

Quantum Computation & Quantum Information

Room No.: 2011

mid-3 quizzed → 25%

Mid-term → 25%

End-term → 50%

{ IBM-Q

On sub-atomic level

Newton's law fail.

Q To what extent Newton's law are right?

Control

↳ Quantum Mechanics being used even outside atomic level.

Machine

Computer

Computer

Nowadays

Fundamentally
same

DNA computation

Peptide computation

Fundamentally
same

Classical

Computer

(Machine
Computer)

Quantum

Computer

Fundamentally
different

Quantum
computers
on
cloud?

Now

Realization that physics of universe
is not entirely based on Newtonian
physics, but quantum mechanics

of Feynman & Manen

→ Basis of
Quantum
computation

1995 → Peter Shor → Algorithm

Q Gilbert asked, "Can all mathematical problems be solved by algorithms?"

Turing in Answer
↳ Turing Machine Model

Computational Complexity

Q Moore's law & its limitations in regard of quantum mechanics?

(Reducing size of device beyond a threshold quantum mechanics has to work)

⇒ Church-Turing Thesis → Any problem that can be solved on some computational model it can be solved on Turing Machine Model too

& Later it was proved wrong

Machine

Deterministic Machine

↓
output is obtained

Probabilistic Machine

↓
output is obtained

Problems related to quantum computation

(i) The basic unit of quantum info whose state is unknown can not be copied.

Noise → Disturbance needed to own a system

But Noise has to be protected too from the system

} Contradictory statements

$$L \frac{d^2q}{dt^2} + R \frac{dq}{dt} + \frac{q}{C} = \theta V_{app}$$

(Electric system)

Or

$$m \frac{d^2x}{dt^2} + \gamma \frac{dx}{dt} + \#x = F$$

(Mechanical system)

Another example

Allow the ball
to be steady
at equilibrium
position

↳ Analog
computation
examples

* Classical Computation :-

based on "classical mechanics"

Finite state machine (FSM)

PDA?

Turing Machine (TM)

Mathematical models,
practically not
applicable

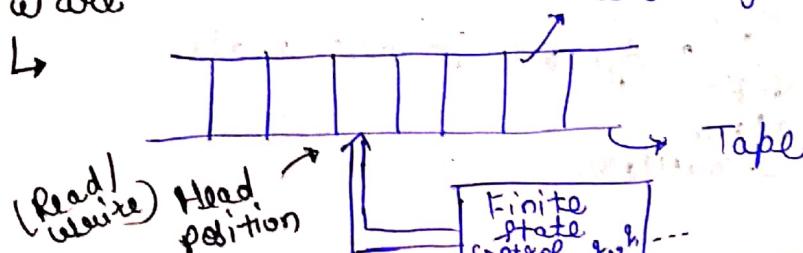
Turing Machine → has following components:

Software

- ↳ (i) A finite set 'S' (alphabet)
- (ii) An element $\sqcup \in S$ (Blank symbol)
- (iii) A set $A \subset S$ (external alphabet)
such that $\sqcup \notin A$
- (iv) A finite set Q whose elements are
the states of a turing machine
- (v) An initial state $q_0 \in Q$
- (vi) A Transition function $\delta : Q \times S \rightarrow Q \times S \times \{l, r\}$

Hardware

↳



Two inputs $\Rightarrow q \in Q$

$s_p \in S$

$$\delta(q, s_p) = (q', s'_p, \Delta P)$$

Transition function

(For each new turing machine, this function will have to be evaluated differently)

$\Delta P \in \{-1, 0, +1\}$

- $-1 \rightarrow$ Head moving left by one unit
- $0 \rightarrow$ Head not moving
- $+1 \rightarrow$ Head moving right by one unit

Turing machine takes up the inputs. Based on those inputs, searches for transition functions out of the list & computes output.

$S = \{ \text{blank symbol} \}$

$\langle \alpha, \sqcup, \sqcup, \sqcup, \sqcup, \dots ; 0 ; q_0 \rangle$ (Initial state, here)

$\langle s_0, s_1, \dots, s_{p-1}, s_p, s_{p+1}, \dots, p + \Delta P ; q' \rangle$

Q Suppose we are given a string of 0's & 1's and we want to replace by $\sqcup \sqcup \sqcup \sqcup \dots$

Ans

$S = \{ 0, 1, \sqcup, \rangle \}$

↳ special symbol

We also define a special state q_H , called halting state

(Machine stops when in state q_H)

$$\delta(q_i, s_i) = (q_{i+1}, s'_i, \Delta P)$$

Movement in right direction
(of head)

$(q_0, \rangle, q_1, \rangle, +1)$

Symbol in next state

↓
Current state
↓
Symbol in current state

↓
Next state encountered

- $(q_0, \triangleright, q_1, \triangleright, +\downarrow)$
- $(q_1, 0, q_1, \sqcup, +\downarrow)$
- $(q_1, \downarrow, q_1, \sqcup, +\downarrow)$
- $(q_1, \sqcup, q_2, \sqcup, -1)$
- $(q_2, \sqcup, q_2, \sqcup, -1)$
- $(q_2, \triangleright, q_3, \triangleright, +1)$
- $(q_3, \sqcup, q_H, 1, 0)$

Note:- Inputs are not changed simultaneously but one by one
 (if $q_i \rightarrow q_{i+1}$,
 $s_p \rightarrow$ same
 if $s_p \rightarrow$ changes
 $q_i \rightarrow q_i$)

Q Design a turing machine which will compute the parity of a binary string that is, it writes '0' if input to the machine. It writes '1' if the parity is even & writes '1' if the parity is odd.

* Computable function:- A function $f: A^* \rightarrow A^*$ is called if there is a turing machine 'M' such that the function ' ϕ_M ' computed is equal to 'f' for every $x \in A^*$

$$\phi_M(x) = f(x) \quad \forall x \in A^*$$

A^* → Set of all strings over A

Church-Turing Thesis :- The class of functions computable by a turing machine corresponds exactly to the class of functions which are regarded as being computable by an algorithm.
 (empirical statement → proof can not be found)

or,

Algorithm \leftrightarrow Turing Machine

As soon as an algorithm of a problem is found, its turing machine exists too (can be found)

Universal turing machine?

$$\hookrightarrow U([M], x)$$

Programmable



'Halting problem' \rightarrow solved by ~~is~~ Turing using Turing Machine model

Computational Complexity :-

Intrinsic efficiency of

an algorithm

In Turing machine \rightarrow Movement of head
(Physics involved)

Classical mechanics \rightarrow mass of object, force, initial position

final position can be
computed

Deterministic

Non-classical mechanics \rightarrow probabilistic
(output in terms of probability)

Definitive probabilistic?
(What is that?)

\rightarrow To compare complexity \rightarrow a common 'reference'
(Time, space occupied--)

\hookrightarrow Important parameters
to decide complexity

Variants of Turing Machine :-

- (i) Multi-tape TM
- (ii) Probabilistic TM
- (iii) Non-deterministic TM

Q Now, which Turing Machine to choose for solving problems?

* Complexity Classes :-

↓

Coarse-based classification

The classification will be based on Asymptotic behavior
 $(n \rightarrow \infty)$

$n = \text{No. of inputs}$

$$\text{e.g.: } 2n^3 + 4n + 3$$

Asymptotic Notations :-

(i) O (big O notation) → Worst case scenario

(sets upper bound for no. of resources used)

(ii) Ω (Omega notation) → Best-case scenario

(sets lower bound for worse resource requirement)

→ If $f(n)$ & $g(n)$ are two functions, one says $f(n)$ is in class $O(g(n))$ if ∃ constant $C \in \mathbb{R}$ such that for all $n > n_0$:

$$f(n) \leq C g(n)$$

→ And, $f(n)$ is in class $\Omega(g(n))$ if ∃ constants $C \in \mathbb{R}$ & n_0 such that for all $n > n_0$:

$$f(n) \geq C g(n)$$

(iii) $\Theta \rightarrow f(n)$ is $\Theta(g(n))$ if $f(n)$ is
 (Theta) both $\Omega(g(n))$ & $O(g(n))$
 i.e. $f(n) \sim c g(n)$
 for all $n > n_0$ ($c \rightarrow$ constant)

e.g. Let $f(n) = n^2$ & $g(n) = \log n$

$\rightarrow f(n)$ is $\Omega(g(n))$

Note:- It is clear that if $f(n)$ is $O(g(n))$
 then $g(n)$ is $\Omega(f(n))$

e.g. $f(n) = n^3$
 $g(n) = 2^n$

$\rightarrow f(n)$ is $O(g(n))$

- * The class of functions computable in polynomial time by a TM is called **class 'P'**
- \rightarrow If we move from one variant to other variant,
 the class 'P'. The change is by a polynomial to being its time complexity to be again a polynomial.
- \rightarrow The space requirement for problems in class P is obviously a polynomial in the size of input.

A function (decision problem) F is said to be computable/decidable in polynomial space if there is a TM that computes/decides F & runs in

space $S(n) = \text{poly}(n)$

The class of all such problems is called
PSPACE

Note:- It is clear that

$$\boxed{P \subseteq PSPACE}$$

Q Prove that $f(n)$ is $O(g(n))$ iff $\exists k$ such that $f(n) \leq g(n)^k$

Q Show that $\log(n)$ is $O(n^k)$ for any $k > 0$.

* Problems for which resource requirement grows faster than any polynomial in n are (wrongly) said to belong to exponential class **EXP**

C^n
↓
Actual exponential

$C^{\log n}$
→ (wrongly termed)
exponential

* NP class → decision problems
{Yes or No}

Non-deterministic
polynomial

Some problems are not solvable on standard turing machine in polynomial time, but solvable on Non-deterministic turing machine in polynomial time.

e.g. Factoring problem → NP class problem
{Finding factors...}

Non-deterministic machine makes random guess & checks if this guess is the answer we're looking for.

$$P \subseteq NP$$

↳ P class → deciding whether a number is prime or composite

e.g. Deciding if a number is prime
Numbers are composite

→ P class

Number → the above is called a

NP class → the above is called a

* BPP class →

↓
Bounded
error
probabilistic

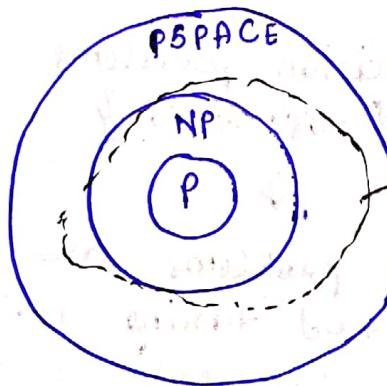
→ the above is called a

* BQP class →

↓
Bounded
quantum
error
probabilistic

$$L \subseteq P \subseteq NP \subseteq PSPACE \subseteq EXP$$

Log
space



BQP

Any problem outside PSPACE

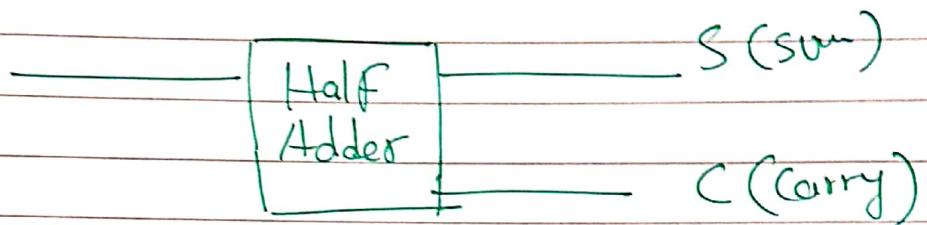
Quantum computers can not solve.

Circuit wires & gates

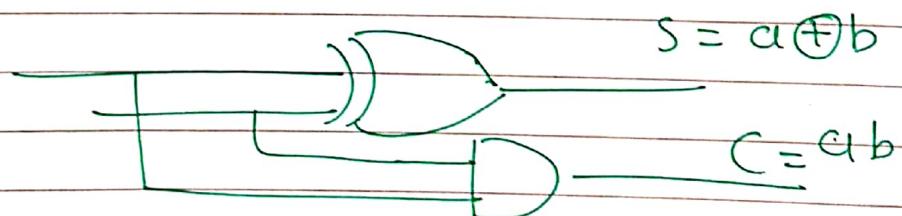
Binary Logic - $B = \{0, 1\}$

Acyclic Circuit i.e. —

e.g. Half adder



a	b	S	C
0	0	0	0
0	1	1	0
1	0	1	0
1	1	0	1

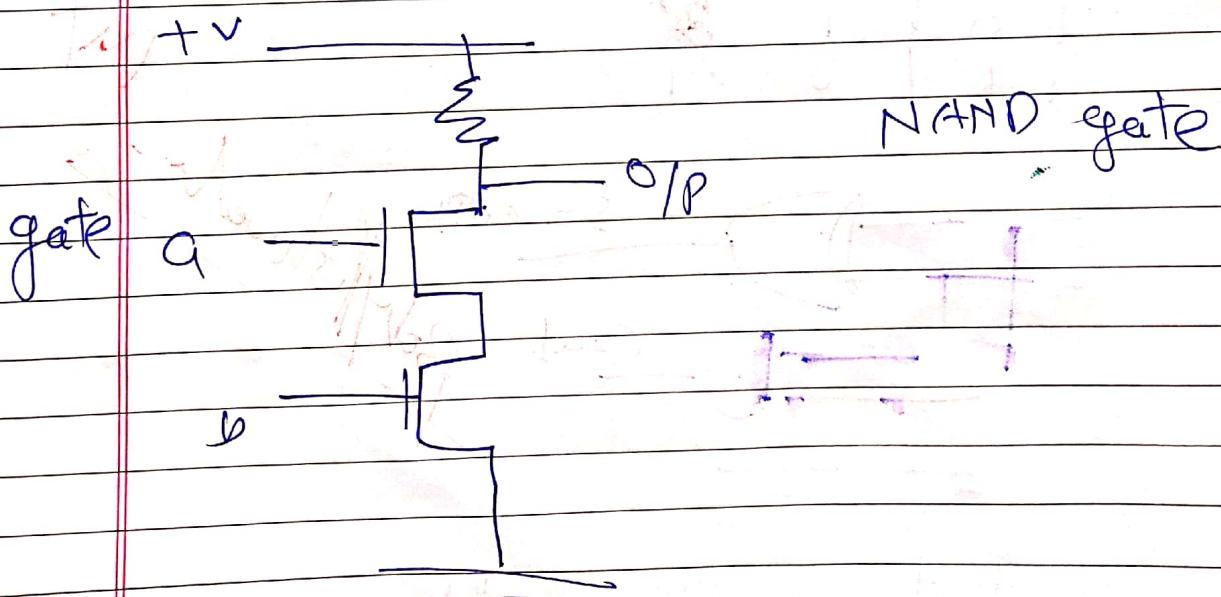
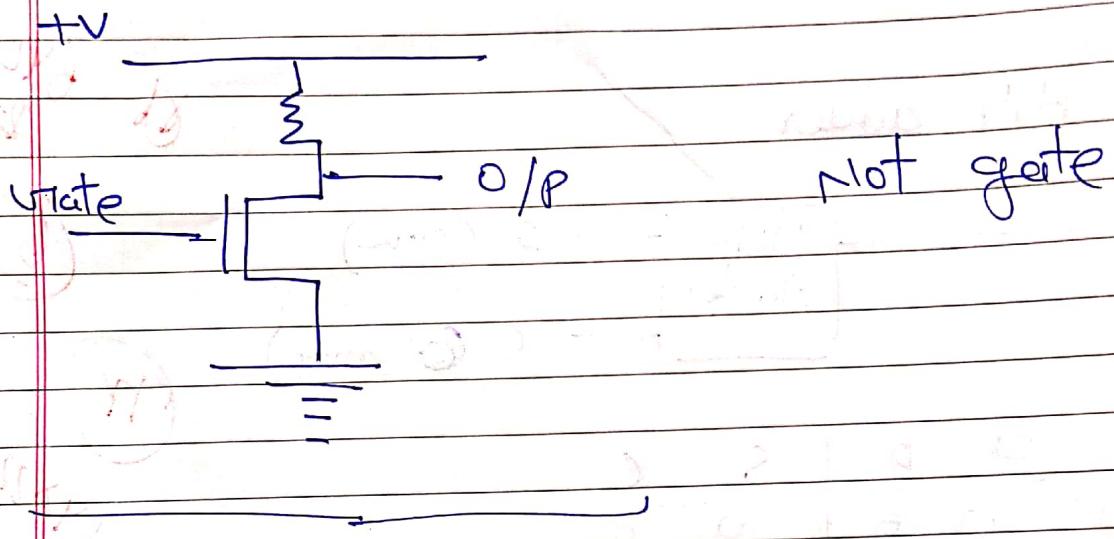


Q - Construct a full adder

- ① directly using XOR, AND & OR
- ② using half adder.

Q - How many half

E.g. How many half adder are required to add two n-bit binary no. 2. Design the Corresponding ckt.



Ex - Construct NOR gate

- A general logic gate is a function

$$f : B^n \rightarrow B^m$$

where $B = \{0, 1\}$

if $m = 1$ i.e. if

$f : B^n \rightarrow B^1$ then f is called

c) Boolean function.

Completeness / Basis

AND, OR, NOT

form a complete set

$$a + b = \overline{(\bar{a} \bar{b})}$$

(De Morgan's
theorem)

Note: NAND is a universal gate.

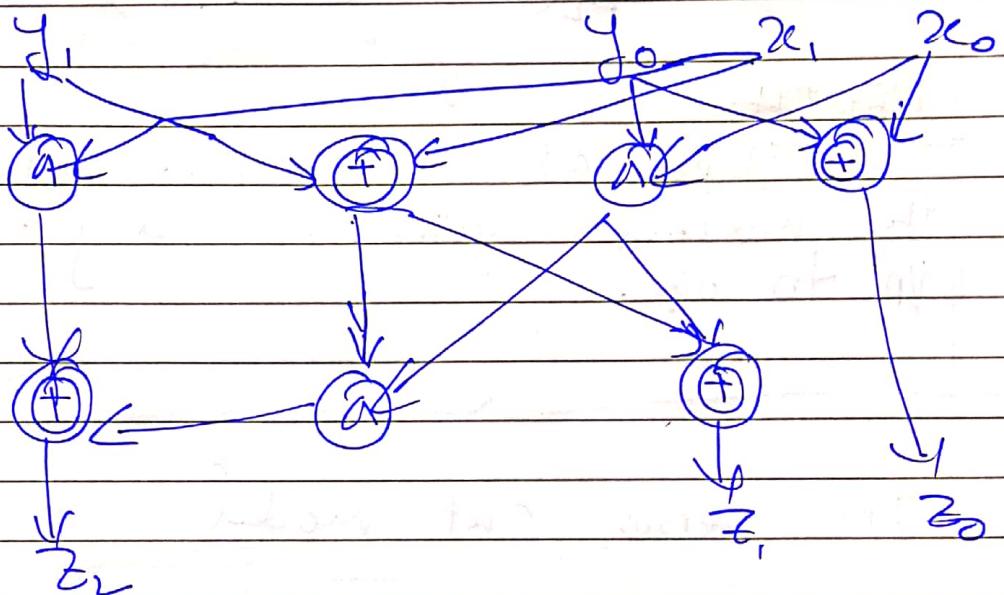
Q) → Proof that AND OR & NOT form a complete set for any Boolean function

Note:

Any boolean function can be represented in terms of its truth table.

Ex - How many distinct n-variable Boolean function are possible.

Circuits can also be represented in terms of graph (acyclic)



Check that the circuit represent binary-addition of 2-bit binary no.

Size (a measure of complexity of circuit)

The minimum size of a circuit over a basis A ((\wedge, \oplus) in the graph) that computes a given function f is called the circuit complexity of the function f (with respect to basis A) and is denoted by $C_A(f)$.

Page

In going from one basis A_2 to another basis A_1 of the circuit complexity changes only by a constant multiple i.e.

$$C_{A_1}(f) = O(C_{A_2}(f))$$

$$\text{and } C_{A_2}(f) = O(C_{A_1}(f))$$

DEPTH

depth of a boolean circuit is the max no. of gates on any path from ip to op.

TM versus Circ model

Circuit model is non-uniform opposed to the TM model which is uniform

Circuit family (for a particular computational problem)

Notatⁿ: $\{C_n\}$
ip size

Consistant Family

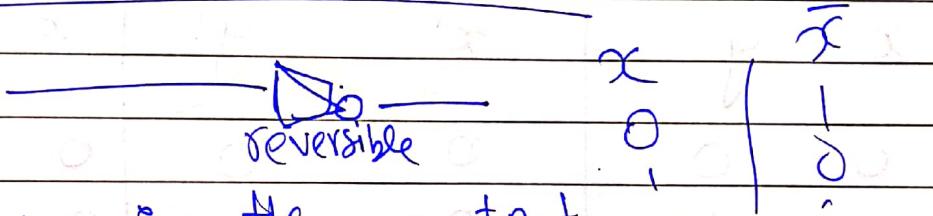
If $m < n$ & if the i/p size is of size i
 then the o/p

$$C_m(x) = C_n(x)$$

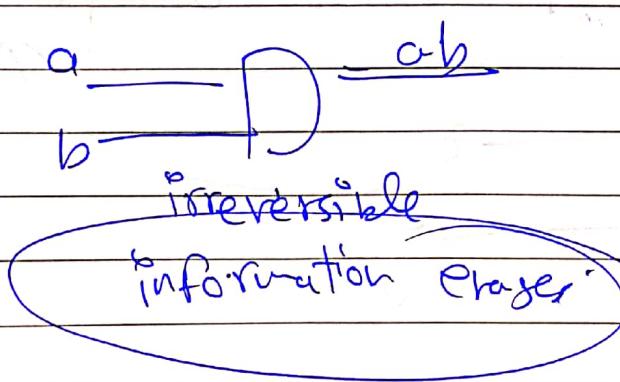
$\underline{C(x)}$

IF a Tm model o/p a description of
 C_n if $n \in N$ is polynomial time then the
 Consist. family is said to be polynomial time
uniform

Reversible Computation



Knowing the output you can predict input.



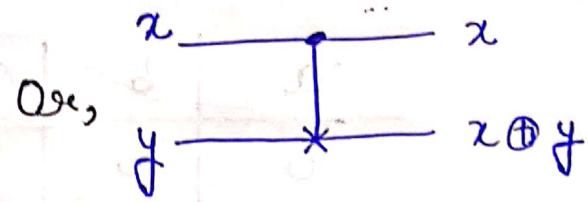
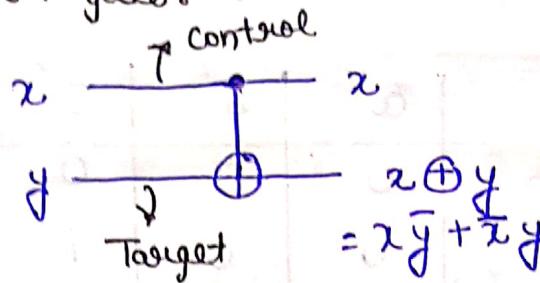
ab	b	ab
0	0	0
0	1	0
1	0	0
1	1	1

Note: Randomness Principle
 the energy dissipated by
 a computer in erasing a single bit is

$K_B T \log_2$ ("information is physical")

Reversible computation:- (i) NOT gate

(ii) CNOT gate:



(a) If control = 0 \rightarrow Target has no meaning
(Target line is untouched)

(b) If control = 1, then -

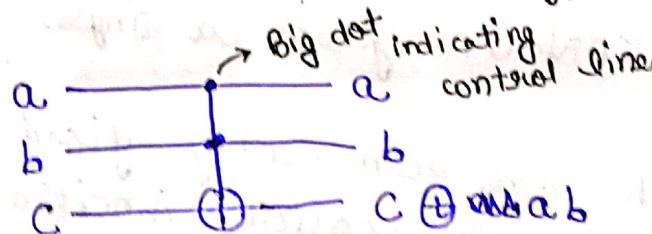
output on the target line is: $|1\rangle \oplus |y\rangle = |\bar{y}\rangle$
i.e. CNOT as NOT gate

(c) We also see that CNOT can implement FANOUT as well.

$$x \quad \text{control} \quad x$$
$$y = 0 \quad \text{Target}$$
$$x \oplus y = x \oplus 0 = x$$

(iii) CCNOT (Controlled-controlled NOT)

↳ Toffoli gate.



Reversible universal

(i) If $c = 0$ then output line is ab
i.e. AND operation

(b) Suppose we fix $a = \pm$, but leave b, c arbitrary, then output on target line is -

$c \oplus b \Rightarrow \text{XOR gate}$

a	b	c	a'	b'	c'
0	0	0	0	0	0
0	0	1	0	0	1
0	1	0	0	1	0
0	1	1	0	1	1
1	0	0	1	0	0
1	0	1	1	0	1
1	1	0	1	1	1
1	1	1	1	1	0

Truth table



(c) If $a = b = \pm$, then output line
 $\bar{c} \rightarrow \text{NOT gate}$

- Q Construct a NAND gate using a single CCNOT gate.
- Q Construct FANOUT from a single CCNOT

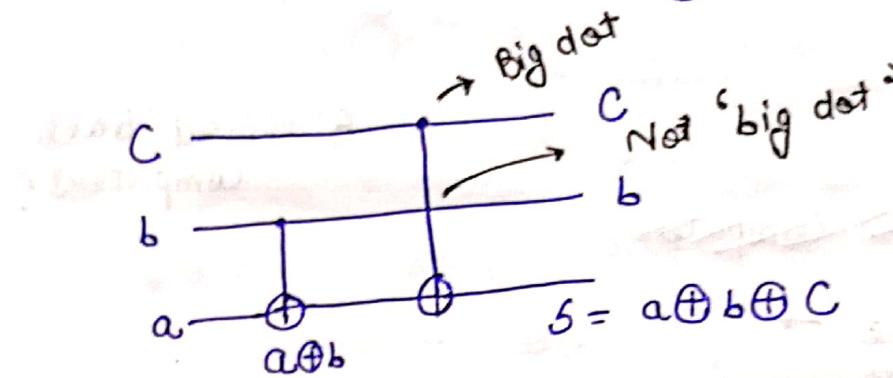
Note:- Bits which are permanently fixed to some definite value are called Ancilla bit

Binary Addition using CNOT/CCNOT :-

If a, b are bits to be summed & c is a previous carry, then sum is -

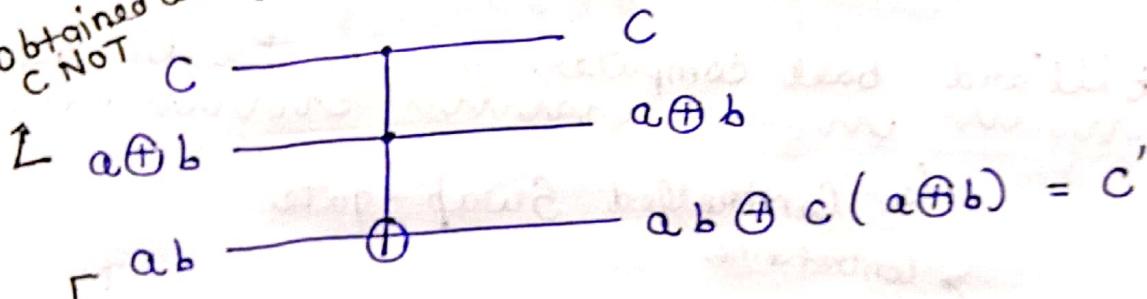
$$S = a \oplus b \oplus c$$

$$\text{+ carry } c' = ab \vee bc \vee ca \\ = ab \oplus bc \oplus ca$$



$$c' = ab \oplus c(a^* + b)$$

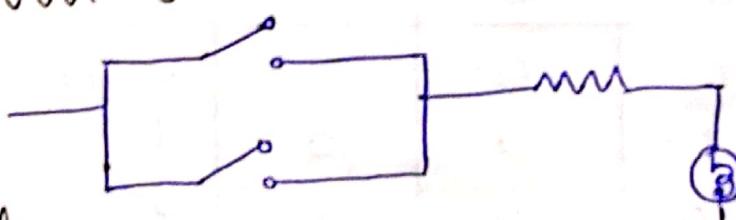
Obtained using
CNOT



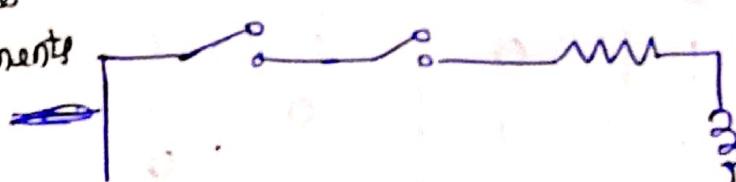
can be
obtained using CCNOT

* Physics & Computation:-

Electrical
Arrangements

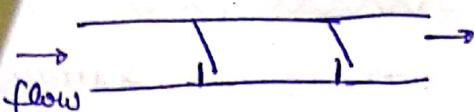


OR gate

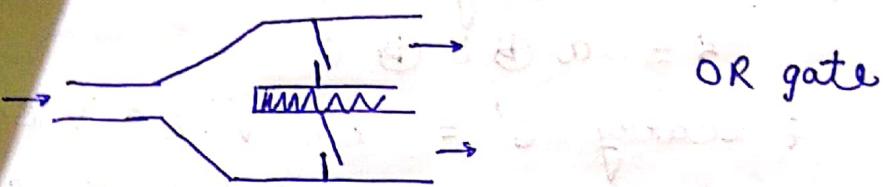


NOT gate

Mechanical Arrangements \Rightarrow



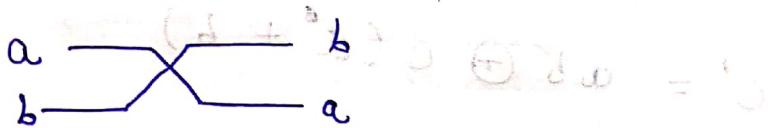
AND gate



Billiard ball
Computers?

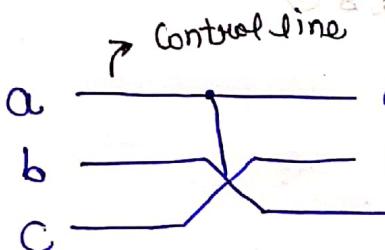
* Billiard ball computers

* Swap gate \rightarrow



* Billiard ball computer or the Fredkin gate:-

$\Theta = \text{ctrl} \hookrightarrow$ Controlled Swap gate



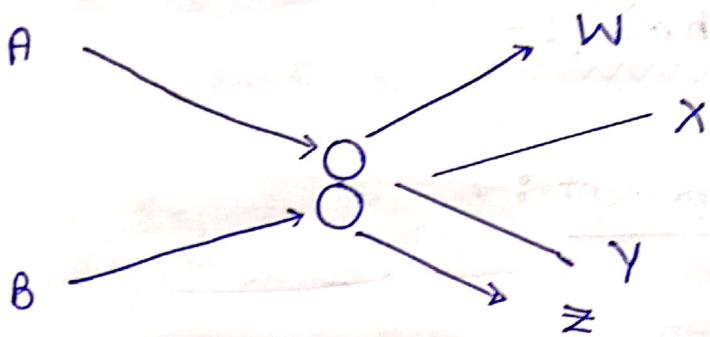
Universal
gate building

a	b	c	a'	b'	c'
0	0	0	0	0	0
0	0	1	0	0	1
0	1	0	0	1	0
0	1	1	0	1	1
1	0	0	1	0	0
1	0	1	1	0	0
1	1	0	1	0	1
1	1	1	1	1	1

$$a = 0 \Rightarrow b' = b, c' = c$$

$$a = \pm \Rightarrow b' = c, c' = b$$

* Take example of two balls colliding \rightarrow

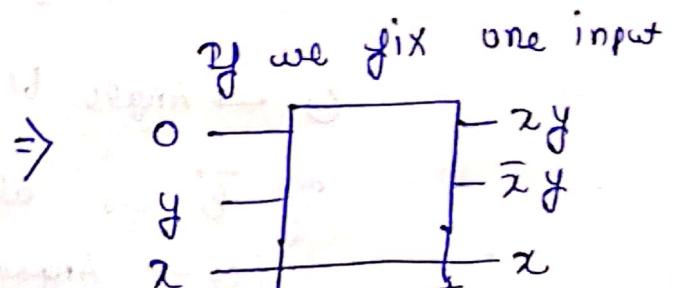
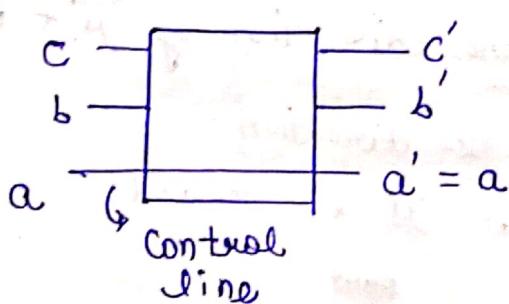


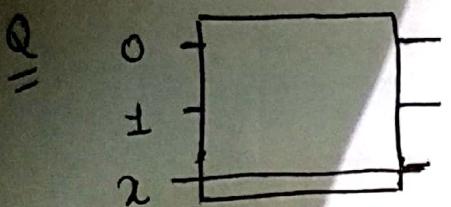
(a) If $A = \pm, B = 0 \Rightarrow$ No collision
 $\Rightarrow Y = \pm; \omega = Z = X = 0$

(b) If $A = 0, B = \pm \Rightarrow X = \pm$
 $\& \omega = Y = Z = 0 \Rightarrow X = \bar{A} \wedge B$

(c) If $A = B = \pm \Rightarrow \omega = Z = \pm \Rightarrow \omega = Z = A \wedge B$
 $\& X = Y = 0$

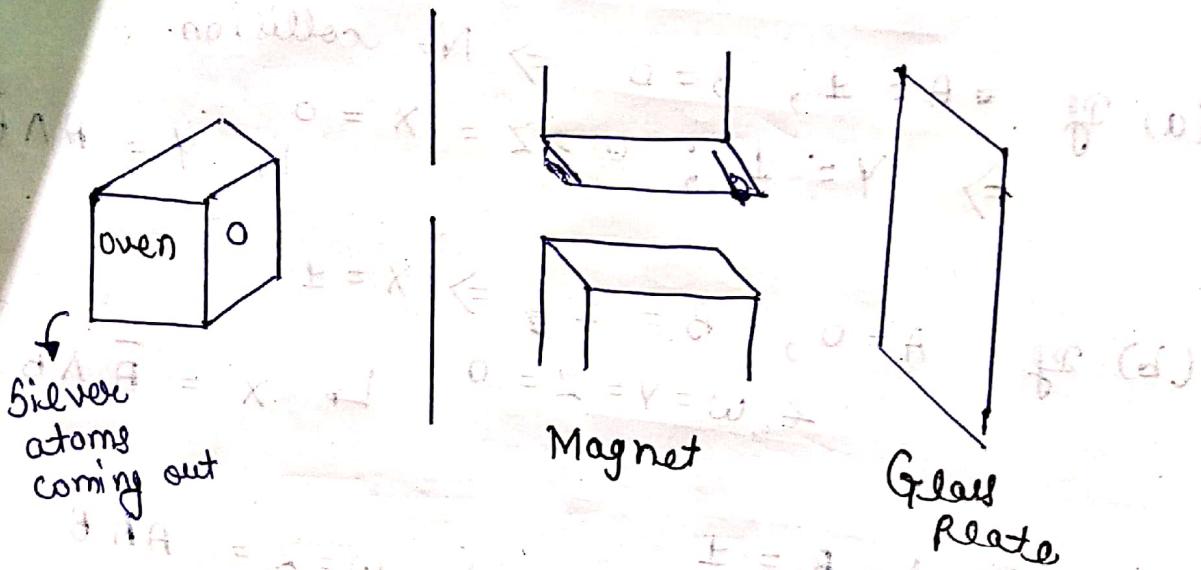
Amazingly, this trivial collision is also performing computation





* Quantum Mechanics :-

Stern-Gerlach Experiment :-



Every silver atom behaves like a little magnet. If it has magnetic moment $\vec{\mu}$ & the magnetic field \vec{B} then change in energy -

$$\Delta U = -\vec{\mu} \cdot \vec{B}$$

$$= -\mu B \cos \theta$$

θ → Angle b/w the direction of $\vec{\mu}$ & \vec{B}

If \vec{B} is along z-direction

θ → Angle b/w $\vec{\mu}$ & z-axis.

And, force = $-\nabla V_c$ Potential gradient

Because of sharp magnet pole the B field is not uniform & there will be a force of the Ag atoms.

$$F_z = -\frac{\partial (\Delta U)}{\partial z}$$

$$F_z = \mu \frac{dB}{dz} \cos \theta$$

Expected result \rightarrow

deviates Maxwell's
electrodynamic
law \rightarrow As per law of
classical mechanics

Actual result \rightarrow

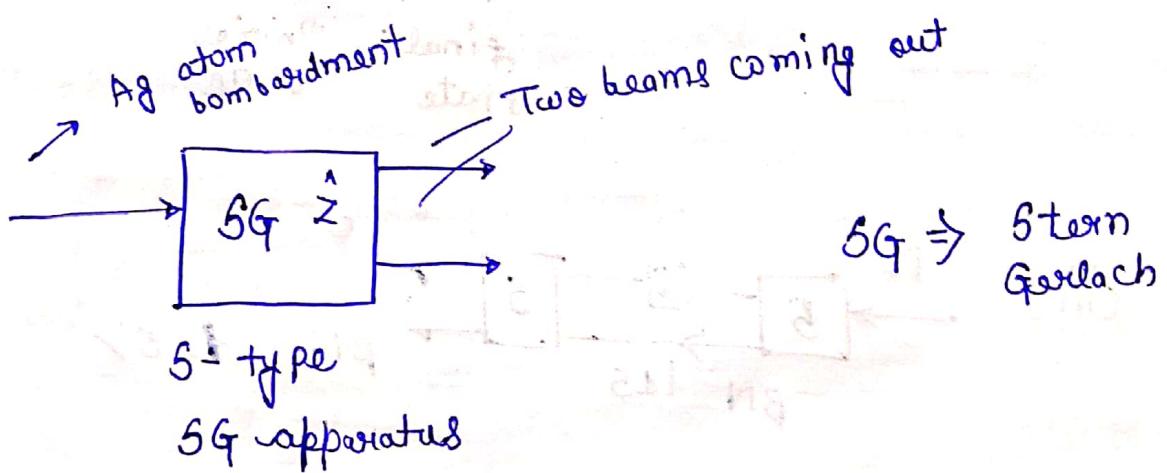
a continuous line appearing
on glass plate

Two dots on both
~~extreme~~ extreme

Ag atoms \rightarrow One unpaired electron
responsible for this behavior

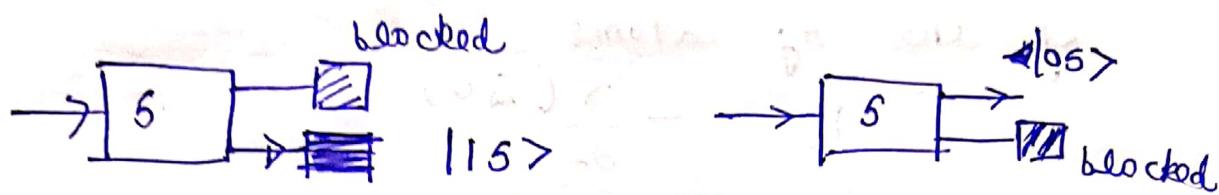
Conclusion We say that magnetic moment & the spin of electron are quantized. And, one may say the electron has 2 possible states.

Note:- If atoms are changed, ^{element} no. of possible states of electrons are changed too.

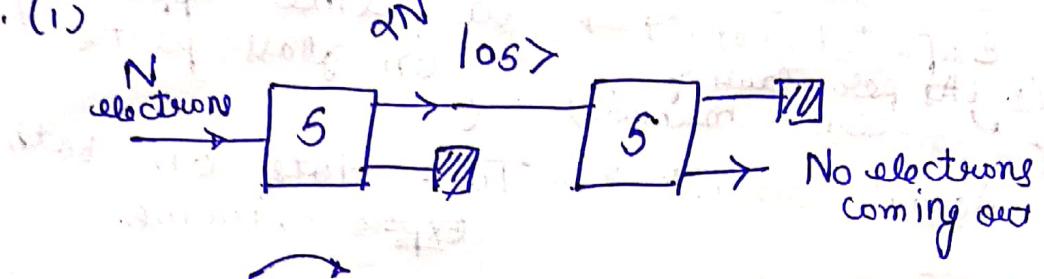


(Unpaired) Electrons coming out on the upper arm of S-type apparatus are said to be in state 105

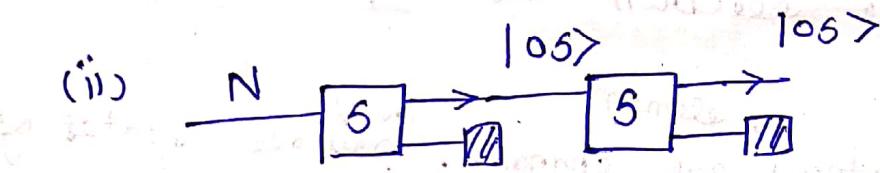
And, e^- in lower arm are said to be in state $| \pm 5 \rangle$



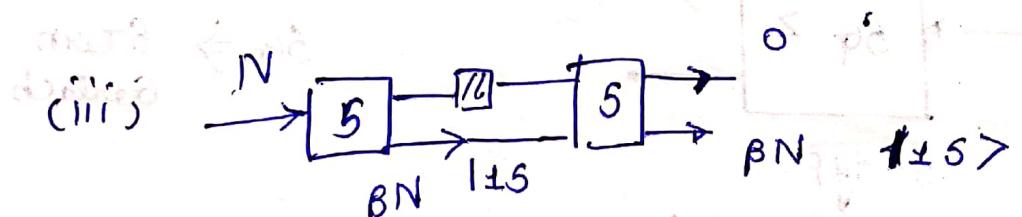
e.g. (i)



Probability amplitude for e^- in $| 05 \rangle$ state to go in $| \pm 5 \rangle$ state $\langle \pm 5 | 05 \rangle = 0$



$$\langle 05 | 05 \rangle = 1$$



$$\therefore \langle 05 | \pm 5 \rangle = 0$$

$$\langle \pm 5 | \pm 5 \rangle = 1$$

		Initial	
		$ 0s\rangle$	$ +s\rangle$
Final	$ 0s\rangle$	$\frac{1}{2}$	0
	$ +s\rangle$	0	$\frac{1}{2}$

In general, the notation $\langle b|a\rangle$ gives

"probability amplitude"

for starting state $|a\rangle$ to be found in state $|b\rangle$

→ The probability for the process is given by the absolute square of probability amplitude

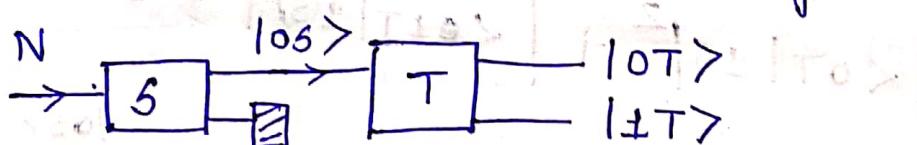
$$\text{i.e. } P(|a\rangle \rightarrow |b\rangle) = |\langle b|a\rangle|^2$$

$$= \langle b|a\rangle \langle b|a\rangle^*$$

* denotes "complex conjugate"

S-apparatus → When magnetic field aligned along z-axis

* T-apparatus → Magnetic field randomly aligned (not along z-axis necessarily)



It is found that:

$$\langle 0T|0s\rangle \neq 0$$

$$\langle +T|0s\rangle \neq 0$$

Similarly,

$$\langle 0T|+s\rangle \neq 0 \text{ & } \langle +T|+s\rangle \neq 0$$

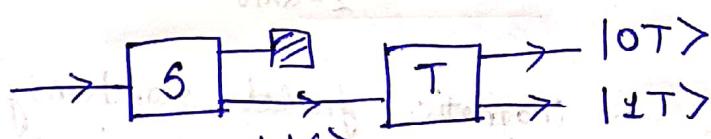
	$ 0S\rangle$	$ +S\rangle$	$ Initial\ state$
$ 0T\rangle$	$\langle 0T 0S \rangle$	$\langle 0T +S \rangle$	$\langle 00T $
$ +T\rangle$	$\langle +T 0S \rangle$	$\langle +T +S \rangle$	$\langle +0T $

If no e^- are created or absorbed, then the no. of e^- coming out of T-type arrangements with both output channels $|0T\rangle$ & $|+T\rangle$ open is same as no. of e^- entering the T-type apparatus in the $|0S\rangle$ state.

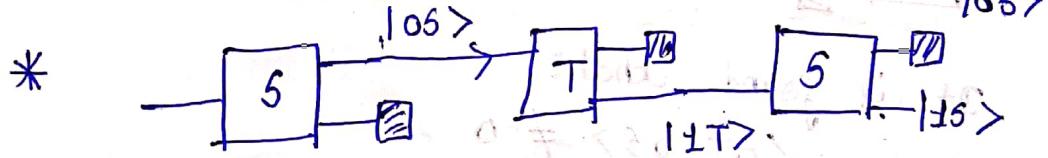
Conservation of e^- no. or probability conservation

$$|\langle 0T|0S \rangle|^2 + |\langle +T|0S \rangle|^2 = 1$$

e.g. what is the corresponding equation for the arrangements?



$$|\langle 0T|+S \rangle|^2 + |\langle +T|+S \rangle|^2 = 1$$

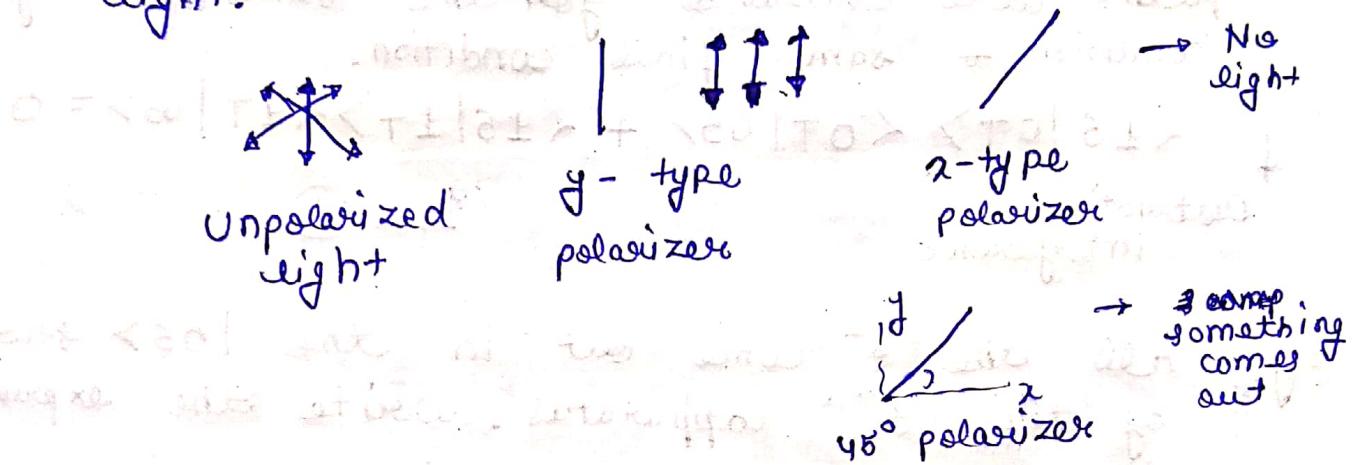


We find that the output from $|+S\rangle$ channel of the 3rd apparatus is not zero. Likewise, the output from the $|0S\rangle$ term is, in general, non-zero.

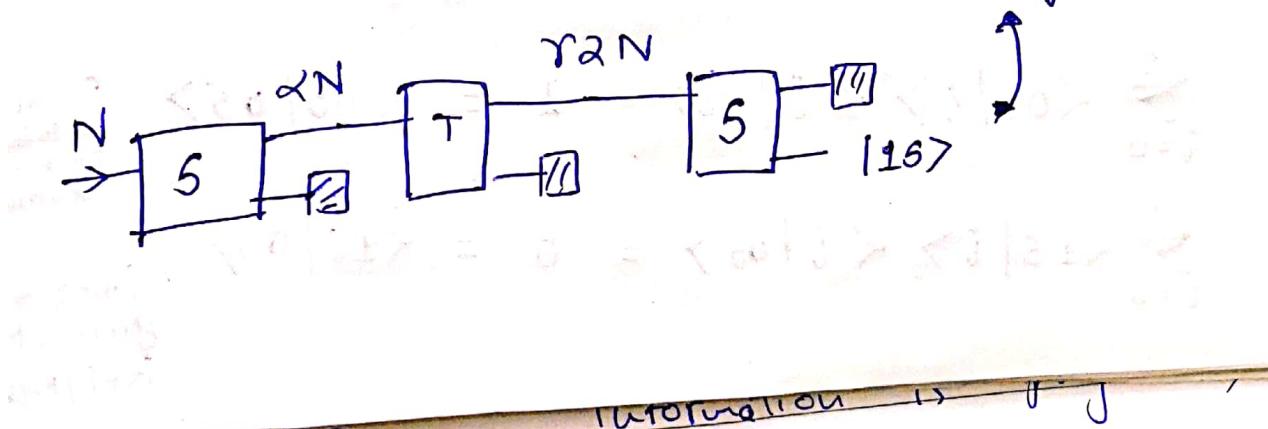
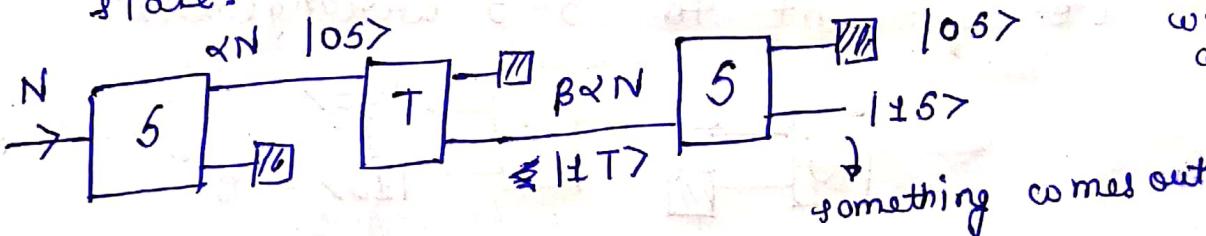
Explanation :-

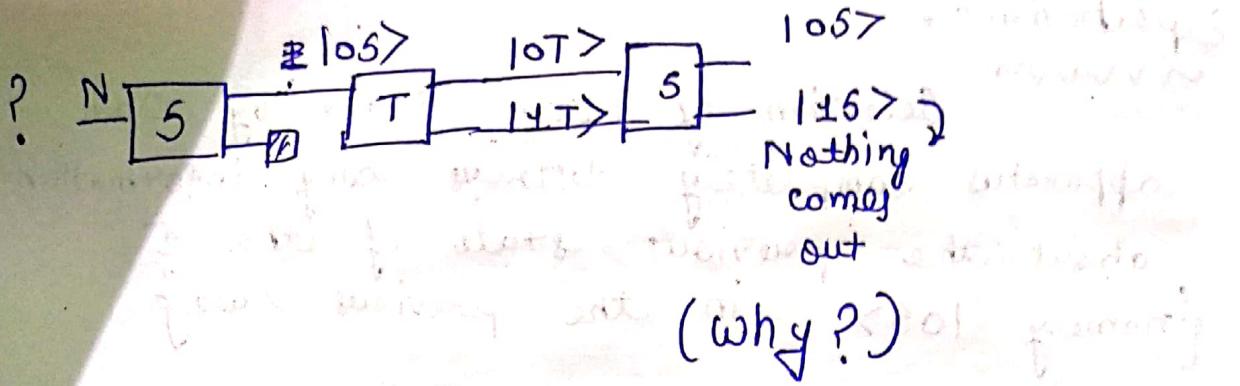
Selection of $| \pm T \rangle$ state by 2nd apparatus completely destroys any information about the previous state of the e^- namely $| 05 \rangle$ in the previous case.

Something similar happens in polarization of light.



* Base states :- We say that filtering process separates the system in base states (w.r.t. that particular apparatus) of the future behavior of the system in that particular base state depends only on that state.





Probability amplitude interfere if alternative paths are available for the same starting condition & same final condition.

$$\langle \pm S | 0T \rangle \langle 0T | 0S \rangle + \langle \pm S | \pm T \rangle \langle \pm T | 0S \rangle = 0$$

\downarrow Destructive interference — (1)

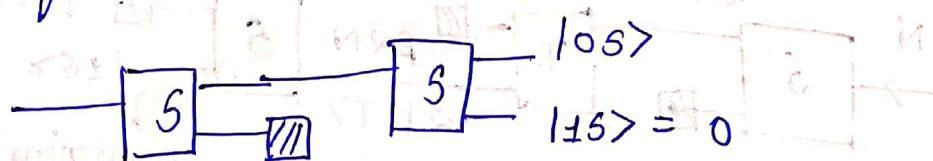
e.g. All the e^- come out in the $|0S\rangle$ state of the 3rd apparatus. Write the expression similar to (1) to describe this.

$$\langle 0S | 0T \rangle \langle 0T | 0S \rangle + \langle 0S | \pm T \rangle \langle \pm T | 0S \rangle = \pm$$

\downarrow Constructive interference — (2)

Note— Interestingly, a wide open T-apparatus is equivalent to the apparatus being present not at all.

i.e. equivalent to S-S arrangement.



$$\sum_{i=0}^{\pm} \langle 0S | i \rangle \langle i | 0S \rangle = \pm = \langle 0S | 0S \rangle$$

Initial state & final state same

$$\sum_{i=0}^{\pm} \langle \pm S | i \rangle \langle i | 0S \rangle = 0 = \langle \pm S | 0S \rangle$$

Initial & final state different

Nothing special about intermediate wide open $|05\rangle$ & $|15\rangle$ states.

$$\langle x|p \rangle = \sum_{i=0}^{\frac{1}{2}} \langle x|i \rangle \langle i|p \rangle$$

$$\left\{ \text{Jokingly, } \sum_{i=0}^{\frac{1}{2}} |i\rangle \langle i| = \frac{1}{2} \right\}$$

Note :- $\langle j|i \rangle = \begin{cases} \pm 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases} \rightarrow \text{Bell states}$

$$\langle j|i \rangle = \begin{cases} \pm 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

Here, $|ij\rangle$ & $|ji\rangle$ are states w.r.t. same SG apparatus.

$$\langle j|i \rangle = \delta_{ji} \quad \left\{ \begin{array}{l} \text{Kronecker} \\ \text{Delta} \\ \text{Symbol} \end{array} \right\}$$

$$\text{So, } \delta_{ji} = \delta_{ij} = \begin{cases} \pm 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

$$\delta_{00} = \pm 1 = \delta_{\pm\pm} = \begin{pmatrix} \pm 1 & 0 \\ 0 & \pm 1 \end{pmatrix}$$

$$\delta_{0\pm} = 0 = \delta_{\pm 0}$$

Note:- e^- has momentum & position states as well but in quantum computation magnetic spin state of e^- is basically helpful

Duality of $e^- \rightarrow$ particle & wave nature

We have seen,

$$\begin{array}{c} \text{---} \boxed{5} \text{---} \boxed{T} \text{---} \\ | \quad \quad \quad | \\ \langle 0T|0S \rangle \langle 0T|0S \rangle^* + \langle \pm T|0S \rangle \langle \pm T|0S \rangle^* = 1 \end{array}$$

— (3)

Comparing eqn = (2) & (3)

$$\begin{cases} \langle 0T|0S \rangle^* = \langle 0S|0T \rangle \\ \langle \pm T|0S \rangle^* = \langle 0S|\pm T \rangle \end{cases}$$

Summary :-

$$(i) \langle j|i \rangle = \delta_{ij}$$

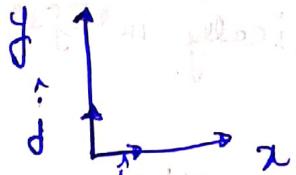
$$\delta_{ij} = \delta_{ji} = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j \end{cases}$$

where, $|i\rangle$ & $|j\rangle$ are base states w.r.t. a particular S-G apparatus.

$$(ii) \sum_{i=0}^{\infty} \langle x|i \rangle \langle i|\phi \rangle = \langle x|\phi \rangle$$

$$(iii) \langle x|\phi \rangle = \langle \phi|x \rangle^*$$

Consider 2-D Euclidean space \mathbb{R}^2



$$\begin{aligned} \hat{i} \cdot \hat{j} &= 1 = \hat{j} \cdot \hat{i} \\ \hat{j} \cdot \hat{j} &= 0 = \hat{i} \cdot \hat{i} \end{aligned}$$

→ compare it
summary
(i)

It seems that \hat{i} & \hat{j} are in some sense similar
to $|i\rangle$ & $|j\rangle$ of the basis states of e^- ?

$$\vec{v} \cdot \vec{\omega} = v_x \omega_x + v_y \omega_y$$

$$\vec{v} = v_x \hat{i} + v_y \hat{j}$$

$$v_x = v \cos \theta_{\pm} = \vec{v} \cdot \hat{i}$$

$$v_y = \text{various } \vec{v} \cdot \hat{j}$$

$$\omega_x = \vec{\omega} \cdot \hat{i}$$

$$\omega_y = \vec{\omega} \cdot \hat{j}$$

$$\vec{v} \cdot \vec{\omega} = (\vec{v} \cdot \hat{i})(\hat{i} \cdot \vec{\omega}) + (\vec{v} \cdot \hat{j})(\hat{j} \cdot \vec{\omega})$$

Compare it with (ii)

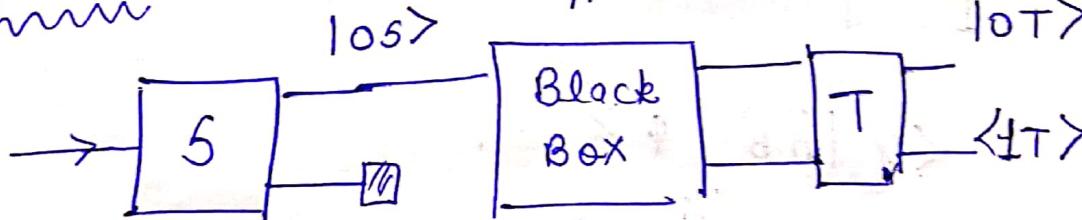
And, ~~$\vec{v} \cdot \hat{i} = \hat{i} \cdot \vec{v}$~~ ~~$= (\hat{i} \cdot \vec{v})^*$~~

$$\vec{v} \cdot \hat{i} = \hat{i} \cdot \vec{v}$$

$$= (\hat{i} \cdot \vec{v})^*$$

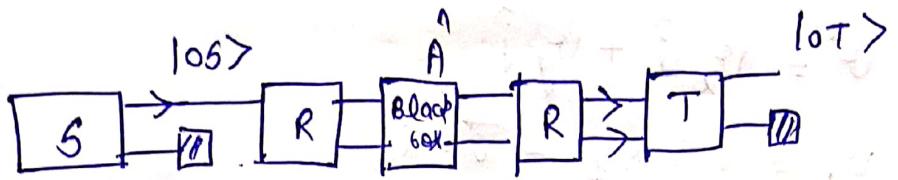
Conjugate of
real no. is
that real no.
itself.

Operators \Rightarrow



affects the
state of
 e^- in some
way

$\langle 0T | \hat{A} | 10S \rangle$
operator



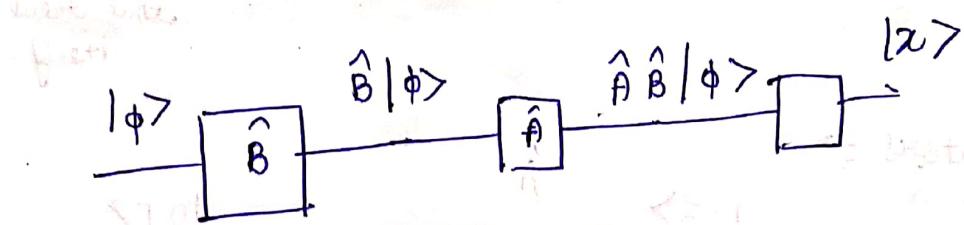
$$\langle \chi | \hat{A} | \phi \rangle = \sum_{i,j} \langle \chi | j \rangle \langle j | \hat{A} | i \rangle \langle i | \phi \rangle$$

$$\langle i | i \rangle \langle i | = I$$

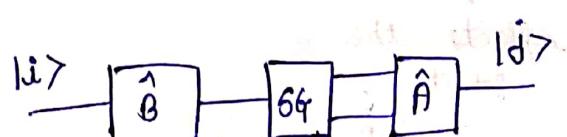
Initial state $| \psi \rangle = \frac{1}{\sqrt{2}}(| 0 \rangle + | 1 \rangle)$

	$ 0 \rangle$	$ 1 \rangle$
$ 0 \rangle$	$\langle 0 \hat{A} 0 \rangle$	$\langle 0 \hat{A} 1 \rangle$
$ 1 \rangle$	$\langle 1 \hat{A} 0 \rangle$	$\langle 1 \hat{A} 1 \rangle$

The operator \hat{A} is completely described by giving 4 notations.



$$\langle \chi | \hat{A} \hat{B} | \phi \rangle$$



$$\langle j | \hat{A} \hat{B} | i \rangle = \sum_{k=0,1} \langle j | \hat{A} | k \rangle \langle k | \hat{B} | i \rangle$$

$$\begin{array}{c}
 \text{matrix} \quad \text{matrix} \\
 (\text{look at tablet}) \\
 (\text{initial-final})
 \end{array}$$

✓ $\langle j\sigma | \phi \rangle = \sum_{i=0}^{\pm} \langle j\sigma | i^T \rangle \langle iT | \phi \rangle$

$i = T$ Legend formation
S-language (writing)

* Linear Algebra (Vector Spaces) \rightarrow

Vector space :- A vector space is a set S where elements are called vectors & denoted by ' $|v\rangle$ ' with following 2 operations defined :

(i) Vector addition \rightarrow If $|a\rangle, |b\rangle \in S$
then $|a\rangle + |b\rangle \in S$

(ii) Multiplication by scalar \rightarrow Multiplication of a vector by a scalar (complex no. for us) if

If $\alpha \in \mathbb{C}$ (complex No.)
& $|a\rangle \in S$, then -

$\Rightarrow \alpha |a\rangle \in S$

Note:- Because the scalars for us ~~are~~ belong to \mathbb{C} , the vector space is a complex vector space; if scalars $\in \mathbb{R}$ then vector space is called Real vector space.

In addition,

- (i) S consists of a special vector, the zero vector (0_V) such that -

$$|a\rangle + 0_V = |a\rangle \quad \forall |a\rangle \in S$$

↳ Identity element

- (ii) For every $|a\rangle \in S$, there exists a $|a'\rangle \in S$ such that -

$$|a\rangle + |a'\rangle = 0_V$$

↳ Additive element

- (iii) Vector addition is commutative

$$|a\rangle + |b\rangle = |b\rangle + |a\rangle$$

$$\forall |a\rangle, |b\rangle \in S$$

and Associative

$$|a\rangle + (|b\rangle + |c\rangle) = (|a\rangle + |b\rangle) + |c\rangle$$

- (iv) Scalar multiplication follows usual commutative & associative & distributive property

* For $\alpha, \beta \in \mathbb{C}$

$$\rightarrow \alpha(\beta|a\rangle) = (\alpha \cdot \beta)|a\rangle$$

$$\rightarrow (\alpha + \beta)|a\rangle = \alpha|a\rangle + \beta|a\rangle$$

$$\rightarrow \alpha(|a\rangle + |b\rangle) = \alpha|a\rangle + \alpha|b\rangle$$

Q Is the set of all quadratic polynomials over real no. a vector space?

$$P(x) = ax^2 + bx + c$$

* Linear independence of vectors :- A set of vectors $|v_1\rangle, |v_2\rangle, \dots, |v_N\rangle$ is said to be linearly independent if a relation $\sum_{i=1}^N \lambda_i |v_i\rangle = 0$ — (1) necessarily imply $\lambda_i = 0 \forall i$

On the other hand, if (1) holds with at least two λ_i 's non-zero then the set of vectors is linearly dependent.

e.g. In \mathbb{R}^2 , $a_x \hat{i} + a_y \hat{j} = 0 \Rightarrow a_x = 0 = a_y$ imply

\hat{i} & \hat{j} are linearly independent.

Dimension of a vector space \Rightarrow is max. no. of linearly independent vectors in that space.

Span :- A sub-set of vectors in S with the property that any vector in ' S ' can be expressed in terms of vectors in the sub-set is said to be span of ' S '.

e.g. If $|v_1\rangle, |v_2\rangle, \dots, |v_N\rangle \in S$ & satisfy the property that any $|a\rangle \in S$ can be written as $|a\rangle = \sum_{i=1}^N \alpha_i |v_i\rangle$ then the set $|v_i\rangle$ span S .

Basis :- A set of linearly independent vectors in 'S' which spans S is said to form a basis for S.

* Postulates of Quantum Mechanics :-

- (i) Any isolated (or closed) physical system has an associated complex vector space also called the state space of the system. The state of the system is described by a vector (the state vector) in the state space (the state vector) in the state space depends on the system under consideration.

$$|a\rangle \rightarrow \boxed{\text{Ket Vector}}$$

And, this state space is called Ket space.

→ If $|a\rangle$ & $|b\rangle$ are any two Ket vectors, then their sum is another Ket vector.

$$|a\rangle + |b\rangle = |c\rangle$$

Similarly, $\alpha |a\rangle$ ($\alpha \in \mathbb{C}$) is also Ket vector.

Note :- In quantum mechanics, $|a\rangle$ & $\alpha |a\rangle$ describe the same state.

(why?) i.e. Scaling a vector does not change its state

$$\checkmark \quad \{ \alpha \neq 0 \}$$

→ If we multiply $|a\rangle$ by a zero number, then we get a zero vector.

$$0 \cdot |a\rangle = 0$$

* Linear superposition → A more general linear combination of state vectors

will be $\alpha|a\rangle + \beta|b\rangle$; $\alpha, \beta \in \mathbb{C}$
and we say that this represents linear superposition of $|a\rangle$ & $|b\rangle$.

(ii) Observables (for e.g. position, momentum, spin etc.) are represented by linear operators on the vector space
of operators denoted by \hat{O}, \hat{A} etc.

→ Operators act on ket vectors from the left $\hat{A}(|c\rangle) = |\hat{A}c\rangle$ is the result if another ket.

* Distinction b/w vector space & state space

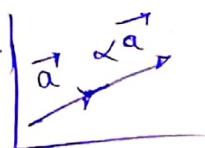


To form a circle

$\pi, 3\pi$ are distinct vectors in vector space

But $\pi, 3\pi$ are same vectors in state space.

Because they represent same state.



a & αa are distinct vectors in vector space, but not in state space.

→ Sometimes the action of an operator on a vector gives back same vector multiplied by a number.

$$\hat{A}|\alpha\rangle = \alpha|\alpha\rangle$$

In such a case we say that →

\hat{A} → Eigen Vector

α → Eigen Value

e.g. (i) Suppose you place a vector along Z rotation so now if you rotate (operator applied) the vector about Z -axis, its state won't change.

(ii)



state does not change

$$S_Z|10\rangle = \frac{\hbar}{2}|10\rangle$$

* Operators Algebra :-

(1.) If \hat{x} & \hat{y} are any 2 operators then $\hat{x} + \hat{y} = \hat{y} + \hat{x}$ is also an operator.

$$(\hat{x} + \hat{y})|\alpha\rangle = \hat{x}|\alpha\rangle + \hat{y}|\alpha\rangle$$

(2.) Operators \hat{A} & \hat{B} are said to be equal ($\hat{A} = \hat{B}$) iff :

$$\cancel{\hat{A}} \cdot \hat{A}|\alpha\rangle = \hat{B}|\alpha\rangle$$

(3.) If $\hat{x}|\alpha\rangle = 0$, & $k \in S$, then \hat{x} is called the null operator.

* Linearity of operation \rightarrow

$$\hat{X}(\alpha|\alpha\rangle + \beta|\beta\rangle) = \alpha\hat{X}|\alpha\rangle + \beta\hat{X}|\beta\rangle$$

(4.) If \hat{X} & \hat{Y} are two operators,

$$\hat{X}\hat{Y}|\alpha\rangle \equiv \hat{X}(\hat{Y}|\alpha\rangle)$$

In general, operators don't commute.

$$\Rightarrow \hat{X}\hat{Y} \neq \hat{Y}\hat{X}$$

$$\Rightarrow \hat{X}\hat{Y} - \hat{Y}\hat{X} \neq 0$$

$$\Rightarrow [\hat{X}, \hat{Y}] \neq 0$$

denoting commutes

Not commutative

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(5.) Associative law \rightarrow

$$(\hat{X}\hat{Y})\hat{Z} = \hat{X}(\hat{Y}\hat{Z})$$

* Inner product :- Additional on the vector space

$$S \times S \rightarrow \mathbb{C}$$

Notation \rightarrow If $|\alpha\rangle$ & $|\beta\rangle$ are two vectors then
their inner product is $\langle \alpha | \beta \rangle$

Similarly,
Inner product of $|\beta\rangle$ & $|\alpha\rangle$ is $\langle \beta | \alpha \rangle$

Some requirements for Inner Product \rightarrow

• Some requirements for Inner Product \rightarrow

(i) Inner product has to be linear in 2nd argument i.e.

$$|\beta\rangle = \alpha|\alpha\rangle + \beta|\beta\rangle$$

then inner product $| \alpha \rangle, | \beta \rangle$ is -

$$\langle \alpha | \beta \rangle = \underbrace{\langle \alpha |}_{\langle \alpha |} (a| \gamma \rangle + b| \delta \rangle) \\ = a \langle \alpha | \gamma \rangle + b \langle \alpha | \delta \rangle$$

(ii) ~~that is~~ $\langle \alpha | \beta \rangle = \langle \beta | \alpha \rangle^*$

$$= \overline{(\langle \beta | \alpha \rangle)}$$

* i.e. \Rightarrow complex conjugate

(iii) $\langle \alpha | \alpha \rangle \geq 0$

$\langle \alpha | \alpha \rangle \rightarrow$ Real no. (why?)

equality holds only when

$$|\alpha \rangle = 0_v$$

Look at last property

Orthogonal vectors :- $|a\rangle$ & $|b\rangle$ are orthogonal

if:

$$\text{Now } \langle a | b \rangle = \langle b | a \rangle = 0$$

For any vector $|\alpha \rangle$, $\sqrt{|\langle \alpha | \alpha \rangle|}$

↓ \hookrightarrow Norm (or length)
of vector $|\alpha \rangle$

Notation:

$$\| |\alpha \rangle \|$$

So, for a given vector $|\alpha \rangle$

Unit vector $\rightarrow \tilde{|\alpha \rangle} = \frac{|\alpha \rangle}{\| |\alpha \rangle \|} = \frac{|\alpha \rangle}{\sqrt{|\langle \alpha | \alpha \rangle|}}$

{ Normalized
vector }

* Dual Vector (or Bra Vector) :-

Given any $|x\rangle$ in \mathcal{S} we can define a vector dual to $|x\rangle$ denoted by $\langle x|$

Dual vectors can act on ket vectors to give "scalar". In particular if $|\beta\rangle$ is a ket vector & $\langle x|$ is dual to $|x\rangle$ then -

$$\langle x| |\beta\rangle = \langle x|\beta\rangle$$

$$\langle x|\cdot|\beta\rangle \equiv \langle x|\beta\rangle$$

Bra(x)Ket

Q Check that the space of dual vectors is also a vector space. (Use pencholate)

Fourier transforms

~~Dual vector~~ \leftrightarrow Ket vector

$$\tilde{f}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(t) e^{i\omega t} dt$$
$$f(t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \tilde{f}(\omega) e^{-i\omega t} d\omega$$
$$|x\rangle = \sum_{i=1}^n c_i |i\rangle$$

(i) $|x\rangle \xrightarrow{\text{Dual}} \langle x|$

(ii) $|x\rangle + |\beta\rangle \xrightarrow{\text{Dual}} \langle x| + \langle \beta|$

(iii) $a|x\rangle + b|\beta\rangle \xrightarrow{\text{dual?}}$

Let $a|\alpha\rangle + b|\beta\rangle = |\gamma\rangle \rightarrow$ linearity
dual vector $\langle\gamma|$

so, $\langle\gamma|\gamma\rangle = \overline{\langle\gamma|\gamma\rangle} \quad \text{is second argument}$ \therefore (i) property
 $= \langle\gamma| (a|\alpha\rangle + b|\beta\rangle)$ of inner product

$$= \bar{a} \overline{\langle\gamma|\alpha\rangle} + \bar{b} \overline{\langle\gamma|\beta\rangle}$$

$$= a^* \langle\alpha|\gamma\rangle + b^* \langle\beta|\gamma\rangle$$

$$\langle\gamma|\gamma\rangle = (a^* \langle\alpha| + b^* \langle\beta|) \cancel{\langle\gamma|}$$

$$\therefore \cancel{\langle\gamma|} \langle\gamma| = a^* \cancel{\langle\alpha|} + b^* \cancel{\langle\beta|}$$

(iii) \Rightarrow

e.g. $|\psi\rangle = (3+i)|\pm\rangle + 4i|\downarrow\rangle$

$$\Rightarrow \begin{cases} \langle\psi| = (3-i)\langle\pm| - 4i\langle\downarrow| \\ \text{Length of } |\psi\rangle \end{cases} \quad \begin{matrix} \text{using (iii)} \\ \text{property just discussed} \end{matrix}$$

if $|\pm\rangle$ & $|\downarrow\rangle$ were unit vectors

$\langle\psi|\psi\rangle ?$

↳ inner product

(iv) $\hat{A}|\alpha\rangle \xrightarrow{\text{dual}} \langle\alpha|\hat{A}^\dagger$

How?

\hat{A}^\dagger adjoint of op- \hat{A}

$$\text{Let } \hat{A}|\alpha\rangle = |\beta\rangle \quad - \textcircled{1}$$

If $|\alpha\rangle$ is any other vector

$$\text{then } \langle \alpha | \beta \rangle = \langle \alpha | \hat{A} | \gamma \rangle \quad - \textcircled{2}$$

But

$$\langle \alpha | \beta \rangle = \frac{\langle \beta | \alpha \rangle}{\langle \alpha | \hat{A}^+ | \alpha \rangle}$$

$$\left\{ \begin{array}{l} \text{let} \\ \langle \alpha | \hat{A}^+ = \langle \beta | \end{array} \right\}$$

$$\Rightarrow \langle \beta | \hat{A}^+ | \alpha \rangle = \langle \alpha | \hat{A} | \gamma \rangle$$

$$\Rightarrow \langle \gamma | \hat{A}^+ | \alpha \rangle = \langle \alpha | \hat{A} | \gamma \rangle$$

* If $\hat{A}^+ = \hat{A}$ i.e.

$$\langle \gamma | \hat{A}^+ | \alpha \rangle = \langle \gamma | \hat{A} | \alpha \rangle = \overline{\langle \alpha | \hat{A} | \gamma \rangle}$$

then \hat{A} is called Hermitian operator
(or self adjoint op.)

Q Show that $(\hat{x} \hat{y})^+ = \hat{y}^+ \hat{x}^+$

* Outer Product:-

op. acting left on Ket vector

$\hookrightarrow \hat{A}|\alpha\rangle \rightarrow$ Ket vector

op. acting right on Bra vector

$\hookrightarrow \langle \beta | \hat{A} \rightarrow$ Bra vector

Again, $\alpha \otimes |\alpha\rangle\langle\beta| \rightarrow$ what does this signify?

$$\hookrightarrow |\alpha\rangle\langle\beta| \leftarrow (\left|\alpha\right\rangle)$$

$\hookrightarrow |\alpha\rangle\langle\beta| (\left|\alpha\right\rangle) \rightarrow$ Ket vector

$$\Rightarrow |\alpha\rangle\langle\beta| \alpha \rangle \quad \begin{matrix} \hookdownarrow \\ \text{Scalar} \end{matrix} \quad \Rightarrow \text{Resultant Ket vector}$$

\hookrightarrow Ket vector

Similarly,

$$(\langle\alpha|) |\alpha\rangle\langle\beta|$$

\hookleftarrow Bra vector

$$\Rightarrow \langle\alpha| \alpha\rangle\langle\beta| \quad \begin{matrix} \hookrightarrow \\ \text{Bra} \end{matrix} \quad \Rightarrow \text{Resultant Bra vector}$$

$|\alpha\rangle\langle\beta|$ follows properties of \otimes operator.

$|\alpha\rangle\langle\beta| \rightarrow$ Outer Product

\hookrightarrow acting on left from ket vector
gives \otimes ket vector

& acting on right of bra vector
gives bra vector

Q Show that:

$$|\alpha\rangle\langle\beta| \xrightarrow{\text{dual}} \langle\beta|\alpha\rangle$$

$\begin{matrix} \text{mn} & \text{mm} \\ \hat{x} & \hat{x}^+ \end{matrix}$

Statement :- For Hermitian operator i.e. for \hat{A} (Theorem) satisfying $\hat{A}^+ = \hat{A}$, the eigenvalues are all real.

$$\hat{A} |h_i\rangle = h_i |h_i\rangle \text{ for } h_i \in \mathbb{R}$$

& if $|h_i\rangle$ & $|h_j\rangle$ are eigen vectors belonging to different eigen values:

$$h_i \neq h_j$$

then $|h_i\rangle$ & $|h_j\rangle$ are orthogonal.

$$\langle h_i | h_j \rangle = \langle h_j | h_i \rangle = 0$$

* $\hat{A} |a'\rangle = a' |a'\rangle \rightarrow \{ \text{Eigen equation} \}$

\downarrow \downarrow
 operator Eigen ket
 \downarrow
 corresponding
 eigen value

Assumption :- It is clear that the eigen kets of an operator (in our case, Hermitian) will generate a vector space.

We assume that these eigenkets span the entire state space of the physical system under consideration.

→ The eigen kets are orthogonal to each other & because we work with unit vectors, we have, what is known as "Orthogonal set" i.e. if $|a'\rangle$ & $|a''\rangle$ are eigen kets of an Hermitian operator, then we have

$$\langle a' | a'' \rangle = \delta_{a'a''}$$

Eigenkets span the state space of the system

Any ket (Normalized)
can be expressed as linear
combination of eigen kets $|a_i\rangle$

$$|\alpha\rangle = \sum_i c_{a_i} |a_i\rangle \quad \text{--- (1)}$$

Q What are coeff. c_{a_i} ?

Ans Using orthogonality of eigenkets we have -

$$\langle a_j | \alpha \rangle = \sum c_{a_i} \langle a_j | a_i \rangle$$

$$\Rightarrow \langle a_j | \alpha \rangle = \sum c_{a_i} \delta_{j,i} \quad \left\{ \begin{array}{l} \text{For } i=j \\ \delta_{j,i} = 1 \end{array} \right.$$

$$\Rightarrow c_{a_j} = \langle a_j | \alpha \rangle \quad \text{--- (2)}$$

∴ Again, writing eqⁿ (1)

$$|\alpha\rangle = \sum_i \langle a_i | \alpha \rangle |a_i\rangle$$

$$\text{or } |\alpha\rangle = \sum_i |a_i\rangle \langle a_i | \alpha \rangle$$

∴ $|\alpha\rangle$ arbitrary

$$\Rightarrow \boxed{\sum_i |a_i\rangle \langle a_i | \alpha \rangle = 1}$$

Remember,
we have formally
used this during
5G experiment
mathematics

Again,

$$\langle \alpha | \alpha \rangle = 1 = \sum_i \langle \alpha | a_i \rangle \langle a_i | \alpha \rangle$$

$$= \sum_i |c_{ai}|^2 |\alpha_i\rangle\langle\alpha_i| \alpha_i$$

$$= \sum_i c_{ai}^* c_{ai}$$

$$\mathbb{1} = \sum_i |c_{ai}|^2$$

$$\therefore \boxed{\sum_i |c_{ai}|^2 = \mathbb{1}} \quad \checkmark$$

* Projection ~~operator~~ operator :-

$$P_i = |\alpha_i\rangle\langle\alpha_i|$$

$$\Rightarrow P_i^2 = (|\alpha_i\rangle\langle\alpha_i|) (|\alpha_i\rangle\langle\alpha_i|)$$

$$= |\alpha_i\rangle\langle\alpha_i| \alpha_i\rangle\langle\alpha_i|$$

$$= |\alpha_i\rangle\langle\alpha_i|$$

$$= P_i$$

$$\text{And, } P_i^+ = |\alpha_i\rangle\langle\alpha_i|$$

$$= P_i$$

$$\begin{aligned} P_i^2 &= P_i \\ \& P_i^+ = P_i \end{aligned} \quad \left. \begin{array}{l} \text{Any vector following these two} \\ \text{properties is} \\ \text{projection vector} \end{array} \right\}$$

* Unitary operator :- If \hat{U} is an operator such that -

$$UU^+ = U^+U = \mathbb{1}$$

$$\Rightarrow U^+ = U^{-1} \quad \hookrightarrow \text{Inverse of } U$$

Unitary operator take orthogonal basis to orthogonal basis. (what does this mean?)

Suppose, $|i\rangle, |j\rangle$ are such that -

$$|i\rangle\langle i| = 1 = |j\rangle\langle j|$$

$$\& \langle j|i\rangle = 0 = \langle j|j\rangle$$

$$|i\rangle \xrightarrow{U} |i'\rangle = U|i\rangle$$

$$|j\rangle \longrightarrow |j'\rangle = U|j\rangle$$

$$\therefore \langle i|j\rangle \xrightarrow{U} \langle i'|j'\rangle$$

Dual
vector's
operation

$$= \langle i|U^+ U|j\rangle$$

$$|i'\rangle = U|i\rangle = \langle i|j\rangle$$

$$\begin{matrix} \uparrow & \downarrow \\ \text{Dual vector} & \text{dual vector} \end{matrix} = \delta_{ij}$$

$$\langle i' | = \delta \langle i | U^+$$

Q Show that for any 2 vectors $|\alpha\rangle, |\beta\rangle$, then inner product $\langle \alpha | \beta \rangle$ does not change under unitary transformation.

↳ Proved just above

* Matrix Representation :-

$$\sum_i |\alpha_i\rangle \langle \alpha_i| = 1$$

Let \hat{x} be any operator on a n-dimensional space

$$\Rightarrow X = \sum_{i=1}^n \sum_{j=1}^n |a_j\rangle \langle a_j| \hat{X} |a_i\rangle \langle a_i|$$

n^2 no.

which can be arranged as $n \times n$ matrix

$$\begin{matrix} & \langle a_j | \hat{X} | a_i \rangle \\ \downarrow & \downarrow \\ \text{Row} & \text{Column} \end{matrix}$$

$$\hat{X} = \begin{pmatrix} \langle a_1 | x | a_1 \rangle & \langle a_1 | x | a_2 \rangle & \dots & \langle a_1 | x | a_n \rangle \\ \langle a_2 | x | a_1 \rangle & \langle a_2 | x | a_2 \rangle & \dots & \langle a_2 | x | a_n \rangle \\ \vdots & \vdots & & \vdots \\ \langle a_n | x | a_1 \rangle & \langle a_n | x | a_2 \rangle & \dots & \langle a_n | x | a_n \rangle \end{pmatrix}$$

$$\hat{X}^+ = ?$$

$$* \quad \langle a_i | x^+ | a_j \rangle = \overline{\langle a_j | x | a_i \rangle} \rightarrow \begin{array}{l} \text{Complex conjugate} \\ \text{of each element} \\ \text{of transpose} \\ \text{of matrix} \end{array}$$

(i) If X is Hermitian

$$x^+ = \underline{x}$$

$$\Rightarrow \langle a_i | x^+ | a_j \rangle = \langle a_j | x | a_i \rangle$$

↳ Diagonal elements \rightarrow Real No.

$$* \quad \text{Let } |\gamma\rangle = X|\alpha\rangle$$

$$\Rightarrow \langle a_i | \gamma \rangle = \langle a_i | x | \alpha \rangle$$

$$= \sum_{j=1}^n \langle a_i | x | a_j \rangle \langle a_j | \alpha \rangle$$

$$|\alpha\rangle = \begin{pmatrix} \langle a_1 | \alpha \rangle \\ \langle a_2 | \alpha \rangle \\ \vdots \\ \langle a_n | \alpha \rangle \end{pmatrix}$$

↳ column matrix

Similarly,

$$\therefore |\gamma\rangle = \begin{pmatrix} \langle a_1 | \gamma \rangle \\ \langle a_2 | \gamma \rangle \\ \vdots \\ \langle a_n | \gamma \rangle \end{pmatrix}$$

Show that $\langle \gamma | = \langle \alpha | X$ allows one to represent dual vectors by row vectors.

$$\begin{aligned} \langle \gamma | &= (\langle \gamma | a_1 \rangle \quad \langle \gamma | a_2 \rangle \quad \dots \quad \langle \gamma | a_n \rangle) \\ &= (\langle a_1 | \gamma \rangle^* \quad \langle a_2 | \gamma \rangle^* \quad \dots \quad \langle a_n | \gamma \rangle^*) \end{aligned}$$

* Under duality

$$|\gamma\rangle \leftrightarrow \cancel{|\alpha\rangle} \langle \gamma |$$

Note:- Representation of $|\gamma\rangle$ is related to representation of $\langle \gamma |$ by complex conjugate transpose.

Just as for $x \leftarrow x^T$

$$\Rightarrow \langle \alpha | \beta \rangle = (\underbrace{\langle \alpha_1 | \alpha \rangle^*}_{\substack{\downarrow \\ \text{Inner product}}} \underbrace{\langle \alpha_2 | \alpha \rangle^*}_{\substack{\downarrow \\ \text{Row matrix}}} \dots \underbrace{\langle \alpha_n | \alpha \rangle^*}_{\substack{\downarrow \\ \text{Row matrix}}}) / \langle \alpha_1 | \beta \rangle$$

$$\begin{pmatrix} \langle \alpha_1 | \beta \rangle \\ \langle \alpha_2 | \beta \rangle \\ \vdots \\ \langle \alpha_n | \beta \rangle \end{pmatrix}$$

↓
Column matrix

$$Q \quad |\alpha\rangle \langle \beta| = ?$$

* Representation of \hat{A} as its own basis.
 eigen

$$\hat{A} = \begin{pmatrix} \langle \alpha_1 | A | \alpha_1 \rangle & \langle \alpha_1 | A | \alpha_2 \rangle & \dots \\ \langle \alpha_2 | A | \alpha_1 \rangle & \langle \alpha_2 | A | \alpha_2 \rangle & \dots \\ \vdots & \vdots & \ddots \\ \langle \alpha_n | A | \alpha_1 \rangle & \langle \alpha_n | A | \alpha_2 \rangle & \dots & \langle \alpha_n | A | \alpha_n \rangle \end{pmatrix}$$

$$\hat{A} |\alpha_i\rangle \equiv \alpha_i |\alpha_i\rangle$$

$$\Rightarrow \langle \alpha_j | A | \alpha_i \rangle = \alpha_i \delta_{ij}$$

$$\Rightarrow \hat{A} = \begin{pmatrix} \alpha_1 & & & 0 \\ & \alpha_2 & & \\ & & \ddots & \\ 0 & & & \alpha_n \end{pmatrix} = \sum_i \alpha_i |\alpha_i\rangle \langle \alpha_i|$$

e.g. $|0\rangle, |\pm\rangle$

$$\langle 0 | 0 \rangle = 1 = \langle \pm | \pm \rangle$$

$$\langle 0 | \pm \rangle = 0 = \langle \pm | 0 \rangle$$

$$\therefore |0\rangle = \begin{pmatrix} \langle 0|0 \rangle \\ \langle \pm|0 \rangle \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\& |+\rangle = \begin{pmatrix} \langle 0|+ \rangle \\ \langle \pm|+ \rangle \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Let us define an operator \otimes

$$\otimes|0\rangle = |0\rangle \quad \rightarrow \text{operation of } \otimes \text{ on } |0\rangle \text{ gives } |0\rangle$$

$$\& \otimes|+\rangle = -|+\rangle$$

$$\therefore \otimes = \begin{pmatrix} \langle 0|\otimes|0 \rangle & \langle 0|\otimes|+ \rangle \\ \langle +|\otimes|0 \rangle & \langle +|\otimes|+ \rangle \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\otimes^* = \otimes \quad \rightarrow \text{Hermitian operator}$$

Q Representation of $|0\rangle \langle +|$?

Q Are the states

$$|+\rangle = \frac{|0\rangle + |+\rangle}{\sqrt{2}}$$

$$\& |- \rangle = \frac{|0\rangle - |+\rangle}{\sqrt{2}}$$

Orthogonal?

Q What is the matrix representation of $|0\rangle$ in the $(|+\rangle, |-\rangle)$ basis?

Q Representation of \hat{z} in $(|+\rangle, |-\rangle)$ basis

* Measurement postulated:-

$$|\alpha\rangle = \sum_{i=1}^n c_{\alpha i} |a_i\rangle$$

(i) If $|\alpha\rangle$ is an vector, then after the measurement it jumps to one of eigen kets.

i.e. $|\alpha\rangle \xrightarrow[\hat{A}]{} |a_i\rangle$

But, if $|\alpha\rangle$ happens to be an eigen ket say $|a_j\rangle$ then $|a_j\rangle \xrightarrow[\hat{A}]{} |a_j\rangle$

(ii) In general, the probability to be found in state $|a_i\rangle$ on measurement is -

~~Fact~~ $|c_{\alpha i}| |\alpha\rangle|^2 = |c_{\alpha i}|^2$

$$\Rightarrow \sum |c_{\alpha i}|^2 = 1 \rightarrow \left\{ \begin{array}{l} \text{Sum of} \\ \text{probability} \end{array} \right\}$$

* Expectation value of \hat{A} in state $|\alpha\rangle$:-

$$\langle \hat{A} \rangle = \langle \alpha | \hat{A} | \alpha \rangle$$

$$\begin{aligned}
 &= \sum_{i,j} \langle \alpha | \alpha_j \rangle \langle \alpha_j | A | \alpha_i \rangle \langle \alpha_i | \alpha \rangle \\
 &= \sum_{i,j} a_i \langle \alpha | \alpha_j \rangle \langle \alpha_i | \alpha \rangle \delta_{ij} \\
 &= \sum_{i,j} a_i |c_{\alpha_i}|^2
 \end{aligned}$$

$$\langle \alpha | \alpha \rangle = \sum_{i=1}^n = \infty$$

For every state α there can be $\langle \alpha | \alpha \rangle = \infty$
because it is impossible to normalize

$$\langle \alpha | \alpha \rangle = \frac{\langle \alpha | \alpha \rangle}{\langle \alpha | \alpha \rangle}$$

It's better to use the concept $\langle \alpha | \alpha \rangle$ instead
of $\langle \alpha | \alpha \rangle$ because it is easier to work with

and it's also helpful with choosing of α
as the normalized state α or not

so if $\langle \alpha | \alpha \rangle = 0$ then α is not

normalized and we have to choose another

so if $\langle \alpha | \alpha \rangle > 0$ then α is normalized and we can choose it