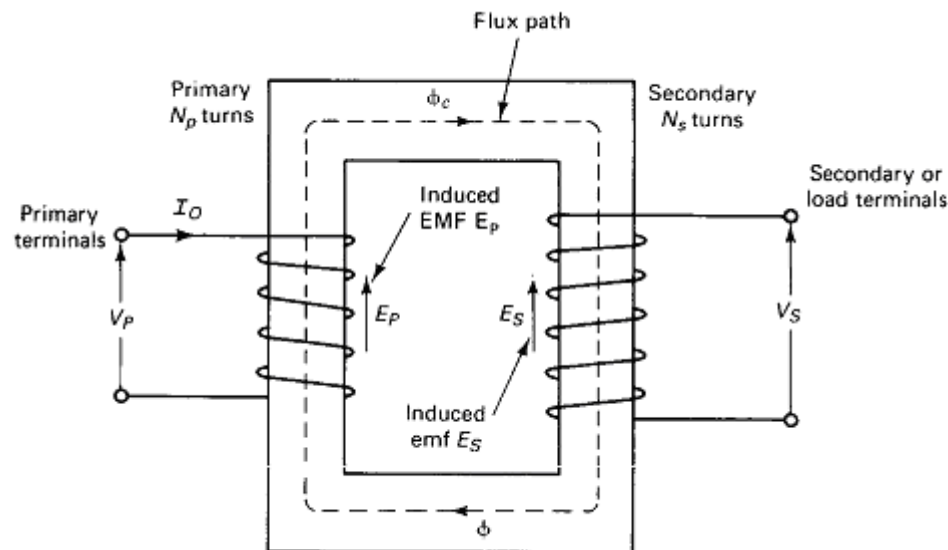
Transformers



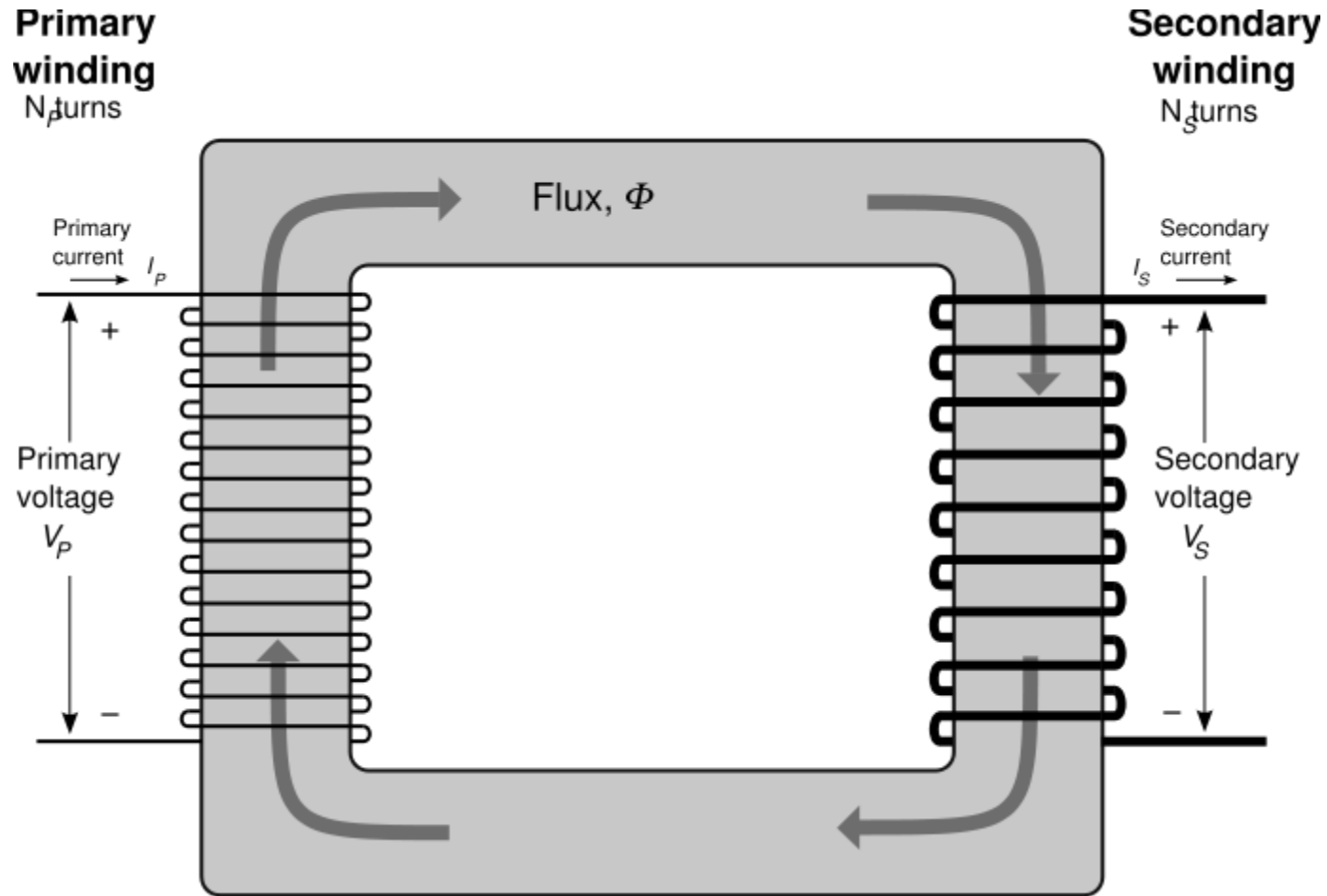
- Static electromagnetic device which converts AC from one voltage to another without change in frequency.
- Consists of two windings that are electrically isolated from each other.
- AC voltage when applied to one winding sets up alternating flux in the magnetic core.
- This flux links with the other magnetic core and induces emf which circulates current when connected to load.



- Winding to which input is applied is called primary winding.
- Winding which is connected to the load is called secondary winding.



Principle of Operation



- Alternating voltage V_p is applied at primary coil , a current I_p flows producing magnetic flux in the core.
- As per Faraday's laws of electromagnetic induction, self-induced emf is set up in primary given by,

$$E_p = -N_p \frac{d\phi}{dt}$$

- Assuming that there is no leakage flux, ϕ will link with each turn of secondary coil S.
- This sets up a mutually induced emf given by,

$$E_s = -N_s \frac{d\phi}{dt}$$

- This emf will circulate current in the load circuit

Ideal transformer

- Core is highly permeable so that it requires very small magnetomotive force(mmf) to set up flux in the core.
- Leakage flux is zero, i.e. entire flux is confined to the core and links with both windings.
- Resistance of primary and secondary winding is negligible.
- There are no losses due to resistance, hysteresis and eddy currents.

- For an ideal transformer,

$$I_p N_p = I_s N_s \text{ (mmf of the windings)}$$

$$V_p I_p = V_s I_s$$

$$\frac{E_p}{E_s} = \frac{V_p}{V_s} = \frac{I_s}{I_p} = \frac{N_p}{N_s} = a \text{ (turns ratio)}$$

emf equation

emf induced due to change of main flux is

$$e_p = -N_p \frac{d\phi}{dt}$$

Main flux is

$$\phi = \phi_{\max} \sin \omega t$$

$$e_p = -N_p \frac{d}{dt} (\phi_{\max} \sin \omega t)$$

$$= -N_p \omega \phi_{\max} \cos \omega t$$

$$E_{p \max} = N_p \omega \phi_{\max}$$

rms value is given by,

$$E_p = \frac{E_{p \max}}{\sqrt{2}} = \frac{N_p \omega \phi_{\max}}{\sqrt{2}} = \frac{N_p 2\pi f \phi_{\max}}{\sqrt{2}}$$

$$= 4.44 f N_p \phi_{\max} \text{ volts}$$

$$= 4.44 f N_p B_m A_i \text{ volts}$$

f- frequency

B_m –maximum flux density

A_i - cross-sectional area

Emf in secondary is $= 4.44 f N_s B_m A_i \text{ volts}$

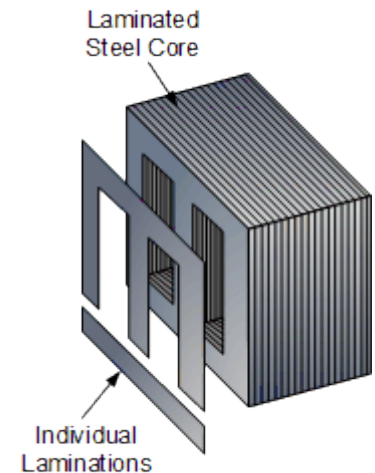
- When a voltage is applied to the primary keeping the secondary open circuited, a current $I_m \sim 0$ phase shifted 90° (lagging) w.r.t the primary voltage would be present.
- The current I_m and induced flux are in phase.
- We already know that flux lags e_p by 90° .
- Therefore e_p lags v_p by 180° .

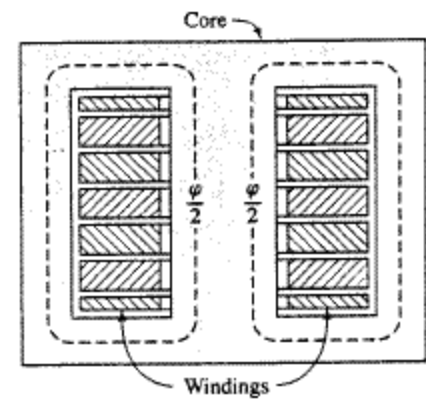
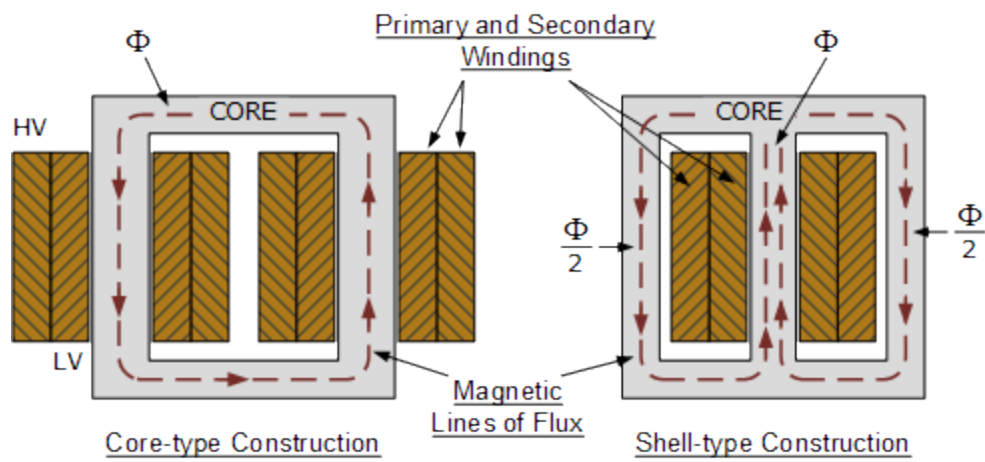
Construction

1. Magnetic circuit (core)
2. Electric circuit (primary and secondary windings)
3. Dielectric circuit consisting of insulation
4. Tank and accessories

1. Magnetic circuit(cores)

- Provides path to the flow of magnetic flux
- Cores are laminated to reduce eddy current loss
- The iron core is made of thin laminated silicon steel (2-3 % silicon)
- Transformers types based on magnetic circuit :-
a) core type b) shell type





- Electric circuit
 - Primary and secondary winding(copper)
 - Insulation may be double cotton or single cotton with layer of enamel
- Dielectric circuit
 - Used to insulate conducting parts b/w magnetic and electric parts
 - Insulators used are paper, bakelite or pressboard

- Tank and accessories

- Tank

- Assembled transformer with magnetic frame and windings are housed in proper tank that contains transformer oil. Tanks are fabricated from welded sheet steel. Lids from cast iron. Water-proof gasket used at joints

- Accessories

- Conservator:- airtight cylindrical metal drum supported horizontally. Used for oil expansion and contraction volume compensation while over loading.
 - Breather:- Mainly calcium chloride or silica gel which extracts moisture from the air which enters the tank during expansion and contraction of air.
 - Bushing:- Current carrying rod and porcelain cylinder for isolation.

Losses in a transformer

- Iron losses
 - caused by varying magnetization
 - constant
 - sub divided as hysteresis and eddy current losses
 - Hysteresis loss: The energy used by core for alignment with the varying flux is dissipated as heat within the iron core.
 - Eddy current loss: Varying magnetic field cuts the conducting core material and induces a voltage into it. The induced voltage causes random currents to flow through the core which dissipates power in the form of heat.
- Copper loss: $I^2 R$ loss

Efficiency

$$\text{efficiency}, \eta = \frac{\text{output power}}{\text{input power}}$$

$$\text{input power} = \text{output power} + \text{total losses}$$

$$\text{total losses} = \text{iron losses} + \text{copper losses}$$

$$= W_i + (I_p^2 R_p + I_s^2 R_s)$$

$$\text{output power} = V_s I_s \cos \theta$$

$$\therefore \text{efficiency}(\eta) = \frac{V_s I_s \cos \theta}{V_s I_s \cos \theta + W_i + (I_p^2 R_p + I_s^2 R_s)}$$

Condition for maximum efficiency

Total copper losses = $I_s^2 \bar{R}_s$

$$\eta = \frac{V_s I_s \cos \theta}{V_s I_s \cos \theta + W_i + I_s^2 \bar{R}_s}$$

efficiency maximum when the denominator is minimum, i.e.

$$\frac{d}{dI_s} \left(V_s \cos \theta + \frac{W_i}{I_s} + I_s \bar{R}_s \right) = 0$$

$$W_i = I_s^2 \bar{R}_s$$

Total copper loss = iron loss

All day efficiency

$$\begin{aligned} \text{all day efficiency, } \eta &= \frac{\text{output in kWh over 24 hours}}{\text{input in kWh over 24 hours}} \\ &= \frac{\text{output in kWh over 24 hours}}{\text{output in kWh over 24 hrs} + 24 * W_i + (\text{copper losses in kWh in 24 hrs})} \end{aligned}$$