
```

clc;
clear all;
close all;

a=imread('fig1.jpg');
r=a(:, :, 1); %separate red component from
               coloured image
g=a(:, :, 2);
b=a(:, :, 3);
grayimg=rgb2gray(a); %coloured to gray for original image
sub_r=imsubtract(r,grayimg); %subtract coloured red and gray
sub_g=imsubtract(g,grayimg);
sub_b=imsubtract(b,grayimg);

bin_r=imbinarize(sub_r); %gray into binary
bin_g=imbinarize(sub_g);
bin_b=imbinarize(sub_b);
cout=imshow(bin_r); %show image

count_red=bwconncomp(bin_r); %count number of red objects
count_green=bwconncomp(bin_g);
count_blue=bwconncomp(bin_b);

numobj1=count_red.NumObjects; %count number of red images
numobj2=count_green.NumObjects;
numobj3=count_blue.NumObjects;

bound_r=regionprops(bin_r); %to draw the regions around red image
bound_g=regionprops(bin_g);
bound_b=regionprops(bin_b);

imshow(a); %taken original image
hold on;

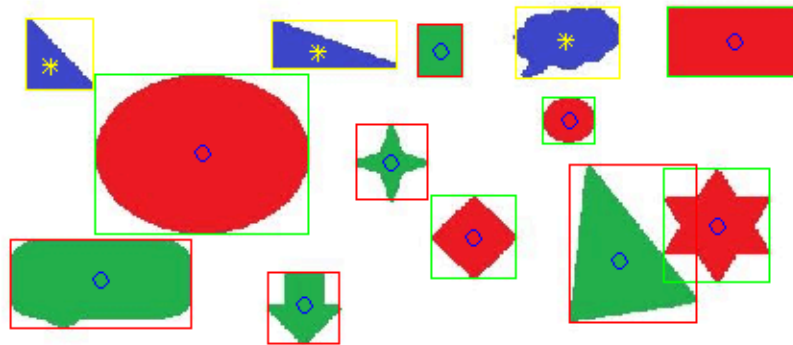
for i=1:numobj1
    rectangle('Position',bound_r(i,1).BoundingBox,'EdgeColor','g');
    plot(bound_r(i,1).Centroid(1),bound_r(i,1).Centroid(2),'bo')
    %to plot the centroid
end

for i=1:numobj2
    rectangle('Position',bound_g(i,1).BoundingBox,'EdgeColor','r');
    plot(bound_g(i,1).Centroid(1),bound_g(i,1).Centroid(2),'bo')
    %to plot the centroid
end

for i=1:numobj3
    rectangle('Position',bound_b(i,1).BoundingBox,'EdgeColor','y');
    plot(bound_b(i,1).Centroid(1),bound_b(i,1).Centroid(2),'y*')
    %to plot the centroid
end
hold off;

```

```
%yellow for blue recognition  
%green for red recognition  
%red for green recognition
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Published with MATLAB® R2019a