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**dsPIC33FJ32MC302/304,  
dsPIC33FJ64MCX02/X04 and  
dsPIC33FJ128MCX02/X04**  
**Data Sheet**

High-Performance,  
16-bit Digital Signal Controllers

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# dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 AND dsPIC33FJ128MCX02/X04

## High-Performance, 16-bit Digital Signal Controllers

### Operating Range:

- Up to 40 MIPS operation (at 3.0V-3.6V):
  - Industrial temperature range (-40°C to +85°C)
  - Extended temperature range (-40°C to +125°C)
- Up to 20 MIPS operation (at 3.0V-3.6V):
  - High temperature range (-40°C to +150°C)

### High-Performance DSC CPU:

- Modified Harvard architecture
- C compiler optimized instruction set
- 16-bit wide data path
- 24-bit wide instructions
- Linear program memory addressing up to 4M instruction words
- Linear data memory addressing up to 64 Kbytes
- 83 base instructions: mostly 1 word/1 cycle
- Two 40-bit accumulators with rounding and saturation options
- Flexible and powerful addressing modes:
  - Indirect
  - Modulo
  - Bit-Reversed
- Software stack
- 16 x 16 fractional/integer multiply operations
- 32/16 and 16/16 divide operations
- Single-cycle multiply and accumulate:
  - Accumulator write back for DSP operations
  - Dual data fetch
- Up to  $\pm$ 16-bit shifts for up to 40-bit data

### Direct Memory Access (DMA):

- 8-channel hardware DMA
- Up to 2 Kbytes dual ported DMA buffer area (DMA RAM) to store data transferred via DMA:
  - Allows data transfer between RAM and a peripheral while CPU is executing code (no cycle stealing)
- Most peripherals support DMA

### Timers/Capture/Compare/PWM:

- Timer/Counters, up to five 16-bit timers:
  - Can pair up to make two 32-bit timers
  - One timer runs as a Real-Time Clock with an external 32.768 kHz oscillator
  - Programmable prescaler
- Input Capture (up to four channels):
  - Capture on up, down or both edges
  - 16-bit capture input functions
  - 4-deep FIFO on each capture
- Output Compare (up to four channels):
  - Single or Dual 16-bit Compare mode
  - 16-bit Glitchless PWM mode
- Hardware Real-Time Clock and Calendar (RTCC):
  - Provides clock, calendar and alarm functions

### Interrupt Controller:

- 5-cycle latency
- Up to 53 available interrupt sources
- Up to three external interrupts
- Seven programmable priority levels
- Five processor exceptions

### Digital I/O:

- Peripheral pin Select functionality
- Up to 35 programmable digital I/O pins
- Wake-up/Interrupt-on-Change for up to 31 pins
- Output pins can drive from 3.0V to 3.6V
- Up to 5.5V output with open drain configuration on 5V tolerant pins with external pull-up
- 4 mA sink on all I/O pins

### On-Chip Flash and SRAM:

- Flash program memory (up to 128 Kbytes)
- Data SRAM (up to 16 Kbytes)
- Boot, Secure, and General Security for program Flash

### **System Management:**

- Flexible clock options:
  - External, crystal, resonator, internal RC
  - Fully integrated Phase-Locked Loop (PLL)
  - Extremely low jitter PLL
- Power-up Timer
- Oscillator Start-up Timer/Stabilizer
- Watchdog Timer with its own RC oscillator
- Fail-Safe Clock Monitor (FSCM)
- Reset by multiple sources

### **Power Management:**

- On-chip 2.5V voltage regulator
- Switch between clock sources in real time
- Idle, Sleep, and Doze modes with fast wake-up

### **Analog-to-Digital Converters (ADCs):**

- 10-bit, 1.1 Msps or 12-bit, 500 Ksps conversion:
  - Two and four simultaneous samples (10-bit ADC)
  - Up to nine input channels with auto-scanning
  - Conversion start can be manual or synchronized with one of four trigger sources
  - Conversion possible in Sleep mode
  - $\pm 2$  LSb max integral nonlinearity
  - $\pm 1$  LSb max differential nonlinearity

### **Audio Digital-to-Analog Converter (DAC):**

- 16-bit Dual Channel DAC module
- 100 Ksps maximum sampling rate
- Second-Order Digital Delta-Sigma Modulator

### **Comparator Module:**

- Two analog comparators with programmable input/output configuration

### **CMOS Flash Technology:**

- Low-power, high-speed Flash technology
- Fully static design
- 3.3V ( $\pm 10\%$ ) operating voltage
- Industrial and Extended temperature
- Low power consumption

### **Motor Control Peripherals:**

- 6-channel 16-bit Motor Control PWM:
  - Three duty cycle generators
  - Independent or Complementary mode
  - Programmable dead-time and output polarity
  - Edge-aligned or center-aligned
  - Manual output override control
  - One Fault input
  - Trigger for ADC conversions
  - PWM frequency for 16-bit resolution (@ 40 MIPS) = 1220 Hz for Edge-Aligned mode, 610 Hz for Center-Aligned mode
  - PWM frequency for 11-bit resolution (@ 40 MIPS) = 39.1 kHz for Edge-Aligned mode, 19.55 kHz for Center-Aligned mode
- 2-channel 16-bit Motor Control PWM:
  - One duty cycle generator
  - Independent or Complementary mode
  - Programmable dead time and output polarity
  - Edge-aligned or center-aligned
  - Manual output override control
  - One Fault input
  - Trigger for ADC conversions
  - PWM frequency for 16-bit resolution (@ 40 MIPS) = 1220 Hz for Edge-Aligned mode, 610 Hz for Center-Aligned mode
  - PWM frequency for 11-bit resolution (@ 40 MIPS) = 39.1 kHz for Edge-Aligned mode, 19.55 kHz for Center-Aligned mode
- 2-Quadrature Encoder Interface module:
  - Phase A, Phase B, and index pulse input
  - 16-bit up/down position counter
  - Count direction status
  - Position Measurement (x2 and x4) mode
  - Programmable digital noise filters on inputs
  - Alternate 16-bit Timer/Counter mode
  - Interrupt on position counter rollover/underflow

## Communication Modules:

- 4-wire SPI (up to two modules):
  - Framing supports I/O interface to simple codecs
  - Supports 8-bit and 16-bit data
  - Supports all serial clock formats and sampling modes
- I<sup>2</sup>C™:
  - Full Multi-Master Slave mode support
  - 7-bit and 10-bit addressing
  - Bus collision detection and arbitration
  - Integrated signal conditioning
  - Slave address masking
- UART (up to two modules):
  - Interrupt on address bit detect
  - Interrupt on UART error
  - Wake-up on Start bit from Sleep mode
  - 4-character TX and RX FIFO buffers
  - LIN 2.0 bus support
  - IrDA® encoding and decoding in hardware
  - High-Speed Baud mode
  - Hardware Flow Control with CTS and RTS
- Enhanced CAN (ECANTM module) 2.0B active:
  - Up to eight transmit and up to 32 receive buffers
  - 16 receive filters and three masks
  - Loopback, Listen Only and Listen All
  - Messages modes for diagnostics and bus monitoring
  - Wake-up on CAN message
  - Automatic processing of Remote Transmission Requests
  - FIFO mode using DMA
  - DeviceNet™ addressing support
- Parallel Master Slave Port (PMP/EPSP):
  - Supports 8-bit or 16-bit data
  - Supports 16 address lines
- Programmable Cyclic Redundancy Check (CRC):
  - Programmable bit length for the CRC generator polynomial (up to 16-bit length)
  - 8-deep, 16-bit or 16-deep, 8-bit FIFO for data input

## Packaging:

- 28-pin SPDIP/SOIC/QFN-S
- 44-pin TQFP/QFN

**Note:** See [Table 1](#) for the exact peripheral features per device.

**dsPIC33FJ32MC302/304,  
dsPIC33FJ64MCX02/X04 AND  
dsPIC33FJ128MCX02/X04 PRODUCT  
FAMILIES**

The device names, pin counts, memory sizes, and peripheral availability of each device are listed in [Table 1](#). The pages that follow show their pinout diagrams.

**TABLE 1: dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 AND dsPIC33FJ128MCX02/X04  
CONTROLLER FAMILIES**

Device	Pins	Remappable Peripheral										I/O Pins	Packages									
		Program Flash Memory (Kbyte)	RAM (Kbyte) <sup>(1)</sup>	Remappable Pins		16-bit Timer <sup>(2)</sup>	Input Capture	Output Compare Standard PWM	Motor Control PWM (Channels) <sup>(3)</sup>	Quadrature Encoder Interface	UART	SPI	ECAN™	External Interrupts <sup>(4)</sup>	RTCC	I <sup>2</sup> C™	CRC Generator	10-bit/12-bit ADC (Channels)	6-pin 16-bit DAC	Analog Comparator (2 Channels)/Voltage Regulator	8-bit Parallel Master Port (Address Lines)	
dsPIC33FJ128MC804	44	128	16	26	5	4	4	6, 2	2	2	2	2	1	3	1	1	1	9	1	1/1	11	35 QFN TQFP
dsPIC33FJ128MC802	28	128	16	16	5	4	4	6, 2	2	2	2	2	1	3	1	1	1	6	0	1/0	2	21 SPDIP SOIC QFN-S
dsPIC33FJ128MC204	44	128	8	26	5	4	4	6, 2	2	2	2	2	0	3	1	1	1	9	0	1/1	11	35 QFN TQFP
dsPIC33FJ128MC202	28	128	8	16	5	4	4	6, 2	2	2	2	2	0	3	1	1	1	6	0	1/0	2	21 SPDIP SOIC QFN-S
dsPIC33FJ64MC804	44	64	16	26	5	4	4	6, 2	2	2	2	1	3	1	1	1	1	9	1	1/1	11	35 QFN TQFP
dsPIC33FJ64MC802	28	64	16	16	5	4	4	6, 2	2	2	2	1	3	1	1	1	1	6	0	1/0	2	21 SPDIP SOIC QFN-S
dsPIC33FJ64MC204	44	64	8	26	5	4	4	6, 2	2	2	2	0	3	1	1	1	1	9	0	1/1	11	35 QFN TQFP
dsPIC33FJ64MC202	28	64	8	16	5	4	4	6, 2	2	2	2	0	3	1	1	1	1	6	0	1/0	2	21 SPDIP SOIC QFN-S
dsPIC33FJ32MC304	44	32	4	26	5	4	4	6, 2	2	2	2	0	3	1	1	1	1	9	0	1/1	11	35 QFN TQFP
dsPIC33FJ32MC302	28	32	4	16	5	4	4	6, 2	2	2	2	0	3	1	1	1	1	6	0	1/0	2	21 SPDIP SOIC QFN-S

**Note 1:** RAM size is inclusive of 2 Kbytes of DMA RAM for all devices except dsPIC33FJ32MC302/304, which include 1 Kbyte of DMA RAM.

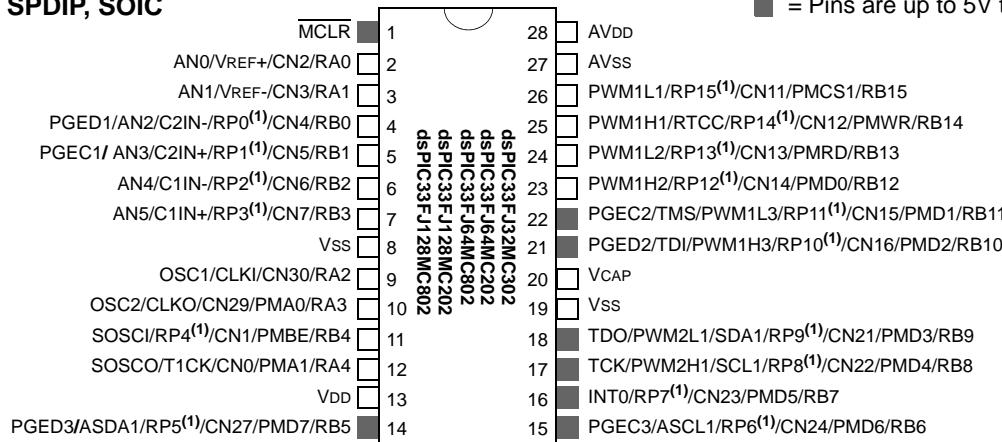
**2:** Only four out of five timers are remappable.

**3:** Only PWM fault pins are remappable.

**4:** Only two out of three interrupts are remappable.

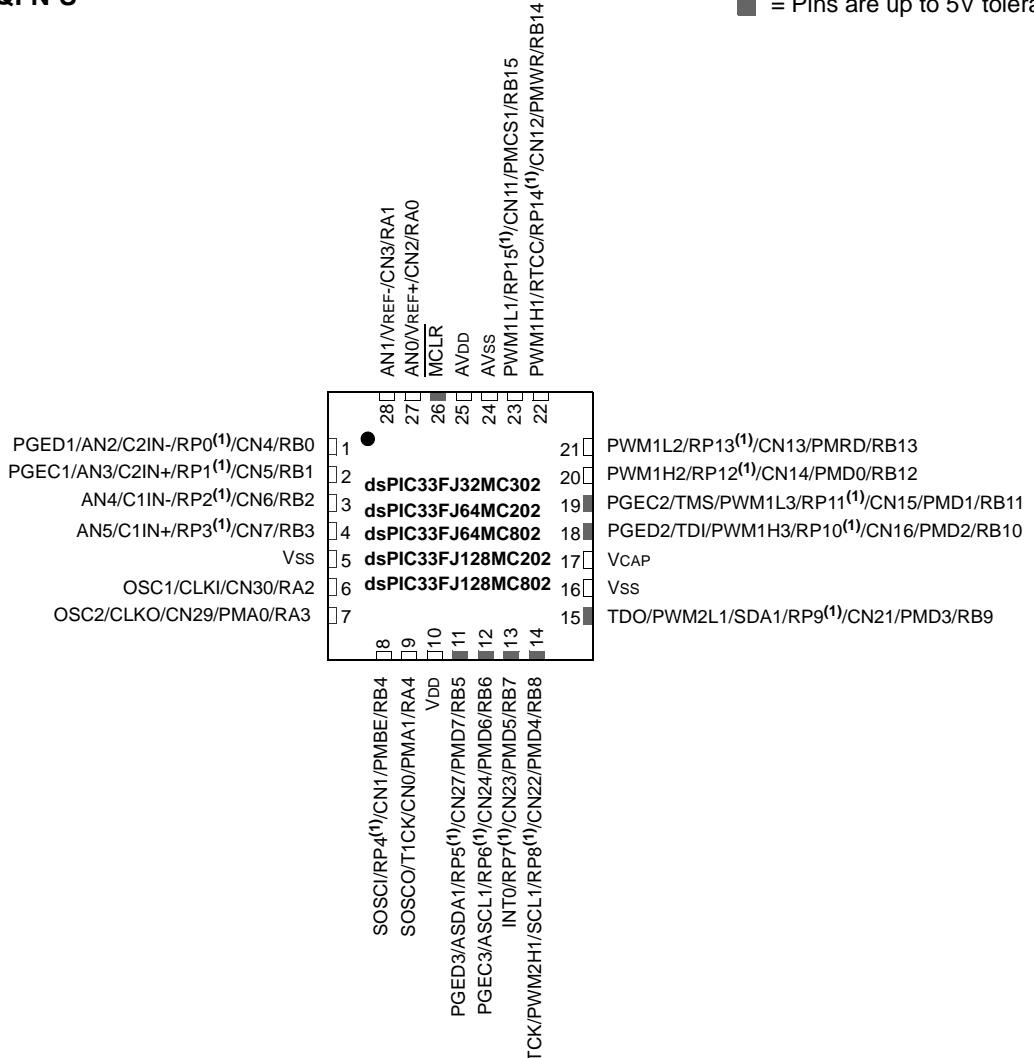
## Pin Diagrams

### 28-Pin SPDIP, SOIC



■ = Pins are up to 5V tolerant

### 28-Pin QFN-S<sup>(2)</sup>



■ = Pins are up to 5V tolerant

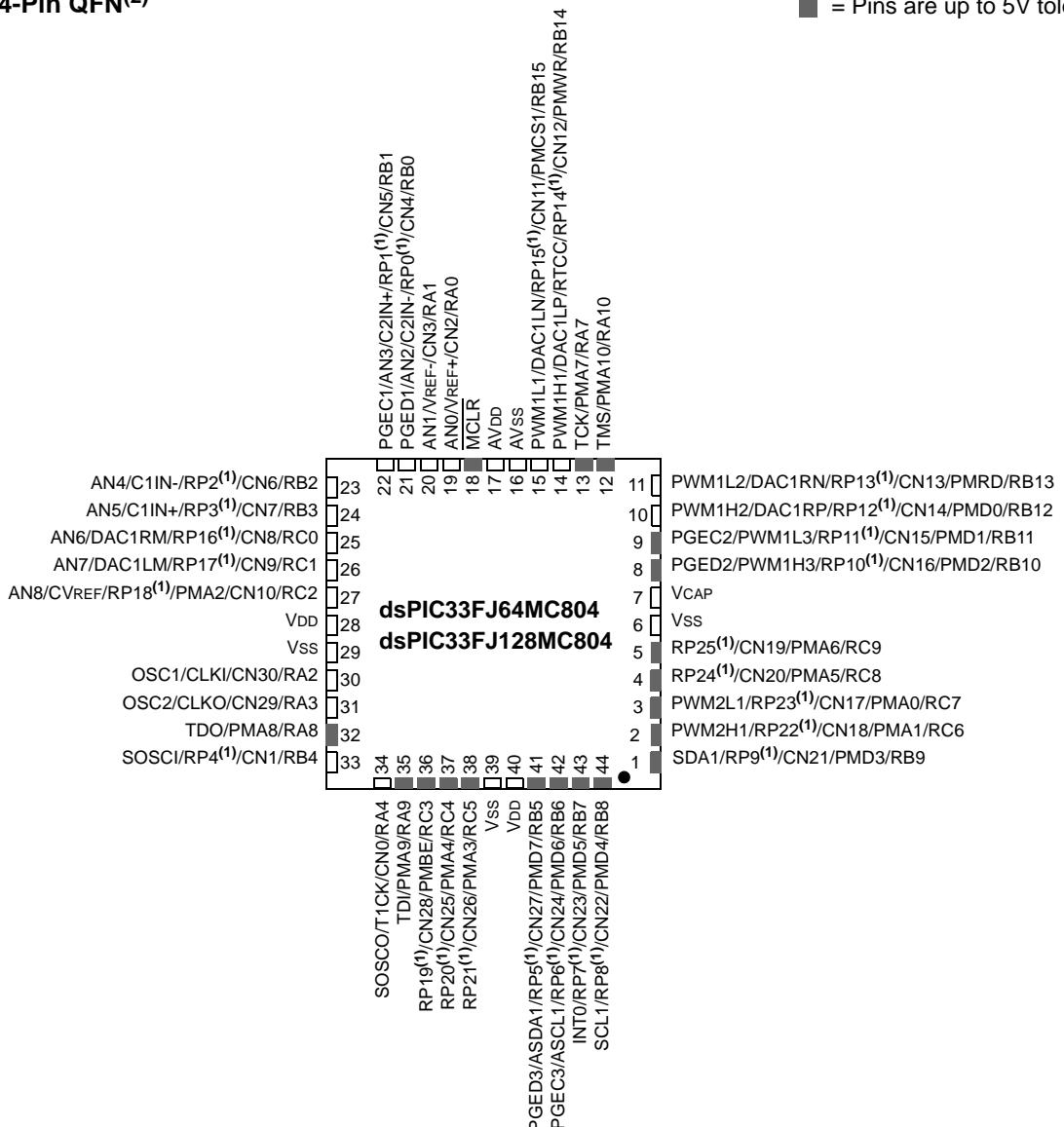
**Note 1:** The RPx pins can be used by any remappable peripheral. See [Table 1](#) in this section for the list of available peripherals.

**2:** The metal plane at the bottom of the device is not connected to any pins and is recommended to be connected to Vss externally.

**Pin Diagrams (Continued)**

**44-Pin QFN<sup>(2)</sup>**

■ = Pins are up to 5V tolerant

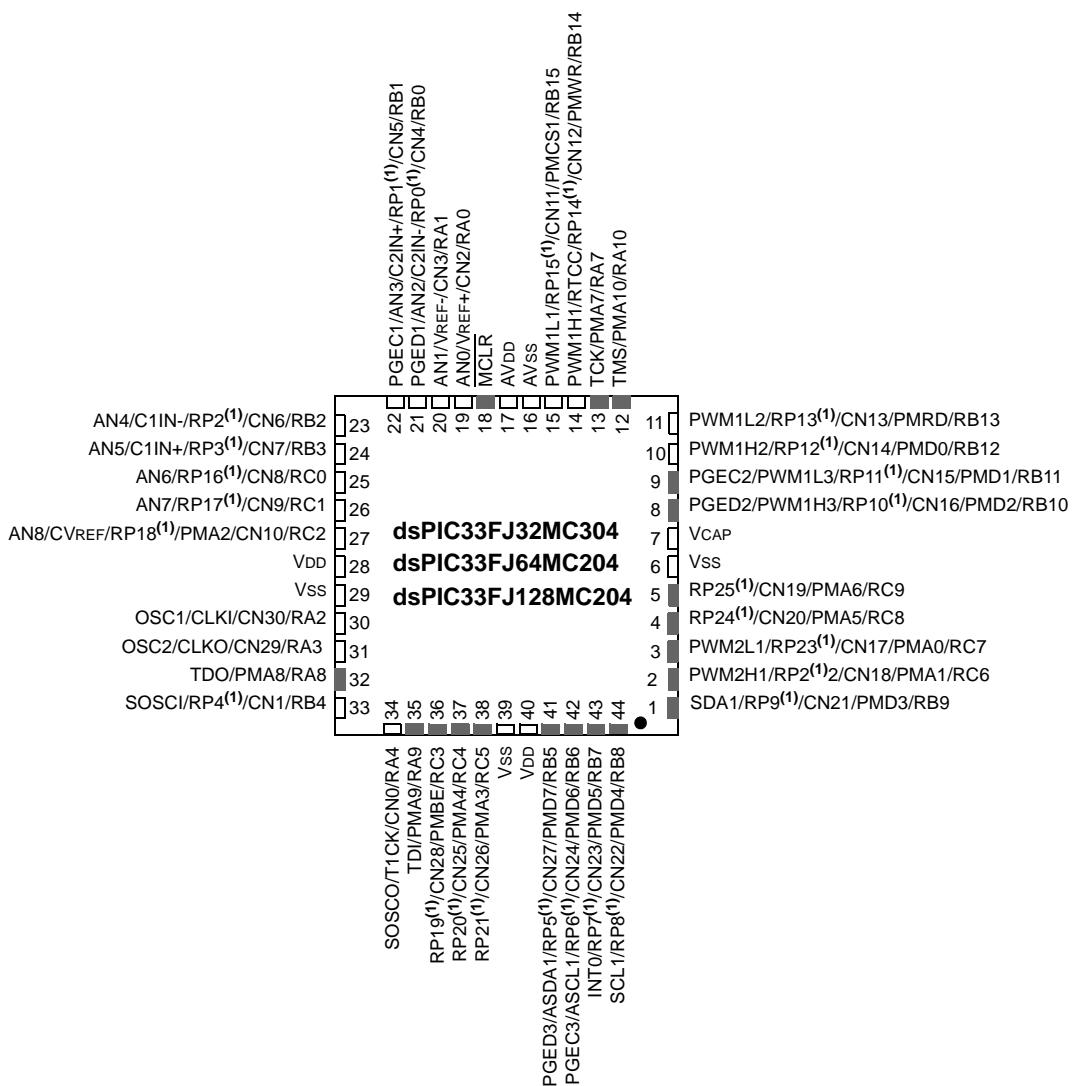


- Note 1:** The RPx pins can be used by any remappable peripheral. See [Table 1](#) in this section for the list of available peripherals.
- 2:** The metal plane at the bottom of the device is not connected to any pins and is recommended to be connected to Vss externally.

## Pin Diagrams (Continued)

### 44-Pin QFN<sup>(2)</sup>

■ = Pins are up to 5V tolerant



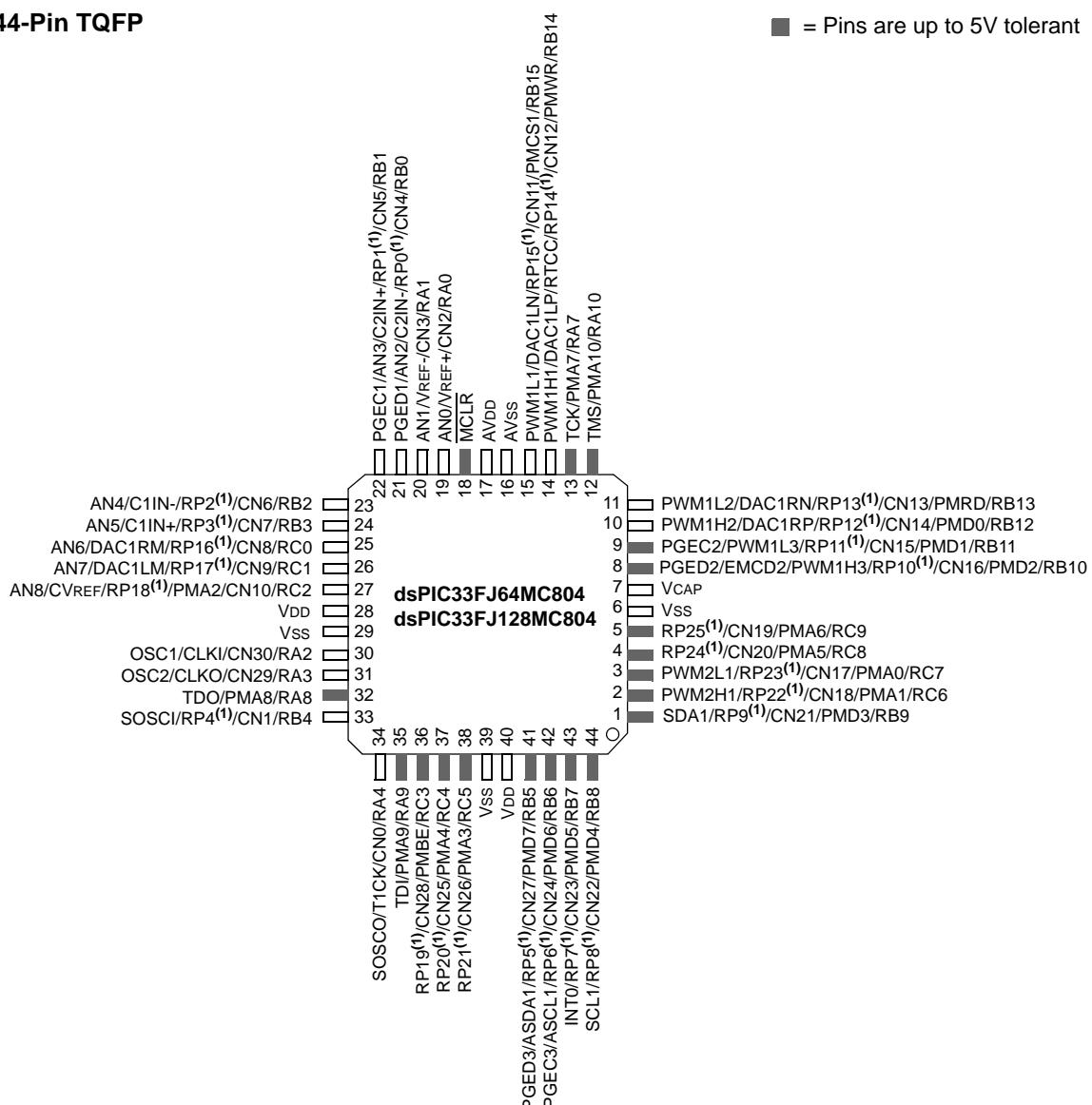
**Note 1:** The RPx pins can be used by any remappable peripheral. See [Table 1](#) in this section for the list of available peripherals.

**2:** The metal plane at the bottom of the device is not connected to any pins and is recommended to be connected to Vss externally.

**Pin Diagrams (Continued)**

**44-Pin TQFP**

■ = Pins are up to 5V tolerant

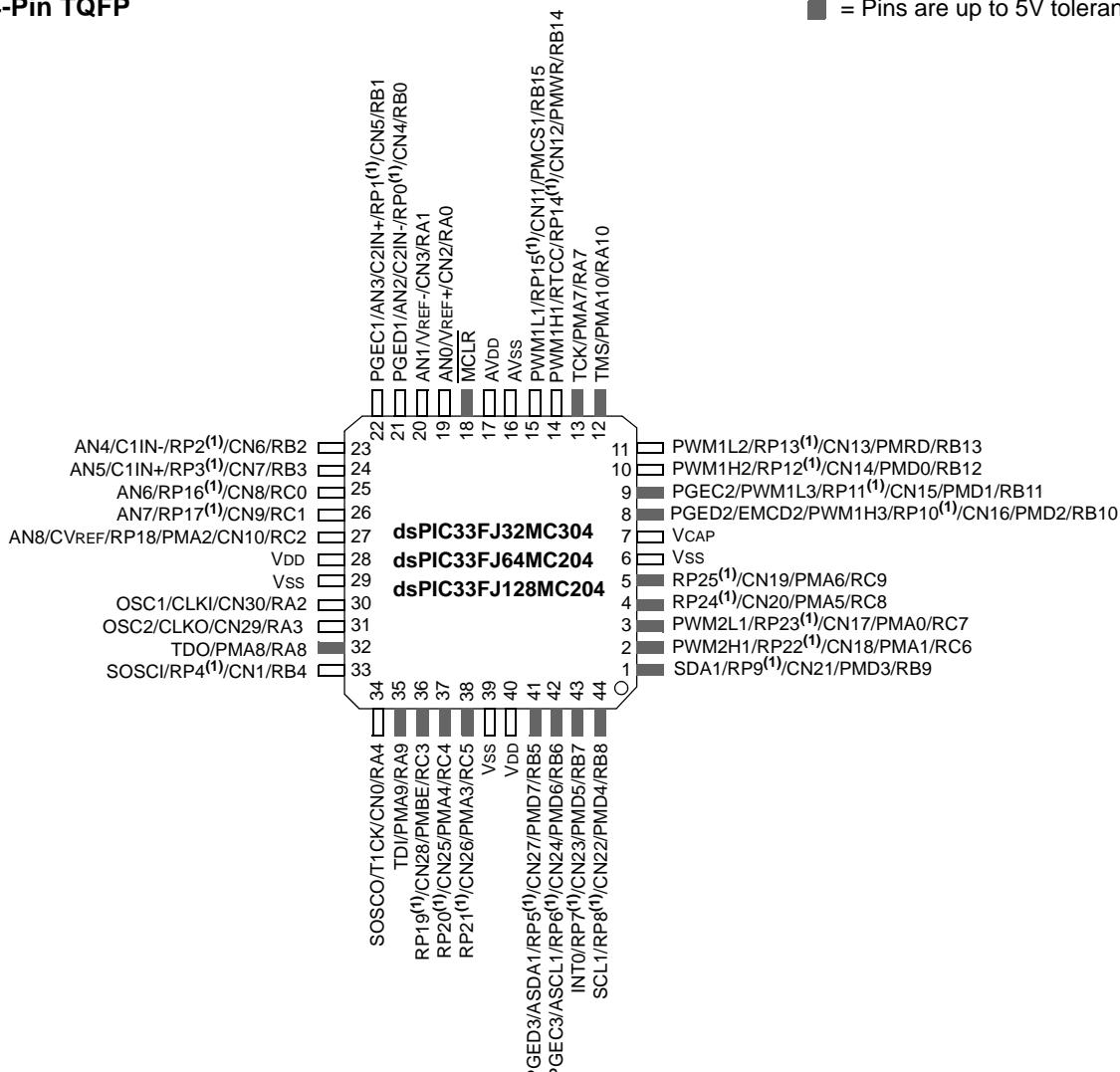


**Note 1:** The RPx pins can be used by any remappable peripheral. See [Table 1](#) in this section for the list of available peripherals.

## Pin Diagrams (Continued)

### 44-Pin TQFP

■ = Pins are up to 5V tolerant



**Note 1:** The RPx pins can be used by any remappable peripheral. See [Table 1](#) in this section for the list of available peripherals.

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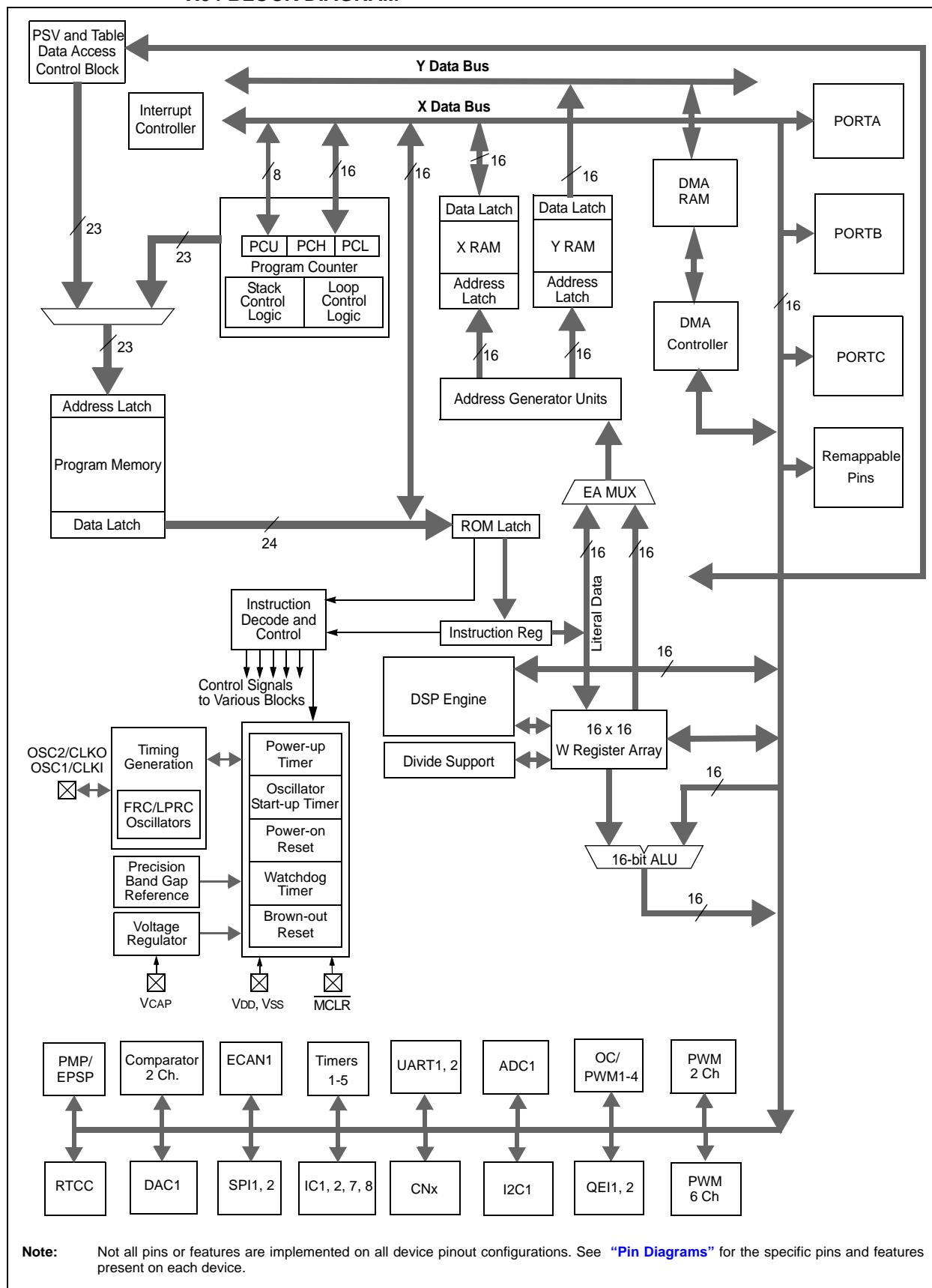
## 1.0 DEVICE OVERVIEW

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. However, it is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the “*dsPIC33F/PIC24H Family Reference Manual*”. Please see the Microchip web site ([www.microchip.com](http://www.microchip.com)) for the latest dsPIC33F/PIC24H Family Reference Manual sections.
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

This document contains device specific information for the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 Digital Signal Controller (DSC) devices. The dsPIC33F devices contain extensive Digital Signal Processor (DSP) functionality with a high performance 16-bit Microcontroller (MCU) architecture.

Figure 1-1 shows a general block diagram of the core and peripheral modules in the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 families of devices. Table 1-1 lists the functions of the various pins shown in the pinout diagrams.

**FIGURE 1-1: dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 AND dsPIC33FJ128MCX02/X04 BLOCK DIAGRAM**



**TABLE 1-1: PINOUT I/O DESCRIPTIONS**

Pin Name	Pin Type	Buffer Type	PPS	Description
AN0-AN8	I	Analog	No	Analog input channels.
CLKI	I	ST/CMOS	No	External clock source input. Always associated with OSC1 pin function. Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. Optionally, functions as CLKO in RC and EC modes.
CLKO	O	—	No	Always associated with OSC2 pin function.
OSC1	I	ST/CMOS	No	Oscillator crystal input. ST buffer when configured in RC mode; CMOS otherwise.
OSC2	I/O	—	No	Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. Optionally functions as CLKO in RC and EC modes.
SOSCI SOSCO	I O	ST/CMOS —	No No	32.768 kHz low-power oscillator crystal input; CMOS otherwise. 32.768 kHz low-power oscillator crystal output.
CN0-CN30	I	ST	No	Change notification inputs. Can be software programmed for internal weak pull-ups on all inputs.
IC1-IC2 IC7-IC8	I I	ST ST	Yes Yes	Capture inputs 1/2. Capture inputs 7/8.
OCFA OC1-OC4	I O	ST —	Yes Yes	Compare Fault A input (for Compare Channels 1, 2, 3 and 4). Compare outputs 1 through 4.
INT0 INT1 INT2	I	ST	No Yes Yes	External interrupt 0. External interrupt 1. External interrupt 2.
RA0-RA4 RA7-RA10	I/O I/O	ST ST	No No	PORTA is a bidirectional I/O port. PORTA is a bidirectional I/O port.
RB0-RB15	I/O	ST	No	PORTB is a bidirectional I/O port.
RC0-RC9	I/O	ST	No	PORTC is a bidirectional I/O port.
T1CK T2CK T3CK T4CK T5CK	I	ST	No Yes Yes Yes Yes	Timer1 external clock input. Timer2 external clock input. Timer3 external clock input. Timer4 external clock input. Timer5 external clock input.
U1CTS U1RTS U1RX U1TX	I O I O	ST — ST —	Yes Yes Yes Yes	UART1 clear to send. UART1 ready to send. UART1 receive. UART1 transmit.
U2CTS U2RTS U2RX U2TX	I O I O	ST — ST —	Yes Yes Yes Yes	UART2 clear to send. UART2 ready to send. UART2 receive. UART2 transmit.
SCK1 SDI1 SDO1 SS1	I/O I O I/O	ST ST — ST	Yes Yes Yes Yes	Synchronous serial clock input/output for SPI1. SPI1 data in. SPI1 data out. SPI1 slave synchronization or frame pulse I/O.
SCK2 SDI2 SDO2 SS2	I/O I O I/O	ST ST — ST	Yes Yes Yes Yes	Synchronous serial clock input/output for SPI2. SPI2 data in. SPI2 data out. SPI2 slave synchronization or frame pulse I/O.
SCL1 SDA1 ASCL1 ASDA1	I/O I/O I/O I/O	ST ST ST ST	No No No No	Synchronous serial clock input/output for I2C1. Synchronous serial data input/output for I2C1. Alternate synchronous serial clock input/output for I2C1. Alternate synchronous serial data input/output for I2C1.

**Legend:** CMOS = CMOS compatible input or output  
 ST = Schmitt Trigger input with CMOS levels  
 PPS = Peripheral Pin Select

Analog = Analog input  
 O = Output  
 TTL = TTL input buffer  
 P = Power  
 I = Input

**TABLE 1-1: PINOUT I/O DESCRIPTIONS (CONTINUED)**

Pin Name	Pin Type	Buffer Type	PPS	Description
TMS	I	ST	No	JTAG Test mode select pin.
TCK	I	ST	No	JTAG test clock input pin.
TDI	I	ST	No	JTAG test data input pin.
TDO	O	—	No	JTAG test data output pin.
INDX1	I	ST	Yes	Quadrature Encoder Index1 Pulse input.
QEA1	I	ST	Yes	Quadrature Encoder Phase A input in QEI1 mode. Auxiliary Timer External Clock/Gate input in Timer mode.
QEB1	I	ST	Yes	Quadrature Encoder Phase B input in QEI1 mode. Auxiliary Timer External Clock/Gate input in Timer mode.
UPDN1	O	CMOS	Yes	Position Up/Down Counter Direction State.
INDX2	I	ST	Yes	Quadrature Encoder Index2 Pulse input.
QEA2	I	ST	Yes	Quadrature Encoder Phase A input in QEI2 mode. Auxiliary Timer External Clock/Gate input in Timer mode.
QEB2	I	ST	Yes	Quadrature Encoder Phase B input in QEI2 mode. Auxiliary Timer External Clock/Gate input in Timer mode.
UPDN2	O	CMOS	Yes	Position Up/Down Counter Direction State.
C1RX	I	ST	Yes	ECAN1 bus receive pin.
C1TX	O	—	Yes	ECAN1 bus transmit pin.
RTCC	O	—	No	Real-Time Clock Alarm Output.
CVREF	O	ANA	No	Comparator Voltage Reference Output.
C1IN-	I	ANA	No	Comparator 1 Negative Input.
C1IN+	I	ANA	No	Comparator 1 Positive Input.
C1OUT	O	—	Yes	Comparator 1 Output.
C2IN-	I	ANA	No	Comparator 2 Negative Input.
C2IN+	I	ANA	No	Comparator 2 Positive Input.
C2OUT	O	—	Yes	Comparator 2 Output.
PMA0	I/O	TTL/ST	No	Parallel Master Port Address Bit 0 Input (Buffered Slave modes) and Output (Master modes).
PMA1	I/O	TTL/ST	No	Parallel Master Port Address Bit 1 Input (Buffered Slave modes) and Output (Master modes).
PMA2 -PMPA10	O	—	No	Parallel Master Port Address (Demultiplexed Master modes).
PMBE	O	—	No	Parallel Master Port Byte Enable Strobe.
PMCS1	O	—	No	Parallel Master Port Chip Select 1 Strobe.
PMD0-PMPD7	I/O	TTL/ST	No	Parallel Master Port Data (Demultiplexed Master mode) or Address/Data (Multiplexed Master modes).
PMRD	O	—	No	Parallel Master Port Read Strobe.
PMWR	O	—	No	Parallel Master Port Write Strobe.
DAC1RN	O	—	No	DAC1 Negative Output.
DAC1RP	O	—	No	DAC1 Positive Output.
DAC1RM	O	—	No	DAC1 Output indicating middle point value (typically 1.65V).
DAC2RN	O	—	No	DAC2 Negative Output.
DAC2RP	O	—	No	DAC2 Positive Output.
DAC2RM	O	—	No	DAC2 Output indicating middle point value (typically 1.65V).

**Legend:** CMOS = CMOS compatible input or output  
 ST = Schmitt Trigger input with CMOS levels  
 PPS = Peripheral Pin Select

Analog = Analog input      P = Power  
 O = Output      I = Input  
 TTL = TTL input buffer

**TABLE 1-1: PINOUT I/O DESCRIPTIONS (CONTINUED)**

Pin Name	Pin Type	Buffer Type	PPS	Description
FLTA1	I	ST	Yes	PWM1 Fault A input.
PWM1L1	O	—	No	PWM1 Low output 1
PWM1H1	O	—	No	PWM1 High output 1
PWM1L2	O	—	No	PWM1 Low output 2
PWM1H2	O	—	No	PWM1 High output 2
PWM1L3	O	—	No	PWM1 Low output 3
PWM1H3	O	—	No	PWM1 High output 3
FLTA2	I	ST	Yes	PWM2 Fault A input.
PWM2L1	O	—	No	PWM2 Low output 1
PWM2H1	O	—	No	PWM2 High output 1
PGED1	I/O	ST	No	Data I/O pin for programming/debugging communication channel 1.
PGEC1	I	ST	No	Clock input pin for programming/debugging communication channel 1.
PGED2	I/O	ST	No	Data I/O pin for programming/debugging communication channel 2.
PGEC2	I	ST	No	Clock input pin for programming/debugging communication channel 2.
PGED3	I/O	ST	No	Data I/O pin for programming/debugging communication channel 3.
PGEC3	I	ST	No	Clock input pin for programming/debugging communication channel 3.
MCLR	I/P	ST	No	Master Clear (Reset) input. This pin is an active-low Reset to the device.
AVDD	P	P	No	Positive supply for analog modules. This pin must be connected at all times.
AVSS	P	P	No	Ground reference for analog modules.
VDD	P	—	No	Positive supply for peripheral logic and I/O pins.
VCAP	P	—	No	CPU logic filter capacitor connection.
VSS	P	—	No	Ground reference for logic and I/O pins.
VREF+	I	Analog	No	Analog voltage reference (high) input.
VREF-	I	Analog	No	Analog voltage reference (low) input.

**Legend:** CMOS = CMOS compatible input or output

Analog = Analog input

P = Power

ST = Schmitt Trigger input with CMOS levels

O = Output

I = Input

PPS = Peripheral Pin Select

TTL = TTL input buffer

## 1.1 Referenced Sources

This device data sheet is based on the following individual chapters of the “dsPIC33F/PIC24H Family Reference Manual”. These documents should be considered as the general reference for the operation of a particular module or device feature.

**Note 1:** To access the documents listed below, browse to the documentation section of the dsPIC33FJ64MC804 product page of the Microchip web site ([www.microchip.com](http://www.microchip.com)) or select a family reference manual section from the following list.

In addition to parameters, features, and other documentation, the resulting page provides links to the related family reference manual sections.

- [Section 1. “Introduction” \(DS70197\)](#)
- [Section 2. “CPU” \(DS70204\)](#)
- [Section 3. “Data Memory” \(DS70202\)](#)
- [Section 4. “Program Memory” \(DS70202\)](#)
- [Section 5. “Flash Programming” \(DS70191\)](#)
- [Section 8. “Reset” \(DS70192\)](#)
- [Section 9. “Watchdog Timer and Power-saving Modes” \(DS70196\)](#)
- [Section 11. “Timers” \(DS70205\)](#)
- [Section 12. “Input Capture” \(DS70198\)](#)
- [Section 13. “Output Compare” \(DS70209\)](#)
- [Section 14. “Motor Control PWM” \(DS70187\)](#)
- [Section 15. “Quadrature Encoder Interface \(QEI\)” \(DS70208\)](#)
- [Section 16. “Analog-to-Digital Converter \(ADC\)” \(DS70183\)](#)
- [Section 17. “UART” \(DS70188\)](#)
- [Section 18. “Serial Peripheral Interface \(SPI\)” \(DS70206\)](#)
- [Section 19. “Inter-Integrated Circuit™ \(I<sup>2</sup>C™\)” \(DS70195\)](#)
- [Section 20. “Data Converter Interface \(DCI\)” \(DS70288\)](#)
- [Section 23. “CodeGuard™ Security \(DS70199\)](#)
- [Section 24. “Programming and Diagnostics” \(DS70207\)](#)
- [Section 25. “Device Configuration \(DS70194\)](#)
- [Section 26. “Development Tool Support” \(DS70200\)](#)
- [Section 30. “I/O Ports with Peripheral Pin Select \(PPS\)” \(DS70190\)](#)
- [Section 32. “Interrupts \(Part III\)” \(DS70214\)](#)
- [Section 33. “Audio Digital-to-Analog Converter \(DAC\)” \(DS70211\)](#)
- [Section 34. “Comparator” \(DS70212\)](#)
- [Section 35. “Parallel Master Port \(PMP\)” \(DS70299\)](#)
- [Section 36. “Programmable Cyclic Redundancy Check \(CRC\)” \(DS70298\)](#)
- [Section 37. “Real-Time Clock and Calendar \(RTCC\)” \(DS70301\)](#)
- [Section 38. “Direct Memory Access” \(DS70215\)](#)
- [Section 39. “Oscillator \(Part III\)” \(DS70216\)](#)

## 2.0 GUIDELINES FOR GETTING STARTED WITH 16-BIT DIGITAL SIGNAL CONTROLLERS

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the “*dsPIC33F/PIC24H Family Reference Manual*”. Please see the Microchip web site ([www.microchip.com](http://www.microchip.com)) for the latest dsPIC33F/PIC24H Family Reference Manual sections.
- 2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

### 2.1 Basic Connection Requirements

Getting started with the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of 16-bit Digital Signal Controllers (DSC) requires attention to a minimal set of device pin connections before proceeding with development. The following is a list of pin names, which must always be connected:

- All VDD and Vss pins  
(see **Section 2.2 “Decoupling Capacitors”**)
- All AVDD and AVss pins (regardless if ADC module is not used)  
(see **Section 2.2 “Decoupling Capacitors”**)
- VCAP  
(see **Section 2.3 “CPU Logic Filter Capacitor Connection (VCAP)”**)
- MCLR pin  
(see **Section 2.4 “Master Clear (MCLR) Pin”**)
- PGECx/PGEDx pins used for In-Circuit Serial Programming™ (ICSP™) and debugging purposes  
(see **Section 2.5 “ICSP Pins”**)
- OSC1 and OSC2 pins when external oscillator source is used  
(see **Section 2.6 “External Oscillator Pins”**)

Additionally, the following pins may be required:

- VREF+/VREF- pins used when external voltage reference for ADC module is implemented

**Note:** The AVDD and AVss pins must be connected independent of the ADC voltage reference source.

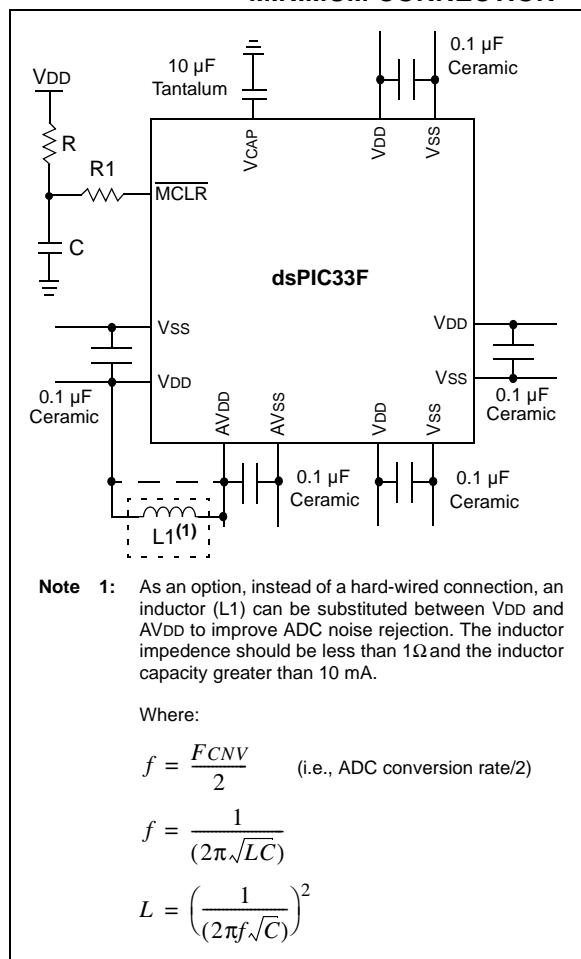
### 2.2 Decoupling Capacitors

The use of decoupling capacitors on every pair of power supply pins, such as VDD, Vss, AVDD and AVss is required.

Consider the following criteria when using decoupling capacitors:

- **Value and type of capacitor:** Recommendation of 0.1  $\mu$ F (100 nF), 10-20V. This capacitor should be a low-ESR and have resonance frequency in the range of 20 MHz and higher. It is recommended that ceramic capacitors be used.
- **Placement on the printed circuit board:** The decoupling capacitors should be placed as close to the pins as possible. It is recommended to place the capacitors on the same side of the board as the device. If space is constricted, the capacitor can be placed on another layer on the PCB using a via; however, ensure that the trace length from the pin to the capacitor is within one-quarter inch (6 mm) in length.
- **Handling high frequency noise:** If the board is experiencing high frequency noise, upward of tens of MHz, add a second ceramic-type capacitor in parallel to the above described decoupling capacitor. The value of the second capacitor can be in the range of 0.01  $\mu$ F to 0.001  $\mu$ F. Place this second capacitor next to the primary decoupling capacitor. In high-speed circuit designs, consider implementing a decade pair of capacitances as close to the power and ground pins as possible. For example, 0.1  $\mu$ F in parallel with 0.001  $\mu$ F.
- **Maximizing performance:** On the board layout from the power supply circuit, run the power and return traces to the decoupling capacitors first, and then to the device pins. This ensures that the decoupling capacitors are first in the power chain. Equally important is to keep the trace length between the capacitor and the power pins to a minimum thereby reducing PCB track inductance.

**FIGURE 2-1: RECOMMENDED MINIMUM CONNECTION**



### 2.2.1 TANK CAPACITORS

On boards with power traces running longer than six inches in length, it is suggested to use a tank capacitor for integrated circuits including DSCs to supply a local power source. The value of the tank capacitor should be determined based on the trace resistance that connects the power supply source to the device, and the maximum current drawn by the device in the application. In other words, select the tank capacitor so that it meets the acceptable voltage sag at the device. Typical values range from 4.7 μF to 47 μF.

### 2.3 CPU Logic Filter Capacitor Connection (VCAP)

A low-ESR (< 5 Ohms) capacitor is required on the VCAP pin, which is used to stabilize the voltage regulator output voltage. The VCAP pin must not be connected to VDD, and must have a capacitor between 4.7 μF and 10 μF, 16V connected to ground. The type can be ceramic or tantalum. Refer to [Section 31.0 “Electrical Characteristics”](#) for additional information.

The placement of this capacitor should be close to the VCAP. It is recommended that the trace length not exceed one-quarter inch (6 mm). Refer to [Section 28.2 “On-Chip Voltage Regulator”](#) for details.

### 2.4 Master Clear (MCLR) Pin

The MCLR pin provides for two specific device functions:

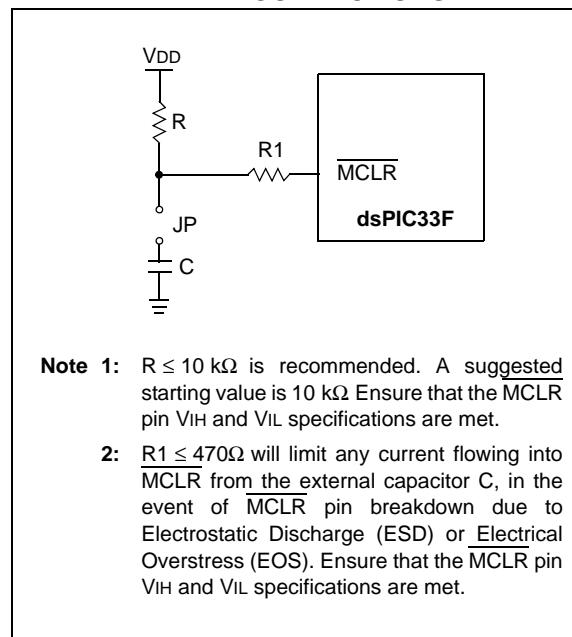
- Device Reset
- Device programming and debugging

During device programming and debugging, the resistance and capacitance that can be added to the pin must be considered. Device programmers and debuggers drive the MCLR pin. Consequently, specific voltage levels (VIH and Vil) and fast signal transitions must not be adversely affected. Therefore, specific values of R and C will need to be adjusted based on the application and PCB requirements.

For example, as shown in [Figure 2-2](#), it is recommended that the capacitor C be isolated from the MCLR pin during programming and debugging operations.

Place the components shown in [Figure 2-2](#) within one-quarter inch (6 mm) from the MCLR pin.

**FIGURE 2-2: EXAMPLE OF MCLR PIN CONNECTIONS**



## 2.5 ICSP Pins

The PGEC<sub>x</sub> and PGED<sub>x</sub> pins are used for In-Circuit Serial Programming™ (ICSP™) and debugging purposes. It is recommended to keep the trace length between the ICSP connector and the ICSP pins on the device as short as possible. If the ICSP connector is expected to experience an ESD event, a series resistor is recommended with a value in the range of a few tens of Ohms, not to exceed 100 Ohms.

Pull-up resistors, series diodes, and capacitors on the PGEC<sub>x</sub> and PGED<sub>x</sub> pins are not recommended as they will interfere with the programmer/debugger communications to the device. If such discrete components are an application requirement, they should be removed from the circuit during programming and debugging. Alternatively, refer to the AC/DC characteristics and timing requirements information in the respective device Flash programming specification for information on capacitive loading limits and pin input voltage high (V<sub>IH</sub>) and input low (V<sub>IL</sub>) requirements.

Ensure that the “Communication Channel Select” (i.e., PGEC<sub>x</sub>/PGED<sub>x</sub> pins) programmed into the device matches the physical connections for the ICSP to MPLAB® ICD 2, MPLAB® ICD 3 or MPLAB® REAL ICE™.

For more information on ICD 2, ICD 3 and REAL ICE connection requirements, refer to the following documents that are available on the Microchip web site.

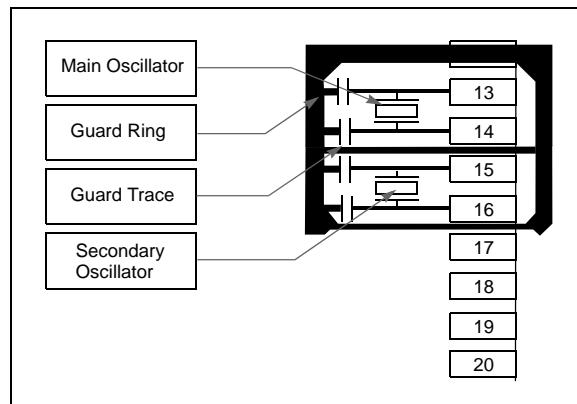
- “MPLAB® ICD 2 In-Circuit Debugger User’s Guide” (DS51331)
- “Using MPLAB® ICD 2” (poster) (DS51265)
- “MPLAB® ICD 2 Design Advisory” (DS51566)
- “Using MPLAB® ICD 3” (poster) (DS51765)
- “MPLAB® ICD 3 Design Advisory” (DS51764)
- “MPLAB® REAL ICE™ In-Circuit Emulator User’s Guide” (DS51616)
- “Using MPLAB® REAL ICE™” (poster) (DS51749)

## 2.6 External Oscillator Pins

Many DSCs have options for at least two oscillators: a high-frequency primary oscillator and a low-frequency secondary oscillator (refer to [Section 9.0 “Oscillator Configuration”](#) for details).

The oscillator circuit should be placed on the same side of the board as the device. Also, place the oscillator circuit close to the respective oscillator pins, not exceeding one-half inch (12 mm) distance between them. The load capacitors should be placed next to the oscillator itself, on the same side of the board. Use a grounded copper pour around the oscillator circuit to isolate them from surrounding circuits. The grounded copper pour should be routed directly to the MCU ground. Do not run any signal traces or power traces inside the ground pour. Also, if using a two-sided board, avoid any traces on the other side of the board where the crystal is placed. A suggested layout is shown in [Figure 2-3](#).

**FIGURE 2-3: SUGGESTED PLACEMENT OF THE OSCILLATOR CIRCUIT**



## **2.7 Oscillator Value Conditions on Device Start-up**

If the PLL of the target device is enabled and configured for the device start-up oscillator, the maximum oscillator source frequency must be limited to less than or equal to 8 MHz for start-up with PLL enabled to comply with device PLL start-up conditions. This means that if the external oscillator frequency is outside this range, the application must start-up in the FRC mode first. The default PLL settings after a POR with an oscillator frequency outside this range will violate the device operating speed.

Once the device powers up, the application firmware can initialize the PLL SFRs, CLKDIV and PLLDBF to a suitable value, and then perform a clock switch to the Oscillator + PLL clock source. Note that clock switching must be enabled in the device Configuration word.

## **2.8 Configuration of Analog and Digital Pins During ICSP Operations**

If MPLAB ICD 2, ICD 3 or REAL ICE is selected as a debugger, it automatically initializes all of the A/D input pins (ANx) as "digital" pins, by setting all bits in the AD1PCFGL register.

The bits in this register that correspond to the A/D pins that are initialized by MPLAB ICD 2, ICD 3 or REAL ICE, must not be cleared by the user application firmware; otherwise, communication errors will result between the debugger and the device.

If your application needs to use certain A/D pins as analog input pins during the debug session, the user application must clear the corresponding bits in the AD1PCFGL register during initialization of the ADC module.

When MPLAB ICD 2, ICD 3 or REAL ICE is used as a programmer, the user application firmware must correctly configure the AD1PCFGL register. Automatic initialization of this register is only done during debugger operation. Failure to correctly configure the register(s) will result in all A/D pins being recognized as analog input pins, resulting in the port value being read as a logic '0', which may affect user application functionality.

## **2.9 Unused I/Os**

Unused I/O pins should be configured as outputs and driven to a logic-low state.

Alternatively, connect a 1k to 10k resistor between Vss and the unused pin.

## 3.0 CPU

- Note 1:** This data sheet summarizes the features of dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 2. CPU**” (DS70204) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

### 3.1 Overview

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 CPU module has a 16-bit (data) modified Harvard architecture with an enhanced instruction set, including significant support for DSP. The CPU has a 24-bit instruction word with a variable length opcode field. The Program Counter (PC) is 23 bits wide and addresses up to 4M x 24 bits of user program memory space. The actual amount of program memory implemented varies by device. A single-cycle instruction prefetch mechanism is used to help maintain throughput and provides predictable execution. All instructions execute in a single cycle, with the exception of instructions that change the program flow, the double-word move (MOV.D) instruction and the table instructions. Overhead-free program loop constructs are supported using the DO and REPEAT instructions, both of which are interruptible at any time.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices have sixteen, 16-bit working registers in the programmer’s model. Each of the working registers can serve as a data, address or address offset register. The 16th working register (W15) operates as a software Stack Pointer (SP) for interrupts and calls.

There are two classes of instruction in the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices: MCU and DSP. These two instruction classes are seamlessly integrated into a single CPU. The instruction set includes many addressing modes and is designed for optimum C compiler efficiency. For most instructions, the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 is capable of executing a data (or program data) memory read, a working register (data) read, a data memory write and a program (instruction) memory read per instruction cycle. As a result, three parameter instructions can be supported, allowing  $A + B = C$  operations to be executed in a single cycle.

A block diagram of the CPU is shown in [Figure 3-1](#), and the programmer’s model for the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 is shown in [Figure 3-2](#).

### 3.2 Data Addressing Overview

The data space can be addressed as 32K words or 64 Kbytes and is split into two blocks, referred to as X and Y data memory. Each memory block has its own independent Address Generation Unit (AGU). The MCU class of instructions operates solely through the X memory AGU, which accesses the entire memory map as one linear data space. Certain DSP instructions operate through the X and Y AGUs to support dual operand reads, which splits the data address space into two parts. The X and Y data space boundary is device-specific.

Overhead-free circular buffers (Modulo Addressing mode) are supported in both X and Y address spaces. The Modulo Addressing removes the software boundary checking overhead for DSP algorithms. Furthermore, the X AGU circular addressing can be used with any of the MCU class of instructions. The X AGU also supports Bit-Reversed Addressing to greatly simplify input or output data reordering for radix-2 FFT algorithms.

The upper 32 Kbytes of the data space memory map can optionally be mapped into program space at any 16K program word boundary defined by the 8-bit Program Space Visibility Page (PSVPAG) register. The program-to-data-space mapping feature lets any instruction access program space as if it were data space.

### **3.3 DSP Engine Overview**

The DSP engine features a high-speed 17-bit by 17-bit multiplier, a 40-bit ALU, two 40-bit saturating accumulators and a 40-bit bidirectional barrel shifter. The barrel shifter is capable of shifting a 40-bit value up to 16 bits right or left, in a single cycle. The DSP instructions operate seamlessly with all other instructions and have been designed for optimal real-time performance. The MAC instruction and other associated instructions can concurrently fetch two data operands from memory while multiplying two W registers and accumulating and optionally saturating the result in the same cycle. This instruction functionality requires that the RAM data space be split for these instructions and linear for all others. Data space partitioning is achieved in a transparent and flexible manner by dedicating certain working registers to each address space.

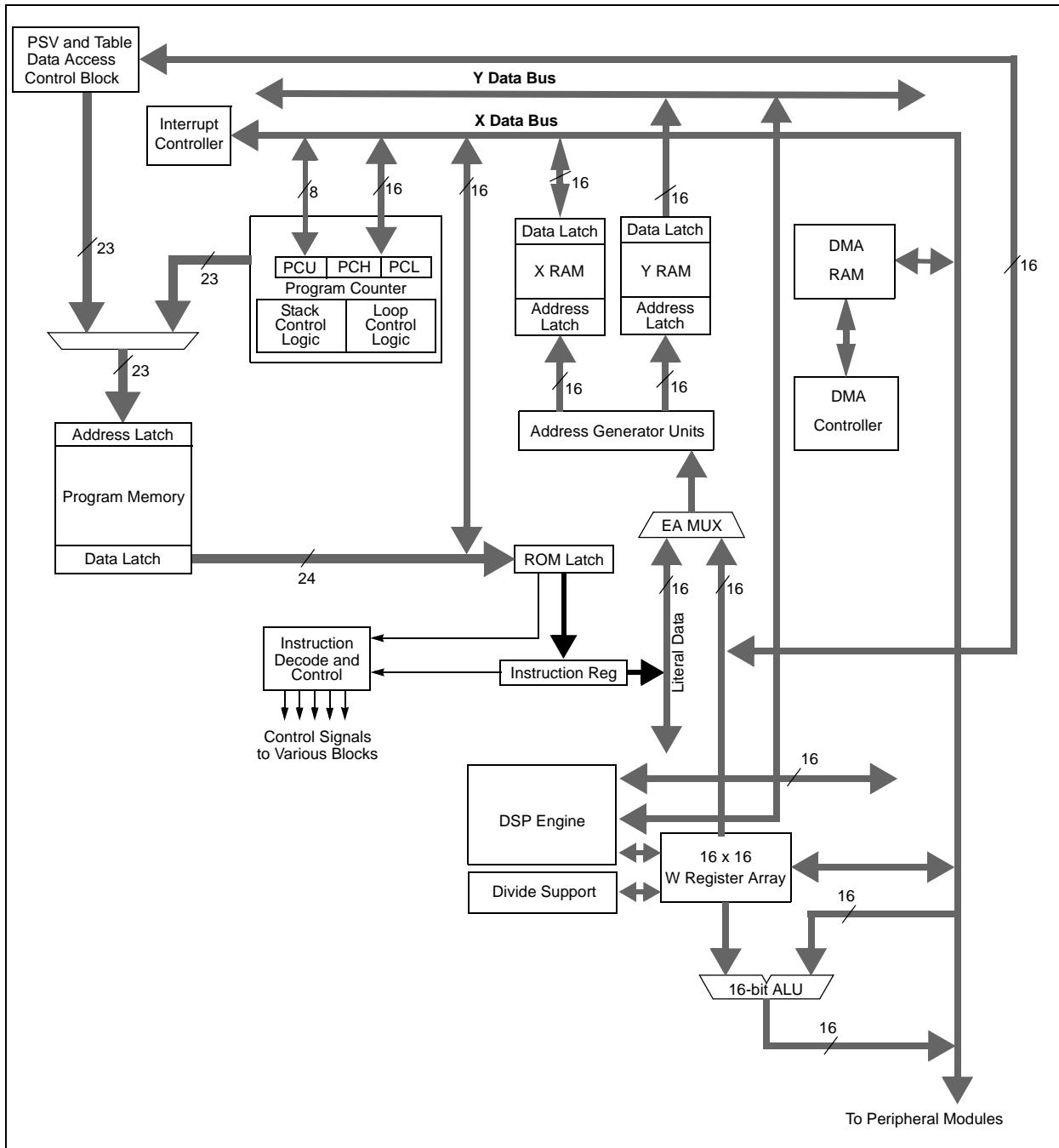
### **3.4 Special MCU Features**

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 features a 17-bit by 17-bit single-cycle multiplier that is shared by both the MCU ALU and DSP engine. The multiplier can perform signed, unsigned and mixed-sign multiplication. Using a 17-bit by 17-bit multiplier for 16-bit by 16-bit multiplication not only allows you to perform mixed-sign multiplication, it also achieves accurate results for special operations, such as (-1.0) x (-1.0).

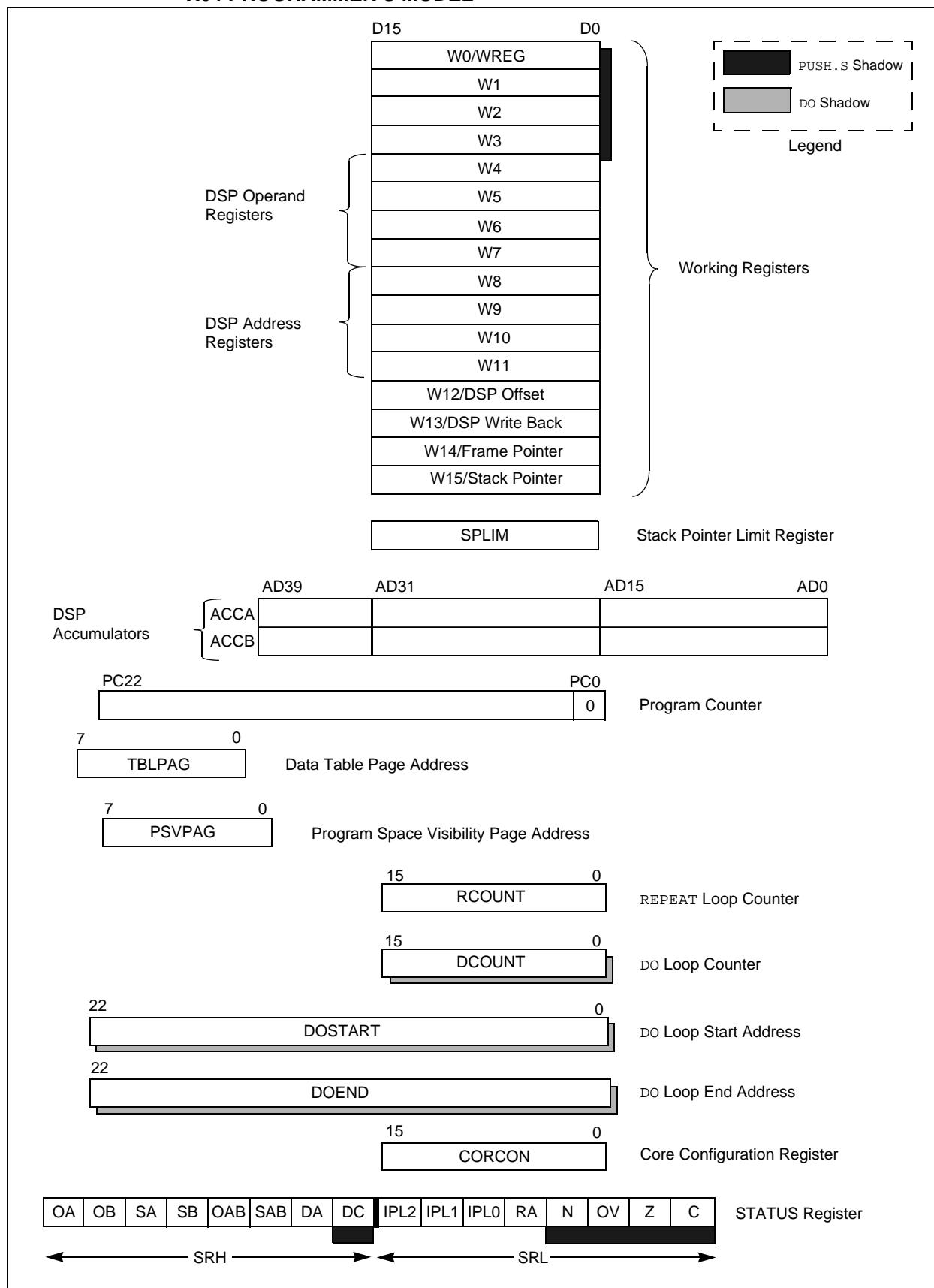
The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 supports 16/16 and 32/16 divide operations, both fractional and integer. All divide instructions are iterative operations. They must be executed within a REPEAT loop, resulting in a total execution time of 19 instruction cycles. The divide operation can be interrupted during any of those 19 cycles without loss of data.

A 40-bit barrel shifter is used to perform up to a 16-bit left or right shift in a single cycle. The barrel shifter can be used by both MCU and DSP instructions.

**FIGURE 3-1: dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 AND dsPIC33FJ128MCX02/X04 CPU CORE BLOCK DIAGRAM**



**FIGURE 3-2: dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 AND dsPIC33FJ128MCX02/X04 PROGRAMMER'S MODEL**



### 3.5 CPU Control Registers

REGISTER 3-1: SR: CPU STATUS REGISTER

R-0	R-0	R/C-0	R/C-0	R-0	R/C-0	R-0	R/W-0
OA	OB	SA <sup>(1)</sup>	SB <sup>(1)</sup>	OAB	SAB	DA	DC
bit 15							bit 8

R/W-0 <sup>(3)</sup>	R/W-0 <sup>(3)</sup>	R/W-0 <sup>(3)</sup>	R-0	R/W-0	R/W-0	R/W-0	R/W-0
IPL<2:0> <sup>(2)</sup>			RA	N	OV	Z	C
bit 7							bit 0

**Legend:**

C = Clear only bit

R = Readable bit

U = Unimplemented bit, read as '0'

S = Set only bit

W = Writable bit

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15	<b>OA:</b> Accumulator A Overflow Status bit 1 = Accumulator A overflowed 0 = Accumulator A has not overflowed
bit 14	<b>OB:</b> Accumulator B Overflow Status bit 1 = Accumulator B overflowed 0 = Accumulator B has not overflowed
bit 13	<b>SA:</b> Accumulator A Saturation 'Sticky' Status bit <sup>(1)</sup> 1 = Accumulator A is saturated or has been saturated at some time 0 = Accumulator A is not saturated
bit 12	<b>SB:</b> Accumulator B Saturation 'Sticky' Status bit <sup>(1)</sup> 1 = Accumulator B is saturated or has been saturated at some time 0 = Accumulator B is not saturated
bit 11	<b>OAB:</b> OA    OB Combined Accumulator Overflow Status bit 1 = Accumulators A or B have overflowed 0 = Neither Accumulators A or B have overflowed
bit 10	<b>SAB:</b> SA    SB Combined Accumulator (Sticky) Status bit <sup>(4)</sup> 1 = Accumulators A or B are saturated or have been saturated at some time in the past 0 = Neither Accumulators A or B are saturated
bit 9	<b>DA:</b> DO Loop Active bit 1 = DO loop in progress 0 = DO loop not in progress
bit 8	<b>DC:</b> MCU ALU Half Carry/Borrow bit 1 = A carry-out from the 4th low-order bit (for byte-sized data) or 8th low-order bit (for word-sized data) of the result occurred 0 = No carry-out from the 4th low-order bit (for byte-sized data) or 8th low-order bit (for word-sized data) of the result occurred

**Note 1:** This bit can be read or cleared (not set).**2:** The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.**3:** The IPL<2:0> Status bits are read only when the NSTDIS bit (INTCON1<15>) = 1.**4:** This bit can be read or cleared (not set). Clearing this bit clears SA and SB.

**REGISTER 3-1: SR: CPU STATUS REGISTER (CONTINUED)**

bit 7-5	<b>IPL&lt;2:0&gt;</b> : CPU Interrupt Priority Level Status bits <sup>(2)</sup>
	111 = CPU Interrupt Priority Level is 7 (15), user interrupts disabled
	110 = CPU Interrupt Priority Level is 6 (14)
	101 = CPU Interrupt Priority Level is 5 (13)
	100 = CPU Interrupt Priority Level is 4 (12)
	011 = CPU Interrupt Priority Level is 3 (11)
	010 = CPU Interrupt Priority Level is 2 (10)
	001 = CPU Interrupt Priority Level is 1 (9)
	000 = CPU Interrupt Priority Level is 0 (8)
bit 4	<b>RA</b> : REPEAT Loop Active bit
	1 = REPEAT loop in progress
	0 = REPEAT loop not in progress
bit 3	<b>N</b> : MCU ALU Negative bit
	1 = Result was negative
	0 = Result was non-negative (zero or positive)
bit 2	<b>OV</b> : MCU ALU Overflow bit
	This bit is used for signed arithmetic (two's complement). It indicates an overflow of a magnitude that causes the sign bit to change state.
	1 = Overflow occurred for signed arithmetic (in this arithmetic operation)
	0 = No overflow occurred
bit 1	<b>Z</b> : MCU ALU Zero bit
	1 = An operation that affects the Z bit has set it at some time in the past
	0 = The most recent operation that affects the Z bit has cleared it (i.e., a non-zero result)
bit 0	<b>C</b> : MCU ALU Carry/Borrow bit
	1 = A carry-out from the Most Significant bit of the result occurred
	0 = No carry-out from the Most Significant bit of the result occurred

**Note 1:** This bit can be read or cleared (not set).

- 2:** The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.
- 3:** The IPL<2:0> Status bits are read only when the NSTDIS bit (INTCON1<15>) = 1.
- 4:** This bit can be read or cleared (not set). Clearing this bit clears SA and SB.

**REGISTER 3-2: CORCON: CORE CONTROL REGISTER**

U-0	U-0	U-0	R/W-0	R/W-0	R-0	R-0	R-0
—	—	—	US	EDT <sup>(1)</sup>	DL<2:0>		
bit 15							bit 8

R/W-0	R/W-0	R/W-1	R/W-0	R/C-0	R/W-0	R/W-0	R/W-0
SATA	SATB	SATDW	ACCSAT	IPL3 <sup>(2)</sup>	PSV	RND	IF
bit 7							bit 0

<b>Legend:</b>	C = Clear only bit
R = Readable bit	W = Writable bit
'0' = Bit is cleared	'x' = Bit is unknown
	-n = Value at POR
	'1' = Bit is set
	U = Unimplemented bit, read as '0'

bit 15-13	<b>Unimplemented:</b> Read as '0'
bit 12	<b>US:</b> DSP Multiply Unsigned/Signed Control bit
	1 = DSP engine multiplies are unsigned
	0 = DSP engine multiplies are signed
bit 11	<b>EDT:</b> Early DO Loop Termination Control bit <sup>(1)</sup>
	1 = Terminate executing DO loop at end of current loop iteration
	0 = No effect
bit 10-8	<b>DL&lt;2:0&gt;:</b> DO Loop Nesting Level Status bits
	111 = 7 DO loops active
	•
	•
	001 = 1 DO loop active
	000 = 0 DO loops active
bit 7	<b>SATA:</b> ACCA Saturation Enable bit
	1 = Accumulator A saturation enabled
	0 = Accumulator A saturation disabled
bit 6	<b>SATB:</b> ACCB Saturation Enable bit
	1 = Accumulator B saturation enabled
	0 = Accumulator B saturation disabled
bit 5	<b>SATDW:</b> Data Space Write from DSP Engine Saturation Enable bit
	1 = Data space write saturation enabled
	0 = Data space write saturation disabled
bit 4	<b>ACCSAT:</b> Accumulator Saturation Mode Select bit
	1 = 9.31 saturation (super saturation)
	0 = 1.31 saturation (normal saturation)
bit 3	<b>IPL3:</b> CPU Interrupt Priority Level Status bit 3 <sup>(2)</sup>
	1 = CPU interrupt priority level is greater than 7
	0 = CPU interrupt priority level is 7 or less
bit 2	<b>PSV:</b> Program Space Visibility in Data Space Enable bit
	1 = Program space visible in data space
	0 = Program space not visible in data space

**Note 1:** This bit is always read as '0'.

**2:** The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU interrupt priority level.

**REGISTER 3-2: CORCON: CORE CONTROL REGISTER (CONTINUED)**

- bit 1           **RND:** Rounding Mode Select bit  
          1 = Biased (conventional) rounding enabled  
          0 = Unbiased (convergent) rounding enabled
- bit 0           **IF:** Integer or Fractional Multiplier Mode Select bit  
          1 = Integer mode enabled for DSP multiply ops  
          0 = Fractional mode enabled for DSP multiply ops

**Note 1:** This bit is always read as '0'.

**2:** The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU interrupt priority level.

### 3.6 Arithmetic Logic Unit (ALU)

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 ALU is 16 bits wide and is capable of addition, subtraction, bit shifts and logic operations. Unless otherwise mentioned, arithmetic operations are two's complement in nature. Depending on the operation, the ALU can affect the values of the Carry (C), Zero (Z), Negative (N), Overflow (OV) and Digit Carry (DC) Status bits in the SR register. The C and DC Status bits operate as Borrow and Digit Borrow bits, respectively, for subtraction operations.

The ALU can perform 8-bit or 16-bit operations, depending on the mode of the instruction that is used. Data for the ALU operation can come from the W register array or data memory, depending on the addressing mode of the instruction. Likewise, output data from the ALU can be written to the W register array or a data memory location.

Refer to the "16-bit MCU and DSC Programmer's Reference Manual" (DS70157) for information on the SR bits affected by each instruction.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 CPU incorporates hardware support for both multiplication and division. This includes a dedicated hardware multiplier and support hardware for 16-bit-divisor division.

#### 3.6.1 MULTIPLIER

Using the high-speed 17-bit x 17-bit multiplier of the DSP engine, the ALU supports unsigned, signed or mixed-sign operation in several MCU multiplication modes:

- 16-bit x 16-bit signed
- 16-bit x 16-bit unsigned
- 16-bit signed x 5-bit (literal) unsigned
- 16-bit unsigned x 16-bit unsigned
- 16-bit unsigned x 5-bit (literal) unsigned
- 16-bit unsigned x 16-bit signed
- 8-bit unsigned x 8-bit unsigned

#### 3.6.2 DIVIDER

The divide block supports 32-bit/16-bit and 16-bit/16-bit signed and unsigned integer divide operations with the following data sizes:

- 32-bit signed/16-bit signed divide
- 32-bit unsigned/16-bit unsigned divide
- 16-bit signed/16-bit signed divide
- 16-bit unsigned/16-bit unsigned divide

The quotient for all divide instructions ends up in W0 and the remainder in W1. 16-bit signed and unsigned DIV instructions can specify any W register for both the 16-bit divisor (Wn) and any W register (aligned) pair (W(m + 1):Wm) for the 32-bit dividend. The divide algorithm takes one cycle per bit of divisor, so both 32-bit/16-bit and 16-bit/16-bit instructions take the same number of cycles to execute.

### 3.7 DSP Engine

The DSP engine consists of a high-speed 17-bit x 17-bit multiplier, a barrel shifter and a 40-bit adder/subtractor (with two target accumulators, round and saturation logic).

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 is a single-cycle instruction flow architecture; therefore, concurrent operation of the DSP engine with MCU instruction flow is not possible. However, some MCU ALU and DSP engine resources can be used concurrently by the same instruction (e.g., ED, EDAC).

The DSP engine can also perform inherent accumulator-to-accumulator operations that require no additional data. These instructions are ADD, SUB and NEG.

The DSP engine has options selected through bits in the CPU Core Control register (CORCON), as listed below:

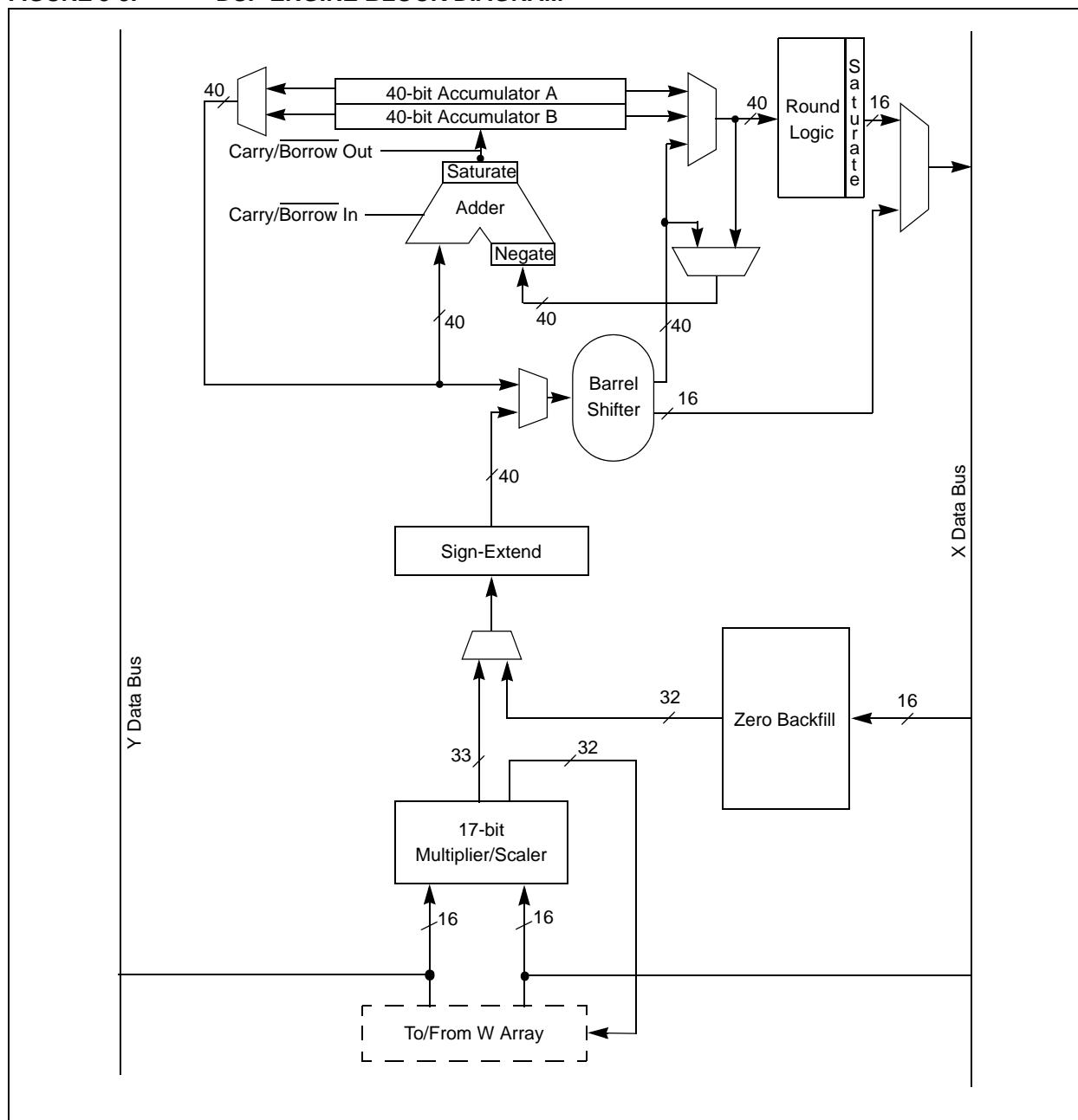
- Fractional or integer DSP multiply (IF)
- Signed or unsigned DSP multiply (US)
- Conventional or convergent rounding (RND)
- Automatic saturation on/off for ACCA (SATA)
- Automatic saturation on/off for ACCB (SATB)
- Automatic saturation on/off for writes to data memory (SATDW)
- Accumulator Saturation mode selection (ACCSAT)

A block diagram of the DSP engine is shown in [Figure 3-3](#).

**TABLE 3-1: DSP INSTRUCTIONS SUMMARY**

Instruction	Algebraic Operation	ACC Write Back
CLR	$A = 0$	Yes
ED	$A = (x - y)^2$	No
EDAC	$A = A + (x - y)^2$	No
MAC	$A = A + (x \cdot y)$	Yes
MAC	$A = A + x^2$	No
MOVSAC	No change in A	Yes
MPY	$A = x \cdot y$	No
MPY	$A = x^2$	No
MPY.N	$A = -x \cdot y$	No
MSC	$A = A - x \cdot y$	Yes

FIGURE 3-3: DSP ENGINE BLOCK DIAGRAM



### 3.7.1 MULTIPLIER

The 17-bit  $\times$  17-bit multiplier is capable of signed or unsigned operation and can multiplex its output using a scaler to support either 1.31 fractional (Q31) or 32-bit integer results. Unsigned operands are zero-extended into the 17th bit of the multiplier input value. Signed operands are sign-extended into the 17th bit of the multiplier input value. The output of the 17-bit  $\times$  17-bit multiplier/scaler is a 33-bit value that is sign-extended to 40 bits. Integer data is inherently represented as a signed two's complement value, where the Most Significant bit (MSb) is defined as a sign bit. The range of an N-bit two's complement integer is  $-2^{N-1}$  to  $2^{N-1} - 1$ .

- For a 16-bit integer, the data range is -32768 (0x8000) to 32767 (0x7FFF) including 0
- For a 32-bit integer, the data range is -2,147,483,648 (0x8000 0000) to 2,147,483,647 (0x7FFF FFFF)

When the multiplier is configured for fractional multiplication, the data is represented as a two's complement fraction, where the MSb is defined as a sign bit and the radix point is implied to lie just after the sign bit (QX format). The range of an N-bit two's complement fraction with this implied radix point is -1.0 to  $(1 - 2^{-N})$ . For a 16-bit fraction, the Q15 data range is -1.0 (0x8000) to 0.999969482 (0x7FFF) including 0 and has a precision of  $3.01518 \times 10^{-5}$ . In Fractional mode, the 16  $\times$  16 multiply operation generates a 1.31 product that has a precision of  $4.65661 \times 10^{-10}$ .

The same multiplier is used to support the MCU multiply instructions, which include integer 16-bit signed, unsigned and mixed sign multiply operations.

The **MUL** instruction can be directed to use byte or word-sized operands. Byte operands direct a 16-bit result, and word operands direct a 32-bit result to the specified registers in the W array.

### 3.7.2 DATA ACCUMULATORS AND ADDER/SUBTRACTER

The data accumulator consists of a 40-bit adder/subtractor with automatic sign extension logic. It can select one of two accumulators (A or B) as its pre-accumulation source and post-accumulation destination. For the ADD and LAC instructions, the data to be accumulated or loaded can be optionally scaled using the barrel shifter prior to accumulation.

#### 3.7.2.1 Adder/Subtractor, Overflow and Saturation

The adder/subtractor is a 40-bit adder with an optional zero input into one side, and either true or complement data into the other input.

- In the case of addition, the Carry/Borrow input is active-high and the other input is true data (not complemented)
- In the case of subtraction, the Carry/Borrow input is active-low and the other input is complemented

The adder/subtractor generates Overflow Status bits, SA/SB and OA/OB, which are latched and reflected in the STATUS register:

- Overflow from bit 39: this is a catastrophic overflow in which the sign of the accumulator is destroyed
- Overflow into guard bits 32 through 39: this is a recoverable overflow. This bit is set whenever all the guard bits are not identical to each other.

The adder has an additional saturation block that controls accumulator data saturation, if selected. It uses the result of the adder, the Overflow Status bits described previously and the SAT<A:B> (CORCON<7:6>) and ACCSAT (CORCON<4>) mode control bits to determine when and to what value to saturate.

Six STATUS register bits support saturation and overflow:

- OA: ACCA overflowed into guard bits
- OB: ACCB overflowed into guard bits
- SA: ACCA saturated (bit 31 overflow and saturation)  
or  
ACCA overflowed into guard bits and saturated (bit 39 overflow and saturation)
- SB: ACCB saturated (bit 31 overflow and saturation)  
or  
ACCB overflowed into guard bits and saturated (bit 39 overflow and saturation)
- OAB: Logical OR of OA and OB
- SAB: Logical OR of SA and SB

The OA and OB bits are modified each time data passes through the adder/subtractor. When set, they indicate that the most recent operation has overflowed into the accumulator guard bits (bits 32 through 39). The OA and OB bits can also optionally generate an arithmetic warning trap when set and the corresponding Overflow Trap Flag Enable bits (OVATE, OVBTE) in the INTCON1 register are set (refer to **Section 7.0 “Interrupt Controller”**). This allows the user application to take immediate action, for example, to correct system gain.

The SA and SB bits are modified each time data passes through the adder/subtractor, but can only be cleared by the user application. When set, they indicate that the accumulator has overflowed its maximum range (bit 31 for 32-bit saturation or bit 39 for 40-bit saturation) and is saturated (if saturation is enabled). When saturation is not enabled, SA and SB default to bit 39 overflow and thus indicate that a catastrophic overflow has occurred. If the COVTE bit in the INTCON1 register is set, the SA and SB bits generate an arithmetic warning trap when saturation is disabled.

The Overflow and Saturation Status bits can optionally be viewed in the STATUS Register (SR) as the logical OR of OA and OB (in bit OAB) and the logical OR of SA and SB (in bit SAB). Programmers can check one bit in the STATUS register to determine if either accumulator has overflowed, or one bit to determine if either accumulator has saturated. This is useful for complex number arithmetic, which typically uses both accumulators.

The device supports three Saturation and Overflow modes:

- Bit 39 Overflow and Saturation:

When bit 39 overflow and saturation occurs, the saturation logic loads the maximally positive 9.31 (0x7FFFFFFF) or maximally negative 9.31 value (0x8000000000) into the target accumulator. The SA or SB bit is set and remains set until cleared by the user application. This condition is referred to as super saturation and provides protection against erroneous data or unexpected algorithm problems (such as gain calculations).

- Bit 31 Overflow and Saturation:

When bit 31 overflow and saturation occurs, the saturation logic then loads the maximally positive 1.31 value (0x007FFFFFFF) or maximally negative 1.31 value (0x0080000000) into the target accumulator. The SA or SB bit is set and remains set until cleared by the user application. When this Saturation mode is in effect, the guard bits are not used, so the OA, OB or OAB bits are never set.

- Bit 39 Catastrophic Overflow:

The bit 39 Overflow Status bit from the adder is used to set the SA or SB bit, which remains set until cleared by the user application. No saturation operation is performed, and the accumulator is allowed to overflow, destroying its sign. If the COVTE bit in the INTCON1 register is set, a catastrophic overflow can initiate a trap exception.

### 3.7.3 ACCUMULATOR WRITE BACK

The MAC class of instructions (with the exception of MPY, MPY.N, ED and EDAC) can optionally write a rounded version of the high word (bits 31 through 16) of the accumulator that is not targeted by the instruction into data space memory. The write is performed across the X bus into combined X and Y address space. The following addressing modes are supported:

- W13, Register Direct:

The rounded contents of the non-target accumulator are written into W13 as a 1.15 fraction.

- [W13] + = 2, Register Indirect with Post-Increment:

The rounded contents of the non-target accumulator are written into the address pointed to by W13 as a 1.15 fraction. W13 is then incremented by 2 (for a word write).

### 3.7.3.1 Round Logic

The round logic is a combinational block that performs a conventional (biased) or convergent (unbiased) round function during an accumulator write (store). The Round mode is determined by the state of the RND bit in the CORCON register. It generates a 16-bit, 1.15 data value that is passed to the data space write saturation logic. If rounding is not indicated by the instruction, a truncated 1.15 data value is stored, and the least significant word is simply discarded.

Conventional rounding zero-extends bit 15 of the accumulator and adds it to the ACCxH word (bits 16 through 31 of the accumulator).

- If the ACCxL word (bits 0 through 15 of the accumulator) is between 0x8000 and 0xFFFF (0x8000 included), ACCxH is incremented.
- If ACCxL is between 0x0000 and 0x7FFF, ACCxH is left unchanged.

A consequence of this algorithm is that over a succession of random rounding operations, the value tends to be biased slightly positive.

Convergent (or unbiased) rounding operates in the same manner as conventional rounding, except when ACCxL equals 0x8000. In this case, the Least Significant bit (bit 16 of the accumulator) of ACCxH is examined:

- If it is '1', ACCxH is incremented.
- If it is '0', ACCxH is not modified.

Assuming that bit 16 is effectively random in nature, this scheme removes any rounding bias that may accumulate.

The SAC and SAC.R instructions store either a truncated (SAC), or rounded (SAC.R) version of the contents of the target accumulator to data memory via the X bus, subject to data saturation (see [Section 3.7.3.2 "Data Space Write Saturation"](#)). For the MAC class of instructions, the accumulator write-back operation functions in the same manner, addressing combined MCU (X and Y) data space through the X bus. For this class of instructions, the data is always subject to rounding.

### 3.7.3.2 Data Space Write Saturation

In addition to adder/subtractor saturation, writes to data space can also be saturated, but without affecting the contents of the source accumulator. The data space write saturation logic block accepts a 16-bit, 1.15 fractional value from the round logic block as its input, together with overflow status from the original source (accumulator) and the 16-bit round adder. These inputs are combined and used to select the appropriate 1.15 fractional value as output to write to data space memory.

If the SATDW bit in the CORCON register is set, data (after rounding or truncation) is tested for overflow and adjusted accordingly:

- For input data greater than 0x007FFF, data written to memory is forced to the maximum positive 1.15 value, 0x7FFF.
- For input data less than 0xFF8000, data written to memory is forced to the maximum negative 1.15 value, 0x8000.

The Most Significant bit of the source (bit 39) is used to determine the sign of the operand being tested.

If the SATDW bit in the CORCON register is not set, the input data is always passed through unmodified under all conditions.

### 3.7.4 BARREL SHIFTER

The barrel shifter can perform up to 16-bit arithmetic or logic right shifts, or up to 16-bit left shifts in a single cycle. The source can be either of the two DSP accumulators or the X bus (to support multi-bit shifts of register or memory data).

The shifter requires a signed binary value to determine both the magnitude (number of bits) and direction of the shift operation. A positive value shifts the operand right. A negative value shifts the operand left. A value of '0' does not modify the operand.

The barrel shifter is 40 bits wide, thereby obtaining a 40-bit result for DSP shift operations and a 16-bit result for MCU shift operations. Data from the X bus is presented to the barrel shifter between bit positions 16 and 31 for right shifts, and between bit positions 0 and 16 for left shifts.

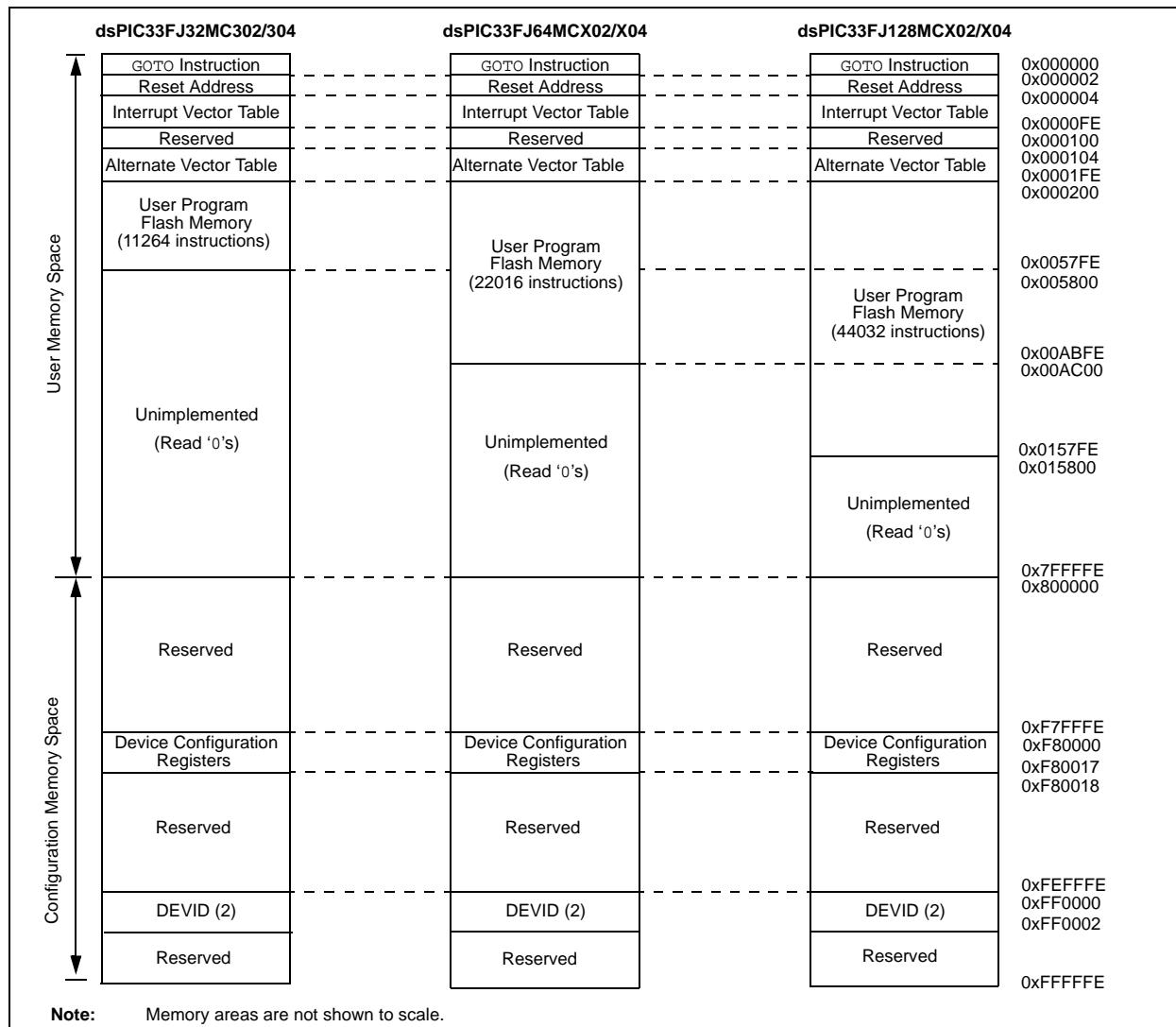
**NOTES:**

## 4.0 MEMORY ORGANIZATION

**Note:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 4. “Program Memory”** (DS70203) of the “*dsPIC33F PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 architecture features separate program and data memory spaces and buses. This architecture also allows the direct access to program memory from the data space during code execution.

**FIGURE 4-1: PROGRAM MEMORY MAP FOR dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 AND dsPIC33FJ128MCX02/X04 DEVICES**



## 4.1 Program Address Space

The program address memory space of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices is 4M instructions. The space is addressable by a 24-bit value derived either from the 23-bit Program Counter (PC) during program execution, or from table operation or data space remapping as described in **Section 4.6 “Interfacing Program and Data Memory Spaces”**.

User application access to the program memory space is restricted to the lower half of the address range (0x000000 to 0x7FFFFFF). The exception is the use of TBLRD/TBLWT operations, which use TBLPAG<7> to permit access to the Configuration bits and Device ID sections of the configuration memory space.

The memory map for the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices is shown in [Figure 4-1](#).

#### 4.1.1 PROGRAM MEMORY ORGANIZATION

The program memory space is organized in word-addressable blocks. Although it is treated as 24 bits wide, it is more appropriate to think of each address of the program memory as a lower and upper word, with the upper byte of the upper word being unimplemented. The lower word always has an even address, while the upper word has an odd address ([Figure 4-2](#)).

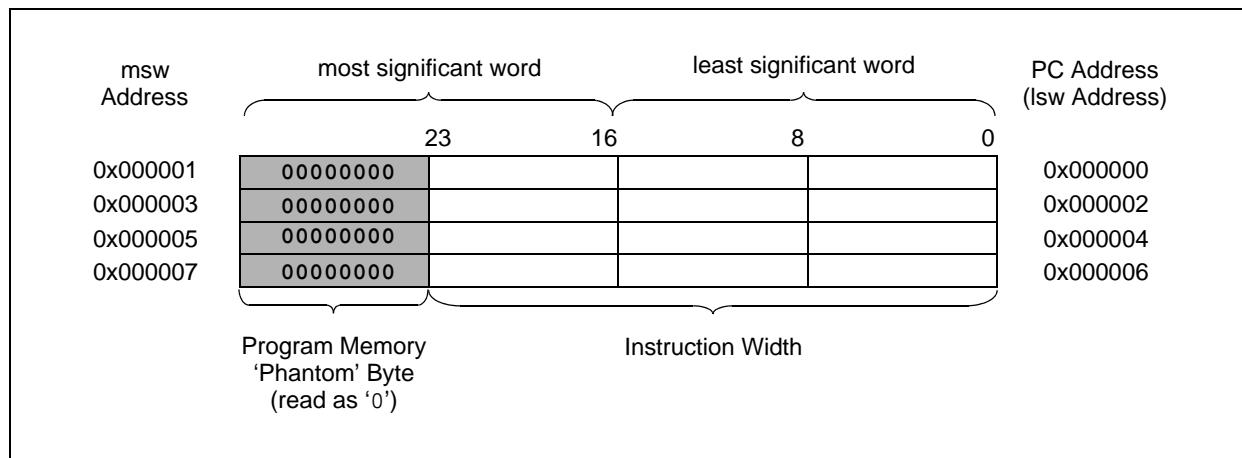
Program memory addresses are always word-aligned on the lower word, and addresses are incremented or decremented by two during code execution. This arrangement provides compatibility with data memory space addressing and makes data in the program memory space accessible.

#### 4.1.2 INTERRUPT AND TRAP VECTORS

All dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices reserve the addresses between 0x000000 and 0x000200 for hard-coded program execution vectors. A hardware Reset vector is provided to redirect code execution from the default value of the PC on device Reset to the actual start of code. A GOTO instruction is programmed by the user application at 0x000000, with the actual address for the start of code at 0x000002.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices also have two interrupt vector tables, located from 0x000004 to 0x0000FF and 0x000100 to 0x0001FF. These vector tables allow each of the device interrupt sources to be handled by separate Interrupt Service Routines (ISRs). A more detailed discussion of the interrupt vector tables is provided in [Section 7.1 “Interrupt Vector Table”](#).

**FIGURE 4-2: PROGRAM MEMORY ORGANIZATION**



## 4.2 Data Address Space

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 CPU has a separate 16 bit wide data memory space. The data space is accessed using separate Address Generation Units (AGUs) for read and write operations. The data memory maps is shown in [Figure 4-4](#).

All Effective Addresses (EAs) in the data memory space are 16 bits wide and point to bytes within the data space. This arrangement gives a data space address range of 64 Kbytes or 32K words. The lower half of the data memory space (that is, when EA<15> = 0) is used for implemented memory addresses, while the upper half (EA<15> = 1) is reserved for the Program Space Visibility area (see [Section 4.6.3 “Reading Data from Program Memory Using Program Space Visibility”](#)).

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices implement up to 16 Kbytes of data memory. Should an EA point to a location outside of this area, an all-zero word or byte is returned.

### 4.2.1 DATA SPACE WIDTH

The data memory space is organized in byte addressable, 16-bit wide blocks. Data is aligned in data memory and registers as 16-bit words, but all data space EAs resolve to bytes. The Least Significant Bytes (LSBs) of each word have even addresses, while the Most Significant Bytes (MSBs) have odd addresses.

### 4.2.2 DATA MEMORY ORGANIZATION AND ALIGNMENT

To maintain backward compatibility with PIC® MCU devices and improve data space memory usage efficiency, the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 instruction set supports both word and byte operations. As a consequence of byte accessibility, all effective address calculations are internally scaled to step through word-aligned memory. For example, the core recognizes that Post-Modified Register Indirect Addressing mode [Ws++ ] results in a value of Ws + 1 for byte operations and Ws + 2 for word operations.

A data byte read, reads the complete word that contains the byte, using the LSB of any EA to determine which byte to select. The selected byte is placed onto the LSB of the data path. That is, data memory and registers are organized as two parallel byte-wide entities with shared (word) address decode but separate write lines. Data byte writes only write to the corresponding side of the array or register that matches the byte address.

All word accesses must be aligned to an even address. Misaligned word data fetches are not supported, so care must be taken when mixing byte and word operations, or translating from 8-bit MCU code. If a misaligned read or write is attempted, an address error trap is generated. If the error occurred on a read, the instruction underway is completed. If the error occurred on a write, the instruction is executed but the write does not occur. In either case, a trap is then executed, allowing the system and/or user application to examine the machine state prior to execution of the address Fault.

All byte loads into any W register are loaded into the Least Significant Byte. The Most Significant Byte is not modified.

A sign-extend instruction (SE) is provided to allow user applications to translate 8-bit signed data to 16-bit signed values. Alternatively, for 16-bit unsigned data, user applications can clear the MSB of any W register by executing a zero-extend (ZE) instruction on the appropriate address.

### 4.2.3 SFR SPACE

The first 2 Kbytes of the Near Data Space, from 0x0000 to 0x07FF, is primarily occupied by Special Function Registers (SFRs). These are used by the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 core and peripheral modules for controlling the operation of the device.

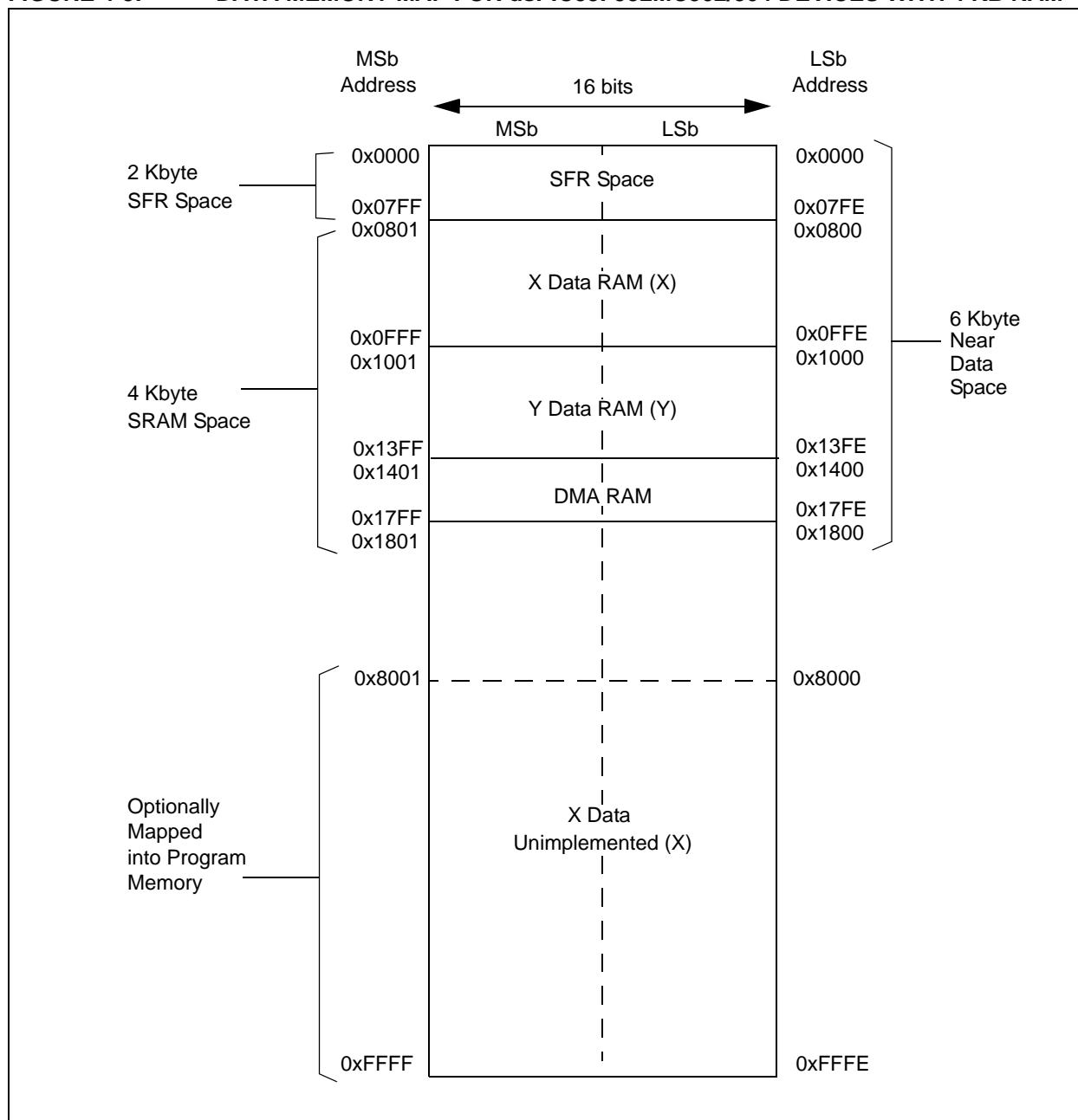
The SFRs are distributed among the modules that they control, and are generally grouped together by module. Much of the SFR space contains unused addresses; these are read as ‘0’.

**Note:** The actual set of peripheral features and interrupts varies by the device. Refer to the corresponding device tables and pinout diagrams for device-specific information.

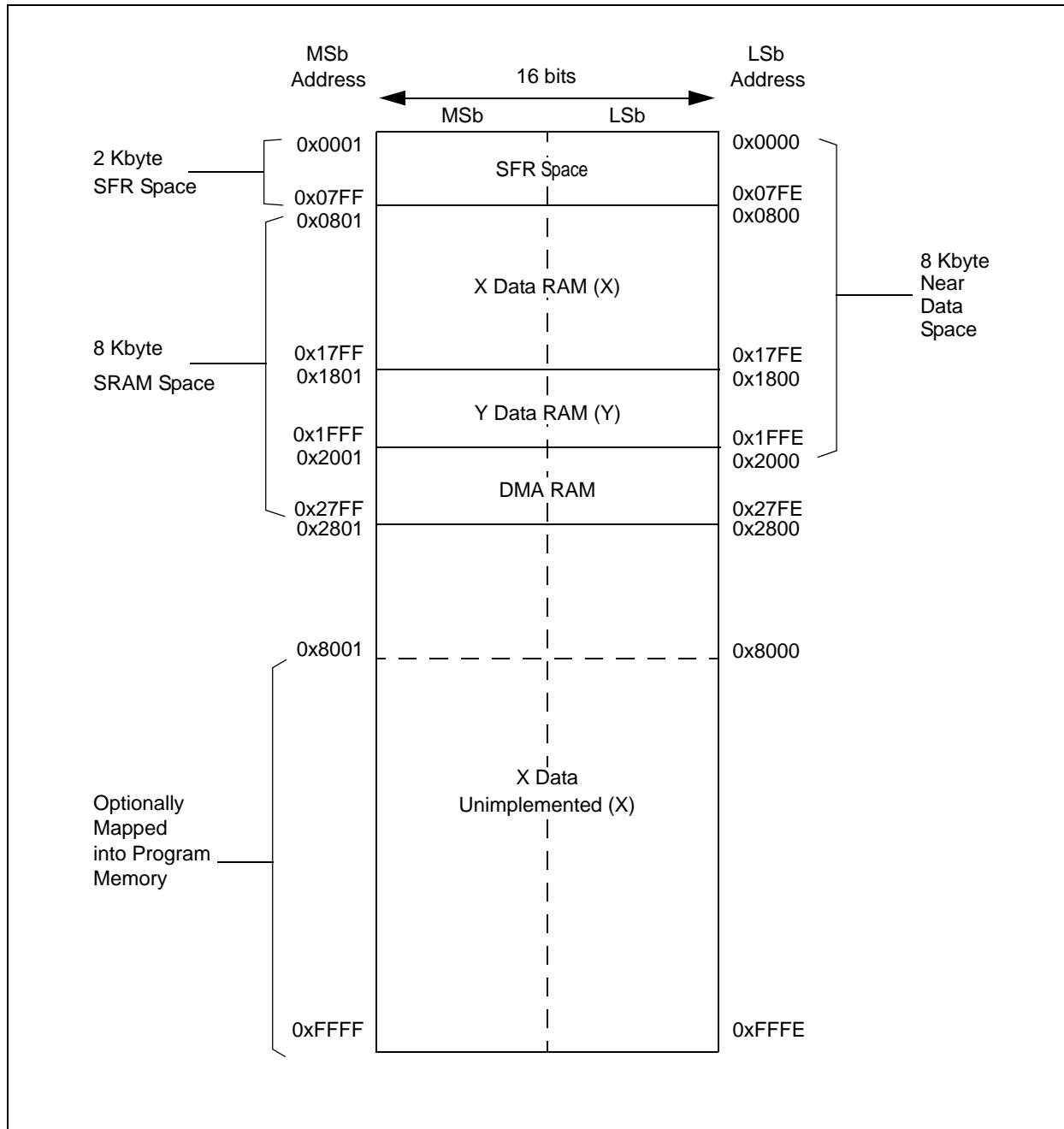
### 4.2.4 NEAR DATA SPACE

The 8 Kbyte area between 0x0000 and 0x1FFF is referred to as the near data space. Locations in this space are directly addressable via a 13-bit absolute address field within all memory direct instructions. Additionally, the whole data space is addressable using the MOV instructions, which support Memory Direct Addressing mode with a 16-bit address field, or by using Indirect Addressing mode using a working register as an address pointer.

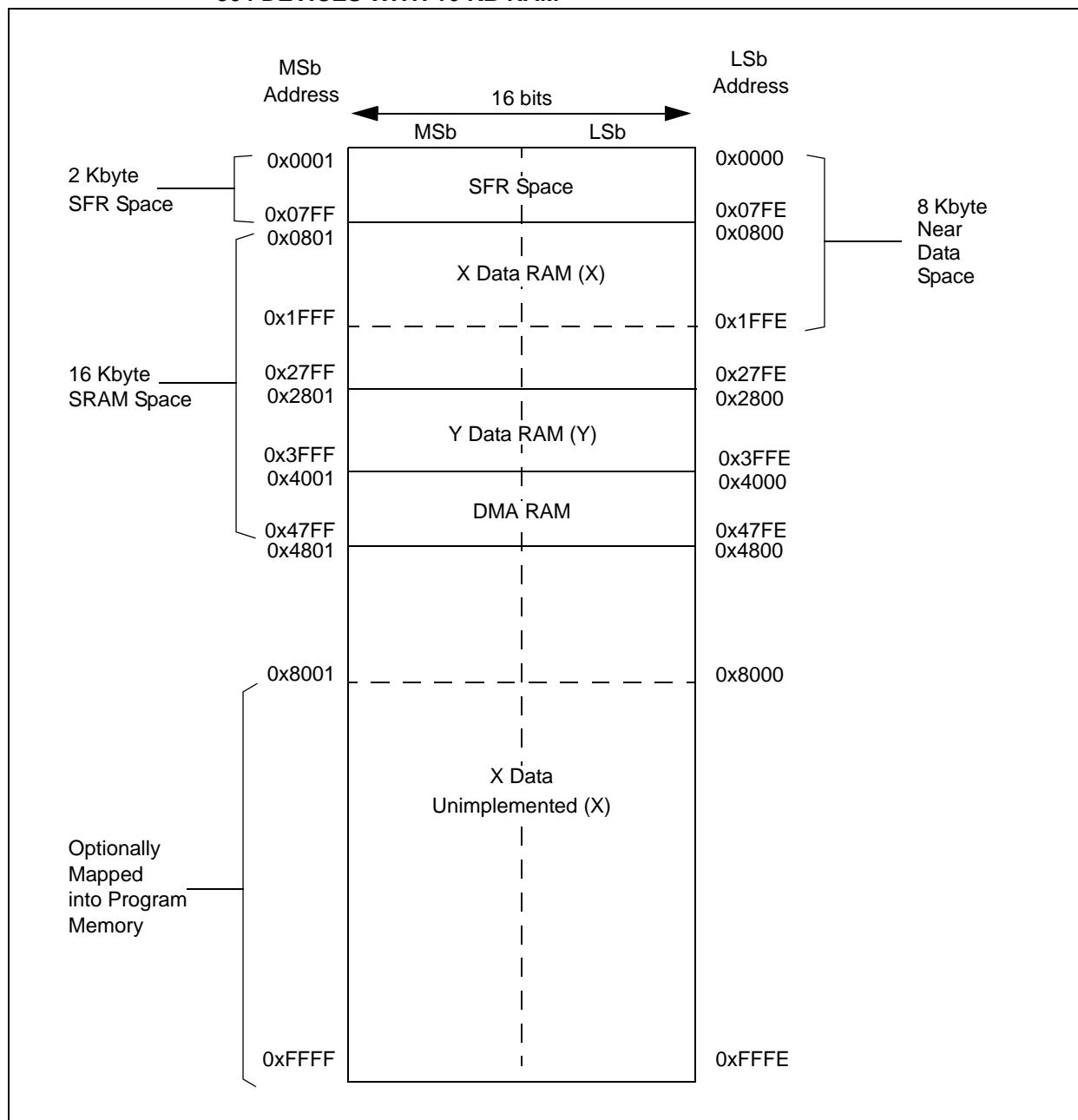
**FIGURE 4-3: DATA MEMORY MAP FOR dsPIC33FJ32MC302/304 DEVICES WITH 4 KB RAM**



**FIGURE 4-4: DATA MEMORY MAP FOR dsPIC33FJ128MC202/204 AND dsPIC33FJ64MC202/204 DEVICES WITH 8 KB RAM**



**FIGURE 4-5: DATA MEMORY MAP FOR dsPIC33FJ128MC802/804 AND dsPIC33FJ64MC802/804 DEVICES WITH 16 KB RAM**



#### 4.2.5 X AND Y DATA SPACES

The core has two data spaces, X and Y. These data spaces can be considered either separate (for some DSP instructions), or as one unified linear address range (for MCU instructions). The data spaces are accessed using two Address Generation Units (AGUs) and separate data paths. This feature allows certain instructions to concurrently fetch two words from RAM, thereby enabling efficient execution of DSP algorithms such as Finite Impulse Response (FIR) filtering and Fast Fourier Transform (FFT).

The X data space is used by all instructions and supports all addressing modes. X data space has separate read and write data buses. The X read data bus is the read data path for all instructions that view data space as combined X and Y address space. It is also the X data prefetch path for the dual operand DSP instructions (MAC class).

The Y data space is used in concert with the X data space by the MAC class of instructions (CLR, ED, EDAC, MAC, MOVSAC, MPY, MPY.N and MSC) to provide two concurrent data read paths.

Both the X and Y data spaces support Modulo Addressing mode for all instructions, subject to addressing mode restrictions. Bit-Reversed Addressing mode is only supported for writes to X data space.

All data memory writes, including in DSP instructions, view data space as combined X and Y address space. The boundary between the X and Y data spaces is device-dependent and is not user-programmable.

All effective addresses are 16 bits wide and point to bytes within the data space. Therefore, the data space address range is 64 Kbytes, or 32K words, though the implemented memory locations vary by device.

#### 4.2.6 DMA RAM

Every dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 device contains up to 2 Kbytes of dual ported DMA RAM located at the end of Y data space, and is a part of Y data space. Memory locations in the DMA RAM space are accessible simultaneously by the CPU and the DMA controller module. The DMA RAM is utilized by the DMA controller to store data to be transferred to various peripherals using DMA, as well as data transferred from various peripherals using DMA. The DMA RAM can be accessed by the DMA controller without having to steal cycles from the CPU.

When the CPU and the DMA controller attempt to concurrently write to the same DMA RAM location, the hardware ensures that the CPU is given precedence in accessing the DMA RAM location. Therefore, the DMA RAM provides a reliable means of transferring DMA data without ever having to stall the CPU.

**Note:** The DMA RAM can be used for general purpose data storage if the DMA function is not required in an application.

TABLE 4-1: CPU CORE REGISTERS MAP

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
WREG0	0000																0000		
WREG1	0002																0000		
WREG2	0004																0000		
WREG3	0006																0000		
WREG4	0008																0000		
WREG5	000A																0000		
WREG6	000C																0000		
WREG7	000E																0000		
WREG8	0010																0000		
WREG9	0012																0000		
WREG10	0014																0000		
WREG11	0016																0000		
WREG12	0018																0000		
WREG13	001A																0000		
WREG14	001C																0000		
WREG15	001E																0800		
SPLIM	0020																xxxx		
ACCAL	0022																xxxx		
ACCAH	0024																xxxx		
ACCAU	0026																xxxx		
ACCBL	0028																xxxx		
ACCBH	002A																xxxx		
ACCBU	002C																xxxx		
PCL	002E																xxxx		
PCH	0030	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	Program Counter High Byte Register	0000	
TBLPAG	0032	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	Table Page Address Pointer Register	0000	
PSVPAG	0034	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	Program Memory Visibility Page Address Pointer Register	0000	
RCOUNT	0036																xxxx		
DCOUNT	0038																xxxx		
DOSTARTL	003A																0	xxxx	
DOSTARTH	003C	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	DOSTARTH<5:0>	00xx	
DOENDL	003E																0	xxxx	
DOENDH	0040	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	DOENDH<5:0>	00xx	
SR	0042	OA	OB	SA	SB	OAB	SAB	DA	DC	IPL2	IPL1	IPL0	RA	N	OV	Z	C	0000	
CORCON	0044	—	—	—	US	EDT				DL<2:0>	SATA	SATB	SATDW	ACCSAT	IPL3	PSV	RND	IF	0020
MODCON	0046	XMODEN	YMODEN	—	—				BWM<3:0>				YWM<3:0>				XWM<3:0>	0000	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-1: CPU CORE REGISTERS MAP (CONTINUED)**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
XMODSRT	0048								XS<15:1>							0	xxxx	
XMODEND	004A								XE<15:1>							1	xxxx	
YMODSRT	004C								YS<15:1>							0	xxxx	
YMODEND	004E								YE<15:1>							1	xxxx	
XBREV	0050	BREN								XB<14:0>							xxxx	
DISICNT	0052	—	—								Disable Interrupts Counter Register						xxxx	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-2: CHANGE NOTIFICATION REGISTER MAP FOR dsPIC33FJ128MC202/802, dsPIC33FJ64MC202/802 AND dsPIC33FJ32MC302**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CNEN1	0060	CN15IE	CN14IE	CN13IE	CN12IE	CN11IE	—	—	—	CN7IE	CN6IE	CN5IE	CN4IE	CN3IE	CN2IE	CN1IE	CN0IE	0000
CNEN2	0062	—	CN30IE	CN29IE	—	CN27IE	—	—	CN24IE	CN23IE	CN22IE	CN21IE	—	—	—	—	CN16IE	0000
CNPUI1	0068	CN15PUE	CN14PUE	CN13PUE	CN12PUE	CN11PUE	—	—	—	CN7PUE	CN6PUE	CN5PUE	CN4PUE	CN3PUE	CN2PUE	CN1PUE	CN0PUE	0000
CNPUI2	006A	—	CN30PUE	CN29PUE	—	CN27PUE	—	—	CN24PUE	CN23PUE	CN22PUE	CN21PUE	—	—	—	—	CN16PUE	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-3: CHANGE NOTIFICATION REGISTER MAP FOR dsPIC33FJ128MC204/804, dsPIC33FJ64MC204/804 AND dsPIC33FJ32MC304**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CNEN1	0060	CN15IE	CN14IE	CN13IE	CN12IE	CN11IE	CN10IE	CN9IE	CN8IE	CN7IE	CN6IE	CN5IE	CN4IE	CN3IE	CN2IE	CN1IE	CN0IE	0000
CNEN2	0062	—	CN30IE	CN29IE	CN28IE	CN27IE	CN26IE	CN25IE	CN24IE	CN23IE	CN22IE	CN21IE	CN20IE	CN19IE	CN18IE	CN17IE	CN16IE	0000
CNPUI1	0068	CN15PUE	CN14PUE	CN13PUE	CN12PUE	CN11PUE	CN10PUE	CN9PUE	CN8PUE	CN7PUE	CN6PUE	CN5PUE	CN4PUE	CN3PUE	CN2PUE	CN1PUE	CN0PUE	0000
CNPUI2	006A	—	CN30PUE	CN29PUE	CN28PUE	CN27PUE	CN26PUE	CN25PUE	CN24PUE	CN23PUE	CN22PUE	CN21PUE	CN20PUE	CN19PUE	CN18PUE	CN17PUE	CN16PUE	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-4: INTERRUPT CONTROLLER REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
INTCON1	0080	NSTDIS	OVAERR	OVBERR	COVAERR	COVBERR	OVATE	OVBTE	COVTE	SFTACERR	DIV0ERR	DMACERR	MATHERR	ADDRERR	STKERR	OSCFAIL	—	0000
INTCON2	0082	ALТИVT	DISI	—	—	—	—	—	—	—	—	—	—	—	INT2EP	INT1EP	INT0EP	0000
IFS0	0084	—	DMA1IF	AD1IF	U1TXIF	U1RXIF	SPI1IF	SPI1EIF	T3IF	T2IF	OC2IF	IC2IF	DMA0IF	T1IF	OC1IF	IC1IF	INT0IF	0000
IFS1	0086	U2TXIF	U2RXIF	INT2IF	T5IF	T4IF	OC4IF	OC3IF	DMA2IF	IC8IF	IC7IF	—	INT1IF	CNIF	CMIF	MI2C1IF	SI2C1IF	0000
IFS2	0088	—	DMA4IF	PMPIF	—	—	—	—	—	—	—	—	DMA3IF	C1IF <sup>(1)</sup>	C1RXIF <sup>(1)</sup>	SPI2IF	SPI2EIF	0000
IFS3	008A	FLTA1IF	RTCIF	DMA5IF	—	—	QEI1IF	PWM1IF	—	—	—	—	—	—	—	—	—	0000
IFS4	008C	DAC1LIF <sup>(2)</sup>	DAC1RIF <sup>(2)</sup>	—	—	QEI2IF	FLTA2IF	PWM2IF	—	—	C1TXIF <sup>(1)</sup>	DMA7IF	DMA6IF	CRCIF	U2EIF	U1EIF	—	0000
IEC0	0094	—	DMA1IE	AD1IE	U1TXIE	U1RXIE	SPI1IE	SPI1EIE	T3IE	T2IE	OC2IE	IC2IE	DMA0IE	T1IE	OC1IE	IC1IE	INT0IE	0000
IEC1	0096	U2TXIE	U2RXIE	INT2IE	T5IE	T4IE	OC4IE	OC3IE	DMA2IE	IC8IE	IC7IE	—	INT1IE	CNIE	CMIE	MI2C1IE	SI2C1IE	0000
IEC2	0098	—	DMA4IE	PMPIE	—	—	—	—	—	—	—	DMA3IE	C1IE <sup>(1)</sup>	C1RXIE <sup>(1)</sup>	SPI2IE	SPI2EIE	0000	
IEC3	009A	FLTA1IE	RTCIE	DMA5IE	—	—	QEI1IE	PWM1IE	—	—	—	—	—	—	—	—	—	0000
IEC4	009C	DAC1LIE <sup>(2)</sup>	DAC1RIE <sup>(2)</sup>	—	—	QEI2IE	FLTA2IE	PWM2IE	—	—	C1TXIE <sup>(1)</sup>	DMA7IE	DMA6IE	CRCIE	U2EIE	U1EIE	—	0000
IPC0	00A4	—	T1IP<2:0>			—	OC1IP<2:0>			—	IC1IP<2:0>			—	INT0IP<2:0>			4444
IPC1	00A6	—	T2IP<2:0>			—	OC2IP<2:0>			—	IC2IP<2:0>			—	DMA0IP<2:0>			4444
IPC2	00A8	—	U1RXIP<2:0>			—	SPI1IP<2:0>			—	SPI1EIP<2:0>			—	T3IP<2:0>			4444
IPC3	00AA	—	—	—	—	—	DMA1IP<2:0>			—	AD1IP<2:0>			—	U1TXIP<2:0>			0444
IPC4	00AC	—	CNIP<2:0>			—	CMIP<2:0>			—	MI2C1IP<2:0>			—	SI2C1IP<2:0>			4444
IPC5	00AE	—	IC8IP<2:0>			—	IC7IP<2:0>			—	—	—	—	—	INT1IP<2:0>			4404
IPC6	00B0	—	T4IP<2:0>			—	OC4IP<2:0>			—	OC3IP<2:0>			—	DMA2IP<2:0>			4444
IPC7	00B2	—	U2TXIP<2:0>			—	U2RXIP<2:0>			—	INT2IP<2:0>			—	T5IP<2:0>			4444
IPC8	00B4	—	C1IP<2:0> <sup>(1)</sup>			—	C1RXIP<2:0> <sup>(1)</sup>			—	SPI2IP<2:0>			—	SPI2EIP<2:0>			4444
IPC9	00B6	—	—	—	—	—	—	—	—	—	—	—	—	—	DMA3IP<2:0>			0004
IPC11	00BA	—	—	—	—	—	DMA4IP<2:0>			—	PMPIP<2:0>			—	—	—	—	0440
IPC14	00C0	—	—	—	—	—	QEI1IP<2:0>			—	PWM1IP<2:0>			—	—	—	—	0440
IPC15	00C2	—	FLTA1IP<2:0>			—	RTCIP<2:0>			—	DMA5IP<2:0>			—	—	—	—	4440
IPC16	00C4	—	CRCIP<2:0>			—	U2EIP<2:0>			—	U1EIP<2:0>			—	—	—	—	4440
IPC17	00C6	—	—	—	—	—	C1TXIP<2:0> <sup>(1)</sup>			—	DMA7IP<2:0>			—	DMA6IP<2:0>			0444
IPC18	00C8	—	QEI2IP<2:0>			—	FLTA2IP<2:0>			—	PWM2IP<2:0>			—	—	—	—	4440
IPC19	00CA	—	DAC1LIP<2:0> <sup>(2)</sup>			—	DAC1RIP<2:0> <sup>(2)</sup>			—	—	—	—	—	—	—	—	4400
INTTREG	00E0	—	—	—	—	ILR<3:0>			—	VECNUM<6:0>								4444

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** Interrupts are disabled on devices without the ECAN™ modules.

**2:** Interrupts are disabled on devices without a DAC module.

**TABLE 4-5: TIMER REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TMR1	0100																0000	
PR1	0102																FFFF	
T1CON	0104	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	—	TSYNC	TCS	—	0000	
TMR2	0106																0000	
TMR3HLD	0108																xxxx	
TMR3	010A																0000	
PR2	010C																FFFF	
PR3	010E																FFFF	
T2CON	0110	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	T32	—	TCS	—	0000	
T3CON	0112	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	—	—	TCS	—	0000	
TMR4	0114																0000	
TMR5HLD	0116																xxxx	
TMR5	0118																0000	
PR4	011A																FFFF	
PR5	011C																FFFF	
T4CON	011E	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	T32	—	TCS	—	0000	
T5CON	0120	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	—	—	TCS	—	0000	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-6: INPUT CAPTURE REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
IC1BUF	0140																xxxx	
IC1CON	0142	—	—	ICSIDL	—	—	—	—	—	ICTMR	ICI<1:0>	ICOV	ICBNE	ICM<2:0>	—	—	0000	
IC2BUF	0144																xxxx	
IC2CON	0146	—	—	ICSIDL	—	—	—	—	—	ICTMR	ICI<1:0>	ICOV	ICBNE	ICM<2:0>	—	—	0000	
IC7BUF	0158																xxxx	
IC7CON	015A	—	—	ICSIDL	—	—	—	—	—	ICTMR	ICI<1:0>	ICOV	ICBNE	ICM<2:0>	—	—	0000	
IC8BUF	015C																xxxx	
IC8CON	015E	—	—	ICSIDL	—	—	—	—	—	ICTMR	ICI<1:0>	ICOV	ICBNE	ICM<2:0>	—	—	0000	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-7: OUTPUT COMPARE REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
OC1RS	0180																	xxxx
OC1R	0182																	xxxx
OC1CON	0184	—	—	OCSIDL	—	—	—	—	—	—	—	—	OCFLT	OCTSEL	OCM<2:0>		0000	
OC2RS	0186																	xxxx
OC2R	0188																	xxxx
OC2CON	018A	—	—	OCSIDL	—	—	—	—	—	—	—	—	—	OCFLT	OCTSEL	OCM<2:0>	0000	
OC3RS	018C																	xxxx
OC3R	018E																	xxxx
OC3CON	0190	—	—	OCSIDL	—	—	—	—	—	—	—	—	—	OCFLT	OCTSEL	OCM<2:0>	0000	
OC4RS	0192																	xxxx
OC4R	0194																	xxxx
OC4CON	0196	—	—	OCSIDL	—	—	—	—	—	—	—	—	—	OCFLT	OCTSEL	OCM<2:0>	0000	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-8: 6-OUTPUT PWM1 REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset State
P1TCON	01C0	PTEN	—	PTSIDL	—	—	—	—	—	PTOPS<3:0>								0000
P1TMR	01C2	PTDIR								PWM Timer Count Value Register								0000
P1TPER	01C4	—								PWM Time Base Period Register								0000
P1SECMP	01C6	SEVTDIR								PWM Special Event Compare Register								0000
PWM1CON1	01C8	—	—	—	—	—	PMOD3	PMOD2	PMOD1	—	PEN3H	PEN2H	PEN1H	—	PEN3L	PEN2L	PEN1L	00FF
PWM1CON2	01CA	—	—	—	—	SEVOPS<3:0>				—	—	—	—	IUE	OSYNC	UDIS		0000
P1DTCON1	01CC	DTBPS<1:0>				DTB<5:0>				DTAPS<1:0>				DTA<5:0>				0000
P1DTCON2	01CE	—	—	—	—	—	—	—	—	—	—	DTS3A	DTS3I	DTS2A	DTS2I	DTS1A	DTS1I	0000
P1FLTACON	01D0	—	—	FAOV3H	FAOV3L	FAOV2H	FAOV2L	FAOV1H	FAOV1L	FLTAM	—	—	—	FAEN3	FAEN2	FAEN1		0000
P1OVDCON	01D4	—	—	POVD3H	POVD3L	POVD2H	POVD2L	POVD1H	POVD1L	—	—	POUT3H	POUT3L	POUT2H	POUT2L	POUT1H	POUT1L	FF00
P1DC1	01D6									PWM Duty Cycle 1 Register								0000
P1DC2	01D8									PWM Duty Cycle 2 Register								0000
P1DC3	01DA									PWM Duty Cycle 3 Register								0000

Legend: u = uninitialized bit, — = unimplemented, read as '0'

**TABLE 4-9: 2-OUTPUT PWM2 REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset State
P2TCON	05C0	PTEN	—	PTSIDL	—	—	—	—	—	PTOPS<3:0>	PTCKPS<1:0>	PTMOD<1:0>	0000					
P2TMR	05C2	PTDIR								PWM Timer Count Value Register				0000				
P2TPER	05C4	—								PWM Time Base Period Register				0000				
P2SECMP	05C6	SEVTDIR								PWM Special Event Compare Register				0000				
PWM2CON1	05C8	—	—	—	—	—	—	—	PMOD1	—	—	—	PEN1H	—	—	—	PEN1L 00FF	
PWM2CON2	05CA	—	—	—	—				SEVOPS<3:0>	—	—	—	—	IUE	OSYNC	UDIS	0000	
P2DTCOM1	05CC	DTBPS<1:0>							DTB<5:0>	DTAPS<1:0>				DTA<5:0>			0000	
P2DTCOM2	05CE	—	—	—	—	—	—	—	—	—	—	—	—	DTS1A	DTS1I	0000		
P2FLTACON	05D0	—	—	—	—	—	—	FAOV1H	FAOV1L	FLTAM	—	—	—	—	—	FAEN1	0000	
P2OVDCON	05D4	—	—	—	—	—	—	POVD1H	POVD1L	—	—	—	—	—	POUT1H	POUT1L	FF00	
P2DC1	05D6									PWM Duty Cycle #1 Register							0000	

Legend: — = unimplemented, read as '0'

**TABLE 4-10: QEI1 REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset State
QE1ICON	01E0	CNTERR	—	QEISIDL	INDX	UPDN		QEIM<2:0>	SWPAB	PCDOUT	TQGATE	TQCKPS<1:0>	POSRES	TQCS	UPDN_SRC	0000		
DFLT1CON	01E2	—	—	—	—	—	IMV<1:0>	CEID	QEOUT		QECK<2:0>	—	—	—	—	—	0000	
POS1CNT	01E4																0000	
MAX1CNT	01E6																FFFF	

Legend: — = unimplemented, read as '0'

**TABLE 4-11: QEI2 REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Reset State
QEI2CON	01F0	CNTERR	—	QEISIDL	INDX	UPDN		QEIM<2:0>	SWPAB	PCDOUT	TQGATE	TQCKPS<1:0>	POSRES	TQCS	UPDN_SRC	0000		
DFLT2CON	01F2	—	—	—	—	—	IMV<1:0>	CEID	QEOUT		QECK<2:0>	—	—	—	—	—	0000	
POS2CNT	01F4																0000	
MAX2CNT	01F6																FFFF	

Legend: — = unimplemented, read as '0'

**TABLE 4-12: I2C1 REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
I2C1RCV	0200	—	—	—	—	—	—	—	—	Receive Register									0000
I2C1TRN	0202	—	—	—	—	—	—	—	—	Transmit Register									00FF
I2C1BRG	0204	—	—	—	—	—	—	—	—	Baud Rate Generator Register									0000
I2C1CON	0206	I2CEN	—	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000	
I2C1STAT	0208	ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10	IWCOL	I2COV	D_A	P	S	R_W	RBF	TBF	0000	
I2C1ADD	020A	—	—	—	—	—	—	—	Address Register									0000	
I2C1MSK	020C	—	—	—	—	—	—	—	Address Mask Register									0000	

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-13: UART1 REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
U1MODE	0220	UARTEN	—	USIDL	IREN	RTSMD	—	UEN1	UEN0	WAKE	LBACK	ABAUD	URXINV	BRGH	PDSEL<1:0>		STSEL	0000	
U1STA	0222	UTXISEL1	UTXINV	UTXISEL0	—	UTXBRK	UTXEN	UTXBF	TRMT	URXISEL<1:0>		ADDEN	RIDLE	PERR	FERR	OERR	URXDA	0110	
U1TXREG	0224	—	—	—	—	—	—	—	UTX8	UART Transmit Register									xxxxx
U1RXREG	0226	—	—	—	—	—	—	—	URX8	UART Received Register									0000
U1BRG	0228	Baud Rate Generator Prescaler															0000		

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-14: UART2 REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
U2MODE	0230	UARTEN	—	USIDL	IREN	RTSMD	—	UEN1	UEN0	WAKE	LBACK	ABAUD	URXINV	BRGH	PDSEL<1:0>		STSEL	0000	
U2STA	0232	UTXISEL1	UTXINV	UTXISEL0	—	UTXBRK	UTXEN	UTXBF	TRMT	URXISEL<1:0>		ADDEN	RIDLE	PERR	FERR	OERR	URXDA	0110	
U2TXREG	0234	—	—	—	—	—	—	—	UTX8	UART Transmit Register									xxxxx
U2RXREG	0236	—	—	—	—	—	—	—	URX8	UART Receive Register									0000
U2BRG	0238	Baud Rate Generator Prescaler															0000		

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-15: SPI1 REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
SPI1STAT	0240	SPIEN	—	SPISIDL	—	—	—	—	—	—	SPIROV	—	—	—	—	SPITBF	SPIRBF	0000
SPI1CON1	0242	—	—	—	DISSCK	DISSDO	MODE16	SMP	CKE	SSEN	CKP	MSTEN	SPRE<2:0>	PPRE<1:0>	—	—	0000	
SPI1CON2	0244	FRMEN	SPIFSD	FRMPOL	—	—	—	—	—	—	—	—	—	—	—	FRMDLY	—	0000
SPI1BUF	0248	SPI1 Transmit and Receive Buffer Register															0000	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-16: SPI2 REGISTER MAP**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
SPI2STAT	0260	SPIEN	—	SPISIDL	—	—	—	—	—	—	SPIROV	—	—	—	—	SPITBF	SPIRBF	0000
SPI2CON1	0262	—	—	—	DISSCK	DISSDO	MODE16	SMP	CKE	SSEN	CKP	MSTEN	SPRE<2:0>	PPRE<1:0>	—	—	0000	
SPI2CON2	0264	FRMEN	SPIFSD	FRMPOL	—	—	—	—	—	—	—	—	—	—	—	FRMDLY	—	0000
SPI2BUF	0268	SPI2 Transmit and Receive Buffer Register															0000	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-17: ADC1 REGISTER MAP FOR dsPIC33FJ64MC202/802, dsPIC33FJ128MC202/802 AND dsPIC33FJ32MC302**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ADC1BUFO	0300	ADC Data Buffer 0															xxxx	
AD1CON1	0320	ADON	—	ADSIDL	ADDMABM	—	AD12B	FORM<1:0>	SSRC<2:0>			—	SIMSAM	ASAM	SAMP	DONE	0000	
AD1CON2	0322	VCFG<2:0>			—	—	CSCNA	CHPS<1:0>	BUFS	—	SMPI<3:0>			BUFM	ALTS	0000		
AD1CON3	0324	ADRC	—	—	SAMC<4:0>				ADCS<7:0>								0000	
AD1CHS123	0326	—	—	—	—	—	CH123NB<1:0>	CH123SB	—	—	—	—	—	CH123NA<1:0>	CH123SA	0000		
AD1CHS0	0328	CH0NB	—	—	CH0SB<4:0>				CH0NA	—	—	CH0SA<4:0>					0000	
AD1PCFGL	032C	—	—	—	—	—	—	—	—	—	PCFG5	PCFG4	PCFG3	PCFG2	PCFG1	PCFG0	0000	
AD1CSSL	0330	—	—	—	—	—	—	—	—	—	CSS5	CSS4	CSS3	CSS2	CSS1	CSS0	0000	
AD1CON4	0332	—	—	—	—	—	—	—	—	—	—	—	—	—	DMABL<2:0>		0000	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-18: ADC1 REGISTER MAP FOR dsPIC33FJ64MC204/804, dsPIC33FJ128MC204/804 AND dsPIC33FJ32MC304**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ADC1BUF0	0300																xxxx	
AD1CON1	0320	ADON	—	ADSIDL	ADDMABM	—	AD12B	FORM<1:0>		SSRC<2:0>	—	SIMSAM	ASAM	SAMP	DONE	0000		
AD1CON2	0322	VCFG<2:0>		—	—	CSCNA	CHPS<1:0>	BUFS	—		SMPI<3:0>		BUFM	ALTS	0000			
AD1CON3	0324	ADRC	—	—			SAMC<4:0>				ADCS<7:0>					0000		
AD1CHS123	0326	—	—	—	—	—	CH123NB<1:0>	CH123SB	—	—	—	—	—	CH123NA<1:0>	CH123SA	0000		
AD1CHS0	0328	CH0NB	—	—			CH0SB<4:0>		CH0NA	—	—			CH0SA<4:0>		0000		
AD1PCFGL	032C	—	—	—	—	—	—	PCFG8	PCFG7	PCFG6	PCFG5	PCFG4	PCFG3	PCFG2	PCFG1	PCFG0	0000	
AD1CSSL	0330	—	—	—	—	—	—	CSS8	CSS7	CSS6	CSS5	CSS4	CSS3	CSS2	CSS1	CSS0	0000	
AD1CON4	0332	—	—	—	—	—	—	—	—	—	—	—	—	—	DMABL<2:0>	0000		

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-19: DAC1 REGISTER MAP FOR dsPIC33FJ128MC804 AND dsPIC33FJ64MC804**

SFR Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
DAC1CON	03F0	DACEN	—	DACSIDL	AMPON	—	—	—	FORM	—					DACFDIV<6:0>		0000	
DAC1STAT	03F2	LOEN	—	LMVOEN	—	—	LITYPE	LFULL	LEMPTRY	ROEN	—	RMVOEN	—	—	RITYPE	RFULL	REMPY	0000
DAC1DFLT	03F4								DAC1DFLT<15:0>								0000	
DAC1RDAT	03F6								DAC1RDAT<15:0>								0000	
DAC1LDAT	03F8								DAC1LDAT<15:0>								0000	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-20: DMA REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
DMA0CON	0380	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA0REQ	0382	FORCE	—	—	—	—	—	—	—	—	—	—	—	—	—	IRQSEL<6:0>	0000	
DMA0STA	0384	—	—	—	—	—	—	—	—	—	—	STA<15:0>	—	—	—	—	0000	
DMA0STB	0386	—	—	—	—	—	—	—	—	—	—	STB<15:0>	—	—	—	—	0000	
DMA0PAD	0388	—	—	—	—	—	—	—	—	—	—	PAD<15:0>	—	—	—	—	0000	
DMA0CNT	038A	—	—	—	—	—	—	—	—	—	—	CNT<9:0>	—	—	—	—	0000	
DMA1CON	038C	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA1REQ	038E	FORCE	—	—	—	—	—	—	—	—	—	—	—	—	—	IRQSEL<6:0>	0000	
DMA1STA	0390	—	—	—	—	—	—	—	—	—	—	STA<15:0>	—	—	—	—	0000	
DMA1STB	0392	—	—	—	—	—	—	—	—	—	—	STB<15:0>	—	—	—	—	0000	
DMA1PAD	0394	—	—	—	—	—	—	—	—	—	—	PAD<15:0>	—	—	—	—	0000	
DMA1CNT	0396	—	—	—	—	—	—	—	—	—	—	CNT<9:0>	—	—	—	—	0000	
DMA2CON	0398	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA2REQ	039A	FORCE	—	—	—	—	—	—	—	—	—	—	—	—	—	IRQSEL<6:0>	0000	
DMA2STA	039C	—	—	—	—	—	—	—	—	—	—	STA<15:0>	—	—	—	—	0000	
DMA2STB	039E	—	—	—	—	—	—	—	—	—	—	STB<15:0>	—	—	—	—	0000	
DMA2PAD	03A0	—	—	—	—	—	—	—	—	—	—	PAD<15:0>	—	—	—	—	0000	
DMA2CNT	03A2	—	—	—	—	—	—	—	—	—	—	CNT<9:0>	—	—	—	—	0000	
DMA3CON	03A4	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA3REQ	03A6	FORCE	—	—	—	—	—	—	—	—	—	—	—	—	—	IRQSEL<6:0>	0000	
DMA3STA	03A8	—	—	—	—	—	—	—	—	—	—	STA<15:0>	—	—	—	—	0000	
DMA3STB	03AA	—	—	—	—	—	—	—	—	—	—	STB<15:0>	—	—	—	—	0000	
DMA3PAD	03AC	—	—	—	—	—	—	—	—	—	—	PAD<15:0>	—	—	—	—	0000	
DMA3CNT	03AE	—	—	—	—	—	—	—	—	—	—	CNT<9:0>	—	—	—	—	0000	
DMA4CON	03B0	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA4REQ	03B2	FORCE	—	—	—	—	—	—	—	—	—	—	—	—	—	IRQSEL<6:0>	0000	
DMA4STA	03B4	—	—	—	—	—	—	—	—	—	—	STA<15:0>	—	—	—	—	0000	
DMA4STB	03B6	—	—	—	—	—	—	—	—	—	—	STB<15:0>	—	—	—	—	0000	
DMA4PAD	03B8	—	—	—	—	—	—	—	—	—	—	PAD<15:0>	—	—	—	—	0000	
DMA4CNT	03BA	—	—	—	—	—	—	—	—	—	—	CNT<9:0>	—	—	—	—	0000	
DMA5CON	03BC	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA5REQ	03BE	FORCE	—	—	—	—	—	—	—	—	—	—	—	—	—	IRQSEL<6:0>	0000	
DMA5STA	03C0	—	—	—	—	—	—	—	—	—	—	STA<15:0>	—	—	—	—	0000	
DMA5STB	03C2	—	—	—	—	—	—	—	—	—	—	STB<15:0>	—	—	—	—	0000	

Legend: — = unimplemented, read as '0'.

**TABLE 4-20: DMA REGISTER MAP (CONTINUED)**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
DMA5PAD	03C4																0000	
DMA5CNT	03C6	—	—	—	—	—	—										0000	
DMA6CON	03C8	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA6REQ	03CA	FORCE	—	—	—	—	—	—	—	—	—					IRQSEL<6:0>	0000	
DMA6STA	03CC																0000	
DMA6STB	03CE																0000	
DMA6PAD	03D0																0000	
DMA6CNT	03D2	—	—	—	—	—	—									CNT<9:0>	0000	
DMA7CON	03D4	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>	—	—	—	MODE<1:0>	0000	
DMA7REQ	03D6	FORCE	—	—	—	—	—	—	—	—	—					IRQSEL<6:0>	0000	
DMA7STA	03D8																0000	
DMA7STB	03DA																0000	
DMA7PAD	03DC																0000	
DMA7CNT	03DE	—	—	—	—	—	—									CNT<9:0>	0000	
DMACS0	03E0	PWCOL7	PWCOL6	PWCOL5	PWCOL4	PWCOL3	PWCOL2	PWCOL1	PWCOL0	XWCOL7	XWCOL6	XWCOL5	XWCOL4	XWCOL3	XWCOL2	XWCOL1	XWCOL0	0000
DMACS1	03E2	—	—	—	—			LSTCH<3:0>		PPST7	PPST6	PPST5	PPST4	PPST3	PPST2	PPST1	PPST0	0000
DSADR	03E4								DSADR<15:0>								0000	

**Legend:** — = unimplemented, read as '0'.

**TABLE 4-21: ECAN1 REGISTER MAP WHEN C1CTRL1.WIN = 0 OR 1 (FOR dsPIC33FJ128MC802/804 AND dsPIC33FJ64MC802/804)**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
C1CTRL1	0400	—	—	CSIDL	ABAT	—	REQOP<2:0>			OPMODE<2:0>			—	CANCAP	—	—	WIN	0480
C1CTRL2	0402	—	—	—	—	—	—	—	—	—	—	—	—	DNCNT<4:0>				0000
C1VEC	0404	—	—	—	FILHIT<4:0>					—	ICODE<6:0>						0000	
C1FCCTRL	0406	DMABS<2:0>			—	—	—	—	—	—	—	—	—	FSA<4:0>				0000
C1FIFO	0408	—	—	FBP<5:0>						—	—	—	—	FNRB<5:0>				0000
C1INTF	040A	—	—	TXBO	TXB P	RXB P	TXWAR	RXWAR	EWARN	IVRIF	WAKIF	ERRIF	—	FIFOIF	RBOVIF	RBIF	TBIF	0000
C1INTE	040C	—	—	—	—	—	—	—	—	IVRIE	WAKIE	ERRIE	—	FIFOIE	RBOVIE	RBIE	TBIE	0000
C1EC	040E	TERRCNT<7:0>								RERRCNT<7:0>								0000
C1CFG1	0410	—	—	—	—	—	—	—	—	SJW<1:0>		BRP<5:0>						0000
C1CFG2	0412	—	WAKFIL	—	—	—	SEG2PH<2:0>			SEG2PHTS	SAM	SEG1PH<2:0>			PRSEG<2:0>			0000
C1FEN1	0414	FLTEN15	FLTEN14	FLTEN13	FLTEN12	FLTEN11	FLTEN10	FLTEN9	FLTEN8	FLTEN7	FLTEN6	FLTEN5	FLTEN4	FLTEN3	FLTEN2	FLTEN1	FLTEN0	FFFF
C1FMSKSEL1	0418	F7MSK<1:0>		F6MSK<1:0>		F5MSK<1:0>		F4MSK<1:0>		F3MSK<1:0>	F2MSK<1:0>		F1MSK<1:0>		F0MSK<1:0>		0000	
C1FMSKSEL2	041A	F15MSK<1:0>		F14MSK<1:0>		F13MSK<1:0>		F12MSK<1:0>		F11MSK<1:0>	F10MSK<1:0>		F9MSK<1:0>		F8MSK<1:0>		0000	

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-22: ECAN1 REGISTER MAP WHEN C1CTRL1.WIN = 0 (FOR dsPIC33FJ128MC802/804 AND dsPIC33FJ64MC802/804)**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets				
	0400-041E	See definition when WIN = x																				
C1RXFUL1	0420	RXFUL15	RXFUL14	RXFUL13	RXFUL12	RXFUL11	RXFUL10	RXFUL9	RXFUL8	RXFUL7	RXFUL6	RXFUL5	RXFUL4	RXFUL3	RXFUL2	RXFUL1	RXFUL0	0000				
C1RXFUL2	0422	RXFUL31	RXFUL30	RXFUL29	RXFUL28	RXFUL27	RXFUL26	RXFUL25	RXFUL24	RXFUL23	RXFUL22	RXFUL21	RXFUL20	RXFUL19	RXFUL18	RXFUL17	RXFUL16	0000				
C1RXOVF1	0428	RXOVF15	RXOVF14	RXOVF13	RXOVF12	RXOVF11	RXOVF10	RXOVF9	RXOVF8	RXOVF7	RXOVF6	RXOVF5	RXOVF4	RXOVF3	RXOVF2	RXOVF1	RXOVF0	0000				
C1RXOVF2	042A	RXOVF31	RXOVF30	RXOVF29	RXOVF28	RXOVF27	RXOVF26	RXOVF25	RXOVF24	RXOVF23	RXOVF22	RXOVF21	RXOVF20	RXOVF19	RXOVF18	RXOVF17	RXOVF16	0000				
C1TR01CON	0430	TXEN1	TXABT1	TXLARB1	TXERR1	TXREQ1	RTREN1	TX1PRI<1:0>		TXEN0	TXABT0	TXLARB0	TXERR0	TXREQ0	RTREN0	TX0PRI<1:0>		0000				
C1TR23CON	0432	TXEN3	TXABT3	TXLARB3	TXERR3	TXREQ3	RTREN3	TX3PRI<1:0>		TXEN2	TXABT2	TXLARB2	TXERR2	TXREQ2	RTREN2	TX2PRI<1:0>		0000				
C1TR45CON	0434	TXEN5	TXABT5	TXLARB5	TXERR5	TXREQ5	RTREN5	TX5PRI<1:0>		TXEN4	TXABT4	TXLARB4	TXERR4	TXREQ4	RTREN4	TX4PRI<1:0>		0000				
C1TR67CON	0436	TXEN7	TXABT7	TXLARB7	TXERR7	TXREQ7	RTREN7	TX7PRI<1:0>		TXEN6	TXABT6	TXLARB6	TXERR6	TXREQ6	RTREN6	TX6PRI<1:0>		0000				
C1RXD	0440	Received Data Word																xxxx				
C1TXD	0442	Transmit Data Word																xxxx				

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-23: ECAN1 REGISTER MAP WHEN C1CTRL1.WIN = 1 (FOR dsPIC33FJ128MC802/804 AND dsPIC33FJ64MC802/804)**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets		
	0400-041E	See definition when WIN = x																		
C1BUFPNT1	0420	F3BP<3:0>			F2BP<3:0>			F1BP<3:0>			F0BP<3:0>			0000						
C1BUFPNT2	0422	F7BP<3:0>			F6BP<3:0>			F5BP<3:0>			F4BP<3:0>			0000						
C1BUFPNT3	0424	F11BP<3:0>			F10BP<3:0>			F9BP<3:0>			F8BP<3:0>			0000						
C1BUFPNT4	0426	F15BP<3:0>			F14BP<3:0>			F13BP<3:0>			F12BP<3:0>			0000						
C1RXM0SID	0430	SID<10:3>						SID<2:0>		—	MIDE	—	EID<17:16>	xxxx						
C1RXM0EID	0432	EID<15:8>						EID<7:0>						xxxx						
C1RXM1SID	0434	SID<10:3>						SID<2:0>		—	MIDE	—	EID<17:16>	xxxx						
C1RXM1EID	0436	EID<15:8>						EID<7:0>						xxxx						
C1RXM2SID	0438	SID<10:3>						SID<2:0>		—	MIDE	—	EID<17:16>	xxxx						
C1RXM2EID	043A	EID<15:8>						EID<7:0>						xxxx						
C1RXF0SID	0440	SID<10:3>						SID<2:0>		—	EXIDE	—	EID<17:16>	xxxx						
C1RXF0EID	0442	EID<15:8>						EID<7:0>						xxxx						
C1RXF1SID	0444	SID<10:3>						SID<2:0>		—	EXIDE	—	EID<17:16>	xxxx						
C1RXF1EID	0446	EID<15:8>						EID<7:0>						xxxx						
C1RXF2SID	0448	SID<10:3>						SID<2:0>		—	EXIDE	—	EID<17:16>	xxxx						
C1RXF2EID	044A	EID<15:8>						EID<7:0>						xxxx						
C1RXF3SID	044C	SID<10:3>						SID<2:0>		—	EXIDE	—	EID<17:16>	xxxx						
C1RXF3EID	044E	EID<15:8>						EID<7:0>						xxxx						
C1RXF4SID	0450	SID<10:3>						SID<2:0>		—	EXIDE	—	EID<17:16>	xxxx						
C1RXF4EID	0452	EID<15:8>						EID<7:0>						xxxx						
C1RXF5SID	0454	SID<10:3>						SID<2:0>		—	EXIDE	—	EID<17:16>	xxxx						
C1RXF5EID	0456	EID<15:8>						EID<7:0>						xxxx						
C1RXF6SID	0458	SID<10:3>						SID<2:0>		—	EXIDE	—	EID<17:16>	xxxx						
C1RXF6EID	045A	EID<15:8>						EID<7:0>						xxxx						
C1RXF7SID	045C	SID<10:3>						SID<2:0>		—	EXIDE	—	EID<17:16>	xxxx						
C1RXF7EID	045E	EID<15:8>						EID<7:0>						xxxx						
C1RXF8SID	0460	SID<10:3>						SID<2:0>		—	EXIDE	—	EID<17:16>	xxxx						
C1RXF8EID	0462	EID<15:8>						EID<7:0>						xxxx						
C1RXF9SID	0464	SID<10:3>						SID<2:0>		—	EXIDE	—	EID<17:16>	xxxx						
C1RXF9EID	0466	EID<15:8>						EID<7:0>						xxxx						
C1RXF10SID	0468	SID<10:3>						SID<2:0>		—	EXIDE	—	EID<17:16>	xxxx						
C1RXF10EID	046A	EID<15:8>						EID<7:0>						xxxx						
C1RXF11SID	046C	SID<10:3>						SID<2:0>		—	EXIDE	—	EID<17:16>	xxxx						

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-23: ECAN1 REGISTER MAP WHEN C1CTRL1.WIN = 1 (FOR dsPIC33FJ128MC802/804 AND dsPIC33FJ64MC802/804) (CONTINUED)**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
C1RXF11EID	046E	EID<15:8>								EID<7:0>								xxxx	
C1RXF12SID	0470	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>				xxxx
C1RXF12EID	0472	EID<15:8>								EID<7:0>								xxxx	
C1RXF13SID	0474	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>				xxxx
C1RXF13EID	0476	EID<15:8>								EID<7:0>								xxxx	
C1RXF14SID	0478	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>				xxxx
C1RXF14EID	047A	EID<15:8>								EID<7:0>								xxxx	
C1RXF15SID	047C	SID<10:3>								SID<2:0>		—	EXIDE	—	EID<17:16>				xxxx
C1RXF15EID	047E	EID<15:8>								EID<7:0>								xxxx	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-24: PERIPHERAL PIN SELECT INPUT REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RPINR0	0680	—	—	—									—	—	—	—	—	1FO0
RPINR1	0682	—	—	—	—	—	—	—	—	—	—	—					001F	
RPINR3	0686	—	—	—													1F1F	
RPINR4	0688	—	—	—													1F1F	
RPINR7	068E	—	—	—													1F1F	
RPINR10	0694	—	—	—													1F1F	
RPINR11	0696	—	—	—	—	—	—	—	—	—	—	—					001F	
RPINR12	0698	—	—	—	—	—	—	—	—	—	—	—					001F	
RPINR13	069A	—	—	—	—	—	—	—	—	—	—	—					001F	
RPINR14	069C	—	—	—													1F1F	
RPINR15	069E	—	—	—	—	—	—	—	—	—	—	—					001F	
RPINR16	06A0	—	—	—													1F1F	
RPINR17	06A2	—	—	—	—	—	—	—	—	—	—	—					001F	
RPINR18	06A4	—	—	—													1F1F	
RPINR19	06A6	—	—	—													1F1F	
RPINR20	06A8	—	—	—													1F1F	
RPINR21	06AA	—	—	—	—	—	—	—	—	—	—	—					001F	
RPINR22	06AC	—	—	—													1F1F	
RPINR23	06AE	—	—	—	—	—	—	—	—	—	—	—					001F	
RPINR26 <sup>(1)</sup>	06B4	—	—	—	—	—	—	—	—	—	—	—					001F	

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** This register is present in dsPIC33FJ128MC802/804 and dsPIC33FJ64MC802/804 devices only.

**TABLE 4-25: PERIPHERAL PIN SELECT OUTPUT REGISTER MAP FOR dsPIC33FJ128MC202/802, dsPIC33FJ64MC202/802 AND dsPIC33FJ32MC302**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RPOR0	06C0	—	—	—	RP1R<4:0>					—	—	—	RP0R<4:0>					0000
RPOR1	06C2	—	—	—	RP3R<4:0>					—	—	—	RP2R<4:0>					0000
RPOR2	06C4	—	—	—	RP5R<4:0>					—	—	—	RP4R<4:0>					0000
RPOR3	06C6	—	—	—	RP7R<4:0>					—	—	—	RP6R<4:0>					0000
RPOR4	06C8	—	—	—	RP9R<4:0>					—	—	—	RP8R<4:0>					0000
RPOR5	06CA	—	—	—	RP11R<4:0>					—	—	—	RP10R<4:0>					0000
RPOR6	06CC	—	—	—	RP13R<4:0>					—	—	—	RP12R<4:0>					0000
RPOR7	06CE	—	—	—	RP15R<4:0>					—	—	—	RP14R<4:0>					0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'.

**TABLE 4-26: PERIPHERAL PIN SELECT OUTPUT REGISTER MAP FOR dsPIC33FJ128MC204/804, dsPIC33FJ64MC204/804 AND dsPIC33FJ32MC304**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RPOR0	06C0	—	—	—	RP1R<4:0>					—	—	—	RP0R<4:0>					0000
RPOR1	06C2	—	—	—	RP3R<4:0>					—	—	—	RP2R<4:0>					0000
RPOR2	06C4	—	—	—	RP5R<4:0>					—	—	—	RP4R<4:0>					0000
RPOR3	06C6	—	—	—	RP7R<4:0>					—	—	—	RP6R<4:0>					0000
RPOR4	06C8	—	—	—	RP9R<4:0>					—	—	—	RP8R<4:0>					0000
RPOR5	06CA	—	—	—	RP11R<4:0>					—	—	—	RP10R<4:0>					0000
RPOR6	06CC	—	—	—	RP13R<4:0>					—	—	—	RP12R<4:0>					0000
RPOR7	06CE	—	—	—	RP15R<4:0>					—	—	—	RP14R<4:0>					0000
RPOR8	06D0	—	—	—	RP17R<4:0>					—	—	—	RP16R<4:0>					0000
RPOR9	06D2	—	—	—	RP19R<4:0>					—	—	—	RP18R<4:0>					0000
RPOR10	06D4	—	—	—	RP21R<4:0>					—	—	—	RP20R<4:0>					0000
RPOR11	06D6	—	—	—	RP23R<4:0>					—	—	—	RP22R<4:0>					0000
RPOR12	06D8	—	—	—	RP25R<4:0>					—	—	—	RP24R<4:0>					0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'.

**TABLE 4-27: PARALLEL MASTER/SLAVE PORT REGISTER MAP FOR dsPIC33FJ128MC202/802, dsPIC33FJ64MC202/802 AND dsPIC33FJ32MC302**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMCON	0600	PMPEN	—	PSIDL	ADRMUX<1:0>	PTBEN	PTWREN	PTRDEN	CSF1	CSF0	ALP	—	CS1P	BEP	WRSP	RDSP	0000	
PMMODE	0602	BUSY	IRQM<1:0>	INCM<1:0>	MODE16	MODE<1:0>	WAITB<1:0>	WAITM<3:0>	WAITE<1:0>	—	—	—	—	—	—	—	0000	
PMADDR	0604	ADDR15	CS1	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
PMDOUT1	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
PMDOUT2	0606	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
PMDIN1	0608	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
PMPDIN2	060A	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
PMAEN	060C	—	PTEN14	—	—	—	—	—	—	—	—	—	—	—	—	PTEN<1:0>	0000	
PMSTAT	060E	IBF	IBOV	—	—	IB3F	IB2F	IB1F	IB0F	OBE	OBUF	—	—	OB3E	OB2E	OB1E	OB0E	008F

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-28: PARALLEL MASTER/SLAVE PORT REGISTER MAP FOR dsPIC33FJ128MC204/804, dsPIC33FJ64MC204/804 AND dsPIC33FJ32MC304**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMCON	0600	PMPEN	—	PSIDL	ADRMUX<1:0>	PTBEN	PTWREN	PTRDEN	CSF1	CSF0	ALP	—	CS1P	BEP	WRSP	RDSP	0000	
PMMODE	0602	BUSY	IRQM<1:0>	INCM<1:0>	MODE16	MODE<1:0>	WAITB<1:0>	WAITM<3:0>	WAITE<1:0>	—	—	—	—	—	—	—	0000	
PMADDR	0604	ADDR15	CS1	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
PMDOUT1	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
PMDOUT2	0606	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
PMDIN1	0608	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
PMPDIN2	060A	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
PMAEN	060C	—	PTEN14	—	—	—	—	—	—	—	—	—	—	—	—	PTEN<10:0>	0000	
PMSTAT	060E	IBF	IBOV	—	—	IB3F	IB2F	IB1F	IB0F	OBE	OBUF	—	—	OB3E	OB2E	OB1E	OB0E	008F

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-29: REAL-TIME CLOCK AND CALENDAR REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ALRMVAL	0620																	xxxx
ALCFGGRPT	0622	ALRMEN	CHIME		AMASK<3:0>		ALRMPTR<1:0>						ARPT<7:0>					0000
RTCVAL	0624						RTCC Value Register Window based on RTCPTR<1:0>											xxxx
RCFGCAL	0626	RTCEN	—	RTCWREN	RTCSYNC	HALFSEC	RTCOE	RTCPTR<1:0>					CAL<7:0>					0000
PADCFG1	02FC	—	—	—	—	—	—	—	—	—	—	—	—	—	—	RTSECSEL	PMPTTL	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-30: CRC REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CRCCON	0640	—	—	CSIDL		VWORD<4:0>		CRCFUL	CRCMPT	—	CRCGO		PLEN<3:0>					0000
CRCXOR	0642					X<15:0>												0000
CRCDAT	0644					CRC Data Input Register												0000
CRCWDAT	0646					CRC Result Register												0000

Legend: — = unimplemented, read as '0'.

**TABLE 4-31: DUAL COMPARATOR REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CMCON	0630	CMIDL	—	C2EVT	C1EVT	C2EN	C1EN	C2OUTEN	C1OUTEN	C2OUT	C1OUT	C2INV	C1INV	C2NEG	C2POS	C1NEG	C1POS	0000
CVRCON	0632	—	—	—	—	—	—	—	—	CVREN	CVROE	CVRR	CVRSS		CVR<3:0>			0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-32: PORTA REGISTER MAP FOR dsPIC33FJ128MC202/802, dsPIC33FJ64MC202/802 AND dsPIC33FJ32MC302**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISA	02C0	—	—	—	—	—	—	—	—	—	—	—	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	001F
PORTA	02C2	—	—	—	—	—	—	—	—	—	—	—	RA4	RA3	RA2	RA1	RA0	xxxx
LATA	02C4	—	—	—	—	—	—	—	—	—	—	—	LATA4	LATA3	LATA2	LATA1	LATA0	xxxx
ODCA	02C6	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-33: PORTA REGISTER MAP FOR dsPIC33FJ128MC204/804, dsPIC33FJ64MC204/804 AND dsPIC33FJ32MC304**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISA	02C0	—	—	—	—	—	TRISA10	TRISA9	TRISA8	TRISA7	—	—	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	001F
PORTA	02C2	—	—	—	—	—	RA10	RA9	RA8	RA7	—	—	RA4	RA3	RA2	RA1	RA0	xxxx
LATA	02C4	—	—	—	—	—	LATA10	LATA9	LATA8	LATA7	—	—	LATA4	LATA3	LATA2	LATA1	LATA0	xxxx
ODCA	02C6	—	—	—	—	—	ODCA10	ODCA9	ODCA8	ODCA7	—	—	—	—	—	—	0000	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-34: PORTB REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISB	02C8	TRISB15	TRISB14	TRISB13	TRISB12	TRISB11	TRISB10	TRISB9	TRISB8	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	FFFF
PORTB	02CA	RB15	RB14	RB13	RB12	RB11	RB10	RB9	RB8	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx
LATB	02CC	LATB15	LATB14	LATB13	LATB12	LATB11	LATB10	LATB9	LATB8	LATB7	LATB6	LATB5	LATB4	LATB3	LATB2	LATB1	LATB0	xxxx
ODCB	02CE	—	—	—	—	ODCB11	ODCB10	ODCB9	ODCB8	ODCB7	ODCB6	ODCB5	—	—	—	—	0000	

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-35: PORTC REGISTER MAP FOR dsPIC33FJ128MC204/804, dsPIC33FJ64MC204/804 AND dsPIC33FJ32MC304**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISC	02D0	—	—	—	—	—	—	TRISC9	TRISC8	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	03FF
PORTC	02D2	—	—	—	—	—	—	RC9	RC8	RC7	RC6	RC5	RC4	RC3	RC2	RC1	RC0	xxxx
LATC	02D4	—	—	—	—	—	—	LATC9	LATC8	LATC7	LATC6	LATC5	LATC4	LATC3	LATC2	LATC1	LATC0	xxxx
ODCC	02D6	—	—	—	—	—	—	ODCC9	ODCC8	ODCC7	ODCC6	ODCC5	ODCC4	ODCC3	—	—	—	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-36: SYSTEM CONTROL REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RCON	0740	TRAPR	IOPUWR	—	—	—	—	CM	VREGS	EXTR	SWR	SWDTEN	WDTO	SLEEP	IDLE	BOR	POR	xxxx <sup>(1)</sup>
OSCCON	0742	—	COSC<2:0>			—	NOSC<2:0>			CLKLOCK	IOLOCK	LOCK	—	CF	—	LPOSCEN	OSWEN	0300 <sup>(2)</sup>
CLKDIV	0744	ROI	DOZE<2:0>			DOZEN	FRCDIV<2:0>			PLLPOST<1:0>		—	PLLPRE<4:0>					3040
PLLFBD	0746	—	—	—	—	—	—	—	—	PLLDIV<8:0>								0030
OSCTUN	0748	—	—	—	—	—	—	—	—	—	—	—	TUN<5:0>					0000
ACLKCON	074A	—	—	SELACLK	AOSCMD<1:0>		APSTSCLR<2:0>			ASRCSEL	—	—	—	—	—	—	—	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: The RCON register Reset values are dependent on the type of Reset.

2: The OSCCON register Reset values are dependent on the FOSC Configuration bits and the type of Reset.

**TABLE 4-37: SECURITY REGISTER MAP FOR dsPIC33FJ128MC204/804 AND dsPIC33FJ64MC204/804 ONLY**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
BSRAM	0750	—	—	—	—	—	—	—	—	—	—	—	—	—	IW_BSR	IR_BSR	RL_BSR	0000
SSRAM	0752	—	—	—	—	—	—	—	—	—	—	—	—	—	IW_SSR	IR_SSR	RL_SSR	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'.

**TABLE 4-38: NVM REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
NVMCON	0760	WR	WREN	WRERR	—	—	—	—	—	—	ERASE	—	—	NVMOP<3:0>				0000
NVMKEY	0766	—	—	—	—	—	—	—	—	NVMKEY<7:0>								0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'.

**TABLE 4-39: PMD REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMD1	0770	T5MD	T4MD	T3MD	T2MD	T1MD	QEI1MD	PWM1MD	—	I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	C1MD	AD1MD	0000
PMD2	0772	IC8MD	IC7MD	—	—	—	—	IC2MD	IC1MD	—	—	—	OC4MD	OC3MD	OC2MD	OC1MD	0000	
PMD3	0774	—	—	—	—	—	CMPMD	RTCCMD	PMPMD	CRCMD	DAC1MD	QEI2MD	PWM2MD	—	—	—	—	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'.

#### 4.2.7 SOFTWARE STACK

In addition to its use as a working register, the W15 register in the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices is also used as a software Stack Pointer. The Stack Pointer always points to the first available free word and grows from lower to higher addresses. It pre-decrements for stack pops and post-increments for stack pushes, as shown in [Figure 4-6](#). For a PC push during any `CALL` instruction, the MSb of the PC is zero-extended before the push, ensuring that the MSb is always clear.

**Note:** A PC push during exception processing concatenates the SRL register to the MSb of the PC prior to the push.

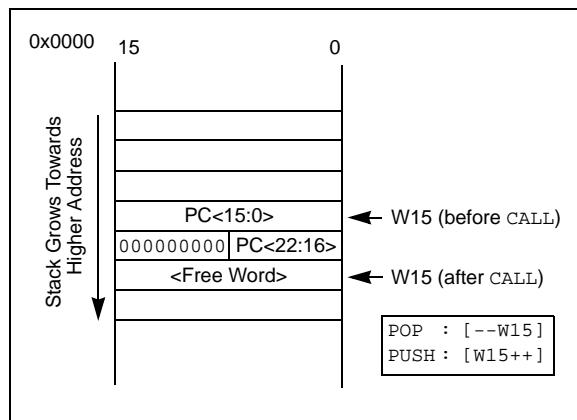
The Stack Pointer Limit register (SPLIM) associated with the Stack Pointer sets an upper address boundary for the stack. The SPLIM is uninitialized at Reset. As is the case for the Stack Pointer, the SPLIM<0> is forced to '0' because all stack operations must be word aligned.

Whenever an EA is generated using the W15 as a source or destination pointer, the resulting address is compared with the value in the SPLIM register. If the contents of the Stack Pointer (W15) and the SPLIM register are equal and a push operation is performed, a stack error trap does not occur. The stack error trap occurs on a subsequent push operation. For example, to cause a stack error trap when the stack grows beyond address 0x2000 in RAM, initialize the SPLIM with the value 0x1FFE.

Similarly, a Stack Pointer underflow (stack error) trap is generated when the Stack Pointer address is found to be less than 0x0800. This prevents the stack from interfering with the Special Function Register (SFR) space.

A write to the SPLIM register should not be immediately followed by an indirect read operation using W15.

**FIGURE 4-6: CALL STACK FRAME**



#### 4.2.8 DATA RAM PROTECTION FEATURE

The dsPIC33F product family supports Data RAM protection features that enable segments of RAM to be protected when used in conjunction with Boot and Secure Code Segment Security. The BSRAM (Secure RAM segment for BS) is accessible only from the Boot Segment Flash code when enabled. The SSRAM (Secure RAM segment for RAM) is accessible only from the Secure Segment Flash code when enabled. See [Table 4-1](#) for an overview of the BSRAM and SSRAM SFRs.

### 4.3 Instruction Addressing Modes

The addressing modes shown in [Table 4-40](#) form the basis of the addressing modes optimized to support the specific features of individual instructions. The addressing modes provided in the MAC class of instructions differ from those in the other instruction types.

#### 4.3.1 FILE REGISTER INSTRUCTIONS

Most file register instructions use a 13-bit address field (f) to directly address data present in the first 8192 bytes of data memory (near data space). Most file register instructions employ a working register, W0, which is denoted as WREG in these instructions. The destination is typically either the same file register or WREG (with the exception of the `MUL` instruction), which writes the result to a register or register pair. The `MOV` instruction allows additional flexibility and can access the entire data space.

#### 4.3.2 MCU INSTRUCTIONS

The three-operand MCU instructions are of the form:

Operand 3 = Operand 1 <function> Operand 2  
where:

Operand 1 is always a working register (that is, the addressing mode can only be register direct), which is referred to as Wb.

Operand 2 can be a W register, fetched from data memory, or a 5-bit literal. The result location can be either a W register or a data memory location. The following addressing modes are supported by MCU instructions:

- Register Direct
- Register Indirect
- Register Indirect Post-Modified
- Register Indirect Pre-Modified
- 5-bit or 10-bit Literal

**Note:** Not all instructions support all the addressing modes listed above. Individual instructions can support different subsets of these addressing modes.

**TABLE 4-40: FUNDAMENTAL ADDRESSING MODES SUPPORTED**

Addressing Mode	Description
File Register Direct	The address of the file register is specified explicitly.
Register Direct	The contents of a register are accessed directly.
Register Indirect	The contents of Wn forms the Effective Address (EA).
Register Indirect Post-Modified	The contents of Wn forms the EA. Wn is post-modified (incremented or decremented) by a constant value.
Register Indirect Pre-Modified	Wn is pre-modified (incremented or decremented) by a signed constant value to form the EA.
Register Indirect with Register Offset (Register Indexed)	The sum of Wn and Wb forms the EA.
Register Indirect with Literal Offset	The sum of Wn and a literal forms the EA.

#### 4.3.3 MOVE AND ACCUMULATOR INSTRUCTIONS

Move instructions and the DSP accumulator class of instructions provide a greater degree of addressing flexibility than any other instructions. In addition to the addressing modes supported by most MCU instructions, move and accumulator instructions also support Register Indirect with Register Offset Addressing mode, also referred to as Register Indexed mode.

**Note:** For the MOV instructions, the addressing mode specified in the instruction can differ for the source and destination EA. However, the 4-bit Wb (Register Offset) field is shared by both source and destination (but typically only used by one).

In summary, the following addressing modes are supported by move and accumulator instructions:

- Register Direct
- Register Indirect
- Register Indirect Post-Modified
- Register Indirect Pre-Modified
- Register Indirect with Register Offset (Indexed)
- Register Indirect with Literal Offset
- 8-bit Literal
- 16-bit Literal

**Note:** Not all instructions support all the addressing modes listed above. Individual instructions may support different subsets of these addressing modes.

#### 4.3.4 MAC INSTRUCTIONS

The dual source operand DSP instructions (CLR, ED, EDAC, MAC, MPY, MPY.N, MOVSAC and MSC), also referred to as MAC instructions, use a simplified set of addressing modes to allow the user application to effectively manipulate the data pointers through register indirect tables.

The two-source operand prefetch registers must be members of the set {W8, W9, W10, W11}. For data reads, W8 and W9 are always directed to the X RAGU, and W10 and W11 are always directed to the Y AGU. The effective addresses generated (before and after modification) must, therefore, be valid addresses within X data space for W8 and W9 and Y data space for W10 and W11.

**Note:** Register Indirect with Register Offset Addressing mode is available only for W9 (in X space) and W11 (in Y space).

In summary, the following addressing modes are supported by the MAC class of instructions:

- Register Indirect
- Register Indirect Post-Modified by 2
- Register Indirect Post-Modified by 4
- Register Indirect Post-Modified by 6
- Register Indirect with Register Offset (Indexed)

#### 4.3.5 OTHER INSTRUCTIONS

Apart from the addressing modes outlined previously, some instructions use literal constants of various sizes. For example, BRA (branch) instructions use 16-bit signed literals to specify the branch destination directly, whereas, the DISI instruction uses a 14-bit unsigned literal field. In some instructions, such as ADD Acc, the source of an operand or result is implied by the opcode itself. Certain operations, such as NOP, do not have any operands.

#### 4.4 Modulo Addressing

Modulo Addressing mode is a method of providing an automated means to support circular data buffers using hardware. The objective is to remove the need for software to perform data address boundary checks when executing tightly looped code, as is typical in many DSP algorithms.

Modulo Addressing can operate in either data or program space (because the data pointer mechanism is essentially the same for both). One circular buffer can be supported in each of the X (which also provides the pointers into program space) and Y data spaces. Modulo Addressing can operate on any W register pointer. However, it is not advisable to use W14 or W15 for Modulo Addressing as these two registers are used as the Stack Frame Pointer and Stack Pointer, respectively.

In general, any particular circular buffer can be configured to operate in only one direction as there are certain restrictions on the buffer start address (for incrementing buffers), or end address (for decrementing buffers), based upon the direction of the buffer.

The only exception to the usage restrictions is for buffers that have a power-of-two length. As these buffers satisfy the start and end address criteria, they can operate in a bidirectional mode (that is, address boundary checks are performed on both the lower and upper address boundaries).

##### 4.4.1 START AND END ADDRESS

The Modulo Addressing scheme requires that a starting and ending address be specified and loaded into the 16-bit Modulo Buffer Address registers: XMDSRT, XMODEND, YMDSRT and YMODEND (see [Table 4-1](#)).

**Note:** Y space Modulo Addressing EA calculations assume word-sized data (LSb of every EA is always clear).

The length of a circular buffer is not directly specified. It is determined by the difference between the corresponding start and end addresses. The maximum possible length of the circular buffer is 32K words (64 Kbytes).

##### 4.4.2 W ADDRESS REGISTER SELECTION

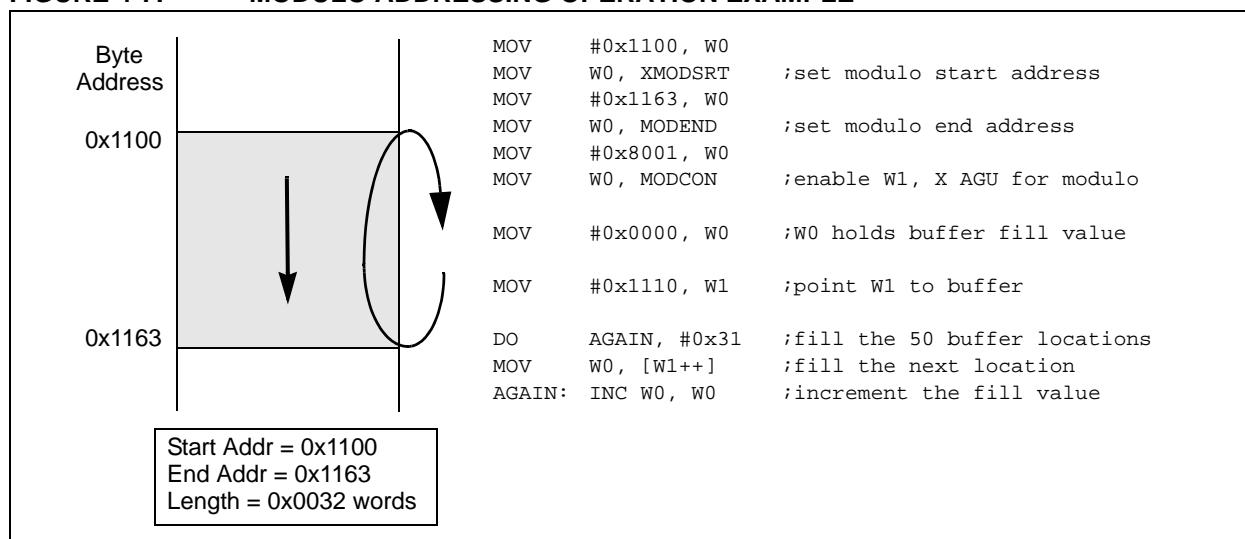
The Modulo and Bit-Reversed Addressing Control register, MODCON<15:0>, contains enable flags as well as a W register field to specify the W Address registers. The XWM and YWM fields select the registers that operate with Modulo Addressing:

- If XWM = 15, X RAGU and X WAGU Modulo Addressing is disabled
- If YWM = 15, Y AGU Modulo Addressing is disabled

The X Address Space Pointer W register (XWM), to which Modulo Addressing is to be applied, is stored in MODCON<3:0> (see [Table 4-1](#)). Modulo Addressing is enabled for X data space when XWM is set to any value other than '15' and the XMODEN bit is set at MODCON<15>.

The Y Address Space Pointer W register (YWM) to which Modulo Addressing is to be applied is stored in MODCON<7:4>. Modulo Addressing is enabled for Y data space when YWM is set to any value other than '15' and the YMODEN bit is set at MODCON<14>.

**FIGURE 4-7: MODULO ADDRESSING OPERATION EXAMPLE**



#### 4.4.3 MODULO ADDRESSING APPLICABILITY

Modulo Addressing can be applied to the Effective Address (EA) calculation associated with any W register. Address boundaries check for addresses equal to:

- The upper boundary addresses for incrementing buffers
- The lower boundary addresses for decrementing buffers

It is important to realize that the address boundaries check for addresses less than or greater than the upper (for incrementing buffers) and lower (for decrementing buffers) boundary addresses (not just equal to). Address changes can, therefore, jump beyond boundaries and still be adjusted correctly.

**Note:** The modulo corrected effective address is written back to the register only when Pre-Modify or Post-Modify Addressing mode is used to compute the effective address. When an address offset (such as [W7 + W2]) is used, Modulo Address correction is performed, but the contents of the register remain unchanged.

The XB<14:0> bits is the Bit-Reversed Address modifier, or pivot point, which is typically a constant. In the case of an FFT computation, its value is equal to half of the FFT data buffer size.

**Note:** All bit-reversed EA calculations assume word-sized data (LSb of every EA is always clear). The XB value is scaled accordingly to generate compatible (byte) addresses.

When enabled, Bit-Reversed Addressing is executed only for Register Indirect with Pre-Increment or Post-Increment Addressing and word-sized data writes. It does not function for any other addressing mode or for byte-sized data, and normal addresses are generated instead. When Bit-Reversed Addressing is active, the W Address Pointer is always added to the address modifier (XB), and the offset associated with the Register Indirect Addressing mode is ignored. In addition, as word-sized data is a requirement, the LSb of the EA is ignored (and always clear).

**Note:** The Modulo Addressing and Bit-Reversed Addressing should not be enabled together. If an application attempts to do so, Bit-Reversed Addressing assumes priority when active for the X WAGU and X WAGU, Modulo Addressing is disabled. However, Modulo Addressing continues to function in the X RAGU.

### 4.5 Bit-Reversed Addressing

Bit-Reversed Addressing mode is intended to simplify data reordering for radix-2 FFT algorithms. It is supported by the X AGU for data writes only.

The modifier, which can be a constant value or register contents, is regarded as having its bit order reversed. The address source and destination are kept in normal order. Therefore, the only operand requiring reversal is the modifier.

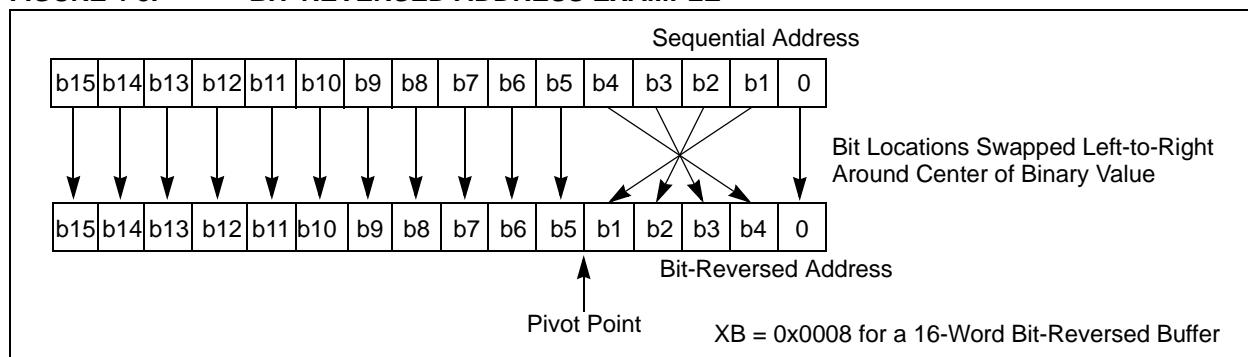
#### 4.5.1 BIT-REVERSED ADDRESSING IMPLEMENTATION

Bit-Reversed Addressing mode is enabled in any of these situations:

- The BWM bits (W register selection) in the MODCON register are any value other than '15' (the stack cannot be accessed using Bit-Reversed Addressing)
- The BREN bit is set in the XBREV register
- The addressing mode used is Register Indirect with Pre-Increment or Post-Increment

If the length of a bit-reversed buffer is  $M = 2^N$  bytes, the last 'N' bits of the data buffer start address must be zeros.

If Bit-Reversed Addressing has already been enabled by setting the BREN bit (XBREV<15>), a write to the XBREV register should not be immediately followed by an indirect read operation using the W register that has been designated as the bit-reversed pointer.

**FIGURE 4-8: BIT-REVERSED ADDRESS EXAMPLE****TABLE 4-41: BIT-REVERSED ADDRESS SEQUENCE (16-ENTRY)**

Normal Address					Bit-Reversed Address				
A3	A2	A1	A0	Decimal	A3	A2	A1	A0	Decimal
0	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	0	0	0	8
0	0	1	0	2	0	1	0	0	4
0	0	1	1	3	1	1	0	0	12
0	1	0	0	4	0	0	1	0	2
0	1	0	1	5	1	0	1	0	10
0	1	1	0	6	0	1	1	0	6
0	1	1	1	7	1	1	1	0	14
1	0	0	0	8	0	0	0	1	1
1	0	0	1	9	1	0	0	1	9
1	0	1	0	10	0	1	0	1	5
1	0	1	1	11	1	1	0	1	13
1	1	0	0	12	0	0	1	1	3
1	1	0	1	13	1	0	1	1	11
1	1	1	0	14	0	1	1	1	7
1	1	1	1	15	1	1	1	1	15

## 4.6 Interfacing Program and Data Memory Spaces

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 architecture uses a 24-bit-wide program space and a 16-bit-wide data space. The architecture is a modified Harvard scheme, meaning that data can also be present in the program space. To use this data successfully, it must be accessed in a way that preserves the alignment of information in both spaces.

Aside from normal execution, the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 architecture provides two methods by which program space can be accessed during operation:

- Using table instructions to access individual bytes or words anywhere in the program space
- Remapping a portion of the program space into the data space (Program Space Visibility)

Table instructions allow an application to read or write to small areas of the program memory. This capability makes the method ideal for accessing data tables that need to be updated periodically. It also allows access to all bytes of the program word. The remapping method allows an application to access a large block of data on a read-only basis, which is ideal for look-ups from a large table of static data. The application can only access the least significant word of the program word.

### 4.6.1 ADDRESSING PROGRAM SPACE

As the address ranges for the data and program spaces are 16 and 24 bits, respectively, a method is needed to create a 23-bit or 24-bit program address from 16-bit data registers. The solution depends on the interface method to be used.

For table operations, the 8-bit Table Page register (TBLPAG) is used to define a 32K word region within the program space. This is concatenated with a 16-bit EA to arrive at a full 24-bit program space address. In this format, the Most Significant bit of TBLPAG is used to determine if the operation occurs in the user memory (TBLPAG<7> = 0) or the configuration memory (TBLPAG<7> = 1).

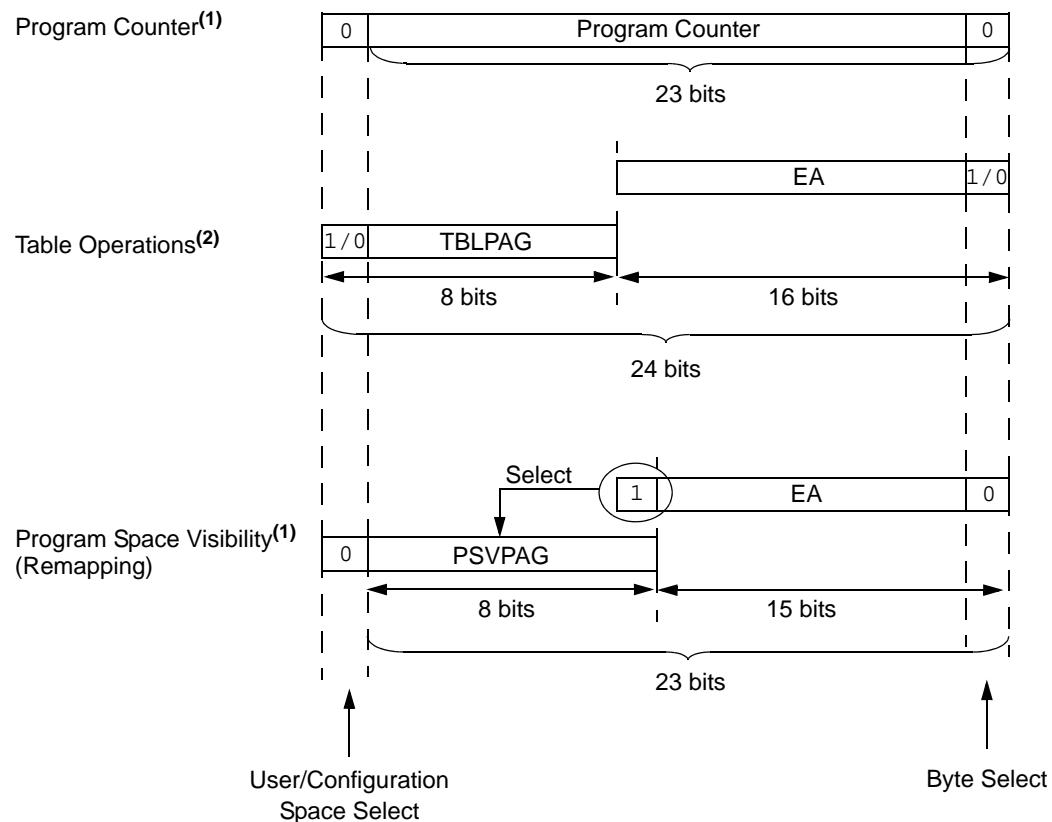
For remapping operations, the 8-bit Program Space Visibility register (PSVPAG) is used to define a 16K word page in the program space. When the Most Significant bit of the EA is '1', the PSVPAG is concatenated with the lower 15 bits of the EA to form a 23-bit program space address. Unlike table operations, this limits remapping operations strictly to the user memory area.

Table 4-42 and Figure 4-9 show how the program EA is created for table operations and remapping accesses from the data EA. Here, P<23:0> refers to a program space word, and D<15:0> refers to a data space word.

**TABLE 4-42: PROGRAM SPACE ADDRESS CONSTRUCTION**

Access Type	Access Space	Program Space Address						
		<23>	<22:16>	<15>	<14:1>	<0>		
Instruction Access (Code Execution)	User	0	PC<22:1>			0		
		0xx xxxx xxxx xxxx xxxx xxxx xxx0						
TBLRD/TBLWT (Byte/Word Read/Write)	User	TBLPAG<7:0>		Data EA<15:0>				
		0xxx xxxx xxxx xxxx xxxx xxxx						
Program Space Visibility (Block Remap/Read)	User	TBLPAG<7:0>		Data EA<15:0>				
		1xxx xxxx xxxx xxxx xxxx xxxx						
		0	PSVPAG<7:0>		Data EA<14:0> <sup>(1)</sup>			
		0	xxxx xxxx		xxx xxxx xxxx xxxx			

**Note 1:** Data EA<15> is always '1' in this case, but is not used in calculating the program space address. Bit 15 of the address is PSVPAG<0>.

**FIGURE 4-9: DATA ACCESS FROM PROGRAM SPACE ADDRESS GENERATION**

**Note 1:** The Least Significant bit (LSb) of program space addresses is always fixed as '0' to maintain word alignment of data in the program and data spaces.

**2:** Table operations are not required to be word aligned. Table read operations are permitted in the configuration memory space.

#### 4.6.2 DATA ACCESS FROM PROGRAM MEMORY USING TABLE INSTRUCTIONS

The TBLRDL and TBLWTL instructions offer a direct method of reading or writing the lower word of any address within the program space without going through data space. The TBLRDH and TBLWTH instructions are the only method to read or write the upper 8 bits of a program space word as data.

The PC is incremented by two for each successive 24-bit program word. This allows program memory addresses to directly map to data space addresses. Program memory can thus be regarded as two 16-bit-wide word address spaces, residing side by side, each with the same address range. The TBLRDL and TBLWTL access the space that contains the least significant data word. The TBLRDH and TBLWTH access the space that contains the upper data byte.

Two table instructions are provided to move byte or word-sized (16-bit) data to and from program space. Both function as either byte or word operations.

- **TBLRDL (Table Read Low):**
  - In Word mode, this instruction maps the lower word of the program space location ( $P<15:0>$ ) to a data address ( $D<15:0>$ ).

- In Byte mode, either the upper or lower byte of the lower program word is mapped to the lower byte of a data address. The upper byte is selected when Byte Select is '1'; the lower byte is selected when it is '0'.

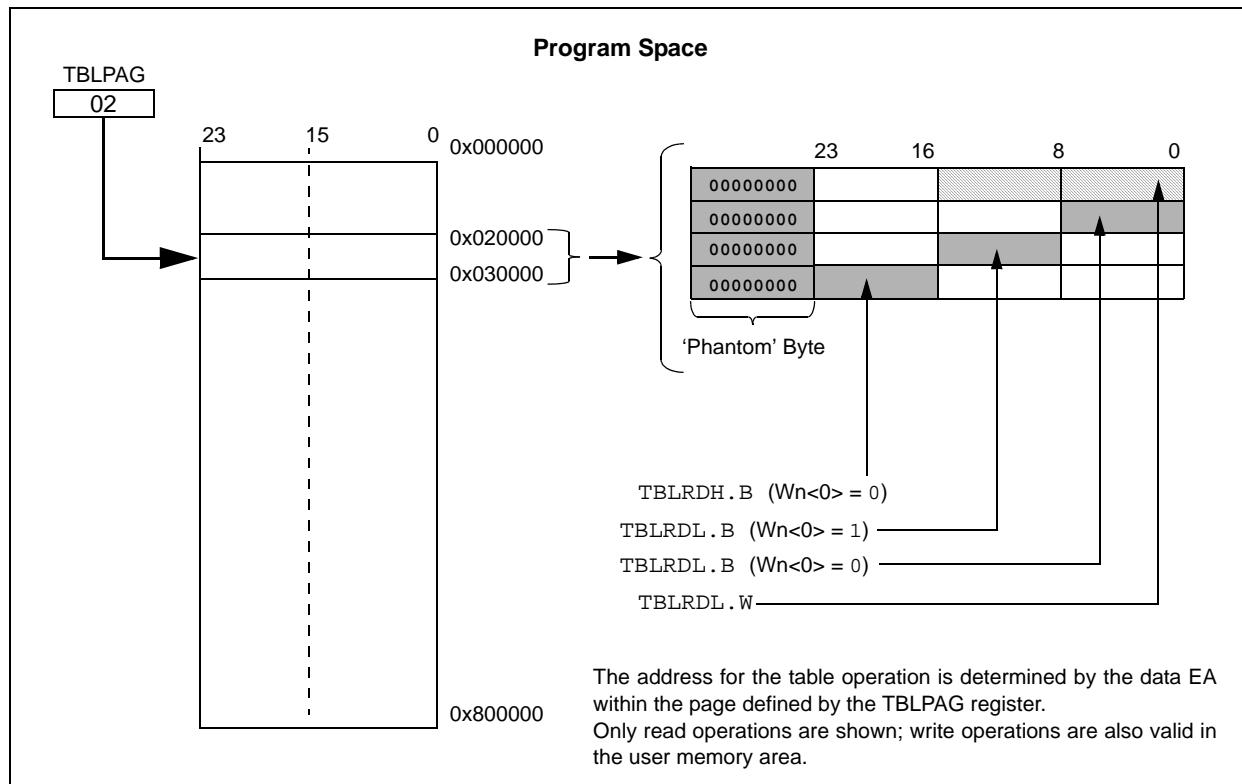
- **TBLRDH (Table Read High):**

- In Word mode, this instruction maps the entire upper word of a program address ( $P<23:16>$ ) to a data address. The phantom byte ( $D<15:8>$ ), is always '0'.
- In Byte mode, this instruction maps the upper or lower byte of the program word to  $D<7:0>$  of the data address, in the TBLRDL instruction. The data is always '0' when the upper phantom byte is selected (Byte Select = 1).

In a similar fashion, two table instructions, TBLWTH and TBLWTL, are used to write individual bytes or words to a program space address. The details of their operation are explained in [Section 5.0 “Flash Program Memory”](#).

For all table operations, the area of program memory space to be accessed is determined by the Table Page register (TBLPAG). The TBLPAG covers the entire program memory space of the device, including user application and configuration spaces. When TBLPAG $<7>$  = 0, the table page is located in the user memory space. When TBLPAG $<7>$  = 1, the page is located in configuration space.

**FIGURE 4-10: ACCESSING PROGRAM MEMORY WITH TABLE INSTRUCTIONS**



#### 4.6.3 READING DATA FROM PROGRAM MEMORY USING PROGRAM SPACE VISIBILITY

The upper 32 Kbytes of data space may optionally be mapped into any 16K word page of the program space. This option provides transparent access to stored constant data from the data space without the need to use special instructions (such as TBLRDH).

Program space access through the data space occurs if the Most Significant bit of the data space EA is '1' and program space visibility is enabled by setting the PSV bit in the Core Control register (CORCON<2>). The location of the program memory space to be mapped into the data space is determined by the Program Space Visibility Page register (PSVPAG). This 8-bit register defines any one of 256 possible pages of 16K words in program space. In effect, PSVPAG functions as the upper 8 bits of the program memory address, with the 15 bits of the EA functioning as the lower bits. By incrementing the PC by 2 for each program memory word, the lower 15 bits of data space addresses directly map to the lower 15 bits in the corresponding program space addresses.

Data reads to this area add a cycle to the instruction being executed, since two program memory fetches are required.

Although each data space address 0x8000 and higher maps directly into a corresponding program memory address (see [Figure 4-11](#)), only the lower 16 bits of the

24-bit program word are used to contain the data. The upper 8 bits of any program space location used as data should be programmed with '1111 1111' or '0000 0000' to force a NOP. This prevents possible issues should the area of code ever be accidentally executed.

**Note:** PSV access is temporarily disabled during table reads/writes.

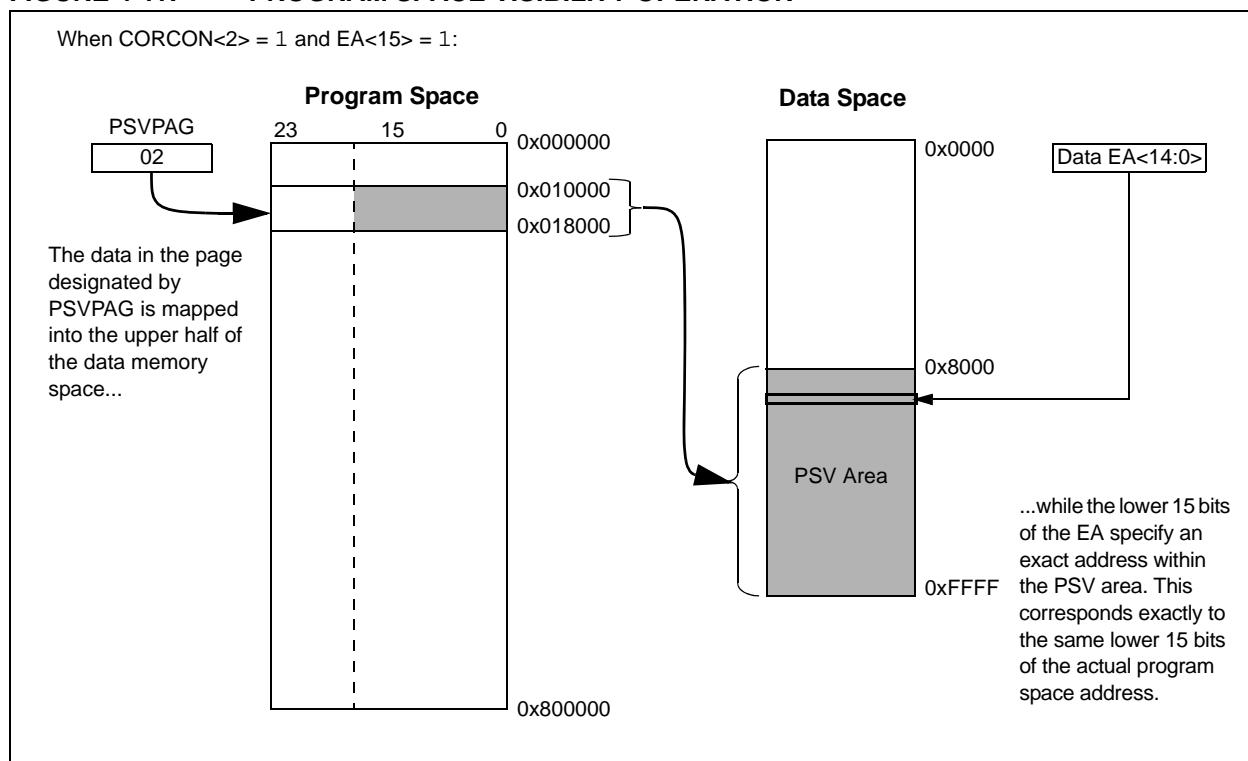
For operations that use PSV and are executed outside a REPEAT loop, the MOV and MOV.D instructions require one instruction cycle in addition to the specified execution time. All other instructions require two instruction cycles in addition to the specified execution time.

For operations that use PSV, and are executed inside a REPEAT loop, these instances require two instruction cycles in addition to the specified execution time of the instruction:

- Execution in the first iteration
- Execution in the last iteration
- Execution prior to exiting the loop due to an interrupt
- Execution upon re-entering the loop after an interrupt is serviced

Any other iteration of the REPEAT loop allows the instruction using PSV to access data, to execute in a single cycle.

**FIGURE 4-11: PROGRAM SPACE VISIBILITY OPERATION**



**NOTES:**

## 5.0 FLASH PROGRAM MEMORY

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 5. "Flash Programming"** (DS70191) of the "dsPIC33F/PIC24H Family Reference Manual", which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices contain internal Flash program memory for storing and executing application code. The memory is readable, writable and erasable during normal operation over the entire VDD range.

Flash memory can be programmed in two ways:

- In-Circuit Serial Programming™ (ICSP™) programming capability
- Run-Time Self-Programming (RTSP)

ICSP allows a dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 device to be serially programmed while in the end application circuit. This is done with two lines for

programming clock and programming data (one of the alternate programming pin pairs: PGECx/PGEDx), and three other lines for power (VDD), ground (Vss) and Master Clear (MCLR). This allows customers to manufacture boards with unprogrammed devices and then program the digital signal controller just before shipping the product. This also allows the most recent firmware or a custom firmware to be programmed.

RTSP is accomplished using TBLRD (table read) and TBLWT (table write) instructions. With RTSP, the user application can write program memory data either in blocks or rows of 64 instructions (192 bytes) at a time or a single program memory word, and erase program memory in blocks or pages of 512 instructions (1536 bytes) at a time.

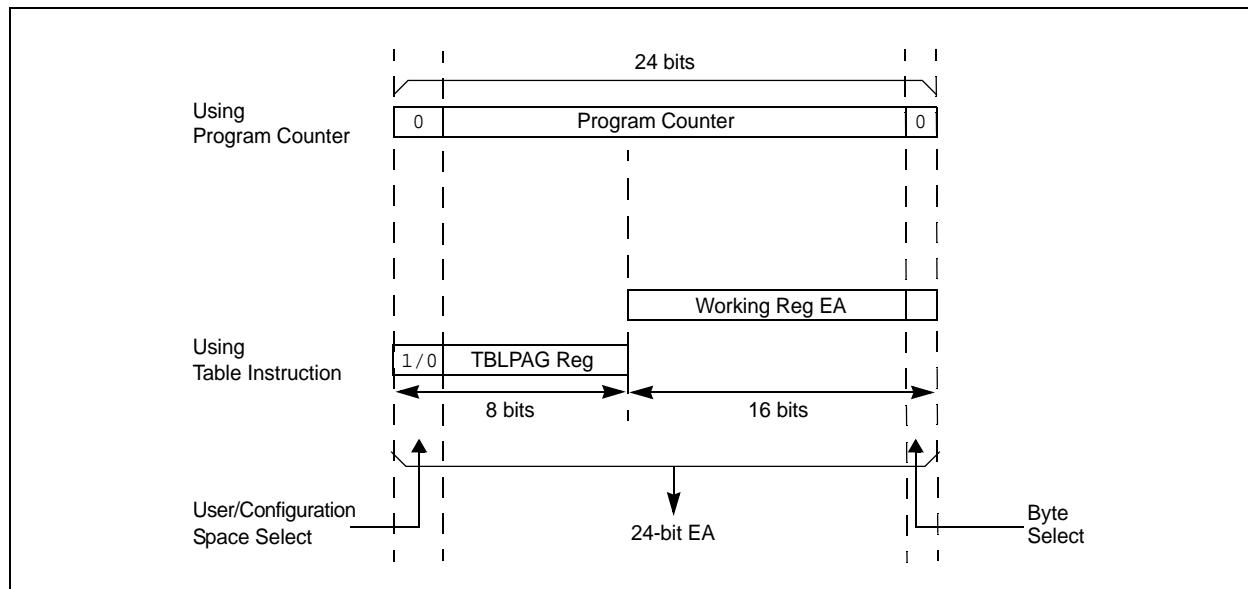
### 5.1 Table Instructions and Flash Programming

Regardless of the method used, all programming of Flash memory is done with the table read and table write instructions. These allow direct read and write access to the program memory space from the data memory while the device is in normal operating mode. The 24-bit target address in the program memory is formed using bits <7:0> of the TBLPAG register and the Effective Address (EA) from a W register specified in the table instruction, as shown in **Figure 5-1**.

The TBLRDL and the TBLWTL instructions are used to read or write to bits <15:0> of program memory. The TBLRDL and TBLWTL instructions can access program memory in both Word and Byte modes.

The TBLRDH and TBLWTH instructions are used to read or write to bits <23:16> of program memory. The TBLRDH and TBLWTH can also access program memory in Word or Byte mode.

**FIGURE 5-1: ADDRESSING FOR TABLE REGISTERS**



## 5.2 RTSP Operation

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 Flash program memory array is organized into rows of 64 instructions or 192 bytes. RTSP allows the user application to erase a page of memory, which consists of eight rows (512 instructions) at a time, and to program one row or one word at a time. [Table 31-12](#) shows typical erase and programming times. The 8-row erase pages and single row write rows are edge-aligned from the beginning of program memory, on boundaries of 1536 bytes and 192 bytes, respectively.

The program memory implements holding buffers that can contain 64 instructions of programming data. Prior to the actual programming operation, the write data must be loaded into the buffers sequentially. The instruction words loaded must always be from a group of 64 boundary.

The basic sequence for RTSP programming is to set up a Table Pointer, then do a series of TBLWT instructions to load the buffers. Programming is performed by setting the control bits in the NVMCON register. A total of 64 TBLWTL and TBLWTH instructions are required to load the instructions.

All of the table write operations are single-word writes (two instruction cycles) because only the buffers are written. A programming cycle is required for programming each row.

## 5.3 Programming Operations

A complete programming sequence is necessary for programming or erasing the internal Flash in RTSP mode. The processor stalls (waits) until the programming operation is finished.

The programming time depends on the FRC accuracy (see [Table 31-19](#)) and the value of the FRC Oscillator Tuning register (see [Register 9-4](#)). Use the following formula to calculate the minimum and maximum values for the Row Write Time, Page Erase Time, and Word Write Cycle Time parameters (see [Table 31-12](#)).

### EQUATION 5-1: PROGRAMMING TIME

$$T = \frac{1}{7.37 \text{ MHz} \times (\text{FRC Accuracy})\% \times (\text{FRC Tuning})\%}$$

For example, if the device is operating at +125°C, the FRC accuracy will be  $\pm 5\%$ . If the TUN<5:0> bits (see [Register 9-4](#)) are set to 'b11111, the minimum row write time is equal to [Equation 5-2](#).

### EQUATION 5-2: MINIMUM ROW WRITE TIME

$$T_{RW} = \frac{11064 \text{ Cycles}}{7.37 \text{ MHz} \times (1 + 0.05) \times (1 - 0.00375)} = 1.435ms$$

The maximum row write time is equal to [Equation 5-3](#).

### EQUATION 5-3: MAXIMUM ROW WRITE TIME

$$T_{RW} = \frac{11064 \text{ Cycles}}{7.37 \text{ MHz} \times (1 - 0.05) \times (1 - 0.00375)} = 1.586ms$$

Setting the WR bit (NVMCON<15>) starts the operation, and the WR bit is automatically cleared when the operation is finished.

## 5.4 Control Registers

Two SFRs are used to read and write the program Flash memory:

- NVMCON: The NVMCON register ([Register 5-1](#)) controls which blocks are to be erased, which memory type is to be programmed and the start of the programming cycle.
- NVMKEY: NVMKEY ([Register 5-2](#)) is a write-only register that is used for write protection. To start a programming or erase sequence, the user application must consecutively write 0x55 and 0xAA to the NVMKEY register. Refer to [Section 5.3 "Programming Operations"](#) for further details.

**REGISTER 5-1: NVMCON: FLASH MEMORY CONTROL REGISTER**

R/SO-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	U-0	U-0	U-0	U-0	U-0
WR	WREN	WRERR	—	—	—	—	—
bit 15	bit 8						

U-0	R/W-0 <sup>(1)</sup>	U-0	U-0	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>
—	ERASE	—	—	NVMOP<3:0> <sup>(2)</sup>			
bit 7	bit 0						

**Legend:**

R = Readable bit

-n = Value at POR

SO = Satisfiable only bit

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **WR:** Write Control bit  
   1 = Initiates a Flash memory program or erase operation. The operation is self-timed and the bit is cleared by hardware once operation is complete  
   0 = Program or erase operation is complete and inactive
- bit 14      **WREN:** Write Enable bit  
   1 = Enable Flash program/erase operations  
   0 = Inhibit Flash program/erase operations
- bit 13      **WRERR:** Write Sequence Error Flag bit  
   1 = An improper program or erase sequence attempt or termination has occurred (bit is set automatically on any set attempt of the WR bit)  
   0 = The program or erase operation completed normally
- bit 12-7     **Unimplemented:** Read as '0'
- bit 6        **ERASE:** Erase/Program Enable bit  
   1 = Perform the erase operation specified by the NVMOP<3:0> bits on the next WR command  
   0 = Perform the program operation specified by the NVMOP<3:0> bits on the next WR command
- bit 5-4      **Unimplemented:** Read as '0'
- bit 3-0      **NVMOP<3:0>:** NVM Operation Select bits<sup>(2)</sup>
- If ERASE = 1:  
   1111 = Memory bulk erase operation  
   1110 = Reserved  
   1101 = Erase General Segment  
   1100 = Erase Secure Segment  
   1011 = Reserved  
   0011 = No operation  
   0010 = Memory page erase operation  
   0001 = No operation  
   0000 = Erase a single Configuration register byte
- If ERASE = 0:  
   1111 = No operation  
   1110 = Reserved  
   1101 = No operation  
   1100 = No operation  
   1011 = Reserved  
   0011 = Memory word program operation  
   0010 = No operation  
   0001 = Memory row program operation  
   0000 = Program a single Configuration register byte

**Note 1:** These bits can only be reset on POR.**2:** All other combinations of NVMOP<3:0> are unimplemented.

**REGISTER 5-2: NVMKEY: NONVOLATILE MEMORY KEY REGISTER**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

W-0	W-0	W-0	W-0	W-0	W-0	W-0	W-0
NVMKEY<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8      **Unimplemented:** Read as '0'

bit 7-0      **NVMKEY<7:0>:** Key Register (write-only) bits

#### 5.4.1 PROGRAMMING ALGORITHM FOR FLASH PROGRAM MEMORY

Programmers can program one row of program Flash memory at a time. To do this, it is necessary to erase the 8-row erase page that contains the desired row. The general process is:

1. Read eight rows of program memory (512 instructions) and store in data RAM.
2. Update the program data in RAM with the desired new data.
3. Erase the block (see [Example 5-1](#)):
  - a) Set the NVMOP bits (NVMCON<3:0>) to '0010' to configure for block erase. Set the ERASE (NVMCON<6>) and WREN (NVMCON<14>) bits.
  - b) Write the starting address of the page to be erased into the TBLPAG and W registers.
  - c) Write 0x55 to NVMKEY.
  - d) Write 0xAA to NVMKEY.
  - e) Set the WR bit (NVMCON<15>). The erase cycle begins and the CPU stalls for the duration of the erase cycle. When the erase is done, the WR bit is cleared automatically.

4. Write the first 64 instructions from data RAM into the program memory buffers (see [Example 5-2](#)).
5. Write the program block to Flash memory:
  - a) Set the NVMOP bits to '0001' to configure for row programming. Clear the ERASE bit and set the WREN bit.
  - b) Write 0x55 to NVMKEY.
  - c) Write 0xAA to NVMKEY.
  - d) Set the WR bit. The programming cycle begins and the CPU stalls for the duration of the write cycle. When the write to Flash memory is done, the WR bit is cleared automatically.
6. Repeat steps 4 and 5, using the next available 64 instructions from the block in data RAM by incrementing the value in TBLPAG, until all 512 instructions are written back to Flash memory.

For protection against accidental operations, the write initiate sequence for NVMKEY must be used to allow any erase or program operation to proceed. After the programming command has been executed, the user application must wait for the programming time until programming is complete. The two instructions following the start of the programming sequence should be NOPs, as shown in [Example 5-3](#).

#### EXAMPLE 5-1: ERASING A PROGRAM MEMORY PAGE

```
; Set up NVMCON for block erase operation
    MOV    #0x4042, W0
    MOV    W0, NVMCON
; Initialize NVMCON

; Init pointer to row to be ERASED
    MOV    #tblpage(PROG_ADDR), W0
    MOV    W0, TBLPAG
    MOV    #tbloffset(PROG_ADDR), W0
    TBLWTL W0, [W0]
    DISI   #5
; Initialize PM Page Boundary SFR
; Initialize in-page EA[15:0] pointer
; Set base address of erase block
; Block all interrupts with priority < 7
; for next 5 instructions

    MOV    #0x55, W0
    MOV    W0, NVMKEY
; Write the 55 key
    MOV    #0xAA, W1
    MOV    W1, NVMKEY
; Write the AA key
    BSET  NVMCON, #WR
; Start the erase sequence
    NOP
; Insert two NOPs after the erase
    NOP
; command is asserted
```

**EXAMPLE 5-2: LOADING THE WRITE BUFFERS**

```
; Set up NVMCON for row programming operations
    MOV      #0x4001, W0          ;
    MOV      W0, NVMCON           ; Initialize NVMCON
; Set up a pointer to the first program memory location to be written
; program memory selected, and writes enabled
    MOV      #0x0000, W0          ;
    MOV      W0, TBLPAG            ; Initialize PM Page Boundary SFR
    MOV      #0x6000, W0          ; An example program memory address
; Perform the TBLWT instructions to write the latches
; 0th_program_word
    MOV      #LOW_WORD_0, W2        ;
    MOV      #HIGH_BYT_0, W3        ;
    TBLWTL  W2, [W0]              ; Write PM low word into program latch
    TBLWTH  W3, [W0++]             ; Write PM high byte into program latch
; 1st_program_word
    MOV      #LOW_WORD_1, W2        ;
    MOV      #HIGH_BYT_1, W3        ;
    TBLWTL  W2, [W0]              ; Write PM low word into program latch
    TBLWTH  W3, [W0++]             ; Write PM high byte into program latch
; 2nd_program_word
    MOV      #LOW_WORD_2, W2        ;
    MOV      #HIGH_BYT_2, W3        ;
    TBLWTL  W2, [W0]              ; Write PM low word into program latch
    TBLWTH  W3, [W0++]             ; Write PM high byte into program latch
    .
    .
    .
; 63rd_program_word
    MOV      #LOW_WORD_31, W2       ;
    MOV      #HIGH_BYT_31, W3       ;
    TBLWTL  W2, [W0]              ; Write PM low word into program latch
    TBLWTH  W3, [W0++]             ; Write PM high byte into program latch
```

**EXAMPLE 5-3: INITIATING A PROGRAMMING SEQUENCE**

```
DISI    #5                  ; Block all interrupts with priority < 7
                                ; for next 5 instructions
    MOV      #0x55, W0
    MOV      W0, NVMKEY           ; Write the 55 key
    MOV      #0xAA, W1
    MOV      W1, NVMKEY           ; Write the AA key
    BSET   NVMCON, #WR           ; Start the erase sequence
    NOP
    NOP                         ; Insert two NOPs after the
                                ; erase command is asserted
```

## 6.0 RESETS

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 8. "Reset"** (DS70192) of the "dsPIC33F/PIC24H Family Reference Manual", which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

- 2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The Reset module combines all reset sources and controls the device Master Reset Signal, SYSRST. The following is a list of device Reset sources:

- POR: Power-on Reset
- BOR: Brown-out Reset
- MCLR: Master Clear Pin Reset
- SWR: RESET Instruction
- WDTO: Watchdog Timer Reset
- CM: Configuration Mismatch Reset
- TRAPR: Trap Conflict Reset
- IOPUWR: Illegal Condition Device Reset
  - Illegal Opcode Reset
  - Uninitialized W Register Reset
  - Security Reset

A simplified block diagram of the Reset module is shown in [Figure 6-1](#).

Any active source of Reset will make the SYSRST signal active. On system Reset, some of the registers associated with the CPU and peripherals are forced to a known Reset state and some are unaffected.

**Note:** Refer to the specific peripheral section or [Section 3.0 "CPU"](#) in this data sheet for register Reset states.

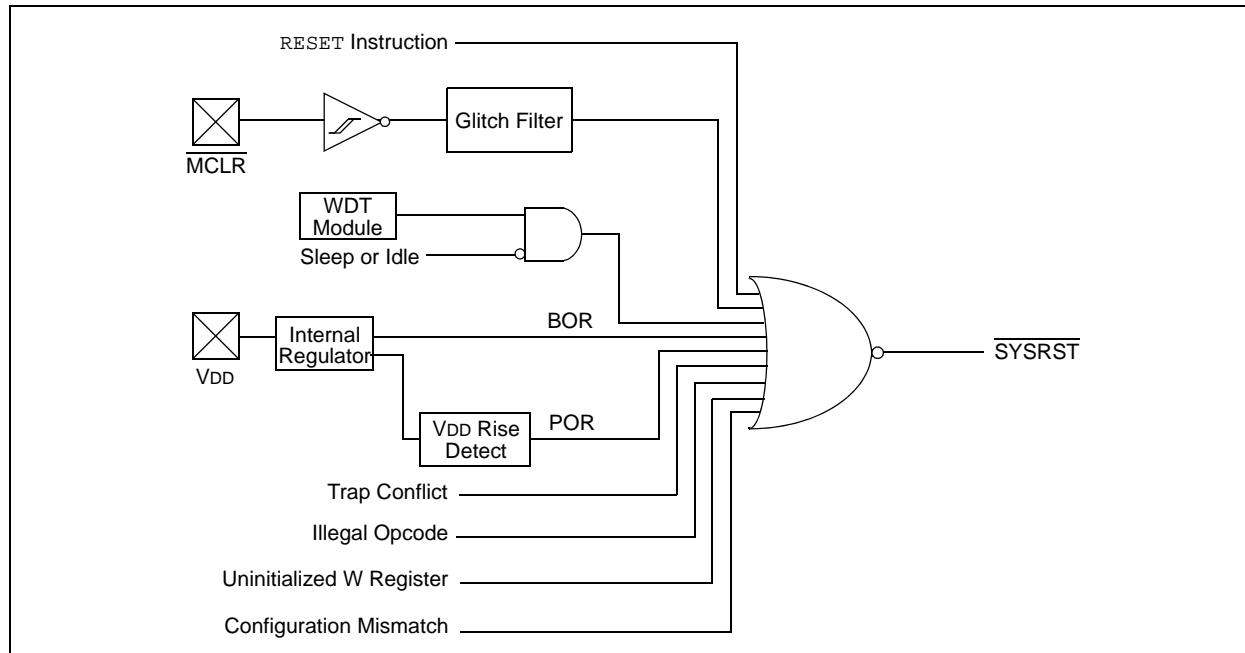
All types of device Reset set a corresponding status bit in the RCON register to indicate the type of Reset (see [Register 6-1](#)).

A POR clears all the bits, except for the POR bit (RCON<0>), that are set. The user application can set or clear any bit at any time during the code execution. The RCON bits only serve as status bits. Setting a particular Reset status bit in software does not cause a device Reset to occur.

The RCON register also has other bits associated with the Watchdog Timer and device power-saving states. The function of these bits is discussed in other sections of this manual.

**Note:** The status bits in the RCON register should be cleared after they are read so that the next RCON register value after a device Reset is meaningful.

**FIGURE 6-1: RESET SYSTEM BLOCK DIAGRAM**



**REGISTER 6-1: RCON: RESET CONTROL REGISTER<sup>(1)</sup>**

R/W-0	R/W-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
TRAPR	IOPUWR	—	—	—	—	CM	VREGS
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-1
EXTR	SWR	SWDTEN <sup>(2)</sup>	WDTO	SLEEP	IDLE	BOR	POR
bit 7						bit 0	

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **TRAPR:** Trap Reset Flag bit  
               1 = A Trap Conflict Reset has occurred  
               0 = A Trap Conflict Reset has not occurred
- bit 14      **IOPUWR:** Illegal Opcode or Uninitialized W Access Reset Flag bit  
               1 = An illegal opcode detection, an illegal address mode or uninitialized W register used as an Address Pointer caused a Reset  
               0 = An illegal opcode or uninitialized W Reset has not occurred
- bit 13-10    **Unimplemented:** Read as '0'
- bit 9        **CM:** Configuration Mismatch Flag bit  
               1 = A configuration mismatch Reset has occurred  
               0 = A configuration mismatch Reset has NOT occurred
- bit 8        **VREGS:** Voltage Regulator Standby During Sleep bit  
               1 = Voltage regulator is active during Sleep  
               0 = Voltage regulator goes into Standby mode during Sleep
- bit 7        **EXTR:** External Reset (MCLR) Pin bit  
               1 = A Master Clear (pin) Reset has occurred  
               0 = A Master Clear (pin) Reset has not occurred
- bit 6        **SWR:** Software Reset (Instruction) Flag bit  
               1 = A RESET instruction has been executed  
               0 = A RESET instruction has not been executed
- bit 5        **SWDTEN:** Software Enable/Disable of WDT bit<sup>(2)</sup>  
               1 = WDT is enabled  
               0 = WDT is disabled
- bit 4        **WDTO:** Watchdog Timer Time-out Flag bit  
               1 = WDT time-out has occurred  
               0 = WDT time-out has not occurred
- bit 3        **SLEEP:** Wake-up from Sleep Flag bit  
               1 = Device has been in Sleep mode  
               0 = Device has not been in Sleep mode
- bit 2        **IDLE:** Wake-up from Idle Flag bit  
               1 = Device was in Idle mode  
               0 = Device was not in Idle mode

**Note 1:** All of the Reset status bits can be set or cleared in software. Setting one of these bits in software does not cause a device Reset.

**2:** If the FWDTEN Configuration bit is '1' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.

**REGISTER 6-1: RCON: RESET CONTROL REGISTER<sup>(1)</sup> (CONTINUED)**

bit 1	<b>BOR:</b> Brown-out Reset Flag bit 1 = A Brown-out Reset has occurred 0 = A Brown-out Reset has not occurred
bit 0	<b>POR:</b> Power-on Reset Flag bit 1 = A Power-on Reset has occurred 0 = A Power-on Reset has not occurred

- Note 1:** All of the Reset status bits can be set or cleared in software. Setting one of these bits in software does not cause a device Reset.
- 2:** If the FWDTEN Configuration bit is '1' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.

## 6.1 System Reset

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices have two types of Reset:

- Cold Reset
- Warm Reset

A cold Reset is the result of a Power-on Reset (POR) or a Brown-out Reset (BOR). On a cold Reset, the FNOSC Configuration bits in the FOSC device Configuration register selects the device clock source.

A warm Reset is the result of all other reset sources, including the RESET instruction. On warm Reset, the device will continue to operate from the current clock source as indicated by the Current Oscillator Selection bits (COSC<2:0>) in the Oscillator Control register (OSCCON<14:12>).

The device is kept in a Reset state until the system power supplies have stabilized at appropriate levels and the oscillator clock is ready. The description of the sequence in which this occurs is shown in [Figure 6-2](#).

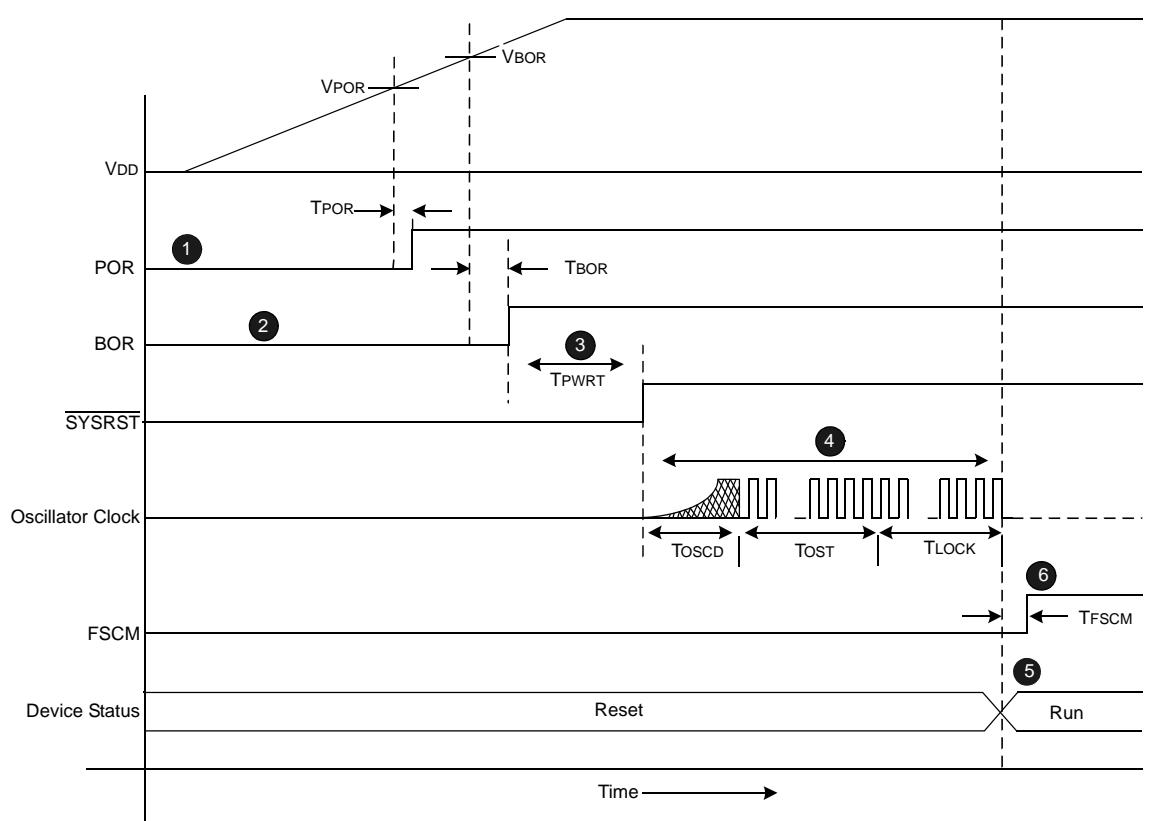
TABLE 6-1: OSCILLATOR DELAY

Oscillator Mode	Oscillator Startup Delay	Oscillator Startup Timer	PLL Lock Time	Total Delay
FRC, FRCDIV16, FRCDIV/N	TOSCD	—	—	TOSCD
FRCPLL	TOSCD	—	TLOCK	TOSCD + TLOCK
XT	TOSCD	TOST	—	TOSCD + TOST
HS	TOSCD	TOST	—	TOSCD + TOST
EC	—	—	—	—
XTPLL	TOSCD	TOST	TLOCK	TOSCD + TOST + TLOCK
HSPLL	TOSCD	TOST	TLOCK	TOSCD + TOST + TLOCK
ECPLL	—	—	TLOCK	TLOCK
SOSC	TOSCD	TOST	—	TOSCD + TOST
LPRC	TOSCD	—	—	TOSCD

**Note 1:** TOSCD = Oscillator Start-up Delay (1.1  $\mu$ s max for FRC, 70  $\mu$ s max for LPRC). Crystal Oscillator start-up times vary with crystal characteristics, load capacitance, etc.

**2:** TOST = Oscillator Start-up Timer Delay (1024 oscillator clock period). For example, TOST = 102.4  $\mu$ s for a 10 MHz crystal and TOST = 32 ms for a 32 kHz crystal.

**3:** TLOCK = PLL lock time (1.5 ms nominal), if PLL is enabled.

**FIGURE 6-2: SYSTEM RESET TIMING**

- Note 1:** **POR:** A POR circuit holds the device in Reset when the power supply is turned on. The POR circuit is active until VDD crosses the VPOR threshold and the delay TPOR has elapsed.
- 2:** **BOR:** The on-chip voltage regulator has a BOR circuit that keeps the device in Reset until VDD crosses the VBOR threshold and the delay TBOR has elapsed. The delay TBOR ensures the voltage regulator output becomes stable.
- 3:** **PWRT Timer:** The programmable power-up timer continues to hold the processor in Reset for a specific period of time (TPWRT) after a BOR. The delay TPWRT ensures that the system power supplies have stabilized at the appropriate level for full-speed operation. After the delay TPWRT has elapsed, the SYSRST becomes inactive, which in turn enables the selected oscillator to start generating clock cycles.
- 4:** **Oscillator Delay:** The total delay for the clock to be ready for various clock source selections are given in [Table 6-1](#). Refer to [Section 9.0 “Oscillator Configuration”](#) for more information.
- 5:** When the oscillator clock is ready, the processor begins execution from location 0x000000. The user application programs a GOTO instruction at the reset address, which redirects program execution to the appropriate start-up routine.
- 6:** The Fail-Safe Clock Monitor (FSCM), if enabled, begins to monitor the system clock when the system clock is ready and the delay TFSCM has elapsed.

**TABLE 6-2: OSCILLATOR PARAMETERS**

Symbol	Parameter	Value
VPOR	POR threshold	1.8V nominal
TPOR	POR extension time	30 $\mu$ s maximum
VBOR	BOR threshold	2.5V nominal
TBOR	BOR extension time	100 $\mu$ s maximum
TPWRT	Programmable power-up time delay	0-128 ms nominal
TFSCM	Fail-Safe Clock Monitor Delay	900 $\mu$ s maximum

**Note:** When the device exits the Reset condition (begins normal operation), the device operating parameters (voltage, frequency, temperature, etc.) must be within their operating ranges, otherwise, the device may not function correctly. The user application must ensure that the delay between the time power is first applied, and the time SYSRST becomes inactive, is long enough to get all operating parameters within specification.

## 6.2 Power-on Reset (POR)

A Power-on Reset (POR) circuit ensures the device is reset from power-on. The POR circuit is active until VDD crosses the VPOR threshold and the delay TPOR has elapsed. The delay TPOR ensures the internal device bias circuits become stable.

The device supply voltage characteristics must meet the specified starting voltage and rise rate requirements to generate the POR. Refer to [Section 31.0 “Electrical Characteristics”](#) for details.

The POR status bit (POR) in the Reset Control register (RCON<0>) is set to indicate the Power-on Reset.

## 6.2.1 Brown-out Reset (BOR) and Power-up Timer (PWRT)

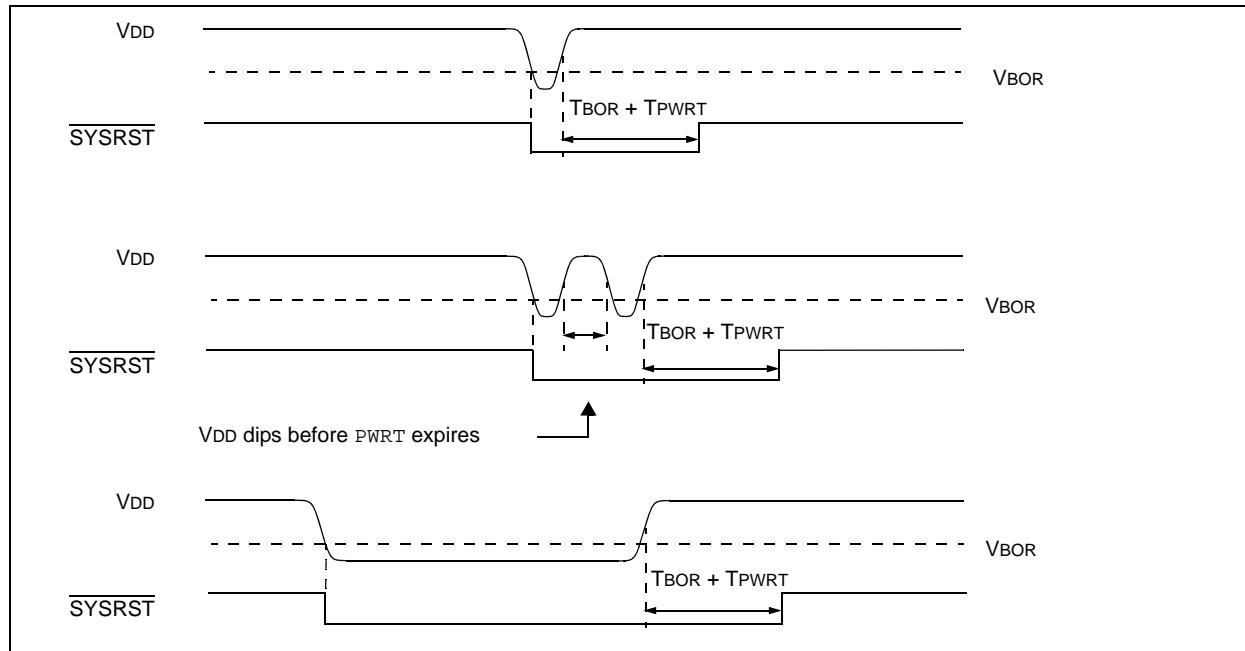
The on-chip regulator has a Brown-out Reset (BOR) circuit that resets the device when the VDD is too low ( $VDD < VBOR$ ) for proper device operation. The BOR circuit keeps the device in Reset until VDD crosses VBOR threshold and the delay TBOR has elapsed. The delay TBOR ensures the voltage regulator output becomes stable.

The BOR status bit (BOR) in the Reset Control register (RCON<1>) is set to indicate the Brown-out Reset.

The device will not run at full speed after a BOR as the VDD should rise to acceptable levels for full-speed operation. The PWRT provides power-up time delay (TPWRT) to ensure that the system power supplies have stabilized at the appropriate levels for full-speed operation before the SYSRST is released.

The power-up timer delay (TPWRT) is programmed by the Power-on Reset Timer Value Select bits (FPWRT<2:0>) in the POR Configuration register (FPOR<2:0>), which provides eight settings (from 0 ms to 128 ms). Refer to [Section 28.0 “Special Features”](#) for further details.

[Figure 6-3](#) shows the typical brown-out scenarios. The reset delay (TBOR + TPWRT) is initiated each time VDD rises above the VBOR trip point

**FIGURE 6-3: BROWN-OUT SITUATIONS**

### 6.3 External Reset (EXTR)

The external Reset is generated by driving the MCLR pin low. The MCLR pin is a Schmitt trigger input with an additional glitch filter. Reset pulses that are longer than the minimum pulse width will generate a Reset. Refer to [Section 31.0 “Electrical Characteristics”](#) for minimum pulse width specifications. The External Reset (MCLR) Pin bit (EXTR) in the Reset Control register (RCON<7>) is set to indicate the MCLR Reset.

#### 6.3.0.1 EXTERNAL SUPERVISORY CIRCUIT

Many systems have external supervisory circuits that generate reset signals to Reset multiple devices in the system. This external Reset signal can be directly connected to the MCLR pin to Reset the device when the rest of system is Reset.

#### 6.3.0.2 INTERNAL SUPERVISORY CIRCUIT

When using the internal power supervisory circuit to Reset the device, the external reset pin (MCLR) should be tied directly or resistively to Vdd. In this case, the MCLR pin will not be used to generate a Reset. The external reset pin (MCLR) does not have an internal pull-up and must not be left unconnected.

### 6.4 Software RESET Instruction (SWR)

Whenever the RESET instruction is executed, the device will assert SYSRST, placing the device in a special Reset state. This Reset state will not re-initialize the clock. The clock source in effect prior to the RESET instruction will remain. SYSRST is released at the next instruction cycle, and the reset vector fetch will commence.

The Software Reset (Instruction) Flag bit (SWR) in the Reset Control register (RCON<6>) is set to indicate the software Reset.

### 6.5 Watchdog Time-out Reset (WDTO)

Whenever a Watchdog time-out occurs, the device will asynchronously assert SYSRST. The clock source will remain unchanged. A WDT time-out during Sleep or Idle mode will wake-up the processor, but will not reset the processor.

The Watchdog Timer Time-out Flag bit (WDTO) in the Reset Control register (RCON<4>) is set to indicate the Watchdog Reset. Refer to [Section 28.4 “Watchdog Timer \(WDT\)”](#) for more information on Watchdog Reset.

### 6.6 Trap Conflict Reset

If a lower-priority hard trap occurs while a higher-priority trap is being processed, a hard trap conflict Reset occurs. The hard traps include exceptions of priority level 13 through level 15, inclusive. The address error (level 13) and oscillator error (level 14) traps fall into this category.

The Trap Reset Flag bit (TRAPR) in the Reset Control register (RCON<15>) is set to indicate the Trap Conflict Reset. Refer to [Section 7.0 “Interrupt Controller”](#) for more information on trap conflict Resets.

## 6.7 Configuration Mismatch Reset

To maintain the integrity of the peripheral pin select control registers, they are constantly monitored with shadow registers in hardware. If an unexpected change in any of the registers occur (such as cell disturbances caused by ESD or other external events), a configuration mismatch Reset occurs.

The Configuration Mismatch Flag bit (CM) in the Reset Control register (RCON<9>) is set to indicate the configuration mismatch Reset. Refer to [Section 11.0 "I/O Ports"](#) for more information on the configuration mismatch Reset.

**Note:** The configuration mismatch feature and associated reset flag is not available on all devices.

## 6.8 Illegal Condition Device Reset

An illegal condition device Reset occurs due to the following sources:

- Illegal Opcode Reset
- Uninitialized W Register Reset
- Security Reset

The Illegal Opcode or Uninitialized W Access Reset Flag bit (IOPUWR) in the Reset Control register (RCON<14>) is set to indicate the illegal condition device Reset.

### 6.8.0.1 ILLEGAL OPCODE RESET

A device Reset is generated if the device attempts to execute an illegal opcode value that is fetched from program memory.

The illegal opcode Reset function can prevent the device from executing program memory sections that are used to store constant data. To take advantage of the illegal opcode Reset, use only the lower 16 bits of

each program memory section to store the data values. The upper 8 bits should be programmed with 3Fh, which is an illegal opcode value.

### 6.8.0.2 UNINITIALIZED W REGISTER RESET

Any attempts to use the uninitialized W register as an address pointer will Reset the device. The W register array (with the exception of W15) is cleared during all resets and is considered uninitialized until written to.

### 6.8.0.3 SECURITY RESET

If a Program Flow Change (PFC) or Vector Flow Change (VFC) targets a restricted location in a protected segment (Boot and Secure Segment), that operation will cause a security Reset.

The PFC occurs when the Program Counter is reloaded as a result of a Call, Jump, Computed Jump, Return, Return from Subroutine, or other form of branch instruction.

The VFC occurs when the Program Counter is reloaded with an Interrupt or Trap vector.

Refer to [Section 28.8 "Code Protection and CodeGuard Security"](#) for more information on Security Reset.

## 6.9 Using the RCON Status Bits

The user application can read the Reset Control register (RCON) after any device Reset to determine the cause of the reset.

**Note:** The status bits in the RCON register should be cleared after they are read so that the next RCON register value after a device Reset will be meaningful.

[Table 6-3](#) provides a summary of the Reset flag bit operation.

**TABLE 6-3: RESET FLAG BIT OPERATION<sup>(1)</sup>**

Flag Bit	Set by:	Cleared by:
TRAPR (RCON<15>)	Trap conflict event	POR, BOR
IOPWR (RCON<14>)	Illegal opcode or uninitialized W register access or Security Reset	POR, BOR
CM (RCON<9>)	Configuration Mismatch	POR, BOR
EXTR (RCON<7>)	MCLR Reset	POR
SWR (RCON<6>)	RESET instruction	POR, BOR
WDTO (RCON<4>)	WDT time-out	PWRSAV instruction, CLRWDT instruction, POR, BOR
SLEEP (RCON<3>)	PWRSAV #SLEEP instruction	POR, BOR
IDLE (RCON<2>)	PWRSAV #IDLE instruction	POR, BOR
BOR (RCON<1>)	POR, BOR	—
POR (RCON<0>)	POR	—

**Note 1:** All Reset flag bits can be set or cleared by user software.

## 7.0 INTERRUPT CONTROLLER

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 32. Interrupts (Part III)**” (DS70214) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 interrupt controller reduces the numerous peripheral interrupt request signals to a single interrupt request signal to the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 CPU.

The interrupt controller has the following features:

- Up to eight processor exceptions and software traps
- Eight user-selectable priority levels
- Interrupt Vector Table (IVT) with up to 118 vectors
- A unique vector for each interrupt or exception source
- Fixed priority within a specified user priority level
- Alternate Interrupt Vector Table (AIVT) for debug support
- Fixed interrupt entry and return latencies

### 7.1 Interrupt Vector Table

The Interrupt Vector Table (IVT) shown in [Figure 7-1](#), resides in program memory, starting at location 000004h. The IVT contains 126 vectors consisting of eight nonmaskable trap vectors plus up to 118 sources of interrupt. In general, each interrupt source has its own vector. Each interrupt vector contains a 24-bit wide address. The value programmed into each interrupt vector location is the starting address of the associated Interrupt Service Routine (ISR).

Interrupt vectors are prioritized in terms of their natural priority. This priority is linked to their position in the vector table. Lower addresses generally have a higher natural priority. For example, the interrupt associated with vector 0 takes priority over interrupts at any other vector address.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices implement up to 53 unique interrupts and five nonmaskable traps. These are summarized in [Table 7-1](#).

#### 7.1.1 ALTERNATE INTERRUPT VECTOR TABLE

The Alternate Interrupt Vector Table (AIVT) is located after the IVT, as shown in [Figure 7-1](#). Access to the AIVT is provided by the ALTIVT control bit (INTCON2<15>). If the ALTIVT bit is set, all interrupt and exception processes use the alternate vectors instead of the default vectors. The alternate vectors are organized in the same manner as the default vectors.

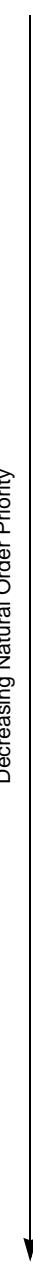
The AIVT supports debugging by providing a means to switch between an application and a support environment without requiring the interrupt vectors to be reprogrammed. This feature also enables switching between applications for evaluation of different software algorithms at run time. If the AIVT is not needed, the AIVT should be programmed with the same addresses used in the IVT.

### 7.2 Reset Sequence

A device Reset is not a true exception because the interrupt controller is not involved in the Reset process. The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 device clears its registers in response to a Reset, which forces the PC to zero. The digital signal controller then begins program execution at location 0x000000. A GOTO instruction at the Reset address can redirect program execution to the appropriate start-up routine.

**Note:** Any unimplemented or unused vector locations in the IVT and AIVT should be programmed with the address of a default interrupt handler routine that contains a RESET instruction.

**FIGURE 7-1: dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 AND dsPIC33FJ128MCX02/X04 INTERRUPT VECTOR TABLE**

<p style="margin: 0;">Decreasing Natural Order Priority</p> 	<table border="1" style="width: 100%; border-collapse: collapse;"> <tbody> <tr><td>Reset – GOTO Instruction</td><td style="text-align: right;">0x000000</td></tr> <tr><td>Reset – GOTO Address</td><td style="text-align: right;">0x000002</td></tr> <tr><td>Reserved</td><td style="text-align: right;">0x000004</td></tr> <tr><td>Oscillator Fail Trap Vector</td><td></td></tr> <tr><td>Address Error Trap Vector</td><td></td></tr> <tr><td>Stack Error Trap Vector</td><td></td></tr> <tr><td>Math Error Trap Vector</td><td></td></tr> <tr><td>DMA Error Trap Vector</td><td></td></tr> <tr><td>Reserved</td><td></td></tr> <tr><td>Reserved</td><td></td></tr> <tr><td>Interrupt Vector 0</td><td style="text-align: right;">0x000014</td></tr> <tr><td>Interrupt Vector 1</td><td></td></tr> <tr><td>~</td><td></td></tr> <tr><td>~</td><td></td></tr> <tr><td>~</td><td></td></tr> <tr><td>Interrupt Vector 52</td><td style="text-align: right;">0x00007C</td></tr> <tr><td>Interrupt Vector 53</td><td style="text-align: right;">0x00007E</td></tr> <tr><td>Interrupt Vector 54</td><td style="text-align: right;">0x000080</td></tr> <tr><td>~</td><td></td></tr> <tr><td>~</td><td></td></tr> <tr><td>~</td><td></td></tr> <tr><td>Interrupt Vector 116</td><td style="text-align: right;">0x0000FC</td></tr> <tr><td>Interrupt Vector 117</td><td style="text-align: right;">0x0000FE</td></tr> <tr><td>Reserved</td><td style="text-align: right;">0x000100</td></tr> <tr><td>Reserved</td><td style="text-align: right;">0x000102</td></tr> <tr><td>Reserved</td><td></td></tr> <tr><td>Oscillator Fail Trap Vector</td><td></td></tr> <tr><td>Address Error Trap Vector</td><td></td></tr> <tr><td>Stack Error Trap Vector</td><td></td></tr> <tr><td>Math Error Trap Vector</td><td></td></tr> <tr><td>DMA Error Trap Vector</td><td></td></tr> <tr><td>Reserved</td><td></td></tr> <tr><td>Reserved</td><td></td></tr> <tr><td>Interrupt Vector 0</td><td style="text-align: right;">0x000114</td></tr> <tr><td>Interrupt Vector 1</td><td></td></tr> <tr><td>~</td><td></td></tr> <tr><td>~</td><td></td></tr> <tr><td>~</td><td></td></tr> <tr><td>Interrupt Vector 52</td><td style="text-align: right;">0x00017C</td></tr> <tr><td>Interrupt Vector 53</td><td style="text-align: right;">0x00017E</td></tr> <tr><td>Interrupt Vector 54</td><td style="text-align: right;">0x000180</td></tr> <tr><td>~</td><td></td></tr> <tr><td>~</td><td></td></tr> <tr><td>~</td><td></td></tr> <tr><td>Interrupt Vector 116</td><td style="text-align: right;">0x0001FE</td></tr> <tr><td>Interrupt Vector 117</td><td></td></tr> <tr><td>Start of Code</td><td style="text-align: right;">0x000200</td></tr> </tbody> </table>	Reset – GOTO Instruction	0x000000	Reset – GOTO Address	0x000002	Reserved	0x000004	Oscillator Fail Trap Vector		Address Error Trap Vector		Stack Error Trap Vector		Math Error Trap Vector		DMA Error Trap Vector		Reserved		Reserved		Interrupt Vector 0	0x000014	Interrupt Vector 1		~		~		~		Interrupt Vector 52	0x00007C	Interrupt Vector 53	0x00007E	Interrupt Vector 54	0x000080	~		~		~		Interrupt Vector 116	0x0000FC	Interrupt Vector 117	0x0000FE	Reserved	0x000100	Reserved	0x000102	Reserved		Oscillator Fail Trap Vector		Address Error Trap Vector		Stack Error Trap Vector		Math Error Trap Vector		DMA Error Trap Vector		Reserved		Reserved		Interrupt Vector 0	0x000114	Interrupt Vector 1		~		~		~		Interrupt Vector 52	0x00017C	Interrupt Vector 53	0x00017E	Interrupt Vector 54	0x000180	~		~		~		Interrupt Vector 116	0x0001FE	Interrupt Vector 117		Start of Code	0x000200	<p style="margin: 0;"><b>Alternate Interrupt Vector Table (AIVT)<sup>(1)</sup></b></p>
Reset – GOTO Instruction	0x000000																																																																																															
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Start of Code	0x000200																																																																																															

**Note 1:** See [Table 7-1](#) for the list of implemented interrupt vectors.

**TABLE 7-1: INTERRUPT VECTORS**

<b>Vector Number</b>	<b>IVT Address</b>	<b>AIVT Address</b>	<b>Interrupt Source</b>
0	0x000004	0x000104	Reserved
1	0x000006	0x000106	Oscillator Failure
2	0x000008	0x000108	Address Error
3	0x00000A	0x00010A	Stack Error
4	0x00000C	0x00010C	Math Error
5	0x00000E	0x00010E	DMA Error
6	0x000010	0x000110	Reserved
7	0x000012	0x000112	Reserved
8	0x000014	0x000114	INT0 – External Interrupt 0
9	0x000016	0x000116	IC1 – Input Capture 1
10	0x000018	0x000118	OC1 – Output Compare 1
11	0x00001A	0x00011A	T1 – Timer1
12	0x00001C	0x00011C	DMA0 – DMA Channel 0
13	0x00001E	0x00011E	IC2 – Input Capture 2
14	0x000020	0x000120	OC2 – Output Compare 2
15	0x000022	0x000122	T2 – Timer2
16	0x000024	0x000124	T3 – Timer3
17	0x000026	0x000126	SPI1E – SPI1 Error
18	0x000028	0x000128	SPI1 – SPI1 Transfer Done
19	0x00002A	0x00012A	U1RX – UART1 Receiver
20	0x00002C	0x00012C	U1TX – UART1 Transmitter
21	0x00002E	0x00012E	ADC1 – ADC 1
22	0x000030	0x000130	DMA1 – DMA Channel 1
23	0x000032	0x000132	Reserved
24	0x000034	0x000134	SI2C1 – I2C1 Slave Events
25	0x000036	0x000136	MI2C1 – I2C1 Master Events
26	0x000038	0x000138	CM – Comparator Interrupt
27	0x00003A	0x00013A	Change Notification Interrupt
28	0x00003C	0x00013C	INT1 – External Interrupt 1
29	0x00003E	0x00013E	Reserved
30	0x000040	0x000140	IC7 – Input Capture 7
31	0x000042	0x000142	IC8 – Input Capture 8
32	0x000044	0x000144	DMA2 – DMA Channel 2
33	0x000046	0x000146	OC3 – Output Compare 3
34	0x000048	0x000148	OC4 – Output Compare 4
35	0x00004A	0x00014A	T4 – Timer4
36	0x00004C	0x00014C	T5 – Timer5
37	0x00004E	0x00014E	INT2 – External Interrupt 2
38	0x000050	0x000150	U2RX – UART2 Receiver
39	0x000052	0x000152	U2TX – UART2 Transmitter
40	0x000054	0x000154	SPI2E – SPI2 Error
41	0x000056	0x000156	SPI2 – SPI2 Transfer Done
42	0x000058	0x000158	C1RX – ECAN1 RX Data Ready
43	0x00005A	0x00015A	C1 – ECAN1 Event
44	0x00005C	0x00015C	DMA3 – DMA Channel 3
45	0x00005E	0x00015E	Reserved
46	0x000060	0x000160	Reserved

**TABLE 7-1: INTERRUPT VECTORS (CONTINUED)**

<b>Vector Number</b>	<b>IVT Address</b>	<b>AIvt Address</b>	<b>Interrupt Source</b>
47	0x000062	0x000162	Reserved
48	0x000064	0x000164	Reserved
49	0x000066	0x000166	Reserved
50	0x000068	0x000168	Reserved
51	0x00006A	0x00016A	Reserved
52	0x00006C	0x00016C	Reserved
53	0x00006E	0x00016E	PMP – Parallel Master Port
54	0x000070	0x000170	DMA – DMA Channel 4
55	0x000072	0x000172	Reserved
56	0x000074	0x000174	Reserved
57	0x000076	0x000176	Reserved
58	0x000078	0x000178	Reserved
59	0x00007A	0x00017A	Reserved
60	0x00007C	0x00017C	Reserved
61	0x00007E	0x00017E	Reserved
62	0x000080	0x000180	Reserved
63	0x000082	0x000182	Reserved
64	0x000084	0x000184	Reserved
65	0x000086	0x000186	PWM1 – PWM1 Period Match
66	0x000088	0x000188	QEI1 – Position Counter Compare
67	0x00008A	0x00018A	Reserved
68	0x00008C	0x00018C	Reserved
69	0x00008E	0x00018E	DMA5 – DMA Channel 5
70	0x000090	0x000190	RTCC – Real Time Clock
71	0x000092	0x000192	<u>FLTA1</u> – PWM1 Fault A
72	0x000094	0x000194	Reserved
73	0x000096	0x000196	U1E – UART1 Error
74	0x000098	0x000198	U2E – UART2 Error
75	0x00009A	0x00019A	CRC – CRC Generator Interrupt
76	0x00009C	0x00019C	DMA6 – DMA Channel 6
77	0x00009E	0x00019E	DMA7 – DMA Channel 7
78	0x0000A0	0x0001A0	C1TX – ECAN1 TX Data Request
79	0x0000A2	0x0001A2	Reserved
80	0x0000A4	0x0001A4	Reserved
81	0x0000A6	0x0001A6	PWM2 – PWM2 Period Match
82	0x0000A8	0x0001A8	<u>FLTA2</u> – PWM2 Fault A
83	0x0000AA	0x0001AA	QEI2 – Position Counter Compare
84	0x0000AC	0x0001AC	Reserved
85	0x0000AE	0x0001AE	Reserved
86	0x0000B0	0x0001B0	DAC1R – DAC1 Right Data Request
87	0x0000B2	0x0001B2	DAC1L – DAC1 Left Data Request
88-126	0x0000B4-0x0000FE	0x0001B4-0x0001FE	Reserved

### **7.3 Interrupt Control and Status Registers**

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices implement a total of 30 registers for the interrupt controller:

- INTCON1
- INTCON2
- IFSx
- IECx
- IPCx
- INTTREG

#### **7.3.1 INTCON1 AND INTCON2**

Global interrupt control functions are controlled from INTCON1 and INTCON2. INTCON1 contains the Interrupt Nesting Disable bit (NSTDIS) as well as the control and status flags for the processor trap sources. The INTCON2 register controls the external interrupt request signal behavior and the use of the Alternate Interrupt Vector Table (AIVT).

#### **7.3.2 IFSx**

The IFS registers maintain all of the interrupt request flags. Each source of interrupt has a status bit, which is set by the respective peripherals or external signal and is cleared via software.

#### **7.3.3 IECx**

The IEC registers maintain all of the interrupt enable bits. These control bits are used to individually enable interrupts from the peripherals or external signals.

#### **7.3.4 IPCx**

The IPC registers are used to set the interrupt priority level for each source of interrupt. Each user interrupt source can be assigned to one of eight priority levels.

#### **7.3.5 INTTREG**

The INTTREG register contains the associated interrupt vector number and the new CPU interrupt priority level, which are latched into vector number bits (VECNUM<6:0>) and Interrupt level bits (ILR<3:0>) in the INTTREG register. The new interrupt priority level is the priority of the pending interrupt.

The interrupt sources are assigned to the IFSx, IECx and IPCx registers in the same sequence that they are listed in [Table 7-1](#). For example, the INT0 (External Interrupt 0) is shown as having vector number 8 and a natural order priority of 0. Thus, the INT0IF bit is found in IFS0<0>, the INT0IE bit in IEC0<0>, and the INT0IP bits in the first position of IPC0 (IPC0<2:0>).

#### **7.3.6 STATUS/CONTROL REGISTERS**

Although they are not specifically part of the interrupt control hardware, two of the CPU control registers contain bits that control interrupt functionality.

- The CPU Status register, SR, contains the IPL<2:0> bits (SR<7:5>). These bits indicate the current CPU interrupt priority level. The user software can change the current CPU priority level by writing to the IPL bits.
- The CORCON register contains the IPL3 bit, which together with IPL<2:0>, also indicates the current CPU priority level. The IPL3 is a read-only bit so that trap events cannot be masked by the user software.

All Interrupt registers are described in [Register 7-1](#) through [Register 7-32](#).

**REGISTER 7-1: SR: CPU STATUS REGISTER<sup>(1)</sup>**

R-0	R-0	R/C-0	R/C-0	R-0	R/C-0	R -0	R/W-0
OA	OB	SA	SB	OAB	SAB	DA	DC
bit 15							bit 8

R/W-0 <sup>(3)</sup>	R/W-0 <sup>(3)</sup>	R/W-0 <sup>(3)</sup>	R-0	R/W-0	R/W-0	R/W-0	R/W-0
IPL2 <sup>(2)</sup>	IPL1 <sup>(2)</sup>	IPL0 <sup>(2)</sup>	RA	N	OV	Z	C
bit 7							bit 0

**Legend:**

C = Clear only bit	R = Readable bit	U = Unimplemented bit, read as '0'
S = Set only bit	W = Writable bit	-n = Value at POR
'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-5      **IPL<2:0>**: CPU Interrupt Priority Level Status bits<sup>(2)</sup>

- 111 = CPU Interrupt Priority Level is 7 (15), user interrupts disabled
- 110 = CPU Interrupt Priority Level is 6 (14)
- 101 = CPU Interrupt Priority Level is 5 (13)
- 100 = CPU Interrupt Priority Level is 4 (12)
- 011 = CPU Interrupt Priority Level is 3 (11)
- 010 = CPU Interrupt Priority Level is 2 (10)
- 001 = CPU Interrupt Priority Level is 1 (9)
- 000 = CPU Interrupt Priority Level is 0 (8)

**Note 1:** For complete register details, see [Register 3-1](#).

- 2:** The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.
- 3:** The IPL<2:0> status bits are read-only when the NSTDIS bit (INTCON1<15>) = 1.

**REGISTER 7-2: CORCON: CORE CONTROL REGISTER<sup>(1)</sup>**

U-0	U-0	U-0	R/W-0	R/W-0	R-0	R-0	R-0
—	—	—	US	EDT	DL<2:0>		
bit 15							bit 8

R/W-0	R/W-0	R/W-1	R/W-0	R/C-0	R/W-0	R/W-0	R/W-0
SATA	SATB	SATDW	ACCSAT	IPL3 <sup>(2)</sup>	PSV	RND	IF
bit 7							bit 0

**Legend:**

C = Clear only bit	
R = Readable bit	W = Writable bit
0' = Bit is cleared	'x = Bit is unknown

-n = Value at POR

'1' = Bit is set

U = Unimplemented bit, read as '0'

bit 3      **IPL3**: CPU Interrupt Priority Level Status bit 3<sup>(2)</sup>

- 1 = CPU interrupt priority level is greater than 7
- 0 = CPU interrupt priority level is 7 or less

**Note 1:** For complete register details, see [Register 3-2](#).

- 2:** The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU Interrupt Priority Level.

**REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NSTDIS	OVAERR	OVBERR	COVAERR	COVBERR	OVATE	OVBTE	COVTE
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
SFTACERR	DIV0ERR	DMACERR	MATHERR	ADDRERR	STKERR	OSCFAIL	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15	<b>NSTDIS:</b> Interrupt Nesting Disable bit 1 = Interrupt nesting is disabled 0 = Interrupt nesting is enabled
bit 14	<b>OVAERR:</b> Accumulator A Overflow Trap Flag bit 1 = Trap was caused by overflow of Accumulator A 0 = Trap was not caused by overflow of Accumulator A
bit 13	<b>OVBERR:</b> Accumulator B Overflow Trap Flag bit 1 = Trap was caused by overflow of Accumulator B 0 = Trap was not caused by overflow of Accumulator B
bit 12	<b>COVAERR:</b> Accumulator A Catastrophic Overflow Trap Flag bit 1 = Trap was caused by catastrophic overflow of Accumulator A 0 = Trap was not caused by catastrophic overflow of Accumulator A
bit 11	<b>COVBERR:</b> Accumulator B Catastrophic Overflow Trap Flag bit 1 = Trap was caused by catastrophic overflow of Accumulator B 0 = Trap was not caused by catastrophic overflow of Accumulator B
bit 10	<b>OVATE:</b> Accumulator A Overflow Trap Enable bit 1 = Trap overflow of Accumulator A 0 = Trap disabled
bit 9	<b>OVBTE:</b> Accumulator B Overflow Trap Enable bit 1 = Trap overflow of Accumulator B 0 = Trap disabled
bit 8	<b>COVTE:</b> Catastrophic Overflow Trap Enable bit 1 = Trap on catastrophic overflow of Accumulator A or B enabled 0 = Trap disabled
bit 7	<b>SFTACERR:</b> Shift Accumulator Error Status bit 1 = Math error trap was caused by an invalid accumulator shift 0 = Math error trap was not caused by an invalid accumulator shift
bit 6	<b>DIV0ERR:</b> Arithmetic Error Status bit 1 = Math error trap was caused by a divide by zero 0 = Math error trap was not caused by a divide by zero
bit 5	<b>DMACERR:</b> DMA Controller Error Status bit 1 = DMA controller error trap has occurred 0 = DMA controller error trap has not occurred
bit 4	<b>MATHERR:</b> Arithmetic Error Status bit 1 = Math error trap has occurred 0 = Math error trap has not occurred

**REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1 (CONTINUED)**

- |       |  |
|-------|--|
| bit 3 | <b>ADDRERR:</b> Address Error Trap Status bit<br>1 = Address error trap has occurred<br>0 = Address error trap has not occurred                |
| bit 2 | <b>STKERR:</b> Stack Error Trap Status bit<br>1 = Stack error trap has occurred<br>0 = Stack error trap has not occurred                       |
| bit 1 | <b>OSCFAIL:</b> Oscillator Failure Trap Status bit<br>1 = Oscillator failure trap has occurred<br>0 = Oscillator failure trap has not occurred |
| bit 0 | <b>Unimplemented:</b> Read as '0'  |

**REGISTER 7-4: INTCON2: INTERRUPT CONTROL REGISTER 2**

R/W-0	R-0	U-0	U-0	U-0	U-0	U-0	U-0
ALTIvt	DISI	—	—	—	—	—	—
bit 15							

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	INT2EP	INT1EP	INT0EP
bit 7							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **ALTIvt:** Enable Alternate Interrupt Vector Table bit

1 = Use alternate vector table

0 = Use standard (default) vector table

bit 14      **DISI:** DISI Instruction Status bit

1 = DISI instruction is active

0 = DISI instruction is not active

bit 13-3      **Unimplemented:** Read as '0'bit 2      **INT2EP:** External Interrupt 2 Edge Detect Polarity Select bit

1 = Interrupt on negative edge

0 = Interrupt on positive edge

bit 1      **INT1EP:** External Interrupt 1 Edge Detect Polarity Select bit

1 = Interrupt on negative edge

0 = Interrupt on positive edge

bit 0      **INT0EP:** External Interrupt 0 Edge Detect Polarity Select bit

1 = Interrupt on negative edge

0 = Interrupt on positive edge

## REGISTER 7-5: IFS0: INTERRUPT FLAG STATUS REGISTER 0

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	DMA1IF	AD1IF	U1TXIF	U1RXIF	SPI1IF	SPI1EIF	T3IF
bit 15	bit 8						

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
T2IF	OC2IF	IC2IF	DMA0IF	T1IF	OC1IF	IC1IF	INT0IF
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'
- bit 14      **DMA1IF:** DMA Channel 1 Data Transfer Complete Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 13      **AD1IF:** ADC1 Conversion Complete Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 12      **U1TXIF:** UART1 Transmitter Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 11      **U1RXIF:** UART1 Receiver Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 10      **SPI1IF:** SPI1 Event Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 9      **SPI1EIF:** SPI1 Error Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 8      **T3IF:** Timer3 Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 7      **T2IF:** Timer2 Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 6      **OC2IF:** Output Compare Channel 2 Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 5      **IC2IF:** Input Capture Channel 2 Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 4      **DMA0IF:** DMA Channel 0 Data Transfer Complete Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 3      **T1IF:** Timer1 Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred

**REGISTER 7-5: IFS0: INTERRUPT FLAG STATUS REGISTER 0 (CONTINUED)**

- |       |  |
|-------|--|
| bit 2 | <b>OC1IF:</b> Output Compare Channel 1 Interrupt Flag Status bit<br>1 = Interrupt request has occurred<br>0 = Interrupt request has not occurred |
| bit 1 | <b>IC1IF:</b> Input Capture Channel 1 Interrupt Flag Status bit<br>1 = Interrupt request has occurred<br>0 = Interrupt request has not occurred  |
| bit 0 | <b>INT0IF:</b> External Interrupt 0 Flag Status bit<br>1 = Interrupt request has occurred<br>0 = Interrupt request has not occurred              |

## REGISTER 7-6: IFS1: INTERRUPT FLAG STATUS REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
U2TXIF	U2RXIF	INT2IF	T5IF	T4IF	OC4IF	OC3IF	DMA2IF
bit 15	bit 8						

R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
IC8IF	IC7IF	—	INT1IF	CNIF	CMIF	MI2C1IF	SI2C1IF
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **U2TXIF:** UART2 Transmitter Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 14      **U2RXIF:** UART2 Receiver Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 13      **INT2IF:** External Interrupt 2 Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 12      **T5IF:** Timer5 Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 11      **T4IF:** Timer4 Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 10      **OC4IF:** Output Compare Channel 4 Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 9      **OC3IF:** Output Compare Channel 3 Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 8      **DMA2IF:** DMA Channel 2 Data Transfer Complete Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 7      **IC8IF:** Input Capture Channel 8 Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 6      **IC7IF:** Input Capture Channel 7 Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 5      **Unimplemented:** Read as '0'
- bit 4      **INT1IF:** External Interrupt 1 Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 3      **CNIF:** Input Change Notification Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred

**REGISTER 7-6: IFS1: INTERRUPT FLAG STATUS REGISTER 1 (CONTINUED)**

- |       |  |
|-------|--|
| bit 2 | <b>CMIF:</b> Comparator Interrupt Flag Status bit<br>1 = Interrupt request has occurred<br>0 = Interrupt request has not occurred            |
| bit 1 | <b>MI2C1IF:</b> I2C1 Master Events Interrupt Flag Status bit<br>1 = Interrupt request has occurred<br>0 = Interrupt request has not occurred |
| bit 0 | <b>SI2C1IF:</b> I2C1 Slave Events Interrupt Flag Status bit<br>1 = Interrupt request has occurred<br>0 = Interrupt request has not occurred  |

**REGISTER 7-7: IFS2: INTERRUPT FLAG STATUS REGISTER 2**

U-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
—	DMA4IF	PMPIF	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	DMA3IF	C1IF <sup>(1)</sup>	C1RXIF <sup>(1)</sup>	SPI2IF	SPI2EIF
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'
- bit 14      **DMA4IF:** DMA Channel 4 Data Transfer Complete Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 13      **PMPIF:** Parallel Master Port Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 12-5     **Unimplemented:** Read as '0'
- bit 4        **DMA3IF:** DMA Channel 3 Data Transfer Complete Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 3        **C1IF:** ECAN1 Event Interrupt Flag Status bit<sup>(1)</sup>  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 2        **C1RXIF:** ECAN1 Receive Data Ready Interrupt Flag Status bit<sup>(1)</sup>  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 1        **SPI2IF:** SPI2 Event Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred
- bit 0        **SPI2EIF:** SPI2 Error Interrupt Flag Status bit  
1 = Interrupt request has occurred  
0 = Interrupt request has not occurred

**Note 1:** Interrupts are disabled on devices without an ECANTM module.

**REGISTER 7-8: IFS3: INTERRUPT FLAG STATUS REGISTER 3**

R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	U-0
FLTA1IF	RTCIF	DMA5IF	—	—	QEI1IF	PWM1IF	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **FLTA1IF:** PWM1 Fault A Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 14      **RTCIF:** Real-Time Clock and Calendar Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 13      **DMA5IF:** DMA Channel 5 Data Transfer Complete Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 12-11     **Unimplemented:** Read as '0'
- bit 10      **QEI1IF:** QEI1 Event Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 9      **PWM1IF:** PWM1 Event Interrupt Flag Status bit  
               1 = Interrupt request has occurred  
               0 = Interrupt request has not occurred
- bit 8-0     **Unimplemented:** Read as '0'

**REGISTER 7-9: IFS4: INTERRUPT FLAG STATUS REGISTER 4**

R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	U-0
DAC1LIF <sup>(2)</sup>	DAC1RIF <sup>(2)</sup>	—	—	QEI2IF	FLTA2IF	PWM2IF	—
bit 15							bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
—	C1TXIF <sup>(1)</sup>	DMA7IF	DMA6IF	CRCIF	U2EIF	U1EIF	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **DAC1LIF:** DAC Left Channel Interrupt Flag Status bit<sup>(2)</sup>  
                 1 = Interrupt request has occurred  
                 0 = Interrupt request has not occurred
- bit 14      **DAC1RIF:** DAC Right Channel Interrupt Flag Status bit<sup>(2)</sup>  
                 1 = Interrupt request has occurred  
                 0 = Interrupt request has not occurred
- bit 13-12    **Unimplemented:** Read as '0'
- bit 11      **QEI2IF:** QEI2 Event Interrupt Flag Status bit  
                 1 = Interrupt request has occurred  
                 0 = Interrupt request has not occurred
- bit 10      **FLTA2IF:** PWM2 Fault A Interrupt Flag Status bit  
                 1 = Interrupt request has occurred  
                 0 = Interrupt request has not occurred
- bit 9        **PWM2IF:** PWM2 Error Interrupt Enable bit  
                 1 = Interrupt request has occurred  
                 0 = Interrupt request has not occurred
- bit 8-7     **Unimplemented:** Read as '0'
- bit 6        **C1TXIF:** ECAN1 Transmit Data Request Interrupt Flag Status bit<sup>(1)</sup>  
                 1 = Interrupt request has occurred  
                 0 = Interrupt request has not occurred
- bit 5        **DMA7IF:** DMA Channel 7 Data Transfer Complete Interrupt Flag Status bit  
                 1 = Interrupt request has occurred  
                 0 = Interrupt request has not occurred
- bit 4        **DMA6IF:** DMA Channel 6 Data Transfer Complete Interrupt Flag Status bit  
                 1 = Interrupt request has occurred  
                 0 = Interrupt request has not occurred
- bit 3        **CRCIF:** CRC Generator Interrupt Flag Status bit  
                 1 = Interrupt request has occurred  
                 0 = Interrupt request has not occurred
- bit 2        **U2EIF:** UART2 Error Interrupt Flag Status bit  
                 1 = Interrupt request has occurred  
                 0 = Interrupt request has not occurred
- bit 1        **U1EIF:** UART1 Error Interrupt Flag Status bit  
                 1 = Interrupt request has occurred  
                 0 = Interrupt request has not occurred
- bit 0        **Unimplemented:** Read as '0'

**Note 1:** Interrupts are disabled on devices without an ECANTM module.

**2:** Interrupts are disabled on devices without an Audio DAC module.

**REGISTER 7-10: IEC0: INTERRUPT ENABLE CONTROL REGISTER 0**

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	DMA1IE	AD1IE	U1TXIE	U1RXIE	SPI1IE	SPI1EIE	T3IE
bit 15	bit 8						

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
T2IE	OC2IE	IC2IE	DMA0IE	T1IE	OC1IE	IC1IE	INT0IE
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'
- bit 14      **DMA1IE:** DMA Channel 1 Data Transfer Complete Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 13      **AD1IE:** ADC1 Conversion Complete Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 12      **U1TXIE:** UART1 Transmitter Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 11      **U1RXIE:** UART1 Receiver Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 10      **SPI1IE:** SPI1 Event Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 9      **SPI1EIE:** SPI1 Error Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 8      **T3IE:** Timer3 Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 7      **T2IE:** Timer2 Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 6      **OC2IE:** Output Compare Channel 2 Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 5      **IC2IE:** Input Capture Channel 2 Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 4      **DMA0IE:** DMA Channel 0 Data Transfer Complete Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 3      **T1IE:** Timer1 Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled

**REGISTER 7-10: IEC0: INTERRUPT ENABLE CONTROL REGISTER 0 (CONTINUED)**

- bit 2           **OC1IE:** Output Compare Channel 1 Interrupt Enable bit  
          1 = Interrupt request enabled  
          0 = Interrupt request not enabled
- bit 1           **IC1IE:** Input Capture Channel 1 Interrupt Enable bit  
          1 = Interrupt request enabled  
          0 = Interrupt request not enabled
- bit 0           **INT0IE:** External Interrupt 0 Flag Status bit  
          1 = Interrupt request enabled  
          0 = Interrupt request not enabled

**REGISTER 7-11: IEC1: INTERRUPT ENABLE CONTROL REGISTER 1**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
U2TXIE	U2RXIE	INT2IE	T5IE	T4IE	OC4IE	OC3IE	DMA2IE
bit 15							bit 8

R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
IC8IE	IC7IE	—	INT1IE	CNIE	CMIE	MI2C1IE	SI2C1IE
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15	<b>U2TXIE:</b> UART2 Transmitter Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 14	<b>U2RXIE:</b> UART2 Receiver Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 13	<b>INT2IE:</b> External Interrupt 2 Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 12	<b>T5IE:</b> Timer5 Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 11	<b>T4IE:</b> Timer4 Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 10	<b>OC4IE:</b> Output Compare Channel 4 Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 9	<b>OC3IE:</b> Output Compare Channel 3 Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 8	<b>DMA2IE:</b> DMA Channel 2 Data Transfer Complete Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 7	<b>IC8IE:</b> Input Capture Channel 8 Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 6	<b>IC7IE:</b> Input Capture Channel 7 Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 5	<b>Unimplemented:</b> Read as '0'
bit 4	<b>INT1IE:</b> External Interrupt 1 Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 3	<b>CNIE:</b> Input Change Notification Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled

**REGISTER 7-11: IEC1: INTERRUPT ENABLE CONTROL REGISTER 1 (CONTINUED)**

- |       |   |
|-------|---|
| bit 2 | <b>CMIE:</b> Comparator Interrupt Enable bit<br>1 = Interrupt request enabled<br>0 = Interrupt request not enabled            |
| bit 1 | <b>MI2C1IE:</b> I2C1 Master Events Interrupt Enable bit<br>1 = Interrupt request enabled<br>0 = Interrupt request not enabled |
| bit 0 | <b>SI2C1IE:</b> I2C1 Slave Events Interrupt Enable bit<br>1 = Interrupt request enabled<br>0 = Interrupt request not enabled  |

**REGISTER 7-12: IEC2: INTERRUPT ENABLE CONTROL REGISTER 2**

U-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
—	DMA4IE	PMPIE	—	—	—	—	—
bit 15	bit 8						

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	DMA3IE	C1IE <sup>(1)</sup>	C1RXIE <sup>(1)</sup>	SPI2IE	SPI2EIE
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15	<b>Unimplemented:</b> Read as '0'
bit 14	<b>DMA4IE:</b> DMA Channel 4 Data Transfer Complete Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 13	<b>PMPIE:</b> Parallel Master Port Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 12-5	<b>Unimplemented:</b> Read as '0'
bit 4	<b>DMA3IE:</b> DMA Channel 3 Data Transfer Complete Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 3	<b>C1IE:</b> ECAN1 Event Interrupt Enable bit <sup>(1)</sup> 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 2	<b>C1RXIE:</b> ECAN1 Receive Data Ready Interrupt Enable bit <sup>(1)</sup> 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 1	<b>SPI2IE:</b> SPI2 Event Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 0	<b>SPI2EIE:</b> SPI2 Error Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled

**Note 1:** Interrupts are disabled on devices without an ECAN™ module.

## REGISTER 7-13: IEC3: INTERRUPT ENABLE CONTROL REGISTER 3

R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	U-0
FLTA1IE	RTCIE	DMA5IE	—	—	QEI1IE	PWM1IE	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **FLTA1IE:** PWM1 Fault A Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 14      **RTCIE:** Real-Time Clock and Calendar Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 13      **DMA5IE:** DMA Channel 5 Data Transfer Complete Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 12-11    **Unimplemented:** Read as '0'
- bit 10      **QEI1IE:** QEI1 Event Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 9        **PWM1IE:** PWM1 Event Interrupt Enable bit  
1 = Interrupt request enabled  
0 = Interrupt request not enabled
- bit 8-0      **Unimplemented:** Read as '0'

## REGISTER 7-14: IEC4: INTERRUPT ENABLE CONTROL REGISTER 4

R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	U-0
DAC1LIE <sup>(2)</sup>	DAC1RIE <sup>(2)</sup>	—	—	QEI2IE	FLTA2IE	PWM2IE	—
				bit 15	bit 8		
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
—	C1TXIE <sup>(1)</sup>	DMA7IE	DMA6IE	CRCIE	U2EIE	U1EIE	—
				bit 7	bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15	<b>DAC1LIE:</b> DAC Left Channel Interrupt Enable bit <sup>(2)</sup> 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 14	<b>DAC1RIE:</b> DAC Right Channel Interrupt Enable bit <sup>(2)</sup> 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 13-12	<b>Unimplemented:</b> Read as '0'
bit 11	<b>QEI2IE:</b> QEI2 Event Interrupt Flag Status bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 10	<b>FLTA2IE:</b> PWM2 Fault A Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 9	<b>PWM2IE:</b> PWM2 Error Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 8-7	<b>Unimplemented:</b> Read as '0'
bit 6	<b>C1TXIE:</b> ECAN1 Transmit Data Request Interrupt Enable bit <sup>(1)</sup> 1 = Interrupt request occurred 0 = Interrupt request not occurred
bit 5	<b>DMA7IE:</b> DMA Channel 7 Data Transfer Complete Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 4	<b>DMA6IE:</b> DMA Channel 6 Data Transfer Complete Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 3	<b>CRCIE:</b> CRC Generator Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 2	<b>U2EIE:</b> UART2 Error Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 1	<b>U1EIE:</b> UART1 Error Interrupt Enable bit 1 = Interrupt request enabled 0 = Interrupt request not enabled
bit 0	<b>Unimplemented:</b> Read as '0'

**Note 1:** Interrupts are disabled on devices without an ECANTM module.**2:** Interrupts are disabled on devices without an Audio DAC module.

**REGISTER 7-15: IPC0: INTERRUPT PRIORITY CONTROL REGISTER 0**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		T1IP<2:0>		—		OC1IP<2:0>	
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		IC1IP<2:0>		—		INT0IP<2:0>	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'

bit 14-12    **T1IP<2:0>:** Timer1 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'

bit 10-8     **OC1IP<2:0>:** Output Compare Channel 1 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7        **Unimplemented:** Read as '0'

bit 6-4      **IC1IP<2:0>:** Input Capture Channel 1 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3        **Unimplemented:** Read as '0'

bit 2-0      **INT0IP<2:0>:** External Interrupt 0 Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

**REGISTER 7-16: IPC1: INTERRUPT PRIORITY CONTROL REGISTER 1**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		T2IP<2:0>		—		OC2IP<2:0>	
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		IC2IP<2:0>		—		DMA0IP<2:0>	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'bit 14-12    **T2IP<2:0>:** Timer2 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'bit 10-8    **OC2IP<2:0>:** Output Compare Channel 2 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7      **Unimplemented:** Read as '0'bit 6-4    **IC2IP<2:0>:** Input Capture Channel 2 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3      **Unimplemented:** Read as '0'bit 2-0    **DMA0IP<2:0>:** DMA Channel 0 Data Transfer Complete Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

**REGISTER 7-17: IPC2: INTERRUPT PRIORITY CONTROL REGISTER 2**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		U1RXIP<2:0>		—		SPI1IP<2:0>	
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		SPI1EIP<2:0>		—		T3IP<2:0>	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'

bit 14-12    **U1RXIP<2:0>:** UART1 Receiver Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'

bit 10-8     **SPI1IP<2:0>:** SPI1 Event Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7        **Unimplemented:** Read as '0'

bit 6-4     **SPI1EIP<2:0>:** SPI1 Error Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3        **Unimplemented:** Read as '0'

bit 2-0     **T3IP<2:0>:** Timer3 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

**REGISTER 7-18: IPC3: INTERRUPT PRIORITY CONTROL REGISTER 3**

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	DMA1IP<2:0>		
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		AD1IP<2:0>		—		U1TXIP<2:0>	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11      **Unimplemented:** Read as '0'bit 10-8      **DMA1IP<2:0>:** DMA Channel 1 Data Transfer Complete Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7      **Unimplemented:** Read as '0'bit 6-4      **AD1IP<2:0>:** ADC1 Conversion Complete Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3      **Unimplemented:** Read as '0'bit 2-0      **U1TXIP<2:0>:** UART1 Transmitter Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

**REGISTER 7-19: IPC4: INTERRUPT PRIORITY CONTROL REGISTER 4**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		CNIP<2:0>		—		CMIP<2:0>	
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		MI2C1IP<2:0>		—		SI2C1IP<2:0>	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'

bit 14-12    **CNIP<2:0>:** Change Notification Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'

bit 10-8     **CMIP<2:0>:** Comparator Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7        **Unimplemented:** Read as '0'

bit 6-4      **MI2C1IP<2:0>:** I2C1 Master Events Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3        **Unimplemented:** Read as '0'

bit 2-0      **SI2C1IP<2:0>:** I2C1 Slave Events Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

**REGISTER 7-20: IPC5: INTERRUPT PRIORITY CONTROL REGISTER 5**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		IC8IP<2:0>		—		IC7IP<2:0>	
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—		INT1IP<2:0>	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'bit 14-12    **IC8IP<2:0>:** Input Capture Channel 8 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'bit 10-8    **IC7IP<2:0>:** Input Capture Channel 7 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7-3      **Unimplemented:** Read as '0'bit 2-0      **INT1IP<2:0>:** External Interrupt 1 Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

**REGISTER 7-21: IPC6: INTERRUPT PRIORITY CONTROL REGISTER 6**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		T4IP<2:0>		—		OC4IP<2:0>	
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		OC3IP<2:0>		—		DMA2IP<2:0>	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'

bit 14-12    **T4IP<2:0>:** Timer4 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'

bit 10-8     **OC4IP<2:0>:** Output Compare Channel 4 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7        **Unimplemented:** Read as '0'

bit 6-4     **OC3IP<2:0>:** Output Compare Channel 3 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3        **Unimplemented:** Read as '0'

bit 2-0     **DMA2IP<2:0>:** DMA Channel 2 Data Transfer Complete Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

**REGISTER 7-22: IPC7: INTERRUPT PRIORITY CONTROL REGISTER 7**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	U2TXIP<2:0>			—	U2RXIP<2:0>		
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	INT2IP<2:0>			—	T5IP<2:0>		
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'bit 14-12    **U2TXIP<2:0>:** UART2 Transmitter Interrupt Priority bits  
111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'bit 10-8     **U2RXIP<2:0>:** UART2 Receiver Interrupt Priority bits  
111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7        **Unimplemented:** Read as '0'bit 6-4      **INT2IP<2:0>:** External Interrupt 2 Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3        **Unimplemented:** Read as '0'bit 2-0      **T5IP<2:0>:** Timer5 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

**REGISTER 7-23: IPC8: INTERRUPT PRIORITY CONTROL REGISTER 8**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		C1IP<2:0> <sup>(1)</sup>		—		C1RXIP<2:0> <sup>(1)</sup>	
bit 15	bit 8						

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		SPI2IP<2:0>		—		SPI2EIP<2:0>	
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'

bit 14-12    **C1IP<2:0>:** ECAN1 Event Interrupt Priority bits<sup>(1)</sup>

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'

bit 10-8     **C1RXIP<2:0>:** ECAN1 Receive Data Ready Interrupt Priority bits<sup>(1)</sup>

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7        **Unimplemented:** Read as '0'

bit 6-4      **SPI2IP<2:0>:** SPI2 Event Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3        **Unimplemented:** Read as '0'

bit 2-0      **SPI2EIP<2:0>:** SPI2 Error Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

**Note 1:** Interrupts are disabled on devices without an ECAN™ module.

**REGISTER 7-24: IPC9: INTERRUPT PRIORITY CONTROL REGISTER 9**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	DMA3IP<2:0>		
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-3      **Unimplemented:** Read as '0'bit 2-0      **DMA3IP<2:0>:** DMA Channel 3 Data Transfer Complete Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

## REGISTER 7-25: IPC11: INTERRUPT PRIORITY CONTROL REGISTER 11

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	DMA4IP<2:0>		
bit 15							

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—		PMPPIP<2:0>		—	—	—	—
bit 7							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11      **Unimplemented:** Read as '0'bit 10-8      **DMA4IP<2:0>:** DMA Channel 4 Data Transfer Complete Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7      **Unimplemented:** Read as '0'bit 6-4      **PMPPIP<2:0>:** Parallel Master Port Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3-0      **Unimplemented:** Read as '0'

**REGISTER 7-26: IPC14: INTERRUPT PRIORITY CONTROL REGISTER 14**

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	QEI1IP<2:0>		
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—		PWM1IP<2:0>		—	—	—	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11      **Unimplemented:** Read as '0'bit 10-8      **QEI1IP<2:0>:** QEI1 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7      **Unimplemented:** Read as '0'bit 6-4      **PWM1IP<2:0>:** PWM1 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3-0      **Unimplemented:** Read as '0'

## REGISTER 7-27: IPC15: INTERRUPT PRIORITY CONTROL REGISTER 15

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		FLTA1IP<2:0>		—		RTCIP<2:0>	
bit 15							

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—		DMA5IP<2:0>		—	—	—	—
bit 7							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'bit 14-12    **FLTA1IP<2:0>:** PWM Fault A Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'bit 10-8     **RTCIP<2:0>:** Real-Time Clock and Calendar Interrupt Flag Status bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7        **Unimplemented:** Read as '0'bit 6-4     **DMA5IP<2:0>:** DMA Channel 5 Data Transfer Complete Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3-0     **Unimplemented:** Read as '0'

**REGISTER 7-28: IPC16: INTERRUPT PRIORITY CONTROL REGISTER 16**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	CRCIP<2:0>			—	U2EIP<2:0>		
bit 15	bit 8						

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	U1EIP<2:0>			—	—	—	—
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'bit 14-12    **CRCIP<2:0>:** CRC Generator Error Interrupt Flag Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'bit 10-8     **U2EIP<2:0>:** UART2 Error Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7        **Unimplemented:** Read as '0'bit 6-4     **U1EIP<2:0>:** UART1 Error Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3-0     **Unimplemented:** Read as '0'

**REGISTER 7-29: IPC17: INTERRUPT PRIORITY CONTROL REGISTER 17**

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	C1TXIP<2:0> <sup>(1)</sup>		
bit 15							

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—		DMA7IP<2:0>		—		DMA6IP<2:0>	
bit 7							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11      **Unimplemented:** Read as '0'

bit 10-8      **C1TXIP<2:0>:** ECAN1 Transmit Data Request Interrupt Priority bits<sup>(1)</sup>

111 = Interrupt is priority 7 (highest priority interrupt)

- 

- 

- 

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7      **Unimplemented:** Read as '0'

bit 6-4      **DMA7IP<2:0>:** DMA Channel 7 Data Transfer Complete Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

- 

- 

- 

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3      **Unimplemented:** Read as '0'

bit 2-0      **DMA6IP<2:0>:** DMA Channel 6 Data Transfer Complete Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

- 

- 

- 

001 = Interrupt is priority 1

000 = Interrupt source is disabled

**Note 1:** Interrupts are disabled on devices without an ECAN™ module.

**REGISTER 7-30: IPC18: INTERRUPT PRIORITY CONTROL REGISTER 18**

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
—		QEI2IP<2:0>		—		FLTA2IP<2:0>	
bit 15							

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—		PWM2IP<2:0>		—	—	—	—
bit 7							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'bit 14-12    **QEI2IP<2:0>:** QEI2 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'bit 10-8     **FLTA2IP<2:0>:** PWM2 Fault A Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7        **Unimplemented:** Read as '0'bit 6-4      **PWM2IP<2:0>:** PWM2 Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3-0      **Unimplemented:** Read as '0'

## REGISTER 7-31: IPC19: INTERRUPT PRIORITY CONTROL REGISTER 19

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
—		DAC1LIP<2:0> <sup>(1)</sup>		—		DAC1RIP<2:0> <sup>(1)</sup>	
bit 15							

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'bit 14-12    **DAC1LIP<2:0>:** DAC Left Channel Interrupt Flag Status bit<sup>(1)</sup>

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11      **Unimplemented:** Read as '0'bit 10-8     **DAC1RIP<2:0>:** DAC Right Channel Interrupt Flag Status bit<sup>(1)</sup>

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7-0     **Unimplemented:** Read as '0'**Note 1:** Interrupts are disabled on devices without an Audio DAC module.

**REGISTER 7-32: INTTREG: INTERRUPT CONTROL AND STATUS REGISTER**

U-0	U-0	U-0	U-0	R-0	R-0	R-0	R-0			
—	—	—	—	ILR<3:0>						
bit 15								bit 8		

U-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0	
—	VECNUM<6:0>							
bit 7								bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-12      **Unimplemented:** Read as '0'bit 11-8      **ILR<3:0>:** New CPU Interrupt Priority Level bits

1111 = CPU Interrupt Priority Level is 15

•

•

•

0001 = CPU Interrupt Priority Level is 1

0000 = CPU Interrupt Priority Level is 0

bit 7      **Unimplemented:** Read as '0'bit 6-0      **VECNUM<6:0>:** Vector Number of Pending Interrupt bits

0111111 = Interrupt Vector pending is number 135

•

•

•

0000001 = Interrupt Vector pending is number 9

0000000 = Interrupt Vector pending is number 8

## 7.4 Interrupt Setup Procedures

### 7.4.1 INITIALIZATION

To configure an interrupt source at initialization:

1. Set the NSTDIS bit (INTCON1<15>) if nested interrupts are not desired.
2. Select the user-assigned priority level for the interrupt source by writing the control bits in the appropriate IPCx register. The priority level depends on the specific application and type of interrupt source. If multiple priority levels are not desired, the IPCx register control bits for all enabled interrupt sources can be programmed to the same non-zero value.

**Note:** At a device Reset, the IPCx registers are initialized such that all user interrupt sources are assigned to priority level 4.

3. Clear the interrupt flag status bit associated with the peripheral in the associated IFSx register.
4. Enable the interrupt source by setting the interrupt enable control bit associated with the source in the appropriate IECx register.

### 7.4.2 INTERRUPT SERVICE ROUTINE

The method used to declare an ISR and initialize the IVT with the correct vector address depends on the programming language (C or assembler) and the language development tool suite used to develop the application.

In general, the user application must clear the interrupt flag in the appropriate IFSx register for the source of interrupt that the ISR handles. Otherwise, the program re-enters the ISR immediately after exiting the routine. If the ISR is coded in assembly language, it must be terminated using a RETFIE instruction to unstack the saved PC value, SRL value and old CPU priority level.

### 7.4.3 TRAP SERVICE ROUTINE

A Trap Service Routine (TSR) is coded like an ISR, except that the appropriate trap status flag in the INTCON1 register must be cleared to avoid re-entry into the TSR.

### 7.4.4 INTERRUPT DISABLE

All user interrupts can be disabled using this procedure:

1. Push the current SR value onto the software stack using the PUSH instruction.
2. Force the CPU to priority level 7 by inclusive ORing the value OEh with SRL.

To enable user interrupts, the POP instruction can be used to restore the previous SR value.

**Note:** Only user interrupts with a priority level of 7 or lower can be disabled. Trap sources (level 8-level 15) cannot be disabled.

The DISI instruction provides a convenient way to disable interrupts of priority levels 1-6 for a fixed period of time. Level 7 interrupt sources are not disabled by the DISI instruction.

## 8.0 DIRECT MEMORY ACCESS (DMA)

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 38. Direct Memory Access (DMA) (Part III)**” (DS70215) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

Direct Memory Access (DMA) is a very efficient mechanism of copying data between peripheral SFRs (e.g., UART Receive register, Input Capture 1 buffer), and buffers or variables stored in RAM, with minimal CPU intervention. The DMA controller can automatically copy entire blocks of data without requiring the user software to read or write the peripheral Special Function Registers (SFRs) every time a peripheral interrupt occurs. The DMA controller uses a dedicated bus for data transfers and therefore, does not steal cycles from the code execution flow of the CPU. To exploit the DMA capability, the corresponding user buffers or variables must be located in DMA RAM.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 peripherals that can utilize DMA are listed in [Table 8-1](#).

**TABLE 8-1: DMA CHANNEL TO PERIPHERAL ASSOCIATIONS**

Peripheral to DMA Association	DMAxREQ Register IRQSEL<6:0> Bits	DMAxPAD Register Values to Read From Peripheral	DMAxPAD Register Values to Write to Peripheral
INT0 – External Interrupt 0	0000000	—	—
IC1 – Input Capture 1	0000001	0x0140 (IC1BUF)	—
OC1 – Output Compare 1 Data	0000010	—	0x0182 (OC1R)
OC1 – Output Compare 1 Secondary Data	0000010	—	0x0180 (OC1RS)
IC2 – Input Capture 2	0000101	0x0144 (IC2BUF)	—
OC2 – Output Compare 2 Data	0000110	—	0x0188 (OC2R)
OC2 – Output Compare 2 Secondary Data	0000110	—	0x0186 (OC2RS)
TMR2 – Timer2	0000111	—	—
TMR3 – Timer3	0001000	—	—
SPI1 – Transfer Done	0001010	0x0248 (SPI1BUF)	0x0248 (SPI1BUF)
UART1RX – UART1 Receiver	0001011	0x0226 (U1RXREG)	—
UART1TX – UART1 Transmitter	0001100	—	0x0224 (U1TXREG)
ADC1 – ADC1 Convert Done	0001101	0x0300 (ADC1BUF0)	—
UART2RX – UART2 Receiver	0011110	0x0236 (U2RXREG)	—
UART2TX – UART2 Transmitter	0011111	—	0x0234 (U2TXREG)
SPI2 – Transfer Done	0100001	0x0268 (SPI2BUF)	0x0268 (SPI2BUF)
ECAN1 – RX Data Ready	0100010	0x0440 (C1RXD)	—
PMP - Master Data Transfer	0101101	0x0608 (PMDIN1)	0x0608 (PMDIN1)
ECAN1 – TX Data Request	1000110	—	0x0442 (C1TXD)
DAC1 - Right Data Output	1001110	—	0x3F6 (DAC1RDAT)
DAC2 - Left Data Output	1001111	—	0x03F8 (DAC1LDAT)

The DMA controller features eight identical data transfer channels.

Each channel has its own set of control and status registers. Each DMA channel can be configured to copy data either from buffers stored in dual port DMA RAM to peripheral SFRs, or from peripheral SFRs to buffers in DMA RAM.

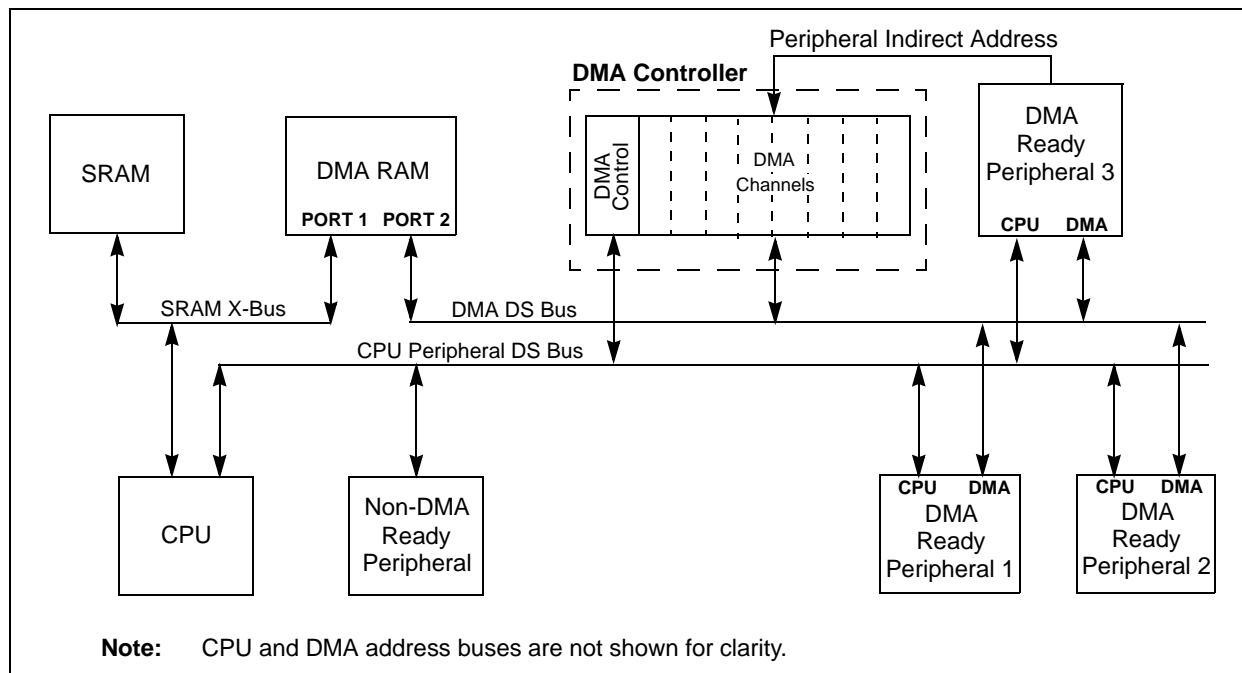
The DMA controller supports the following features:

- Eight DMA channels
- Register Indirect with Post-increment Addressing mode
- Register Indirect without Post-increment Addressing mode
- Peripheral Indirect Addressing mode (peripheral generates destination address)
- CPU interrupt after half or full block transfer complete

- Byte or word transfers
- Fixed priority channel arbitration
- Manual (software) or Automatic (peripheral DMA requests) transfer initiation
- One-Shot or Auto-Repeat block transfer modes
- Ping-Pong mode (automatic switch between two DPSRAM start addresses after each block transfer complete)
- DMA request for each channel can be selected from any supported interrupt source
- Debug support features

For each DMA channel, a DMA interrupt request is generated when a block transfer is complete. Alternatively, an interrupt can be generated when half of the block has been filled.

**FIGURE 8-1: TOP LEVEL SYSTEM ARCHITECTURE USING A DEDICATED TRANSACTION BUS**



## 8.1 DMAC Registers

Each DMAC Channel x (x = 0, 1, 2, 3, 4, 5, 6 or 7) contains the following registers:

- A 16-bit DMA Channel Control register (DMAxCON)
- A 16-bit DMA Channel IRQ Select register (DMAxREQ)
- A 16-bit DMA RAM Primary Start Address register (DMAxSTA)
- A 16-bit DMA RAM Secondary Start Address register (DMAxSTB)
- A 16-bit DMA Peripheral Address register (DMAxPAD)
- A 10-bit DMA Transfer Count register (DMAxCNT)

An additional pair of status registers, DMACS0 and DMACS1, are common to all DMAC channels. DMACS0 contains the DMA RAM and SFR write collision flags, XWCOLx and PWCOLx, respectively. DMACS1 indicates DMA channel and Ping-Pong mode status.

The DMAxCON, DMAxREQ, DMAxPAD and DMAxCNT are all conventional read/write registers. Reads of DMAxSTA or DMAxSTB reads the contents of the DMA RAM Address register. Writes to DMAxSTA or DMAxSTB write to the registers. This allows the user to determine the DMA buffer pointer value (address) at any time.

The interrupt flags (DMAxIF) are located in an IFSx register in the interrupt controller. The corresponding interrupt enable control bits (DMAxIE) are located in an IECx register in the interrupt controller, and the corresponding interrupt priority control bits (DMAxIP) are located in an IPCx register in the interrupt controller.

**REGISTER 8-1: DMAxCON: DMA CHANNEL x CONTROL REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
CHEN	SIZE	DIR	HALF	NULLW	—	—	—
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0
—	—	AMODE<1:0>	—	—	—	MODE<1:0>	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **CHEN:** Channel Enable bit  
               1 = Channel enabled  
               0 = Channel disabled
- bit 14      **SIZE:** Data Transfer Size bit  
               1 = Byte  
               0 = Word
- bit 13      **DIR:** Transfer Direction bit (source/destination bus select)  
               1 = Read from DMA RAM address, write to peripheral address  
               0 = Read from peripheral address, write to DMA RAM address
- bit 12      **HALF:** Early Block Transfer Complete Interrupt Select bit  
               1 = Initiate block transfer complete interrupt when half of the data has been moved  
               0 = Initiate block transfer complete interrupt when all of the data has been moved
- bit 11      **NULLW:** Null Data Peripheral Write Mode Select bit  
               1 = Null data write to peripheral in addition to DMA RAM write (DIR bit must also be clear)  
               0 = Normal operation
- bit 10-6     **Unimplemented:** Read as '0'
- bit 5-4      **AMODE<1:0>:** DMA Channel Operating Mode Select bits  
               11 = Reserved (acts as Peripheral Indirect Addressing mode)  
               10 = Peripheral Indirect Addressing mode  
               01 = Register Indirect without Post-Increment mode  
               00 = Register Indirect with Post-Increment mode
- bit 3-2      **Unimplemented:** Read as '0'
- bit 1-0      **MODE<1:0>:** DMA Channel Operating Mode Select bits  
               11 = One-Shot, Ping-Pong modes enabled (one block transfer from/to each DMA RAM buffer)  
               10 = Continuous, Ping-Pong modes enabled  
               01 = One-Shot, Ping-Pong modes disabled  
               00 = Continuous, Ping-Pong modes disabled

**REGISTER 8-2: DMAxREQ: DMA CHANNEL x IRQ SELECT REGISTER**

R/W-0	U-0						
FORCE <sup>(1)</sup>	—	—	—	—	—	—	—
bit 15							

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	IRQSEL<6:0> <sup>(2)</sup>						
bit 7							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **FORCE:** Force DMA Transfer bit<sup>(1)</sup>

1 = Force a single DMA transfer (Manual mode)

0 = Automatic DMA transfer initiation by DMA request

bit 14-7      **Unimplemented:** Read as '0'bit 6-0      **IRQSEL<6:0>:** DMA Peripheral IRQ Number Select bits<sup>(2)</sup>

0000000-1111111 = DMAIRQ0-DMAIRQ127 selected to be Channel DMAREQ

**Note 1:** This bit cannot be cleared by the user. It is cleared by hardware when the forced DMA transfer is complete.

**2:** Refer to [Table 7-1](#) for a complete listing of IRQ numbers for all interrupt sources.

REGISTER 8-3: DMAxSTA: DMA CHANNEL x RAM START ADDRESS REGISTER A<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STA<15:8>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STA<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **STA<15:0>**: Primary DMA RAM Start Address bits (source or destination)

**Note 1:** A read of this address register returns the current contents of the DMA RAM Address register, not the contents written to STA<15:0>. If the channel is enabled (i.e., active), writes to this register may result in unpredictable behavior of the DMA channel and should be avoided.

REGISTER 8-4: DMAxSTB: DMA CHANNEL x RAM START ADDRESS REGISTER B<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STB<15:8>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STB<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **STB<15:0>**: Secondary DMA RAM Start Address bits (source or destination)

**Note 1:** A read of this address register returns the current contents of the DMA RAM Address register, not the contents written to STB<15:0>. If the channel is enabled (i.e., active), writes to this register may result in unpredictable behavior of the DMA channel and should be avoided.

**REGISTER 8-5: DMAxPAD: DMA CHANNEL x PERIPHERAL ADDRESS REGISTER<sup>(1)</sup>**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PAD<15:8>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PAD<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **PAD<15:0>**: Peripheral Address Register bits

**Note 1:** If the channel is enabled (i.e., active), writes to this register may result in unpredictable behavior of the DMA channel and should be avoided.

**REGISTER 8-6: DMAxCNT: DMA CHANNEL x TRANSFER COUNT REGISTER<sup>(1)</sup>**

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	CNT<9:8> <sup>(2)</sup>	
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CNT<7:0> <sup>(2)</sup>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-10      **Unimplemented:** Read as '0'bit 9-0      **CNT<9:0>**: DMA Transfer Count Register bits<sup>(2)</sup>

**Note 1:** If the channel is enabled (i.e., active), writes to this register may result in unpredictable behavior of the DMA channel and should be avoided.

**2:** Number of DMA transfers = CNT<9:0> + 1.

## REGISTER 8-7: DMACS0: DMA CONTROLLER STATUS REGISTER 0

| R/C-0  |
|--------|--------|--------|--------|--------|--------|--------|--------|
| PWCOL7 | PWCOL6 | PWCOL5 | PWCOL4 | PWCOL3 | PWCOL2 | PWCOL1 | PWCOL0 |
| bit 15 | bit 8  |        |        |        |        |        |        |

| R/C-0  |
|--------|--------|--------|--------|--------|--------|--------|--------|
| XWCOL7 | XWCOL6 | XWCOL5 | XWCOL4 | XWCOL3 | XWCOL2 | XWCOL1 | XWCOL0 |
| bit 7  | bit 0  |        |        |        |        |        |        |

<b>Legend:</b>	C = Clear only bit
R = Readable bit	W = Writable bit
-n = Value at POR	U = Unimplemented bit, read as '0'
	'1' = Bit is set
	'0' = Bit is cleared
	x = Bit is unknown

- bit 15      **PWCOL7:** Channel 7 Peripheral Write Collision Flag bit  
1 = Write collision detected  
0 = No write collision detected
- bit 14      **PWCOL6:** Channel 6 Peripheral Write Collision Flag bit  
1 = Write collision detected  
0 = No write collision detected
- bit 13      **PWCOL5:** Channel 5 Peripheral Write Collision Flag bit  
1 = Write collision detected  
0 = No write collision detected
- bit 12      **PWCOL4:** Channel 4 Peripheral Write Collision Flag bit  
1 = Write collision detected  
0 = No write collision detected
- bit 11      **PWCOL3:** Channel 3 Peripheral Write Collision Flag bit  
1 = Write collision detected  
0 = No write collision detected
- bit 10      **PWCOL2:** Channel 2 Peripheral Write Collision Flag bit  
1 = Write collision detected  
0 = No write collision detected
- bit 9      **PWCOL1:** Channel 1 Peripheral Write Collision Flag bit  
1 = Write collision detected  
0 = No write collision detected
- bit 8      **PWCOL0:** Channel 0 Peripheral Write Collision Flag bit  
1 = Write collision detected  
0 = No write collision detected
- bit 7      **XWCOL7:** Channel 7 DMA RAM Write Collision Flag bit  
1 = Write collision detected  
0 = No write collision detected
- bit 6      **XWCOL6:** Channel 6 DMA RAM Write Collision Flag bit  
1 = Write collision detected  
0 = No write collision detected
- bit 5      **XWCOL5:** Channel 5 DMA RAM Write Collision Flag bit  
1 = Write collision detected  
0 = No write collision detected
- bit 4      **XWCOL4:** Channel 4 DMA RAM Write Collision Flag bit  
1 = Write collision detected  
0 = No write collision detected

**REGISTER 8-7: DMACS0: DMA CONTROLLER STATUS REGISTER 0 (CONTINUED)**

- |       |  |
|-------|--|
| bit 3 | <b>XWCOL3:</b> Channel 3 DMA RAM Write Collision Flag bit<br>1 = Write collision detected<br>0 = No write collision detected |
| bit 2 | <b>XWCOL2:</b> Channel 2 DMA RAM Write Collision Flag bit<br>1 = Write collision detected<br>0 = No write collision detected |
| bit 1 | <b>XWCOL1:</b> Channel 1 DMA RAM Write Collision Flag bit<br>1 = Write collision detected<br>0 = No write collision detected |
| bit 0 | <b>XWCOL0:</b> Channel 0 DMA RAM Write Collision Flag bit<br>1 = Write collision detected<br>0 = No write collision detected |

**REGISTER 8-8: DMACS1: DMA CONTROLLER STATUS REGISTER 1**

U-0	U-0	U-0	U-0	R-1	R-1	R-1	R-1			
—	—	—	—	LSTCH<3:0>						
bit 15							bit 8			

| R-0   |
|-------|-------|-------|-------|-------|-------|-------|-------|
| PPST7 | PPST6 | PPST5 | PPST4 | PPST3 | PPST2 | PPST1 | PPST0 |
| bit 7 | bit 0 |       |       |       |       |       |       |

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-12      **Unimplemented:** Read as '0'

bit 11-8      **LSTCH<3:0>:** Last DMA Channel Active bits

1111 = No DMA transfer has occurred since system Reset

1110-1000 = Reserved

0111 = Last data transfer was by DMA Channel 7

0110 = Last data transfer was by DMA Channel 6

0101 = Last data transfer was by DMA Channel 5

0100 = Last data transfer was by DMA Channel 4

0011 = Last data transfer was by DMA Channel 3

0010 = Last data transfer was by DMA Channel 2

0001 = Last data transfer was by DMA Channel 1

0000 = Last data transfer was by DMA Channel 0

bit 7      **PPST7:** Channel 7 Ping-Pong Mode Status Flag bit

1 = DMA7STB register selected

0 = DMA7STA register selected

bit 6      **PPST6:** Channel 6 Ping-Pong Mode Status Flag bit

1 = DMA6STB register selected

0 = DMA6STA register selected

bit 5      **PPST5:** Channel 5 Ping-Pong Mode Status Flag bit

1 = DMA5STB register selected

0 = DMA5STA register selected

bit 4      **PPST4:** Channel 4 Ping-Pong Mode Status Flag bit

1 = DMA4STB register selected

0 = DMA4STA register selected

bit 3      **PPST3:** Channel 3 Ping-Pong Mode Status Flag bit

1 = DMA3STB register selected

0 = DMA3STA register selected

bit 2      **PPST2:** Channel 2 Ping-Pong Mode Status Flag bit

1 = DMA2STB register selected

0 = DMA2STA register selected

bit 1      **PPST1:** Channel 1 Ping-Pong Mode Status Flag bit

1 = DMA1STB register selected

0 = DMA1STA register selected

bit 0      **PPST0:** Channel 0 Ping-Pong Mode Status Flag bit

1 = DMA0STB register selected

0 = DMA0STA register selected

**REGISTER 8-9: DSADR: MOST RECENT DMA RAM ADDRESS**

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
DSADR<15:8>							
bit 15							bit 8

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
DSADR<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0

**DSADR<15:0>:** Most Recent DMA RAM Address Accessed by DMA Controller bits

**NOTES:**

## 9.0 OSCILLATOR CONFIGURATION

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 39. Oscillator (Part III)**” (DS70216) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

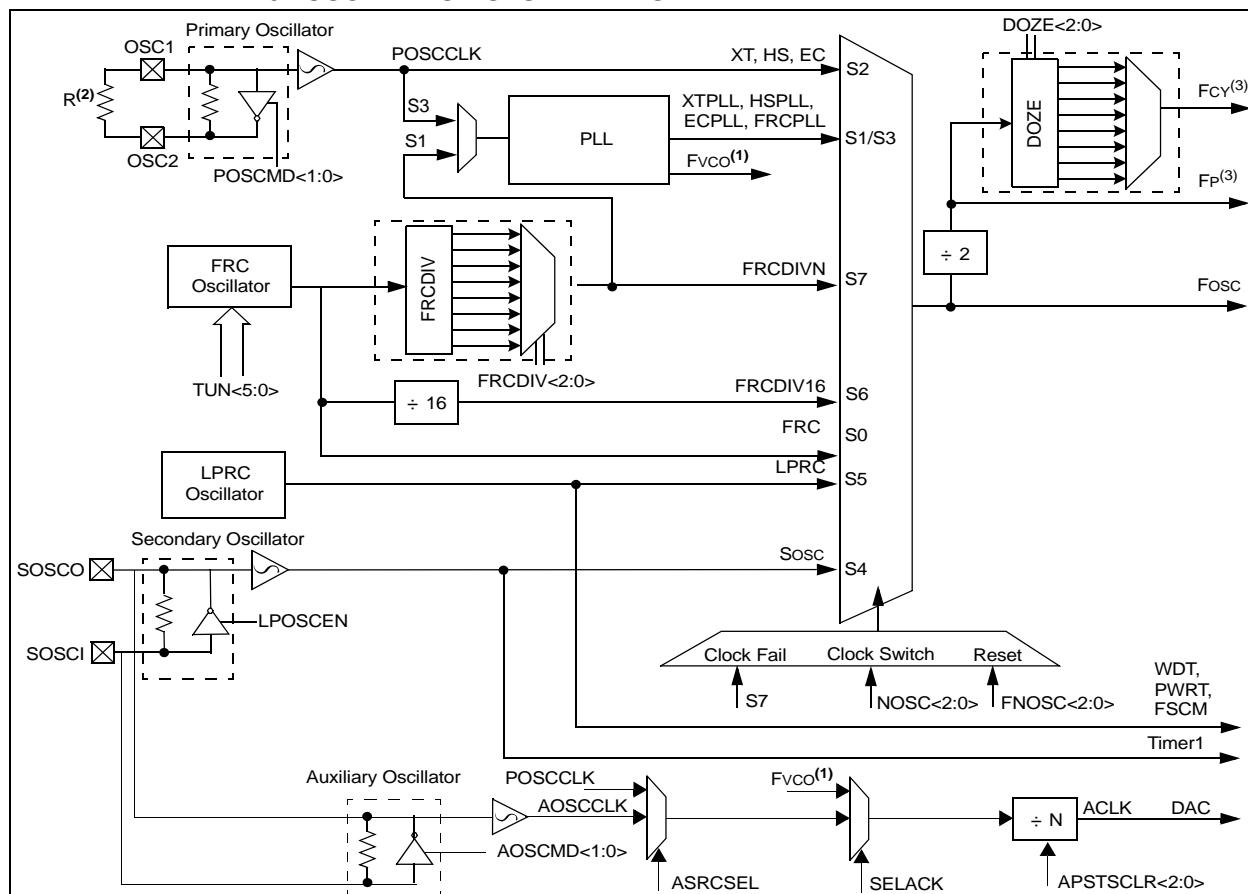
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 oscillator system provides:

- External and internal oscillator options as clock sources
- An on-chip Phase-Locked Loop (PLL) to scale the internal operating frequency to the required system clock frequency
- An internal FRC oscillator that can also be used with the PLL, thereby allowing full-speed operation without any external clock generation hardware
- Clock switching between various clock sources
- Programmable clock postscaler for system power savings
- A Fail-Safe Clock Monitor (FSCM) that detects clock failure and takes fail-safe measures
- An Oscillator Control register (OSCCON)
- Non-volatile Configuration bits for main oscillator selection
- An auxiliary crystal oscillator for audio DAC

A simplified diagram of the oscillator system is shown in [Figure 9-1](#).

**FIGURE 9-1: dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 AND dsPIC33FJ128MCX02/X04 OSCILLATOR SYSTEM DIAGRAM**



**Note 1:** See [Figure 9-2](#) for PLL details.

**2:** If the Oscillator is used with XT or HS modes, an external parallel resistor with the value of  $1\text{ M}\Omega$  must be connected.

**3:** The term FP refers to the clock source for all the peripherals, while FCY refers to the clock source for the CPU. Throughout this document FCY and FP are used interchangeably, except in the case of Doze mode. FP and FCY will be different when Doze mode is used in any ratio other than 1:1, which is the default.

## 9.1 CPU Clocking System

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices provide seven system clock options:

- Fast RC (FRC) Oscillator
- FRC Oscillator with Phase Locked Loop (PLL)
- Primary (XT, HS or EC) Oscillator
- Primary Oscillator with PLL
- Secondary (LP) Oscillator
- Low-Power RC (LPRC) Oscillator
- FRC Oscillator with postscaler

### 9.1.1 SYSTEM CLOCK SOURCES

The Fast RC (FRC) internal oscillator runs at a nominal frequency of 7.37 MHz. User software can tune the FRC frequency. User software can optionally specify a factor (ranging from 1:2 to 1:256) by which the FRC clock frequency is divided. This factor is selected using the FRCDIV<2:0> bits (CLKDIV<10:8>).

The primary oscillator can use one of the following as its clock source:

- Crystal (XT): Crystals and ceramic resonators in the range of 3 MHz to 10 MHz. The crystal is connected to the OSC1 and OSC2 pins.
- High-Speed Crystal (HS): Crystals in the range of 10 MHz to 40 MHz. The crystal is connected to the OSC1 and OSC2 pins.
- External Clock (EC): External clock signal is directly applied to the OSC1 pin.

The secondary (LP) oscillator is designed for low power and uses a 32.768 kHz crystal or ceramic resonator. The LP oscillator uses the SOSCI and SOSCO pins.

The Low-Power RC (LPRC) internal oscillator runs at a nominal frequency of 32.768 kHz. It is also used as a reference clock by the Watchdog Timer (WDT) and Fail-Safe Clock Monitor (FSCM).

The clock signals generated by the FRC and primary oscillators can be optionally applied to an on-chip PLL to provide a wide range of output frequencies for device operation. PLL configuration is described in [Section 9.1.4 “PLL Configuration”](#).

The FRC frequency depends on the FRC accuracy (see [Table 31-19](#)) and the value of the FRC Oscillator Tuning register (see [Register 9-4](#)).

### 9.1.2 SYSTEM CLOCK SELECTION

The oscillator source used at a device Power-on Reset event is selected by using the Configuration bit settings. The oscillator Configuration bit settings are located in the Configuration registers in the program memory. (Refer to [Section 28.1 “Configuration Bits”](#) for further details.) The Initial Oscillator Selection Configuration bits, FNOSC<2:0> (FOSCSEL<2:0>), and the Primary Oscillator Mode Select Configuration bits, POSCMD<1:0> (FOSC<1:0>), select the oscillator source that is used at a Power-on Reset. The FRC primary oscillator is the default (unprogrammed) selection.

The Configuration bits allow users to choose among 12 different clock modes, shown in [Table 9-1](#).

The output of the oscillator (or the output of the PLL if a PLL mode has been selected) FOSC is divided by 2 to generate the device instruction clock (FcY) and the peripheral clock time base (Fp). FcY defines the operating speed of the device, and speeds up to 40 MHz are supported by the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 architecture.

Instruction execution speed or device operating frequency, FcY, is given by:

### EQUATION 9-1: DEVICE OPERATING FREQUENCY

$$FcY = \frac{Fosc}{2}$$

### 9.1.3 AUXILIARY OSCILLATOR

The Auxiliary Oscillator (AOSC) can be used for peripheral that needs to operate at a frequency unrelated to the system clock such as DAC.

The Auxiliary Oscillator can use one of the following as its clock source:

- Crystal (XT): Crystal and ceramic resonators in the range of 3 MHz to 10 MHz. The crystal is connected to the SOCI and SOSCO pins.
- High-Speed Crystal (HS): Crystals in the range of 10 to 40 Hz. The crystal is connected to the SOSCI and SOSCO pins.
- External Clock (EC): External clock signal up to 64 MHz. The external clock signal is directly applied to SOSCI pin.

#### 9.1.4 PLL CONFIGURATION

The primary oscillator and internal FRC oscillator can optionally use an on-chip PLL to obtain higher speeds of operation. The PLL provides significant flexibility in selecting the device operating speed. A block diagram of the PLL is shown in [Figure 9-2](#).

The output of the primary oscillator or FRC, denoted as  $F_{IN}$ , is divided down by a prescale factor ( $N_1$ ) of 2, 3, ... or 33 before being provided to the PLL's Voltage Controlled Oscillator (VCO). The input to the VCO must be selected in the range of 0.8 MHz to 8 MHz. The prescale factor,  $N_1$ , is selected using the  $PLL_{PRE}<4:0>$  bits (CLKDIV<4:0>).

The PLL Feedback Divisor, selected using the  $PLL_{DIV}<8:0>$  bits (PLLFB $D$ <8:0>), provides a factor  $M$ , by which the input to the VCO is multiplied. This factor must be selected such that the resulting VCO output frequency is in the range of 100 MHz to 200 MHz.

The VCO output is further divided by a postscale factor  $N_2$ . This factor is selected using the  $PLL_{POST}<1:0>$  bits (CLKDIV<7:6>).  $N_2$  can be either 2, 4 or 8, and must be selected such that the PLL output frequency ( $F_{OSC}$ ) is in the range of 12.5 MHz to 80 MHz, which generates device operating speeds of 6.25-40 MIPS.

For a primary oscillator or FRC oscillator, output  $F_{IN}$ , the PLL output  $F_{OSC}$  is given by:

#### EQUATION 9-2: $F_{OSC}$ CALCULATION

$$F_{OSC} = F_{IN} \cdot \left( \frac{M}{N_1 \cdot N_2} \right)$$

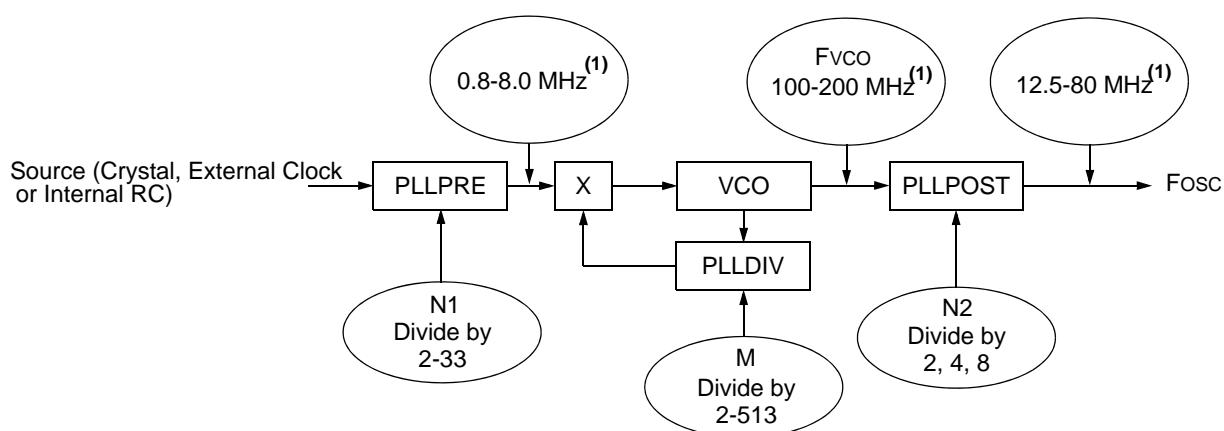
For example, suppose a 10 MHz crystal is being used with the selected oscillator mode of XT with PLL.

- If  $PLL_{PRE}<4:0> = 0$ , then  $N_1 = 2$ . This yields a VCO input of  $10/2 = 5$  MHz, which is within the acceptable range of 0.8 MHz - 8 MHz.
- If  $PLL_{DIV}<8:0> = 0x1E$ , then  $M = 32$ . This yields a VCO output of  $5 \times 32 = 160$  MHz, which is within the 100 MHz - 200 MHz ranged needed.
- If  $PLL_{POST}<1:0> = 0$ , then  $N_2 = 2$ . This provides a  $F_{OSC}$  of  $160/2 = 80$  MHz. The resultant device operating speed is  $80/2 = 40$  MIPS.

#### EQUATION 9-3: XT WITH PLL MODE EXAMPLE

$$FCY = \frac{F_{OSC}}{2} = \frac{1}{2} \left( \frac{10000000 \cdot 32}{2 \cdot 2} \right) = 40MIPS$$

**FIGURE 9-2: dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 AND dsPIC33FJ128MCX02/X04 PLL BLOCK DIAGRAM**



**Note 1:** This frequency range must be satisfied at all times.

**TABLE 9-1: CONFIGURATION BIT VALUES FOR CLOCK SELECTION**

Oscillator Mode	Oscillator Source	POSCMD<1:0>	FNOSC<2:0>	See Note
Fast RC Oscillator with Divide-by-N (FRCDIVN)	Internal	xx	111	1, 2
Fast RC Oscillator with Divide-by-16 (FRCDIV16)	Internal	xx	110	1
Low-Power RC Oscillator (LPRC)	Internal	xx	101	1
Secondary (Timer1) Oscillator (Sosc)	Secondary	xx	100	1
Primary Oscillator (HS) with PLL (HSPLL)	Primary	10	011	—
Primary Oscillator (XT) with PLL (XTPLL)	Primary	01	011	—
Primary Oscillator (EC) with PLL (ECPLL)	Primary	00	011	1
Primary Oscillator (HS)	Primary	10	010	—
Primary Oscillator (XT)	Primary	01	010	—
Primary Oscillator (EC)	Primary	00	010	1
Fast RC Oscillator with PLL (FRCPLL)	Internal	xx	001	1
Fast RC Oscillator (FRC)	Internal	xx	000	1

**Note 1:** OSC2 pin function is determined by the OSCIOFNC Configuration bit.

**2:** This is the default oscillator mode for an unprogrammed (erased) device.

**REGISTER 9-1: OSCCON: OSCILLATOR CONTROL REGISTER<sup>(1,3)</sup>**

U-0	R-0	R-0	R-0	U-0	R/W-y	R/W-y	R/W-y
—	COSC<2:0>			—	NOSC<2:0> <sup>(2)</sup>		
bit 15	bit 8						

R/W-0	R/W-0	R-0	U-0	R/C-0	U-0	R/W-0	R/W-0
CLKLOCK	IOLOCK	LOCK	—	CF	—	LPOSSEN	OSWEN
bit 7	bit 0						

<b>Legend:</b>	C = Clear only bit	y = Value set from Configuration bits on POR
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'
- bit 14-12    **COSC<2:0>:** Current Oscillator Selection bits (read-only)  
 111 = Fast RC (FRC) oscillator with Divide-by-n  
 110 = Fast RC (FRC) oscillator with Divide-by-16  
 101 = Low-Power RC (LPRC) oscillator  
 100 = Secondary Oscillator (Sosc)  
 011 = Primary oscillator (XT, HS, EC) with PLL  
 010 = Primary oscillator (XT, HS, EC)  
 001 = Fast RC (FRC) oscillator with divide-by-N and PLL (FRCDIVN + PLL)  
 000 = Fast RC (FRC) oscillator
- bit 11      **Unimplemented:** Read as '0'
- bit 10-8     **NOSC<2:0>:** New Oscillator Selection bits<sup>(2)</sup>  
 111 = Fast RC (FRC) oscillator with Divide-by-n  
 110 = Fast RC (FRC) oscillator with Divide-by-16  
 101 = Low-Power RC (LPRC) oscillator  
 100 = Secondary Oscillator (Sosc)  
 011 = Primary oscillator (XT, HS, EC) with PLL  
 010 = Primary oscillator (XT, HS, EC)  
 001 = Fast RC (FRC) oscillator with divide-by-N and PLL (FRCDIVN + PLL)  
 000 = Fast RC (FRC) oscillator
- bit 7        **CLKLOCK:** Clock Lock Enable bit  
If clock switching is enabled and FSCM is disabled, (FCKSM<1:0> (FOSC<7:6>) = 0b01)  
 1 = Clock switching is disabled, system clock source is locked  
 0 = Clock switching is enabled, system clock source can be modified by clock switching
- bit 6        **IOLOCK:** Peripheral Pin Select Lock bit  
 1 = Peripheral pin select is locked, write to peripheral pin select registers not allowed  
 0 = Peripheral pin select is not locked, write to peripheral pin select registers allowed
- bit 5        **LOCK:** PLL Lock Status bit (read-only)  
 1 = Indicates that PLL is in lock, or PLL start-up timer is satisfied  
 0 = Indicates that PLL is out of lock, start-up timer is in progress or PLL is disabled
- bit 4        **Unimplemented:** Read as '0'

- Note 1:** Writes to this register require an unlock sequence. Refer to **Section 39. "Oscillator (Part III)"** (DS70216) in the "dsPIC33F/PIC24H Family Reference Manual" (available from the Microchip web site) for details.
- 2:** Direct clock switches between any primary oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.
- 3:** This register is reset only on a Power-on Reset (POR).

REGISTER 9-1: OSCCON: OSCILLATOR CONTROL REGISTER<sup>(1,3)</sup> (CONTINUED)

bit 3	<b>CF:</b> Clock Fail Detect bit (read/clear by application) 1 = FSCM has detected clock failure 0 = FSCM has not detected clock failure
bit 2	<b>Unimplemented:</b> Read as '0'
bit 1	<b>LPOSCE:</b> Secondary (LP) Oscillator Enable bit 1 = Enable secondary oscillator 0 = Disable secondary oscillator
bit 0	<b>OSWEN:</b> Oscillator Switch Enable bit 1 = Request oscillator switch to selection specified by NOSC<2:0> bits 0 = Oscillator switch is complete

- Note 1:** Writes to this register require an unlock sequence. Refer to **Section 39. “Oscillator (Part III)”** (DS70216) in the “dsPIC33F/PIC24H Family Reference Manual” (available from the Microchip web site) for details.
- 2:** Direct clock switches between any primary oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.
- 3:** This register is reset only on a Power-on Reset (POR).

**REGISTER 9-2: CLKDIV: CLOCK DIVISOR REGISTER<sup>(2)</sup>**

R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
ROI		DOZE<2:0>		DOZEN <sup>(1)</sup>		FRCDIV<2:0>	
bit 15						bit 8	

R/W-0	R/W-1	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	PLLPOST<1:0>	—		PLLPRE<4:0>			
bit 7						bit 0	

<b>Legend:</b>	y = Value set from Configuration bits on POR
R = Readable bit	W = Writable bit
-n = Value at POR	'1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15      **ROI:** Recover on Interrupt bit  
           1 = Interrupts clear the DOZEN bit and the processor clock/peripheral clock ratio is set to 1:1  
           0 = Interrupts have no effect on the DOZEN bit
- bit 14-12     **DOZE<2:0>:** Processor Clock Reduction Select bits  
           111 = FCY/128  
           110 = FCY/64  
           101 = FCY/32  
           100 = FCY/16  
           011 = FCY/8 (default)  
           010 = FCY/4  
           001 = FCY/2  
           000 = FCY/1
- bit 11        **DOZEN:** DOZE Mode Enable bit<sup>(1)</sup>  
           1 = DOZE<2:0> field specifies the ratio between the peripheral clocks and the processor clocks  
           0 = Processor clock/peripheral clock ratio forced to 1:1
- bit 10-8      **FRCDIV<2:0>:** Internal Fast RC Oscillator Postscaler bits  
           111 = FRC divide by 256  
           110 = FRC divide by 64  
           101 = FRC divide by 32  
           100 = FRC divide by 16  
           011 = FRC divide by 8  
           010 = FRC divide by 4  
           001 = FRC divide by 2  
           000 = FRC divide by 1 (default)
- bit 7-6       **PLLPOST<1:0>:** PLL VCO Output Divider Select bits (also denoted as 'N2', PLL postscaler)  
           11 = Output/8  
           10 = Reserved  
           01 = Output/4 (default)  
           00 = Output/2
- bit 5          **Unimplemented:** Read as '0'
- bit 4-0       **PLLPRE<4:0>:** PLL Phase Detector Input Divider bits (also denoted as 'N1', PLL prescaler)  
           11111 = Input/33  
           •  
           •  
           •  
           00001 = Input/3  
           00000 = Input/2 (default)

**Note 1:** This bit is cleared when the ROI bit is set and an interrupt occurs.

**2:** This register is reset only on a Power-on Reset (POR).

REGISTER 9-3: PLLFBD: PLL FEEDBACK DIVISOR REGISTER<sup>(1)</sup>

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0 <sup>(1)</sup>
—	—	—	—	—	—	—	PLLDIV<8>
bit 15							bit 8

R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
PLLDIV<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-9      **Unimplemented:** Read as '0'bit 8-0      **PLLDIV<8:0>:** PLL Feedback Divisor bits (also denoted as 'M', PLL multiplier)

1111111111 = 513

•

•

•

000110000 = 50 (default)

•

•

•

000000010 = 4

000000001 = 3

000000000 = 2

**Note 1:** This register is reset only on a Power-on Reset (POR).

**REGISTER 9-4: OSCTUN: FRC OSCILLATOR TUNING REGISTER<sup>(2)</sup>**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—			TUN<5:0> <sup>(1)</sup>						
bit 7				bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-6

**Unimplemented:** Read as '0'

bit 5-0

**TUN<5:0>:** FRC Oscillator Tuning bits<sup>(1)</sup>

111111 = Center frequency -0.375% (7.345 MHz)

•

•

•

100001 = Center frequency -11.625% (6.52 MHz)

100000 = Center frequency -12% (6.49 MHz)

011111 = Center frequency +11.625% (8.23 MHz)

011110 = Center frequency +11.25% (8.20 MHz)

•

•

•

000001 = Center frequency +0.375% (7.40 MHz)

000000 = Center frequency (7.37 MHz nominal)

**Note 1:** OSCTUN functionality has been provided to help customers compensate for temperature effects on the FRC frequency over a wide range of temperatures. The tuning step size is an approximation and is neither characterized nor tested.

**2:** This register is reset only on a Power-on Reset (POR).

**REGISTER 9-5: ACLKCON: AUXILIARY CLOCK DIVISOR CONTROL REGISTER<sup>(1)</sup>**

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	SELACLK	AOSCMD<1:0>	APSTSCLR<2:0>			
bit 15							bit 8

R/W-0	U-0						
ASRCSEL	—	—	—	—	—	—	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14      **Unimplemented:** Read as '0'

bit 13      **SELACLK:** Select Auxiliary Clock Source for Auxiliary Clock Divider

1 = Auxiliary Oscillators provides the source clock for Auxiliary Clock Divider  
0 = PLL output (Fvco) provides the source clock for the Auxiliary Clock Divider

bit 12-11      **AOSCMD<1:0>:** Auxiliary Oscillator Mode

11 = EC External Clock Mode Select  
10 = XT Oscillator Mode Select  
01 = HS Oscillator Mode Select  
00 = Auxiliary Oscillator Disabled (default)

bit 10-8      **APSTSCLR<2:0>:** Auxiliary Clock Output Divider

111 = Divided by 1  
110 = Divided by 2  
101 = Divided by 4  
100 = Divided by 8  
011 = Divided by 16  
010 = Divided by 32  
001 = Divided by 64  
000 = Divided by 256 (default)

bit 7      **ASRCSEL:** Select Reference Clock Source for Auxiliary Clock

1 = Primary Oscillator is the Clock Source  
0 = Auxiliary Oscillator is the Clock Source

bit 6-0      **Unimplemented:** Read as '0'

**Note 1:** This register is reset only on a Power-on Reset (POR).

## 9.2 Clock Switching Operation

Applications are free to switch among any of the four clock sources (Primary, LP, FRC and LPRC) under software control at any time. To limit the possible side effects of this flexibility, dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices have a safeguard lock built into the switch process.

**Note:** Primary Oscillator mode has three different submodes (XT, HS and EC), which are determined by the POSCMD<1:0> Configuration bits. While an application can switch to and from Primary Oscillator mode in software, it cannot switch among the different primary submodes without reprogramming the device.

### 9.2.1 ENABLING CLOCK SWITCHING

To enable clock switching, the FCKSM1 Configuration bit in the Configuration register must be programmed to '0'. (Refer to [Section 28.1 "Configuration Bits"](#) for further details.) If the FCKSM1 Configuration bit is unprogrammed ('1'), the clock switching function and Fail-Safe Clock Monitor function are disabled. This is the default setting.

The NOSC control bits (OSCCON<10:8>) do not control the clock selection when clock switching is disabled. However, the COSC bits (OSCCON<14:12>) reflect the clock source selected by the FNOSC Configuration bits.

The OSWEN control bit (OSCCON<0>) has no effect when clock switching is disabled. It is held at '0' at all times.

### 9.2.2 OSCILLATOR SWITCHING SEQUENCE

Performing a clock switch requires this basic sequence:

1. If desired, read the COSC bits (OSCCON<14:12>) to determine the current oscillator source.
2. Perform the unlock sequence to allow a write to the OSCCON register high byte.
3. Write the appropriate value to the NOSC control bits (OSCCON<10:8>) for the new oscillator source.
4. Perform the unlock sequence to allow a write to the OSCCON register low byte.
5. Set the OSWEN bit (OSCCON<0>) to initiate the oscillator switch.

Once the basic sequence is completed, the system clock hardware responds automatically as follows:

1. The clock switching hardware compares the COSC status bits with the new value of the NOSC control bits. If they are the same, the clock switch is a redundant operation. In this case, the OSWEN bit is cleared automatically and the clock switch is aborted.

2. If a valid clock switch has been initiated, the LOCK (OSCCON<5>) and the CF (OSCCON<3>) status bits are cleared.
3. The new oscillator is turned on by the hardware if it is not currently running. If a crystal oscillator must be turned on, the hardware waits until the Oscillator Start-up Timer (OST) expires. If the new source is using the PLL, the hardware waits until a PLL lock is detected (LOCK = 1).
4. The hardware waits for 10 clock cycles from the new clock source and then performs the clock switch.
5. The hardware clears the OSWEN bit to indicate a successful clock transition. In addition, the NOSC bit values are transferred to the COSC status bits.
6. The old clock source is turned off at this time, with the exception of LPRC (if WDT or FSCM are enabled) or LP (if LPOSCE remains set).

**Note 1:** The processor continues to execute code throughout the clock switching sequence. Timing-sensitive code should not be executed during this time.

- 2: Direct clock switches between any primary oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.
- 3: Refer to [Section 39. "Oscillator \(Part III\)"](#) (DS70216) in the "dsPIC33F/PIC24H Family Reference Manual" for details.

## 9.3 Fail-Safe Clock Monitor (FSCM)

The Fail-Safe Clock Monitor (FSCM) allows the device to continue to operate even in the event of an oscillator failure. The FSCM function is enabled by programming. If the FSCM function is enabled, the LPRC internal oscillator runs at all times (except during Sleep mode) and is not subject to control by the Watchdog Timer.

In the event of an oscillator failure, the FSCM generates a clock failure trap event and switches the system clock over to the FRC oscillator. Then the application program can either attempt to restart the oscillator or execute a controlled shutdown. The trap can be treated as a warm Reset by simply loading the Reset address into the oscillator fail trap vector.

If the PLL multiplier is used to scale the system clock, the internal FRC is also multiplied by the same factor on clock failure. Essentially, the device switches to FRC with PLL on a clock failure.

**NOTES:**

## 10.0 POWER-SAVING FEATURES

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 9. Watchdog Timer and Power Savings Modes**” (DS70196) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

- 2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices provide the ability to manage power consumption by selectively managing clocking to the CPU and the peripherals. In general, a lower clock frequency and a reduction in the number of circuits being clocked constitutes lower consumed power.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices can manage power consumption in four ways:

- Clock frequency
- Instruction-based Sleep and Idle modes
- Software-controlled Doze mode
- Selective peripheral control in software

Combinations of these methods can be used to selectively tailor an application’s power consumption while still maintaining critical application features, such as timing-sensitive communications.

### 10.1 Clock Frequency and Clock Switching

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices allow a wide range of clock frequencies to be selected under application control. If the system clock configuration is not locked, users can choose low-power or high-precision oscillators by simply changing the NOSC bits (OSCCON<10:8>). The process of changing a system clock during operation, as well as limitations to the process, are discussed in detail in **Section 9.0 “Oscillator Configuration”**.

### EXAMPLE 10-1: PWRSAV INSTRUCTION SYNTAX

```
PWRSAV #SLEEP_MODE      ; Put the device into Sleep mode
PWRSAV #IDLE_MODE       ; Put the device into Idle mode
```

### 10.2 Instruction-Based Power-Saving Modes

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices have two special power-saving modes that are entered through the execution of a special PWRSAV instruction. Sleep mode stops clock operation and halts all code execution. Idle mode halts the CPU and code execution, but allows peripheral modules to continue operation. The assembler syntax of the PWRSAV instruction is shown in **Example 10-1**.

**Note:** SLEEP\_MODE and IDLE\_MODE are constants defined in the assembler include file for the selected device.

Sleep and Idle modes can be exited as a result of an enabled interrupt, WDT time-out or a device Reset. When the device exits these modes, it is said to wake up.

#### 10.2.1 SLEEP MODE

The following occur in Sleep mode:

- The system clock source is shut down. If an on-chip oscillator is used, it is turned off.
- The device current consumption is reduced to a minimum, provided that no I/O pin is sourcing current.
- The Fail-Safe Clock Monitor does not operate, since the system clock source is disabled.
- The LPRC clock continues to run in Sleep mode if the WDT is enabled.
- The WDT, if enabled, is automatically cleared prior to entering Sleep mode.
- Some device features or peripherals can continue to operate. This includes items such as the input change notification on the I/O ports, or peripherals that use an external clock input.
- Any peripheral that requires the system clock source for its operation is disabled.

The device wakes up from Sleep mode on any of the these events:

- Any interrupt source that is individually enabled
- Any form of device Reset
- A WDT time-out

On wake-up from Sleep mode, the processor restarts with the same clock source that was active when Sleep mode was entered.

## 10.2.2 IDLE MODE

The following occur in Idle mode:

- The CPU stops executing instructions.
- The WDT is automatically cleared.
- The system clock source remains active. By default, all peripheral modules continue to operate normally from the system clock source, but can also be selectively disabled (see [Section 10.4 "Peripheral Module Disable"](#)).
- If the WDT or FSCM is enabled, the LPRC also remains active.

The device wakes from Idle mode on any of these events:

- Any interrupt that is individually enabled
- Any device Reset
- A WDT time-out

On wake-up from Idle mode, the clock is reapplied to the CPU and instruction execution will begin (2 to 4 cycles later), starting with the instruction following the PWRSAV instruction, or the first instruction in the ISR.

## 10.2.3 INTERRUPTS COINCIDENT WITH POWER SAVE INSTRUCTIONS

Any interrupt that coincides with the execution of a PWRSAV instruction is held off until entry into Sleep or Idle mode has completed. The device then wakes up from Sleep or Idle mode.

## 10.3 Doze Mode

The preferred strategies for reducing power consumption are changing clock speed and invoking one of the power-saving modes. In some circumstances, this cannot be practical. For example, it may be necessary for an application to maintain uninterrupted synchronous communication, even while it is doing nothing else. Reducing system clock speed can introduce communication errors, while using a power-saving mode can stop communications completely.

Doze mode is a simple and effective alternative method to reduce power consumption while the device is still executing code. In this mode, the system clock continues to operate from the same source and at the same speed. Peripheral modules continue to be clocked at the same speed, while the CPU clock speed is reduced. Synchronization between the two clock domains is maintained, allowing the peripherals to access the SFRs while the CPU executes code at a slower rate.

Doze mode is enabled by setting the DOZEN bit (CLKDIV<11>). The ratio between peripheral and core clock speed is determined by the DOZE<2:0> bits (CLKDIV<14:12>). There are eight possible configurations, from 1:1 to 1:128, with 1:1 being the default setting.

Programs can use Doze mode to selectively reduce power consumption in event-driven applications. This allows clock-sensitive functions, such as synchronous communications, to continue without interruption while the CPU idles, waiting for something to invoke an interrupt routine. An automatic return to full-speed CPU operation on interrupts can be enabled by setting the ROI bit (CLKDIV<15>). By default, interrupt events have no effect on Doze mode operation.

For example, suppose the device is operating at 20 MIPS and the ECAN module has been configured for 500 kbps based on this device operating speed. If the device is placed in Doze mode with a clock frequency ratio of 1:4, the ECAN module continues to communicate at the required bit rate of 500 kbps, but the CPU now starts executing instructions at a frequency of 5 MIPS.

## 10.4 Peripheral Module Disable

The Peripheral Module Disable (PMD) registers provide a method to disable a peripheral module by stopping all clock sources supplied to that module. When a peripheral is disabled using the appropriate PMD control bit, the peripheral is in a minimum power consumption state. The control and status registers associated with the peripheral are also disabled, so writes to those registers do not have effect and read values are invalid.

A peripheral module is enabled only if both the associated bit in the PMD register is cleared and the peripheral is supported by the specific dsPIC® DSC variant. If the peripheral is present in the device, it is enabled in the PMD register by default.

**Note:** If a PMD bit is set, the corresponding module is disabled after a delay of one instruction cycle. Similarly, if a PMD bit is cleared, the corresponding module is enabled after a delay of one instruction cycle (assuming the module control registers are already configured to enable module operation).

**REGISTER 10-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
T5MD	T4MD	T3MD	T2MD	T1MD	QEI1MD	PWM1MD	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	C1MD	AD1MD
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **T5MD:** Timer5 Module Disable bit  
1 = Timer5 module is disabled  
0 = Timer5 module is enabled
- bit 14      **T4MD:** Timer4 Module Disable bit  
1 = Timer4 module is disabled  
0 = Timer4 module is enabled
- bit 13      **T3MD:** Timer3 Module Disable bit  
1 = Timer3 module is disabled  
0 = Timer3 module is enabled
- bit 12      **T2MD:** Timer2 Module Disable bit  
1 = Timer2 module is disabled  
0 = Timer2 module is enabled
- bit 11      **T1MD:** Timer1 Module Disable bit  
1 = Timer1 module is disabled  
0 = Timer1 module is enabled
- bit 10      **QEI1MD:** QEI1 Module Disable bit  
1 = QEI1 module is disabled  
0 = QEI1 module is enabled
- bit 9      **PWM1MD:** PWM1 Module Disable bit  
1 = PWM1 module is disabled  
0 = PWM1 module is enabled
- bit 8      **Unimplemented:** Read as '0'
- bit 7      **I2C1MD:** I<sup>2</sup>C1 Module Disable bit  
1 = I<sup>2</sup>C1 module is disabled  
0 = I<sup>2</sup>C1 module is enabled
- bit 6      **U2MD:** UART2 Module Disable bit  
1 = UART2 module is disabled  
0 = UART2 module is enabled
- bit 5      **U1MD:** UART1 Module Disable bit  
1 = UART1 module is disabled  
0 = UART1 module is enabled
- bit 4      **SPI2MD:** SPI2 Module Disable bit  
1 = SPI2 module is disabled  
0 = SPI2 module is enabled
- bit 3      **SPI1MD:** SPI1 Module Disable bit  
1 = SPI1 module is disabled  
0 = SPI1 module is enabled
- bit 2      **Unimplemented:** Read as '0'

**REGISTER 10-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1 (CONTINUED)**

bit 1      **C1MD:** ECAN1 Module Disable bit

  1 = ECAN1 module is disabled

  0 = ECAN1 module is enabled

bit 0      **AD1MD:** ADC1 Module Disable bit

  1 = ADC1 module is disabled

  0 = ADC1 module is enabled

**REGISTER 10-2: PMD2: PERIPHERAL MODULE DISABLE CONTROL REGISTER 2**

R/W-0	R/W-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
IC8MD	IC7MD	—	—	—	—	IC2MD	IC1MD
bit 15							bit 8

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	OC4MD	OC3MD	OC2MD	OC1MD
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **IC8MD:** Input Capture 8 Module Disable bit  
               1 = Input Capture 8 module is disabled  
               0 = Input Capture 8 module is enabled
- bit 14      **IC7MD:** Input Capture 7 Module Disable bit  
               1 = Input Capture 7 module is disabled  
               0 = Input Capture 7 module is enabled
- bit 13-10    **Unimplemented:** Read as '0'
- bit 9        **IC2MD:** Input Capture 2 Module Disable bit  
               1 = Input Capture 2 module is disabled  
               0 = Input Capture 2 module is enabled
- bit 8        **IC1MD:** Input Capture 1 Module Disable bit  
               1 = Input Capture 1 module is disabled  
               0 = Input Capture 1 module is enabled
- bit 7-4      **Unimplemented:** Read as '0'
- bit 3        **OC4MD:** Output Compare 4 Module Disable bit  
               1 = Output Compare 4 module is disabled  
               0 = Output Compare 4 module is enabled
- bit 2        **OC3MD:** Output Compare 3 Module Disable bit  
               1 = Output Compare 3 module is disabled  
               0 = Output Compare 3 module is enabled
- bit 1        **OC2MD:** Output Compare 2 Module Disable bit  
               1 = Output Compare 2 module is disabled  
               0 = Output Compare 2 module is enabled
- bit 0        **OC1MD:** Output Compare 1 Module Disable bit  
               1 = Output Compare 1 module is disabled  
               0 = Output Compare 1 module is enabled

## REGISTER 10-3: PMD3: PERIPHERAL MODULE DISABLE CONTROL REGISTER 3

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	CMPMD	RTCCMD	PMPMD
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0
CRCMD	DAC1MD	QEI2MD	PWM2MD	—	—	—	—
bit 7						bit 0	

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-11      **Unimplemented:** Read as '0'
- bit 10      **CMPMD:** Comparator Module Disable bit  
               1 = Comparator module is disabled  
               0 = Comparator module is enabled
- bit 9      **RTCCMD:** RTCC Module Disable bit  
               1 = RTCC module is disabled  
               0 = RTCC module is enabled
- bit 8      **PMPMD:** PMP Module Disable bit  
               1 = PMP module is disabled  
               0 = PMP module is enabled
- bit 7      **CRCMD:** CRC Module Disable bit  
               1 = CRC module is disabled  
               0 = CRC module is enabled
- bit 6      **DAC1MD:** DAC1 Module Disable bit  
               1 = DAC1 module is disabled  
               0 = DAC1 module is enabled
- bit 5      **QEI2MD:** QEI2 Module Disable bit  
               1 = QEI2 module is disabled  
               0 = QEI2 module is enabled
- bit 4      **PWM2MD:** PWM2 Module Disable bit  
               1 = PWM2 module is disabled  
               0 = PWM2 module is enabled
- bit 3-0     **Unimplemented:** Read as '0'

## 11.0 I/O PORTS

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 10. I/O Ports**” (DS70193) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

All of the device pins (except VDD, Vss, MCLR and OSC1/CLK1) are shared among the peripherals and the parallel I/O ports. All I/O input ports feature Schmitt Trigger inputs for improved noise immunity.

### 11.1 Parallel I/O (PIO) Ports

Generally, a parallel I/O port that shares a pin with a peripheral is subservient to the peripheral. The peripheral's output buffer data and control signals are provided to a pair of multiplexers. The multiplexers select whether the peripheral or the associated port

has ownership of the output data and control signals of the I/O pin. The logic also prevents loop through, in which a port's digital output can drive the input of a peripheral that shares the same pin. [Figure 11-1](#) shows how ports are shared with other peripherals and the associated I/O pin to which they are connected.

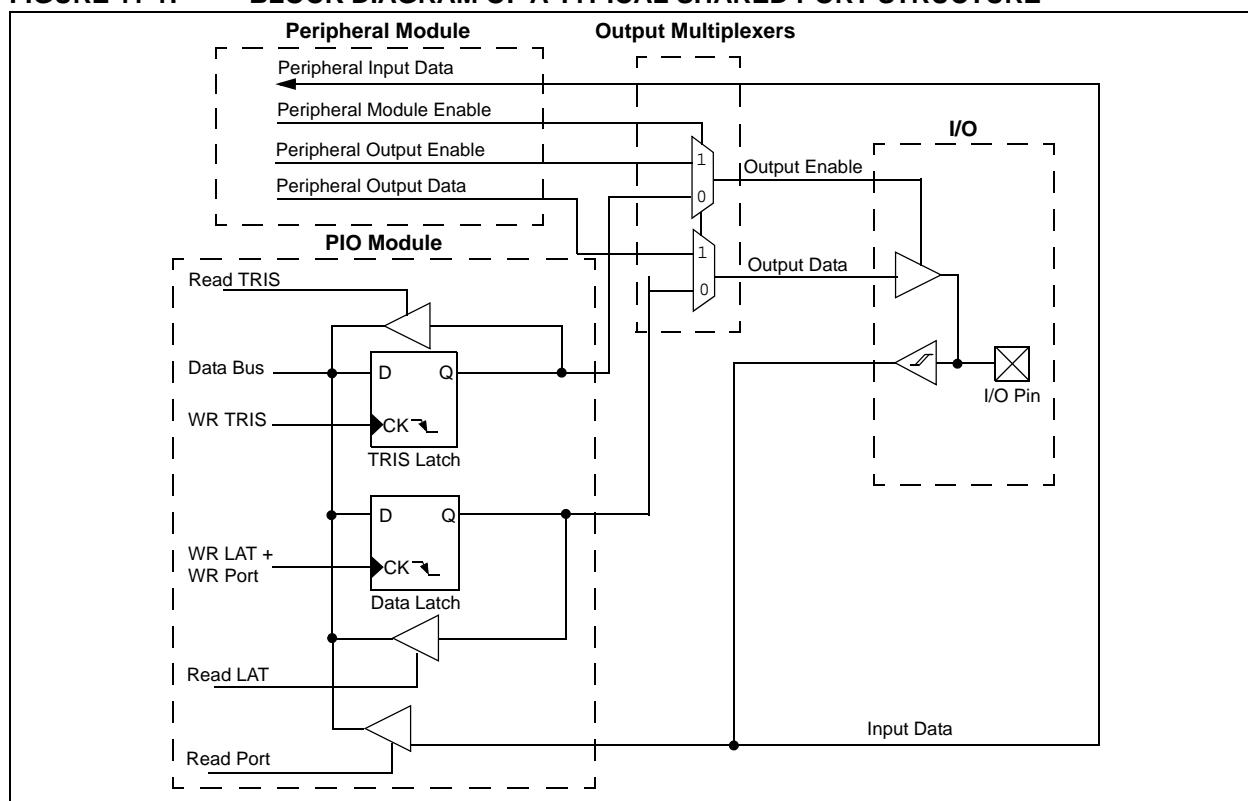
When a peripheral is enabled and the peripheral is actively driving an associated pin, the use of the pin as a general purpose output pin is disabled. The I/O pin can be read, but the output driver for the parallel port bit is disabled. If a peripheral is enabled, but the peripheral is not actively driving a pin, that pin can be driven by a port.

All port pins have three registers directly associated with their operation as digital I/O. The data direction register (TRISx) determines whether the pin is an input or an output. If the data direction bit is a ‘1’, then the pin is an input. All port pins are defined as inputs after a Reset. Reads from the latch (LATx) read the latch. Writes to the latch write the latch. Reads from the port (PORTx) read the port pins, while writes to the port pins write the latch.

Any bit and its associated data and control registers that are not valid for a particular device is disabled. This means the corresponding LATx and TRISx registers and the port pin are read as zeros.

When a pin is shared with another peripheral or function that is defined as an input only, it is nevertheless regarded as a dedicated port because there is no other competing source of outputs.

**FIGURE 11-1: BLOCK DIAGRAM OF A TYPICAL SHARED PORT STRUCTURE**



## 11.2 Open-Drain Configuration

In addition to the PORT, LAT and TRIS registers for data control, some port pins can also be individually configured for either digital or open-drain output. This is controlled by the Open-Drain Control register, ODCx, associated with each port. Setting any of the bits configures the corresponding pin to act as an open-drain output.

The open-drain feature allows the generation of outputs higher than VDD (e.g., 5V) on any desired 5V tolerant pins by using external pull-up resistors. The maximum open-drain voltage allowed is the same as the maximum VIH specification.

See “[Pin Diagrams](#)” for the available pins and their functionality.

## 11.3 Configuring Analog Port Pins

The AD1PCFGL and TRIS registers control the operation of the analog-to-digital (A/D) port pins. The port pins that are to function as analog inputs must have their corresponding TRIS bit set (input). If the TRIS bit is cleared (output), the digital output level (VOH or VOL) is converted.

The AD1PCFGL register has a default value of 0x0000; therefore, all pins that share ANx functions are analog (not digital) by default.

When the PORT register is read, all pins configured as analog input channels are read as cleared (a low level).

Pins configured as digital inputs do not convert an analog input. Analog levels on any pin defined as a digital input (including the ANx pins) can cause the input buffer to consume current that exceeds the device specifications.

## 11.4 I/O Port Write/Read Timing

One instruction cycle is required between a port direction change or port write operation and a read operation of the same port. Typically, this instruction would be an `NOP`, as shown in [Example 11-1](#).

## 11.5 Input Change Notification

The input change notification function of the I/O ports allows the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices to generate interrupt requests to the processor in response to a change-of-state on selected input pins. This feature can detect input change-of-states even in Sleep mode, when the clocks are disabled. Depending on the device pin count, up to 21 external signals (CNx pin) can be selected (enabled) for generating an interrupt request on a change-of-state.

Four control registers are associated with the CN module. The CNEN1 and CNEN2 registers contain the interrupt enable control bits for each of the CN input pins. Setting any of these bits enables a CN interrupt for the corresponding pins.

Each CN pin also has a weak pull-up connected to it. The pull-ups act as a current source connected to the pin, and eliminate the need for external resistors when push-button or keypad devices are connected. The pull-ups are enabled separately using the CNPU1 and CNPU2 registers, which contain the control bits for each of the CN pins. Setting any of the control bits enables the weak pull-ups for the corresponding pins.

**Note:** Pull-ups on change notification pins should always be disabled when the port pin is configured as a digital output.

### EXAMPLE 11-1: PORT WRITE/READ EXAMPLE

```
MOV 0xFF00, W0          ; Configure PORTB<15:8> as inputs
MOV W0, TRISBB          ; and PORTB<7:0> as outputs
NOP                   ; Delay 1 cycle
btss PORTB, #13         ; Next Instruction
```

## 11.6 Peripheral Pin Select

Peripheral pin select configuration enables peripheral set selection and placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, programmers can better tailor the microcontroller to their entire application, rather than trimming the application to fit the device.

The peripheral pin select configuration feature operates over a fixed subset of digital I/O pins. Programmers can independently map the input and/or output of most digital peripherals to any one of these I/O pins. Peripheral pin select is performed in software, and generally does not require the device to be reprogrammed. Hardware safeguards are included that prevent accidental or spurious changes to the peripheral mapping, once it has been established.

### 11.6.1 AVAILABLE PINS

The peripheral pin select feature is used with a range of up to 26 pins. The number of available pins depends on the particular device and its pin count. Pins that support the peripheral pin select feature include the designation RPn in their full pin designation, where RP designates a remappable peripheral and n is the remappable pin number.

### 11.6.2 CONTROLLING PERIPHERAL PIN SELECT

Peripheral pin select features are controlled through two sets of special function registers: one to map peripheral inputs, and one to map outputs. Because they are separately controlled, a particular peripheral's input and output (if the peripheral has both) can be placed on any selectable function pin without constraint.

The association of a peripheral to a peripheral selectable pin is handled in two different ways, depending on whether an input or output is being mapped.

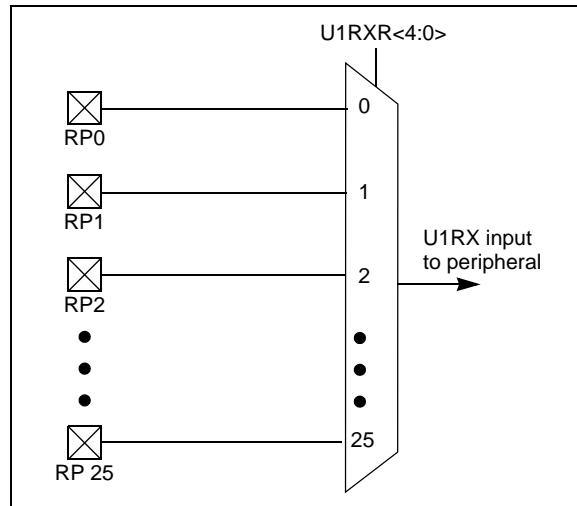
#### 11.6.2.1 Input Mapping

The inputs of the peripheral pin select options are mapped on the basis of the peripheral. A control register associated with a peripheral dictates the pin it is mapped to. The RPINRx registers are used to configure peripheral input mapping (see [Register 11-1](#) through [Register 11-20](#)). Each register contains sets of 5-bit fields, with each set associated with one of the remappable peripherals. Programming a given peripheral's bit field with an appropriate 5-bit value maps the RPn pin with that value to that peripheral. For any given device, the valid range of values for any bit field corresponds to the maximum number of peripheral pin selections supported by the device.

[Figure 11-2](#) Illustrates remappable pin selection for U1RX input.

**Note:** For input mapping only, the Peripheral Pin Select (PPS) functionality does not have priority over the TRISx settings. Therefore, when configuring the RPx pin for input, the corresponding bit in the TRISx register must also be configured for input (i.e., set to '1').

**FIGURE 11-2: REMAPPABLE MUX INPUT FOR U1RX**



**TABLE 11-1: SELECTABLE INPUT SOURCES (MAPS INPUT TO FUNCTION)<sup>(1)</sup>**

Input Name	Function Name	Register	Configuration Bits
External Interrupt 1	INT1	RPINR0	INT1R<4:0>
External Interrupt 2	INT2	RPINR1	INT2R<4:0>
Timer2 External Clock	T2CK	RPINR3	T2CKR<4:0>
Timer3 External Clock	T3CK	RPINR3	T3CKR<4:0>
Timer4 External Clock	T4CK	RPINR4	T4CKR<4:0>
Timer5 External Clock	T5CK	RPINR4	T5CKR<4:0>
Input Capture 1	IC1	RPINR7	IC1R<4:0>
Input Capture 2	IC2	RPINR7	IC2R<4:0>
Input Capture 7	IC7	RPINR10	IC7R<4:0>
Input Capture 8	IC8	RPINR10	IC8R<4:0>
Output Compare Fault A	OCFA	RPINR11	OCFAR<4:0>
PWM1 Fault	<u>FLTA1</u>	RPINR12	FLTA1R<4:0>
PWM2 Fault	<u>FLTA2</u>	RPINR13	FLTA2R<4:0>
QEI1 Phase A	QEA1	RPINR14	QEA1R<4:0>
QEI1 Phase B	QEB1	RPINR14	QEB1R<4:0>
QEI1 Index	IDX1	RPINR15	IDX1R<4:0>
QEI2 Phase A	QEA2	RPINR16	QEA2R<4:0>
QEI2Phase B	QEB2	RPINR16	QEB2R<4:0>
QEI2 Index	IDX2	RPINR17	IDX2R<4:0>
UART1 Receive	U1RX	RPINR18	U1RXR<4:0>
UART1 Clear To Send	<u>U1CTS</u>	RPINR18	U1CTSR<4:0>
UART2 Receive	U2RX	RPINR19	U2RXR<4:0>
UART2 Clear To Send	<u>U2CTS</u>	RPINR19	U2CTSR<4:0>
SPI1 Data Input	SDI1	RPINR20	SDI1R<4:0>
SPI1 Clock Input	SCK1	RPINR20	SCK1R<4:0>
SPI1 Slave Select Input	<u>SS1</u>	RPINR21	SS1R<4:0>
SPI2 Data Input	SDI2	RPINR22	SDI2R<4:0>
SPI2 Clock Input	SCK2	RPINR22	SCK2R<4:0>
SPI2 Slave Select Input	<u>SS2</u>	RPINR23	SS2R<4:0>
ECAN1 Receive	CIRX	RPINR26	CIRXR<4:0>

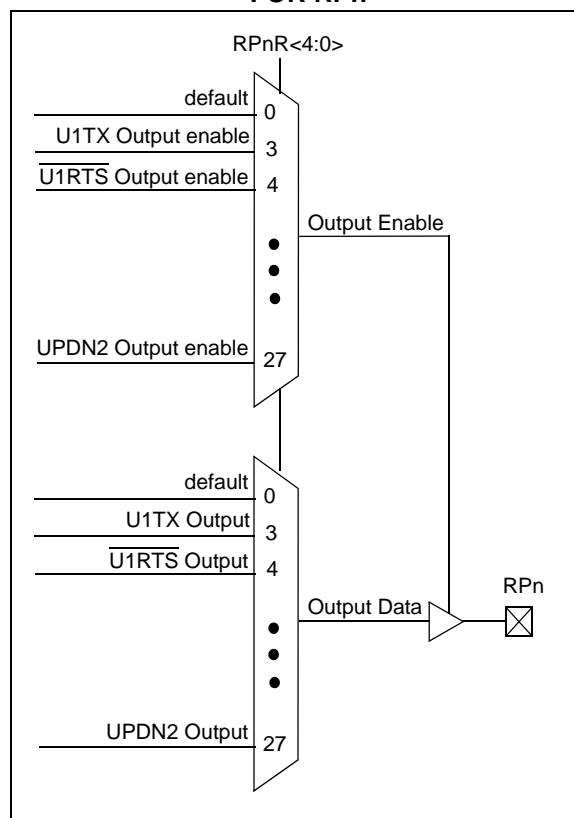
**Note 1:** Unless otherwise noted, all inputs use Schmitt input buffers.

### 11.6.2.2 Output Mapping

In contrast to inputs, the outputs of the peripheral pin select options are mapped on the basis of the pin. In this case, a control register associated with a particular pin dictates the peripheral output to be mapped. The RPORx registers are used to control output mapping. Like the RPINRx registers, each register contains sets of 5-bit fields, with each set associated with one RPn pin (see [Register 11-21](#) through [Register 11-33](#)). The value of the bit field corresponds to one of the peripherals, and that peripheral's output is mapped to the pin (see [Table 11-2](#) and [Figure 11-3](#)).

The list of peripherals for output mapping also includes a null value of '00000' because of the mapping technique. This permits any given pin to remain unconnected from the output of any of the pin selectable peripherals.

**FIGURE 11-3: MULTIPLEXING OF REMAPPABLE OUTPUT FOR RPn**



**TABLE 11-2: OUTPUT SELECTION FOR REMAPPABLE PIN (RPn)**

Function	RPnR<4:0>	Output Name
NULL	00000	RPn tied to default port pin
C1OUT	00001	RPn tied to Comparator1 Output
C2OUT	00010	RPn tied to Comparator2 Output
U1TX	00011	RPn tied to UART1 Transmit
U1RTS	00100	RPn tied to UART1 Ready To Send
U2TX	00101	RPn tied to UART2 Transmit
U2RTS	00110	RPn tied to UART2 Ready To Send
SDO1	00111	RPn tied to SPI1 Data Output
SCK1	01000	RPn tied to SPI1 Clock Output
SS1	01001	RPn tied to SPI1 Slave Select Output
SDO2	01010	RPn tied to SPI2 Data Output
SCK2	01011	RPn tied to SPI2 Clock Output
SS2	01100	RPn tied to SPI2 Slave Select Output
C1TX	10000	RPn tied to ECAN1 Transmit
OC1	10010	RPn tied to Output Compare 1
OC2	10011	RPn tied to Output Compare 2
OC3	10100	RPn tied to Output Compare 3
OC4	10101	RPn tied to Output Compare 4
UPDN1	11010	RPn tied to QEI1 direction (UPDN) status
UPDN2	11011	RPn tied to QEI2 direction (UPDN) status

### 11.6.3 CONTROLLING CONFIGURATION CHANGES

Because peripheral remapping can be changed during run time, some restrictions on peripheral remapping are needed to prevent accidental configuration changes. The dsPIC33F devices include three features to prevent alterations to the peripheral map:

- Control register lock sequence
- Continuous state monitoring
- Configuration bit pin select lock

#### 11.6.3.1 Control Register Lock

Under normal operation, writes to the RPINRx and RPORx registers are not allowed. Attempted writes appear to execute normally, but the contents of the registers remain unchanged. To change these registers, they must be unlocked in hardware. The register lock is controlled by the IOLOCK bit (OSCCON<6>). Setting IOLOCK prevents writes to the control registers;

clearing IOLOCK allows writes.

To set or clear the IOLOCK bit, a specific command sequence must be executed:

1. Write 0x46 to OSCCON<7:0>.
2. Write 0x57 to OSCCON<7:0>.
3. Clear (or set) the IOLOCK bit as a single operation.

**Note:** MPLAB® C30 provides built-in C language functions for unlocking the OSCCON register:

```
_builtin_write_OSCCONL(value)  
_builtin_write_OSCCONH(value)
```

See MPLAB IDE Help for more information.

Unlike the similar sequence with the oscillator's LOCK bit, IOLOCK remains in one state until changed. This allows all of the peripheral pin selects to be configured with a single unlock sequence followed by an update to all control registers, then locked with a second lock sequence.

#### 11.6.3.2 Continuous State Monitoring

In addition to being protected from direct writes, the contents of the RPINRx and RPORx registers are constantly monitored in hardware by shadow registers. If an unexpected change in any of the registers occurs (such as cell disturbances caused by ESD or other external events), a configuration mismatch Reset is triggered.

#### 11.6.3.3 Configuration Bit Pin Select Lock

As an additional level of safety, the device can be configured to prevent more than one write session to the RPINRx and RPORx registers. The IOL1WAY Configuration bit (FOSC<5>) blocks the IOLOCK bit from being cleared after it has been set once. If IOLOCK remains set, the register unlock procedure does not execute, and the peripheral pin select control registers cannot be written to. The only way to clear the bit and re-enable peripheral remapping is to perform a device Reset.

In the default (unprogrammed) state, IOL1WAY is set, restricting users to one write session. Programming IOL1WAY allows user applications unlimited access (with the proper use of the unlock sequence) to the peripheral pin select registers.

## 11.7 Peripheral Pin Select Registers

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices implement 33 registers for remappable peripheral configuration:

- 20 Input Remappable Peripheral Registers:
  - RPINR0-RPINR1, RPINR3-RPINR4, RPINR7, RPINR10-RPINR21, PRINR23, and PRINR26
- 13 Output Remappable Peripheral Registers:
  - RPOR0-RPOR12

**Note:** Input and output register values can only be changed if the IOLOCK bit (OSCCON<6>) is set to '0'. See [Section 11.6.3.1 "Control Register Lock"](#) for a specific command sequence.

### REGISTER 11-1: RPINR0: PERIPHERAL PIN SELECT INPUT REGISTER 0

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1				
—	—	—		INT1R<4:0>							
bit 15											bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0				
—	—	—	—	—	—	—	—				
bit 7											bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'

bit 12-8      **INT1R<4:0>:** Assign External Interrupt 1 (INTR1) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-0      **Unimplemented:** Read as '0'

**REGISTER 11-2: RPINR1: PERIPHERAL PIN SELECT INPUT REGISTER 1**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1			
—	—	—		INTR2R<4:0>						
bit 7							bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5      **Unimplemented:** Read as '0'

bit 4-0      **INTR2R<4:0>:** Assign External Interrupt 2 (INTR2) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-3: RPINR3: PERIPHERAL PIN SELECT INPUT REGISTER 3**

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1				
—	—	—		T3CKR<4:0>							
bit 15											bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1				
—	—	—		T2CKR<4:0>							
bit 7											bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **T3CKR<4:0>:** Assign Timer3 External Clock (T3CK) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **T2CKR<4:0>:** Assign Timer2 External Clock (T2CK) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

## REGISTER 11-4: RPINR4: PERIPHERAL PIN SELECT INPUT REGISTER 4

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—		T5CKR<4:0>			
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—		T4CKR<4:0>			
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **T5CKR<4:0>:** Assign Timer5 External Clock (T5CK) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **T4CKR<4:0>:** Assign Timer4 External Clock (T4CK) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-5: RPINR7: PERIPHERAL PIN SELECT INPUT REGISTER 7**

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1				
—	—	—		IC2R<4:0>							
bit 15											bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1				
—	—	—		IC1R<4:0>							
bit 7											bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **IC2R<4:0>:** Assign Input Capture 2 (IC2) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **IC1R<4:0>:** Assign Input Capture 1 (IC1) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

## REGISTER 11-6: RPINR10: PERIPHERAL PIN SELECT INPUT REGISTERS 10

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1		
—	—	—	IC8R<4:0>						
bit 15							bit 8		

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1		
—	—	—	IC7R<4:0>						
bit 7							bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **IC8R<4:0>:** Assign Input Capture 8 (IC8) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **IC7R<4:0>:** Assign Input Capture 7 (IC7) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-7: RPINR11: PERIPHERAL PIN SELECT INPUT REGISTER 11**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1			
—	—	—		OCFAR<4:0>						
bit 7							bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5

**Unimplemented:** Read as '0'

bit 4-0

**OCFAR<4:0>:** Assign Output Compare A (OCFA) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-8: RPINR12: PERIPHERAL PIN SELECT INPUT REGISTER 12**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1			
—	—	—		FLTA1R<4:0>						
bit 7							bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5

**Unimplemented:** Read as '0'

bit 4-0

**FLTA1R<4:0>:** Assign PWM1 Fault (FLTA1) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-9: RPINR13: PERIPHERAL PIN SELECT INPUT REGISTER 13**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—		FLTA2R<4:0>			
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5      **Unimplemented:** Read as '0'

bit 4-0      **FLTA2R<4:0>:** Assign PWM2 Fault (FLTA2) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-10: RPINR14: PERIPHERAL PIN SELECT INPUT REGISTERS 14**

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1			
—	—	—					QEB1R<4:0>			
bit 15										bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1			
—	—	—					QEA1R<4:0>			
bit 7										bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **QEB1R<4:0>:** Assign B (QEB1) to the corresponding pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **QEA1R<4:0>:** Assign A (QEA1) to the corresponding pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-11: RPINR15: PERIPHERAL PIN SELECT INPUT REGISTER 15**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1			
—	—	—		INDX1R<4:0>						
bit 7							bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5      **Unimplemented:** Read as '0'

bit 4-0      **INDX1R<4:0>:** Assign QEI1 INDEX (INDX1) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-12: RPINR16: PERIPHERAL PIN SELECT INPUT REGISTERS 16**

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1			
—	—	—					QEB2R<4:0>			
bit 15										bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1			
—	—	—					QEA2R<4:0>			
bit 7										bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **QEB2R<4:0>:** Assign B (QEB2) to the corresponding pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **QEA2R<4:0>:** Assign A (QEA2) to the corresponding pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-13: RPINR17: PERIPHERAL PIN SELECT INPUT REGISTER 17**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1			
—	—	—		INDX2R<4:0>						
bit 7							bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5      **Unimplemented:** Read as '0'

bit 4-0      **INDX2R<4:0>:** Assign QEI2 INDEX (INDX2) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-14: RPINR18: PERIPHERAL PIN SELECT INPUT REGISTER 18**

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1				
—	—	—		U1CTSR<4:0>							
bit 15											bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1				
—	—	—		U1RXR<4:0>							
bit 7											bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **U1CTSR<4:0>:** Assign UART1 Clear to Send (U1CTS) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **U1RXR<4:0>:** Assign UART1 Receive (U1RX) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-15: RPINR19: PERIPHERAL PIN SELECT INPUT REGISTER 19**

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	
—	—	—	U2CTSR<4:0>					
bit 15						bit 8		

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	
—	—	—	U2RXR<4:0>					
bit 7						bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'

bit 12-8      **U2CTSR<4:0>:** Assign UART2 Clear to Send (U2CTS) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5      **Unimplemented:** Read as '0'

bit 4-0      **U2RXR<4:0>:** Assign UART2 Receive (U2RX) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-16: RPINR20: PERIPHERAL PIN SELECT INPUT REGISTER 20**

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—			SCK1R<4:0>		
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—			SDI1R<4:0>		
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **SCK1R<4:0>:** Assign SPI1 Clock Input (SCK1) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **SDI1R<4:0>:** Assign SPI1 Data Input (SDI1) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-17: RPINR21: PERIPHERAL PIN SELECT INPUT REGISTER 21**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—		SS1R<4:0>			
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5      **Unimplemented:** Read as '0'

bit 4-0      **SS1R<4:0>:** Assign SPI1 Slave Select Input (SS1) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-18: RPINR22: PERIPHERAL PIN SELECT INPUT REGISTER 22**

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—			SCK2R<4:0>		
bit 15					bit 8		

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—			SDI2R<4:0>		
bit 7					bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **SCK2R<4:0>:** Assign SPI2 Clock Input (SCK2) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **SDI2R<4:0>:** Assign SPI2 Data Input (SDI2) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-19: RPINR23: PERIPHERAL PIN SELECT INPUT REGISTER 23**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—		SS2R<4:0>			
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5      **Unimplemented:** Read as '0'

bit 4-0      **SS2R<4:0>:** Assign SPI2 Slave Select Input ( $\overline{SS2}$ ) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 11-20: RPINR26: PERIPHERAL PIN SELECT INPUT REGISTER 26<sup>(1)</sup>**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—		C1RXR<4:0>			
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5      **Unimplemented:** Read as '0'

bit 4-0      **C1RXR<4:0>:** Assign ECAN1 Receive (C1RX) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**Note 1:** This register is disabled on devices without an ECAN™ module.

**REGISTER 11-21: RPOR0: PERIPHERAL PIN SELECT OUTPUT REGISTER 0**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
—	—	—		RP1R<4:0>							
bit 15											bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
—	—	—		RP0R<4:0>							
bit 7											bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **RP1R<4:0>:** Peripheral Output Function is Assigned to RP1 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **RP0R<4:0>:** Peripheral Output Function is Assigned to RP0 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)**REGISTER 11-22: RPOR1: PERIPHERAL PIN SELECT OUTPUT REGISTER 1**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
—	—	—		RP3R<4:0>							
bit 15											bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
—	—	—		RP2R<4:0>							
bit 7											bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **RP3R<4:0>:** Peripheral Output Function is Assigned to RP3 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **RP2R<4:0>:** Peripheral Output Function is Assigned to RP2 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)

**REGISTER 11-23: RPOR2: PERIPHERAL PIN SELECT OUTPUT REGISTER 2**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP5R<4:0>						
bit 15								bit 8		

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP4R<4:0>						
bit 7								bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-13      **Unimplemented:** Read as '0'
- bit 12-8      **RP5R<4:0>:** Peripheral Output Function is Assigned to RP5 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)
- bit 7-5      **Unimplemented:** Read as '0'
- bit 4-0      **RP4R<4:0>:** Peripheral Output Function is Assigned to RP4 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)

**REGISTER 11-24: RPOR3: PERIPHERAL PIN SELECT OUTPUT REGISTER 3**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP7R<4:0>						
bit 15								bit 8		

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP6R<4:0>						
bit 7								bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-13      **Unimplemented:** Read as '0'
- bit 12-8      **RP7R<4:0>:** Peripheral Output Function is Assigned to RP7 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)
- bit 7-5      **Unimplemented:** Read as '0'
- bit 4-0      **RP6R<4:0>:** Peripheral Output Function is Assigned to RP6 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)

**REGISTER 11-25: RPOR4: PERIPHERAL PIN SELECT OUTPUT REGISTER 4**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
—	—	—		RP9R<4:0>							
bit 15											bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
—	—	—		RP8R<4:0>							
bit 7											bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **RP9R<4:0>:** Peripheral Output Function is Assigned to RP9 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **RP8R<4:0>:** Peripheral Output Function is Assigned to RP8 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)**REGISTER 11-26: RPOR5: PERIPHERAL PIN SELECT OUTPUT REGISTER 5**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
—	—	—		RP11R<4:0>							
bit 15											bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
—	—	—		RP10R<4:0>							
bit 7											bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **RP11R<4:0>:** Peripheral Output Function is Assigned to RP11 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **RP10R<4:0>:** Peripheral Output Function is Assigned to RP10 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)

**REGISTER 11-27: RPOR6: PERIPHERAL PIN SELECT OUTPUT REGISTER 6**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP13R<4:0>						
bit 15								bit 8		

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP12R<4:0>						
bit 7								bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- |           |  |
|-----------|--|
| bit 15-13 | <b>Unimplemented:</b> Read as '0'  |
| bit 12-8  | <b>RP13R&lt;4:0&gt;:</b> Peripheral Output Function is Assigned to RP13 Output Pin bits (see <a href="#">Table 11-2</a> for peripheral function numbers) |
| bit 7-5   | <b>Unimplemented:</b> Read as '0'  |
| bit 4-0   | <b>RP12R&lt;4:0&gt;:</b> Peripheral Output Function is Assigned to RP12 Output Pin bits (see <a href="#">Table 11-2</a> for peripheral function numbers) |

**REGISTER 11-28: RPOR7: PERIPHERAL PIN SELECT OUTPUT REGISTER 7**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP15R<4:0>						
bit 15								bit 8		

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP14R<4:0>						
bit 7								bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- |           |  |
|-----------|--|
| bit 15-13 | <b>Unimplemented:</b> Read as '0'  |
| bit 12-8  | <b>RP15R&lt;4:0&gt;:</b> Peripheral Output Function is Assigned to RP15 Output Pin bits (see <a href="#">Table 11-2</a> for peripheral function numbers) |
| bit 7-5   | <b>Unimplemented:</b> Read as '0'  |
| bit 4-0   | <b>RP14R&lt;4:0&gt;:</b> Peripheral Output Function is Assigned to RP14 Output Pin bits (see <a href="#">Table 11-2</a> for peripheral function numbers) |

**REGISTER 11-29: RPOR8: PERIPHERAL PIN SELECT OUTPUT REGISTER 8<sup>(1)</sup>**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP17R<4:0>						
bit 15				bit 8						

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP16R<4:0>						
bit 7				bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **RP17R<4:0>:** Peripheral Output Function is Assigned to RP17 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **RP16R<4:0>:** Peripheral Output Function is Assigned to RP16 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)**Note 1:** This register is implemented in 44-pin devices only.**REGISTER 11-30: RPOR9: PERIPHERAL PIN SELECT OUTPUT REGISTER 9<sup>(1)</sup>**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP19R<4:0>						
bit 15				bit 8						

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP18R<4:0>						
bit 7				bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **RP19R<4:0>:** Peripheral Output Function is Assigned to RP19 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **RP18R<4:0>:** Peripheral Output Function is Assigned to RP18 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)**Note 1:** This register is implemented in 44-pin devices only.

**REGISTER 11-31: RPOR10: PERIPHERAL PIN SELECT OUTPUT REGISTER 10<sup>(1)</sup>**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP21R<4:0>						
bit 15								bit 8		

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP20R<4:0>						
bit 7								bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'

bit 12-8      **RP21R<4:0>:** Peripheral Output Function is Assigned to RP21 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)

bit 7-5      **Unimplemented:** Read as '0'

bit 4-0      **RP20R<4:0>:** Peripheral Output Function is Assigned to RP20 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)

**Note 1:** This register is implemented in 44-pin devices only.

**REGISTER 11-32: RPOR11: PERIPHERAL PIN SELECT OUTPUT REGISTER 11<sup>(1)</sup>**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP23R<4:0>						
bit 15								bit 8		

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—		RP22R<4:0>						
bit 7								bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'

bit 12-8      **RP23R<4:0>:** Peripheral Output Function is Assigned to RP23 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)

bit 7-5      **Unimplemented:** Read as '0'

bit 4-0      **RP22R<4:0>:** Peripheral Output Function is Assigned to RP22 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)

**Note 1:** This register is implemented in 44-pin devices only.

**REGISTER 11-33: RPOR12: PERIPHERAL PIN SELECT OUTPUT REGISTER 12<sup>(1)</sup>**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—					RP25R<4:0>			
bit 15										bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	—					RP24R<4:0>			
bit 7										bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12-8      **RP25R<4:0>:** Peripheral Output Function is Assigned to RP25 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)bit 7-5      **Unimplemented:** Read as '0'bit 4-0      **RP24R<4:0>:** Peripheral Output Function is Assigned to RP24 Output Pin bits (see [Table 11-2](#) for peripheral function numbers)**Note 1:** This register is implemented in 44-pin devices only.

**NOTES:**

## 12.0 TIMER1

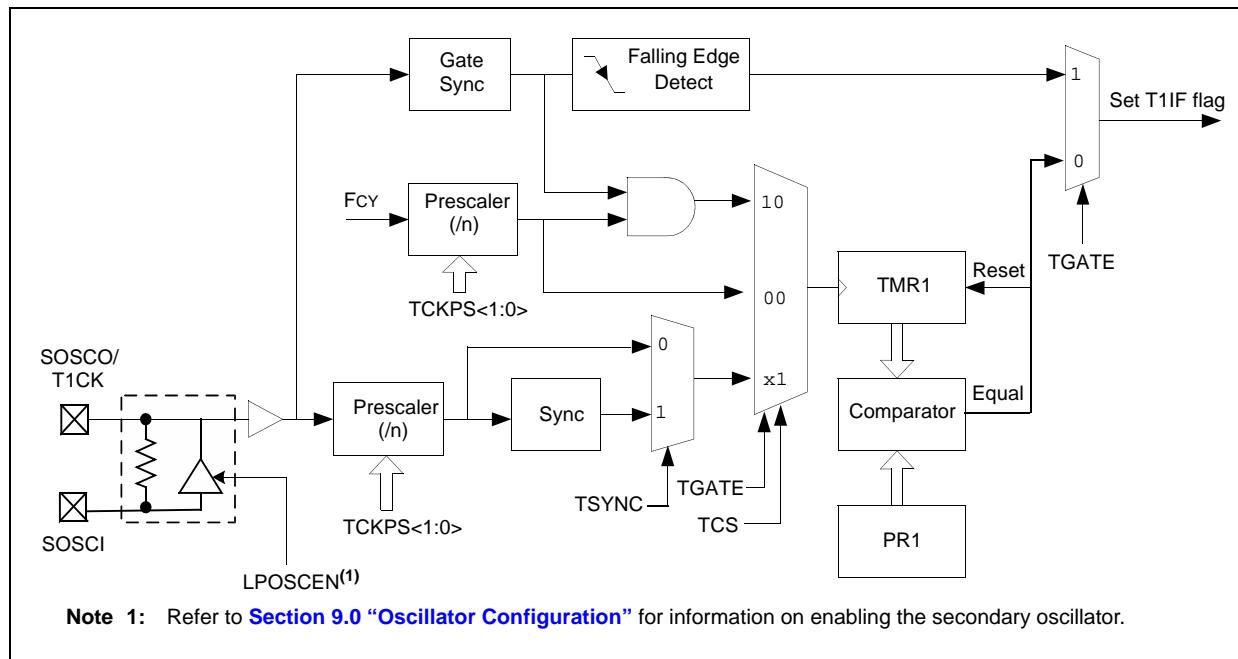
- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 11. Timers**” (DS70205) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The Timer1 module is a 16-bit timer, which can serve as the time counter for the real-time clock, or operate as a free-running interval timer/counter.

The Timer1 module has the following unique features over other timers:

- Can be operated from the low power 32 kHz crystal oscillator available on the device.
- Can be operated in Asynchronous Counter mode from an external clock source.
- The external clock input (T1CK) can optionally be synchronized to the internal device clock and the clock synchronization is performed after the prescaler.

**FIGURE 12-1: 16-BIT TIMER1 MODULE BLOCK DIAGRAM**



The unique features of Timer1 allow it to be used for Real-Time Clock (RTC) applications. A block diagram of Timer1 is shown in [Figure 12-1](#).

The Timer1 module can operate in one of the following modes:

- Timer mode
- Gated Timer mode
- Synchronous Counter mode
- Asynchronous Counter mode

In Timer and Gated Timer modes, the input clock is derived from the internal instruction cycle clock (FCY). In Synchronous and Asynchronous Counter modes, the input clock is derived from the external clock input at the T1CK pin.

The Timer modes are determined by the following bits:

- Timer Clock Source Control bit (TCS): T1CON<1>
- Timer Synchronization Control bit (TSYNC): T1CON<2>
- Timer Gate Control bit (TGATE): T1CON<6>

Timer control bit setting for different operating modes are given in the [Table 12-1](#).

**TABLE 12-1: TIMER MODE SETTINGS**

Mode	TCS	TGATE	TSYNC
Timer	0	0	x
Gated timer	0	1	x
Synchronous Counter	1	x	1
Asynchronous Counter	1	x	0

**REGISTER 12-1: T1CON: TIMER1 CONTROL REGISTER**

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON	—	TSIDL	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	U-0
—	TGATE	TCKPS<1:0>	—	—	TSYNC	TCS	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **TON:** Timer1 On bit  
               1 = Starts 16-bit Timer1  
               0 = Stops 16-bit Timer1
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **TSIDL:** Stop in Idle Mode bit  
               1 = Discontinue module operation when device enters Idle mode  
               0 = Continue module operation in Idle mode
- bit 12-7     **Unimplemented:** Read as '0'
- bit 6        **TGATE:** Timer1 Gated Time Accumulation Enable bit  
               When TCS = 1:  
               This bit is ignored.  
               When TCS = 0:  
               1 = Gated time accumulation enabled  
               0 = Gated time accumulation disabled
- bit 5-4      **TCKPS<1:0>** Timer1 Input Clock Prescale Select bits  
               11 = 1:256  
               10 = 1:64  
               01 = 1:8  
               00 = 1:1
- bit 3        **Unimplemented:** Read as '0'
- bit 2        **TSYNC:** Timer1 External Clock Input Synchronization Select bit  
               When TCS = 1:  
               1 = Synchronize external clock input  
               0 = Do not synchronize external clock input  
               When TCS = 0:  
               This bit is ignored.
- bit 1        **TCS:** Timer1 Clock Source Select bit  
               1 = External clock from pin T1CK (on the rising edge)  
               0 = Internal clock (FCY)
- bit 0        **Unimplemented:** Read as '0'

## 13.0 TIMER2/3 AND TIMER4/5 FEATURE

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 11. Timers**” (DS70205) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

Timer2 and Timer4 are Type B timers with the following specific features:

- A Type B timer can be concatenated with a Type C timer to form a 32-bit timer
- The external clock input (TxCK) is always synchronized to the internal device clock and the clock synchronization is performed after the prescaler

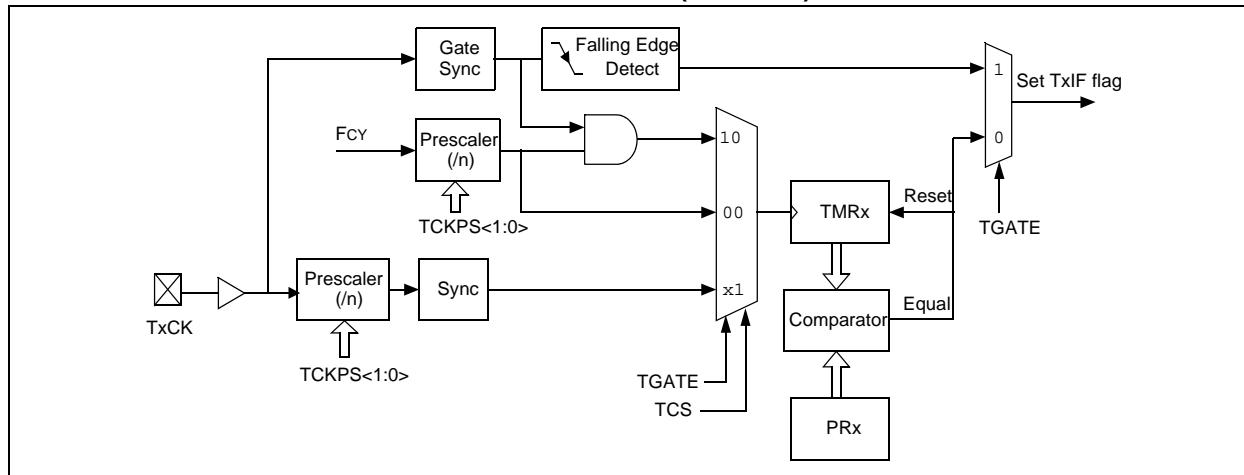
A block diagram of the Type B timer is shown in [Figure 13-1](#).

Timer3 and Timer5 are Type C timers with the following specific features:

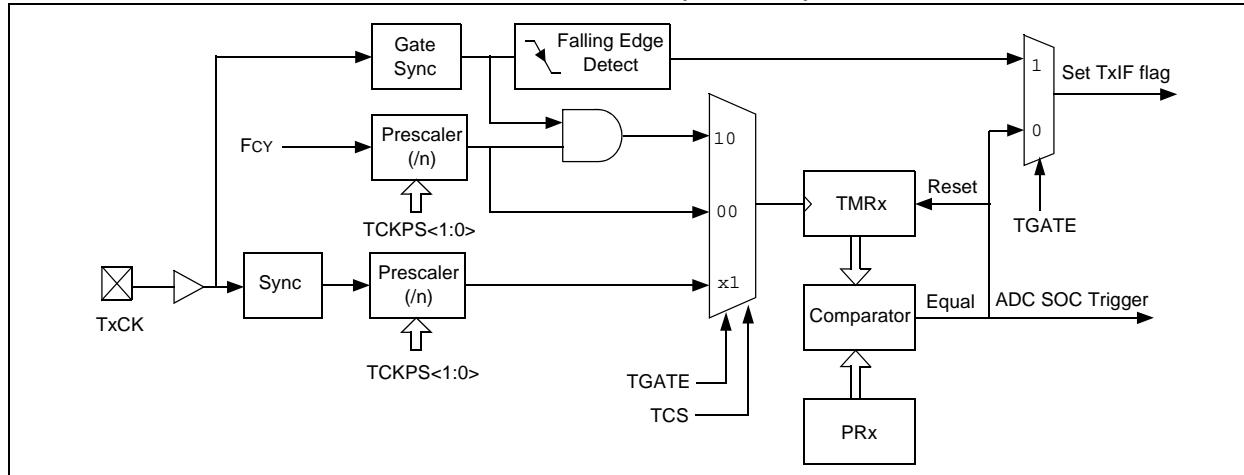
- A Type C timer can be concatenated with a Type B timer to form a 32-bit timer
- At least one Type C timer has the ability to trigger an A/D conversion
- The external clock input (TxCK) is always synchronized to the internal device clock and the clock synchronization is performed before the prescaler

A block diagram of the Type C timer is shown in [Figure 13-2](#).

**FIGURE 13-1: TYPE B TIMER BLOCK DIAGRAM (x = 2 or 4)**



**FIGURE 13-2: TYPE C TIMER BLOCK DIAGRAM (x = 3 or 5)**



The Timer2/3 and Timer4/5 modules can operate in one of the following modes:

- Timer mode
- Gated Timer mode
- Synchronous Counter mode

In Timer and Gated Timer modes, the input clock is derived from the internal instruction cycle clock (Fc<sub>y</sub>). In Synchronous Counter mode, the input clock is derived from the external clock input at TxCK pin.

The timer modes are determined by the following bits:

- TCS (TxCON<1>): Timer Clock Source Control bit
- TGATE (TxCON<6>): Timer Gate Control bit

Timer control bit settings for different operating modes are given in the [Table 13-1](#).

**TABLE 13-1: TIMER MODE SETTINGS**

Mode	TCS	TGATE
Timer	0	0
Gated timer	0	1
Synchronous counter	1	x

### 13.1 16-bit Operation

To configure any of the timers for individual 16-bit operation:

1. Clear the T32 bit corresponding to that timer.
2. Select the timer prescaler ratio using the TCKPS<1:0> bits.
3. Set the Clock and Gating modes using the TCS and TGATE bits.
4. Load the timer period value into the PR<sub>x</sub> register.
5. If interrupts are required, set the interrupt enable bit, TxIE. Use the priority bits, TxIP<2:0>, to set the interrupt priority.
6. Set the TON bit.

**Note:** Only Timer2 and Timer3 can trigger a DMA data transfer.

### 13.2 32-bit Operation

A 32-bit timer module can be formed by combining a Type B and a Type C 16-bit timer module. For 32-bit timer operation, the T32 control bit in the Type B Timer Control register (TxCON<3>) must be set. The Type C timer holds the most significant word (msw) and the Type B timer holds the least significant word (lsw) for 32-bit operation.

When configured for 32-bit operation, only the Type B Timer Control register (TxCON) bits are required for setup and control. Type C timer control register bits are ignored (except TSIDL bit).

For interrupt control, the combined 32-bit timer uses the interrupt enable, interrupt flag and interrupt priority control bits of the Type C timer. The interrupt control and status bits for the Type B timer are ignored during 32-bit timer operation.

The Type B and Type C timers that can be combined to form a 32-bit timer are listed in [Table 13-2](#).

**TABLE 13-2: 32-BIT TIMER**

TYPE B Timer (lsw)	TYPE C Timer (msw)
Timer2	Timer3
Timer4	Timer5

A block diagram representation of the 32-bit timer module is shown in [Figure 13-3](#). The 32-timer module can operate in one of the following modes:

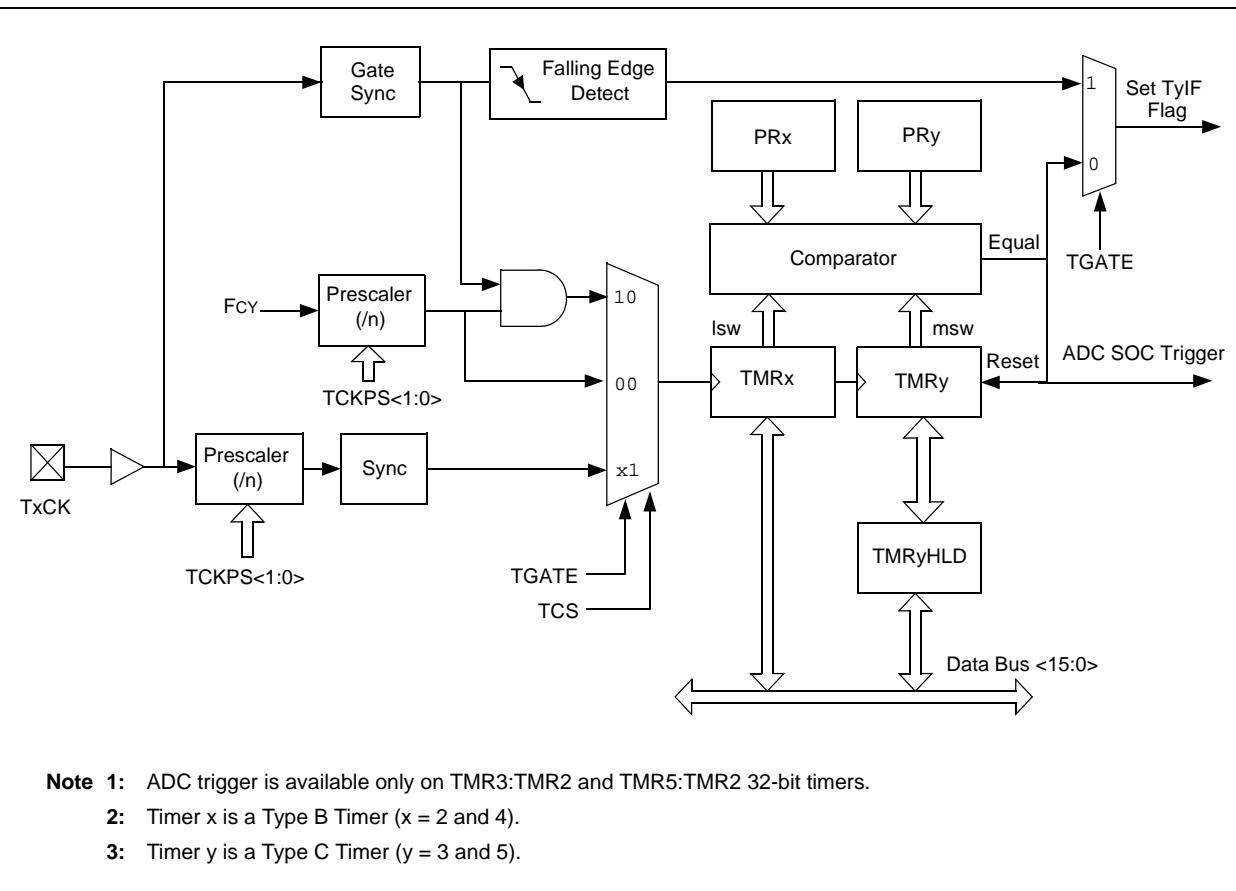
- Timer mode
- Gated Timer mode
- Synchronous Counter mode

To configure the features of Timer2/3 or Timer4/5 for 32-bit operation:

1. Set the T32 control bit.
2. Select the prescaler ratio for Timer2 or Timer4 using the TCKPS<1:0> bits.
3. Set the Clock and Gating modes using the corresponding TCS and TGATE bits.
4. Load the timer period value. PR<sub>3</sub> or PR<sub>5</sub> contains the most significant word of the value, while PR<sub>2</sub> or PR<sub>4</sub> contains the least significant word.
5. If interrupts are required, set the interrupt enable bits, T3IE or T5IE. Use the priority bits, T3IP<2:0> or T5IP<2:0> to set the interrupt priority. While Timer2 or Timer4 controls the timer, the interrupt appears as a Timer3 or Timer5 interrupt.
6. Set the corresponding TON bit.

The timer value at any point is stored in the register pair, TMR3:TMR2 or TMR5:TMR4, which always contains the most significant word of the count, while TMR2 or TMR4 contains the least significant word.

**FIGURE 13-3: 32-BIT TIMER BLOCK DIAGRAM**



**REGISTER 13-1: TxCON: TIMER CONTROL REGISTER (x = 2 or 4)**

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON	—	TSIDL	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	U-0
—	TGATE	TCKPS<1:0>	T32	—	TCS	—	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **TON:** Timerx On bit

When T32 = 1 (in 32-bit Timer mode):

1 = Starts 32-bit TMRx:TMRy timer pair

0 = Stops 32-bit TMRx:TMRy timer pair

When T32 = 0 (in 16-bit Timer mode):

1 = Starts 16-bit timer

0 = Stops 16-bit timer

bit 14      **Unimplemented:** Read as '0'

bit 13      **TSIDL:** Stop in Idle Mode bit

1 = Discontinue timer operation when device enters Idle mode

0 = Continue timer operation in Idle mode

bit 12-7      **Unimplemented:** Read as '0'

bit 6      **TGATE:** Timerx Gated Time Accumulation Enable bit

When TCS = 1:

This bit is ignored.

When TCS = 0:

1 = Gated time accumulation enabled

0 = Gated time accumulation disabled

bit 5-4      **TCKPS<1:0>:** Timerx Input Clock Prescale Select bits

11 = 1:256 prescale value

10 = 1:64 prescale value

01 = 1:8 prescale value

00 = 1:1 prescale value

bit 3      **T32:** 32-bit Timerx Mode Select bit

1 = TMRx and TMRy form a 32-bit timer

0 = TMRx and TMRy form separate 16-bit timer

bit 2      **Unimplemented:** Read as '0'

bit 1      **TCS:** Timerx Clock Source Select bit

1 = External clock from TxCK pin

0 = Internal clock (Fosc/2)

bit 0      **Unimplemented:** Read as '0'

**REGISTER 13-2: TyCON: TIMER CONTROL REGISTER (y = 3 or 5)**

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON <sup>(2)</sup>	—	TSIDL <sup>(1)</sup>	—	—	—	—	—
bit 15							

U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	U-0
—	TGATE <sup>(2)</sup>	—	TCKPS<1:0> <sup>(2)</sup>	—	—	TCS <sup>(2)</sup>	—
bit 7							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15	<b>TON:</b> Timery On bit <sup>(2)</sup> 1 = Starts 16-bit TimerX 0 = Stops 16-bit TimerX
bit 14	<b>Unimplemented:</b> Read as '0'
bit 13	<b>TSIDL:</b> Stop in Idle Mode bit <sup>(1)</sup> 1 = Discontinue timer operation when device enters Idle mode 0 = Continue timer operation in Idle mode
bit 12-7	<b>Unimplemented:</b> Read as '0'
bit 6	<b>TGATE:</b> TimerX Gated Time Accumulation Enable bit <sup>(2)</sup> <u>When TCS = 1:</u> This bit is ignored. <u>When TCS = 0:</u> 1 = Gated time accumulation enabled 0 = Gated time accumulation disabled
bit 5-4	<b>TCKPS&lt;1:0&gt;:</b> TimerX Input Clock Prescale Select bits <sup>(2)</sup> 11 = 1:256 prescale value 10 = 1:64 prescale value 01 = 1:8 prescale value 00 = 1:1 prescale value
bit 3-2	<b>Unimplemented:</b> Read as '0'
bit 1	<b>TCS:</b> TimerX Clock Source Select bit <sup>(2)</sup> 1 = External clock from TxCK pin 0 = Internal clock (Fosc/2)
bit 0	<b>Unimplemented:</b> Read as '0'

**Note 1:** When 32-bit timer operation is enabled (T32 = 1) in the Timer Control register (TxCON<3>), the TSIDL bit must be cleared to operate the 32-bit timer in Idle mode.

**2:** When the 32-bit timer operation is enabled (T32 = 1) in the Timer Control register (TxCON<3>), these bits have no effect.

**NOTES:**

## 14.0 INPUT CAPTURE

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 12. Input Capture**” (DS70198) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The Input Capture module is useful in applications that require frequency (period) and pulse measurement. The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices support up to four input capture channels.

The input capture module captures the 16-bit value of the selected Time Base register when an event occurs at the ICx pin. The events that cause a capture event are listed below in three categories:

- Simple Capture Event modes:

- Capture timer value on every falling edge of input at ICx pin
- Capture timer value on every rising edge of input at ICx pin

- Capture timer value on every edge (rising and falling)

- Prescaler Capture Event modes:

- Capture timer value on every 4th rising edge of input at ICx pin
- Capture timer value on every 16th rising edge of input at ICx pin

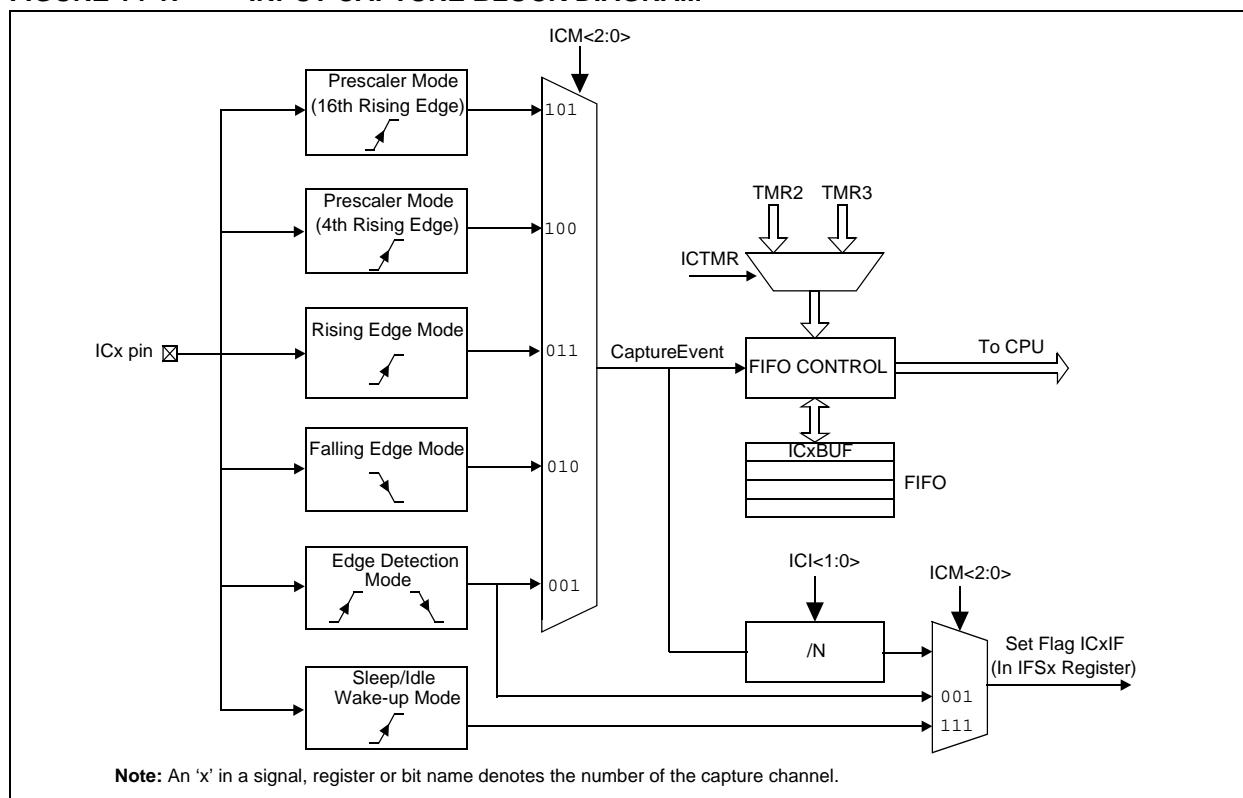
Each input capture channel can select one of two 16-bit timers (Timer2 or Timer3) for the time base. The selected timer can use either an internal or external clock.

Other operational features include:

- Device wake-up from capture pin during CPU Sleep and Idle modes
- Interrupt on input capture event
- 4-word FIFO buffer for capture values
  - Interrupt optionally generated after 1, 2, 3 or 4 buffer locations are filled
- Use of input capture to provide additional sources of external interrupts

**Note:** Only IC1 and IC2 can trigger a DMA data transfer. If DMA data transfers are required, the FIFO buffer size must be set to ‘1’ (ICI<1:0> = 00)

**FIGURE 14-1: INPUT CAPTURE BLOCK DIAGRAM**



## 14.1 Input Capture Registers

REGISTER 14-1: IC<sub>x</sub>CON: INPUT CAPTURE x CONTROL REGISTER (x = 1, 2, 7 or 8)

U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
—	—	ICSIDL	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R-0, HC	R-0, HC	R/W-0	R/W-0	R/W-0
ICTMR	ICI<1:0>	ICOV	ICBNE		ICM<2:0>		
bit 7						bit 0	

**Legend:**

HC = Cleared in Hardware

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-14      **Unimplemented:** Read as '0'
- bit 13      **ICSIDL:** Input Capture Module Stop in Idle Control bit  
1 = Input capture module halts in CPU Idle mode  
0 = Input capture module continues to operate in CPU Idle mode
- bit 12-8      **Unimplemented:** Read as '0'
- bit 7      **ICTMR:** Input Capture Timer Select bits  
1 = TMR2 contents are captured on capture event  
0 = TMR3 contents are captured on capture event
- bit 6-5      **ICI<1:0>:** Select Number of Captures per Interrupt bits  
11 = Interrupt on every fourth capture event  
10 = Interrupt on every third capture event  
01 = Interrupt on every second capture event  
00 = Interrupt on every capture event
- bit 4      **ICOV:** Input Capture Overflow Status Flag bit (read-only)  
1 = Input capture overflow occurred  
0 = No input capture overflow occurred
- bit 3      **ICBNE:** Input Capture Buffer Empty Status bit (read-only)  
1 = Input capture buffer is not empty, at least one more capture value can be read  
0 = Input capture buffer is empty
- bit 2-0      **ICM<2:0>:** Input Capture Mode Select bits  
111 = Input capture functions as interrupt pin only when device is in Sleep or Idle mode  
         (Rising edge detect only, all other control bits are not applicable).  
110 = Unused (module disabled)  
101 = Capture mode, every 16th rising edge  
100 = Capture mode, every 4th rising edge  
011 = Capture mode, every rising edge  
010 = Capture mode, every falling edge  
001 = Capture mode, every edge (rising and falling)  
         (ICI<1:0> bits do not control interrupt generation for this mode).  
000 = Input capture module turned off

## 15.0 OUTPUT COMPARE

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 13. Output Compare**” (DS70209) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

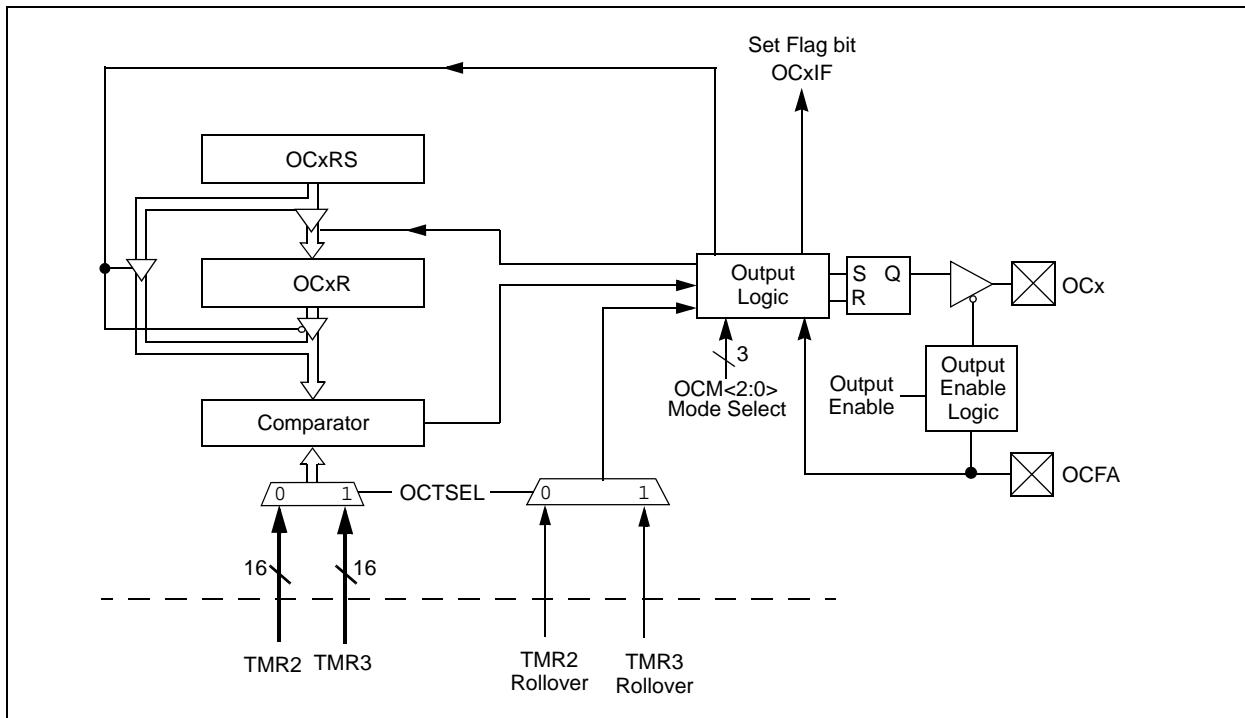
- 2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The Output Compare module can select either Timer2 or Timer3 for its time base. The module compares the value of the timer with the value of one or two compare registers depending on the operating mode selected. The state of the output pin changes when the timer value matches the compare register value. The Output Compare module generates either a single output pulse or a sequence of output pulses, by changing the state of the output pin on the compare match events. The Output Compare module can also generate interrupts on compare match events.

The Output Compare module has multiple operating modes:

- Active-Low One-Shot mode
- Active-High One-Shot mode
- Toggle mode
- Delayed One-Shot mode
- Continuous Pulse mode
- PWM mode without fault protection
- PWM mode with fault protection

**FIGURE 15-1: OUTPUT COMPARE MODULE BLOCK DIAGRAM**



## 15.1 Output Compare Modes

Configure the Output Compare modes by setting the appropriate Output Compare Mode bits ( $OCM<2:0>$ ) in the Output Compare Control register ( $OCxCON<2:0>$ ). Table 15-1 lists the different bit settings for the Output Compare modes. Figure 15-2 illustrates the output compare operation for various modes. The user application must disable the associated timer when writing to the output compare control registers to avoid malfunctions.

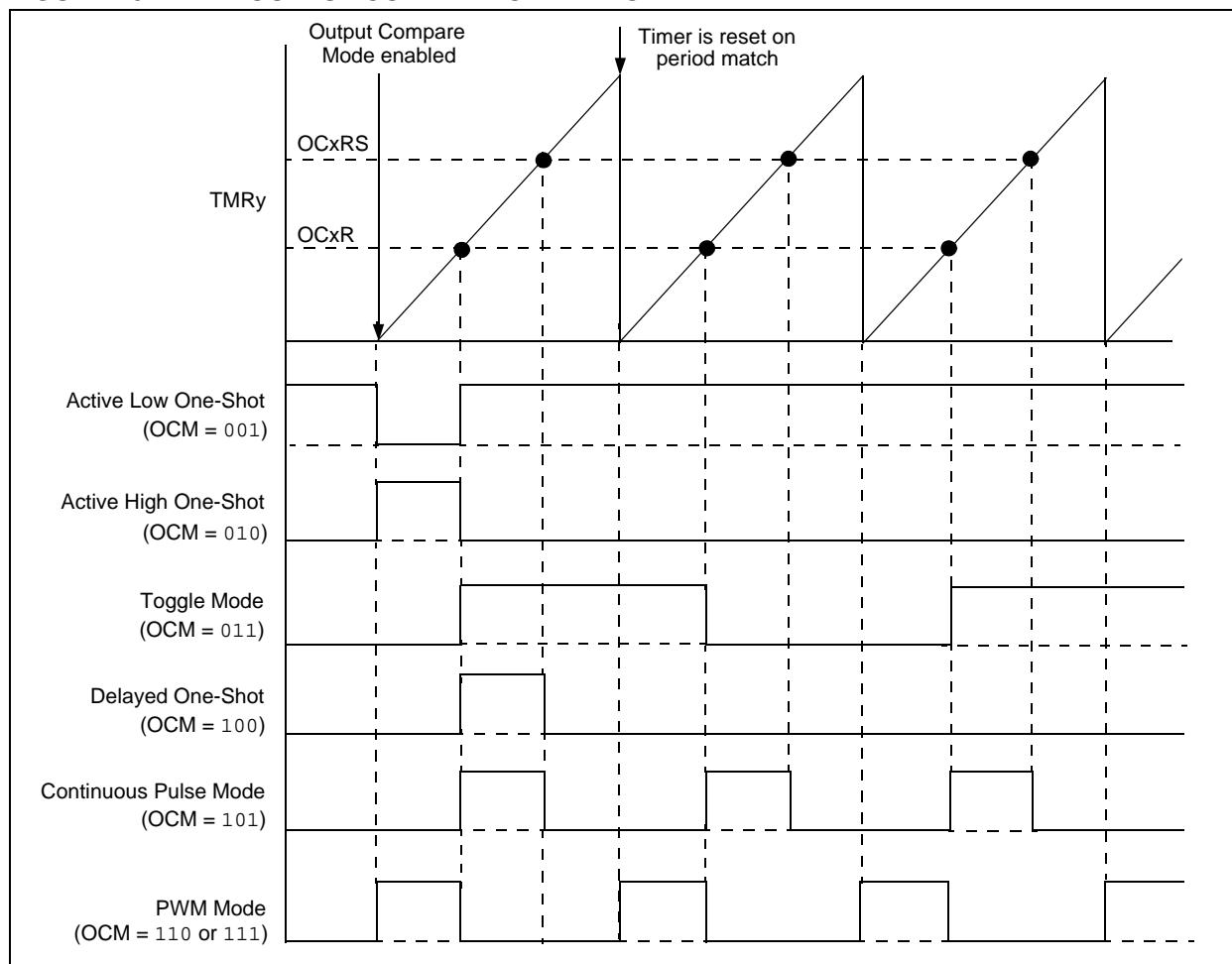
**Note 1:** Only OC1 and OC2 can trigger a DMA data transfer.

**2:** See **Section 13. “Output Compare”** (DS70209) in the “dsPIC33F/PIC24H Family Reference Manual” for  $OCxR$  and  $OCxRS$  register restrictions.

**TABLE 15-1: OUTPUT COMPARE MODES**

$OCM<2:0>$	Mode	OCx Pin Initial State	OCx Interrupt Generation
000	Module Disabled	Controlled by GPIO register	—
001	Active-Low One-Shot	0	OCx Rising edge
010	Active-High One-Shot	1	OCx Falling edge
011	Toggle Mode	Current output is maintained	OCx Rising and Falling edge
100	Delayed One-Shot	0	OCx Falling edge
101	Continuous Pulse mode	0	OCx Falling edge
110	PWM mode without fault protection	0, if $OCxR$ is zero 1, if $OCxR$ is non-zero	No interrupt
111	PWM mode with fault protection	0, if $OCxR$ is zero 1, if $OCxR$ is non-zero	OCFA Falling edge for OC1 to OC4

**FIGURE 15-2: OUTPUT COMPARE OPERATION**



**REGISTER 15-1: OC<sub>x</sub>CON: OUTPUT COMPARE x CONTROL REGISTER (x = 1, 2, 3 or 4)**

U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
—	—	OCSIDL	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R-0, HC	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	OCFLT	OCTSEL	OCM<2:0>		
bit 7							bit 0

<b>Legend:</b>	HC = Cleared in Hardware	HS = Set in Hardware
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

- bit 15-14      **Unimplemented:** Read as '0'
- bit 13      **OCSIDL:** Stop Output Compare in Idle Mode Control bit  
               1 = Output Compare x halts in CPU Idle mode  
               0 = Output Compare x continues to operate in CPU Idle mode
- bit 12-5      **Unimplemented:** Read as '0'
- bit 4      **OCFLT:** PWM Fault Condition Status bit  
               1 = PWM Fault condition has occurred (cleared in hardware only)  
               0 = No PWM Fault condition has occurred  
               (This bit is only used when OCM<2:0> = 111).
- bit 3      **OCTSEL:** Output Compare Timer Select bit  
               1 = Timer3 is the clock source for Compare x  
               0 = Timer2 is the clock source for Compare x
- bit 2-0      **OCM<2:0>:** Output Compare Mode Select bits  
               111 = PWM mode on OC<sub>x</sub>, Fault pin enabled  
               110 = PWM mode on OC<sub>x</sub>, Fault pin disabled  
               101 = Initialize OC<sub>x</sub> pin low, generate continuous output pulses on OC<sub>x</sub> pin  
               100 = Initialize OC<sub>x</sub> pin low, generate single output pulse on OC<sub>x</sub> pin  
               011 = Compare event toggles OC<sub>x</sub> pin  
               010 = Initialize OC<sub>x</sub> pin high, compare event forces OC<sub>x</sub> pin low  
               001 = Initialize OC<sub>x</sub> pin low, compare event forces OC<sub>x</sub> pin high  
               000 = Output compare channel is disabled

**NOTES:**

## 16.0 MOTOR CONTROL PWM MODULE

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 14. Motor Control PWM**” (DS70187) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 device supports up to two dedicated Pulse Width Modulation (PWM) modules. The PWM1 module is a 6-channel PWM generator, and the PWM2 module is a 2-channel PWM generator.

The PWM module has the following features:

- Up to 16-bit resolution
- On-the-fly PWM frequency changes
- Edge and Center-Aligned Output modes
- Single Pulse Generation mode
- Interrupt support for asymmetrical updates in Center-Aligned mode
- Output override control for Electrically Commutative Motor (ECM) operation or Brushless DC (BLDC)
- Special Event Comparator for scheduling other peripheral events
- Fault pins to optionally drive each of the PWM output pins to a defined state
- Duty cycle updates configurable to be immediate or synchronized to the PWM time base

### 16.1 PWM1: 6-Channel PWM Module

This module simplifies the task of generating multiple synchronized PWM outputs. The following power and motion control applications are supported by the PWM module:

- 3-Phase AC Induction Motor
- Switched Reluctance (SR) Motor
- Brushless DC (BLDC) Motor
- Uninterruptible Power Supply (UPS)

This module contains three duty cycle generators, numbered 1 through 3. The module has six PWM output pins, numbered PWM1H1/PWM1L1 through PWM1H3/PWM1L3. The six I/O pins are grouped into high/low numbered pairs, denoted by the suffix H or L, respectively. For complementary loads, the low PWM pins are always the complement of the corresponding high I/O pin.

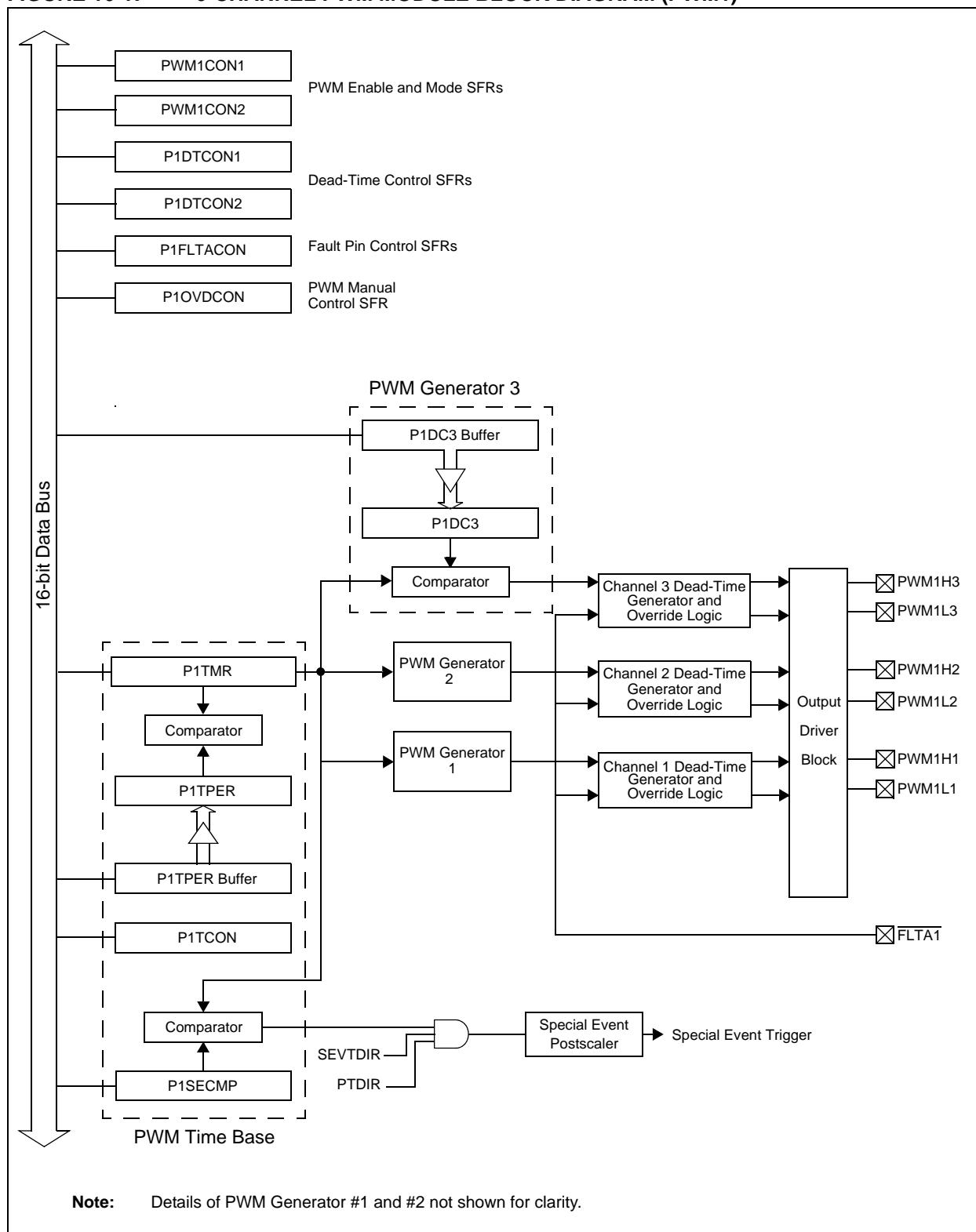
### 16.2 PWM2: 2-Channel PWM Module

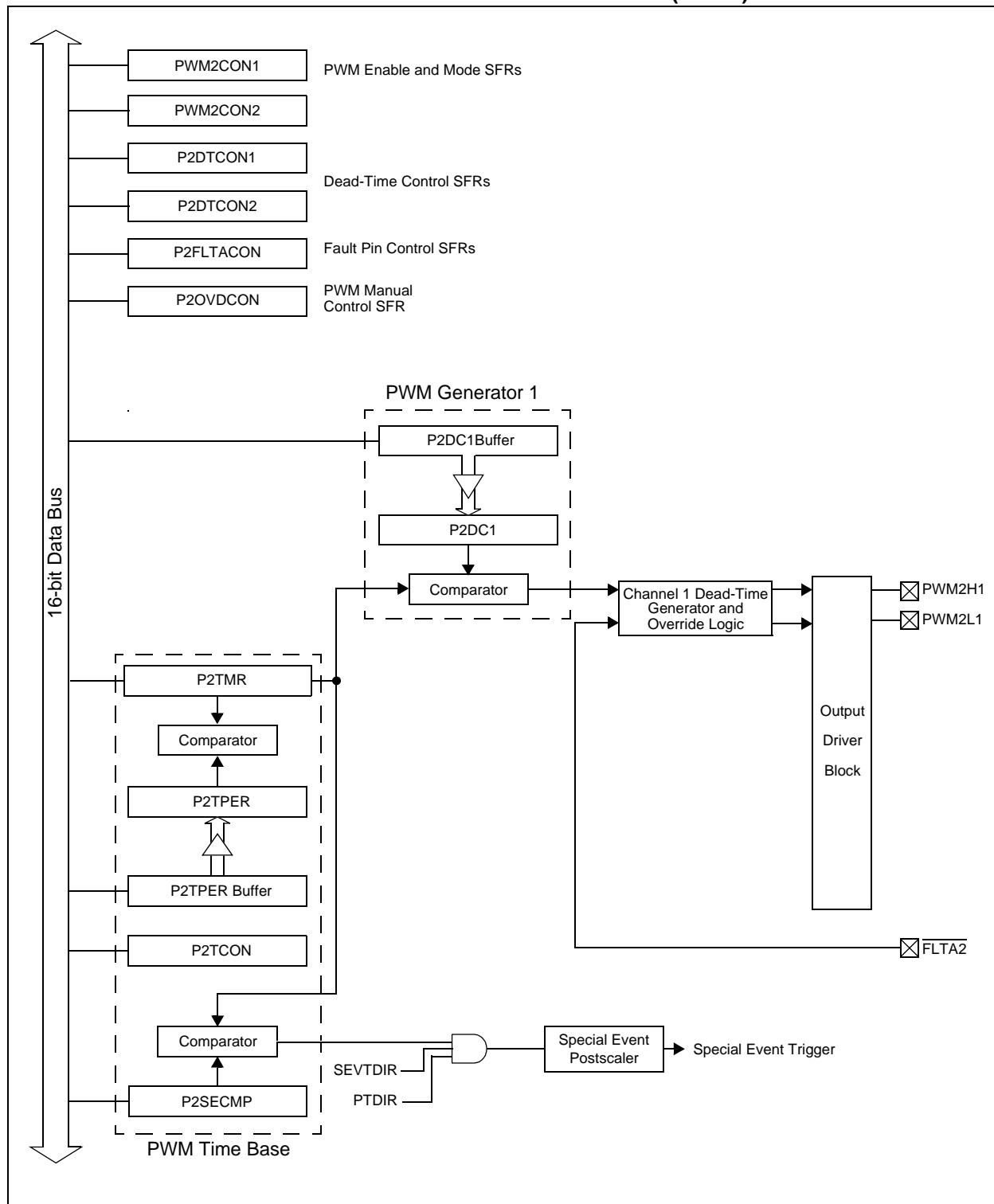
This module provides an additional pair of complimentary PWM outputs that can be used for:

- Independent PFC correction in a motor system
- Induction cooking

This module contains a duty cycle generator that provides two PWM outputs, numbered PWM2H1/PWM2L1.

**FIGURE 16-1: 6-CHANNEL PWM MODULE BLOCK DIAGRAM (PWM1)**



**FIGURE 16-2: 2-CHANNEL PWM MODULE BLOCK DIAGRAM (PWM2)**

## REGISTER 16-1: PxTCON: PWM TIME BASE CONTROL REGISTER

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
PTEN	—	PTSIDL	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTOPS<3:0>			PTCKPS<1:0>			PTMOD<1:0>	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **PTEN:** PWM Time Base Timer Enable bit  
1 = PWM time base is on  
0 = PWM time base is off
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **PTSIDL:** PWM Time Base Stop in Idle Mode bit  
1 = PWM time base halts in CPU Idle mode  
0 = PWM time base runs in CPU Idle mode
- bit 12-8     **Unimplemented:** Read as '0'
- bit 7-4      **PTOPS<3:0>:** PWM Time Base Output Postscale Select bits  
1111 = 1:16 postscale  
•  
•  
•  
0001 = 1:2 postscale  
0000 = 1:1 postscale
- bit 3-2      **PTCKPS<1:0>:** PWM Time Base Input Clock Prescale Select bits  
11 = PWM time base input clock period is 64 Tcy (1:64 prescale)  
10 = PWM time base input clock period is 16 Tcy (1:16 prescale)  
01 = PWM time base input clock period is 4 Tcy (1:4 prescale)  
00 = PWM time base input clock period is Tcy (1:1 prescale)
- bit 1-0      **PTMOD<1:0>:** PWM Time Base Mode Select bits  
11 = PWM time base operates in a Continuous Up/Down Count mode with interrupts for double PWM updates  
10 = PWM time base operates in a Continuous Up/Down Count mode  
01 = PWM time base operates in Single Pulse mode  
00 = PWM time base operates in a Free-Running mode

**REGISTER 16-2: PxTMR: PWM TIMER COUNT VALUE REGISTER**

R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTDIR	PTMR<14:8>						
bit 15	bit 8						

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTMR<7:0>							
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **PTDIR:** PWM Time Base Count Direction Status bit (read-only)

1 = PWM time base is counting down

0 = PWM time base is counting up

bit 14-0      **PTMR<14:0>:** PWM Time Base Register Count Value bits**REGISTER 16-3: PxTPER: PWM TIME BASE PERIOD REGISTER**

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	PTPER<14:8>						
bit 15	bit 8						

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTPER<7:0>							
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'bit 14-0      **PTPER<14:0>:** PWM Time Base Period Value bits

**REGISTER 16-4: PxSECMP: SPECIAL EVENT COMPARE REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SEVTDIR <sup>(1)</sup>	SEVTCMP<14:8> <sup>(2)</sup>						
bit 15	bit 8						

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SEVTCMP<7:0> <sup>(2)</sup>							
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **SEVTDIR:** Special Event Trigger Time Base Direction bit<sup>(1)</sup>

1 = A Special Event Trigger occurs when the PWM time base is counting downward

0 = A Special Event Trigger occurs when the PWM time base is counting upward

bit 14-0      **SEVTCMP<14:0>:** Special Event Compare Value bits<sup>(2)</sup>

**Note 1:** This bit is compared with the PTDIR bit (PxTMR<15>) to generate the Special Event Trigger.

**2:** The PxSECMP<14:0> bits are compared with the PxTMR<14:0> bits to generate the Special Event Trigger.

**REGISTER 16-5: PWM<sub>x</sub>CON1: PWM CONTROL REGISTER 1<sup>(2)</sup>**

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	PMOD3	PMOD2	PMOD1
bit 15						bit 8	

U-0	R/W-1	R/W-1	R/W-1	U-0	R/W-1	R/W-1	R/W-1
—	PEN3H <sup>(1)</sup>	PEN2H <sup>(1)</sup>	PEN1H <sup>(1)</sup>	—	PEN3L <sup>(1)</sup>	PEN2L <sup>(1)</sup>	PEN1L <sup>(1)</sup>
bit 7						bit 0	

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11      **Unimplemented:** Read as '0'bit 10-8      **PMOD3:PMOD1:** PWM I/O Pair Mode bits

1 = PWM I/O pin pair is in the Independent PWM Output mode

0 = PWM I/O pin pair is in the Complementary Output mode

bit 7      **Unimplemented:** Read as '0'bit 6-4      **PEN3H:PEN1H:** PWM<sub>x</sub>H I/O Enable bits<sup>(1)</sup>  1 = PWM<sub>x</sub>H pin is enabled for PWM output  0 = PWM<sub>x</sub>H pin disabled, I/O pin becomes general purpose I/Obit 3      **Unimplemented:** Read as '0'bit 2-0      **PEN3L:PEN1L:** PWM<sub>x</sub>L I/O Enable bits<sup>(1)</sup>  1 = PWM<sub>x</sub>L pin is enabled for PWM output  0 = PWM<sub>x</sub>L pin disabled, I/O pin becomes general purpose I/O

**Note 1:** Reset condition of the PEN<sub>x</sub>H and PEN<sub>x</sub>L bits depends on the value of the PWMPIN Configuration bit in the FPOR Configuration register.

**2:** PWM2 supports only one PWM I/O pin pair.

**REGISTER 16-6: PWMxCON2: PWM CONTROL REGISTER 2**

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0		
—	—	—	—	SEVOPS<3:0>					
bit 15						bit 8			

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	IUE	OSYNC	UDIS
bit 7						bit 0	

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-12      **Unimplemented:** Read as '0'

bit 11-8      **SEVOPS<3:0>:** PWM Special Event Trigger Output Postscale Select bits

1111 = 1:16 postscale

•

•

•

0001 = 1:2 postscale

0000 = 1:1 postscale

bit 7-3      **Unimplemented:** Read as '0'

bit 2      **IUE:** Immediate Update Enable bit

1 = Updates to the active PxDC registers are immediate

0 = Updates to the active PxDC registers are synchronized to the PWM time base

bit 1      **OSYNC:** Output Override Synchronization bit

1 = Output overrides via the PxOVDCON register are synchronized to the PWM time base

0 = Output overrides via the PxOVDCON register occur on next TCY boundary

bit 0      **UDIS:** PWM Update Disable bit

1 = Updates from Duty Cycle and Period Buffer registers are disabled

0 = Updates from Duty Cycle and Period Buffer registers are enabled

**REGISTER 16-7: PxDTCON1: DEAD-TIME CONTROL REGISTER 1**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DTBPS<1:0>	DTB<5:0>						
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DTAPS<1:0>	DTA<5:0>						
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14      **DTBPS<1:0>:** Dead-Time Unit B Prescale Select bits

11 = Clock period for Dead-Time Unit B is 8 TCY

10 = Clock period for Dead-Time Unit B is 4 TCY

01 = Clock period for Dead-Time Unit B is 2 TCY

00 = Clock period for Dead-Time Unit B is TCY

bit 13-8      **DTB<5:0>:** Unsigned 6-bit Dead-Time Value for Dead-Time Unit B bitsbit 7-6      **DTAPS<1:0>:** Dead-Time Unit A Prescale Select bits

11 = Clock period for Dead-Time Unit A is 8 TCY

10 = Clock period for Dead-Time Unit A is 4 TCY

01 = Clock period for Dead-Time Unit A is 2 TCY

00 = Clock period for Dead-Time Unit A is TCY

bit 5-0      **DTA<5:0>:** Unsigned 6-bit Dead-Time Value for Dead-Time Unit A bits

**REGISTER 16-8: PxDTCON2: DEAD-TIME CONTROL REGISTER 2<sup>(1)</sup>**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	DTS3A	DTS3I	DTS2A	DTS2I	DTS1A	DTS1I
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-6      **Unimplemented:** Read as '0'bit 5      **DTS3A:** Dead-Time Select for PWMxH3 Signal Going Active bit1 = Dead time provided from Unit B  
0 = Dead time provided from Unit Abit 4      **DTS3I:** Dead-Time Select for PWMxL3 Signal Going Inactive bit1 = Dead time provided from Unit B  
0 = Dead time provided from Unit Abit 3      **DTS2A:** Dead-Time Select for PWMxH2 Signal Going Active bit1 = Dead time provided from Unit B  
0 = Dead time provided from Unit Abit 2      **DTS2I:** Dead-Time Select for PWMxL2 Signal Going Inactive bit1 = Dead time provided from Unit B  
0 = Dead time provided from Unit Abit 1      **DTS1A:** Dead-Time Select for PWMxH1 Signal Going Active bit1 = Dead time provided from Unit B  
0 = Dead time provided from Unit Abit 0      **DTS1I:** Dead-Time Select for PWMxL1 Signal Going Inactive bit1 = Dead time provided from Unit B  
0 = Dead time provided from Unit A**Note 1:** PWM2 supports only one PWM I/O pin pair.

**REGISTER 16-9: PxFLTACON: FAULT A CONTROL REGISTER<sup>(1)</sup>**

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	FAOV3H	FAOV3L	FAOV2H	FAOV2L	FAOV1H	FAOV1L
bit 15							bit 8

R/W-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
FLTAM	—	—	—	—	FAEN3	FAEN2	FAEN1
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-14      **Unimplemented:** Read as '0'
- bit 13-8      **FAOVxH<3:1>:FAOVxL<3:1>:** Fault Input A PWM Override Value bits  
   1 = The PWM output pin is driven active on an external Fault input event  
   0 = The PWM output pin is driven inactive on an external Fault input event
- bit 7      **FLTAM:** Fault A Mode bit  
   1 = The Fault A input pin functions in the Cycle-by-Cycle mode  
   0 = The Fault A input pin latches all control pins to the programmed states in PxFLTACON<13:8>
- bit 6-3      **Unimplemented:** Read as '0'
- bit 2      **FAEN3:** Fault Input A Enable bit  
   1 = PWMxH3/PWMxL3 pin pair is controlled by Fault Input A  
   0 = PWMxH3/PWMxL3 pin pair is not controlled by Fault Input A
- bit 1      **FAEN2:** Fault Input A Enable bit  
   1 = PWMxH2/PWMxL2 pin pair is controlled by Fault Input A  
   0 = PWMxH2/PWMxL2 pin pair is not controlled by Fault Input A
- bit 0      **FAEN1:** Fault Input A Enable bit  
   1 = PWMxH1/PWMxL1 pin pair is controlled by Fault Input A  
   0 = PWMxH1/PWMxL1 pin pair is not controlled by Fault Input A

**Note 1:** PWM2 supports only one PWM I/O pin pair.

**REGISTER 16-10: PxOVDCON: OVERRIDE CONTROL REGISTER<sup>(1)</sup>**

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	POVD3H	POVD3L	POVD2H	POVD2L	POVD1H	POVD1L
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	POUT3H	POUT3L	POUT2H	POUT2L	POUT1H	POUT1L
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14      **Unimplemented:** Read as '0'

bit 13-8      **POVDxH<3:1>:POVDxL<3:1>:** PWM Output Override bits

1 = Output on PWMx I/O pin is controlled by the PWM generator

0 = Output on PWMx I/O pin is controlled by the value in the corresponding POUTxH:POUTxL bit

bit 7-6      **Unimplemented:** Read as '0'

bit 5-0      **POUTxH<3:1>:POUTxL<3:1>:** PWM Manual Output bits

1 = PWMx I/O pin is driven active when the corresponding POVDxH:POVDxL bit is cleared

0 = PWMx I/O pin is driven inactive when the corresponding POVDxH:POVDxL bit is cleared

**Note 1:** PWM2 supports only one PWM I/O pin pair.

**REGISTER 16-11: PxDC1: PWM DUTY CYCLE REGISTER 1**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PDC1<15:8>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PDC1<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **PDC1<15:0>:** PWM Duty Cycle 1 Value bits**REGISTER 16-12: P1DC2: PWM DUTY CYCLE REGISTER 2**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PDC2<15:8>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PDC2<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **PDC2<15:0>:** PWM Duty Cycle 2 Value bits**REGISTER 16-13: P1DC3: PWM DUTY CYCLE REGISTER 3**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PDC3<15:8>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PDC3<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **PDC3<15:0>:** PWM Duty Cycle 3 Value bits

**NOTES:**

## 17.0 QUADRATURE ENCODER INTERFACE (QEI) MODULE

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 15. Quadrature Encoder Interface (QEI)**” (DS70208) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

This chapter describes the Quadrature Encoder Interface (QEI) module and associated operational modes. The QEI module provides the interface to incremental encoders for obtaining mechanical position data.

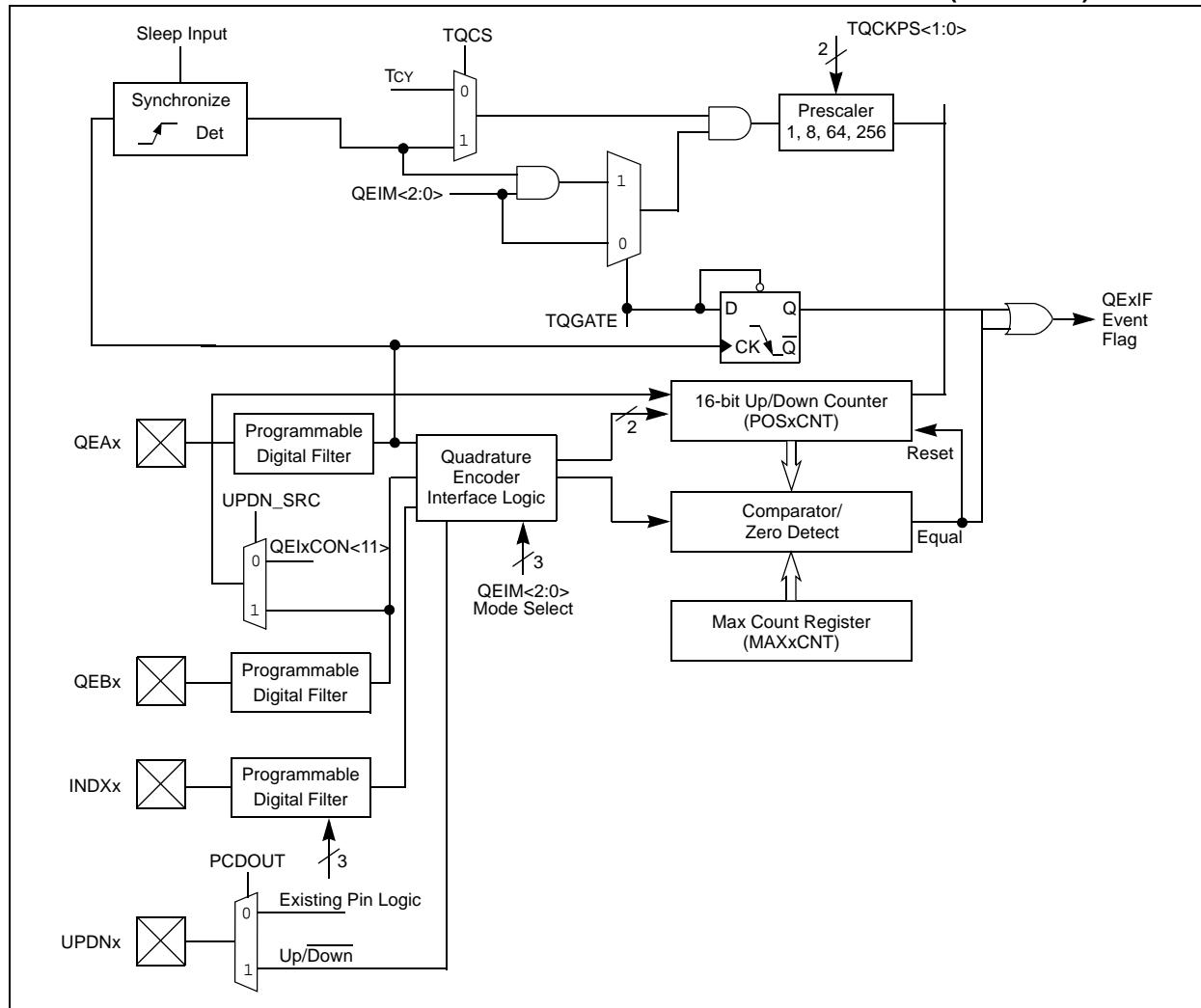
The operational features of the QEI include:

- Three input channels for two phase signals and index pulse
- 16-bit up/down position counter
- Count direction status
- Position Measurement (x2 and x4) mode
- Programmable digital noise filters on inputs
- Alternate 16-bit Timer/Counter mode
- Quadrature Encoder Interface interrupts

These operating modes are determined by setting the appropriate bits, QEIM<2:0> bits (QEIxCON<10:8>). **Figure 17-1** depicts the Quadrature Encoder Interface block diagram.

**Note:** An ‘x’ used in the names of pins, control/status bits and registers denotes a particular Quadrature Encoder Interface (QEI) module number (x = 1 or 2).

**FIGURE 17-1: QUADRATURE ENCODER INTERFACE BLOCK DIAGRAM (x = 1 OR 2)**



**REGISTER 17-1: QEIxCON: QEIx CONTROL REGISTER (x = 1 or 2)**

R/W-0	U-0	R/W-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0
CNTERR <sup>(1)</sup>	—	QEISIDL	INDEX	UPDN <sup>(2)</sup>	QEIM<2:0>		
bit 15	bit 8						

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SWPAB	PCDOUT	TQGATE	TQCKPS<1:0>		POSRES	TQCS	UPDN_SRC
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15	<b>CNTERR:</b> Count Error Status Flag bit <sup>(1)</sup> 1 = Position count error has occurred 0 = No position count error has occurred
bit 14	<b>Unimplemented:</b> Read as '0'
bit 13	<b>QEISIDL:</b> Stop in Idle Mode bit 1 = Discontinue module operation when device enters Idle mode 0 = Continue module operation in Idle mode
bit 12	<b>INDEX:</b> Index Pin State Status bit (read-only) 1 = Index pin is High 0 = Index pin is Low
bit 11	<b>UPDN:</b> Position Counter Direction Status bit <sup>(2)</sup> 1 = Position Counter Direction is positive (+) 0 = Position Counter Direction is negative (-)
bit 10-8	<b>QEIM&lt;2:0&gt;:</b> Quadrature Encoder Interface Mode Select bits 111 = Quadrature Encoder Interface enabled (x4 mode) with position counter reset by match (MAXxCNT) 110 = Quadrature Encoder Interface enabled (x4 mode) with Index Pulse reset of position counter 101 = Quadrature Encoder Interface enabled (x2 mode) with position counter reset by match (MAXxCNT) 100 = Quadrature Encoder Interface enabled (x2 mode) with Index Pulse reset of position counter 011 = Unused (Module disabled) 010 = Unused (Module disabled) 001 = Starts 16-bit Timer 000 = Quadrature Encoder Interface/Timer off
bit 7	<b>SWPAB:</b> Phase A and Phase B Input Swap Select bit 1 = Phase A and Phase B inputs swapped 0 = Phase A and Phase B inputs not swapped
bit 6	<b>PCDOUT:</b> Position Counter Direction State Output Enable bit 1 = Position Counter Direction Status Output Enable (QEI logic controls state of I/O pin) 0 = Position Counter Direction Status Output Disabled (Normal I/O pin operation)

**Note 1:** This bit only applies when QEIM<2:0> = '110' or '100'.

**2:** Read-only bit when QEIM<2:0> = '1xx'. Read/write bit when QEIM<2:0> = '001'.

**3:** Prescaler utilized for 16-bit Timer mode only.

**4:** This bit applies only when QEIM<2:0> = 100 or 110.

**5:** When configured for QEI mode, this control bit is a 'don't care'.

**REGISTER 17-1: QEIxCON: QEIx CONTROL REGISTER (x = 1 or 2) (CONTINUED)**

bit 5	<b>TQGATE:</b> Timer Gated Time Accumulation Enable bit 1 = Timer gated time accumulation enabled 0 = Timer gated time accumulation disabled
bit 4-3	<b>TQCKPS&lt;1:0&gt;:</b> Timer Input Clock Prescale Select bits <sup>(3)</sup> 11 = 1:256 prescale value 10 = 1:64 prescale value 01 = 1:8 prescale value 00 = 1:1 prescale value
bit 2	<b>POSRES:</b> Position Counter Reset Enable bit <sup>(4)</sup> 1 = Index Pulse resets Position Counter 0 = Index Pulse does not reset Position Counter
bit 1	<b>TQCS:</b> Timer Clock Source Select bit 1 = External clock from pin QEAx (on the rising edge) 0 = Internal clock (Tcy)
bit 0	<b>UPDN_SRC:</b> Position Counter Direction Selection Control bit <sup>(5)</sup> 1 = QEbx pin state defines position counter direction 0 = Control/Status bit, UPDN (QEIxCON<11>), defines timer counter (POSxCNT) direction

**Note 1:** This bit only applies when QEIM<2:0> = '110' or '100'.

**2:** Read-only bit when QEIM<2:0> = '1XX'. Read/write bit when QEIM<2:0> = '001'.

**3:** Prescaler utilized for 16-bit Timer mode only.

**4:** This bit applies only when QEIM<2:0> = 100 or 110.

**5:** When configured for QEI mode, this control bit is a 'don't care'.

**REGISTER 17-2: DFLTxCON: DIGITAL FILTER CONTROL REGISTER**

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	IMV<1:0>	CEID	
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0
QEOUT		QECK<2:0>		—	—	—	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11      **Unimplemented:** Read as '0'

bit 10-9      **IMV<1:0>:** Index Match Value bits – These bits allow the user application to specify the state of the QEAx and QEbx input pins during an Index pulse when the POSxCNT register is to be reset.

In x4 Quadrature Count Mode:

  IMV1 = Required State of Phase B input signal for match on index pulse

  IMV0 = Required State of Phase A input signal for match on index pulse

In x4 Quadrature Count Mode:

  IMV1 = Selects Phase input signal for Index state match (0 = Phase A, 1 = Phase B)

  IMV0 = Required state of the selected Phase input signal for match on index pulse

bit 8      **CEID:** Count Error Interrupt Disable bit

  1 = Interrupts due to count errors are disabled

  0 = Interrupts due to count errors are enabled

bit 7      **QEOUT:** QEAx/QEBx/INDEXx Pin Digital Filter Output Enable bit

  1 = Digital filter outputs enabled

  0 = Digital filter outputs disabled (normal pin operation)

bit 6-4      **QECK<2:0>:** QEAx/QEBx/INDEXx Digital Filter Clock Divide Select bits

  111 = 1:256 Clock Divide

  110 = 1:128 Clock Divide

  101 = 1:64 Clock Divide

  100 = 1:32 Clock Divide

  011 = 1:16 Clock Divide

  010 = 1:4 Clock Divide

  001 = 1:2 Clock Divide

  000 = 1:1 Clock Divide

bit 3-0      **Unimplemented:** Read as '0'

## 18.0 SERIAL PERIPHERAL INTERFACE (SPI)

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 18. Serial Peripheral Interface (SPI)**” (DS70206) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The Serial Peripheral Interface (SPI) module is a synchronous serial interface useful for communicating with other peripheral or microcontroller devices. These peripheral devices can be serial EEPROMs, shift registers, display drivers, analog-to-digital converters, etc. The SPI module is compatible with Motorola® SPI and SIOP.

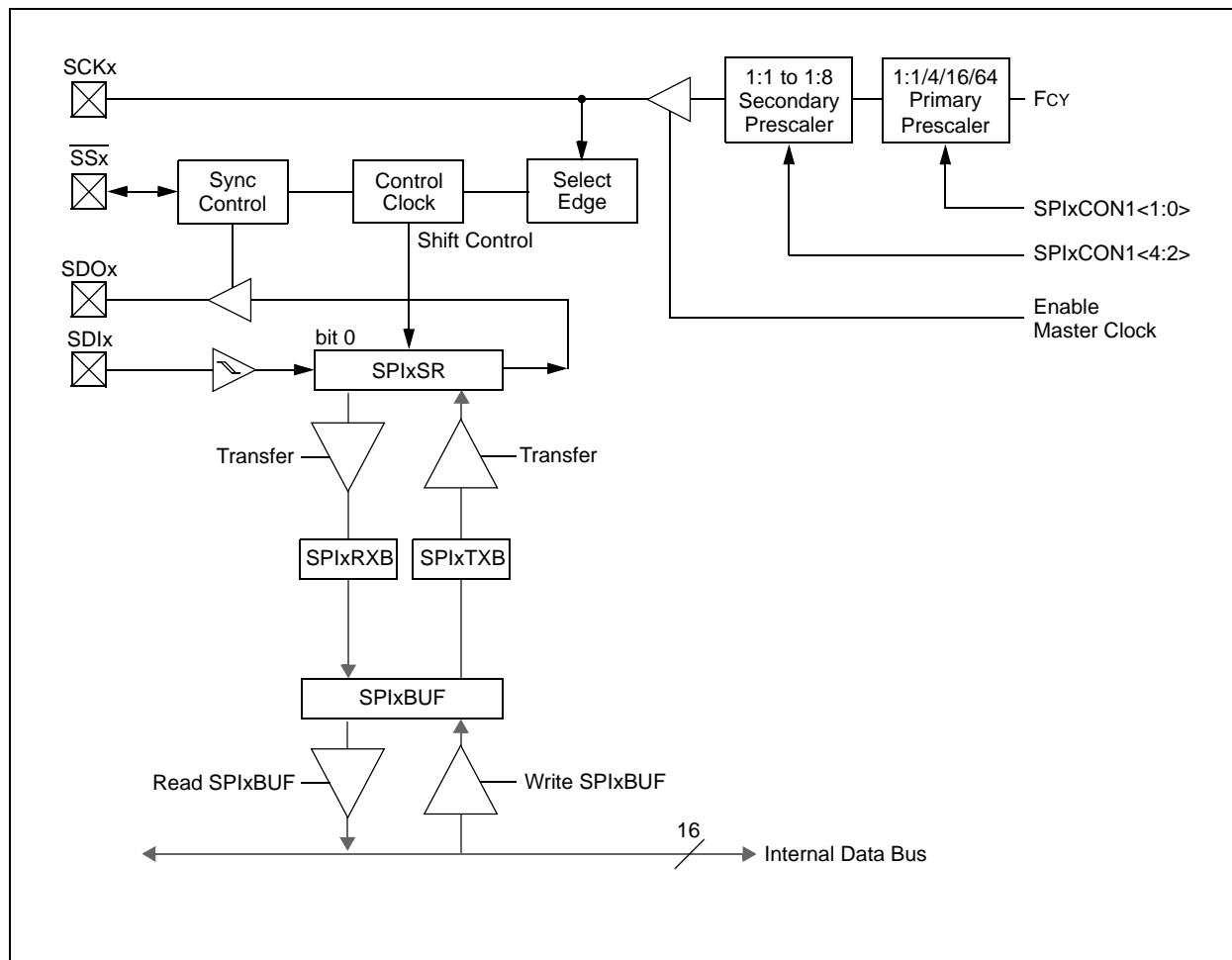
Each SPI module consists of a 16-bit shift register, SPIxSR (where  $x = 1$  or  $2$ ), used for shifting data in and out, and a buffer register, SPIxBUF. A control register, SPIxCON, configures the module. Additionally, a status register, SPIxSTAT, indicates status conditions.

The serial interface consists of 4 pins:

- SDIx (serial data input)
- SDOx (serial data output)
- SCKx (shift clock input or output)
- SSx (active-low slave select)

In Master mode operation, SCK is a clock output. In Slave mode, it is a clock input.

**FIGURE 18-1: SPI MODULE BLOCK DIAGRAM**



**REGISTER 18-1: SPIxSTAT: SPIx STATUS AND CONTROL REGISTER**

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
SPIEN	—	SPISIDL	—	—	—	—	—
bit 15	bit 8						

U-0	R/C-0	U-0	U-0	U-0	U-0	R-0	R-0
—	SPIROV	—	—	—	—	SPITBF	SPIRBF
bit 7	bit 0						

<b>Legend:</b>	C = Clearable bit
R = Readable bit	W = Writable bit
-n = Value at POR	'1' = Bit is set
	'0' = Bit is cleared
	x = Bit is unknown

- bit 15      **SPIEN:** SPIx Enable bit  
               1 = Enables module and configures SCKx, SDOx, SDIx and SSx as serial port pins  
               0 = Disables module
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **SPISIDL:** Stop in Idle Mode bit  
               1 = Discontinue module operation when device enters Idle mode  
               0 = Continue module operation in Idle mode
- bit 12-7     **Unimplemented:** Read as '0'
- bit 6        **SPIROV:** Receive Overflow Flag bit  
               1 = A new byte/word is completely received and discarded. The user software has not read the previous data in the SPIxBUF register  
               0 = No overflow has occurred
- bit 5-2      **Unimplemented:** Read as '0'
- bit 1        **SPITBF:** SPIx Transmit Buffer Full Status bit  
               1 = Transmit not yet started, SPIxTXB is full  
               0 = Transmit started, SPIxTXB is empty  
               Automatically set in hardware when CPU writes SPIxBUF location, loading SPIxTXB  
               Automatically cleared in hardware when SPIx module transfers data from SPIxTXB to SPIxSR
- bit 0        **SPIRBF:** SPIx Receive Buffer Full Status bit  
               1 = Receive complete, SPIxRXB is full  
               0 = Receive is not complete, SPIxRXB is empty  
               Automatically set in hardware when SPIx transfers data from SPIxSR to SPIxRXB  
               Automatically cleared in hardware when core reads SPIxBUF location, reading SPIxRXB

## REGISTER 18-2: SPIxCON1: SPIx CONTROL REGISTER 1

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	DISSCK	DISSDO	MODE16	SMP	CKE <sup>(1)</sup>
bit 15	bit 8						

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SSEN <sup>(3)</sup>	CKP	MSTEN	SPRE<2:0> <sup>(2)</sup>		PPRE<1:0> <sup>(2)</sup>		
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13	<b>Unimplemented:</b> Read as '0'
bit 12	<b>DISSCK:</b> Disable SCKx Pin bit (SPI Master modes only) 1 = Internal SPI clock is disabled, pin functions as I/O 0 = Internal SPI clock is enabled
bit 11	<b>DISSDO:</b> Disable SDOx Pin bit 1 = SDOx pin is not used by module; pin functions as I/O 0 = SDOx pin is controlled by the module
bit 10	<b>MODE16:</b> Word/Byte Communication Select bit 1 = Communication is word-wide (16 bits) 0 = Communication is byte-wide (8 bits)
bit 9	<b>SMP:</b> SPIx Data Input Sample Phase bit <u>Master mode:</u> 1 = Input data sampled at end of data output time 0 = Input data sampled at middle of data output time <u>Slave mode:</u> SMP must be cleared when SPIx is used in Slave mode.
bit 8	<b>CKE:</b> SPIx Clock Edge Select bit <sup>(1)</sup> 1 = Serial output data changes on transition from active clock state to Idle clock state (see bit 6) 0 = Serial output data changes on transition from Idle clock state to active clock state (see bit 6)
bit 7	<b>SSEN:</b> Slave Select Enable bit (Slave mode) <sup>(3)</sup> 1 = SS <sub>x</sub> pin used for Slave mode 0 = SS <sub>x</sub> pin not used by module. Pin controlled by port function
bit 6	<b>CKP:</b> Clock Polarity Select bit 1 = Idle state for clock is a high level; active state is a low level 0 = Idle state for clock is a low level; active state is a high level
bit 5	<b>MSTEN:</b> Master Mode Enable bit 1 = Master mode 0 = Slave mode

**Note 1:** This bit is not used in Framed SPI modes. Program this bit to '0' for the Framed SPI modes (FRMEN = 1).**2:** Do not set both Primary and Secondary prescalers to a value of 1:1.**3:** This bit must be cleared when FRMEN = 1.

**REGISTER 18-2: SPIxCON1: SPIx CONTROL REGISTER 1 (CONTINUED)**

bit 4-2      **SPRE<2:0>**: Secondary Prescale bits (Master mode)<sup>(2)</sup>

111 = Secondary prescale 1:1  
110 = Secondary prescale 2:1

•  
•  
•

000 = Secondary prescale 8:1

bit 1-0      **PPRE<1:0>**: Primary Prescale bits (Master mode)<sup>(2)</sup>

11 = Primary prescale 1:1  
10 = Primary prescale 4:1  
01 = Primary prescale 16:1  
00 = Primary prescale 64:1

**Note 1:** This bit is not used in Framed SPI modes. Program this bit to '0' for the Framed SPI modes (FRMEN = 1).

**2:** Do not set both Primary and Secondary prescalers to a value of 1:1.

**3:** This bit must be cleared when FRMEN = 1.

**REGISTER 18-3: SPIxCON2: SPIx CONTROL REGISTER 2**

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
FRMEN	SPIFSD	FRMPOL	—	—	—	—	—
bit 15	bit 8						

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	U-0
—	—	—	—	—	—	FRMDLY	—
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **FRMEN:** Framed SPIx Support bit  
               1 = Framed SPIx support enabled ( $\overline{SS}_x$  pin used as frame sync pulse input/output)  
               0 = Framed SPIx support disabled
- bit 14      **SPIFSD:** Frame Sync Pulse Direction Control bit  
               1 = Frame sync pulse input (slave)  
               0 = Frame sync pulse output (master)
- bit 13      **FRMPOL:** Frame Sync Pulse Polarity bit  
               1 = Frame sync pulse is active-high  
               0 = Frame sync pulse is active-low
- bit 12-2     **Unimplemented:** Read as '0'
- bit 1        **FRMDLY:** Frame Sync Pulse Edge Select bit  
               1 = Frame sync pulse coincides with first bit clock  
               0 = Frame sync pulse precedes first bit clock
- bit 0        **Unimplemented:** This bit must not be set to '1' by the user application

**NOTES:**

## 19.0 INTER-INTEGRATED CIRCUIT™ (I<sup>2</sup>C™)

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 19. Inter-Integrated Circuit™ (I<sup>2</sup>C™)**” (DS70195) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The Inter-Integrated Circuit (I<sup>2</sup>C) module provides complete hardware support for both Slave and Multi-Master modes of the I<sup>2</sup>C serial communication standard, with a 16-bit interface.

The I<sup>2</sup>C module has a 2-pin interface:

- The SCLx pin is clock
- The SDAx pin is data

The I<sup>2</sup>C module offers the following key features:

- I<sup>2</sup>C interface supporting both Master and Slave modes of operation
- I<sup>2</sup>C Slave mode supports 7-bit and 10-bit addressing
- I<sup>2</sup>C Master mode supports 7-bit and 10-bit addressing
- I<sup>2</sup>C port allows bidirectional transfers between master and slaves
- Serial clock synchronization for I<sup>2</sup>C port can be used as a handshake mechanism to suspend and resume serial transfer (SCLREL control)
- I<sup>2</sup>C supports multi-master operation, detects bus collision and arbitrates accordingly

## 19.1 Operating Modes

The hardware fully implements all the master and slave functions of the I<sup>2</sup>C Standard and Fast mode specifications, as well as 7 and 10-bit addressing.

The I<sup>2</sup>C module can operate either as a slave or a master on an I<sup>2</sup>C bus.

The following types of I<sup>2</sup>C operation are supported:

- I<sup>2</sup>C slave operation with 7-bit addressing
- I<sup>2</sup>C slave operation with 10-bit addressing
- I<sup>2</sup>C master operation with 7-bit or 10-bit addressing

For details about the communication sequence in each of these modes, refer to the “*dsPIC33F/PIC24H Family Reference Manual*”. Please see the Microchip web site ([www.microchip.com](http://www.microchip.com)) for the latest dsPIC33F/PIC24H Family Reference Manual chapters.

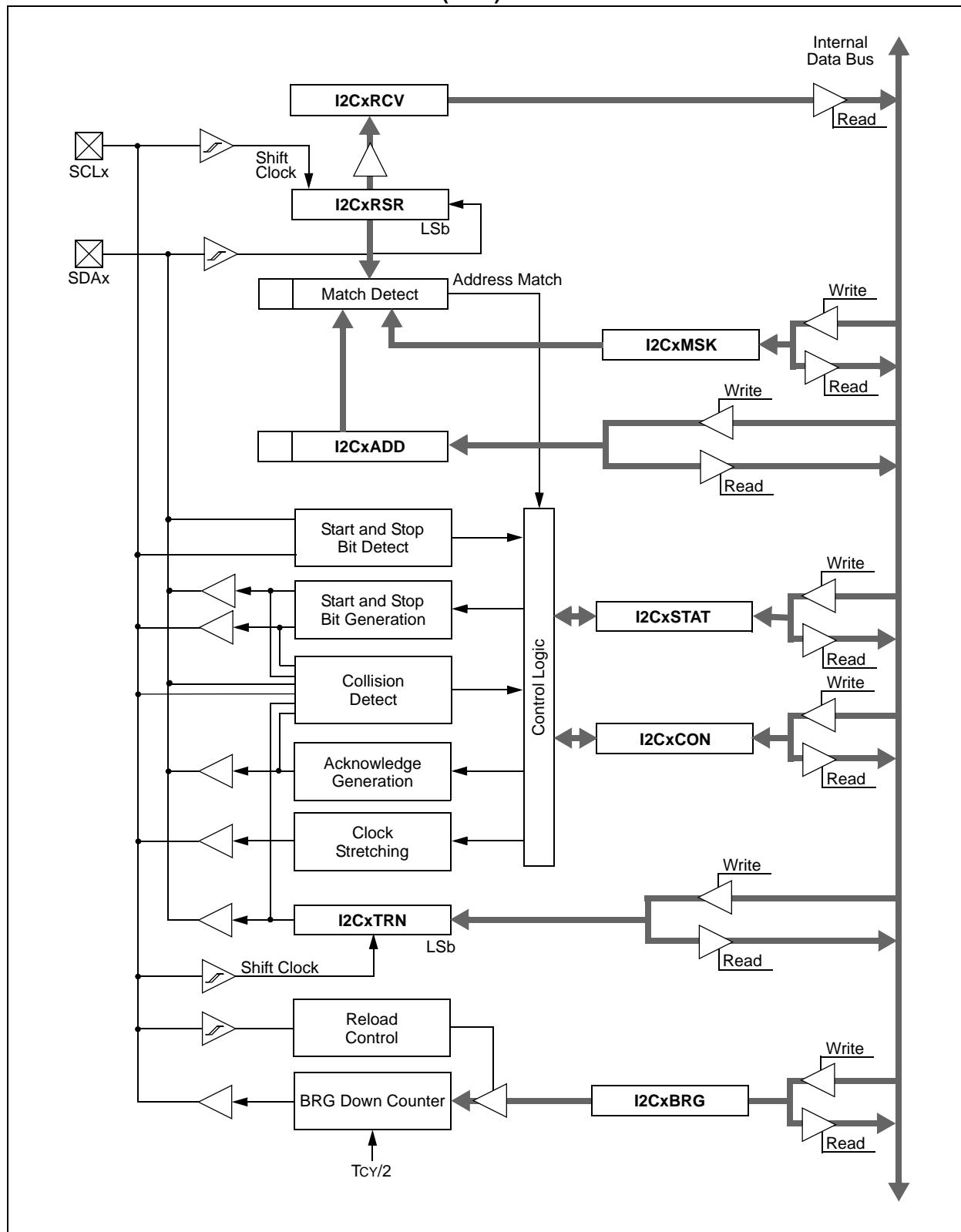
## 19.2 I<sup>2</sup>C Registers

The I2CxCON and I2CxSTAT are control and status registers, respectively. The I2CxCON register is readable and writable. The lower six bits of I2CxSTAT are read-only. The remaining bits of the I2CxSTAT are read/write:

- I2CxRSR is the shift register used for shifting data internal to the module and the user application has no access to it
- I2CxRCV is the receive buffer and the register to which data bytes are written, or from which data bytes are read
- I2CxTRN is the transmit register to which bytes are written during a transmit operation
- The I2CxADD register holds the slave address
- A status bit, ADD10, indicates 10-bit Address mode
- The I2CxBRG acts as the Baud Rate Generator (BRG) reload value

In receive operations, I2CxRSR and I2CxRCV together form a double-buffered receiver. When I2CxRSR receives a complete byte, it is transferred to I2CxRCV, and an interrupt pulse is generated.

FIGURE 19-1: I<sup>2</sup>C™ BLOCK DIAGRAM (x = 1)



**REGISTER 19-1: I2CxCON: I2Cx CONTROL REGISTER**

R/W-0	U-0	R/W-0	R/W-1, HC	R/W-0	R/W-0	R/W-0	R/W-0
I2CEN	—	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN
bit 15	bit 8						

R/W-0	R/W-0	R/W-0	R/W-0, HC				
GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN
bit 7	bit 0						

**Legend:**

R = Readable bit

-n = Value at POR

U = Unimplemented bit, read as '0'

W = Writable bit

'1' = Bit is set

HS = Set in hardware

'0' = Bit is cleared

HC = Cleared in Hardware

x = Bit is unknown

bit 15	<b>I2CEN:</b> I2Cx Enable bit 1 = Enables the I2Cx module and configures the SDAx and SCLx pins as serial port pins 0 = Disables the I2Cx module. All I <sup>2</sup> C™ pins are controlled by port functions
bit 14	<b>Unimplemented:</b> Read as '0'
bit 13	<b>I2CSIDL:</b> Stop in Idle Mode bit 1 = Discontinue module operation when device enters an Idle mode 0 = Continue module operation in Idle mode
bit 12	<b>SCLREL:</b> SCLx Release Control bit (when operating as I <sup>2</sup> C slave) 1 = Release SCLx clock 0 = Hold SCLx clock low (clock stretch) <u>If STREN = 1:</u> Bit is R/W (i.e., software can write '0' to initiate stretch and write '1' to release clock). Hardware clear at beginning of slave transmission. Hardware clear at end of slave reception. <u>If STREN = 0:</u> Bit is R/S (i.e., software can only write '1' to release clock). Hardware clear at beginning of slave transmission.
bit 11	<b>IPMIEN:</b> Intelligent Peripheral Management Interface (IPMI) Enable bit 1 = IPMI mode is enabled; all addresses Acknowledged 0 = IPMI mode disabled
bit 10	<b>A10M:</b> 10-bit Slave Address bit 1 = I2CxADD is a 10-bit slave address 0 = I2CxADD is a 7-bit slave address
bit 9	<b>DISSLW:</b> Disable Slew Rate Control bit 1 = Slew rate control disabled 0 = Slew rate control enabled
bit 8	<b>SMEN:</b> SMBus Input Levels bit 1 = Enable I/O pin thresholds compliant with SMBus specification 0 = Disable SMBus input thresholds
bit 7	<b>GCEN:</b> General Call Enable bit (when operating as I <sup>2</sup> C slave) 1 = Enable interrupt when a general call address is received in the I2CxRSR (module is enabled for reception) 0 = General call address disabled
bit 6	<b>STREN:</b> SCLx Clock Stretch Enable bit (when operating as I <sup>2</sup> C slave) Used in conjunction with SCLREL bit. 1 = Enable software or receive clock stretching 0 = Disable software or receive clock stretching

**REGISTER 19-1: I2CxCON: I2Cx CONTROL REGISTER (CONTINUED)**

bit 5	<b>ACKDT:</b> Acknowledge Data bit (when operating as I <sup>2</sup> C master, applicable during master receive) Value that is transmitted when the software initiates an Acknowledge sequence. 1 = Send NACK during Acknowledge 0 = Send ACK during Acknowledge
bit 4	<b>ACKEN:</b> Acknowledge Sequence Enable bit (when operating as I <sup>2</sup> C master, applicable during master receive) 1 = Initiate Acknowledge sequence on SDAx and SCLx pins and transmit ACKDT data bit. Hardware clear at end of master Acknowledge sequence 0 = Acknowledge sequence not in progress
bit 3	<b>RCEN:</b> Receive Enable bit (when operating as I <sup>2</sup> C master) 1 = Enables Receive mode for I <sup>2</sup> C. Hardware clear at end of eighth bit of master receive data byte 0 = Receive sequence not in progress
bit 2	<b>PEN:</b> Stop Condition Enable bit (when operating as I <sup>2</sup> C master) 1 = Initiate Stop condition on SDAx and SCLx pins. Hardware clear at end of master Stop sequence 0 = Stop condition not in progress
bit 1	<b>RSEN:</b> Repeated Start Condition Enable bit (when operating as I <sup>2</sup> C master) 1 = Initiate Repeated Start condition on SDAx and SCLx pins. Hardware clear at end of master Repeated Start sequence 0 = Repeated Start condition not in progress
bit 0	<b>SEN:</b> Start Condition Enable bit (when operating as I <sup>2</sup> C master) 1 = Initiate Start condition on SDAx and SCLx pins. Hardware clear at end of master Start sequence 0 = Start condition not in progress

**REGISTER 19-2: I2CxSTAT: I2Cx STATUS REGISTER**

R-0, HSC ACKSTAT	R-0, HSC TRSTAT	U-0 —	U-0 —	U-0 —	R/C-0, HS BCL	R-0, HSC GCSTAT	R-0, HSC ADD10
bit 15				bit 8			

R/C-0, HS IWCOL	R/C-0, HS I2COV	R-0, HSC D_A	R/C-0, HSC P	R/C-0, HSC S	R-0, HSC R_W	R-0, HSC RBF	R-0, HSC TBF
bit 7				bit 0			

<b>Legend:</b>	C = Clear only bit	U = Unimplemented bit, read as '0'
R = Readable bit	W = Writable bit	HS = Set in hardware
-n = Value at POR	'1' = Bit is set	HSC = Hardware set/cleared

- bit 15      **ACKSTAT:** Acknowledge Status bit  
(when operating as I<sup>2</sup>C™ master, applicable to master transmit operation)  
1 = NACK received from slave  
0 = ACK received from slave  
Hardware set or clear at end of slave Acknowledge.
- bit 14      **TRSTAT:** Transmit Status bit (when operating as I<sup>2</sup>C master, applicable to master transmit operation)  
1 = Master transmit is in progress (8 bits + ACK)  
0 = Master transmit is not in progress  
Hardware set at beginning of master transmission. Hardware clear at end of slave Acknowledge.
- bit 13-11    **Unimplemented:** Read as '0'
- bit 10       **BCL:** Master Bus Collision Detect bit  
1 = A bus collision has been detected during a master operation  
0 = No collision  
Hardware set at detection of bus collision.
- bit 9         **GCSTAT:** General Call Status bit  
1 = General call address was received  
0 = General call address was not received  
Hardware set when address matches general call address. Hardware clear at Stop detection.
- bit 8         **ADD10:** 10-bit Address Status bit  
1 = 10-bit address was matched  
0 = 10-bit address was not matched  
Hardware set at match of 2nd byte of matched 10-bit address. Hardware clear at Stop detection.
- bit 7         **IWCOL:** Write Collision Detect bit  
1 = An attempt to write the I2CxTRN register failed because the I<sup>2</sup>C module is busy  
0 = No collision  
Hardware set at occurrence of write to I2CxTRN while busy (cleared by software).
- bit 6         **I2COV:** Receive Overflow Flag bit  
1 = A byte was received while the I2CxRCV register is still holding the previous byte  
0 = No overflow  
Hardware set at attempt to transfer I2CxRSR to I2CxRCV (cleared by software).
- bit 5         **D\_A:** Data/Address bit (when operating as I<sup>2</sup>C slave)  
1 = Indicates that the last byte received was data  
0 = Indicates that the last byte received was device address  
Hardware clear at device address match. Hardware set by reception of slave byte.
- bit 4         **P:** Stop bit  
1 = Indicates that a Stop bit has been detected last  
0 = Stop bit was not detected last  
Hardware set or clear when Start, Repeated Start or Stop detected.

**REGISTER 19-2: I2CxSTAT: I2Cx STATUS REGISTER (CONTINUED)**

bit 3	<b>S:</b> Start bit 1 = Indicates that a Start (or Repeated Start) bit has been detected last 0 = Start bit was not detected last Hardware set or clear when Start, Repeated Start or Stop detected.
bit 2	<b>R_W:</b> Read/Write Information bit (when operating as I <sup>2</sup> C slave) 1 = Read – indicates data transfer is output from slave 0 = Write – indicates data transfer is input to slave Hardware set or clear after reception of I <sup>2</sup> C device address byte.
bit 1	<b>RB<sub>F</sub>:</b> Receive Buffer Full Status bit 1 = Receive complete, I2CxRCV is full 0 = Receive not complete, I2CxRCV is empty Hardware set when I2CxRCV is written with received byte. Hardware clear when software reads I2CxRCV.
bit 0	<b>TB<sub>F</sub>:</b> Transmit Buffer Full Status bit 1 = Transmit in progress, I2CxTRN is full 0 = Transmit complete, I2CxTRN is empty Hardware set when software writes I2CxTRN. Hardware clear at completion of data transmission.

**REGISTER 19-3: I2CxMSK: I2Cx SLAVE MODE ADDRESS MASK REGISTER**

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	AMSK9	AMSK8
bit 15						bit 8	

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| AMSK7 | AMSK6 | AMSK5 | AMSK4 | AMSK3 | AMSK2 | AMSK1 | AMSK0 |
| bit 7 |       |       |       |       |       | bit 0 |       |

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-10

**Unimplemented:** Read as '0'

bit 9-0

**AMSKx:** Mask for Address bit x Select bit

1 = Enable masking for bit x of incoming message address; bit match not required in this position  
0 = Disable masking for bit x; bit match required in this position

**NOTES:**

## 20.0 UNIVERSAL ASYNCHRONOUS RECEIVER TRANSMITTER (UART)

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 17. UART**” (DS70188) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The Universal Asynchronous Receiver Transmitter (UART) module is one of the serial I/O modules available in the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 device family. The UART is a full-duplex asynchronous system that can communicate with peripheral devices, such as personal computers, LIN 2.0, RS-232 and RS-485 interfaces. The module also supports a hardware flow control option with the UxCTS and UxRTS pins and also includes an IrDA® encoder and decoder.

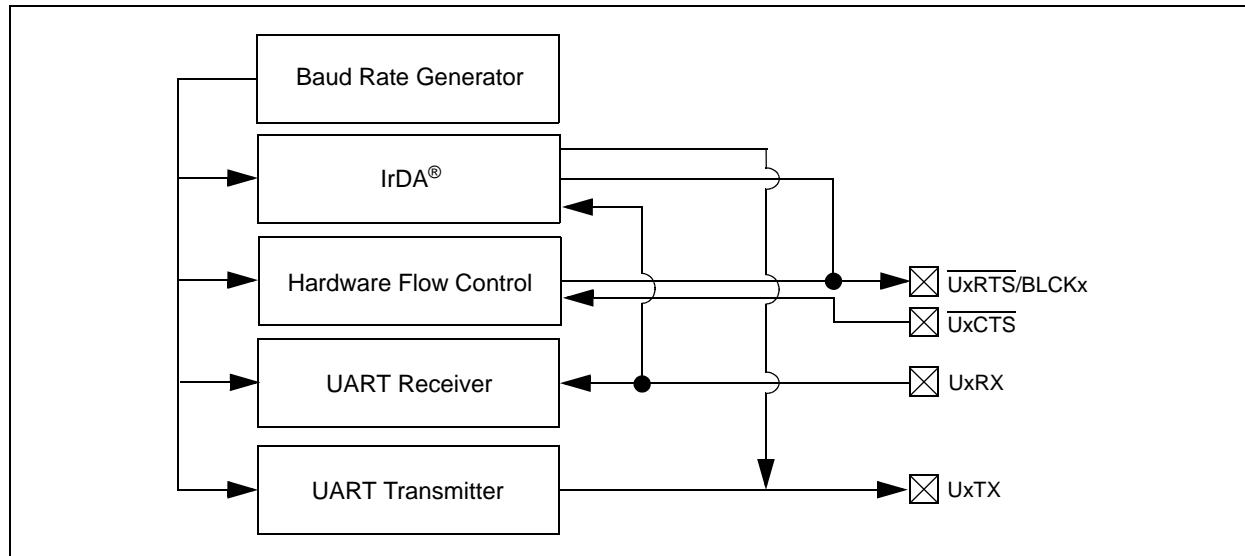
The primary features of the UART module are:

- Full-Duplex, 8- or 9-bit Data Transmission through the UxTX and UxRX pins
- Even, Odd or No Parity options (for 8-bit data)
- One or two stop bits
- Hardware flow control option with UxCTS and UxRTS pins
- Fully integrated Baud Rate Generator with 16-bit prescaler
- Baud rates ranging from 10 Mbps to 38 bps at 40 MIPS
- Baud rates ranging from 4 Mbps to 61 bps at 4x mode at 40 MIPS
- 4-deep First-In First-Out (FIFO) Transmit Data buffer
- 4-deep FIFO Receive Data buffer
- Parity, framing and buffer overrun error detection
- Support for 9-bit mode with Address Detect (9th bit = 1)
- Transmit and Receive interrupts
- A separate interrupt for all UART error conditions
- Loopback mode for diagnostic support
- Support for sync and break characters
- Support for automatic baud rate detection
- IrDA® encoder and decoder logic
- 16x baud clock output for IrDA® support

A simplified block diagram of the UART module is shown in **Figure 20-1**. The UART module consists of these key hardware elements:

- Baud Rate Generator
- Asynchronous Transmitter
- Asynchronous Receiver

**FIGURE 20-1: UART SIMPLIFIED BLOCK DIAGRAM**



**Note 1:** Both UART1 and UART2 can trigger a DMA data transfer.

**2:** If DMA transfers are required, the UART TX/RX FIFO buffer must be set to a size of 1 byte/word (i.e., UTXISEL<1:0> = 00 and URXISEL<1:0> = 00).

**REGISTER 20-1: UxMODE: UARTx MODE REGISTER**

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
UARTEN <sup>(1)</sup>	—	USIDL	IREN <sup>(2)</sup>	RTSMD	—	UEN<1:0>	
bit 15							

R/W-0, HC	R/W-0	R/W-0, HC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAKE	LPBACK	ABAUD	URXINV	BRGH	PDSEL<1:0>	STSEL	
bit 7							

<b>Legend:</b>	HC = Hardware cleared
R = Readable bit	W = Writable bit
-n = Value at POR	‘1’ = Bit is set                    ‘0’ = Bit is cleared                    x = Bit is unknown

bit 15	<b>UARTEN:</b> UARTx Enable bit 1 = UARTx is enabled; all UARTx pins are controlled by UARTx as defined by UEN<1:0> 0 = UARTx is disabled; all UARTx pins are controlled by port latches; UARTx power consumption minimal
bit 14	<b>Unimplemented:</b> Read as ‘0’
bit 13	<b>USIDL:</b> Stop in Idle Mode bit 1 = Discontinue module operation when device enters Idle mode 0 = Continue module operation in Idle mode
bit 12	<b>IREN:</b> IrDA® Encoder and Decoder Enable bit <sup>(2)</sup> 1 = IrDA encoder and decoder enabled 0 = IrDA encoder and decoder disabled
bit 11	<b>RTSMD:</b> Mode Selection for <u>UxRTS</u> Pin bit 1 = <u>UxRTS</u> pin in Simplex mode 0 = <u>UxRTS</u> pin in Flow Control mode
bit 10	<b>Unimplemented:</b> Read as ‘0’
bit 9-8	<b>UEN&lt;1:0&gt;:</b> UARTx Enable bits 11 = UxTX, UxRX and BCLK pins are enabled and used; <u>UxCTS</u> pin controlled by port latches 10 = UxTX, UxRX, <u>UxCTS</u> and <u>UxRTS</u> pins are enabled and used 01 = UxTX, UxRX and <u>UxRTS</u> pins are enabled and used; <u>UxCTS</u> pin controlled by port latches 00 = UxTX and UxRX pins are enabled and used; <u>UxCTS</u> and <u>UxRTS/BCLK</u> pins controlled by port latches
bit 7	<b>WAKE:</b> Wake-up on Start bit Detect During Sleep Mode Enable bit 1 = UARTx continues to sample the UxRX pin; interrupt generated on falling edge; bit cleared in hardware on following rising edge 0 = No wake-up enabled
bit 6	<b>LPBACK:</b> UARTx Loopback Mode Select bit 1 = Enable Loopback mode 0 = Loopback mode is disabled
bit 5	<b>ABAUD:</b> Auto-Baud Enable bit 1 = Enable baud rate measurement on the next character – requires reception of a Sync field (55h) before other data; cleared in hardware upon completion 0 = Baud rate measurement disabled or completed

**Note 1:** Refer to **Section 17. “UART”** (DS70188) in the “dsPIC33F/PIC24H Family Reference Manual” for information on enabling the UART module for receive or transmit operation.

**2:** This feature is only available for the 16x BRG mode (BRGH = 0).

**REGISTER 20-1: UxMODE: UARTx MODE REGISTER (CONTINUED)**

bit 4	<b>URXINV:</b> Receive Polarity Inversion bit 1 = UxRX Idle state is '0' 0 = UxRX Idle state is '1'
bit 3	<b>BRGH:</b> High Baud Rate Enable bit 1 = BRG generates 4 clocks per bit period (4x baud clock, High-Speed mode) 0 = BRG generates 16 clocks per bit period (16x baud clock, Standard mode)
bit 2-1	<b>PDSEL&lt;1:0&gt;:</b> Parity and Data Selection bits 11 = 9-bit data, no parity 10 = 8-bit data, odd parity 01 = 8-bit data, even parity 00 = 8-bit data, no parity
bit 0	<b>STSEL:</b> Stop Bit Selection bit 1 = Two Stop bits 0 = One Stop bit

- Note 1:** Refer to **Section 17. “UART”** (DS70188) in the “*dsPIC33F/PIC24H Family Reference Manual*” for information on enabling the UART module for receive or transmit operation.
- 2:** This feature is only available for the 16x BRG mode (BRGH = 0).

**REGISTER 20-2: UxSTA: UART<sub>x</sub> STATUS AND CONTROL REGISTER**

R/W-0	R/W-0	R/W-0	U-0	R/W-0, HC	R/W-0	R-0	R-1
UTXISEL1	UTXINV	UTXISEL0	—	UTXBRK	UTXEN <sup>(1)</sup>	UTXBF	TRMT
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R-1	R-0	R-0	R/C-0	R-0
URXISEL<1:0>	ADDEN	RIDLE	PERR	FERR	OERR	URXDA	
bit 7							bit 0

<b>Legend:</b>	C = Clear only bit	HC = Hardware cleared
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared                    x = Bit is unknown

- bit 15,13      **UTXISEL<1:0>**: Transmission Interrupt Mode Selection bits
- 11 = Reserved; do not use
  - 10 = Interrupt when a character is transferred to the Transmit Shift register, and as a result, the transmit buffer becomes empty
  - 01 = Interrupt when the last character is shifted out of the Transmit Shift register; all transmit operations are completed
  - 00 = Interrupt when a character is transferred to the Transmit Shift register (this implies there is at least one character open in the transmit buffer)
- bit 14      **UTXINV**: Transmit Polarity Inversion bit
- If IREN = 0:
- 1 = UxTX Idle state is '0'
  - 0 = UxTX Idle state is '1'
- If IREN = 1:
- 1 = IrDA encoded UxTX Idle state is '1'
  - 0 = IrDA encoded UxTX Idle state is '0'
- bit 12      **Unimplemented**: Read as '0'
- bit 11      **UTXBRK**: Transmit Break bit
- 1 = Send Sync Break on next transmission – Start bit, followed by twelve '0' bits, followed by Stop bit; cleared by hardware upon completion
  - 0 = Sync Break transmission disabled or completed
- bit 10      **UTXEN**: Transmit Enable bit<sup>(1)</sup>
- 1 = Transmit enabled, UxTX pin controlled by UART<sub>x</sub>
  - 0 = Transmit disabled, any pending transmission is aborted and buffer is reset. UxTX pin controlled by port
- bit 9      **UTXBF**: Transmit Buffer Full Status bit (read-only)
- 1 = Transmit buffer is full
  - 0 = Transmit buffer is not full, at least one more character can be written
- bit 8      **TRMT**: Transmit Shift Register Empty bit (read-only)
- 1 = Transmit Shift register is empty and transmit buffer is empty (the last transmission has completed)
  - 0 = Transmit Shift register is not empty, a transmission is in progress or queued
- bit 7-6      **URXISEL<1:0>**: Receive Interrupt Mode Selection bits
- 11 = Interrupt is set on UxRSR transfer making the receive buffer full (i.e., has 4 data characters)
  - 10 = Interrupt is set on UxRSR transfer making the receive buffer 3/4 full (i.e., has 3 data characters)
  - 0x = Interrupt is set when any character is received and transferred from the UxRSR to the receive buffer. Receive buffer has one or more characters

**Note 1:** Refer to **Section 17. "UART"** (DS70188) in the *"dsPIC33F/PIC24H Family Reference Manual"* for information on enabling the UART module for transmit operation.

**REGISTER 20-2: UxSTA: UARTx STATUS AND CONTROL REGISTER (CONTINUED)**

bit 5	<b>ADDEN:</b> Address Character Detect bit (bit 8 of received data = 1) 1 = Address Detect mode enabled. If 9-bit mode is not selected, this does not take effect 0 = Address Detect mode disabled
bit 4	<b>RIDLE:</b> Receiver Idle bit (read-only) 1 = Receiver is Idle 0 = Receiver is active
bit 3	<b>PERR:</b> Parity Error Status bit (read-only) 1 = Parity error has been detected for the current character (character at the top of the receive FIFO) 0 = Parity error has not been detected
bit 2	<b>FERR:</b> Framing Error Status bit (read-only) 1 = Framing error has been detected for the current character (character at the top of the receive FIFO) 0 = Framing error has not been detected
bit 1	<b>OERR:</b> Receive Buffer Overrun Error Status bit (read/clear only) 1 = Receive buffer has overflowed 0 = Receive buffer has not overflowed. Clearing a previously set OERR bit (1 → 0 transition) resets the receiver buffer and the UxRSR to the empty state
bit 0	<b>URXDA:</b> Receive Buffer Data Available bit (read-only) 1 = Receive buffer has data, at least one more character can be read 0 = Receive buffer is empty

**Note 1:** Refer to **Section 17. “UART”** (DS70188) in the “*dsPIC33F/PIC24H Family Reference Manual*” for information on enabling the UART module for transmit operation.

**NOTES:**

## 21.0 ENHANCED CAN (ECAN™) MODULE

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 21. Enhanced Controller Area Network (ECAN™)**” (DS70185) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

### 21.1 Overview

The Enhanced Controller Area Network (ECAN) module is a serial interface, useful for communicating with other CAN modules or microcontroller devices. This interface/protocol was designed to allow communications within noisy environments. The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices contain up to two ECAN modules.

The ECAN module is a communication controller implementing the CAN 2.0 A/B protocol, as defined in the BOSCH CAN specification. The module supports CAN 1.2, CAN 2.0A, CAN 2.0B Passive and CAN 2.0B Active versions of the protocol. The module implementation is a full CAN system. The CAN specification is not covered within this data sheet. The reader can refer to the BOSCH CAN specification for further details.

The module features are as follows:

- Implementation of the CAN protocol, CAN 1.2, CAN 2.0A and CAN 2.0B
- Standard and extended data frames
- 0-8 bytes data length
- Programmable bit rate up to 1 Mbit/sec
- Automatic response to remote transmission requests
- Up to eight transmit buffers with application specified prioritization and abort capability (each buffer can contain up to 8 bytes of data)
- Up to 32 receive buffers (each buffer can contain up to 8 bytes of data)
- Up to 16 full (standard/extended identifier) acceptance filters
- Three full acceptance filter masks
- DeviceNet™ addressing support
- Programmable wake-up functionality with

integrated low-pass filter

- Programmable Loopback mode supports self-test operation
- Signaling via interrupt capabilities for all CAN receiver and transmitter error states
- Programmable clock source
- Programmable link to input capture module (IC2 for CAN1) for time-stamping and network synchronization
- Low-power Sleep and Idle mode

The CAN bus module consists of a protocol engine and message buffering/control. The CAN protocol engine handles all functions for receiving and transmitting messages on the CAN bus. Messages are transmitted by first loading the appropriate data registers. Status and errors can be checked by reading the appropriate registers. Any message detected on the CAN bus is checked for errors and then matched against filters to see if it should be received and stored in one of the receive registers.

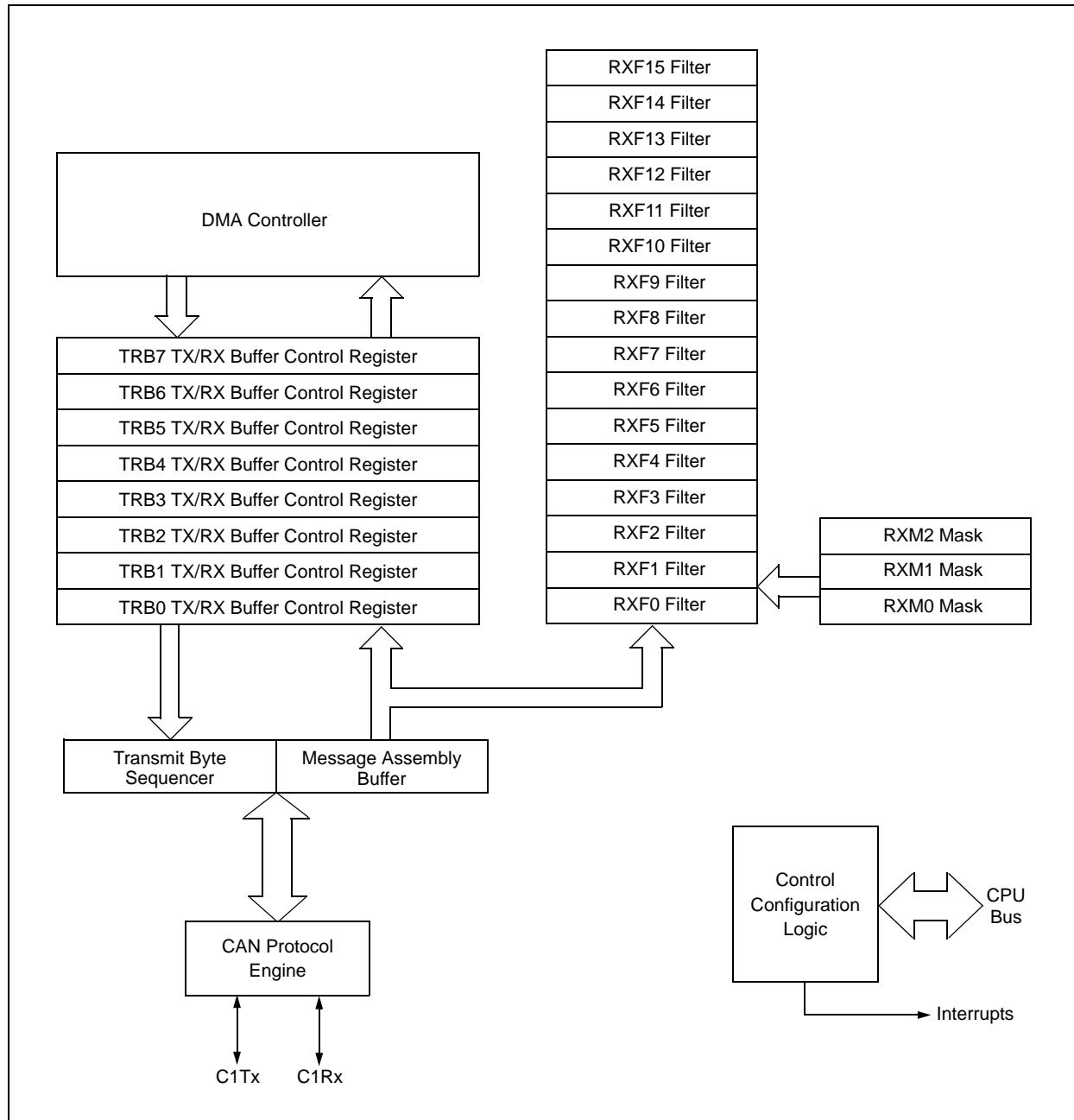
### 21.2 Frame Types

The ECAN module transmits various types of frames which include data messages, or remote transmission requests initiated by the user, as other frames that are automatically generated for control purposes. The following frame types are supported:

- Standard Data Frame:  
A standard data frame is generated by a node when the node wishes to transmit data. It includes an 11-bit Standard Identifier (SID), but not an 18-bit Extended Identifier (EID).
- Extended Data Frame:  
An extended data frame is similar to a standard data frame, but includes an extended identifier as well.
- Remote Frame:  
It is possible for a destination node to request the data from the source. For this purpose, the destination node sends a remote frame with an identifier that matches the identifier of the required data frame. The appropriate data source node sends a data frame as a response to this remote request.
- Error Frame:  
An error frame is generated by any node that detects a bus error. An error frame consists of two fields: an error flag field and an error delimiter field.
- Overload Frame:  
An overload frame can be generated by a node as a result of two conditions. First, the node detects a dominant bit during interframe space which is an illegal condition. Second, due to internal conditions, the node is not yet able to start reception of the next message. A node can generate a maximum of 2 sequential overload frames to delay the start of the next message.
- Interframe Space:

Interframe space separates a proceeding frame (of whatever type) from a following data or remote frame.

**FIGURE 21-1: ECAN™ MODULE BLOCK DIAGRAM**



## 21.3 Modes of Operation

The ECAN module can operate in one of several operation modes selected by the user. These modes include:

- Initialization mode
- Disable mode
- Normal Operation mode
- Listen Only mode
- Listen All Messages mode
- Loopback mode

Modes are requested by setting the REQOP<2:0> bits (CiCTRL1<10:8>). Entry into a mode is Acknowledged by monitoring the OPMODE<2:0> bits (CiCTRL1<7:5>). The module does not change the mode and the OPMODE bits until a change in mode is acceptable, generally during bus Idle time, which is defined as at least 11 consecutive recessive bits.

### 21.3.1 INITIALIZATION MODE

In the Initialization mode, the module does not transmit or receive. The error counters are cleared and the interrupt flags remain unchanged. The user application has access to Configuration registers that are access restricted in other modes. The module protects the user from accidentally violating the CAN protocol through programming errors. All registers which control the configuration of the module can not be modified while the module is on-line. The ECAN module is not allowed to enter the Configuration mode while a transmission is taking place. The Configuration mode serves as a lock to protect the following registers:

- All Module Control registers
- Baud Rate and Interrupt Configuration registers
- Bus Timing registers
- Identifier Acceptance Filter registers
- Identifier Acceptance Mask registers

### 21.3.2 DISABLE MODE

In Disable mode, the module does not transmit or receive. The module has the ability to set the WAKIF bit due to bus activity, however, any pending interrupts remains and the error counters retains their value.

If the REQOP<2:0> bits (CiCTRL1<10:8>) = 001, the module enters the Module Disable mode. If the module is active, the module waits for 11 recessive bits on the CAN bus, detect that condition as an Idle bus, then accept the module disable command. When the OPMODE<2:0> bits (CiCTRL1<7:5>) = 001, that indicates whether the module successfully went into Module Disable mode. The I/O pins reverts to normal I/O function when the module is in the Module Disable mode.

The module can be programmed to apply a low-pass filter function to the CiRX input line while the module or the CPU is in Sleep mode. The WAKFIL bit (CiCFG2<14>) enables or disables the filter.

**Note:** Typically, if the ECAN module is allowed to transmit in a particular mode of operation and a transmission is requested immediately after the ECAN module has been placed in that mode of operation, the module waits for 11 consecutive recessive bits on the bus before starting transmission. If the user switches to Disable mode within this 11-bit period, then this transmission is aborted and the corresponding TXABT bit is set and TXREQ bit is cleared.

### 21.3.3 NORMAL OPERATION MODE

Normal Operation mode is selected when the REQOP<2:0> = 000. In this mode, the module is activated and the I/O pins assumes the CAN bus functions. The module transmits and receive CAN bus messages via the CiTX and CiRX pins.

### 21.3.4 LISTEN ONLY MODE

If the Listen Only mode is activated, the module on the CAN bus is passive. The transmitter buffers revert to the port I/O function. The receive pins remain inputs. For the receiver, no error flags or Acknowledge signals are sent. The error counters are deactivated in this state. The Listen Only mode can be used for detecting the baud rate on the CAN bus. To use this, it is necessary that there are at least two further nodes that communicate with each other.

### 21.3.5 LISTEN ALL MESSAGES MODE

The module can be set to ignore all errors and receive any message. The Listen All Messages mode is activated by setting the REQOP<2:0> = 111. In this mode, the data which is in the message assembly buffer, until the time an error occurred, is copied in the receive buffer and can be read via the CPU interface.

### 21.3.6 LOOPBACK MODE

If the Loopback mode is activated, the module connects the internal transmit signal to the internal receive signal at the module boundary. The transmit and receive pins revert to their port I/O function.

**REGISTER 21-1: CiCTRL1: ECAN™ CONTROL REGISTER 1**

U-0	U-0	R/W-0	R/W-0	r-0	R/W-1	R/W-0	R/W-0	
—	—	CSIDL	ABAT	—	REQOP<2:0>			
bit 15		bit 8						

R-1	R-0	R-0	U-0	R/W-0	U-0	U-0	R/W-0	
		OPMODE<2:0>	—	CANCAP	—	—	WIN	
bit 7		bit 0						

**Legend:**

R = Readable bit  
-n = Value at POR

r = Bit is Reserved

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared

x = Bit is unknown

- bit 15-14      **Unimplemented:** Read as '0'
- bit 13      **CSIDL:** Stop in Idle Mode bit  
1 = Discontinue module operation when device enters Idle mode  
0 = Continue module operation in Idle mode
- bit 12      **ABAT:** Abort All Pending Transmissions bit  
1 = Signal all transmit buffers to abort transmission  
0 = Module will clear this bit when all transmissions are aborted
- bit 11      **Reserved:** Do not use
- bit 10-8      **REQOP<2:0>:** Request Operation Mode bits  
111 = Set Listen All Messages mode  
110 = Reserved  
101 = Reserved  
100 = Set Configuration mode  
011 = Set Listen Only Mode  
010 = Set Loopback mode  
001 = Set Disable mode  
000 = Set Normal Operation mode
- bit 7-5      **OPMODE<2:0>:** Operation Mode bits  
111 = Module is in Listen All Messages mode  
110 = Reserved  
101 = Reserved  
100 = Module is in Configuration mode  
011 = Module is in Listen Only mode  
010 = Module is in Loopback mode  
001 = Module is in Disable mode  
000 = Module is in Normal Operation mode
- bit 4      **Unimplemented:** Read as '0'
- bit 3      **CANCAP:** CAN Message Receive Timer Capture Event Enable bit  
1 = Enable input capture based on CAN message receive  
0 = Disable CAN capture
- bit 2-1      **Unimplemented:** Read as '0'
- bit 0      **WIN:** SFR Map Window Select bit  
1 = Use filter window  
0 = Use buffer window

**REGISTER 21-2: CiCTRL2: ECAN™ CONTROL REGISTER 2**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R-0	R-0	R-0	R-0	R-0
—	—	—		DNCNT<4:0>			
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5      **Unimplemented:** Read as '0'bit 4-0      **DNCNT<4:0>:** DeviceNet™ Filter Bit Number bits

10010-11111 = Invalid selection

10001 = Compare up to data byte 3, bit 6 with EID&lt;17&gt;

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00001 = Compare up to data byte 1, bit 7 with EID&lt;0&gt;

00000 = Do not compare data bytes

**REGISTER 21-3: CiVEC: ECAN™ INTERRUPT CODE REGISTER**

U-0	U-0	U-0	R-0	R-0	R-0	R-0	R-0		
—	—	—	FILHIT<4:0>						
bit 15							bit 8		

U-0	R-1	R-0	R-0	R-0	R-0	R-0	R-0
—	ICODE<6:0>						
bit 7							bit 0

**Legend:**

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared      x = Bit is unknown

- bit 15-13      **Unimplemented:** Read as '0'
- bit 12-8      **FILHIT<4:0>:** Filter Hit Number bits  
 10000-11111 = Reserved  
 01111 = Filter 15  
 •  
 •  
 •  
 00001 = Filter 1  
 00000 = Filter 0
- bit 7      **Unimplemented:** Read as '0'
- bit 6-0      **ICODE<6:0>:** Interrupt Flag Code bits  
 1000101-1111111 = Reserved  
 1000100 = FIFO almost full interrupt  
 1000011 = Receiver overflow interrupt  
 1000010 = Wake-up interrupt  
 1000001 = Error interrupt  
 1000000 = No interrupt  
 •  
 •  
 •  
 0010000-0111111 = Reserved  
 0001111 = RB15 buffer interrupt  
 •  
 •  
 •  
 0001001 = RB9 buffer interrupt  
 0001000 = RB8 buffer interrupt  
 0000111 = TRB7 buffer interrupt  
 0000110 = TRB6 buffer interrupt  
 0000101 = TRB5 buffer interrupt  
 0000100 = TRB4 buffer interrupt  
 0000011 = TRB3 buffer interrupt  
 0000010 = TRB2 buffer interrupt  
 0000001 = TRB1 buffer interrupt  
 0000000 = TRB0 Buffer interrupt

**REGISTER 21-4: CiFCTRL: ECAN™ FIFO CONTROL REGISTER**

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
		DMABS<2:0>	—	—	—	—	—
bit 15							

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—		FSA<4:0>			
bit 7							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **DMABS<2:0>:** DMA Buffer Size bits

111 = Reserved

110 = 32 buffers in DMA RAM

101 = 24 buffers in DMA RAM

100 = 16 buffers in DMA RAM

011 = 12 buffers in DMA RAM

010 = 8 buffers in DMA RAM

001 = 6 buffers in DMA RAM

000 = 4 buffers in DMA RAM

bit 12-5      **Unimplemented:** Read as '0'bit 4-0      **FSA<4:0>:** FIFO Area Starts with Buffer bits

11111 = Read buffer RB31

11110 = Read buffer RB30

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00001 = TX/RX buffer TRB1

00000 = TX/RX buffer TRB0

**REGISTER 21-5: CiFIFO: ECAN™ FIFO STATUS REGISTER**

U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0
—	—	FBP<5:0>					
bit 15							bit 8

U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0
—	—	FNRB<5:0>					
bit 7							bit 0

**Legend:**

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared  
x = Bit is unknown

bit 15-14      **Unimplemented:** Read as '0'

bit 13-8      **FBP<5:0>:** FIFO Buffer Pointer bits

011111 = RB31 buffer  
011110 = RB30 buffer

•

•

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000001 = TRB1 buffer  
000000 = TRB0 buffer

bit 7-6      **Unimplemented:** Read as '0'

bit 5-0      **FNRB<5:0>:** FIFO Next Read Buffer Pointer bits

011111 = RB31 buffer  
011110 = RB30 buffer

•

•

•

000001 = TRB1 buffer  
000000 = TRB0 buffer

**REGISTER 21-6: CiINTF: ECAN™ INTERRUPT FLAG REGISTER**

U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0
—	—	TXBO	TXBP	RXBP	TXWAR	RXWAR	EWARN
bit 15							bit 8

R/C-0	R/C-0	R/C-0	U-0	R/C-0	R/C-0	R/C-0	R/C-0
IVRIF	WAKIF	ERRIF	—	FIFOIF	RBOVIF	RBIF	TBIF
bit 7							bit 0

**Legend:**

R = Readable bit

-n = Value at POR

C = Writable bit, but only '0' can be written to clear the bit

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

- bit 15-14      **Unimplemented:** Read as '0'
- bit 13      **TXBO:** Transmitter in Error State Bus Off bit  
1 = Transmitter is in Bus Off state  
0 = Transmitter is not in Bus Off state
- bit 12      **TXBP:** Transmitter in Error State Bus Passive bit  
1 = Transmitter is in Bus Passive state  
0 = Transmitter is not in Bus Passive state
- bit 11      **RXBP:** Receiver in Error State Bus Passive bit  
1 = Receiver is in Bus Passive state  
0 = Receiver is not in Bus Passive state
- bit 10      **TXWAR:** Transmitter in Error State Warning bit  
1 = Transmitter is in Error Warning state  
0 = Transmitter is not in Error Warning state
- bit 9      **RXWAR:** Receiver in Error State Warning bit  
1 = Receiver is in Error Warning state  
0 = Receiver is not in Error Warning state
- bit 8      **EWARN:** Transmitter or Receiver in Error State Warning bit  
1 = Transmitter or Receiver is in Error State Warning state  
0 = Transmitter or Receiver is not in Error State Warning state
- bit 7      **IVRIF:** Invalid Message Received Interrupt Flag bit  
1 = Interrupt Request has occurred  
0 = Interrupt Request has not occurred
- bit 6      **WAKIF:** Bus Wake-up Activity Interrupt Flag bit  
1 = Interrupt Request has occurred  
0 = Interrupt Request has not occurred
- bit 5      **ERRIF:** Error Interrupt Flag bit (multiple sources in CiINTF<13:8> register)  
1 = Interrupt Request has occurred  
0 = Interrupt Request has not occurred
- bit 4      **Unimplemented:** Read as '0'
- bit 3      **FIFOIF:** FIFO Almost Full Interrupt Flag bit  
1 = Interrupt Request has occurred  
0 = Interrupt Request has not occurred
- bit 2      **RBOVIF:** RX Buffer Overflow Interrupt Flag bit  
1 = Interrupt Request has occurred  
0 = Interrupt Request has not occurred
- bit 1      **RBIF:** RX Buffer Interrupt Flag bit  
1 = Interrupt Request has occurred  
0 = Interrupt Request has not occurred
- bit 0      **TBIF:** TX Buffer Interrupt Flag bit  
1 = Interrupt Request has occurred  
0 = Interrupt Request has not occurred

## REGISTER 21-7: CiINTE: ECAN™ INTERRUPT ENABLE REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
IVRIE	WAKIE	ERRIE	—	FIFOIE	RBOVIE	RBIE	TBIE
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-8      **Unimplemented:** Read as '0'
- bit 7      **IVRIE:** Invalid Message Received Interrupt Enable bit  
           1 = Interrupt Request Enabled  
           0 = Interrupt Request not enabled
- bit 6      **WAKIE:** Bus Wake-up Activity Interrupt Flag bit  
           1 = Interrupt Request Enabled  
           0 = Interrupt Request not enabled
- bit 5      **ERRIE:** Error Interrupt Enable bit  
           1 = Interrupt Request Enabled  
           0 = Interrupt Request not enabled
- bit 4      **Unimplemented:** Read as '0'
- bit 3      **FIFOIE:** FIFO Almost Full Interrupt Enable bit  
           1 = Interrupt Request Enabled  
           0 = Interrupt Request not enabled
- bit 2      **RBOVIE:** RX Buffer Overflow Interrupt Enable bit  
           1 = Interrupt Request Enabled  
           0 = Interrupt Request not enabled
- bit 1      **RBIE:** RX Buffer Interrupt Enable bit  
           1 = Interrupt Request Enabled  
           0 = Interrupt Request not enabled
- bit 0      **TBIE:** TX Buffer Interrupt Enable bit  
           1 = Interrupt Request Enabled  
           0 = Interrupt Request not enabled

**REGISTER 21-8: CiEC: ECAN™ TRANSMIT/RECEIVE ERROR COUNT REGISTER**

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
TERRCNT<7:0>							
bit 15							bit 8

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
RERRCNT<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit -n = Value at POR	W = Writable bit '1' = Bit is set	U = Unimplemented bit, read as '0' '0' = Bit is cleared	x = Bit is unknown
---------------------------------------	--------------------------------------	--	--------------------

bit 15-8      **TERRCNT<7:0>**: Transmit Error Count bits

bit 7-0      **RERRCNT<7:0>**: Receive Error Count bits

**REGISTER 21-9: CiCFG1: ECAN™ BAUD RATE CONFIGURATION REGISTER 1**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SJW<1:0>	BRP<5:0>						
bit 7	bit 0						

**Legend:**

R = Readable bit -n = Value at POR	W = Writable bit '1' = Bit is set	U = Unimplemented bit, read as '0' '0' = Bit is cleared	x = Bit is unknown
---------------------------------------	--------------------------------------	--	--------------------

bit 15-8      **Unimplemented**: Read as '0'

bit 7-6      **SJW<1:0>**: Synchronization Jump Width bits

11 = Length is 4 x TQ

10 = Length is 3 x TQ

01 = Length is 2 x TQ

00 = Length is 1 x TQ

bit 5-0      **BRP<5:0>**: Baud Rate Prescaler bits

11 1111 = TQ = 2 x 64 x 1/FCAN

•

•

•

00 0010 = TQ = 2 x 3 x 1/FCAN

00 0001 = TQ = 2 x 2 x 1/FCAN

00 0000 = TQ = 2 x 1 x 1/FCAN

**REGISTER 21-10: CiCFG2: ECAN™ BAUD RATE CONFIGURATION REGISTER 2**

U-0	R/W-x	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x
—	WAKFIL	—	—	—	SEG2PH<2:0>		
bit 15	bit 8						

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
SEG2PHTS	SAM		SEG1PH<2:0>		PRSEG<2:0>		
bit 7	bit 0						

**Legend:**

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared  
x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'
- bit 14      **WAKFIL:** Select CAN Bus Line Filter for Wake-up bit  
1 = Use CAN bus line filter for wake-up  
0 = CAN bus line filter is not used for wake-up
- bit 13-11    **Unimplemented:** Read as '0'
- bit 10-8     **SEG2PH<2:0>:** Phase Segment 2 bits  
111 = Length is 8 x TQ  
•  
•  
•  
000 = Length is 1 x TQ
- bit 7        **SEG2PHTS:** Phase Segment 2 Time Select bit  
1 = Freely programmable  
0 = Maximum of SEG1PH bits or Information Processing Time (IPT), whichever is greater
- bit 6        **SAM:** Sample of the CAN Bus Line bit  
1 = Bus line is sampled three times at the sample point  
0 = Bus line is sampled once at the sample point
- bit 5-3     **SEG1PH<2:0>:** Phase Segment 1 bits  
111 = Length is 8 x TQ  
•  
•  
•  
000 = Length is 1 x TQ
- bit 2-0     **PRSEG<2:0>:** Propagation Time Segment bits  
111 = Length is 8 x TQ  
•  
•  
•  
000 = Length is 1 x TQ

**REGISTER 21-11: CiFEN1: ECAN™ ACCEPTANCE FILTER ENABLE REGISTER**

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
FLTEN15	FLTEN14	FLTEN13	FLTEN12	FLTEN11	FLTEN10	FLTEN9	FLTEN8
bit 15							bit 8

| R/W-1  |
|--------|--------|--------|--------|--------|--------|--------|--------|
| FLTEN7 | FLTEN6 | FLTEN5 | FLTEN4 | FLTEN3 | FLTEN2 | FLTEN1 | FLTEN0 |
| bit 7  |        |        |        |        |        |        | bit 0  |

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **FLTEFn:** Enable Filter n to Accept Messages bits  
 1 = Enable Filter n  
 0 = Disable Filter n

**REGISTER 21-12: CiBUFPNT1: ECAN™ FILTER 0-3 BUFFER POINTER REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F3BP<3:0>				F2BP<3:0>			
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F1BP<3:0>				F0BP<3:0>			
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-12      **F3BP<3:0>:** RX Buffer mask for Filter 3  
 1111 = Filter hits received in RX FIFO buffer  
 1110 = Filter hits received in RX Buffer 14  
 •  
 •  
 •  
 0001 = Filter hits received in RX Buffer 1  
 0000 = Filter hits received in RX Buffer 0  
 bit 11-8      **F2BP<3:0>:** RX Buffer mask for Filter 2 (same values as bit 15-12)  
 bit 7-4      **F1BP<3:0>:** RX Buffer mask for Filter 1 (same values as bit 15-12)  
 bit 3-0      **F0BP<3:0>:** RX Buffer mask for Filter 0 (same values as bit 15-12)

**REGISTER 21-13: CiBUFPNT2: ECAN™ FILTER 4-7 BUFFER POINTER REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F7BP<3:0>				F6BP<3:0>			
bit 15				bit 8			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F5BP<3:0>				F4BP<3:0>			
bit 7				bit 0			

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared

- bit 15-12      **F7BP<3:0>**: RX Buffer Mask for Filter 7  
                   1111 = Filter hits received in RX FIFO buffer  
                   1110 = Filter hits received in RX Buffer 14  
                   •  
                   •  
                   •  
                   0001 = Filter hits received in RX Buffer 1  
                   0000 = Filter hits received in RX Buffer 0
- bit 11-8      **F6BP<3:0>**: RX Buffer Mask for Filter 6 (same values as bit 15-12)
- bit 7-4      **F5BP<3:0>**: RX Buffer Mask for Filter 5 (same values as bit 15-12)
- bit 3-0      **F4BP<3:0>**: RX Buffer Mask for Filter 4 (same values as bit 15-12)

**REGISTER 21-14: CiBUFPNT3: ECAN™ FILTER 8-11 BUFFER POINTER REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F11BP<3:0>				F10BP<3:0>			
bit 15				bit 8			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F9BP<3:0>				F8BP<3:0>			
bit 7				bit 0			

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared

- bit 15-12      **F11BP<3:0>**: RX Buffer Mask for Filter 11  
                   1111 = Filter hits received in RX FIFO buffer  
                   1110 = Filter hits received in RX Buffer 14  
                   •  
                   •  
                   •  
                   0001 = Filter hits received in RX Buffer 1  
                   0000 = Filter hits received in RX Buffer 0
- bit 11-8      **F10BP<3:0>**: RX Buffer Mask for Filter 10 (same values as bit 15-12)
- bit 7-4      **F9BP<3:0>**: RX Buffer Mask for Filter 9 (same values as bit 15-12)
- bit 3-0      **F8BP<3:0>**: RX Buffer Mask for Filter 8 (same values as bit 15-12)

**REGISTER 21-15: CiBUFPNT4: ECAN™ FILTER 12-15 BUFFER POINTER REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F15BP<3:0>				F14BP<3:0>			
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F13BP<3:0>				F12BP<3:0>			
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-12      **F15BP<3:0>**: RX Buffer Mask for Filter 15

1111 = Filter hits received in RX FIFO buffer

1110 = Filter hits received in RX Buffer 14

•

•

•

0001 = Filter hits received in RX Buffer 1

0000 = Filter hits received in RX Buffer 0

bit 11-8      **F14BP<3:0>**: RX Buffer Mask for Filter 14 (same values as bit 15-12)bit 7-4      **F13BP<3:0>**: RX Buffer Mask for Filter 13 (same values as bit 15-12)bit 3-0      **F12BP<3:0>**: RX Buffer Mask for Filter 12 (same values as bit 15-12)

**REGISTER 21-16: CiRXFnSID: ECAN™ ACCEPTANCE FILTER STANDARD IDENTIFIER REGISTER n (n = 0-15)**

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
SID10	SID9	SID8	SID7	SID6	SID5	SID4	SID3
bit 15	bit 8						

R/W-x	R/W-x	R/W-x	U-0	R/W-x	U-0	R/W-x	R/W-x
SID2	SID1	SID0	—	EXIDE	—	EID17	EID16
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5      **SID<10:0>**: Standard Identifier bits

1 = Message address bit SIDx must be '1' to match filter

0 = Message address bit SIDx must be '0' to match filter

bit 4      **Unimplemented**: Read as '0'

bit 3      **EXIDE**: Extended Identifier Enable bit

If MIDE = 1:

1 = Match only messages with extended identifier addresses

0 = Match only messages with standard identifier addresses

If MIDE = 0:

Ignore EXIDE bit.

bit 2      **Unimplemented**: Read as '0'

bit 1-0      **EID<17:16>**: Extended Identifier bits

1 = Message address bit EIDx must be '1' to match filter

0 = Message address bit EIDx must be '0' to match filter

**REGISTER 21-17: CiRXFnEID: ECAN™ ACCEPTANCE FILTER EXTENDED IDENTIFIER REGISTER n (n = 0-15)**

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
EID15	EID14	EID13	EID12	EID11	EID10	EID9	EID8
bit 15							bit 8

| R/W-x |
|-------|-------|-------|-------|-------|-------|-------|-------|
| EID7  | EID6  | EID5  | EID4  | EID3  | EID2  | EID1  | EID0  |
| bit 7 |       |       |       |       |       |       | bit 0 |

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0

**EID<15:0>**: Extended Identifier bits

1 = Message address bit EIDx must be '1' to match filter

0 = Message address bit EIDx must be '0' to match filter

**REGISTER 21-18: CiFMSKSEL1: ECAN™ FILTER 7-0 MASK SELECTION REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F7MSK<1:0>		F6MSK<1:0>		F5MSK<1:0>		F4MSK<1:0>	
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F3MSK<1:0>		F2MSK<1:0>		F1MSK<1:0>		F0MSK<1:0>	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14

**F7MSK<1:0>**: Mask Source for Filter 7 bit

11 = No mask

10 = Acceptance Mask 2 registers contain mask

01 = Acceptance Mask 1 registers contain mask

00 = Acceptance Mask 0 registers contain mask

bit 13-12

**F6MSK<1:0>**: Mask Source for Filter 6 bit (same values as bit 15-14)

bit 11-10

**F5MSK<1:0>**: Mask Source for Filter 5 bit (same values as bit 15-14)

bit 9-8

**F4MSK<1:0>**: Mask Source for Filter 4 bit (same values as bit 15-14)

bit 7-6

**F3MSK<1:0>**: Mask Source for Filter 3 bit (same values as bit 15-14)

bit 5-4

**F2MSK<1:0>**: Mask Source for Filter 2 bit (same values as bit 15-14)

bit 3-2

**F1MSK<1:0>**: Mask Source for Filter 1 bit (same values as bit 15-14)

bit 1-0

**F0MSK<1:0>**: Mask Source for Filter 0 bit (same values as bit 15-14)

## REGISTER 21-19: CiFMSKSEL2: ECAN™ FILTER 15-8 MASK SELECTION REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F15MSK<1:0>		F14MSK<1:0>		F13MSK<1:0>		F12MSK<1:0>	
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F11MSK<1:0>		F10MSK<1:0>		F9MSK<1:0>		F8MSK<1:0>	
bit 7				bit 0			

**Legend:**

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared  
x = Bit is unknown

- bit 15-14      **F15MSK<1:0>**: Mask Source for Filter 15 bit  
    11 = No mask  
    10 = Acceptance Mask 2 registers contain mask  
    01 = Acceptance Mask 1 registers contain mask  
    00 = Acceptance Mask 0 registers contain mask
- bit 13-12      **F14MSK<1:0>**: Mask Source for Filter 14 bit (same values as bit 15-14)
- bit 11-10      **F13MSK<1:0>**: Mask Source for Filter 13 bit (same values as bit 15-14)
- bit 9-8      **F12MSK<1:0>**: Mask Source for Filter 12 bit (same values as bit 15-14)
- bit 7-6      **F11MSK<1:0>**: Mask Source for Filter 11 bit (same values as bit 15-14)
- bit 5-4      **F10MSK<1:0>**: Mask Source for Filter 10 bit (same values as bit 15-14)
- bit 3-2      **F9MSK<1:0>**: Mask Source for Filter 9 bit (same values as bit 15-14)
- bit 1-0      **F8MSK<1:0>**: Mask Source for Filter 8 bit (same values as bit 15-14)

**REGISTER 21-20: CiRXMnSID: ECAN™ ACCEPTANCE FILTER MASK STANDARD IDENTIFIER REGISTER n (n = 0-2)**

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
SID10	SID9	SID8	SID7	SID6	SID5	SID4	SID3
bit 15	bit 8						

R/W-x	R/W-x	R/W-x	U-0	R/W-x	U-0	R/W-x	R/W-x
SID2	SID1	SID0	—	MIDE	—	EID17	EID16
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-5	<b>SID&lt;10:0&gt;:</b> Standard Identifier bits 1 = Include bit SIDx in filter comparison 0 = Bit SIDx is don't care in filter comparison
bit 4	<b>Unimplemented:</b> Read as '0'
bit 3	<b>MIDE:</b> Identifier Receive Mode bit 1 = Match only message types (standard or extended address) that correspond to EXIDE bit in filter 0 = Match either standard or extended address message if filters match (i.e., if (Filter SID) = (Message SID) or if (Filter SID/EID) = (Message SID/EID))
bit 2	<b>Unimplemented:</b> Read as '0'
bit 1-0	<b>EID&lt;17:16&gt;:</b> Extended Identifier bits 1 = Include bit EIDx in filter comparison 0 = Bit EIDx is don't care in filter comparison

**REGISTER 21-21: CiRXMnEID: ECAN™ ACCEPTANCE FILTER MASK EXTENDED IDENTIFIER REGISTER n (n = 0-2)**

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
EID15	EID14	EID13	EID12	EID11	EID10	EID9	EID8
bit 15	bit 8						

| R/W-x |
|-------|-------|-------|-------|-------|-------|-------|-------|
| EID7  | EID6  | EID5  | EID4  | EID3  | EID2  | EID1  | EID0  |
| bit 7 | bit 0 |       |       |       |       |       |       |

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0	<b>EID&lt;15:0&gt;:</b> Extended Identifier bits 1 = Include bit EIDx in filter comparison 0 = Bit EIDx is don't care in filter comparison
----------	--

**REGISTER 21-22: CiRXFUL1: ECAN™ RECEIVE BUFFER FULL REGISTER 1**

R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0
RXFUL15	RXFUL14	RXFUL13	RXFUL12	RXFUL11	RXFUL10	RXFUL9	RXFUL8
bit 15	bit 8						

| R/C-0  |
|--------|--------|--------|--------|--------|--------|--------|--------|
| RXFUL7 | RXFUL6 | RXFUL5 | RXFUL4 | RXFUL3 | RXFUL2 | RXFUL1 | RXFUL0 |
| bit 7  | bit 0  |        |        |        |        |        |        |

**Legend:**

R = Readable bit  
-n = Value at POR

C = Writable bit, but only '0' can be written to clear the bit

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **RXFUL<15:0>:** Receive Buffer n Full bits  
1 = Buffer is full (set by module)  
0 = Buffer is empty

**REGISTER 21-23: CiRXFUL2: ECAN™ RECEIVE BUFFER FULL REGISTER 2**

| R/C-0   |
|---------|---------|---------|---------|---------|---------|---------|---------|
| RXFUL31 | RXFUL30 | RXFUL29 | RXFUL28 | RXFUL27 | RXFUL26 | RXFUL25 | RXFUL24 |
| bit 15  | bit 8   |         |         |         |         |         |         |

| R/C-0   |
|---------|---------|---------|---------|---------|---------|---------|---------|
| RXFUL23 | RXFUL22 | RXFUL21 | RXFUL20 | RXFUL19 | RXFUL18 | RXFUL17 | RXFUL16 |
| bit 7   | bit 0   |         |         |         |         |         |         |

**Legend:**

R = Readable bit  
-n = Value at POR

C = Writable bit, but only '0' can be written to clear the bit

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **RXFUL<31:16>:** Receive Buffer n Full bits  
1 = Buffer is full (set by module)  
0 = Buffer is empty

**REGISTER 21-24: CiRXOVF1: ECAN™ RECEIVE BUFFER OVERFLOW REGISTER 1**

R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0
RXOVF15	RXOVF14	RXOVF13	RXOVF12	RXOVF11	RXOVF10	RXOVF9	RXOVF8
bit 15							bit 8

| R/C-0  |
|--------|--------|--------|--------|--------|--------|--------|--------|
| RXOVF7 | RXOVF6 | RXOVF5 | RXOVF4 | RXOVF3 | RXOVF2 | RXOVF1 | RXOVF0 |
| bit 7  |        |        |        |        |        |        | bit 0  |

**Legend:**

R = Readable bit

-n = Value at POR

C = Writable bit, but only '0' can be written to clear the bit

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

bit 15-0

**RXOVF<15:0>: Receive Buffer n Overflow bits**

1 = Module attempted to write to a full buffer (set by module)

0 = No overflow condition

**REGISTER 21-25: CiRXOVF2: ECAN™ RECEIVE BUFFER OVERFLOW REGISTER 2**

| R/C-0   |
|---------|---------|---------|---------|---------|---------|---------|---------|
| RXOVF31 | RXOVF30 | RXOVF29 | RXOVF28 | RXOVF27 | RXOVF26 | RXOVF25 | RXOVF24 |
| bit 15  |         |         |         |         |         |         | bit 8   |

| R/C-0   |
|---------|---------|---------|---------|---------|---------|---------|---------|
| RXOVF23 | RXOVF22 | RXOVF21 | RXOVF20 | RXOVF19 | RXOVF18 | RXOVF17 | RXOVF16 |
| bit 7   |         |         |         |         |         |         | bit 0   |

**Legend:**

R = Readable bit

-n = Value at POR

C = Writable bit, but only '0' can be written to clear the bit

W = Writable bit

'1' = Bit is set

U = Unimplemented bit, read as '0'

'0' = Bit is cleared

x = Bit is unknown

bit 15-0

**RXOVF<31:16>: Receive Buffer n Overflow bits**

1 = Module attempted to write to a full buffer (set by module)

0 = No overflow condition

**REGISTER 21-26: CiTRmnCON: ECAN™ TX/RX BUFFER m CONTROL REGISTER  
(m = 0,2,4,6; n = 1,3,5,7)**

R/W-0	R-0	R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0
TXENn	TXABTn	TXLARBn	TXERRn	TXREQn	RTRENn	TXnPRI<1:0>	
bit 15							

R/W-0	R-0	R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0
TXENm	TXABTm <sup>(1)</sup>	TXLARBm <sup>(1)</sup>	TXERRm <sup>(1)</sup>	TXREQm	RTRENm	TXmPRI<1:0>	
bit 7							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-8      See Definition for Bits 7-0, Controls Buffer n
- bit 7      **TXENm:** TX/RX Buffer Selection bit  
1 = Buffer TRBn is a transmit buffer  
0 = Buffer TRBn is a receive buffer
- bit 6      **TXABTm:** Message Aborted bit<sup>(1)</sup>  
1 = Message was aborted  
0 = Message completed transmission successfully
- bit 5      **TXLARBm:** Message Lost Arbitration bit<sup>(1)</sup>  
1 = Message lost arbitration while being sent  
0 = Message did not lose arbitration while being sent
- bit 4      **TXERRm:** Error Detected During Transmission bit<sup>(1)</sup>  
1 = A bus error occurred while the message was being sent  
0 = A bus error did not occur while the message was being sent
- bit 3      **TXREQm:** Message Send Request bit  
1 = Requests that a message be sent. The bit automatically clears when the message is successfully sent  
0 = Clearing the bit to '0' while set requests a message abort
- bit 2      **RTRENm:** Auto-Remote Transmit Enable bit  
1 = When a remote transmit is received, TXREQ will be set  
0 = When a remote transmit is received, TXREQ will be unaffected
- bit 1-0      **TXmPRI<1:0>:** Message Transmission Priority bits  
11 = Highest message priority  
10 = High intermediate message priority  
01 = Low intermediate message priority  
00 = Lowest message priority

**Note 1:** This bit is cleared when the TXREQ bit is set.

**Note:** The buffers, SID, EID, DLC, Data Field and Receive Status registers are located in DMA RAM.

## 21.4 ECAN Message Buffers

ECAN Message Buffers are part of DMA RAM memory. They are not ECAN special function registers. The user application must directly write into the DMA RAM area that is configured for ECAN Message Buffers. The location and size of the buffer area is defined by the user application.

**BUFFER 21-1: ECAN™ MESSAGE BUFFER WORD 0**

U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	—	SID10	SID9	SID8	SID7	SID6
bit 15							bit 8

| R/W-x |
|-------|-------|-------|-------|-------|-------|-------|-------|
| SID5  | SID4  | SID3  | SID2  | SID1  | SID0  | SRR   | IDE   |
| bit 7 |       |       |       |       |       |       | bit 0 |

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'

bit 12-2      **SID<10:0>:** Standard Identifier bits

bit 1      **SRR:** Substitute Remote Request bit

1 = Message will request remote transmission

0 = Normal message

bit 0      **IDE:** Extended Identifier bit

1 = Message will transmit extended identifier

0 = Message will transmit standard identifier

**BUFFER 21-2: ECAN™ MESSAGE BUFFER WORD 1**

U-0	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x
—	—	—	—	EID17	EID16	EID15	EID14
bit 15							bit 8

| R/W-x |
|-------|-------|-------|-------|-------|-------|-------|-------|
| EID13 | EID12 | EID11 | EID10 | EID9  | EID8  | EID7  | EID6  |
| bit 7 |       |       |       |       |       |       | bit 0 |

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-12      **Unimplemented:** Read as '0'

bit 11-0      **EID<17:6>:** Extended Identifier bits

**BUFFER 21-3: ECAN™ MESSAGE BUFFER WORD 2**

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
EID5	EID4	EID3	EID2	EID1	EID0	RTR	RB1
bit 15							bit 8

U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	—	RB0	DLC3	DLC2	DLC1	DLC0
bit 7							bit 0

**Legend:**

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared

x = Bit is unknown

- bit 15-10      **EID<5:0>**: Extended Identifier bits  
bit 9            **RTR**: Remote Transmission Request bit  
                1 = Message will request remote transmission  
                0 = Normal message  
bit 8            **RB1**: Reserved Bit 1  
                User must set this bit to '0' per CAN protocol.  
bit 7-5           **Unimplemented**: Read as '0'  
bit 4            **RB0**: Reserved Bit 0  
                User must set this bit to '0' per CAN protocol.  
bit 3-0           **DLC<3:0>**: Data Length Code bits

**BUFFER 21-4: ECAN™ MESSAGE BUFFER WORD 3**

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 1							
bit 15							bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 0							
bit 7							bit 0

**Legend:**

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared

x = Bit is unknown

- bit 15-8      **Byte 1<15:8>**: ECAN™ Message byte 0  
bit 7-0           **Byte 0<7:0>**: ECAN Message byte 1

**BUFFER 21-5: ECAN™ MESSAGE BUFFER WORD 4**

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 3							
bit 15							bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 2							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8      **Byte 3<15:8>:** ECAN™ Message byte 3

bit 7-0      **Byte 2<7:0>:** ECAN Message byte 2

**BUFFER 21-6: ECAN™ MESSAGE BUFFER WORD 5**

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 5							
bit 15							bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 4							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8      **Byte 5<15:8>:** ECAN™ Message byte 5

bit 7-0      **Byte 4<7:0>:** ECAN Message byte 4

**BUFFER 21-7: ECAN™ MESSAGE BUFFER WORD 6**

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 7							
bit 15							bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 6							
bit 7							bit 0

**Legend:**

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared

x = Bit is unknown

bit 15-8      **Byte 7<15:8>:** ECAN™ Message byte 7

bit 7-0      **Byte 6<7:0>:** ECAN Message byte 6

**BUFFER 21-8: ECAN™ MESSAGE BUFFER WORD 7**

U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	—	FILHIT<4:0> <sup>(1)</sup>				
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0

**Legend:**

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'

bit 12-8      **FILHIT<4:0>:** Filter Hit Code bits<sup>(1)</sup>

Encodes number of filter that resulted in writing this buffer.

bit 7-0      **Unimplemented:** Read as '0'

**Note 1:** Only written by module for receive buffers, unused for transmit buffers.

## 22.0 10-BIT/12-BIT ANALOG-TO-DIGITAL CONVERTER (ADC1)

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 16. Analog-to-Digital Converter (ADC)**” (DS70183) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices have up to nine ADC input channels.

The AD12B bit (AD1CON1<10>) allows each of the ADC modules to be configured by the user as either a 10-bit, 4-sample and hold (S&H) ADC (default configuration) or a 12-bit, 1-S&H ADC.

**Note:** The ADC module needs to be disabled before modifying the AD12B bit.

### 22.1 Key Features

The 10-bit ADC configuration has the following key features:

- Successive Approximation (SAR) conversion
- Conversion speeds of up to 1.1 Msps
- Up to nine analog input pins
- External voltage reference input pins
- Simultaneous sampling of up to four analog input pins
- Automatic Channel Scan mode
- Selectable conversion trigger source
- Selectable Buffer Fill modes
- Four result alignment options (signed/unsigned, fractional/integer)
- Operation during CPU Sleep and Idle modes

The 12-bit ADC configuration supports all the above features, except:

- In the 12-bit configuration, conversion speeds of up to 500 ksps are supported
- There is only one sample/hold amplifier in the 12-bit configuration, so simultaneous sampling of multiple channels is not supported.

Depending on the particular device pinout, the ADC can have up to nine analog input pins, designated AN0 through AN8. In addition, there are two analog input pins for external voltage reference connections. These voltage reference inputs can be shared with other analog input pins. The actual number of analog input pins and external voltage reference input configuration depends on the specific device.

Block diagrams of the ADC module are shown in [Figure 22-1](#) and [Figure 22-2](#).

### 22.2 ADC Initialization

The following configuration steps should be performed.

1. Configure the ADC module:
  - a) Select port pins as analog inputs (AD1PCFGH<15:0> or AD1PCFGL<15:0>)
  - b) Select voltage reference source to match expected range on analog inputs (AD1CON2<15:13>)
  - c) Select the analog conversion clock to match desired data rate with processor clock (AD1CON3<7:0>)
  - d) Determine how many S/H channels is used (AD1CON2<9:8> and AD1PCFGH<15:0> or AD1PCFGL<15:0>)
  - e) Select the appropriate sample/conversion sequence (AD1CON1<7:5> and AD1CON3<12:8>)
  - f) Select how conversion results are presented in the buffer (AD1CON1<9:8>)
  - g) Turn on ADC module (AD1CON1<15>)
2. Configure ADC interrupt (if required):
  - a) Clear the AD1IF bit
  - b) Select ADC interrupt priority

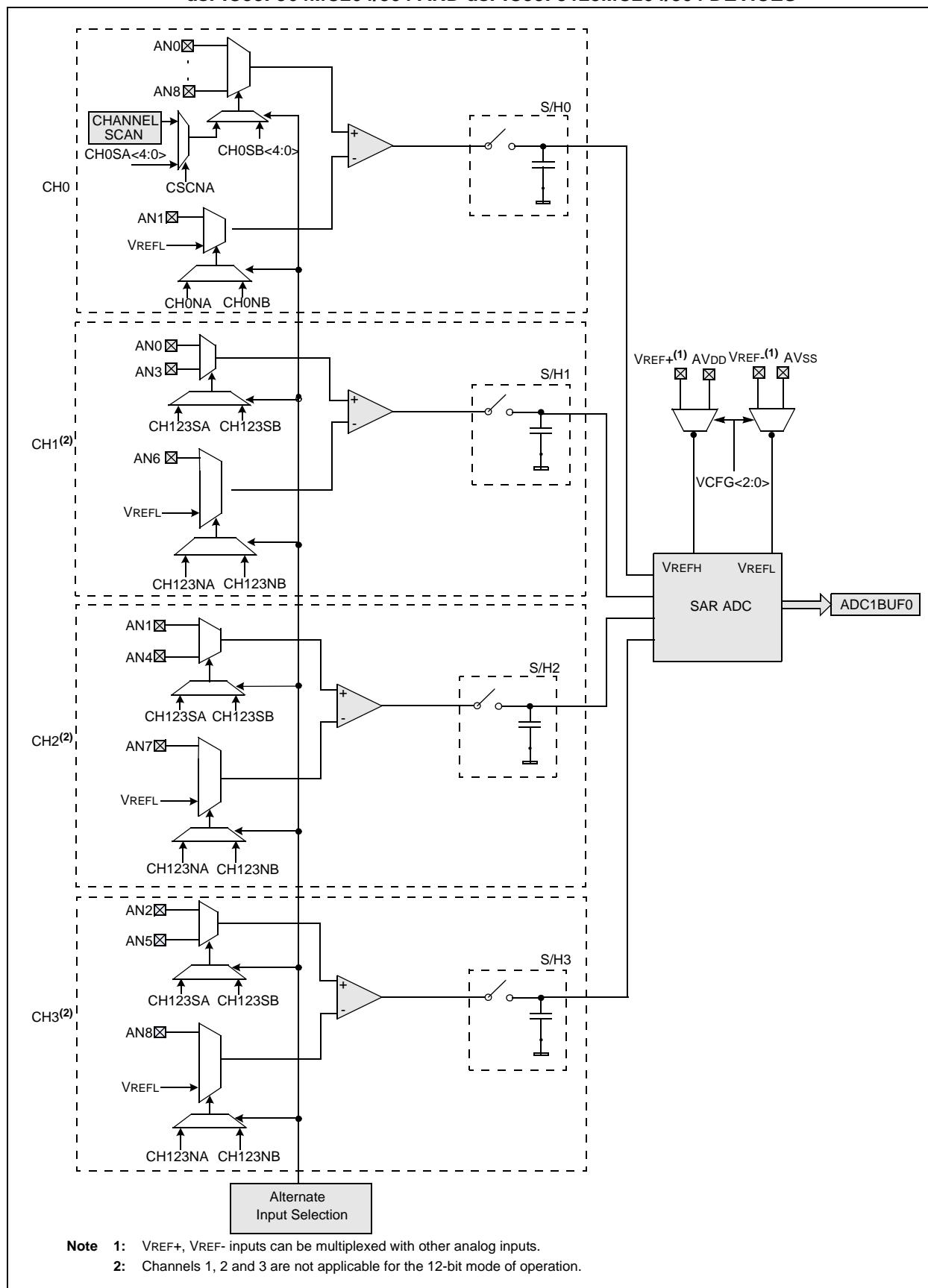
### 22.3 ADC and DMA

If more than one conversion result needs to be buffered before triggering an interrupt, DMA data transfers can be used. ADC1 can trigger a DMA data transfer. If ADC1 is selected as the DMA IRQ source, a DMA transfer occurs when the AD1IF bit gets set as a result of an ADC1 sample conversion sequence.

The SMPI<3:0> bits (AD1CON2<5:2>) are used to select how often the DMA RAM buffer pointer is incremented.

The ADDMABM bit (AD1CON1<12>) determines how the conversion results are filled in the DMA RAM buffer area being used for ADC. If this bit is set, DMA buffers are written in the order of conversion. The module provides an address to the DMA channel that is the same as the address used for the non-DMA stand-alone buffer. If the ADDMABM bit is cleared, then DMA buffers are written in Scatter/Gather mode. The module provides a scatter/gather address to the DMA channel, based on the index of the analog input and the size of the DMA buffer.

**FIGURE 22-1: ADC MODULE BLOCK DIAGRAM FOR dsPIC33FJ32MC304,  
dsPIC33FJ64MC204/804 AND dsPIC33FJ128MC204/804 DEVICES**



**FIGURE 22-2: ADC1 MODULE BLOCK DIAGRAM FOR dsPIC33FJ32MC302,  
dsPIC33FJ64MC202/802 AND dsPIC33FJ128MC202/802 DEVICES**

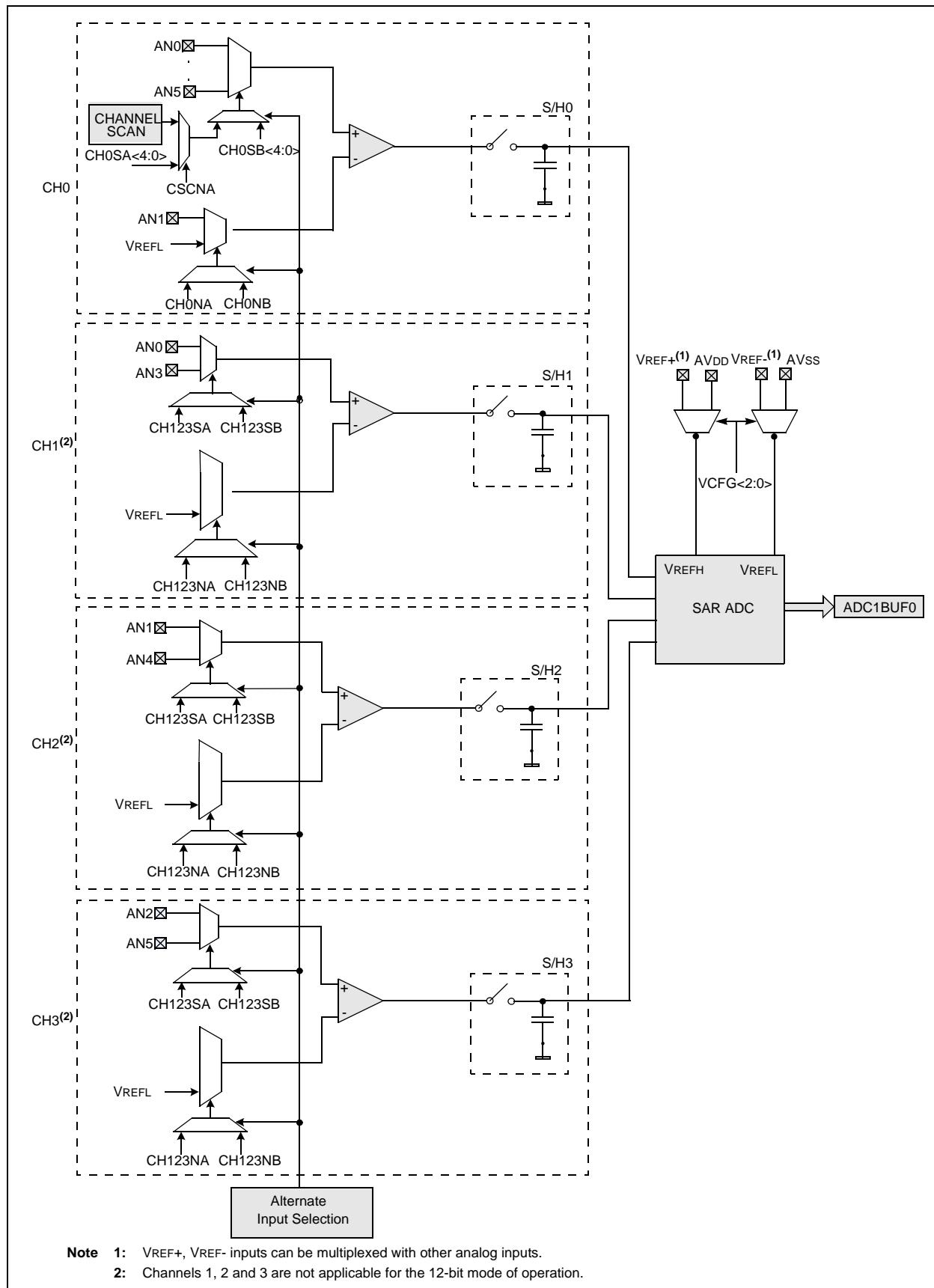
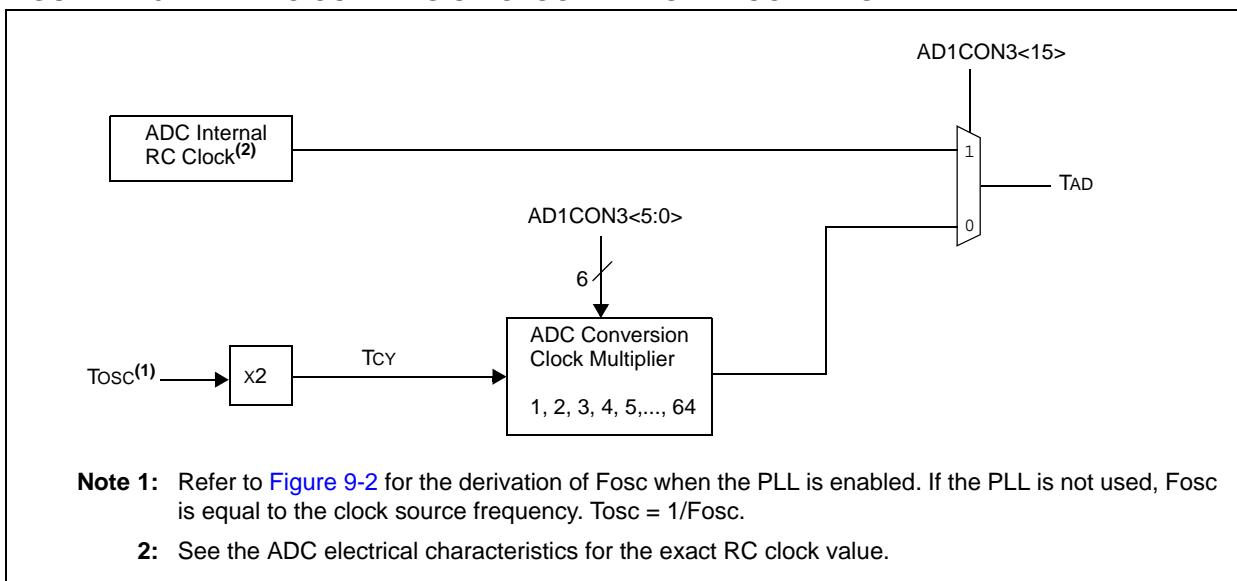


FIGURE 22-3: ADC CONVERSION CLOCK PERIOD BLOCK DIAGRAM



**REGISTER 22-1: AD1CON1: ADC1 CONTROL REGISTER 1**

R/W-0	U-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
ADON	—	ADSIDL	ADDMABM	—	AD12B	FORM<1:0>	
bit 15							

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/C-0
						HC, HS	HC, HS
SSRC<2:0>	—	SIMSAM	ASAM	SAMP	DONE		
bit 7							

<b>Legend:</b>	HC = Cleared by hardware	HS = Set by hardware
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

bit 15	<b>ADON:</b> ADC Operating Mode bit 1 = ADC module is operating 0 = ADC is off
bit 14	<b>Unimplemented:</b> Read as '0'
bit 13	<b>ADSIDL:</b> Stop in Idle Mode bit 1 = Discontinue module operation when device enters Idle mode 0 = Continue module operation in Idle mode
bit 12	<b>ADDMABM:</b> DMA Buffer Build Mode bit 1 = DMA buffers are written in the order of conversion. The module provides an address to the DMA channel that is the same as the address used for the non-DMA stand-alone buffer 0 = DMA buffers are written in Scatter/Gather mode. The module provides a scatter/gather address to the DMA channel, based on the index of the analog input and the size of the DMA buffer
bit 11	<b>Unimplemented:</b> Read as '0'
bit 10	<b>AD12B:</b> 10-bit or 12-bit Operation Mode bit 1 = 12-bit, 1-channel ADC operation 0 = 10-bit, 4-channel ADC operation
bit 9-8	<b>FORM&lt;1:0&gt;:</b> Data Output Format bits <u>For 10-bit operation:</u> 11 = Signed fractional (DOUT = sddd dddd dd00 0000, where s = .NOT.d<9>) 10 = Fractional (DOUT = dddd dddd dd00 0000) 01 = Signed integer (DOUT = ssss sssd dddd dddd, where s = .NOT.d<9>) 00 = Integer (DOUT = 0000 00dd dddd dddd) <u>For 12-bit operation:</u> 11 = Signed fractional (DOUT = sddd dddd dddd 0000, where s = .NOT.d<11>) 10 = Fractional (DOUT = dddd dddd dddd 0000) 01 = Signed Integer (DOUT = ssss ssss dddd dddd, where s = .NOT.d<11>) 00 = Integer (DOUT = 0000 dddd dddd dddd)
bit 7-5	<b>SSRC&lt;2:0&gt;:</b> Sample Clock Source Select bits 111 = Internal counter ends sampling and starts conversion (auto-convert) 110 = Reserved 101 = Motor Control PWM2 interval ends sampling and starts conversion 100 = GP timer (Timer5 for ADC1) compare ends sampling and starts conversion 011 = Motor Control PWM1 interval ends sampling and starts conversion 010 = GP timer (Timer3 for ADC1) compare ends sampling and starts conversion 001 = Active transition on INT0 pin ends sampling and starts conversion 000 = Clearing sample bit ends sampling and starts conversion
bit 4	<b>Unimplemented:</b> Read as '0'

## REGISTER 22-1: AD1CON1: ADC1 CONTROL REGISTER 1 (CONTINUED)

bit 3	<b>SIMSAM:</b> Simultaneous Sample Select bit (only applicable when CHPS<1:0> = 01 or 1x) <b>When AD12B = 1, SIMSAM is: U-0, Unimplemented, Read as '0'</b> 1 = Samples CH0, CH1, CH2, CH3 simultaneously (when CHPS<1:0> = 1x); or Samples CH0 and CH1 simultaneously (when CHPS<1:0> = 01) 0 = Samples multiple channels individually in sequence
bit 2	<b>ASAM:</b> ADC Sample Auto-Start bit 1 = Sampling begins immediately after last conversion. SAMP bit is auto-set 0 = Sampling begins when SAMP bit is set
bit 1	<b>SAMP:</b> ADC Sample Enable bit 1 = ADC sample/hold amplifiers are sampling 0 = ADC sample/hold amplifiers are holding If ASAM = 0, software can write '1' to begin sampling. Automatically set by hardware if ASAM = 1. If SSRC = 000, software can write '0' to end sampling and start conversion. If SSRC ≠ 000, automatically cleared by hardware to end sampling and start conversion.
bit 0	<b>DONE:</b> ADC Conversion Status bit 1 = ADC conversion cycle is completed 0 = ADC conversion not started or in progress Automatically set by hardware when ADC conversion is complete. Software can write '0' to clear DONE status (software not allowed to write '1'). Clearing this bit does NOT affect any operation in progress. Automatically cleared by hardware at start of a new conversion.

**REGISTER 22-2: AD1CON2: ADC1 CONTROL REGISTER 2**

R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0
		VCFG<2:0>	—	—	CSCNA	CHPS<1:0>	
bit 15							bit 8

R-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
BUFS	—		SMPI<3:0>		BUFM		ALTS
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **VCFG<2:0>:** Converter Voltage Reference Configuration bits

	<b>ADREF+</b>	<b>ADREF-</b>
000	AvDD	Avss
001	External VREF+	Avss
010	AvDD	External VREF-
011	External VREF+	External VREF-
1xx	AvDD	Avss

bit 12-11      **Unimplemented:** Read as '0'bit 10      **CSCNA:** Scan Input Selections for CH0+ during Sample A bit

1 = Scan inputs

0 = Do not scan inputs

bit 9-8      **CHPS<1:0>:** Selects Channels Utilized bits**When AD12B = 1, CHPS<1:0> is: U-0, Unimplemented, Read as '0'**

1x = Converts CH0, CH1, CH2 and CH3

01 = Converts CH0 and CH1

00 = Converts CH0

bit 7      **BUFS:** Buffer Fill Status bit (only valid when BUFM = 1)

1 = ADC is currently filling buffer 0x8-0xF, user should access data in 0x0-0x7

0 = ADC is currently filling buffer 0x0-0x7, user should access data in 0x8-0xF

bit 6      **Unimplemented:** Read as '0'bit 5-2      **SMPI<3:0>:** Selects Increment Rate for DMA Addresses bits or number of sample/conversion operations per interrupt

1111 = Increments the DMA address or generates interrupt after completion of every 16th sample/conversion operation

1110 = Increments the DMA address or generates interrupt after completion of every 15th sample/conversion operation

•

•

•

0001 = Increments the DMA address after completion of every 2nd sample/conversion operation

0000 = Increments the DMA address after completion of every sample/conversion operation

bit 1      **BUFM:** Buffer Fill Mode Select bit

1 = Starts buffer filling at address 0x0 on first interrupt and 0x8 on next interrupt

0 = Always starts filling buffer at address 0x0

bit 0      **ALTS:** Alternate Input Sample Mode Select bit

1 = Uses channel input selects for Sample A on first sample and Sample B on next sample

0 = Always uses channel input selects for Sample A

**REGISTER 22-3: AD1CON3: ADC1 CONTROL REGISTER 3**

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
ADRC	—	—		SAMC<4:0> <sup>(1)</sup>						
bit 15								bit 8		

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
				ADCS<7:0> <sup>(2)</sup>				
bit 7								bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **ADRC:** ADC Conversion Clock Source bit

1 = ADC internal RC clock

0 = Clock derived from system clock

bit 14-13    **Unimplemented:** Read as '0'

bit 12-8     **SAMC<4:0>:** Auto Sample Time bits<sup>(1)</sup>

11111 = 31 TAD

•

•

•

00001 = 1 TAD

00000 = 0 TAD

bit 7-0       **ADCS<7:0>:** ADC Conversion Clock Select bits<sup>(2)</sup>

11111111 = Reserved

•

•

•

•

01000000 = Reserved

00111111 = TCY · (ADCS<7:0> + 1) = 64 · TCY = TAD

•

•

•

00000010 = TCY · (ADCS<7:0> + 1) = 3 · TCY = TAD

00000001 = TCY · (ADCS<7:0> + 1) = 2 · TCY = TAD

00000000 = TCY · (ADCS<7:0> + 1) = 1 · TCY = TAD

**Note 1:** These bits are only used if AD1CON1<7:5> (SSRC<2:0>) = 111.

**2:** This bit is not used if AD1CON3<15> (ADRC) = 1.

**REGISTER 22-4: AD1CON4: ADC1 CONTROL REGISTER 4**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	DMABL<2:0>		
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-3      **Unimplemented:** Read as '0'

bit 2-0      **DMABL<2:0>:** Selects Number of DMA Buffer Locations per Analog Input bits

111 = Allocates 128 words of buffer to each analog input

110 = Allocates 64 words of buffer to each analog input

101 = Allocates 32 words of buffer to each analog input

100 = Allocates 16 words of buffer to each analog input

011 = Allocates 8 words of buffer to each analog input

010 = Allocates 4 words of buffer to each analog input

001 = Allocates 2 words of buffer to each analog input

000 = Allocates 1 word of buffer to each analog input

## REGISTER 22-5: AD1CHS123: ADC1 INPUT CHANNEL 1, 2, 3 SELECT REGISTER

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	CH123NB<1:0>	CH123SB	
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	CH123NA<1:0>	CH123SA	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11      **Unimplemented:** Read as '0'bit 10-9      **CH123NB<1:0>:** Channel 1, 2, 3 Negative Input Select for Sample B bits**dsPIC33FJ32MC302, dsPIC33FJ64MC202/802 and dsPIC33FJ128MC202/802 devices only:**If AD12B = 1:

11 = Reserved

10 = Reserved

01 = Reserved

00 = Reserved

If AD12B = 0:

11 = Reserved

10 = Reserved

01 = CH1, CH2, CH3 negative input is VREF-

00 = CH1, CH2, CH3 negative input is VREF-

**dsPIC33FJ32MC304, dsPIC33FJ64MC204/804 and dsPIC33FJ128MC204/804 devices only:**If AD12B = 1:

11 = Reserved

10 = Reserved

01 = Reserved

00 = Reserved

If AD12B = 0:

11 = Reserved

10 = CH1 negative input is AN6, CH2 negative input is AN7, CH3 negative input is AN8

01 = CH1, CH2, CH3 negative input is VREF-

00 = CH1, CH2, CH3 negative input is VREF-

bit 8      **CH123SB:** Channel 1, 2, 3 Positive Input Select for Sample B bitIf AD12B = 1:

1 = Reserved

0 = Reserved

If AD12B = 0:

1 = CH1 positive input is AN3, CH2 positive input is AN4, CH3 positive input is AN5

0 = CH1 positive input is AN0, CH2 positive input is AN1, CH3 positive input is AN2

bit 7-3      **Unimplemented:** Read as '0'

**REGISTER 22-5: AD1CHS123: ADC1 INPUT CHANNEL 1, 2, 3 SELECT REGISTER (CONTINUED)**

bit 2-1

**CH123NA<1:0>**: Channel 1, 2, 3 Negative Input Select for Sample A bits

**dsPIC33FJ32MC302, dsPIC33FJ64MC202/802 and dsPIC33FJ128MC202/802 devices only:**

If AD12B = 1:

11 = Reserved  
10 = Reserved  
01 = Reserved  
00 = Reserved

If AD12B = 0:

11 = Reserved  
10 = Reserved  
01 = CH1, CH2, CH3 negative input is VREF-  
00 = CH1, CH2, CH3 negative input is VREF-

**dsPIC33FJ32MC304, dsPIC33FJ64MC204/804 and dsPIC33FJ128MC204/804 devices only:**

If AD12B = 1:

11 = Reserved  
10 = Reserved  
01 = Reserved  
00 = Reserved

If AD12B = 0:

11 = Reserved  
10 = CH1 negative input is AN6, CH2 negative input is AN7, CH3 negative input is AN8  
01 = CH1, CH2, CH3 negative input is VREF-  
00 = CH1, CH2, CH3 negative input is VREF-

bit 0

**CH123SA**: Channel 1, 2, 3 Positive Input Select for Sample A bit

If AD12B = 1:

1 = Reserved  
0 = Reserved

If AD12B = 0:

1 = CH1 positive input is AN3, CH2 positive input is AN4, CH3 positive input is AN5  
0 = CH1 positive input is AN0, CH2 positive input is AN1, CH3 positive input is AN2

## REGISTER 22-6: AD1CHS0: ADC1 INPUT CHANNEL 0 SELECT REGISTER

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
CH0NB	—	—		CH0SB<4:0>						
bit 15								bit 8		

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
CH0NA	—	—		CH0SA<4:0>						
bit 7								bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **CH0NB:** Channel 0 Negative Input Select for Sample B bit  
1 = Channel 0 negative input is AN1  
0 = Channel 0 negative input is VREF-
- bit 14-13    **Unimplemented:** Read as '0'
- bit 12-8     **CH0SB<4:0>:** Channel 0 Positive Input Select for Sample B bits  
**dsPIC33FJ32MC304, dsPIC33FJ64MC204/804 and dsPIC33FJ128MC204/804 devices only:**  
01000 = Channel 0 positive input is AN8  
•  
•  
•  
00010 = Channel 0 positive input is AN2  
00001 = Channel 0 positive input is AN1  
00000 = Channel 0 positive input is AN0
- dsPIC33FJ32MC302, dsPIC33FJ64MC202/802 and dsPIC33FJ128MC202/802 devices only:**  
00101 = Channel 0 positive input is AN5  
•  
•  
•  
00010 = Channel 0 positive input is AN2  
00001 = Channel 0 positive input is AN1  
00000 = Channel 0 positive input is AN0.
- bit 7        **CH0NA:** Channel 0 Negative Input Select for Sample A bit  
1 = Channel 0 negative input is AN1  
0 = Channel 0 negative input is VREF-
- bit 6-5      **Unimplemented:** Read as '0'

**REGISTER 22-6: AD1CHS0: ADC1 INPUT CHANNEL 0 SELECT REGISTER (CONTINUED)**

bit 4-0

**CH0SA<4:0>**: Channel 0 Positive Input Select for Sample A bits

**dsPIC33FJ32MC304, dsPIC33FJ64MC204/804 and dsPIC33FJ128MC204/804 devices only:**

01000 = Channel 0 positive input is AN8

•

•

•

00010 = Channel 0 positive input is AN2

00001 = Channel 0 positive input is AN1

00000 = Channel 0 positive input is AN0

**dsPIC33FJ32MC302, dsPIC33FJ64MC202/802 and dsPIC33FJ128MC202/802 devices only:**

00101 = Channel 0 positive input is AN5

•

•

•

00010 = Channel 0 positive input is AN2

00001 = Channel 0 positive input is AN1

00000 = Channel 0 positive input is AN0

**REGISTER 22-7: AD1CSSL: ADC1 INPUT SCAN SELECT REGISTER LOW<sup>(1,2)</sup>**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	CSS8
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| CSS7  | CSS6  | CSS5  | CSS4  | CSS3  | CSS2  | CSS1  | CSS0  |
| bit 7 |       |       |       |       |       |       | bit 0 |

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-9      **Unimplemented:** Read as '0'

bit 8-0      **CSS<8:0>:** ADC Input Scan Selection bits

1 = Select ANx for input scan

0 = Skip ANx for input scan

**Note 1:** On devices without nine analog inputs, all AD1CSSL bits can be selected by user application. However, inputs selected for scan without a corresponding input on device converts VREFL.

**2:** CSSx = ANx, where x = 0 through 8.

**REGISTER 22-8: AD1PCFGL: ADC1 PORT CONFIGURATION REGISTER LOW<sup>(1,2,3)</sup>**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	PCFG8
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| PCFG7 | PCFG6 | PCFG5 | PCFG4 | PCFG3 | PCFG2 | PCFG1 | PCFG0 |
| bit 7 |       |       |       |       |       |       | bit 0 |

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-9      **Unimplemented:** Read as '0'

bit 8-0      **PCFG<8:0>:** ADC Port Configuration Control bits

1 = Port pin in Digital mode, port read input enabled, ADC input multiplexer connected to AVss

0 = Port pin in Analog mode, port read input disabled, ADC samples pin voltage

**Note 1:** On devices without nine analog inputs, all PCFG bits are R/W by user. However, PCFG bits are ignored on ports without a corresponding input on device.

**2:** PCFGx = ANx, where x = 0 through 8.

**3:** PCFGx bits have no effect if ADC module is disabled by setting the ADxMD bit in the PMDx register. In this case, all port pins are multiplexed with ANx will be in Digital mode.

## 23.0 AUDIO DIGITAL-TO-ANALOG CONVERTER (DAC)

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 33. Audio Digital-to-Analog Converter (DAC)**” (DS70211) of the *dsPIC33F/PIC24H Family Reference Manual*, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The Audio Digital-to-Analog Converter (DAC) module is a 16-bit Delta-Sigma signal converter designed for audio applications. It has two output channels, left and right to support stereo applications. Each DAC output channel provides three voltage outputs, positive DAC output, negative DAC output, and the midpoint voltage output for the dsPIC33FJ64MC804 and dsPIC33FJ128MC804 devices.

### 23.1 KEY FEATURES

- 16-bit resolution (14-bit accuracy)
- Second-Order Digital Delta-Sigma Modulator
- 256 X Over-Sampling Ratio
- 128-Tap FIR Current-Steering Analog Reconstruction Filter
- 100 KSPS Maximum Sampling Rate
- User controllable Sample Clock
- Input Frequency 45 kHz max
- Differential Analog Outputs
- Signal-To-Noise: 90 dB
- 4-deep input Buffer
- 16-bit Processor I/O, and DMA interfaces

### 23.2 DAC Module Operation

The functional block diagram of the Audio DAC module is shown in [Figure 23-1](#). The Audio DAC module provides a 4-deep data input FIFO buffer for each output channel. If the DMA module and/or the processor cannot provide output data in a timely manner, and the FIFO becomes empty, the DAC accepts data from the DAC Default Data register (DACPFLT). This safety feature is useful for industrial control applications where the DAC output controls an important processor or machinery. The DACPFLT

register should be initialized with a safe output value. Often the safe output value is either the midpoint value (0x8000) or a zero value (0x0000).

The digital interpolator up-samples the input signals, where the over-sampling ratio is 256x which creates data points between the user supplied data points. The interpolator also includes processing by digital filters to provide noise shaping to move the converter noise above 20 kHz (upper limit of the pass band). The output of the interpolator drives the Sigma-Delta modulator. The serial data bit stream from the Sigma-Delta modulator is processed by the reconstruction filter. The differential outputs of the reconstruction filter are amplified by Op Amps to provide the required peak-to-peak voltage swing.

**Note:** The DAC module is designed specifically for audio applications and is not recommended for control type applications.

### 23.3 DAC Output Format

The DAC output data stream can be in a two's complement signed number format or as an unsigned number format.

The Audio DAC module features the ability to accept the 16-bit input data in a two's complement signed number format or as an unsigned number format. The data formatting is controlled by the Data Format Control bit (FORM<8>) in the DAC1CON register. The supported formats are:

- 1 = Signed (two's complement)
- 0 = Unsigned

If the FORM bit is configured for Unsigned data the user input data yields the following behavior:

- 0xFFFF = most positive output voltage
- 0x8000 = mid point output voltage
- 0x7FFF = a value just below the midpoint
- 0x0000 = minimum output voltage

If the FORM bit is configured for signed data the user input data yields the following behavior:

- 0x7FFF = most positive output voltage
- 0x0000 = mid point output voltage
- 0xFFFF = value just below the midpoint
- 0x8000 = minimum output voltage

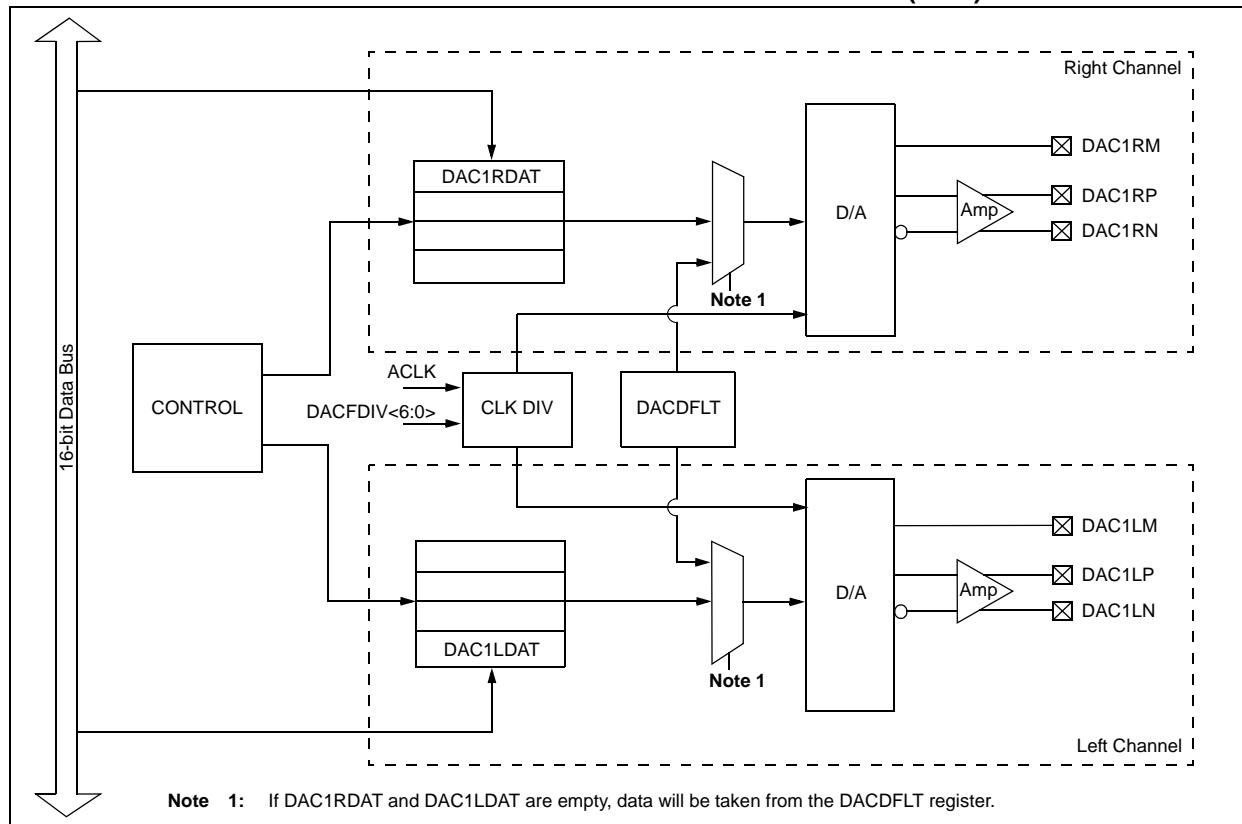
The Audio DAC provides an analog output proportional to the digital input value. The maximum 100,000 samples per second (100 ksp) update rate provides good quality audio reproduction.

## 23.4 DAC CLOCK

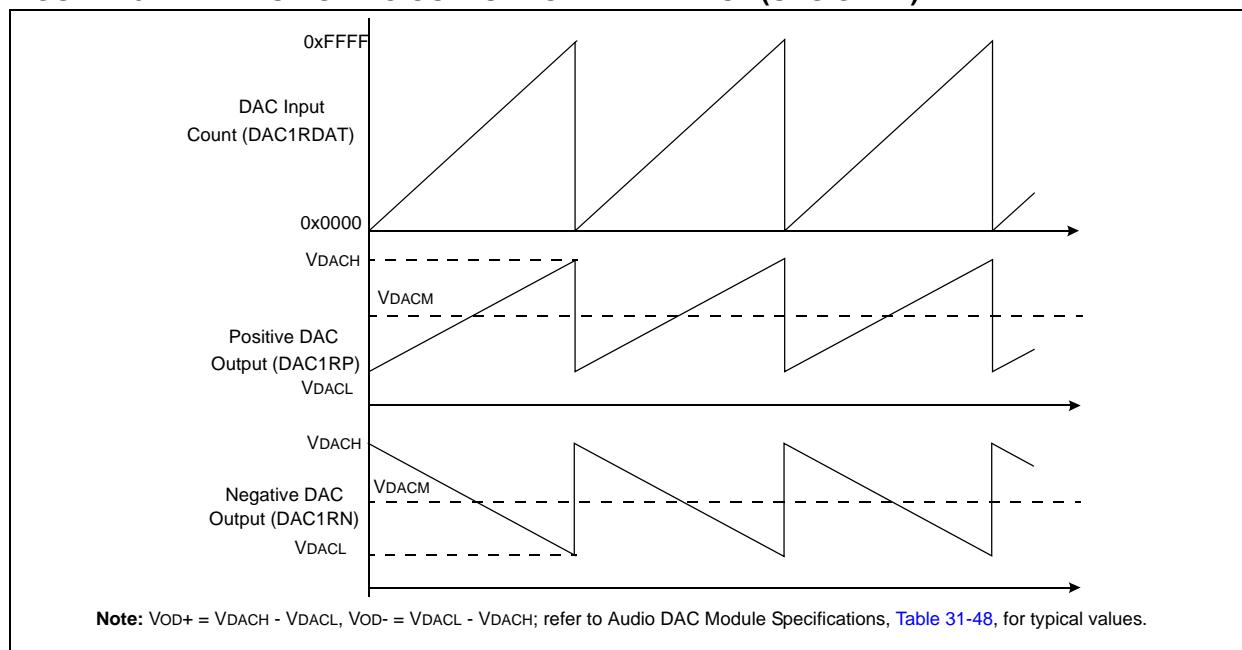
The DAC clock signal clocks the internal logic of the Audio DAC module. The data sample rate of the Audio DAC is an integer division of the rate of the DAC clock. The DAC clock is generated via a clock divider circuit that accepts an auxiliary clock from the auxiliary oscillator. The divisor ratio is programmed by clock

divider bits (DACPFDIV<6:0>) in the DAC Control register (DAC1CON). The resulting DAC clock must not exceed 25.6 MHz. If lower sample rates are to be used, then the DAC filter clock frequency may be reduced to reduce power consumption. The DAC clock frequency is 256 times the sampling frequency.

**FIGURE 23-1: BLOCK DIAGRAM OF AUDIO DIGITAL-TO-ANALOG (DAC) CONVERTER**



**FIGURE 23-2: AUDIO DAC OUTPUT FOR RAMP INPUT (UNSIGNED)**



**REGISTER 23-1: DAC1CON: DAC CONTROL REGISTER**

R/W-0	U-0	R/W-0	R/W-0	U-0	U-0	U-0	R/W-0
DACEN	—	DACSIDL	AMPON	—	—	—	FORM
bit 15	bit 8						

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-1
—	DACFDIV<6:0>						
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **DACEN:** DAC1 Enable bit  
               1 = Enables module  
               0 = Disables module
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **DACSIDL:** Stop in Idle Mode bit  
               1 = Discontinue module operation when device enters Idle mode  
               0 = Continue module operation in Idle mode
- bit 12      **AMPON:** Enable Analog Output Amplifier in Sleep Mode/Stop-in Idle Mode bit  
               1 = Analog Output Amplifier is enabled during Sleep Mode/Stop-in Idle mode  
               0 = Analog Output Amplifier is disabled during Sleep Mode/Stop-in Idle mode
- bit 11-9     **Unimplemented:** Read as '0'
- bit 8        **FORM:** Data Format Select bit  
               1 = Signed integer  
               0 = Unsigned integer
- bit 7        **Unimplemented:** Read as '0'
- bit 6-0      **DACFDIV<6:0>:** DAC Clock Divider bits  
               1111111 = Divide input clock by 128  
               .  
               .  
               .  
               0000101 = Divide input clock by 6 (default)  
               .  
               .  
               .  
               0000010 = Divide input clock by 3  
               0000001 = Divide input clock by 2  
               0000000 = Divide input clock by 1 (no divide)

**REGISTER 23-2: DAC1STAT: DAC STATUS REGISTER**

R/W-0	U-0	R/W-0	U-0	U-0	R/W-0	R-0	R-0
LOEN	—	LMVOEN	—	—	LITYPE	LFULL	LEMPTY
bit 15							bit 8

R/W-0	U-0	R/W-0	U-0	U-0	R/W-0	R-0	R-0
ROEN	—	RMVOEN	—	—	RITYPE	RFULL	REMPY
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **LOEN:** Left Channel DAC Output Enable bit  
1 = Positive and negative DAC outputs are enabled  
0 = DAC outputs are disabled

bit 14      **Unimplemented:** Read as '0'

bit 13      **LMVOEN:** Left Channel Midpoint DAC Output Voltage Enable bit  
1 = Midpoint DAC output is enabled  
0 = Midpoint output is disabled

bit 12-11    **Unimplemented:** Read as '0'

bit 10      **LITYPE:** Left Channel Type of Interrupt bit  
1 = Interrupt if FIFO is EMPTY  
0 = Interrupt if FIFO is NOT FULL

bit 9        **LFULL:** Status, Left Channel Data Input FIFO is FULL bit  
1 = FIFO is Full  
0 = FIFO is not Full

bit 8        **LEMPTY:** Status, Left Channel Data Input FIFO is EMPTY bit  
1 = FIFO is Empty  
0 = FIFO is not Empty

bit 7        **ROEN:** Right Channel DAC Output Enable bit

1 = Positive and negative DAC outputs are enabled  
0 = DAC outputs are disabled

bit 6        **Unimplemented:** Read as '0'

bit 5        **RMVOEN:** Right Channel Midpoint DAC Output Voltage Enable bit  
1 = Midpoint DAC output is enabled  
0 = Midpoint output is disabled

bit 4-3     **Unimplemented:** Read as '0'

bit 2        **RITYPE:** Right Channel Type of Interrupt bit  
1 = Interrupt if FIFO is EMPTY  
0 = Interrupt if FIFO is NOT FULL

bit 1        **RFULL:** Status, Right Channel Data Input FIFO is FULL bit  
1 = FIFO is Full  
0 = FIFO is not Full

bit 0        **REMPY:** Status, Right Channel Data Input FIFO is EMPTY bit  
1 = FIFO is Empty  
0 = FIFO is not Empty

**REGISTER 23-3: DAC1DFLT: DAC DEFAULT DATA REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DAC1DFLT<15:8>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DAC1DFLT<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **DAC1DFLT<15:0>: DAC Default Value bits****REGISTER 23-4: DAC1LDAT: DAC LEFT DATA REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DAC1LDAT<15:8>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DAC1LDAT<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **DAC1LDAT<15:0>: Left Channel Data Port bits****REGISTER 23-5: DAC1RDAT: DAC RIGHT DATA REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DAC1RDAT<15:8>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DAC1RDAT<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0      **DAC1RDAT<15:0>: Right Channel Data Port bits**

**NOTES:**

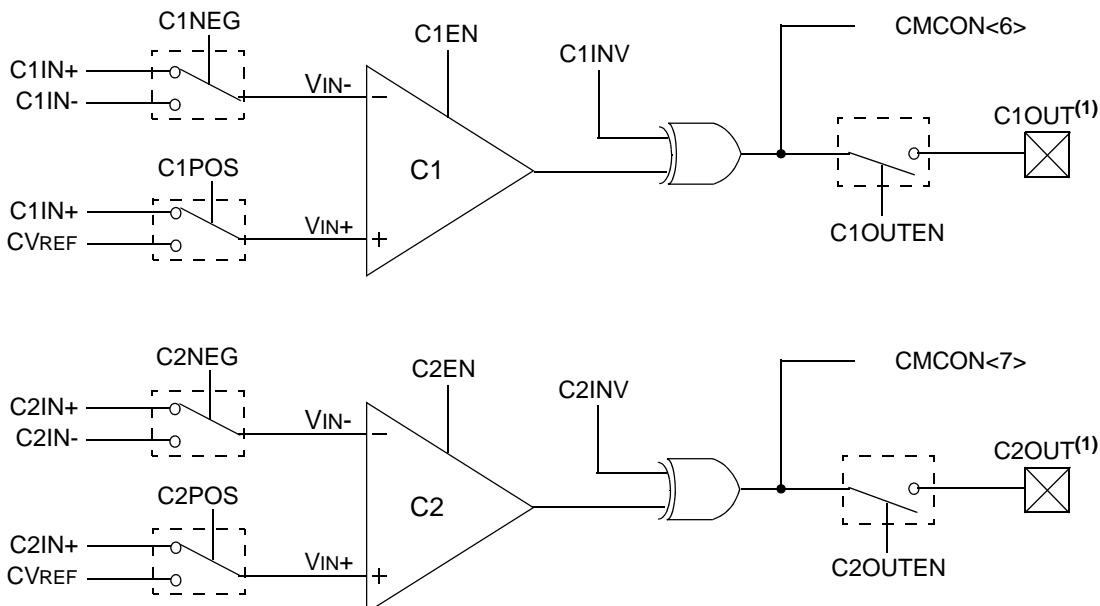
## 24.0 COMPARATOR MODULE

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 34. Comparator**” (DS70212) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The Comparator module provides a set of dual input comparators. The inputs to the comparator can be configured to use any one of the four pin inputs (C1IN+, C1IN-, C2IN+ and C2IN-) as well as the Comparator Voltage Reference Input (CVREF).

**Note:** This peripheral contains output functions that may need to be configured by the peripheral pin select feature. For more information, see **Section 11.6 “Peripheral Pin Select”**.

**FIGURE 24-1: COMPARATOR I/O OPERATING MODES**



**Note 1:** This peripheral's outputs must be assigned to an available RPn pin before use. Refer to **Section 11.6 “Peripheral Pin Select”** for more information.

**REGISTER 24-1: CMCON: COMPARATOR CONTROL REGISTER**

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CMIDL	—	C2EVT	C1EVT	C2EN	C1EN	C2OUTEN <sup>(1)</sup>	C1OUTEN <sup>(2)</sup>
bit 15	bit 8						

R-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
C2OUT	C1OUT	C2INV	C1INV	C2NEG	C2POS	C1NEG	C1POS
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **CMIDL:** Stop in Idle Mode bit  
               1 = When device enters Idle mode, module does not generate interrupts. Module is still enabled  
               0 = Continue normal module operation in Idle mode
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **C2EVT:** Comparator 2 Event bit  
               1 = Comparator output changed states  
               0 = Comparator output did not change states
- bit 12      **C1EVT:** Comparator 1 Event bit  
               1 = Comparator output changed states  
               0 = Comparator output did not change states
- bit 11      **C2EN:** Comparator 2 Enable bit  
               1 = Comparator is enabled  
               0 = Comparator is disabled
- bit 10      **C1EN:** Comparator 1 Enable bit  
               1 = Comparator is enabled  
               0 = Comparator is disabled
- bit 9        **C2OUTEN:** Comparator 2 Output Enable bit<sup>(1)</sup>  
               1 = Comparator output is driven on the output pad  
               0 = Comparator output is not driven on the output pad
- bit 8        **C1OUTEN:** Comparator 1 Output Enable bit<sup>(2)</sup>  
               1 = Comparator output is driven on the output pad  
               0 = Comparator output is not driven on the output pad
- bit 7        **C2OUT:** Comparator 2 Output bit  
When C2INV = 0:  
               1 = C2 VIN+ > C2 VIN-  
               0 = C2 VIN+ < C2 VIN-  
When C2INV = 1:  
               0 = C2 VIN+ > C2 VIN-  
               1 = C2 VIN+ < C2 VIN-

- Note 1:** If C2OUTEN = 1, the C2OUT peripheral output must be configured to an available RPx pin. See [Section 11.6 “Peripheral Pin Select”](#) for more information.
- 2:** If C1OUTEN = 1, the C1OUT peripheral output must be configured to an available RPx pin. See [Section 11.6 “Peripheral Pin Select”](#) for more information.

**REGISTER 24-1: CMCON: COMPARATOR CONTROL REGISTER (CONTINUED)**

bit 6	<b>C1OUT:</b> Comparator 1 Output bit <u>When C1INV = 0:</u> 1 = C1 VIN+ > C1 VIN- 0 = C1 VIN+ < C1 VIN- <u>When C1INV = 1:</u> 0 = C1 VIN+ > C1 VIN- 1 = C1 VIN+ < C1 VIN-
bit 5	<b>C2INV:</b> Comparator 2 Output Inversion bit 1 = C2 output inverted 0 = C2 output not inverted
bit 4	<b>C1INV:</b> Comparator 1 Output Inversion bit 1 = C1 output inverted 0 = C1 output not inverted
bit 3	<b>C2NEG:</b> Comparator 2 Negative Input Configure bit 1 = Input is connected to VIN+ 0 = Input is connected to VIN- See <a href="#">Figure 24-1</a> for Comparator modes.
bit 2	<b>C2POS:</b> Comparator 2 Positive Input Configure bit 1 = Input is connected to VIN+ 0 = Input is connected to CVREF See <a href="#">Figure 24-1</a> for Comparator modes.
bit 1	<b>C1NEG:</b> Comparator 1 Negative Input Configure bit 1 = Input is connected to VIN+ 0 = Input is connected to VIN- See <a href="#">Figure 24-1</a> for Comparator modes.
bit 0	<b>C1POS:</b> Comparator 1 Positive Input Configure bit 1 = Input is connected to VIN+ 0 = Input is connected to CVREF See <a href="#">Figure 24-1</a> for Comparator modes.

- Note 1:** If C2OUTEN = 1, the C2OUT peripheral output must be configured to an available RPx pin. See [Section 11.6 “Peripheral Pin Select”](#) for more information.  
**2:** If C1OUTEN = 1, the C1OUT peripheral output must be configured to an available RPx pin. See [Section 11.6 “Peripheral Pin Select”](#) for more information.

## 24.1 Comparator Voltage Reference

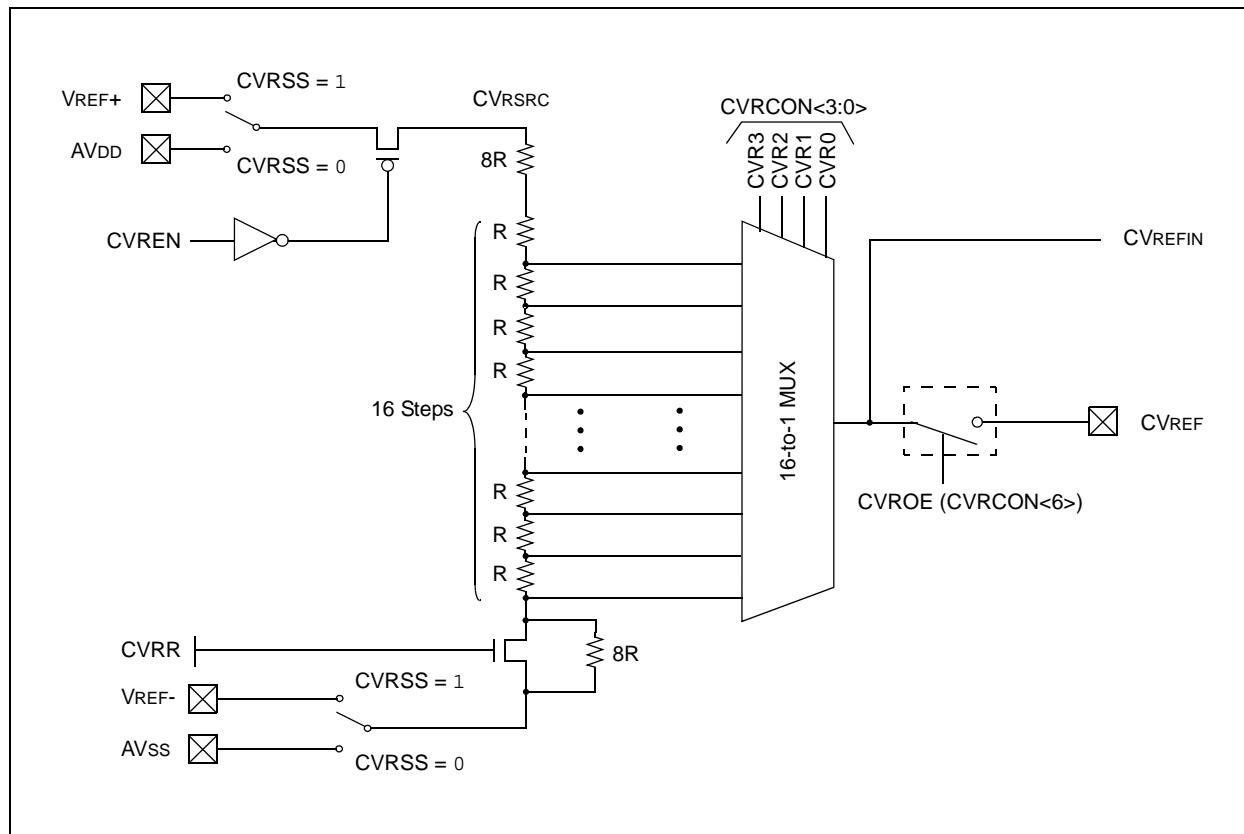
### 24.1.1 CONFIGURING THE COMPARATOR VOLTAGE REFERENCE

The voltage reference module is controlled through the CVRCON register (Register 24-2). The comparator voltage reference provides two ranges of output voltage, each with 16 distinct levels. The range to be used is selected by the CVRR bit (CVRCON<5>). The primary difference between the ranges is the size of the steps selected by the CVREF Selection bits (CVR3:CVR0), with one range offering finer resolution.

The comparator reference supply voltage can come from either VDD and Vss, or the external VREF+ and VREF-. The voltage source is selected by the CVRSS bit (CVRCON<4>).

The settling time of the comparator voltage reference must be considered when changing the CVREF output.

**FIGURE 24-2: COMPARATOR VOLTAGE REFERENCE BLOCK DIAGRAM**



**REGISTER 24-2: CVRCON: COMPARATOR VOLTAGE REFERENCE CONTROL REGISTER**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CVREN	CVROE	CVRR	CVRSS	CVR<3:0>			
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-8      **Unimplemented:** Read as '0'
- bit 7      **CVREN:** Comparator Voltage Reference Enable bit  
           1 = CVREF circuit powered on  
           0 = CVREF circuit powered down
- bit 6      **CVROE:** Comparator VREF Output Enable bit  
           1 = CVREF voltage level is output on CVREF pin  
           0 = CVREF voltage level is disconnected from CVREF pin
- bit 5      **CVRR:** Comparator VREF Range Selection bit  
           1 = CVRSRC range should be 0 to 0.625 CVRSRC with CVRSRC/24 step size  
           0 = CVRSRC range should be 0.25 to 0.719 CVRSRC with CVRSRC/32 step size
- bit 4      **CVRSS:** Comparator VREF Source Selection bit  
           1 = Comparator reference source CVRSRC = VREF+ – VREF-  
           0 = Comparator reference source CVRSRC = AVDD – AVSS
- bit 3-0      **CVR<3:0>:** Comparator VREF Value Selection 0 ≤CVR<3:0> ≤15 bits  
When CVRR = 1:  
 $CVREF = (CVR<3:0>/ 24) \bullet (CVRSRC)$   
When CVRR = 0:  
 $CVREF = 1/4 \bullet (CVRSRC) + (CVR<3:0>/32) \bullet (CVRSRC)$

**NOTES:**

## 25.0 REAL-TIME CLOCK AND CALENDAR (RTCC)

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 37. Real-Time Clock and Calendar (RTCC)**” (DS70301) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

This chapter discusses the Real-Time Clock and Calendar (RTCC) module, available on dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices, and its operation.

The following are some of the key features of this module:

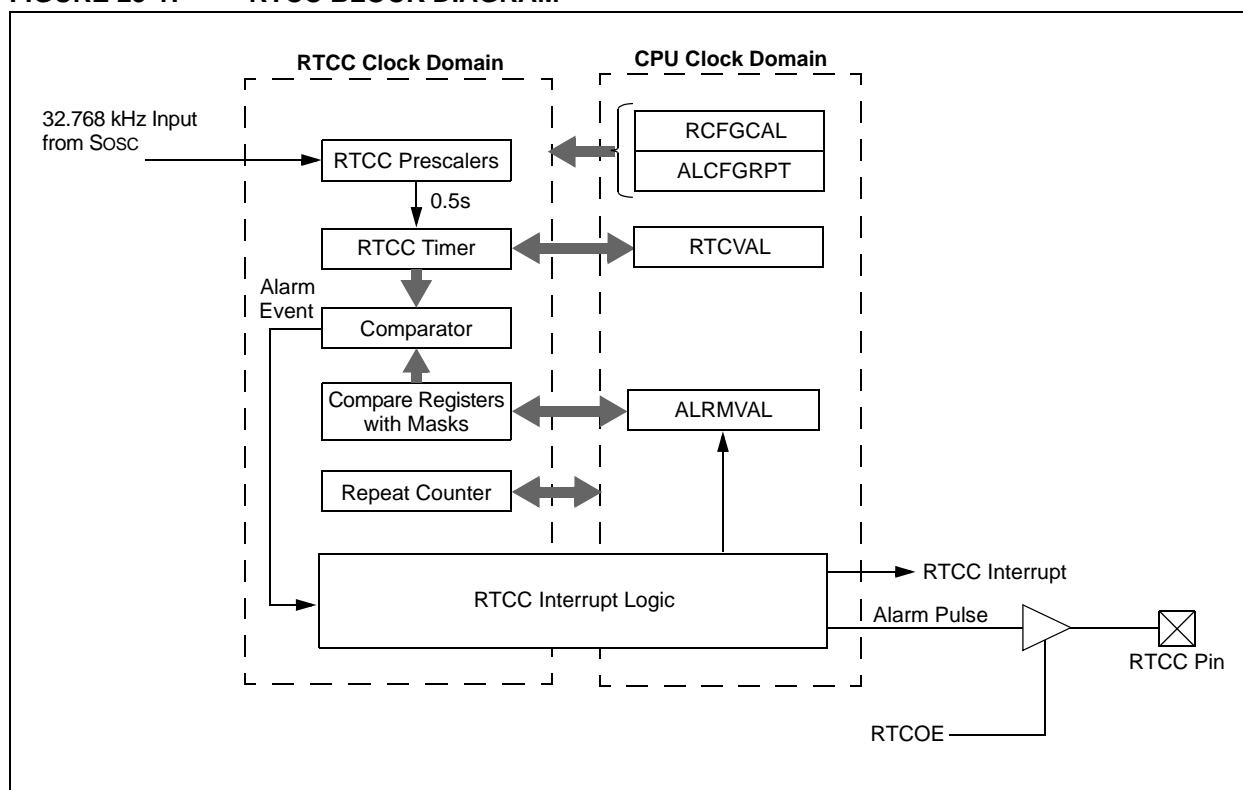
- Time: hours, minutes and seconds
- 24-hour format (military time)
- Calendar: weekday, date, month and year
- Alarm configurable
- Year range: 2000 to 2099
- Leap year correction
- BCD format for compact firmware
- Optimized for low-power operation
- User calibration with auto-adjust
- Calibration range:  $\pm 2.64$  seconds error per month
- Requirements: External 32.768 kHz clock crystal
- Alarm pulse or seconds clock output on RTCC pin

The RTCC module is intended for applications where accurate time must be maintained for extended periods of time with minimum to no intervention from the CPU. The RTCC module is optimized for low-power usage to provide extended battery lifetime while keeping track of time.

The RTCC module is a 100-year clock and calendar with automatic leap year detection. The range of the clock is from 00:00:00 (midnight) on January 1, 2000 to 23:59:59 on December 31, 2099.

The hours are available in 24-hour (military time) format. The clock provides a granularity of one second with half-second visibility to the user.

**FIGURE 25-1: RTCC BLOCK DIAGRAM**



## 25.1 RTCC Module Registers

The RTCC module registers are organized into three categories:

- RTCC Control Registers
- RTCC Value Registers
- Alarm Value Registers

### 25.1.1 REGISTER MAPPING

To limit the register interface, the RTCC Timer and Alarm Time registers are accessed through corresponding register pointers. The RTCC Value register window (RTCVALH and RTCVALL) uses the RTCPTR bits (RCFGCAL<9:8>) to select the desired timer register pair (see [Table 25-1](#)).

By writing the RTCVALH byte, the RTCC Pointer value, RTCPTR<1:0> bits, decrement by one until they reach '00'. Once they reach '00', the MINUTES and SECONDS value will be accessible through RTCVALH and RTCVALL until the pointer value is manually changed.

**TABLE 25-1: RTCVAL REGISTER MAPPING**

RTCPTR <1:0>	RTCC Value Register Window	
	RTCVAL<15:8>	RTCVAL<7:0>
00	MINUTES	SECONDS
01	WEEKDAY	HOURS
10	MONTH	DAY
11	—	YEAR

The Alarm Value register window (ALRMVALH and ALRMVALL) uses the ALRMPTR bits (ALCFGRPT<9:8>) to select the desired Alarm register pair (see [Table 25-2](#)).

By writing the ALRMVALH byte, the Alarm Pointer value, ALRMPTR<1:0> bits, decrement by one until they reach '00'. Once they reach '00', the ALRMMIN and ALRMSEC value will be accessible through ALRMVALH and ALRMVALL until the pointer value is manually changed.

**TABLE 25-2: ALRMVAL REGISTER MAPPING**

ALRMPTR <1:0>	Alarm Value Register Window	
	ALRMVAL<15:8>	ALRMVAL<7:0>
00	ALRMMIN	ALRMSEC
01	ALRMWD	ALRMHR
10	ALRMMNTH	ALRMDAY
11	—	—

Considering that the 16-bit core does not distinguish between 8-bit and 16-bit read operations, the user must be aware that when reading either the ALRMVALH or ALRMVALL bytes will decrement the ALRMPTR<1:0> value. The same applies to the RTCVALH or RTCVALL bytes with the RTCPTR<1:0> being decremented.

**Note:** This only applies to read operations and not write operations.

### 25.1.2 WRITE LOCK

In order to perform a write to any of the RTCC Timer registers, the RTCWREN bit (RCFGCAL<13>) must be set (refer to [Example 25-1](#)).

**Note:** To avoid accidental writes to the timer, it is recommended that the RTCWREN bit (RCFGCAL<13>) is kept clear at any other time. For the RTCWREN bit to be set, there is only 1 instruction cycle time window allowed between the 55/AA sequence and the setting of RTCWREN; therefore, it is recommended that code follow the procedure in [Example 25-1](#).

### EXAMPLE 25-1: SETTING THE RTCWREN BIT

```

MOV    #NVMKEY, W1           ;move the address of NVMKEY into W1
MOV    #0x55, W2
MOV    #0xAA, W3
MOV    W2, [W1]                ;start 55/AA sequence
MOV    W3, [W1]
BSET   RCFGCAL, #13          ;set the RTCWREN bit

```

**REGISTER 25-1: RCFGCAL: RTCC CALIBRATION AND CONFIGURATION REGISTER<sup>(1)</sup>**

R/W-0	U-0	R/W-0	R-0	R-0	R/W-0	R/W-0	R/W-0
RTCEN <sup>(2)</sup>	—	RTCWREN	RTCSYNC	HALFSEC <sup>(3)</sup>	RTCOE	RTCPTR<1:0>	
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CAL<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15	<b>RTCEN:</b> RTCC Enable bit <sup>(2)</sup> 1 = RTCC module is enabled 0 = RTCC module is disabled
bit 14	<b>Unimplemented:</b> Read as '0'
bit 13	<b>RTCWREN:</b> RTCC Value Registers Write Enable bit 1 = RTCVALH and RTCVALL registers can be written to by the user 0 = RTCVALH and RTCVALL registers are locked out from being written to by the user
bit 12	<b>RTCSYNC:</b> RTCC Value Registers Read Synchronization bit 1 = RTCVALH, RTCVALL and ALCFGRPT registers can change while reading due to a rollover ripple resulting in an invalid data read. If the register is read twice and results in the same data, the data can be assumed to be valid 0 = RTCVALH, RTCVALL or ALCFGRPT register can be read without concern over a rollover ripple
bit 11	<b>HALFSEC:</b> Half-Second Status bit <sup>(3)</sup> 1 = Second half period of a second 0 = First half period of a second
bit 10	<b>RTCOE:</b> RTCC Output Enable bit 1 = RTCC output enabled 0 = RTCC output disabled
bit 9-8	<b>RTCPTR&lt;1:0&gt;:</b> RTCC Value Register Window Pointer bits Points to the corresponding RTCC Value registers when reading RTCVALH and RTCVALL registers; the RTCPTR<1:0> value decrements on every read or write of RTCVALH until it reaches '00'. <b>RTCVAL&lt;15:8&gt;:</b> 11 = Reserved 10 = MONTH 01 = WEEKDAY 00 = MINUTES <b>RTCVAL&lt;7:0&gt;:</b> 11 = YEAR 10 = DAY 01 = HOURS 00 = SECONDS

**Note 1:** The RCFGCAL register is only affected by a POR.**2:** A write to the RTCEN bit is only allowed when RTCWREN = 1.**3:** This bit is read-only. It is cleared to '0' on a write to the lower half of the MINSEC register.

**REGISTER 25-1: RCFGCAL: RTCC CALIBRATION AND CONFIGURATION REGISTER<sup>(1)</sup> (CONTINUED)**

- bit 7-0      **CAL<7:0>**: RTC Drift Calibration bits
- 11111111 = Minimum negative adjustment; subtracts 4 RTC clock pulses every one minute
- 
- 
- 
- 10000000 = Maximum negative adjustment; subtracts 512 RTC clock pulses every one minute
- 01111111 = Maximum positive adjustment; adds 508 RTC clock pulses every one minute
- 
- 
- 
- 00000001 = Minimum positive adjustment; adds 4 RTC clock pulses every one minute
- 00000000 = No adjustment

**Note 1:** The RCFGCAL register is only affected by a POR.

**2:** A write to the RTCEN bit is only allowed when RTCWREN = 1.

**3:** This bit is read-only. It is cleared to '0' on a write to the lower half of the MINSEC register.

**REGISTER 25-2: PADCFG1: PAD CONFIGURATION CONTROL REGISTER**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	RTSECSEL <sup>(1)</sup>	PMPTTL
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-2      **Unimplemented:** Read as '0'bit 1      **RTSECSEL:** RTCC Seconds Clock Output Select bit<sup>(1)</sup>1 = RTCC seconds clock is selected for the RTCC pin  
0 = RTCC alarm pulse is selected for the RTCC pinbit 0      **PMPTTL:** PMP Module TTL Input Buffer Select bit1 = PMP module uses TTL input buffers  
0 = PMP module uses Schmitt Trigger input buffers**Note 1:** To enable the actual RTCC output, the RTCOE bit (RCFGCAL) needs to be set.

**REGISTER 25-3: ALCFGRPT: ALARM CONFIGURATION REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
ALRMEN	CHIME		AMASK<3:0>			ALRMPTR<1:0>			
bit 15									bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
		ARPT<7:0>							
bit 7									bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **ALRMEN:** Alarm Enable bit  
               1 = Alarm is enabled (cleared automatically after an alarm event whenever ARPT<7:0> = 0x00 and CHIME = 0)  
               0 = Alarm is disabled
- bit 14      **CHIME:** Chime Enable bit  
               1 = Chime is enabled; ARPT<7:0> bits are allowed to roll over from 0x00 to 0xFF  
               0 = Chime is disabled; ARPT<7:0> bits stop once they reach 0x00
- bit 13-10    **AMASK<3:0>:** Alarm Mask Configuration bits  
               11xx = Reserved – do not use  
               101x = Reserved – do not use  
               1001 = Once a year (except when configured for February 29th, once every 4 years)  
               1000 = Once a month  
               0111 = Once a week  
               0110 = Once a day  
               0101 = Every hour  
               0100 = Every 10 minutes  
               0011 = Every minute  
               0010 = Every 10 seconds  
               0001 = Every second  
               0000 = Every half second
- bit 9-8      **ALRMPTR<1:0>:** Alarm Value Register Window Pointer bits  
               Points to the corresponding Alarm Value registers when reading ALRMVALH and ALRMVALL registers; the ALRMPTR<1:0> value decrements on every read or write of ALRMVALH until it reaches '00'.  
ALRMVAL<15:8>:  
               11 = Unimplemented  
               10 = ALRMMNTH  
               01 = ALRMWD  
               00 = ALRMMIN  
ALRMVAL<7:0>:  
               11 = Unimplemented  
               10 = ALRMDAY  
               01 = ALRMHR  
               00 = ALRMSEC
- bit 7-0      **ARPT<7:0>:** Alarm Repeat Counter Value bits  
               11111111 = Alarm will repeat 255 more times  
               .  
               .  
               .  
               00000000 = Alarm will not repeat  
               The counter decrements on any alarm event. The counter is prevented from rolling over from 0x00 to 0xFF unless CHIME = 1.

**REGISTER 25-4: RTCVAL (WHEN RTCPTR<1:0> = 11): YEAR VALUE REGISTER<sup>(1)</sup>**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
YRTEN<3:0>				YRONE<3:0>			
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8      **Unimplemented:** Read as '0'bit 7-4      **YRTEN<3:0>:** Binary Coded Decimal Value of Year's Tens Digit; contains a value from 0 to 9bit 3-0      **YRONE<3:0>:** Binary Coded Decimal Value of Year's Ones Digit; contains a value from 0 to 9**Note 1:** A write to the YEAR register is only allowed when RTCWREN = 1.**REGISTER 25-5: RTCVAL (WHEN RTCPTR<1:0> = 10): MONTH AND DAY VALUE REGISTER<sup>(1)</sup>**

U-0	U-0	U-0	R-x	R-x	R-x	R-x	R-x
—	—	—	MTHTEN0	MTHONE<3:0>			
bit 15							bit 8

U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	DAYTEN<1:0>		DAYONE<3:0>			
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'bit 12      **MTHTEN0:** Binary Coded Decimal Value of Month's Tens Digit; contains a value of 0 or 1bit 11-8      **MTHONE<3:0>:** Binary Coded Decimal Value of Month's Ones Digit; contains a value from 0 to 9bit 7-6      **Unimplemented:** Read as '0'bit 5-4      **DAYTEN<1:0>:** Binary Coded Decimal Value of Day's Tens Digit; contains a value from 0 to 3bit 3-0      **DAYONE<3:0>:** Binary Coded Decimal Value of Day's Ones Digit; contains a value from 0 to 9**Note 1:** A write to this register is only allowed when RTCWREN = 1.

**REGISTER 25-6: RTCVAL (WHEN RTCPTR<1:0> = 01): WKDYHR: WEEKDAY AND HOURS VALUE REGISTER<sup>(1)</sup>**

U-0	U-0	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x
—	—	—	—	—	WDAY<2:0>		
bit 15							bit 8

U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	HRTEN<1:0>		HRONE<3:0>			
bit 7							bit 0

**Legend:**

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared      x = Bit is unknown

- bit 15-11      **Unimplemented:** Read as '0'  
 bit 10-8      **WDAY<2:0>:** Binary Coded Decimal Value of Weekday Digit; contains a value from 0 to 6  
 bit 7-6      **Unimplemented:** Read as '0'  
 bit 5-4      **HRTEN<1:0>:** Binary Coded Decimal Value of Hour's Tens Digit; contains a value from 0 to 2  
 bit 3-0      **HRONE<3:0>:** Binary Coded Decimal Value of Hour's Ones Digit; contains a value from 0 to 9

**Note 1:** A write to this register is only allowed when RTCWREN = 1.

**REGISTER 25-7: RTCVAL (WHEN RTCPTR<1:0> = 00): MINUTES AND SECONDS VALUE REGISTER**

U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	MINTEN<2:0>			MINONE<3:0>			
bit 15							bit 8

U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	SECTEN<2:0>			SENONE<3:0>			
bit 7							bit 0

**Legend:**

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared      x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'  
 bit 14-12      **MINTEN<2:0>:** Binary Coded Decimal Value of Minute's Tens Digit; contains a value from 0 to 5  
 bit 11-8      **MINONE<3:0>:** Binary Coded Decimal Value of Minute's Ones Digit; contains a value from 0 to 9  
 bit 7      **Unimplemented:** Read as '0'  
 bit 6-4      **SECTEN<2:0>:** Binary Coded Decimal Value of Second's Tens Digit; contains a value from 0 to 5  
 bit 3-0      **SENONE<3:0>:** Binary Coded Decimal Value of Second's Ones Digit; contains a value from 0 to 9

**REGISTER 25-8: ALRMVAL (WHEN ALRMPTR<1:0> = 10): ALARM MONTH AND DAY VALUE REGISTER<sup>(1)</sup>**

U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x			
—	—	—	MTHTEN0	MTHONE<3:0>						
bit 15							bit 8			

U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x		
—	—	DAYTEN<1:0>	DAYONE<3:0>						
bit 7							bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- |           |  |
|-----------|--|
| bit 15-13 | <b>Unimplemented:</b> Read as '0'  |
| bit 12    | <b>MTHTEN0:</b> Binary Coded Decimal Value of Month's Tens Digit; contains a value of 0 or 1             |
| bit 11-8  | <b>MTHONE&lt;3:0&gt;:</b> Binary Coded Decimal Value of Month's Ones Digit; contains a value from 0 to 9 |
| bit 7-6   | <b>Unimplemented:</b> Read as '0'  |
| bit 5-4   | <b>DAYTEN&lt;1:0&gt;:</b> Binary Coded Decimal Value of Day's Tens Digit; contains a value from 0 to 3   |
| bit 3-0   | <b>DAYONE&lt;3:0&gt;:</b> Binary Coded Decimal Value of Day's Ones Digit; contains a value from 0 to 9   |

**Note 1:** A write to this register is only allowed when RTCWREN = 1.

**REGISTER 25-9: ALRMVAL (WHEN ALRMPTR<1:0> = 01): ALARM WEEKDAY AND HOURS VALUE REGISTER<sup>(1)</sup>**

U-0	U-0	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x
—	—	—	—	—	WDAY2	WDAY1	WDAY0
bit 15							bit 8

U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x		
—	—	HRTEN<1:0>	HRONE<3:0>						
bit 7							bit 0		

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- |           |  |
|-----------|--|
| bit 15-11 | <b>Unimplemented:</b> Read as '0'  |
| bit 10-8  | <b>WDAY&lt;2:0&gt;:</b> Binary Coded Decimal Value of Weekday Digit; contains a value from 0 to 6      |
| bit 7-6   | <b>Unimplemented:</b> Read as '0'  |
| bit 5-4   | <b>HRTEN&lt;1:0&gt;:</b> Binary Coded Decimal Value of Hour's Tens Digit; contains a value from 0 to 2 |
| bit 3-0   | <b>HRONE&lt;3:0&gt;:</b> Binary Coded Decimal Value of Hour's Ones Digit; contains a value from 0 to 9 |

**Note 1:** A write to this register is only allowed when RTCWREN = 1.

REGISTER 25-10: ALRMVAL (WHEN ALRMPTR<1:0> = 00): ALARM MINUTES AND SECONDS  
VALUE REGISTER

U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—		MINTEN<2:0>			MINONE<3:0>		
bit 15							bit 8

U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—		SECTEN<2:0>			SECONE<3:0>		
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'  
bit 14-12    **MINTEN<2:0>:** Binary Coded Decimal Value of Minute's Tens Digit; contains a value from 0 to 5  
bit 11-8     **MINONE<3:0>:** Binary Coded Decimal Value of Minute's Ones Digit; contains a value from 0 to 9  
bit 7        **Unimplemented:** Read as '0'  
bit 6-4      **SECTEN<2:0>:** Binary Coded Decimal Value of Second's Tens Digit; contains a value from 0 to 5  
bit 3-0      **SECONE<3:0>:** Binary Coded Decimal Value of Second's Ones Digit; contains a value from 0 to 9

## 26.0 PROGRAMMABLE CYCLIC REDUNDANCY CHECK (CRC) GENERATOR

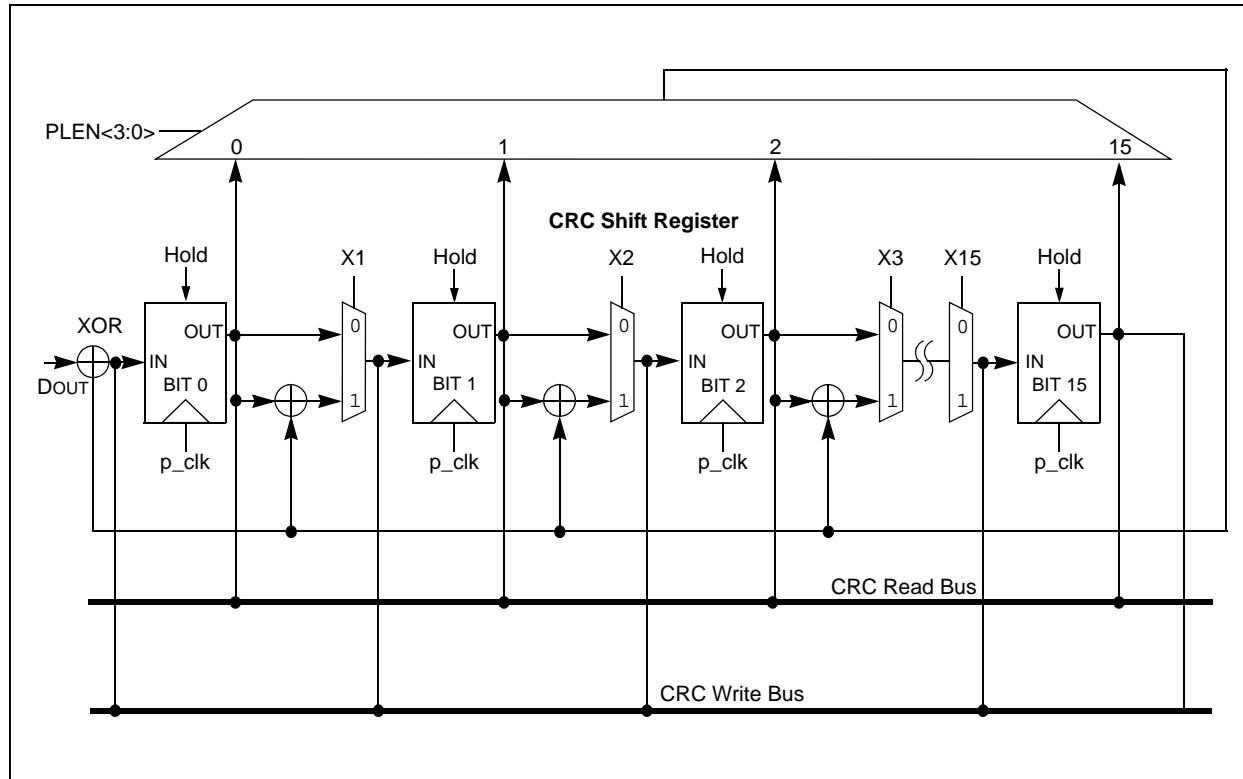
**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 36. Programmable Cyclic Redundancy Check (CRC)**” (DS70298) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

- Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The programmable CRC generator offers the following features:

- User-programmable polynomial CRC equation
- Interrupt output
- Data FIFO

**FIGURE 26-1: CRC SHIFTER DETAILS**



## 26.1 Overview

The module implements a software configurable CRC generator. The terms of the polynomial and its length can be programmed using the *CRCXOR* bits (*X<15:1>*) and the *CRCCON* bits (*PLEN<3:0>*), respectively.

**EQUATION 26-1: CRC EQUATION**

$$x^{16} + x^{12} + x^5 + 1$$

To program this polynomial into the CRC generator, the CRC register bits should be set as shown in **Table 26-1**.

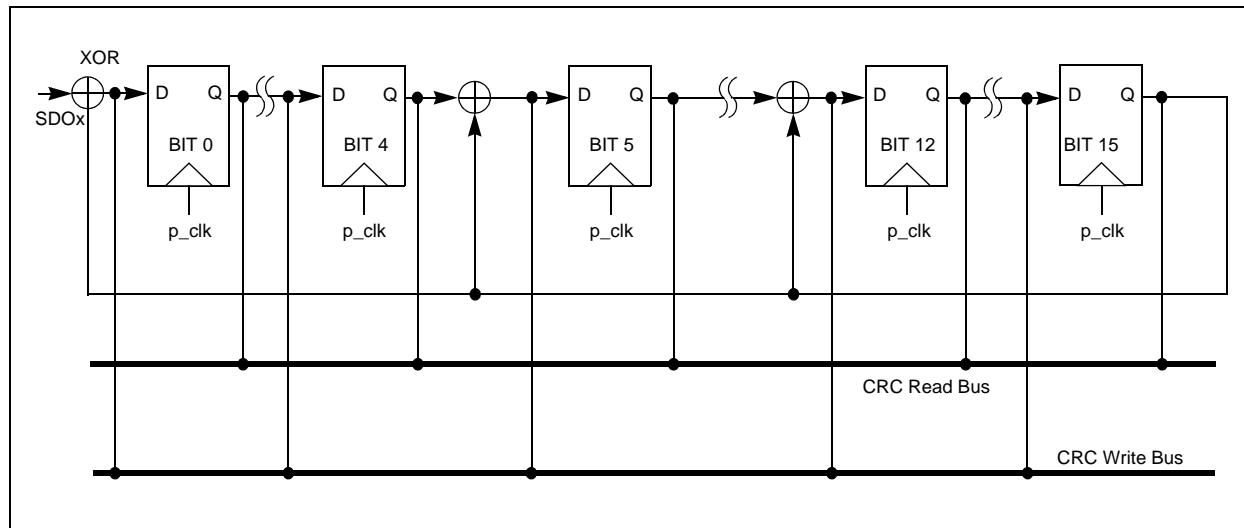
**TABLE 26-1: EXAMPLE CRC SETUP**

Bit Name	Bit Value
<i>PLEN&lt;3:0&gt;</i>	1111
<i>X&lt;15:1&gt;</i>	00010000010000

For the value of *X<15:1>*, the 12th bit and the 5th bit are set to ‘1’, as required by the CRC equation. The 0th bit required by the CRC equation is always XORed. For a 16-bit polynomial, the 16th bit is also always assumed to be XORed; therefore, the *X<15:1>* bits do not have the 0th bit or the 16th bit.

The topology of a standard CRC generator is shown in **Figure 26-2**.

**FIGURE 26-2: CRC GENERATOR RECONFIGURED FOR  $x^{16} + x^{12} + x^5 + 1$**



## 26.2 User Interface

### 26.2.1 DATA INTERFACE

To start serial shifting, a '1' must be written to the CRCGO bit.

The module incorporates a FIFO that is 8 deep when PLEN (PLEN<3:0> > 7, and 16 deep, otherwise. The data for which the CRC is to be calculated must first be written into the FIFO. The smallest data element that can be written into the FIFO is one byte. For example, if PLEN = 5, then the size of the data is PLEN + 1 = 6. The data must be written as follows:

```
data[5:0] = crc_input[5:0]
data[7:6] = 'bxx
```

Once data is written into the CRCWDAT MSb (as defined by PLEN), the value of VWORD (VWORD<4:0>) increments by one. The serial shifter starts shifting data into the CRC engine when CRCGO = 1 and VWORD > 0. When the MSb is shifted out, VWORD decrements by one. The serial shifter continues shifting until the VWORD reaches 0. Therefore, for a given value of PLEN, it will take (PLEN + 1) \* VWORD number of clock cycles to complete the CRC calculations.

When VWORD reaches 8 (or 16), the CRCFUL bit will be set. When VWORD reaches 0, the CRCMPT bit will be set.

To continually feed data into the CRC engine, the recommended mode of operation is to initially "prime" the FIFO with a sufficient number of words so no interrupt is generated before the next word can be written. Once that is done, start the CRC by setting the CRCGO bit to '1'. From that point onward, the VWORD bits should be polled. If they read less than 8 or 16, another word can be written into the FIFO.

To empty words already written into a FIFO, the CRCGO bit must be set to '1' and the CRC shifter allowed to run until the CRCMPT bit is set.

Also, to get the correct CRC reading, it will be necessary to wait for the CRCMPT bit to go high before reading the CRCWDAT register.

If a word is written when the CRCFUL bit is set, the VWORD Pointer will roll over to 0. The hardware will then behave as if the FIFO is empty. However, the condition to generate an interrupt will not be met; therefore, no interrupt will be generated (See [Section 26.2.2 "Interrupt Operation"](#)).

At least one instruction cycle must pass after a write to CRCWDAT before a read of the VWORD bits is done.

### 26.2.2 INTERRUPT OPERATION

When the VWORD4:VWORD0 bits make a transition from a value of '1' to '0', an interrupt will be generated.

## 26.3 Operation in Power-Saving Modes

### 26.3.1 SLEEP MODE

If Sleep mode is entered while the module is operating, the module will be suspended in its current state until clock execution resumes.

### 26.3.2 IDLE MODE

To continue full module operation in Idle mode, the CSIDL bit must be cleared prior to entry into the mode.

If CSIDL = 1, the module will behave the same way as it does in Sleep mode; pending interrupt events will be passed on, even though the module clocks are not available.

## 26.4 Registers

The CRC module provides the following registers:

- CRC Control Register
- CRC XOR Polynomial Register

**REGISTER 26-1: CRCCON: CRC CONTROL REGISTER**

U-0	U-0	R/W-0	R-0	R-0	R-0	R-0	R-0				
—	—	CSIDL		VWORD<4:0>							
bit 15											bit 8
R-0	R-1	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
CRCFUL	CRCMPT	—	CRCGO		PLEN<3:0>						
bit 7											bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14	<b>Unimplemented:</b> Read as '0'
bit 13	<b>CSIDL:</b> CRC Stop in Idle Mode bit 1 = Discontinue module operation when device enters Idle mode 0 = Continue module operation in Idle mode
bit 12-8	<b>VWORD&lt;4:0&gt;:</b> Pointer Value bits Indicates the number of valid words in the FIFO. Has a maximum value of 8 when PLEN<3:0> > 7, or 16 when PLEN<3:0> ≤ 7.
bit 7	<b>CRCFUL:</b> FIFO Full bit 1 = FIFO is full 0 = FIFO is not full
bit 6	<b>CRCMPT:</b> FIFO Empty Bit 1 = FIFO is empty 0 = FIFO is not empty
bit 5	<b>Unimplemented:</b> Read as '0'
bit 4	<b>CRCGO:</b> Start CRC bit 1 = Start CRC serial shifter 0 = Turn off the CRC serial shifter after the FIFO is empty
bit 3-0	<b>PLEN&lt;3:0&gt;:</b> Polynomial Length bits Denotes the length of the polynomial to be generated minus 1.

**REGISTER 26-2: CRCXOR: CRC XOR POLYNOMIAL REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
X<15:8>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
X<7:1>							
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-1      **X<15:1>**: XOR of Polynomial Term  $X^n$  Enable bits

bit 0      **Unimplemented**: Read as '0'

## 27.0 PARALLEL MASTER PORT (PMP)

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Section 35. Parallel Master Port (PMP)**” (DS70299) of the “*dsPIC33F/PIC24H Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

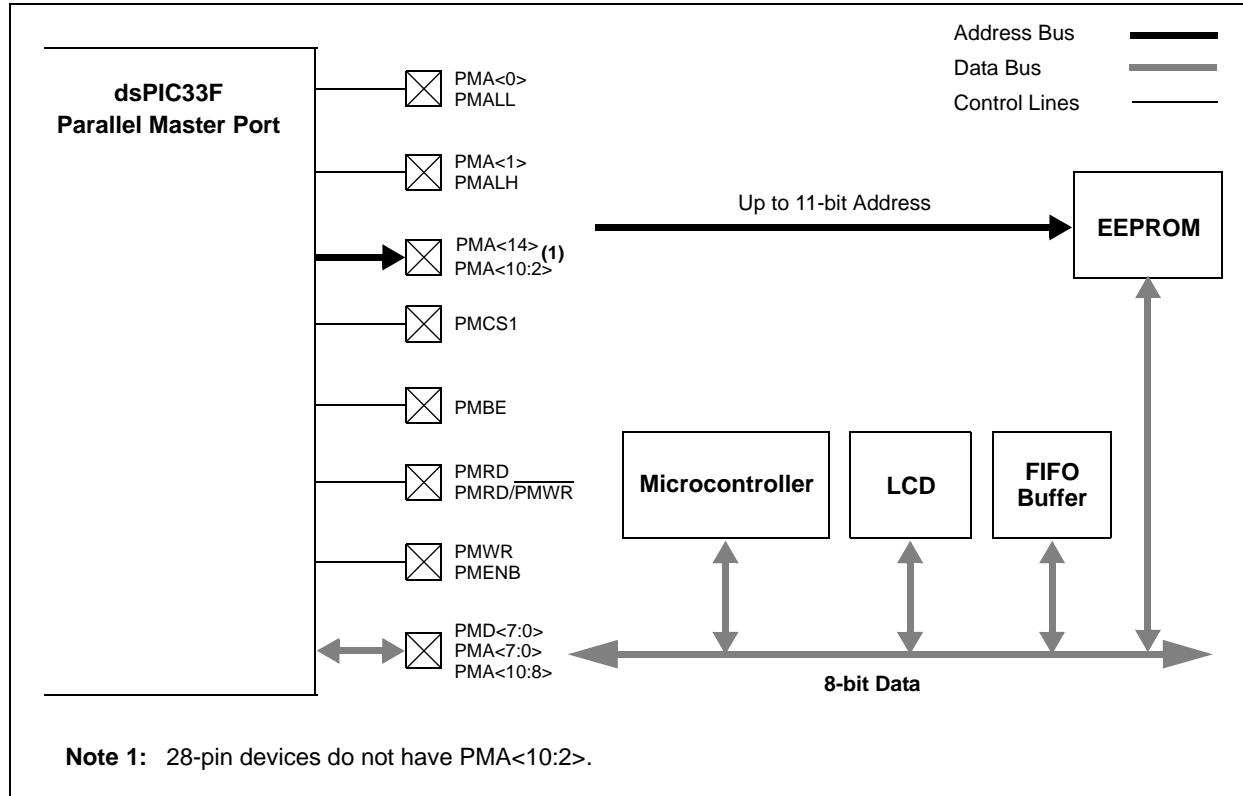
- 2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The Parallel Master Port (PMP) module is a parallel 8-bit I/O module, specifically designed to communicate with a wide variety of parallel devices, such as communication peripherals, LCDs, external memory devices and microcontrollers. Because the interface to parallel peripherals varies significantly, the PMP is highly configurable.

Key features of the PMP module include:

- Fully Multiplexed Address/Data Mode
  - 16 bits of address
- Demultiplexed or Partially Multiplexed Address/Data mode:
  - Up to 11 address lines with single Chip Select
  - Up to 12 address lines without Chip Select
- One Chip Select Line
- Programmable Strobe Options:
  - Individual Read and Write Strobes or;
  - Read/Write Strobe with Enable Strobe
- Address Auto-Increment/Auto-Decrement
- Programmable Address/Data Multiplexing
- Programmable Polarity on Control Signals
- Legacy Parallel Slave Port Support
- Enhanced Parallel Slave Support:
  - Address Support
  - 4-Byte Deep Auto-Incrementing Buffer
- Programmable Wait States
- Selectable Input Voltage Levels

**FIGURE 27-1: PMP MODULE OVERVIEW**



**REGISTER 27-1: PMCON: PARALLEL PORT CONTROL REGISTER**

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
MPEN	—	PSIDL	ADRMUX1 <sup>(1)</sup>	ADRMUX0 <sup>(1)</sup>	PTBEN	PTWREN	PTRDEN
bit 15	bit 8						

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
CSF1	CSF0	ALP <sup>(2)</sup>	—	CS1P <sup>(2)</sup>	BEP	WRSP	RDSP
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15	<b>MPEN:</b> Parallel Master Port Enable bit 1 = PMP enabled 0 = PMP disabled, no off-chip access performed
bit 14	<b>Unimplemented:</b> Read as '0'
bit 13	<b>PSIDL:</b> Stop in Idle Mode bit 1 = Discontinue module operation when device enters Idle mode 0 = Continue module operation in Idle mode
bit 12-11	<b>ADRMUX1:ADRMUX0:</b> Address/Data Multiplexing Selection bits <sup>(1)</sup> 11 = Reserved 10 = All 16 bits of address are multiplexed on PMD<7:0> pins 01 = Lower 8 bits of address are multiplexed on PMD<7:0> pins, upper 3 bits are multiplexed on PMA<10:8> 00 = Address and data appear on separate pins
bit 10	<b>PTBEN:</b> Byte Enable Port Enable bit (16-bit Master mode) 1 = PMBE port enabled 0 = PMBE port disabled
bit 9	<b>PTWREN:</b> Write Enable Strobe Port Enable bit 1 = PMWR/PMENB port enabled 0 = PMWR/PMENB port disabled
bit 8	<b>PTRDEN:</b> Read/Write Strobe Port Enable bit 1 = PMRD/PMWR port enabled 0 = PMRD/PMWR port disabled
bit 7-6	<b>CSF1:CSF0:</b> Chip Select Function bits 11 = Reserved 10 = PMCS1 functions as chip select 0x = PMCS1 functions as address bit 14
bit 5	<b>ALP:</b> Address Latch Polarity bit <sup>(2)</sup> 1 = Active-high (PMALL and PMALH) 0 = Active-low (PMALL and PMALH)
bit 4	<b>Unimplemented:</b> Read as '0'
bit 3	<b>CS1P:</b> Chip Select 1 Polarity bit <sup>(2)</sup> 1 = Active-high (PMCS1/PMCS1) 0 = Active-low (PMCS1/PMCS1)

**Note 1:** 28-pin devices do not have PMA<10:2>.

**2:** These bits have no effect when their corresponding pins are used as address lines.

**REGISTER 27-1: PMCON: PARALLEL PORT CONTROL REGISTER (CONTINUED)**

bit 2	<b>BEP:</b> Byte Enable Polarity bit 1 = Byte enable active-high ( <u>PMBE</u> ) 0 = Byte enable active-low ( <u>PM<sup>BE</sup></u> )
bit 1	<b>WRSP:</b> Write Strobe Polarity bit <u>For Slave modes and Master mode 2 (PMMODE&lt;9:8&gt; = 00,01,10):</u> 1 = Write strobe active-high ( <u>PMWR</u> ) 0 = Write strobe active-low ( <u>PMWR</u> ) <u>For Master mode 1 (PMMODE&lt;9:8&gt; = 11):</u> 1 = Enable strobe active-high ( <u>PMENB</u> ) 0 = Enable strobe active-low ( <u>PM<sup>ENB</sup></u> )
bit 0	<b>RDSP:</b> Read Strobe Polarity bit <u>For Slave modes and Master mode 2 (PMMODE&lt;9:8&gt; = 00,01,10):</u> 1 = Read strobe active-high ( <u>PMRD</u> ) 0 = Read strobe active-low ( <u>PMRD</u> ) <u>For Master mode 1 (PMMODE&lt;9:8&gt; = 11):</u> 1 = Read/write strobe active-high ( <u>PMRD/PMWR</u> ) 0 = Read/write strobe active-low ( <u>PMRD/PMWR</u> )

**Note 1:** 28-pin devices do not have PMA<10:2>.

**2:** These bits have no effect when their corresponding pins are used as address lines.

**Register 27-2: PMMODE: PARALLEL PORT MODE REGISTER**

R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
BUSY	IRQM<1:0>		INCM<1:0>		MODE16	MODE<1:0>	
bit 15	bit 8						

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAITB<1:0> <sup>(1)</sup>			WAITM<3:0>				WAITE<1:0> <sup>(1)</sup>
bit 7	bit 0						

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **BUSY:** Busy bit (Master mode only)  
 1 = Port is busy (not useful when the processor stall is active)  
 0 = Port is not busy
- bit 14-13    **IRQM<1:0>:** Interrupt Request Mode bits  
 11 = Interrupt generated when Read Buffer 3 is read or Write Buffer 3 is written (Buffered PSP mode) or on a read or write operation when PMA<1:0> = 11 (Addressable PSP mode only)  
 10 = No interrupt generated, processor stall activated  
 01 = Interrupt generated at the end of the read/write cycle  
 00 = No interrupt generated
- bit 12-11    **INCM<1:0>:** Increment Mode bits  
 11 = PSP read and write buffers auto-increment (Legacy PSP mode only)  
 10 = Decrement ADDR<10:0> by 1 every read/write cycle  
 01 = Increment ADDR<10:0> by 1 every read/write cycle  
 00 = No increment or decrement of address
- bit 10        **MODE16:** 8/16-bit Mode bit  
 1 = 16-bit mode: data register is 16 bits, a read or write to the data register invokes two 8-bit transfers  
 0 = 8-bit mode: data register is 8 bits, a read or write to the data register invokes one 8-bit transfer
- bit 9-8       **MODE<1:0>:** Parallel Port Mode Select bits  
 11 = Master mode 1 (PMCS1, PMRD/PMWR, PMENB, PMBE, PMA<x:0> and PMD<7:0>)  
 10 = Master mode 2 (PMCS1, PMRD, PMWR, PMBE, PMA<x:0> and PMD<7:0>)  
 01 = Enhanced PSP, control signals (PMRD, PMWR, PMCS1, PMD<7:0> and PMA<1:0>)  
 00 = Legacy Parallel Slave Port, control signals (PMRD, PMWR, PMCS1 and PMD<7:0>)
- bit 7-6       **WAITB<1:0>:** Data Setup to Read/Write Wait State Configuration bits<sup>(1)</sup>  
 11 = Data wait of 4 TCY; multiplexed address phase of 4 TCY  
 10 = Data wait of 3 TCY; multiplexed address phase of 3 TCY  
 01 = Data wait of 2 TCY; multiplexed address phase of 2 TCY  
 00 = Data wait of 1 TCY; multiplexed address phase of 1 TCY
- bit 5-2       **WAITM<3:0>:** Read to Byte Enable Strobe Wait State Configuration bits  
 1111 = Wait of additional 15 TCY  
 •  
 0001 = Wait of additional 1 TCY  
 0000 = No additional wait cycles (operation forced into one TCY)
- bit 1-0       **WAITE<1:0>:** Data Hold After Strobe Wait State Configuration bits<sup>(1)</sup>  
 11 = Wait of 4 TCY  
 10 = Wait of 3 TCY  
 01 = Wait of 2 TCY  
 00 = Wait of 1 TCY

**Note 1:** WAITB and WAITE bits are ignored whenever WAITM3:WAITM0 = 0000.

**REGISTER 27-3: PMADDR: PARALLEL PORT ADDRESS REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ADDR15	CS1			ADDR<13:8>			
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
				ADDR<7:0>			
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **ADDR15:** Parallel Port Destination Address bitbit 14      **CS1:** Chip Select 1 bit

1 = Chip select 1 is active

0 = Chip select 1 is inactive

bit 13-0      **ADDR13:ADDR0:** Parallel Port Destination Address bits**REGISTER 27-4: PMAEN: PARALLEL PORT ENABLE REGISTER**

U-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	PTEN14	—	—	—	PTEN<10:8> <sup>(1)</sup>		
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PTEN<7:2> <sup>(1)</sup>			PTEN<1:0>	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15      **Unimplemented:** Read as '0'bit 14      **PTEN14:** PMCS1 Strobe Enable bit

1 = PMA14 functions as either PMA&lt;14&gt; bit or PMCS1

0 = PMA14 pin functions as port I/O

bit 13-11      **Unimplemented:** Read as '0'bit 10-2      **PTEN<10:2>:** PMP Address Port Enable bits<sup>(1)</sup>

1 = PMA&lt;10:2&gt; function as PMP address lines

0 = PMA&lt;10:2&gt; function as port I/O

bit 1-0      **PTEN<1:0>:** PMALH/PMALL Strobe Enable bits

1 = PMA1 and PMA0 function as either PMA&lt;1:0&gt; or PMALH and PMALL

0 = PMA1 and PMA0 pads functions as port I/O

**Note 1:** Devices with 28 pins do not have PMA<10:2>.

**REGISTER 27-5: PMSTAT: PARALLEL PORT STATUS REGISTER**

R-0	R/W-0, HS	U-0	U-0	R-0	R-0	R-0	R-0
IBF	IBOV	—	—	IB3F	IB2F	IB1F	IB0F
bit 15							bit 8

R-1	R/W-0, HS	U-0	U-0	R-1	R-1	R-1	R-1
OBE	OBUF	—	—	OB3E	OB2E	OB1E	OB0E
bit 7							bit 0

<b>Legend:</b>	HS = Hardware Set bit
R = Readable bit	W = Writable bit
-n = Value at POR	‘1’ = Bit is set      ‘0’ = Bit is cleared      x = Bit is unknown

- bit 15      **IBF:** Input Buffer Full Status bit  
   1 = All writable input buffer registers are full  
   0 = Some or all of the writable input buffer registers are empty
- bit 14      **IBOV:** Input Buffer Overflow Status bit  
   1 = A write attempt to a full input byte register occurred (must be cleared in software)  
   0 = No overflow occurred
- bit 13-12     **Unimplemented:** Read as ‘0’
- bit 11-8      **IB3F:IB0F:** Input Buffer x Status Full bits  
   1 = Input buffer contains data that has not been read (reading buffer will clear this bit)  
   0 = Input buffer does not contain any unread data
- bit 7        **OBE:** Output Buffer Empty Status bit  
   1 = All readable output buffer registers are empty  
   0 = Some or all of the readable output buffer registers are full
- bit 6        **OBUF:** Output Buffer Underflow Status bits  
   1 = A read occurred from an empty output byte register (must be cleared in software)  
   0 = No underflow occurred
- bit 5-4      **Unimplemented:** Read as ‘0’
- bit 3-0      **OB3E:OB0E** Output Buffer x Status Empty bit  
   1 = Output buffer is empty (writing data to the buffer will clear this bit)  
   0 = Output buffer contains data that has not been transmitted

**REGISTER 27-6: PADCFG1: PAD CONFIGURATION CONTROL REGISTER**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	RTSECSEL <sup>(1)</sup>	PMPTTL
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-2      **Unimplemented:** Read as '0'bit 1      **RTSECSEL:** RTCC Seconds Clock Output Select bit<sup>(1)</sup>1 = RTCC seconds clock is selected for the RTCC pin  
0 = RTCC alarm pulse is selected for the RTCC pinbit 0      **PMPTTL:** PMP Module TTL Input Buffer Select bit1 = PMP module uses TTL input buffers  
0 = PMP module uses Schmitt Trigger input buffers**Note 1:** To enable the actual RTCC output, the RTCOE bit (RCFGCAL) needs to be set.

**NOTES:**

## 28.0 SPECIAL FEATURES

- Note 1:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. However, it is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the “*dsPIC33F/PIC24H Family Reference Manual*”. Please see the Microchip web site ([www.microchip.com](http://www.microchip.com)) for the latest dsPIC33F/PIC24H Family Reference Manual sections.
- 2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices include the following features intended to maximize application flexibility and reliability, and minimize cost through elimination of external components:

- Flexible configuration
- Watchdog Timer (WDT)
- Code Protection and CodeGuard™ Security
- JTAG Boundary Scan Interface
- In-Circuit Serial Programming™ (ICSP™)
- In-Circuit Emulation

**TABLE 28-1: DEVICE CONFIGURATION REGISTER MAP**

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0xF80000	FBS	RBS<1:0>	—	—		BSS<2:0>			BWRP
0xF80002	FSS <sup>(1)</sup>	RSS<1:0>	—	—		SSS<2:0>			SWRP
0xF80004	FGS	—	—	—	—	GSS<1:0>			GWRP
0xF80006	FOSCSEL	IESO	—	—	—		FNOSC<2:0>		
0xF80008	FOSC	FCKSM<1:0>	IOL1WAY	—	—	OSCIOFNC	POSCMD<1:0>		
0xF8000A	FWDT	FWDTEN	WINDIS	—	WDTPRE		WDTPOST<3:0>		
0xF8000C	FPOR	PWMPIN	HPOL	LPOL	ALTI2C	—		FPWRT<2:0>	
0xF8000E	FICD	Reserved <sup>(2)</sup>		JTAGEN	—	—	—	ICS<1:0>	
0xF80010	FUID0	User Unit ID Byte 0							
0xF80012	FUID1	User Unit ID Byte 1							
0xF80014	FUID2	User Unit ID Byte 2							
0xF80016	FUID3	User Unit ID Byte 3							

**Legend:** — = unimplemented bit, read as ‘0’.

**Note 1:** This Configuration register is not available and reads as 0xFF on dsPIC33FJ32MC302/304 devices.

**2:** These bits are reserved for use by development tools and must be programmed as ‘1’.

## 28.1 Configuration Bits

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices provide nonvolatile memory implementations for device Configuration bits. Refer to **Section 25. “Device Configuration”** (DS70194) in the “*dsPIC33F/PIC24H Family Reference Manual*” for more information on this implementation.

The Configuration bits can be programmed (read as ‘0’), or left unprogrammed (read as ‘1’), to select various device configurations. These bits are mapped starting at program memory location 0xF80000.

The individual Configuration bit descriptions for the Configuration registers are shown in [Table 28-2](#).

Note that address 0xF80000 is beyond the user program memory space. It belongs to the configuration memory space (0x800000-0xFFFFFFF), which can only be accessed using table reads and table writes.

The Device Configuration register map is shown in [Table 28-1](#).

TABLE 28-2: dsPIC33F CONFIGURATION BITS DESCRIPTION

Bit Field	Register	RTSP Effect	Description
BWRP	FBS	Immediate	Boot Segment Program Flash Write Protection 1 = Boot segment can be written 0 = Boot segment is write-protected
BSS<2:0>	FBS	Immediately	Boot Segment Program Flash Code Protection Size X11 = No Boot program Flash segment  Boot space is 1K Instruction Words (except interrupt vectors) 110 = Standard security; boot program Flash segment ends at 0x0007FE 010 = High security; boot program Flash segment ends at 0x0007FE  Boot space is 4K Instruction Words (except interrupt vectors) 101 = Standard security; boot program Flash segment, ends at 0x001FFE 001 = High security; boot program Flash segment ends at 0x001FFE  Boot space is 8K Instruction Words (except interrupt vectors) 100 = Standard security; boot program Flash segment ends at 0x003FFE 000 = High security; boot program Flash segment ends at 0x003FFE
RBS<1:0> <sup>(1)</sup>	FBS	Immediate	Boot Segment RAM Code Protection Size 11 = No Boot RAM defined 10 = Boot RAM is 128 bytes 01 = Boot RAM is 256 bytes 00 = Boot RAM is 1024 bytes
SWRP <sup>(1)</sup>	FSS <sup>(1)</sup>	Immediate	Secure Segment Program Flash Write-Protect bit 1 = Secure Segment can be written 0 = Secure Segment is write-protected
SSS<2:0>	FSS	Immediate	Secure Segment Program Flash Code Protection Size <b>(Secure segment is not implemented on 32K devices)</b> X11 = No Secure program flash segment  Secure space is 4K IW less BS 110 = Standard security; secure program Flash segment starts at End of BS, ends at 0x001FFE 010 = High security; secure program Flash segment starts at End of BS, ends at 0x001FFE  Secure space is 8K IW less BS 101 = Standard security; secure program Flash segment starts at End of BS, ends at 0x003FFE 001 = High security; secure program Flash segment starts at End of BS, ends at 0x003FFE  Secure space is 16K IW less BS 100 = Standard security; secure program Flash segment starts at End of BS, ends at 007FFEh 000 = High security; secure program Flash segment starts at End of BS, ends at 0x007FFE
RSS<1:0> <sup>(1)</sup>	FSS <sup>(1)</sup>	Immediate	Secure Segment RAM Code Protection 11 = No Secure RAM defined 10 = Secure RAM is 256 Bytes less BS RAM 01 = Secure RAM is 2048 Bytes less BS RAM 00 = Secure RAM is 4096 Bytes less BS RAM

**Note 1:** This Configuration register is not available on dsPIC33FJ32MC302/304 devices.

**TABLE 28-2: dsPIC33F CONFIGURATION BITS DESCRIPTION (CONTINUED)**

Bit Field	Register	RTSP Effect	Description
GSS<1:0>	FGS	Immediate	General Segment Code-Protect bit 11 = User program memory is not code-protected 10 = Standard security 0x = High security
GWRP	FGS	Immediate	General Segment Write-Protect bit 1 = User program memory is not write-protected 0 = User program memory is write-protected
IESO	FOSCSEL	Immediate	Two-speed Oscillator Start-up Enable bit 1 = Start-up device with FRC, then automatically switch to the user-selected oscillator source when ready 0 = Start-up device with user-selected oscillator source
FNOSC<2:0>	FOSCSEL	If clock switch is enabled, RTSP effect is on any device Reset; otherwise, Immediate	Initial Oscillator Source Selection bits 111 = Internal Fast RC (FRC) oscillator with postscaler 110 = Internal Fast RC (FRC) oscillator with divide-by-16 101 = LPRC oscillator 100 = Secondary (LP) oscillator 011 = Primary (XT, HS, EC) oscillator with PLL 010 = Primary (XT, HS, EC) oscillator 001 = Internal Fast RC (FRC) oscillator with PLL 000 = FRC oscillator
FCKSM<1:0>	FOSC	Immediate	Clock Switching Mode bits 1x = Clock switching is disabled, Fail-Safe Clock Monitor is disabled 01 = Clock switching is enabled, Fail-Safe Clock Monitor is disabled 00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled
IOL1WAY	FOSC	Immediate	Peripheral Pin Select Configuration bit 1 = Allow only one reconfiguration 0 = Allow multiple reconfigurations
OSCIOFNC	FOSC	Immediate	OSC2 Pin Function bit (except in XT and HS modes) 1 = OSC2 is clock output 0 = OSC2 is general purpose digital I/O pin
POSCMD<1:0>	FOSC	Immediate	Primary Oscillator Mode Select bits 11 = Primary oscillator disabled 10 = HS Crystal Oscillator mode 01 = XT Crystal Oscillator mode 00 = EC (External Clock) mode
FWDTEN	FWDT	Immediate	Watchdog Timer Enable bit 1 = Watchdog Timer always enabled (LPRC oscillator cannot be disabled. Clearing the SWDTEN bit in the RCON register has no effect.) 0 = Watchdog Timer enabled/disabled by user software (LPRC can be disabled by clearing the SWDTEN bit in the RCON register)
WINDIS	FWDT	Immediate	Watchdog Timer Window Enable bit 1 = Watchdog Timer in Non-Window mode 0 = Watchdog Timer in Window mode
WDTPRE	FWDT	Immediate	Watchdog Timer Prescaler bit 1 = 1:128 0 = 1:32

**Note 1:** This Configuration register is not available on dsPIC33FJ32MC302/304 devices.

**TABLE 28-2: dsPIC33F CONFIGURATION BITS DESCRIPTION (CONTINUED)**

Bit Field	Register	RTSP Effect	Description
WDTPOST<3:0>	FWDT	Immediate	Watchdog Timer Postscaler bits 1111 = 1:32,768 1110 = 1:16,384 • • • 0001 = 1:2 0000 = 1:1
PWMPIN	FPOR	Immediate	Motor Control PWM Module Pin Mode bit 1 = PWM module pins controlled by PORT register at device Reset (tri-stated) 0 = PWM module pins controlled by PWM module at device Reset (configured as output pins)
HPOL	FPOR	Immediate	Motor Control PWM High Side Polarity bit 1 = PWM module high side output pins have active-high output polarity 0 = PWM module high side output pins have active-low output polarity
LPOL	FPOR	Immediate	Motor Control PWM Low Side Polarity bit 1 = PWM module low side output pins have active-high output polarity 0 = PWM module low side output pins have active-low output polarity
FPWRT<2:0>	FPOR	Immediate	Power-on Reset Timer Value Select bits 111 = PWRT = 128 ms 110 = PWRT = 64 ms 101 = PWRT = 32 ms 100 = PWRT = 16 ms 011 = PWRT = 8 ms 010 = PWRT = 4 ms 001 = PWRT = 2 ms 000 = PWRT = Disabled
ALTI2C	FPOR	Immediate	Alternate I <sup>2</sup> C™ pins 1 = I <sup>2</sup> C mapped to SDA1/SCL1 pins 0 = I <sup>2</sup> C mapped to ASDA1/ASCL1 pins
JTAGEN	FICD	Immediate	JTAG Enable bit 1 = JTAG enabled 0 = JTAG disabled
ICS<1:0>	FICD	Immediate	ICD Communication Channel Select bits 11 = Communicate on PGEC1 and PGED1 10 = Communicate on PGEC2 and PGED2 01 = Communicate on PGEC3 and PGED3 00 = Reserved, do not use

**Note 1:** This Configuration register is not available on dsPIC33FJ32MC302/304 devices.

## 28.2 On-Chip Voltage Regulator

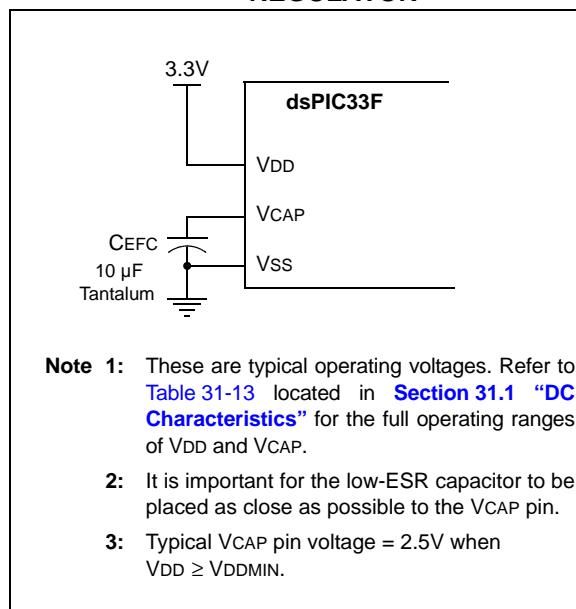
All of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices power their core digital logic at a nominal 2.5V. This can create a conflict for designs that are required to operate at a higher typical voltage, such as 3.3V. To simplify system design, all devices in the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family incorporate an on-chip regulator that allows the device to run its core logic from VDD.

The regulator provides power to the core from the other VDD pins. When the regulator is enabled, a low-ESR (less than 5 Ohms) capacitor (such as tantalum or ceramic) must be connected to the VCAP pin (Figure 28-1). This helps to maintain the stability of the regulator. The recommended value for the filter capacitor is provided in Table 31-13 located in **Section 31.0 “Electrical Characteristics”**.

**Note:** It is important for the low-ESR capacitor to be placed as close as possible to the VCAP pin.

On a POR, it takes approximately 20  $\mu$ s for the on-chip voltage regulator to generate an output voltage. During this time, designated as TSTARTUP, code execution is disabled. TSTARTUP is applied every time the device resumes operation after any power-down.

**FIGURE 28-1: CONNECTIONS FOR THE ON-CHIP VOLTAGE REGULATOR<sup>(1,2,3)</sup>**



## 28.3 Brown-Out Reset (BOR)

The Brown-out Reset (BOR) module is based on an internal voltage reference circuit that monitors the regulated supply voltage VCAP. The main purpose of the BOR module is to generate a device Reset when a brown-out condition occurs. Brown-out conditions are generally caused by glitches on the AC mains (for example, missing portions of the AC cycle waveform due to bad power transmission lines, or voltage sags due to excessive current draw when a large inductive load is turned on).

A BOR generates a Reset pulse, which resets the device. The BOR selects the clock source, based on the device Configuration bit values (FNOSC<2:0> and POSCMD<1:0>).

If an oscillator mode is selected, the BOR activates the Oscillator Start-up Timer (OST). The system clock is held until OST expires. If the PLL is used, the clock is held until the LOCK bit (OSCCON<5>) is ‘1’.

Concurrently, the PWRT time-out (TPWRT) is applied before the internal Reset is released. If TPWRT = 0 and a crystal oscillator is being used, then a nominal delay of TFSCM = 100 is applied. The total delay in this case is TFSCM.

The BOR Status bit (RCON<1>) is set to indicate that a BOR has occurred. The BOR circuit, if enabled, continues to operate while in Sleep or Idle modes and resets the device should VDD fall below the BOR threshold voltage.

## 28.4 Watchdog Timer (WDT)

For dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices, the WDT is driven by the LPRC oscillator. When the WDT is enabled, the clock source is also enabled.

### 28.4.1 PRESCALER/POSTSCALER

The nominal WDT clock source from LPRC is 32 kHz. This feeds a prescaler than can be configured for either 5-bit (divide-by-32) or 7-bit (divide-by-128) operation. The prescaler is set by the WDTPRE Configuration bit. With a 32 kHz input, the prescaler yields a nominal WDT time-out period ( $T_{WDT}$ ) of 1 ms in 5-bit mode, or 4 ms in 7-bit mode.

A variable postscaler divides down the WDT prescaler output and allows for a wide range of time-out periods. The postscaler is controlled by the WDTPOST<3:0> Configuration bits (FWDT<3:0>), which allow the selection of 16 settings, from 1:1 to 1:32,768. Using the prescaler and postscaler, time-out periods ranging from 1 ms to 131 seconds can be achieved.

The WDT, prescaler and postscaler are reset:

- On any device Reset
- On the completion of a clock switch, whether invoked by software (i.e., setting the OSWEN bit after changing the NOSC bits) or by hardware (i.e., Fail-Safe Clock Monitor)
- When a PWRSAV instruction is executed (i.e., Sleep or Idle mode is entered)
- When the device exits Sleep or Idle mode to resume normal operation
- By a CLRWDT instruction during normal execution

**Note:** The CLRWDT and PWRSAV instructions clear the prescaler and postscaler counts when executed.

### 28.4.2 SLEEP AND IDLE MODES

If the WDT is enabled, it continues to run during Sleep or Idle modes. When the WDT time-out occurs, the device wakes the device and code execution continues from where the PWRSAV instruction was executed. The corresponding SLEEP or IDLE bit (RCON<3,2>) needs to be cleared in software after the device wakes up.

### 28.4.3 ENABLING WDT

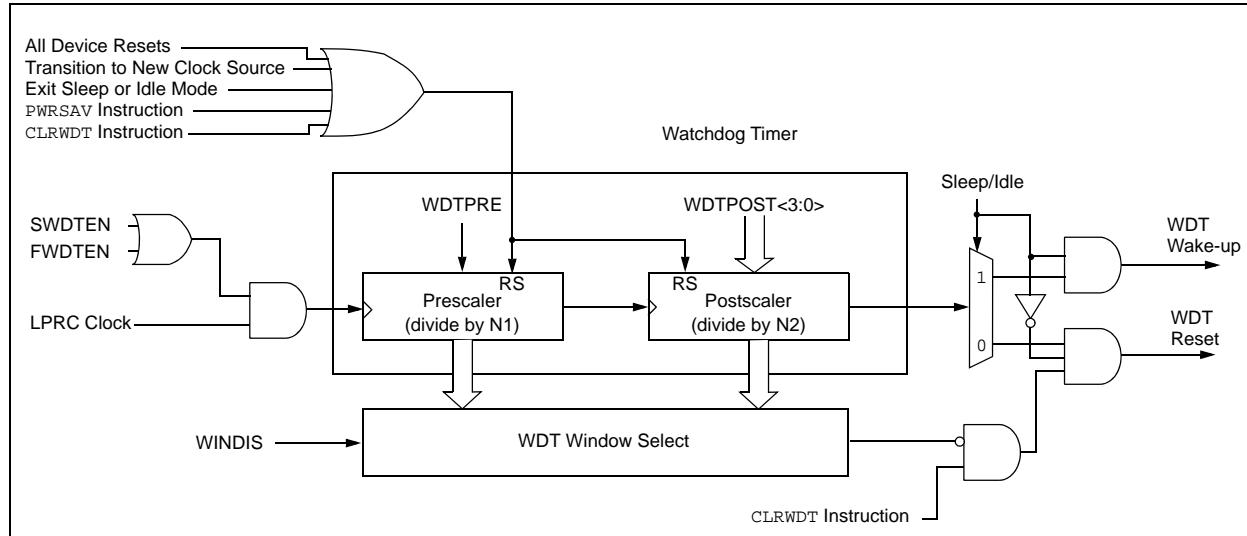
The WDT is enabled or disabled by the FWDTEN Configuration bit in the FWDT Configuration register. When the FWDTEN Configuration bit is set, the WDT is always enabled.

The WDT can be optionally controlled in software when the FWDTEN Configuration bit has been programmed to '0'. The WDT is enabled in software by setting the SWDTEN control bit (RCON<5>). The SWDTEN control bit is cleared on any device Reset. The software WDT option allows the user application to enable the WDT for critical code segments and disable the WDT during non-critical segments for maximum power savings.

**Note:** If the WINDIS bit (FWDT<6>) is cleared, the CLRWDT instruction should be executed by the application software only during the last 1/4 of the WDT period. This CLRWDT window can be determined by using a timer. If a CLRWDT instruction is executed before this window, a WDT Reset occurs.

The WDT flag bit, WDTO (RCON<4>), is not automatically cleared following a WDT time-out. To detect subsequent WDT events, the flag must be cleared in software.

FIGURE 28-2: WDT BLOCK DIAGRAM



## 28.5 JTAG Interface

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices implement a JTAG interface, which supports boundary scan device testing, as well as in-circuit programming. Detailed information on this interface is provided in future revisions of the document.

**Note:** Refer to **Section 24. “Programming and Diagnostics”** (DS70207) of the *dsPIC33F/PIC24H Family Reference Manual* for further information on usage, configuration and operation of the JTAG interface.

## 28.6 In-Circuit Serial Programming

The dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices can be serially programmed while in the end application circuit. This is done with two lines for clock and data and three other lines for power, ground and the programming sequence. Serial programming allows customers to manufacture boards with unprogrammed devices and then program the digital signal controller just before shipping the product. Serial programming also allows the most recent firmware or a custom firmware to be programmed. Refer to the “*dsPIC33F/PIC24H Flash Programming Specification*” (DS70152) for details about In-Circuit Serial Programming (ICSP).

Any of the three pairs of programming clock/data pins can be used:

- PGEC1 and PGED1
- PGEC2 and PGED2
- PGEC3 and PGED3

## 28.7 In-Circuit Debugger

When MPLAB® ICD 2 is selected as a debugger, the in-circuit debugging functionality is enabled. This function allows simple debugging functions when used with MPLAB IDE. Debugging functionality is controlled through the PGECx (Emulation/Debug Clock) and PGEDx (Emulation/Debug Data) pin functions.

Any of the three pairs of debugging clock/data pins can be used:

- PGEC1 and PGED1
- PGEC2 and PGED2
- PGEC3 and PGED3

To use the in-circuit debugger function of the device, the design must implement ICSP connections to MCLR, VDD, Vss, PGC, PGD and the PGECx/PGEDx pin pair. In addition, when the feature is enabled, some of the resources are not available for general use. These resources include the first 80 bytes of data RAM and two I/O pins.

## 28.8 Code Protection and CodeGuard Security

The dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices offer advanced implementation of CodeGuard Security that supports BS, SS and GS while, the dsPIC33FJ32MC302/304 devices offer the intermediate level of CodeGuard Security that supports only BS and GS. CodeGuard Security enables multiple parties to securely share resources (memory, interrupts and peripherals) on a single chip. This feature helps protect individual Intellectual Property in collaborative system designs.

When coupled with software encryption libraries, CodeGuard Security can be used to securely update Flash even when multiple IPs reside on the single chip. The code protection features vary depending on the actual dsPIC33F implemented. The following sections provide an overview of these features.

Secure segment and RAM protection is implemented on the dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 devices. The dsPIC33FJ32MC302/304 devices do not support secure segment and RAM protection.

**Note:** Refer to **Section 23. “CodeGuard™ Security”** (DS70199) of the *dsPIC33F/PIC24H Family Reference Manual* for further information on usage, configuration and operation of CodeGuard Security.

**TABLE 28-3: CODE FLASH SECURITY SEGMENT SIZES FOR 32 KB DEVICES**

CONFIG BITS	BSS<2:0> = x11 0K	BSS<2:0> = x10 1K	BSS<2:0> = x01 4K	BSS<2:0> = x00 8K
<b>SSS&lt;2:0&gt; = x11 0K</b>	VS = 256 IW 00000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 0057FEh  GS = 11008 IW  0157FEh	VS = 256 IW 00000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 0057FEh  BS = 768 IW  0157FEh	VS = 256 IW 00000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 0057FEh  BS = 3840 IW  0157FEh	VS = 256 IW 00000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 0057FEh  BS = 7936 IW  0157FEh

TABLE 28-4: CODE FLASH SECURITY SEGMENT SIZES FOR 64 KB DEVICES

CONFIG BITS	BSS<2:0> = x11 0K	BSS<2:0> = x10 1K	BSS<2:0> = x01 4K	BSS<2:0> = x00 8K
SSS<2:0> = x11 0K	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  GS = 21760 IW  0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  GS = 20992 IW  0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  GS = 17920 IW  0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  GS = 13824 IW  0157FEh
SSS<2:0> = x10 4K	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  SS = 3840 IW  GS = 17920 IW  0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  SS = 3072 IW  GS = 17920 IW  0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  GS = 17920 IW  0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  GS = 13824 IW  0157FEh
SSS<2:0> = x01 8K	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  SS = 7936 IW  GS = 13824 IW  0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  SS = 7168 IW  GS = 13824 IW  0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  SS = 4096 IW  GS = 13824 IW  0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  GS = 13824 IW  0157FEh
SSS<2:0> = x00 16K	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  SS = 16128 IW  GS = 5632 IW  0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  SS = 15360 IW  GS = 5632 IW  0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  SS = 12288 IW  GS = 5632 IW  0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  SS = 8192 IW  GS = 5632 IW  0157FEh

TABLE 28-5: CODE FLASH SECURITY SEGMENT SIZES FOR 128 KB DEVICES

CONFIG BITS	BSS<2:0> = x11 0K	BSS<2:0> = x10 1K	BSS<2:0> = x01 4K	BSS<2:0> = x00 8K
<b>SSS&lt;2:0&gt; = x11 0K</b>	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00FFFEh 010000h 0157FEh  GS = 43776 IW 0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00FFFEh 010000h 0157FEh  GS = 43008 IW 0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00FFFEh 010000h 0157FEh  GS = 39936 IW 0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00FFFEh 010000h 0157FEh  GS = 35840 IW 0157FEh
<b>SSS&lt;2:0&gt; = x10 4K</b>	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  SS = 3840 IW 0157FEh  GS = 39936 IW 0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  SS = 3072 IW 0157FEh  GS = 39936 IW 0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  SS = 4096 IW 0157FEh  GS = 35840 IW 0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00ABFEh  BS = 7936 IW 0157FEh  GS = 35840 IW 0157FEh
<b>SSS&lt;2:0&gt; = x01 8K</b>	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00FFFEh 010000h 0157FEh  SS = 7936 IW 0157FEh  GS = 35840 IW 0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00FFFEh 010000h 0157FEh  SS = 7168 IW 0157FEh  GS = 35840 IW 0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00FFFEh 010000h 0157FEh  SS = 4096 IW 0157FEh  GS = 35840 IW 0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00FFFEh 010000h 0157FEh  BS = 7936 IW 0157FEh  GS = 35840 IW 0157FEh
<b>SSS&lt;2:0&gt; = x00 16K</b>	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00FFFEh 010000h 0157FEh  SS = 16128 IW 0157FEh  GS = 27648 IW 0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00FFFEh 010000h 0157FEh  SS = 15360 IW 0157FEh  GS = 27648 IW 0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00FFFEh 010000h 0157FEh  SS = 12288 IW 0157FEh  GS = 27648 IW 0157FEh	VS = 256 IW 000000h 0001FEh 000200h 0007FEh 000800h 001FFEh 002000h 003FFEh 004000h 007FFEh 008000h 00FFFEh 010000h 0157FEh  BS = 7936 IW 0157FEh  SS = 8192 IW 0157FEh  GS = 27648 IW 0157FEh

## 29.0 INSTRUCTION SET SUMMARY

**Note:** This data sheet summarizes the features of the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the “*dsPIC33F/PIC24H Family Reference Manual*”. Please see the Microchip web site ([www.microchip.com](http://www.microchip.com)) for the latest dsPIC33F/PIC24H Family Reference Manual sections.

The dsPIC33F instruction set is identical to that of the dsPIC30F.

Most instructions are a single program memory word (24 bits). Only three instructions require two program memory locations.

Each single-word instruction is a 24-bit word, divided into an 8-bit opcode, which specifies the instruction type and one or more operands, which further specify the operation of the instruction.

The instruction set is highly orthogonal and is grouped into five basic categories:

- Word or byte-oriented operations
- Bit-oriented operations
- Literal operations
- DSP operations
- Control operations

**Table 29-1** shows the general symbols used in describing the instructions.

The dsPIC33F instruction set summary in **Table 29-2** lists all the instructions, along with the status flags affected by each instruction.

Most word or byte-oriented W register instructions (including barrel shift instructions) have three operands:

- The first source operand, which is typically a register ‘Wb’ without any address modifier
- The second source operand, which is typically a register ‘Ws’ with or without an address modifier
- The destination of the result, which is typically a register ‘Wd’ with or without an address modifier

However, word or byte-oriented file register instructions have two operands:

- The file register specified by the value ‘f’
- The destination, which could be either the file register ‘f’ or the W0 register, which is denoted as ‘WREG’

Most bit-oriented instructions (including simple rotate/shift instructions) have two operands:

- The W register (with or without an address modifier) or file register (specified by the value of ‘Ws’ or ‘f’)
- The bit in the W register or file register (specified by a literal value or indirectly by the contents of register ‘Wb’)

The literal instructions that involve data movement can use some of the following operands:

- A literal value to be loaded into a W register or file register (specified by ‘k’)
- The W register or file register where the literal value is to be loaded (specified by ‘Wb’ or ‘f’)

However, literal instructions that involve arithmetic or logical operations use some of the following operands:

- The first source operand, which is a register ‘Wb’ without any address modifier
- The second source operand, which is a literal value
- The destination of the result (only if not the same as the first source operand), which is typically a register ‘Wd’ with or without an address modifier

The MAC class of DSP instructions can use some of the following operands:

- The accumulator (A or B) to be used (required operand)
- The W registers to be used as the two operands
- The X and Y address space prefetch operations
- The X and Y address space prefetch destinations
- The accumulator write back destination

The other DSP instructions do not involve any multiplication and can include:

- The accumulator to be used (required)
- The source or destination operand (designated as Wso or Wdo, respectively) with or without an address modifier
- The amount of shift specified by a W register ‘Wn’ or a literal value

The control instructions can use some of the following operands:

- A program memory address
- The mode of the table read and table write instructions

Most instructions are a single word. Certain double-word instructions are designed to provide all the required information in these 48 bits. In the second word, the 8 MSbs are '0's. If this second word is executed as an instruction (by itself), it executes as a NOP.

The double-word instructions execute in two instruction cycles.

Most single-word instructions are executed in a single instruction cycle, unless a conditional test is true, or the program counter is changed as a result of the instruction. In these cases, the execution takes two instruction cycles with the additional instruction cycle(s) executed as a NOP. Notable exceptions are the BRA

(unconditional/computed branch), indirect CALL/GOTO, all table reads and writes and RETURN/RETFIE instructions, which are single-word instructions but take two or three cycles. Certain instructions that involve skipping over the subsequent instruction require either two or three cycles if the skip is performed, depending on whether the instruction being skipped is a single-word or two-word instruction. Moreover, double-word moves require two cycles.

**Note:** For more details on the instruction set, refer to the "16-bit MCU and DSC Programmer's Reference Manual" (DS70157).

**TABLE 29-1: SYMBOLS USED IN OPCODE DESCRIPTIONS**

Field	Description
#text	Means literal defined by "text"
(text)	Means "content of text"
[text]	Means "the location addressed by text"
{ }	Optional field or operation
<n:m>	Register bit field
.b	Byte mode selection
.d	Double-Word mode selection
.S	Shadow register select
.w	Word mode selection (default)
Acc	One of two accumulators {A, B}
AWB	Accumulator write back destination address register $\in \{W13, [W13]+ = 2\}$
bit4	4-bit bit selection field (used in word addressed instructions) $\in \{0...15\}$
C, DC, N, OV, Z	MCU Status bits: Carry, Digit Carry, Negative, Overflow, Sticky Zero
Expr	Absolute address, label or expression (resolved by the linker)
f	File register address $\in \{0x0000...0x1FFF\}$
lit1	1-bit unsigned literal $\in \{0,1\}$
lit4	4-bit unsigned literal $\in \{0...15\}$
lit5	5-bit unsigned literal $\in \{0...31\}$
lit8	8-bit unsigned literal $\in \{0...255\}$
lit10	10-bit unsigned literal $\in \{0...255\}$ for Byte mode, $\{0:1023\}$ for Word mode
lit14	14-bit unsigned literal $\in \{0...16384\}$
lit16	16-bit unsigned literal $\in \{0...65535\}$
lit23	23-bit unsigned literal $\in \{0...8388608\}$ ; Lsb must be '0'
None	Field does not require an entry, can be blank
OA, OB, SA, SB	DSP Status bits: ACCA Overflow, ACCB Overflow, ACCA Saturate, ACCB Saturate
PC	Program Counter
Slit10	10-bit signed literal $\in \{-512...511\}$
Slit16	16-bit signed literal $\in \{-32768...32767\}$
Slit6	6-bit signed literal $\in \{-16...16\}$
Wb	Base W register $\in \{W0...W15\}$
Wd	Destination W register $\in \{Wd, [Wd], [Wd++], [Wd--], [+Wd], [-Wd]\}$
Wdo	Destination W register $\in \{Wnd, [Wnd], [Wnd++], [Wnd--], [+Wnd], [-Wnd], [Wnd+Wb]\}$
Wm,Wn	Dividend, Divisor working register pair (direct addressing)

**TABLE 29-1: SYMBOLS USED IN OPCODE DESCRIPTIONS (CONTINUED)**

Field	Description
Wm*Wm	Multiplicand and Multiplier working register pair for Square instructions $\in \{W4 * W4, W5 * W5, W6 * W6, W7 * W7\}$
Wm*Wn	Multiplicand and Multiplier working register pair for DSP instructions $\in \{W4 * W5, W4 * W6, W4 * W7, W5 * W6, W5 * W7, W6 * W7\}$
Wn	One of 16 working registers $\in \{W0...W15\}$
Wnd	One of 16 destination working registers $\in \{W0...W15\}$
Wns	One of 16 source working registers $\in \{W0...W15\}$
WREG	W0 (working register used in file register instructions)
Ws	Source W register $\in \{ Ws, [Ws], [Ws++], [Ws--], [+Ws], [-Ws] \}$
Wso	Source W register $\in \{ Wns, [Wns], [Wns++], [Wns--], [+Wns], [-Wns], [Wns+Wb] \}$
Wx	X data space prefetch address register for DSP instructions $\in \{[W8] += 6, [W8] += 4, [W8] += 2, [W8], [W8] -= 6, [W8] -= 4, [W8] -= 2,$ $[W9] += 6, [W9] += 4, [W9] += 2, [W9], [W9] -= 6, [W9] -= 4, [W9] -= 2,$ $[W9 + W12], none\}$
Wxd	X data space prefetch destination register for DSP instructions $\in \{W4...W7\}$
Wy	Y data space prefetch address register for DSP instructions $\in \{[W10] += 6, [W10] += 4, [W10] += 2, [W10], [W10] -= 6, [W10] -= 4, [W10] -= 2,$ $[W11] += 6, [W11] += 4, [W11] += 2, [W11], [W11] -= 6, [W11] -= 4, [W11] -= 2,$ $[W11 + W12], none\}$
Wyd	Y data space prefetch destination register for DSP instructions $\in \{W4...W7\}$

**TABLE 29-2: INSTRUCTION SET OVERVIEW**

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
1	ADD	ADD Acc	Add Accumulators	1	1	OA,OB,SA,SB
		ADD f	f = f + WREG	1	1	C,DC,N,OV,Z
		ADD f,WREG	WREG = f + WREG	1	1	C,DC,N,OV,Z
		ADD #lit10,Wn	Wd = lit10 + Wd	1	1	C,DC,N,OV,Z
		ADD Wb,Ws,Wd	Wd = Wb + Ws	1	1	C,DC,N,OV,Z
		ADD Wb,#lit5,Wd	Wd = Wb + lit5	1	1	C,DC,N,OV,Z
		ADD Wso,#Slit4,Acc	16-bit Signed Add to Accumulator	1	1	OA,OB,SA,SB
2	ADDC	ADDC f	f = f + WREG + (C)	1	1	C,DC,N,OV,Z
		ADDC f,WREG	WREG = f + WREG + (C)	1	1	C,DC,N,OV,Z
		ADDC #lit10,Wn	Wd = lit10 + Wd + (C)	1	1	C,DC,N,OV,Z
		ADDC Wb,Ws,Wd	Wd = Wb + Ws + (C)	1	1	C,DC,N,OV,Z
		ADDC Wb,#lit5,Wd	Wd = Wb + lit5 + (C)	1	1	C,DC,N,OV,Z
3	AND	AND f	f = f .AND. WREG	1	1	N,Z
		AND f,WREG	WREG = f .AND. WREG	1	1	N,Z
		AND #lit10,Wn	Wd = lit10 .AND. Wd	1	1	N,Z
		AND Wb,Ws,Wd	Wd = Wb .AND. Ws	1	1	N,Z
		AND Wb,#lit5,Wd	Wd = Wb .AND. lit5	1	1	N,Z
4	ASR	ASR f	f = Arithmetic Right Shift f	1	1	C,N,OV,Z
		ASR f,WREG	WREG = Arithmetic Right Shift f	1	1	C,N,OV,Z
		ASR Ws,Wd	Wd = Arithmetic Right Shift Ws	1	1	C,N,OV,Z
		ASR Wb,Wns,Wnd	Wnd = Arithmetic Right Shift Wb by Wns	1	1	N,Z
		ASR Wb,#lit5,Wnd	Wnd = Arithmetic Right Shift Wb by lit5	1	1	N,Z
5	BCLR	BCLR f,#bit4	Bit Clear f	1	1	None
		BCLR Ws,#bit4	Bit Clear Ws	1	1	None
6	BRA	BRA C,Expr	Branch if Carry	1	1 (2)	None
		BRA GE,Expr	Branch if greater than or equal	1	1 (2)	None
		BRA GEU,Expr	Branch if unsigned greater than or equal	1	1 (2)	None
		BRA GT,Expr	Branch if greater than	1	1 (2)	None
		BRA GTU,Expr	Branch if unsigned greater than	1	1 (2)	None
		BRA LE,Expr	Branch if less than or equal	1	1 (2)	None
		BRA LEU,Expr	Branch if unsigned less than or equal	1	1 (2)	None
		BRA LT,Expr	Branch if less than	1	1 (2)	None
		BRA LTU,Expr	Branch if unsigned less than	1	1 (2)	None
		BRA N,Expr	Branch if Negative	1	1 (2)	None
		BRA NC,Expr	Branch if Not Carry	1	1 (2)	None
		BRA NN,Expr	Branch if Not Negative	1	1 (2)	None
		BRA NOV,Expr	Branch if Not Overflow	1	1 (2)	None
		BRA NZ,Expr	Branch if Not Zero	1	1 (2)	None
		BRA OA,Expr	Branch if Accumulator A overflow	1	1 (2)	None
		BRA OB,Expr	Branch if Accumulator B overflow	1	1 (2)	None
		BRA OV,Expr	Branch if Overflow	1	1 (2)	None
7	BSET	BSET f,#bit4	Bit Set f	1	1	None
		BSET Ws,#bit4	Bit Set Ws	1	1	None
		BSW.C Ws,Wb	Write C bit to Ws<Wb>	1	1	None
		BSW.Z Ws,Wb	Write Z bit to Ws<Wb>	1	1	None
		BTG f,#bit4	Bit Toggle f	1	1	None
		BTG Ws,#bit4	Bit Toggle Ws	1	1	None

TABLE 29-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
10	BTSC	BTSC f,#bit4	Bit Test f, Skip if Clear	1	1 (2 or 3)	None
		BTSC Ws,#bit4	Bit Test Ws, Skip if Clear	1	1 (2 or 3)	None
11	BTSS	BTSS f,#bit4	Bit Test f, Skip if Set	1	1 (2 or 3)	None
		BTSS Ws,#bit4	Bit Test Ws, Skip if Set	1	1 (2 or 3)	None
12	BTST	BTST f,#bit4	Bit Test f	1	1	Z
		BTST.C Ws,#bit4	Bit Test Ws to C	1	1	C
		BTST.Z Ws,#bit4	Bit Test Ws to Z	1	1	Z
		BTST.C Ws,Wb	Bit Test Ws<Wb> to C	1	1	C
		BTST.Z Ws,Wb	Bit Test Ws<Wb> to Z	1	1	Z
13	BTSTS	BTSTS f,#bit4	Bit Test then Set f	1	1	Z
		BTSTS.C Ws,#bit4	Bit Test Ws to C, then Set	1	1	C
		BTSTS.Z Ws,#bit4	Bit Test Ws to Z, then Set	1	1	Z
14	CALL	CALL lit23	Call subroutine	2	2	None
		CALL Wn	Call indirect subroutine	1	2	None
15	CLR	CLR f	f = 0x0000	1	1	None
		CLR WREG	WREG = 0x0000	1	1	None
		CLR Ws	Ws = 0x0000	1	1	None
		CLR Acc,Wx,Wxd,Wy,Wyd,AWB	Clear Accumulator	1	1	OA,OB,SA,SB
16	CLRWDT	CLRWDT	Clear Watchdog Timer	1	1	WDTO,Sleep
17	COM	COM f	f = $\bar{f}$	1	1	N,Z
		COM f,WREG	WREG = $\bar{f}$	1	1	N,Z
		COM Ws,Wd	Wd = $\bar{Ws}$	1	1	N,Z
18	CP	CP f	Compare f with WREG	1	1	C,DC,N,OV,Z
		CP Wb,#lit5	Compare Wb with lit5	1	1	C,DC,N,OV,Z
		CP Wb,Ws	Compare Wb with Ws (Wb - Ws)	1	1	C,DC,N,OV,Z
19	CP0	CP0 f	Compare f with 0x0000	1	1	C,DC,N,OV,Z
		CP0 Ws	Compare Ws with 0x0000	1	1	C,DC,N,OV,Z
20	CPB	CPB f	Compare f with WREG, with Borrow	1	1	C,DC,N,OV,Z
		CPB Wb,#lit5	Compare Wb with lit5, with Borrow	1	1	C,DC,N,OV,Z
		CPB Wb,Ws	Compare Wb with Ws, with Borrow (Wb - Ws - C)	1	1	C,DC,N,OV,Z
21	CPSEQ	CPSEQ Wb, Wn	Compare Wb with Wn, skip if =	1	1 (2 or 3)	None
22	CPSGT	CPSGT Wb, Wn	Compare Wb with Wn, skip if >	1	1 (2 or 3)	None
23	CPSLT	CPSLT Wb, Wn	Compare Wb with Wn, skip if <	1	1 (2 or 3)	None
24	CPSNE	CPSNE Wb, Wn	Compare Wb with Wn, skip if ≠	1	1 (2 or 3)	None
25	DAW	DAW Wn	Wn = decimal adjust Wn	1	1	C
26	DEC	DEC f	f = f - 1	1	1	C,DC,N,OV,Z
		DEC f,WREG	WREG = f - 1	1	1	C,DC,N,OV,Z
		DEC Ws,Wd	Wd = Ws - 1	1	1	C,DC,N,OV,Z
27	DEC2	DEC2 f	f = f - 2	1	1	C,DC,N,OV,Z
		DEC2 f,WREG	WREG = f - 2	1	1	C,DC,N,OV,Z
		DEC2 Ws,Wd	Wd = Ws - 2	1	1	C,DC,N,OV,Z
28	DISI	DISI #lit14	Disable Interrupts for k instruction cycles	1	1	None

**TABLE 29-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
29	DIV	DIV.S Wm,Wn	Signed 16/16-bit Integer Divide	1	18	N,Z,C,OV
		DIV.SD Wm,Wn	Signed 32/16-bit Integer Divide	1	18	N,Z,C,OV
		DIV.U Wm,Wn	Unsigned 16/16-bit Integer Divide	1	18	N,Z,C,OV
		DIV.UD Wm,Wn	Unsigned 32/16-bit Integer Divide	1	18	N,Z,C,OV
30	DIVF	DIVF Wm,Wn	Signed 16/16-bit Fractional Divide	1	18	N,Z,C,OV
31	DO	DO #lit14,Expr	Do code to PC + Expr, lit14 + 1 times	2	2	None
		DO Wn,Expr	Do code to PC + Expr, (Wn) + 1 times	2	2	None
32	ED	ED Wm*Wm,Acc,Wx,Wy,Wxd	Euclidean Distance (no accumulate)	1	1	OA,OB,OAB,SA,SB,SAB
33	EDAC	EDAC Wm*Wm,Acc,Wx,Wy,Wxd	Euclidean Distance	1	1	OA,OB,OAB,SA,SB,SAB
34	EXCH	EXCH Wns,Wnd	Swap Wns with Wnd	1	1	None
35	FBCL	FBCL Ws,Wnd	Find Bit Change from Left (MSb) Side	1	1	C
36	FF1L	FF1L Ws,Wnd	Find First One from Left (MSb) Side	1	1	C
37	FF1R	FF1R Ws,Wnd	Find First One from Right (LSb) Side	1	1	C
38	GOTO	GOTO Expr	Go to address	2	2	None
		GOTO Wn	Go to indirect	1	2	None
39	INC	INC f	f = f + 1	1	1	C,DC,N,OV,Z
		INC f,WREG	WREG = f + 1	1	1	C,DC,N,OV,Z
		INC Ws,Wd	Wd = Ws + 1	1	1	C,DC,N,OV,Z
40	INC2	INC2 f	f = f + 2	1	1	C,DC,N,OV,Z
		INC2 f,WREG	WREG = f + 2	1	1	C,DC,N,OV,Z
		INC2 Ws,Wd	Wd = Ws + 2	1	1	C,DC,N,OV,Z
41	IOR	IOR f	f = f .IOR. WREG	1	1	N,Z
		IOR f,WREG	WREG = f .IOR. WREG	1	1	N,Z
		IOR #lit10,Wn	Wd = lit10 .IOR. Wd	1	1	N,Z
		IOR Wb,Ws,Wd	Wd = Wb .IOR. Ws	1	1	N,Z
		IOR Wb,#lit5,Wd	Wd = Wb .IOR. lit5	1	1	N,Z
42	LAC	LAC Wso,#Slit4,Acc	Load Accumulator	1	1	OA,OB,OAB,SA,SB,SAB
43	LINK	LINK #lit14	Link Frame Pointer	1	1	None
44	LSR	LSR f	f = Logical Right Shift f	1	1	C,N,OV,Z
		LSR f,WREG	WREG = Logical Right Shift f	1	1	C,N,OV,Z
		LSR Ws,Wd	Wd = Logical Right Shift Ws	1	1	C,N,OV,Z
		LSR Wb,Wns,Wnd	Wnd = Logical Right Shift Wb by Wns	1	1	N,Z
		LSR Wb,#lit5,Wnd	Wnd = Logical Right Shift Wb by lit5	1	1	N,Z
45	MAC	MAC Wm*Wn,Acc,Wx,Wxd,Wy,Wyd, ,AWB	Multiply and Accumulate	1	1	OA,OB,OAB,SA,SB,SAB
		MAC Wm*Wm,Acc,Wx,Wxd,Wy,Wyd	Square and Accumulate	1	1	OA,OB,OAB,SA,SB,SAB
46	MOV	MOV f,Wn	Move f to Wn	1	1	None
		MOV f	Move f to f	1	1	None
		MOV f,WREG	Move f to WREG	1	1	N,Z
		MOV #lit16,Wn	Move 16-bit literal to Wn	1	1	None
		MOV.b #lit8,Wn	Move 8-bit literal to Wn	1	1	None
		MOV Wn,f	Move Wn to f	1	1	None
		MOV Wso,Wdo	Move Ws to Wd	1	1	None
		MOV WREG,f	Move WREG to f	1	1	None
		MOV.D Wns,Wd	Move Double from W(ns):W(ns+1) to Wd	1	2	None
		MOV.D Ws,Wnd	Move Double from Ws to W(nd+1):W(nd)	1	2	None
47	MOVSAC	MOVSAC Acc,Wx,Wxd,Wy,Wyd,AWB	Prefetch and store accumulator	1	1	None

TABLE 29-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
48	MPY	MPY Wm*Wn,Acc,Wx,Wxd,Wy,Wyd	Multiply Wm by Wn to Accumulator	1	1	OA,OB,OAB, SA,SB,SAB
		MPY Wm*Wn,Acc,Wx,Wxd,Wy,Wyd	Square Wm to Accumulator	1	1	OA,OB,OAB, SA,SB,SAB
49	MPY.N	MPY.N Wm*Wn,Acc,Wx,Wxd,Wy,Wyd	-(Multiply Wm by Wn) to Accumulator	1	1	None
50	MSC	MSC Wm*Wm,Acc,Wx,Wxd,Wy,Wyd ,AWB	Multiply and Subtract from Accumulator	1	1	OA,OB,OAB, SA,SB,SAB
51	MUL	MUL.SS Wb,Ws,Wnd	{Wnd + 1, Wnd} = signed(Wb) * signed(Ws)	1	1	None
		MUL.SU Wb,Ws,Wnd	{Wnd + 1, Wnd} = signed(Wb) * unsigned(Ws)	1	1	None
		MUL.US Wb,Ws,Wnd	{Wnd + 1, Wnd} = unsigned(Wb) * signed(Ws)	1	1	None
		MUL.UU Wb,Ws,Wnd	{Wnd + 1, Wnd} = unsigned(Wb) * unsigned(Ws)	1	1	None
		MUL.SU Wb,#lit5,Wnd	{Wnd + 1, Wnd} = signed(Wb) * unsigned(lit5)	1	1	None
		MUL.UU Wb,#lit5,Wnd	{Wnd + 1, Wnd} = unsigned(Wb) * unsigned(lit5)	1	1	None
		MUL f	W3:W2 = f * WREG	1	1	None
52	NEG	NEG Acc	Negate Accumulator	1	1	OA,OB,OAB, SA,SB,SAB
		NEG f	f = -f + 1	1	1	C,DC,N,OV,Z
		NEG f,WREG	WREG = f + 1	1	1	C,DC,N,OV,Z
		NEG Ws,Wd	Wd = -Ws + 1	1	1	C,DC,N,OV,Z
53	NOP	NOP	No Operation	1	1	None
		NOPR	No Operation	1	1	None
54	POP	POP f	Pop f from Top-of-Stack (TOS)	1	1	None
		POP Wdo	Pop from Top-of-Stack (TOS) to Wdo	1	1	None
		POP.D Wnd	Pop from Top-of-Stack (TOS) to W(nd):W(nd + 1)	1	2	None
		POP.S	Pop Shadow Registers	1	1	All
55	PUSH	PUSH f	Push f to Top-of-Stack (TOS)	1	1	None
		PUSH Wso	Push Wso to Top-of-Stack (TOS)	1	1	None
		PUSH.D Wns	Push W(ns):W(ns + 1) to Top-of-Stack (TOS)	1	2	None
		PUSH.S	Push Shadow Registers	1	1	None
56	PWRSAV	PWRSAV #lit1	Go into Sleep or Idle mode	1	1	WDTO,Sleep
57	RCALL	RCALL Expr	Relative Call	1	2	None
		RCALL Wn	Computed Call	1	2	None
58	REPEAT	REPEAT #lit14	Repeat Next Instruction lit14 + 1 times	1	1	None
		REPEAT Wn	Repeat Next Instruction (Wn) + 1 times	1	1	None
59	RESET	RESET	Software device Reset	1	1	None
60	RETFIE	RETFIE	Return from interrupt	1	3 (2)	None
61	RETLW	RETLW #lit10,Wn	Return with literal in Wn	1	3 (2)	None
62	RETURN	RETURN	Return from Subroutine	1	3 (2)	None
63	RLC	RLC f	f = Rotate Left through Carry f	1	1	C,N,Z
		RLC f,WREG	WREG = Rotate Left through Carry f	1	1	C,N,Z
		RLC Ws,Wd	Wd = Rotate Left through Carry Ws	1	1	C,N,Z
64	RLNC	RLNC f	f = Rotate Left (No Carry) f	1	1	N,Z
		RLNC f,WREG	WREG = Rotate Left (No Carry) f	1	1	N,Z
		RLNC Ws,Wd	Wd = Rotate Left (No Carry) Ws	1	1	N,Z
65	RRC	RRC f	f = Rotate Right through Carry f	1	1	C,N,Z
		RRC f,WREG	WREG = Rotate Right through Carry f	1	1	C,N,Z
		RRC Ws,Wd	Wd = Rotate Right through Carry Ws	1	1	C,N,Z

**TABLE 29-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
66	RRNC	RRNC f	f = Rotate Right (No Carry) f	1	1	N,Z
		RRNC f,WREG	WREG = Rotate Right (No Carry) f	1	1	N,Z
		RRNC Ws,Wd	Wd = Rotate Right (No Carry) Ws	1	1	N,Z
67	SAC	SAC Acc,#Slit4,Wdo	Store Accumulator	1	1	None
		SAC.R Acc,#Slit4,Wdo	Store Rounded Accumulator	1	1	None
68	SE	SE Ws,Wnd	Wnd = sign-extended Ws	1	1	C,N,Z
69	SETM	SETM f	f = 0xFFFF	1	1	None
		SETM WREG	WREG = 0xFFFF	1	1	None
		SETM Ws	Ws = 0xFFFF	1	1	None
70	SFTAC	SFTAC Acc,Wn	Arithmetic Shift Accumulator by (Wn)	1	1	OA,OB,OAB, SA,SB,SAB
		SFTAC Acc,#Slit6	Arithmetic Shift Accumulator by Slit6	1	1	OA,OB,OAB, SA,SB,SAB
71	SL	SL f	f = Left Shift f	1	1	C,N,OV,Z
		SL f,WREG	WREG = Left Shift f	1	1	C,N,OV,Z
		SL Ws,Wd	Wd = Left Shift Ws	1	1	C,N,OV,Z
		SL Wb,Wns,Wnd	Wnd = Left Shift Wb by Wns	1	1	N,Z
		SL Wb,#lit5,Wnd	Wnd = Left Shift Wb by lit5	1	1	N,Z
72	SUB	SUB Acc	Subtract Accumulators	1	1	OA,OB,OAB, SA,SB,SAB
		SUB f	f = f - WREG	1	1	C,DC,N,OV,Z
		SUB f,WREG	WREG = f - WREG	1	1	C,DC,N,OV,Z
		SUB #lit10,Wn	Wn = Wn - lit10	1	1	C,DC,N,OV,Z
		SUB Wb,Ws,Wd	Wd = Wb - Ws	1	1	C,DC,N,OV,Z
		SUB Wb,#lit5,Wd	Wd = Wb - lit5	1	1	C,DC,N,OV,Z
73	SUBB	SUBB f	f = f - WREG - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBB f,WREG	WREG = f - WREG - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBB #lit10,Wn	Wn = Wn - lit10 - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBB Wb,Ws,Wd	Wd = Wb - Ws - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBB Wb,#lit5,Wd	Wd = Wb - lit5 - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
74	SUBR	SUBR f	f = WREG - f	1	1	C,DC,N,OV,Z
		SUBR f,WREG	WREG = WREG - f	1	1	C,DC,N,OV,Z
		SUBR Wb,Ws,Wd	Wd = Ws - Wb	1	1	C,DC,N,OV,Z
		SUBR Wb,#lit5,Wd	Wd = lit5 - Wb	1	1	C,DC,N,OV,Z
75	SUBBR	SUBBR f	f = WREG - f - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBBR f,WREG	WREG = WREG - f - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBBR Wb,Ws,Wd	Wd = Ws - Wb - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
		SUBBR Wb,#lit5,Wd	Wd = lit5 - Wb - ( $\bar{C}$ )	1	1	C,DC,N,OV,Z
76	SWAP	SWAP.b Wn	Wn = nibble swap Wn	1	1	None
		SWAP Wn	Wn = byte swap Wn	1	1	None
77	TBLRDH	TBLRDH Ws,Wd	Read Prog<23:16> to Wd<7:0>	1	2	None
78	TBLRDL	TBLRDL Ws,Wd	Read Prog<15:0> to Wd	1	2	None
79	TBLWTH	TBLWTH Ws,Wd	Write Ws<7:0> to Prog<23:16>	1	2	None
80	TBLWTL	TBLWTL Ws,Wd	Write Ws to Prog<15:0>	1	2	None
81	ULNK	ULNK	Unlink Frame Pointer	1	1	None
82	XOR	XOR f	f = f .XOR. WREG	1	1	N,Z
		XOR f,WREG	WREG = f .XOR. WREG	1	1	N,Z
		XOR #lit10,Wn	Wd = lit10 .XOR. Wd	1	1	N,Z
		XOR Wb,Ws,Wd	Wd = Wb .XOR. Ws	1	1	N,Z
		XOR Wb,#lit5,Wd	Wd = Wb .XOR. lit5	1	1	N,Z
83	ZE	ZE Ws,Wnd	Wnd = Zero-extend Ws	1	1	C,Z,N

## 30.0 DEVELOPMENT SUPPORT

The PIC® microcontrollers and dsPIC® digital signal controllers are supported with a full range of software and hardware development tools:

- Integrated Development Environment
  - MPLAB® IDE Software
- Compilers/Assemblers/Linkers
  - MPLAB C Compiler for Various Device Families
  - HI-TECH C for Various Device Families
  - MPASM™ Assembler
  - MPLINK™ Object Linker/  
MPLIB™ Object Librarian
  - MPLAB Assembler/Linker/Librarian for  
Various Device Families
- Simulators
  - MPLAB SIM Software Simulator
- Emulators
  - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers
  - MPLAB ICD 3
  - PICkit™ 3 Debug Express
- Device Programmers
  - PICkit™ 2 Programmer
  - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards,  
Evaluation Kits, and Starter Kits

## 30.1 MPLAB Integrated Development Environment Software

The MPLAB IDE software brings an ease of software development previously unseen in the 8/16/32-bit microcontroller market. The MPLAB IDE is a Windows® operating system-based application that contains:

- A single graphical interface to all debugging tools
  - Simulator
  - Programmer (sold separately)
  - In-Circuit Emulator (sold separately)
  - In-Circuit Debugger (sold separately)
- A full-featured editor with color-coded context
- A multiple project manager
- Customizable data windows with direct edit of contents
- High-level source code debugging
- Mouse over variable inspection
- Drag and drop variables from source to watch windows
- Extensive on-line help
- Integration of select third party tools, such as IAR C Compilers

The MPLAB IDE allows you to:

- Edit your source files (either C or assembly)
- One-touch compile or assemble, and download to emulator and simulator tools (automatically updates all project information)
- Debug using:
  - Source files (C or assembly)
  - Mixed C and assembly
  - Machine code

MPLAB IDE supports multiple debugging tools in a single development paradigm, from the cost-effective simulators, through low-cost in-circuit debuggers, to full-featured emulators. This eliminates the learning curve when upgrading to tools with increased flexibility and power.

## **30.2 MPLAB C Compilers for Various Device Families**

The MPLAB C Compiler code development systems are complete ANSI C compilers for Microchip's PIC18, PIC24 and PIC32 families of microcontrollers and the dsPIC30 and dsPIC33 families of digital signal controllers. These compilers provide powerful integration capabilities, superior code optimization and ease of use.

For easy source level debugging, the compilers provide symbol information that is optimized to the MPLAB IDE debugger.

## **30.3 HI-TECH C for Various Device Families**

The HI-TECH C Compiler code development systems are complete ANSI C compilers for Microchip's PIC family of microcontrollers and the dsPIC family of digital signal controllers. These compilers provide powerful integration capabilities, omniscient code generation and ease of use.

For easy source level debugging, the compilers provide symbol information that is optimized to the MPLAB IDE debugger.

The compilers include a macro assembler, linker, preprocessor, and one-step driver, and can run on multiple platforms.

## **30.4 MPASM Assembler**

The MPASM Assembler is a full-featured, universal macro assembler for PIC10/12/16/18 MCUs.

The MPASM Assembler generates relocatable object files for the MPLINK Object Linker, Intel® standard HEX files, MAP files to detail memory usage and symbol reference, absolute LST files that contain source lines and generated machine code and COFF files for debugging.

The MPASM Assembler features include:

- Integration into MPLAB IDE projects
- User-defined macros to streamline assembly code
- Conditional assembly for multi-purpose source files
- Directives that allow complete control over the assembly process

## **30.5 MPLINK Object Linker/MLIB Object Librarian**

The MPLINK Object Linker combines relocatable objects created by the MPASM Assembler and the MPLAB C18 C Compiler. It can link relocatable objects from precompiled libraries, using directives from a linker script.

The MLIB Object Librarian manages the creation and modification of library files of precompiled code. When a routine from a library is called from a source file, only the modules that contain that routine will be linked in with the application. This allows large libraries to be used efficiently in many different applications.

The object linker/library features include:

- Efficient linking of single libraries instead of many smaller files
- Enhanced code maintainability by grouping related modules together
- Flexible creation of libraries with easy module listing, replacement, deletion and extraction

## **30.6 MPLAB Assembler, Linker and Librarian for Various Device Families**

MPLAB Assembler produces relocatable machine code from symbolic assembly language for PIC24, PIC32 and dsPIC devices. MPLAB C Compiler uses the assembler to produce its object file. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command line interface
- Rich directive set
- Flexible macro language
- MPLAB IDE compatibility

### **30.7 MPLAB SIM Software Simulator**

The MPLAB SIM Software Simulator allows code development in a PC-hosted environment by simulating the PIC MCUs and dsPIC® DSCs on an instruction level. On any given instruction, the data areas can be examined or modified and stimuli can be applied from a comprehensive stimulus controller. Registers can be logged to files for further run-time analysis. The trace buffer and logic analyzer display extend the power of the simulator to record and track program execution, actions on I/O, most peripherals and internal registers.

The MPLAB SIM Software Simulator fully supports symbolic debugging using the MPLAB C Compilers, and the MPASM and MPLAB Assemblers. The software simulator offers the flexibility to develop and debug code outside of the hardware laboratory environment, making it an excellent, economical software development tool.

### **30.8 MPLAB REAL ICE In-Circuit Emulator System**

MPLAB REAL ICE In-Circuit Emulator System is Microchip's next generation high-speed emulator for Microchip Flash DSC and MCU devices. It debugs and programs PIC® Flash MCUs and dsPIC® Flash DSCs with the easy-to-use, powerful graphical user interface of the MPLAB Integrated Development Environment (IDE), included with each kit.

The emulator is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with either a connector compatible with in-circuit debugger systems (RJ11) or with the new high-speed, noise tolerant, Low-Voltage Differential Signal (LVDS) interconnection (CAT5).

The emulator is field upgradable through future firmware downloads in MPLAB IDE. In upcoming releases of MPLAB IDE, new devices will be supported, and new features will be added. MPLAB REAL ICE offers significant advantages over competitive emulators including low-cost, full-speed emulation, run-time variable watches, trace analysis, complex breakpoints, a ruggedized probe interface and long (up to three meters) interconnection cables.

### **30.9 MPLAB ICD 3 In-Circuit Debugger System**

MPLAB ICD 3 In-Circuit Debugger System is Microchip's most cost effective high-speed hardware debugger/programmer for Microchip Flash Digital Signal Controller (DSC) and microcontroller devices. It debugs and programs PIC® Flash microcontrollers and dsPIC® DSCs with the powerful, yet easy-to-use graphical user interface of MPLAB Integrated Development Environment (IDE).

The MPLAB ICD 3 In-Circuit Debugger probe is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with a connector compatible with the MPLAB ICD 2 or MPLAB REAL ICE systems (RJ-11). MPLAB ICD 3 supports all MPLAB ICD 2 headers.

### **30.10 PICkit 3 In-Circuit Debugger/Programmer and PICkit 3 Debug Express**

The MPLAB PICkit 3 allows debugging and programming of PIC® and dsPIC® Flash microcontrollers at a most affordable price point using the powerful graphical user interface of the MPLAB Integrated Development Environment (IDE). The MPLAB PICkit 3 is connected to the design engineer's PC using a full speed USB interface and can be connected to the target via an Microchip debug (RJ-11) connector (compatible with MPLAB ICD 3 and MPLAB REAL ICE). The connector uses two device I/O pins and the reset line to implement in-circuit debugging and In-Circuit Serial Programming™.

The PICkit 3 Debug Express include the PICkit 3, demo board and microcontroller, hookup cables and CDROM with user's guide, lessons, tutorial, compiler and MPLAB IDE software.

### **30.11 PICkit 2 Development Programmer/Debugger and PICkit 2 Debug Express**

The PICkit™ 2 Development Programmer/Debugger is a low-cost development tool with an easy to use interface for programming and debugging Microchip's Flash families of microcontrollers. The full featured Windows® programming interface supports baseline (PIC10F, PIC12F5xx, PIC16F5xx), midrange (PIC12F6xx, PIC16F), PIC18F, PIC24, dsPIC30, dsPIC33, and PIC32 families of 8-bit, 16-bit, and 32-bit microcontrollers, and many Microchip Serial EEPROM products. With Microchip's powerful MPLAB Integrated Development Environment (IDE) the PICkit™ 2 enables in-circuit debugging on most PIC® microcontrollers. In-Circuit-Debugging runs, halts and single steps the program while the PIC microcontroller is embedded in the application. When halted at a breakpoint, the file registers can be examined and modified.

The PICkit 2 Debug Express include the PICkit 2, demo board and microcontroller, hookup cables and CDROM with user's guide, lessons, tutorial, compiler and MPLAB IDE software.

### **30.12 MPLAB PM3 Device Programmer**

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at VDDMIN and VDDMAX for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages and a modular, detachable socket assembly to support various package types. The ICSP™ cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices and incorporates an MMC card for file storage and data applications.

### **30.13 Demonstration/Development Boards, Evaluation Kits, and Starter Kits**

A wide variety of demonstration, development and evaluation boards for various PIC MCUs and dsPIC DSCs allows quick application development on fully functional systems. Most boards include prototyping areas for adding custom circuitry and provide application firmware and source code for examination and modification.

The boards support a variety of features, including LEDs, temperature sensors, switches, speakers, RS-232 interfaces, LCD displays, potentiometers and additional EEPROM memory.

The demonstration and development boards can be used in teaching environments, for prototyping custom circuits and for learning about various microcontroller applications.

In addition to the PICDEM™ and dsPICDEM™ demonstration/development board series of circuits, Microchip has a line of evaluation kits and demonstration software for analog filter design, KEELOQ® security ICs, CAN, IrDA®, PowerSmart battery management, SEEVAL® evaluation system, Sigma-Delta ADC, flow rate sensing, plus many more.

Also available are starter kits that contain everything needed to experience the specified device. This usually includes a single application and debug capability, all on one board.

Check the Microchip web page ([www.microchip.com](http://www.microchip.com)) for the complete list of demonstration, development and evaluation kits.

## 31.0 ELECTRICAL CHARACTERISTICS

This section provides an overview of dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 electrical characteristics. Additional information will be provided in future revisions of this document as it becomes available.

Absolute maximum ratings for the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 family are listed below. Exposure to these maximum rating conditions for extended periods may affect device reliability. Functional operation of the device at these or any other conditions above the parameters indicated in the operation listings of this specification is not implied.

### Absolute Maximum Ratings<sup>(1)</sup>

Ambient temperature under bias .....	-40°C to +125°C
Storage temperature .....	-65°C to +160°C
Voltage on VDD with respect to Vss .....	-0.3V to +4.0V
Voltage on any pin that is not 5V tolerant with respect to Vss <sup>(4)</sup> .....	-0.3V to (VDD + 0.3V)
Voltage on any 5V tolerant pin with respect to Vss when VDD ≥ 3.0V <sup>(4)</sup> .....	-0.3V to +5.6V
Voltage on any 5V tolerant pin with respect to Vss when VDD < 3.0V <sup>(4)</sup> .....	-0.3V to 3.6V
Maximum current out of Vss pin .....	300 mA
Maximum current into VDD pin <sup>(2)</sup> .....	250 mA
Maximum output current sunk by any I/O pin <sup>(3)</sup> .....	4 mA
Maximum output current sourced by any I/O pin <sup>(3)</sup> .....	4 mA
Maximum current sunk by all ports .....	200 mA
Maximum current sourced by all ports <sup>(2)</sup> .....	200 mA

- Note 1:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.
- 2:** Maximum allowable current is a function of device maximum power dissipation (see [Table 31-2](#)).
- 3:** Exceptions are CLKOUT, which is able to sink/source 25 mA, and the VREF+, VREF-, SCLx, SDAx, PGECx and PGEDx pins, which are able to sink/source 12 mA.
- 4:** See the “[Pin Diagrams](#)” section for 5V tolerant pins.

### 31.1 DC Characteristics

**TABLE 31-1: OPERATING MIPS VS. VOLTAGE**

Characteristic	VDD Range (in Volts)	Temp Range (in °C)	Max MIPS
			dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04
—	3.0-3.6V	-40°C to +85°C	40
—	3.0-3.6V	-40°C to +125°C	40

**TABLE 31-2: THERMAL OPERATING CONDITIONS**

Rating	Symbol	Min	Typ	Max	Unit
Industrial Temperature Devices					
Operating Junction Temperature Range	T <sub>J</sub>	-40	—	+125	°C
Operating Ambient Temperature Range	T <sub>A</sub>	-40	—	+85	°C
Extended Temperature Devices					
Operating Junction Temperature Range	T <sub>J</sub>	-40	—	+155	°C
Operating Ambient Temperature Range	T <sub>A</sub>	-40	—	+125	°C
Power Dissipation:					
Internal chip power dissipation: $P_{INT} = VDD \times (IDD - \sum IOH)$	P <sub>D</sub>	$P_{INT} + PI/O$			W
I/O Pin Power Dissipation: $I/O = \sum (\{VDD - VOH\} \times IOH) + \sum (VOL \times IOL)$					
Maximum Allowed Power Dissipation	P <sub>DMAX</sub>	$(T_J - T_A)/\theta_{JA}$			W

**TABLE 31-3: THERMAL PACKAGING CHARACTERISTICS**

Characteristic	Symbol	Typ	Max	Unit	Notes
Package Thermal Resistance, 44-pin QFN	θ <sub>JA</sub>	30	—	°C/W	1
Package Thermal Resistance, 44-pin TFQP	θ <sub>JA</sub>	40	—	°C/W	1
Package Thermal Resistance, 28-pin SPDIP	θ <sub>JA</sub>	45	—	°C/W	1
Package Thermal Resistance, 28-pin SOIC	θ <sub>JA</sub>	50	—	°C/W	1
Package Thermal Resistance, 28-pin QFN-S	θ <sub>JA</sub>	30	—	°C/W	1

**Note 1:** Junction to ambient thermal resistance, Theta-JA (θ<sub>JA</sub>) numbers are achieved by package simulations.

**TABLE 31-4: DC TEMPERATURE AND VOLTAGE SPECIFICATIONS**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
<b>Operating Voltage</b>							
DC10	<b>Supply Voltage</b>		VDD	—	3.6	V	Industrial and Extended
	VDR	<b>RAM Data Retention Voltage<sup>(2)</sup></b>	1.8	—	—	V	—
DC12	VPOR	<b>V<sub>D</sub>D Start Voltage</b> to ensure internal Power-on Reset signal	—	—	V <sub>SS</sub>	V	—
DC17	SVDD	<b>V<sub>D</sub>D Rise Rate</b> to ensure internal Power-on Reset signal	0.03	—	—	V/ms	0-3.0V in 0.1s

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**2:** This is the limit to which V<sub>D</sub>D may be lowered without losing RAM data.

**TABLE 31-5: DC CHARACTERISTICS: OPERATING CURRENT (IDD)**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ + 85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Parameter No.	Typical <sup>(1)</sup>	Max	Units	Conditions		
<b>Operating Current (IDD)<sup>(2)</sup></b>						
DC20d	18	21	mA	-40°C	3.3V	10 MIPS
DC20a	18	22	mA	+25°C		
DC20b	18	22	mA	+85°C		
DC20c	18	25	mA	+125°C		
DC21d	30	35	mA	-40°C	3.3V	16 MIPS
DC21a	30	34	mA	+25°C		
DC21b	30	34	mA	+85°C		
DC21c	30	36	mA	+125°C		
DC22d	34	42	mA	-40°C	3.3V	20 MIPS
DC22a	34	41	mA	+25°C		
DC22b	34	42	mA	+85°C		
DC22c	35	44	mA	+125°C		
DC23d	49	58	mA	-40°C	3.3V	30 MIPS
DC23a	49	57	mA	+25°C		
DC23b	49	57	mA	+85°C		
DC23c	49	60	mA	+125°C		
DC24d	63	75	mA	-40°C	3.3V	40 MIPS
DC24a	63	74	mA	+25°C		
DC24b	63	74	mA	+85°C		
DC24c	63	76	mA	+125°C		

**Note 1:** Data in "Typical" column is at 3.3V, 25°C unless otherwise stated.

- 2:** The supply current is mainly a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption. The test conditions for all IDD measurements are as follows: OSC1 driven with external square wave from rail to rail. All I/O pins are configured as inputs and pulled to Vss. MCLR = Vdd, WDT and FSCM are disabled. CPU, SRAM, program memory and data memory are operational. No peripheral modules are operating; however, every peripheral is being clocked (PMD bits are all zeroed).

**TABLE 31-6: DC CHARACTERISTICS: IDLE CURRENT (I<sub>IDLE</sub>)**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended		
Parameter No.	Typical <sup>(1)</sup>	Max	Units	Conditions	
<b>Idle Current (I<sub>IDLE</sub>): Core OFF Clock ON Base Current<sup>(2)</sup></b>					
DC40d	8	10	mA	-40°C	3.3V    10 MIPS
DC40a	8	10	mA	+25°C	
DC40b	9	10	mA	+85°C	
DC40c	10	13	mA	+125°C	
DC41d	13	15	mA	-40°C	3.3V    16 MIPS
DC41a	13	15	mA	+25°C	
DC41b	13	16	mA	+85°C	
DC41c	13	19	mA	+125°C	
DC42d	15	18	mA	-40°C	3.3V    20 MIPS
DC42a	16	18	mA	+25°C	
DC42b	16	19	mA	+85°C	
DC42c	17	22	mA	+125°C	
DC43d	23	27	mA	-40°C	3.3V    30 MIPS
DC43a	23	26	mA	+25°C	
DC43b	24	28	mA	+85°C	
DC43c	25	31	mA	+125°C	
DC44d	31	42	mA	-40°C	3.3V    40 MIPS
DC44a	31	36	mA	+25°C	
DC44b	32	39	mA	+85°C	
DC44c	34	43	mA	+125°C	

**Note 1:** Data in "Typical" column is at 3.3V, 25°C unless otherwise stated.

**2:** Base I<sub>IDLE</sub> current is measured with core off, clock on and all modules turned off. Peripheral Module Disable SFR registers are zeroed. All I/O pins are configured as inputs and pulled to V<sub>SS</sub>.

**TABLE 31-7: DC CHARACTERISTICS: POWER-DOWN CURRENT (IPD)**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ + 85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Parameter No.	Typical <sup>(1)</sup>	Max	Units	Conditions		
<b>Power-Down Current (IPD)<sup>(2)</sup></b>						
DC60d	24	68	µA	-40°C	3.3V	Base Power-Down Current <sup>(2,4)</sup>
DC60a	28	87	µA	+25°C		
DC60b	124	292	µA	+85°C		
DC60c	350	1000	µA	+125°C		
DC61d	8	13	µA	-40°C		
DC61a	10	15	µA	+25°C		
DC61b	12	20	µA	+85°C		
DC61c	13	25	µA	+125°C		

**Note 1:** Data in the "Typical" column is at 3.3V, 25°C unless otherwise stated.

- 2:** Base IPD is measured with all peripherals and clocks shut down. All I/Os are configured as inputs and pulled to Vss. WDT, etc., are all switched off and VREGS (RCON<8>) = 1.
- 3:** The Δ current is the additional current consumed when the module is enabled. This current should be added to the base IPD current.
- 4:** These currents are measured on the device containing the most memory in this family.

**TABLE 31-8: DC CHARACTERISTICS: DOZE CURRENT (IDOZE)**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ + 85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Parameter No.	Typical <sup>(1)</sup>	Max	Doze Ratio	Units	Conditions	
DC73a	20	50	1:2	mA	-40°C	3.3V
DC73f	17	30	1:64	mA		
DC73g	17	30	1:128	mA	+25°C	3.3V
DC70a	20	50	1:2	mA		
DC70f	17	30	1:64	mA	+85°C	3.3V
DC70g	17	30	1:128	mA		
DC71a	20	50	1:2	mA	+125°C	3.3V
DC71f	17	30	1:64	mA		
DC71g	17	30	1:128	mA	40 MIPS	40 MIPS
DC72a	21	50	1:2	mA		
DC72f	18	30	1:64	mA	40 MIPS	40 MIPS
DC72g	18	30	1:128	mA		

**Note 1:** Data in the "Typical" column is at 3.3V, 25°C unless otherwise stated.

**TABLE 31-9: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
DI10 DI11 DI15 DI16 DI18 DI19	VIL	<b>Input Low Voltage</b>					
		I/O pins	Vss	—	0.2 VDD	V	
		PMP pins	Vss	—	0.15 VDD	V	PMPTTL = 1
		MCLR	Vss	—	0.2 VDD	V	
		I/O Pins with OSC1 or SOSCI	Vss	—	0.2 VDD	V	
		I/O Pins with SDAx, SCLx	Vss	—	0.3 VDD	V	SMbus disabled
DI20 DI21 DI28 DI29	VIH	<b>Input High Voltage</b>					
		I/O Pins Not 5V Tolerant <sup>(4)</sup>	0.7 VDD	—	VDD	V	—
		I/O Pins 5V Tolerant <sup>(4)</sup>	0.7 VDD	—	5.5	V	
		I/O Pins Not 5V Tolerant with PMP <sup>(4)</sup>	0.24 VDD + 0.8	—	VDD	V	
		I/O Pins 5V Tolerant with PMP <sup>(4)</sup>	0.24 VDD + 0.8	—	5.5	V	
		SDAx, SCLx	0.7 VDD	—	5.5	V	SMbus disabled
DI30	ICNPU	<b>CNx Pull-up Current</b>	50	250	400	μA	VDD = 3.3V, VPIN = VSS

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

- 2:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current can be measured at different input voltages.
- 3:** Negative current is defined as current sourced by the pin.
- 4:** See "[Pin Diagrams](#)" for the 5V tolerant I/O pins.
- 5:** VIL source < (Vss – 0.3). Characterized but not tested.
- 6:** Non-5V tolerant pins VIH source > (VDD + 0.3), 5V tolerant pins VIH source > 5.5V. Characterized but not tested.
- 7:** Digital 5V tolerant pins cannot tolerate any "positive" input injection current from input sources > 5.5V.
- 8:** Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts.
- 9:** Any number and/or combination of I/O pins not excluded under IICL or IICH conditions are permitted provided the mathematical "absolute instantaneous" sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

TABLE 31-9: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS (CONTINUED)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
DI50	IIL	Input Leakage Current <sup>(2,3)</sup> I/O pins 5V Tolerant <sup>(4)</sup>	—	—	$\pm 2$	$\mu\text{A}$	$V_{SS} \leq V_{PIN} \leq V_{DD}$ , Pin at high-impedance
DI51		I/O Pins Not 5V Tolerant <sup>(4)</sup>	—	—	$\pm 1$	$\mu\text{A}$	$V_{SS} \leq V_{PIN} \leq V_{DD}$ , Pin at high-impedance, $40^\circ\text{C} \leq TA \leq 85^\circ\text{C}$
DI51a		I/O Pins Not 5V Tolerant <sup>(4)</sup>	—	—	$\pm 2$	$\mu\text{A}$	Shared with external reference pins, $40^\circ\text{C} \leq TA \leq 85^\circ\text{C}$
DI51b		I/O Pins Not 5V Tolerant <sup>(4)</sup>	—	—	$\pm 3.5$	$\mu\text{A}$	$V_{SS} \leq V_{PIN} \leq V_{DD}$ , Pin at high-impedance, $-40^\circ\text{C} \leq TA \leq 125^\circ\text{C}$
DI51c		I/O Pins Not 5V Tolerant <sup>(4)</sup>	—	—	$\pm 8$	$\mu\text{A}$	Analog pins shared with external reference pins, $-40^\circ\text{C} \leq TA \leq 125^\circ\text{C}$
DI55		MCLR	—	—	$\pm 2$	$\mu\text{A}$	$V_{SS} \leq V_{PIN} \leq V_{DD}$
DI56		OSC1	—	—	$\pm 2$	$\mu\text{A}$	$V_{SS} \leq V_{PIN} \leq V_{DD}$ , XT and HS modes

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

- 2:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current can be measured at different input voltages.
- 3:** Negative current is defined as current sourced by the pin.
- 4:** See “[Pin Diagrams](#)” for the 5V tolerant I/O pins.
- 5:** VIL source < ( $V_{SS} - 0.3$ ). Characterized but not tested.
- 6:** Non-5V tolerant pins VIH source > ( $V_{DD} + 0.3$ ), 5V tolerant pins VIH source > 5.5V. Characterized but not tested.
- 7:** Digital 5V tolerant pins cannot tolerate any “positive” input injection current from input sources > 5.5V.
- 8:** Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts.
- 9:** Any number and/or combination of I/O pins not excluded under IICL or IICH conditions are permitted provided the mathematical “absolute instantaneous” sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

**TABLE 31-9: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS (CONTINUED)**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
DI60a	IICL	<b>Input Low Injection Current</b>	0	—	-5 <sup>(5,8)</sup>	mA	All pins except VDD, Vss, AVDD, AVss, MCLR, VCAP, SOSCI, SOSCO, and RB14
DI60b	IICH	<b>Input High Injection Current</b>	0	—	+5 <sup>(6,7,8)</sup>	mA	All pins except VDD, Vss, AVDD, AVss, MCLR, VCAP, SOSCI, SOSCO, RB14, and digital 5V-tolerant designated pins
DI60c	ΣIICT	<b>Total Input Injection Current (sum of all I/O and control pins)</b>	-20 <sup>(9)</sup>	—	+20 <sup>(9)</sup>	mA	Absolute instantaneous sum of all ± input injection currents from all I/O pins $( IICL  +  IICH ) \leq \Sigma IICT$

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

- 2:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current can be measured at different input voltages.
- 3:** Negative current is defined as current sourced by the pin.
- 4:** See “[Pin Diagrams](#)” for the 5V tolerant I/O pins.
- 5:** VIL source < (Vss – 0.3). Characterized but not tested.
- 6:** Non-5V tolerant pins VIH source > (VDD + 0.3), 5V tolerant pins VIH source > 5.5V. Characterized but not tested.
- 7:** Digital 5V tolerant pins cannot tolerate any “positive” input injection current from input sources > 5.5V.
- 8:** Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts.
- 9:** Any number and/or combination of I/O pins not excluded under IICL or IICH conditions are permitted provided the mathematical “absolute instantaneous” sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

**TABLE 31-10: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
DO10	VOL	Output Low Voltage I/O ports OSC2/CLKO	—	—	0.4	V	IOL = 2 mA, VDD = 3.3V
DO16			—	—	0.4	V	IOL = 2 mA, VDD = 3.3V
DO20	VOH	Output High Voltage I/O ports OSC2/CLKO	2.40	—	—	V	IOH = -2.3 mA, VDD = 3.3V
DO26			2.41	—	—	V	IOH = -1.3 mA, VDD = 3.3V

**TABLE 31-11: ELECTRICAL CHARACTERISTICS: BOR**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min <sup>(1)</sup>	Typ	Max	Units	Conditions
BO10	VBOR	BOR Event on VDD transition high-to-low	2.40	—	2.55	V	VDD

**Note 1:** Parameters are for design guidance only and are not tested in manufacturing.

**TABLE 31-12: DC CHARACTERISTICS: PROGRAM MEMORY**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
D130	EP	Program Flash Memory Cell Endurance	10,000	—	—	E/W	-40°C to +125°C
D131	VPR	VDD for Read	V <sub>MIN</sub>	—	3.6	V	V <sub>MIN</sub> = Minimum operating voltage
D132B	VPEW	VDD for Self-Timed Write	V <sub>MIN</sub>	—	3.6	V	V <sub>MIN</sub> = Minimum operating voltage
D134	TRETD	Characteristic Retention	20	—	—	Year	Provided no other specifications are violated, -40°C to +125°C
D135	IDDP	Supply Current during Programming	—	10	—	mA	—
D136a	TRW	Row Write Time	1.32	—	1.74	ms	TRW = 11064 FRC cycles, TA = +85°C, See <b>Note 2</b>
D136b	TRW	Row Write Time	1.28	—	1.79	ms	TRW = 11064 FRC cycles, TA = +125°C, See <b>Note 2</b>
D137a	TPE	Page Erase Time	20.1	—	26.5	ms	TPE = 168517 FRC cycles, TA = +85°C, See <b>Note 2</b>
D137b	TPE	Page Erase Time	19.5	—	27.3	ms	TPE = 168517 FRC cycles, TA = +125°C, See <b>Note 2</b>
D138a	TWW	Word Write Cycle Time	42.3	—	55.9	μs	TWW = 355 FRC cycles, TA = +85°C, See <b>Note 2</b>
D138b	TWW	Word Write Cycle Time	41.1	—	57.6	μs	TWW = 355 FRC cycles, TA = +125°C, See <b>Note 2</b>

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

- 2:** Other conditions: FRC = 7.37 MHz, TUN<5:0> = b'011111 (for Min), TUN<5:0> = b'100000 (for Max). This parameter depends on the FRC accuracy (see [Table 31-19](#)) and the value of the FRC Oscillator Tuning register (see [Register 9-4](#)). For complete details on calculating the Minimum and Maximum time see [Section 5.3 “Programming Operations”](#).

**TABLE 31-13: INTERNAL VOLTAGE REGULATOR SPECIFICATIONS**

Standard Operating Conditions (unless otherwise stated):							
Param No.	Symbol	Characteristics	Min	Typ	Max	Units	Comments
—	CEFC	External Filter Capacitor Value <sup>(1)</sup>	4.7	10	—	μF	Capacitor must be low series resistance (< 5 ohms)

**Note 1:** Typical V<sub>CAP</sub> voltage = 2.5V when V<sub>DD</sub> ≥ V<sub>DDMIN</sub>.

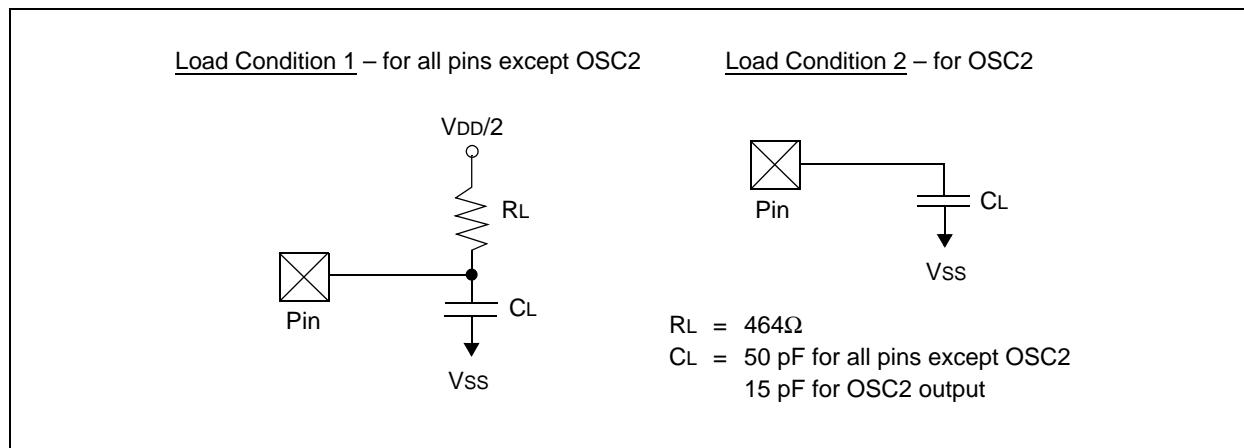
### 31.2 AC Characteristics and Timing Parameters

This section defines dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 AC characteristics and timing parameters.

**TABLE 31-14: TEMPERATURE AND VOLTAGE SPECIFICATIONS – AC**

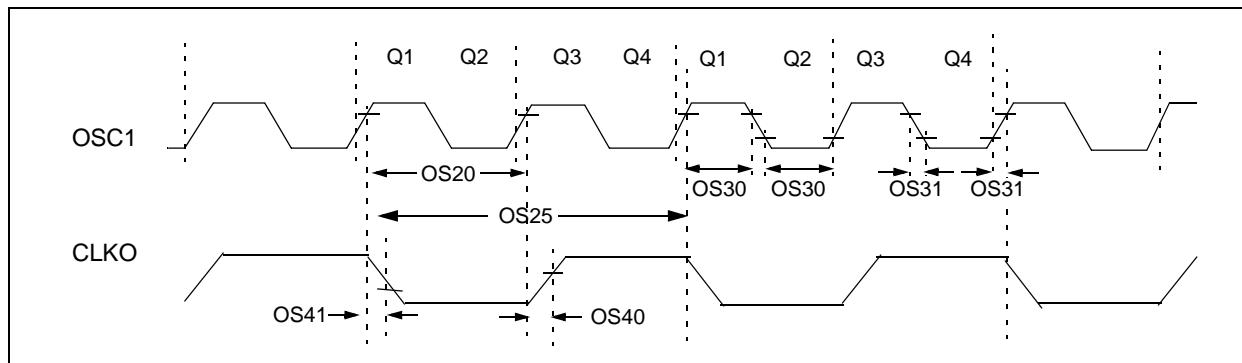
<b>AC CHARACTERISTICS</b>	<b>Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)</b> Operating temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq \text{TA} \leq +125^{\circ}\text{C}$ for Extended Operating voltage VDD range as described in <a href="#">Table 31-1</a> .
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**FIGURE 31-1: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS**



**TABLE 31-15: CAPACITIVE LOADING REQUIREMENTS ON OUTPUT PINS**

Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
DO50	Cosco	OSC2/SOSCO pin	—	—	15	pF	In XT and HS modes when external clock is used to drive OSC1
DO56	C <sub>IO</sub>	All I/O pins and OSC2	—	—	50	pF	EC mode
DO58	C <sub>B</sub>	SCL <sub>x</sub> , SDA <sub>x</sub>	—	—	400	pF	In I <sup>2</sup> C™ mode

**FIGURE 31-2: EXTERNAL CLOCK TIMING****TABLE 31-16: EXTERNAL CLOCK TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symb	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
OS10	FIN	External CLKI Frequency (External clocks allowed only in EC and ECPLL modes)	DC	—	40	MHz	EC
		Oscillator Crystal Frequency	3.5 10	— —	10 40 33	MHz MHz kHz	XT HS Sosc
OS20	TOSC	Tosc = 1/Fosc	12.5	—	DC	ns	—
OS25	TCY	Instruction Cycle Time <sup>(2)</sup>	25	—	DC	ns	—
OS30	TosL, TosH	External Clock in (OSC1) High or Low Time	0.375 x Tosc	—	0.625 x Tosc	ns	EC
OS31	TosR, TosF	External Clock in (OSC1) Rise or Fall Time	—	—	20	ns	EC
OS40	TckR	CLKO Rise Time <sup>(3)</sup>	—	5.2	—	ns	—
OS41	TckF	CLKO Fall Time <sup>(3)</sup>	—	5.2	—	ns	—
OS42	GM	External Oscillator Transconductance <sup>(4)</sup>	14	16	18	mA/V	VDD = 3.3V TA = +25°C

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**2:** Instruction cycle period (TCY) equals two times the input oscillator time-base period. All specified values are based on characterization data for that particular oscillator type under standard operating conditions with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at "min." values with an external clock applied to the OSC1/CLKI pin. When an external clock input is used, the "max." cycle time limit is "DC" (no clock) for all devices.

**3:** Measurements are taken in EC mode. The CLKO signal is measured on the OSC2 pin.

**4:** Data for this parameter is Preliminary. This parameter is characterized, but not tested in manufacturing.

**TABLE 31-17: PLL CLOCK TIMING SPECIFICATIONS (VDD = 3.0V TO 3.6V)**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended					
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
OS50	FPLL1	PLL Voltage Controlled Oscillator (VCO) Input Frequency Range	0.8	—	8	MHz	ECPLL, XTPLL modes
OS51	FSYS	On-Chip VCO System Frequency	100	—	200	MHz	—
OS52	TLOCK	PLL Start-up Time (Lock Time)	0.9	1.5	3.1	ms	—
OS53	DCLK	CLKO Stability (Jitter) <sup>(2)</sup>	-3	0.5	3	%	Measured over 100 ms period

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**2:** These parameters are characterized by similarity, but are not tested in manufacturing. This specification is based on clock cycle by clock cycle measurements. To calculate the effective jitter for individual time bases or communication clocks use this formula:

$$\text{Peripheral Clock Jitter} = \frac{DCLK}{\sqrt{\left(\frac{FOSC}{\text{Peripheral Bit Rate Clock}}\right)}}$$

For example: Fosc = 32 MHz, DCLK = 3%, SPI bit rate clock, (i.e., SCK) is 2 MHz.

$$\text{SPI SCK Jitter} = \left[ \frac{DCLK}{\sqrt{\left(\frac{32 \text{ MHz}}{2 \text{ MHz}}\right)}} \right] = \left[ \frac{3\%}{\sqrt{16}} \right] = \left[ \frac{3\%}{4} \right] = 0.75\%$$

**TABLE 31-18: AC CHARACTERISTICS: INTERNAL RC ACCURACY**

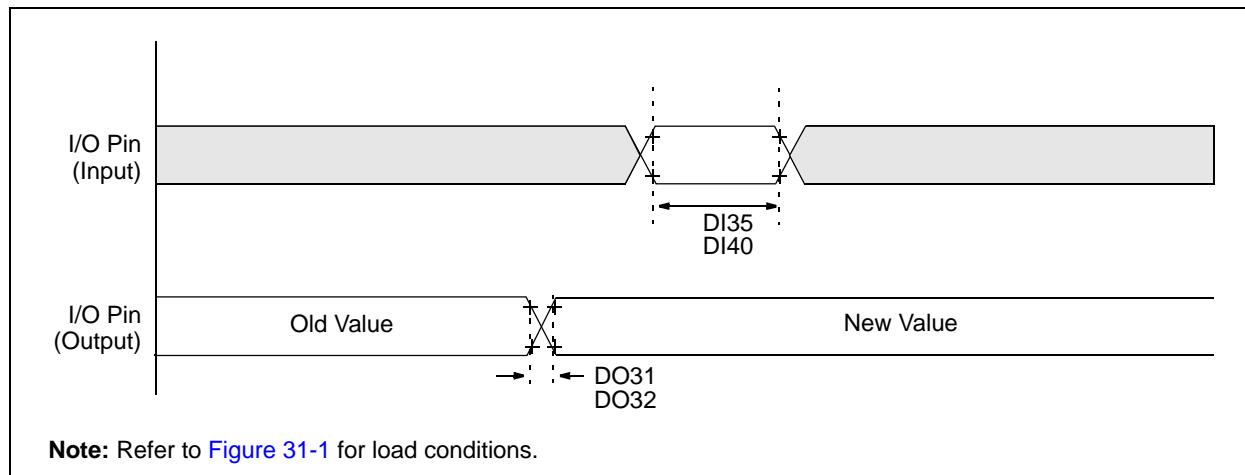
AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for industrial -40°C ≤ TA ≤ +125°C for Extended					
Param No.	Characteristic	Min	Typ	Max	Units	Conditions	
<b>Internal FRC Accuracy @ FRC Frequency = 7.37 MHz<sup>(1)</sup></b>							
F20	FRC	-2	—	+2	%	-40°C ≤ TA ≤ +85°C	VDD = 3.0-3.6V
	FRC	-5	—	+5	%	-40°C ≤ TA ≤ +125°C	VDD = 3.0-3.6V

**Note 1:** Frequency calibrated at 25°C and 3.3V. TUN bits can be used to compensate for temperature drift.

**TABLE 31-19: INTERNAL RC ACCURACY**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended					
Param No.	Characteristic	Min	Typ	Max	Units	Conditions	
<b>LPRC @ 32.768 kHz<sup>(1)</sup></b>							
F21	LPRC	-20	±6	+20	%	-40°C ≤ TA ≤ +85°C	VDD = 3.0-3.6V
	LPRC	-30	—	+30	%	-40°C ≤ TA ≤ +125°C	VDD = 3.0-3.6V

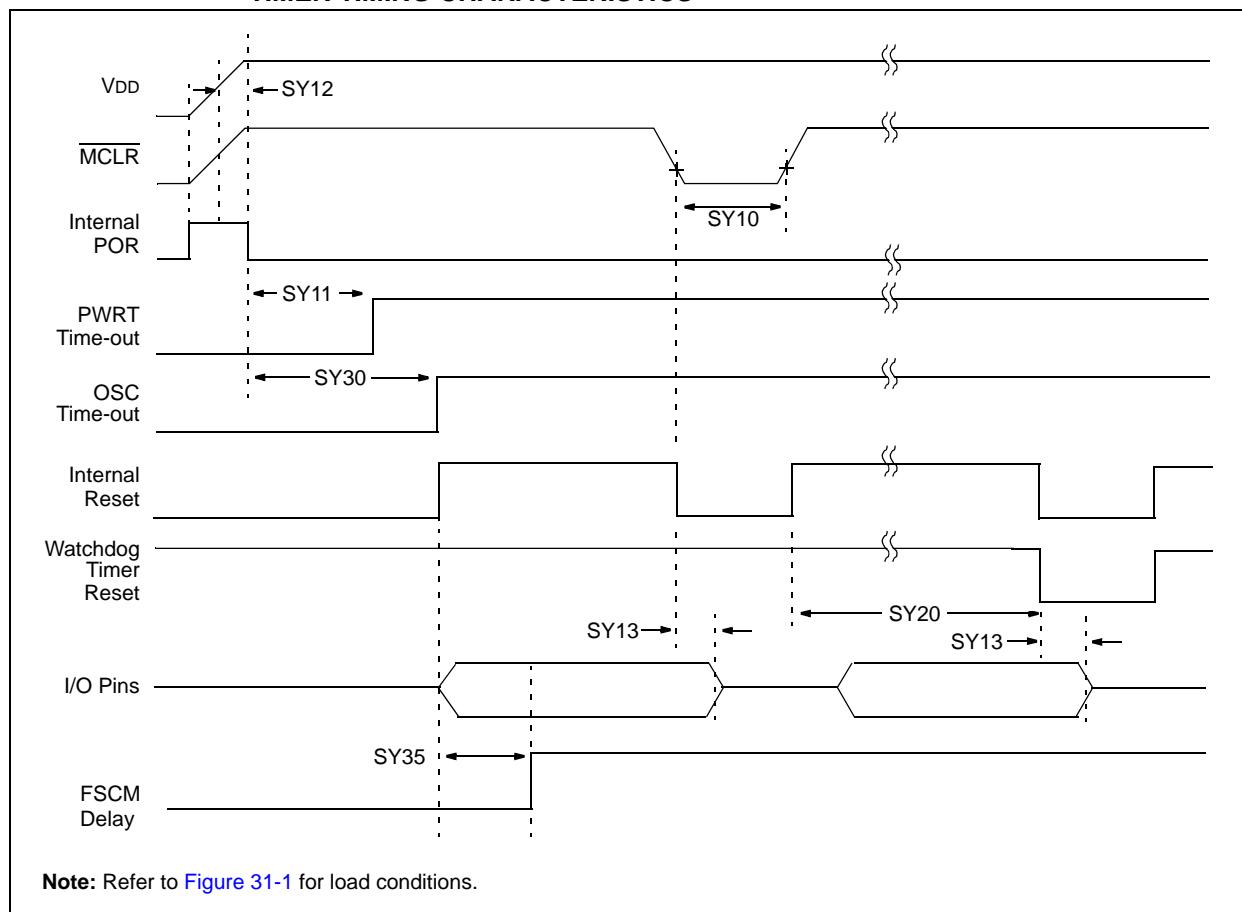
**Note 1:** Change of LPRC frequency as VDD changes.

**FIGURE 31-3: I/O TIMING CHARACTERISTICS****TABLE 31-20: I/O TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
DO31	TioR	Port Output Rise Time	—	10	25	ns	—
DO32	TioF	Port Output Fall Time	—	10	25	ns	—
DI35	TINP	INTx Pin High or Low Time (input)	20	—	—	ns	—
DI40	TRBP	CNx High or Low Time (input)	2	—	—	Tcy	—

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**FIGURE 31-4: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER AND POWER-UP TIMER TIMING CHARACTERISTICS**

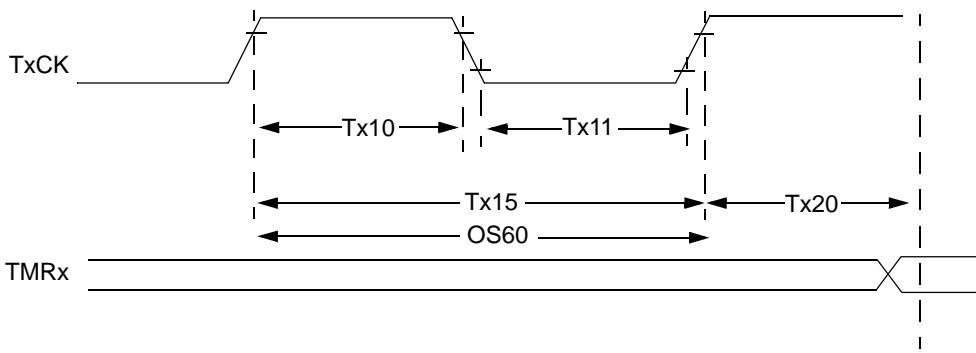


**TABLE 31-21: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER, POWER-UP TIMER TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
SY10	TmCL	MCLR Pulse Width (low)	2	—	—	μs	-40°C to +85°C
SY11	TPWRT	Power-up Timer Period	—	2 4 8 16 32 64 128	—	ms	-40°C to +85°C User programmable
SY12	TPOR	Power-on Reset Delay	3	10	30	μs	-40°C to +85°C
SY13	Tioz	I/O High-Impedance from MCLR Low or Watchdog Timer Reset	0.68	0.72	1.2	μs	—
SY20	TWDT1	Watchdog Timer Time-out Period	—	—	—	—	See <a href="#">Section 28.4 “Watchdog Timer (WDT)”</a> and LPRC specification F21 ( <a href="#">Table 31-19</a> )
SY30	TOST	Oscillator Start-up Time	—	1024 Tosc	—	—	Tosc = OSC1 period
SY35	TFSCM	Fail-Safe Clock Monitor Delay	—	500	900	μs	-40°C to +85°C

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.

**FIGURE 31-5: TIMER1, 2 AND 3 EXTERNAL CLOCK TIMING CHARACTERISTICS**

**Note:** Refer to Figure 31-1 for load conditions.

**TABLE 31-22: TIMER1 EXTERNAL CLOCK TIMING REQUIREMENTS<sup>(1)</sup>**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
TA10	TTxH	TxCK High Time	Synchronous, no prescaler	T <sub>CY</sub> + 20	—	—	ns
			Synchronous, with prescaler	(T <sub>CY</sub> + 20)/N	—	—	ns
			Asynchronous	20	—	—	ns
TA11	TTxL	TxCK Low Time	Synchronous, no prescaler	(T <sub>CY</sub> + 20)	—	—	ns
			Synchronous, with prescaler	(T <sub>CY</sub> + 20)/N	—	—	ns
			Asynchronous	20	—	—	ns
TA15	TTxP	TxCK Input Period	Synchronous, no prescaler	2 T <sub>CY</sub> + 40	—	—	ns
			Synchronous, with prescaler	Greater of: 40 ns or (2 T <sub>CY</sub> + 40)/N	—	—	N = prescale value (1, 8, 64, 256)
			Asynchronous	40	—	—	ns
OS60	Ft1	SOSCI/T1CK Oscillator Input frequency Range (oscillator enabled by setting bit TCS (T1CON<1>))	DC	—	50	kHz	—
TA20	TCKEXTMRL	Delay from External TxCK Clock Edge to Timer Increment	0.75 T <sub>CY</sub> + 40	—	1.75 T <sub>CY</sub> + 40	—	—

**Note 1:** Timer1 is a Type A.

**TABLE 31-23: TIMER2 AND TIMER4 EXTERNAL CLOCK TIMING REQUIREMENTS**

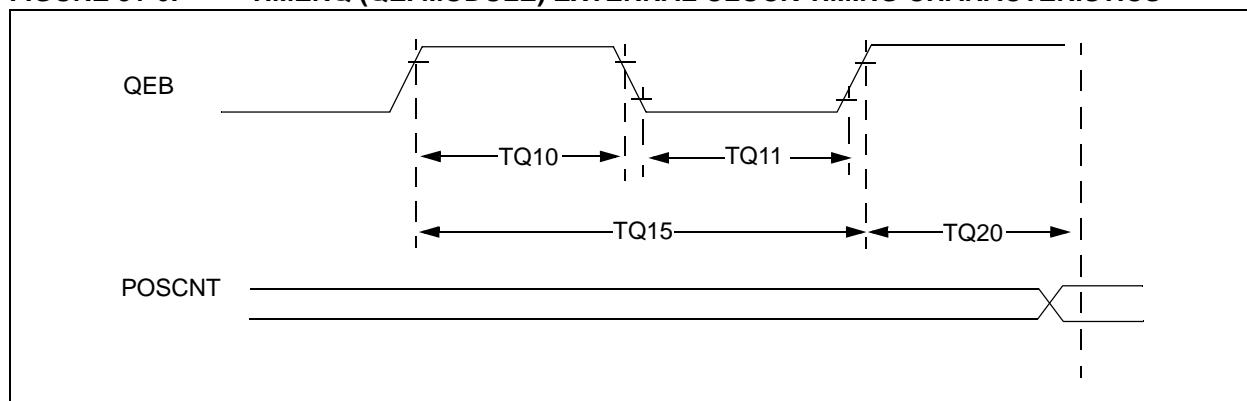
AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)					
Param No.	Symbol	Characteristic <sup>(1)</sup>		Min	Typ	Max	Units	Conditions
TB10	TtxH	TxCK High Time	Synchronous mode	Greater of: 20 or (TCY + 20)/N	—	—	ns	Must also meet parameter TB15 N = prescale value (1, 8, 64, 256)
TB11	TtxL	TxCK Low Time	Synchronous mode	Greater of: 20 or (TCY + 20)/N	—	—	ns	Must also meet parameter TB15 N = prescale value (1, 8, 64, 256)
TB15	TtxP	TxCK Input Period	Synchronous mode	Greater of: 40 or (2 TCY + 40)/N	—	—	ns	N = prescale value (1, 8, 64, 256)
TB20	TCKEXTMRL	Delay from External TxCK Clock Edge to Timer Increment		0.75 TCY + 40	—	1.75 TCY + 40	ns	—

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**TABLE 31-24: TIMER3 AND TIMER5 EXTERNAL CLOCK TIMING REQUIREMENTS**

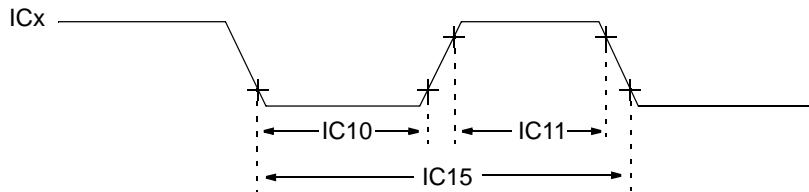
AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)					
Param No.	Symbol	Characteristic <sup>(1)</sup>		Min	Typ	Max	Units	Conditions
TC10	TtxH	TxCK High Time	Synchronous	TCY + 20	—	—	ns	Must also meet parameter TC15
TC11	TtxL	TxCK Low Time	Synchronous	TCY + 20	—	—	ns	Must also meet parameter TC15
TC15	TtxP	TxCK Input Period	Synchronous, with prescaler	2 TCY + 40	—	—	ns	—
TC20	TCKEXTMRL	Delay from External TxCK Clock Edge to Timer Increment		0.75 TCY + 40	—	1.75 TCY + 40	ns	—

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**FIGURE 31-6: TIMERQ (QEI MODULE) EXTERNAL CLOCK TIMING CHARACTERISTICS****TABLE 31-25: QEI MODULE EXTERNAL CLOCK TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
TQ10	TtQH	TQCK High Time Synchronous, with prescaler	TCY + 20		—	ns	Must also meet parameter TQ15
TQ11	TtQL	TQCK Low Time Synchronous, with prescaler	TCY + 20		—	ns	Must also meet parameter TQ15
TQ15	TtQP	TQCP Input Period Synchronous, with prescaler	2 * TCY + 40		—	ns	—
TQ20	TCKEXTMRL	Delay from External TxCK Clock Edge to Timer Increment	0.5 TCY		1.5 TCY	—	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

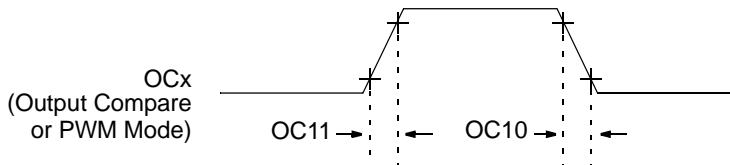
**FIGURE 31-7: INPUT CAPTURE (CAPx) TIMING CHARACTERISTICS**

**Note:** Refer to [Figure 31-1](#) for load conditions.

**TABLE 31-26: INPUT CAPTURE TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>		Min	Max	Units	Conditions
IC10	TccL	ICx Input Low Time	No Prescaler	0.5 TCY + 20	—	ns	
			With Prescaler	10	—	ns	
IC11	TccH	ICx Input High Time	No Prescaler	0.5 TCY + 20	—	ns	
			With Prescaler	10	—	ns	
IC15	TccP	ICx Input Period		(TCY + 40)/N	—	ns	N = prescale value (1, 4, 16)

**Note 1:** These parameters are characterized but not tested in manufacturing.

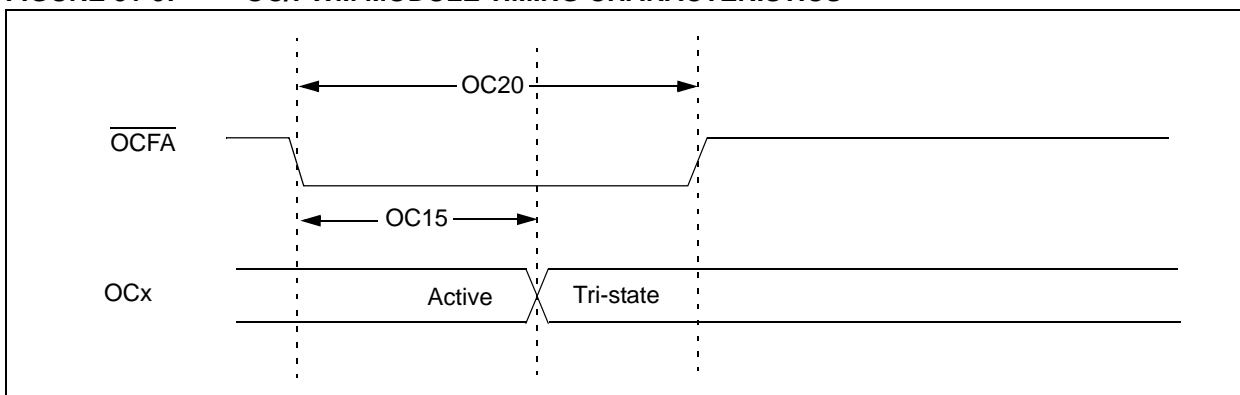
**FIGURE 31-8: OUTPUT COMPARE MODULE (OCx) TIMING CHARACTERISTICS**

**Note:** Refer to [Figure 31-1](#) for load conditions.

**TABLE 31-27: OUTPUT COMPARE MODULE TIMING REQUIREMENTS**

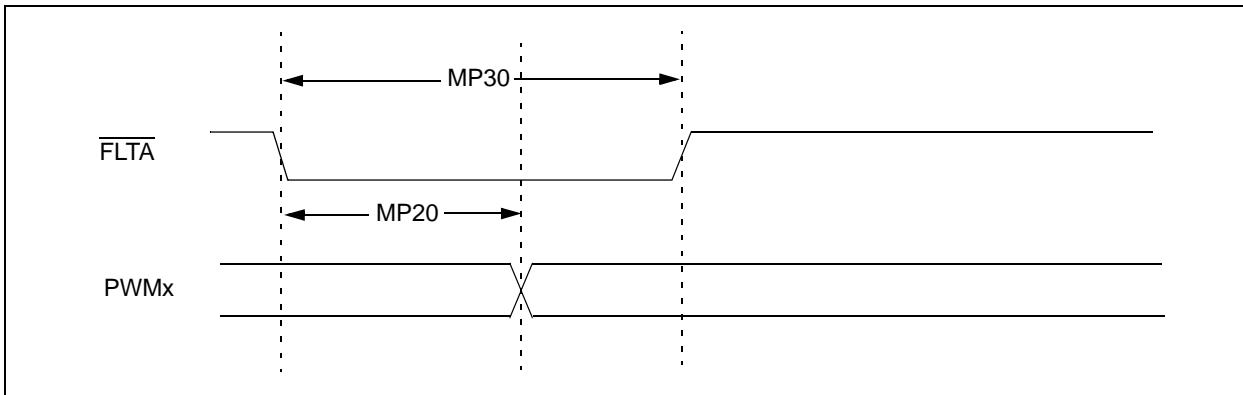
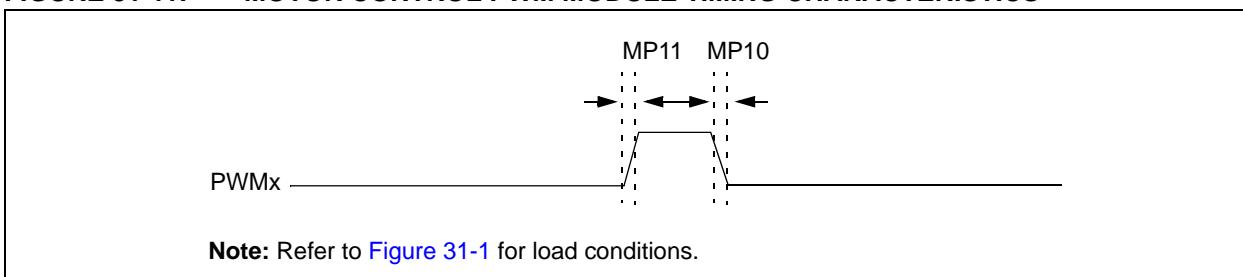
AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
OC10	TccF	OCx Output Fall Time	—	—	—	ns	See parameter D032
OC11	TccR	OCx Output Rise Time	—	—	—	ns	See parameter D031

**Note 1:** These parameters are characterized but not tested in manufacturing.

**FIGURE 31-9:** OC/PWM MODULE TIMING CHARACTERISTICS**TABLE 31-28: SIMPLE OC/PWM MODE TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq TA \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq TA \leq +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
OC15	TFD	Fault Input to PWM I/O Change	—	—	TCY + 20	ns	—
OC20	TFLT	Fault Input Pulse Width	TCY + 20	—	—	ns	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

**FIGURE 31-10: MOTOR CONTROL PWM MODULE FAULT TIMING CHARACTERISTICS****FIGURE 31-11: MOTOR CONTROL PWM MODULE TIMING CHARACTERISTICS****TABLE 31-29: MOTOR CONTROL PWM MODULE TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
MP10	TFPWM	PWM Output Fall Time	—	—	—	ns	See parameter DO32
MP11	TRPWM	PWM Output Rise Time	—	—	—	ns	See parameter DO31
MP20	TFD	Fault Input ↓to PWM I/O Change	—	—	50	ns	—
MP30	TFH	Minimum Pulse Width	50	—	—	ns	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

FIGURE 31-12: QEA/QEB INPUT CHARACTERISTICS

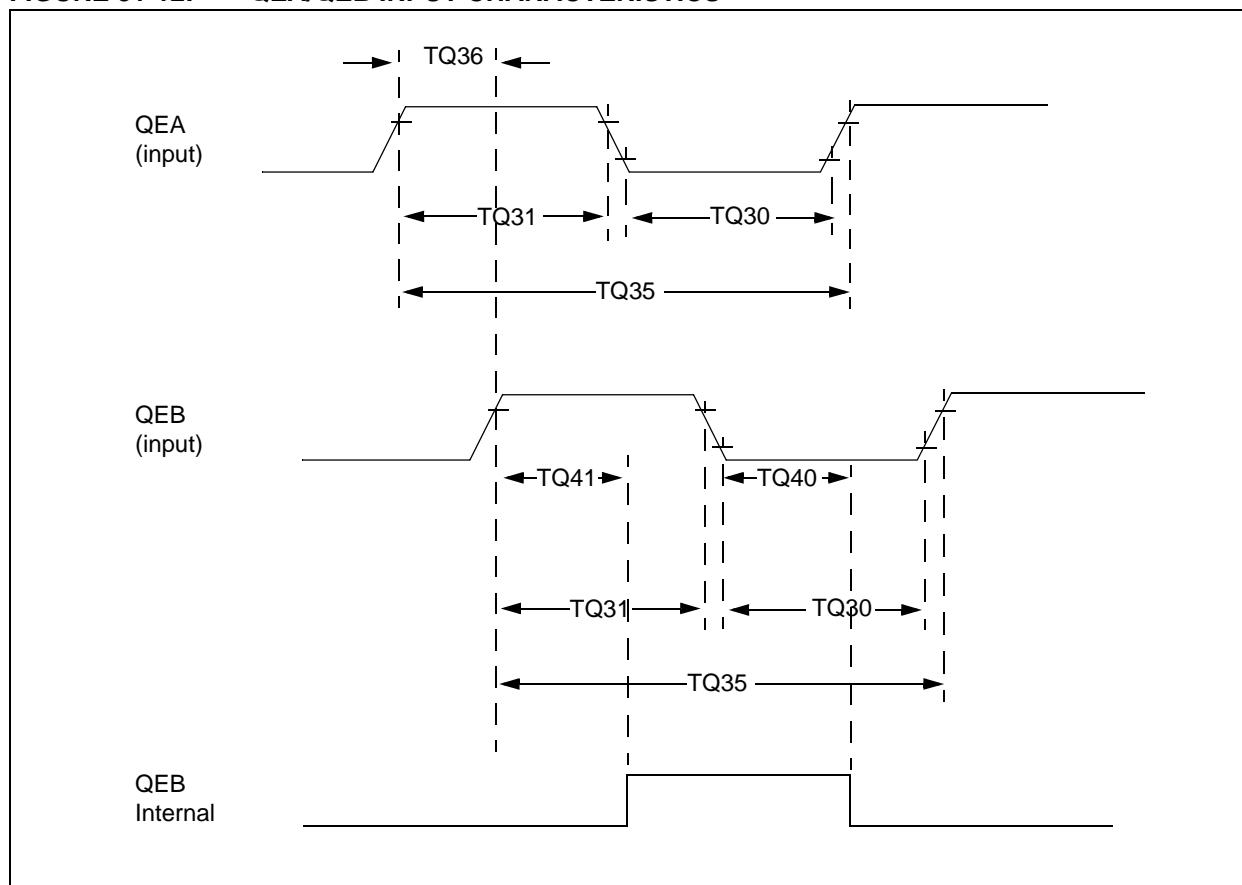


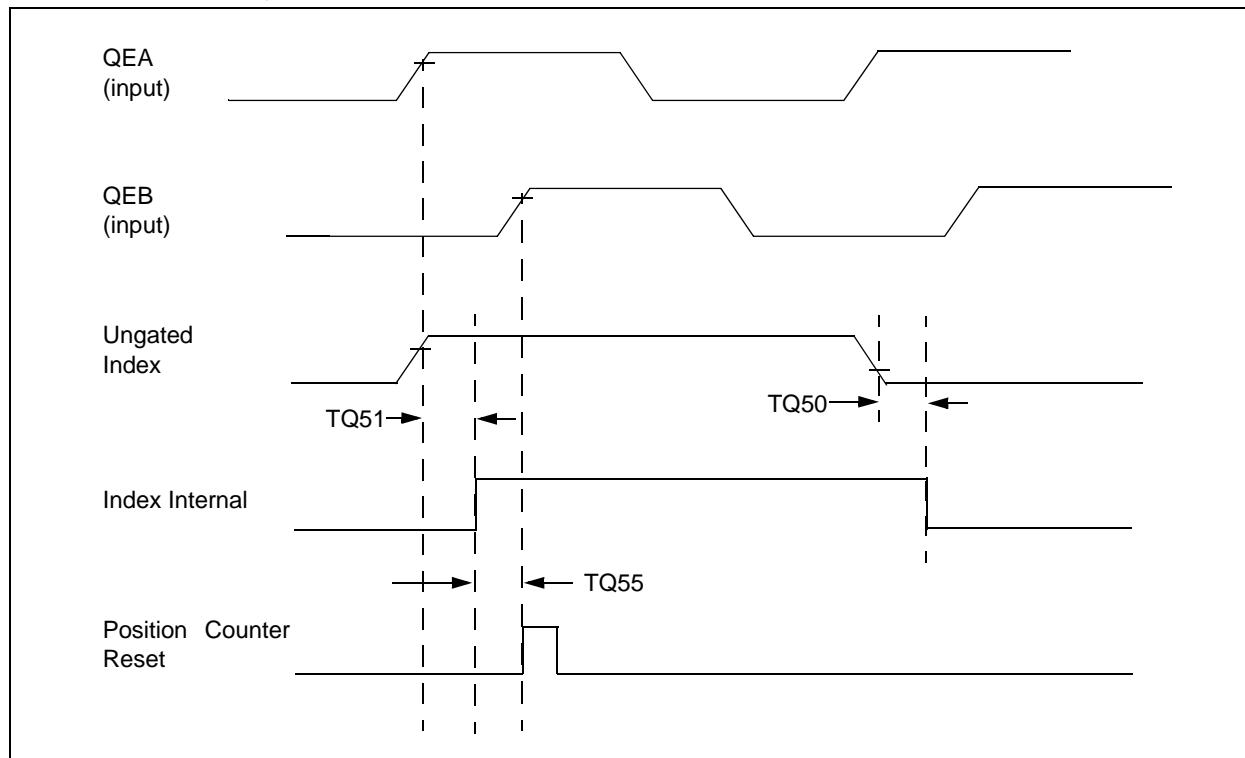
TABLE 31-30: QUADRATURE DECODER TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)			
Param No.	Symbol	Characteristic <sup>(1)</sup>	Typ <sup>(2)</sup>	Max	Units	Conditions
TQ30	TQUL	Quadrature Input Low Time	6 TCY	—	ns	—
TQ31	TQUH	Quadrature Input High Time	6 TCY	—	ns	—
TQ35	TQIN	Quadrature Input Period	12 TCY	—	ns	—
TQ36	TQUP	Quadrature Phase Period	3 TCY	—	ns	—
TQ40	TQFL	Filter Time to Recognize Low, with Digital Filter	$3 * N * TCY$	—	ns	$N = 1, 2, 4, 16, 32, 64,$ $128 \text{ and } 256 \text{ (Note 3)}$
TQ41	TQFH	Filter Time to Recognize High, with Digital Filter	$3 * N * TCY$	—	ns	$N = 1, 2, 4, 16, 32, 64,$ $128 \text{ and } 256 \text{ (Note 3)}$

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**3:** N = Index Channel Digital Filter Clock Divide Select bits. Refer to **Section 15. "Quadrature Encoder Interface (QEI)"** in the "dsPIC33F/PIC24H Family Reference Manual". Please see the Microchip web site for the latest dsPIC33F/PIC24H Family Reference Manual sections.

**FIGURE 31-13: QEI MODULE INDEX PULSE TIMING CHARACTERISTICS****TABLE 31-31: QEI INDEX PULSE TIMING REQUIREMENTS**

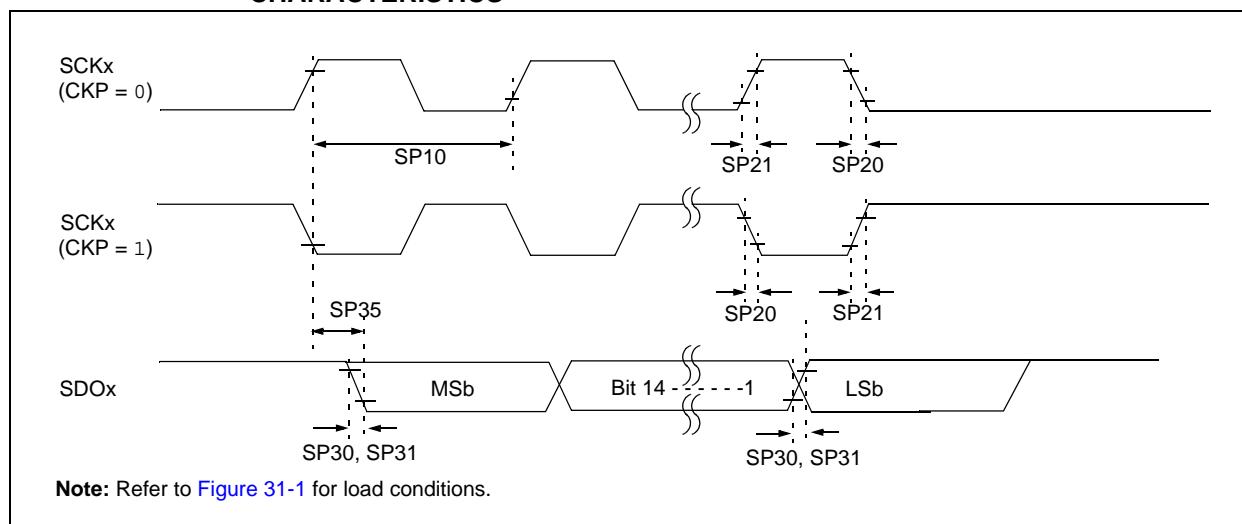
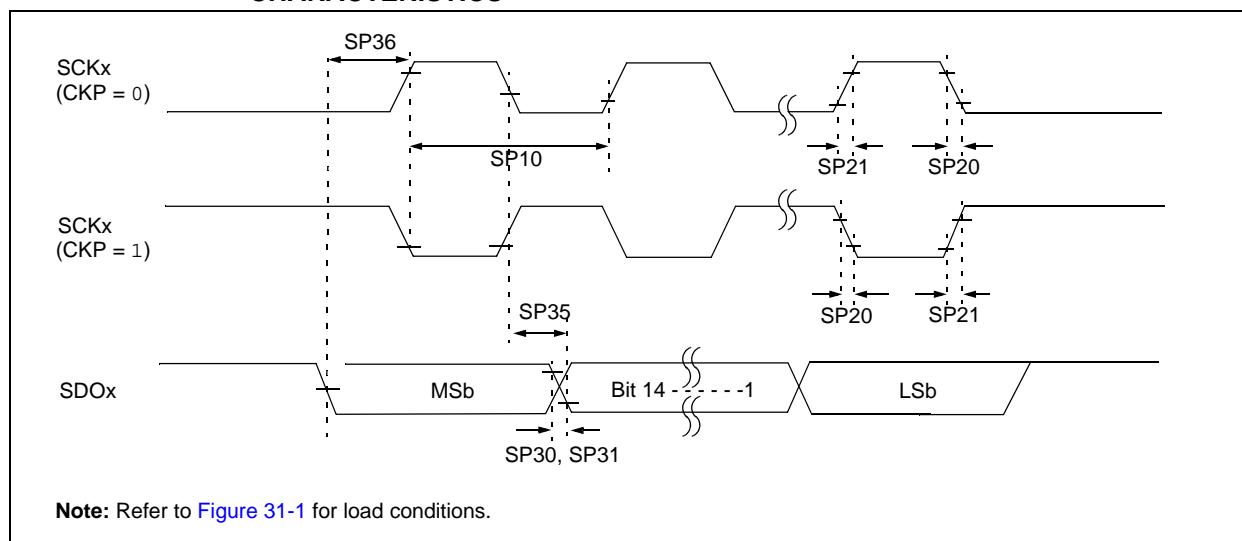
AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)			
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Max	Units	Conditions
TQ50	TqiL	Filter Time to Recognize Low, with Digital Filter	$3 * N * T_{CY}$	—	ns	$N = 1, 2, 4, 16, 32, 64,$ $128 \text{ and } 256 \text{ (Note 2)}$
TQ51	TqiH	Filter Time to Recognize High, with Digital Filter	$3 * N * T_{CY}$	—	ns	$N = 1, 2, 4, 16, 32, 64,$ $128 \text{ and } 256 \text{ (Note 2)}$
TQ55	Tqidxr	Index Pulse Recognized to Position Counter Reset (ungated index)	$3 T_{CY}$	—	ns	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Alignment of index pulses to QEA and QEB is shown for position counter Reset timing only. Shown for forward direction only (QEA leads QEB). Same timing applies for reverse direction (QEA lags QEB) but index pulse recognition occurs on falling edge.

TABLE 31-32: SPI<sub>x</sub> MAXIMUM DATA/CLOCK RATE SUMMARY

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)			
Maximum Data Rate	Master Transmit Only (Half-Duplex)	Master Transmit/Receive (Full-Duplex)	Slave Transmit/Receive (Full-Duplex)	CKE	CKP	SMP
15 Mhz	<a href="#">Table 31-33</a>	—	—	0,1	0,1	0,1
9 Mhz	—	<a href="#">Table 31-34</a>	—	1	0,1	1
9 Mhz	—	<a href="#">Table 31-35</a>	—	0	0,1	1
15 Mhz	—	—	<a href="#">Table 31-36</a>	1	0	0
11 Mhz	—	—	<a href="#">Table 31-37</a>	1	1	0
15 Mhz	—	—	<a href="#">Table 31-38</a>	0	1	0
11 Mhz	—	—	<a href="#">Table 31-39</a>	0	0	0

FIGURE 31-14: SPI<sub>x</sub> MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY CKE = 0) TIMING CHARACTERISTICSFIGURE 31-15: SPI<sub>x</sub> MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY CKE = 1) TIMING CHARACTERISTICS

**TABLE 31-33: SPI<sub>x</sub> MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY) TIMING REQUIREMENTS**

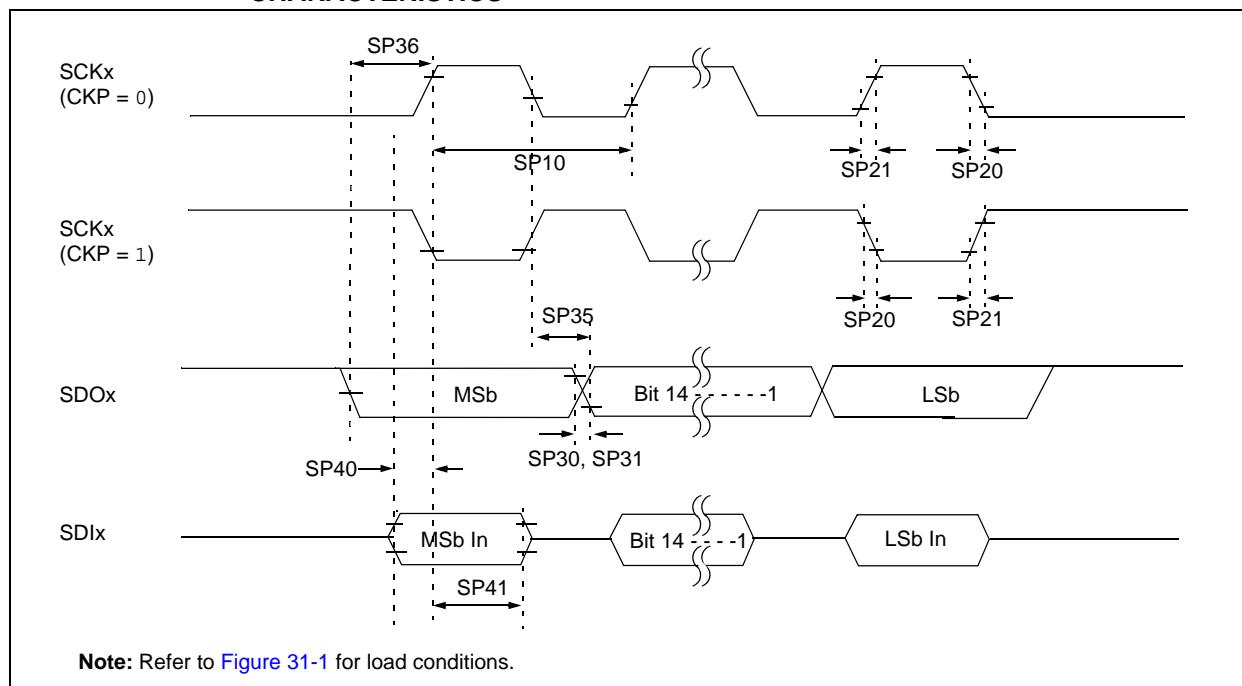
AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
SP10	TscP	Maximum SCK Frequency	—	—	15	MHz	See <b>Note 3</b>
SP20	TscF	SCK <sub>x</sub> Output Fall Time	—	—	—	ns	See parameter <a href="#">DO32</a> and <b>Note 4</b>
SP21	TscR	SCK <sub>x</sub> Output Rise Time	—	—	—	ns	See parameter <a href="#">DO31</a> and <b>Note 4</b>
SP30	TdoF	SDO <sub>x</sub> Data Output Fall Time	—	—	—	ns	See parameter <a href="#">DO32</a> and <b>Note 4</b>
SP31	TdoR	SDO <sub>x</sub> Data Output Rise Time	—	—	—	ns	See parameter <a href="#">DO31</a> and <b>Note 4</b>
SP35	TscH2doV, TscL2doV	SDO <sub>x</sub> Data Output Valid after SCK <sub>x</sub> Edge	—	6	20	ns	—
SP36	TdiV2scH, TdiV2scL	SDO <sub>x</sub> Data Output Setup to First SCK <sub>x</sub> Edge	30	—	—	ns	—

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCK<sub>x</sub> is 66.7 ns. Therefore, the clock generated in Master mode must not violate this specification.

**4:** Assumes 50 pF load on all SPI<sub>x</sub> pins.

**FIGURE 31-16: SPI<sub>x</sub> MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1) TIMING CHARACTERISTICS**

**TABLE 31-34: SPI<sub>x</sub> MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1) TIMING REQUIREMENTS**

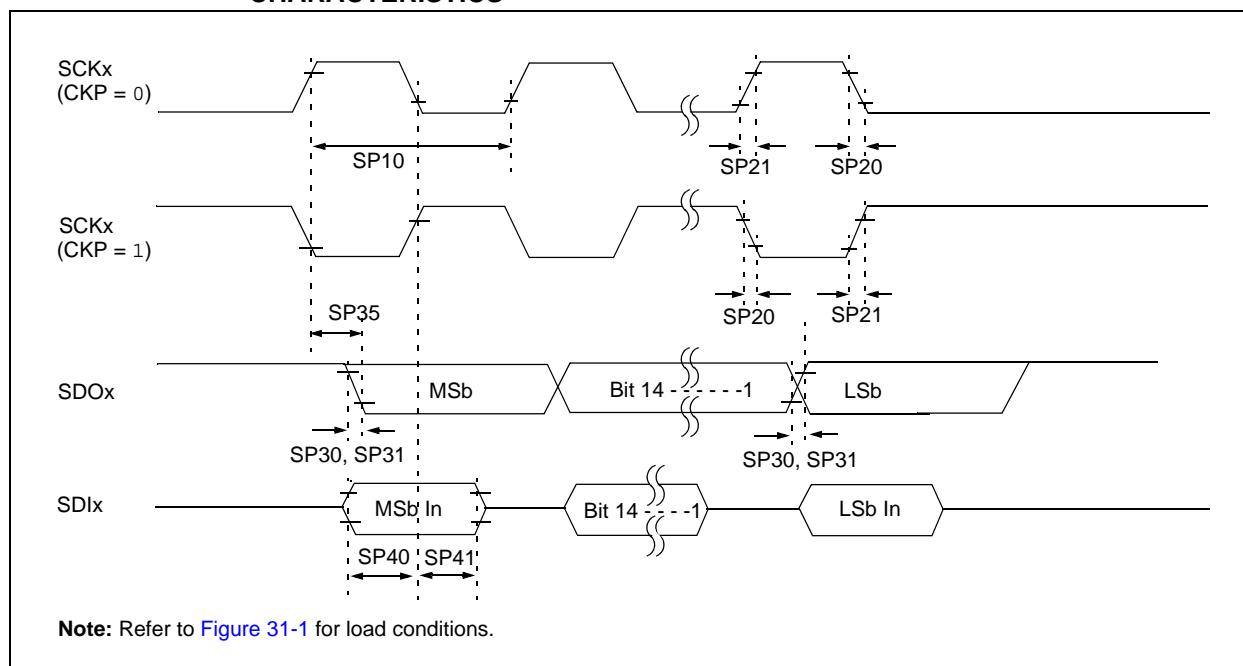
AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
SP10	TscP	Maximum SCK Frequency	—	—	9	MHz	See Note 3
SP20	TscF	SCK <sub>x</sub> Output Fall Time	—	—	—	ns	See parameter DO32 and Note 4
SP21	TscR	SCK <sub>x</sub> Output Rise Time	—	—	—	ns	See parameter DO31 and Note 4
SP30	TdoF	SDO <sub>x</sub> Data Output Fall Time	—	—	—	ns	See parameter DO32 and Note 4
SP31	TdoR	SDO <sub>x</sub> Data Output Rise Time	—	—	—	ns	See parameter DO31 and Note 4
SP35	TscH2doV, TscL2doV	SDO <sub>x</sub> Data Output Valid after SCK <sub>x</sub> Edge	—	6	20	ns	—
SP36	TdoV2sc, TdoV2scL	SDO <sub>x</sub> Data Output Setup to First SCK <sub>x</sub> Edge	30	—	—	ns	—
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCK <sub>x</sub> Edge	30	—	—	ns	—
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCK <sub>x</sub> Edge	30	—	—	ns	—

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCK<sub>x</sub> is 111 ns. The clock generated in Master mode must not violate this specification.

**4:** Assumes 50 pF load on all SPI<sub>x</sub> pins.

**FIGURE 31-17: SPI<sub>x</sub> MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1) TIMING CHARACTERISTICS****TABLE 31-35: SPI<sub>x</sub> MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1) TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
SP10	TscP	Maximum SCK Frequency	—	—	9	MHz	-40°C to +125°C and see <b>Note 3</b>
SP20	TscF	SCKx Output Fall Time	—	—	—	ns	See parameter <b>DO32</b> and <b>Note 4</b>
SP21	TscR	SCKx Output Rise Time	—	—	—	ns	See parameter <b>DO31</b> and <b>Note 4</b>
SP30	TdoF	SDOx Data Output Fall Time	—	—	—	ns	See parameter <b>DO32</b> and <b>Note 4</b>
SP31	TdoR	SDOx Data Output Rise Time	—	—	—	ns	See parameter <b>DO31</b> and <b>Note 4</b>
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns	—
SP36	TdoV2scH, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	—	—	ns	—
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	30	—	—	ns	—
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	30	—	—	ns	—

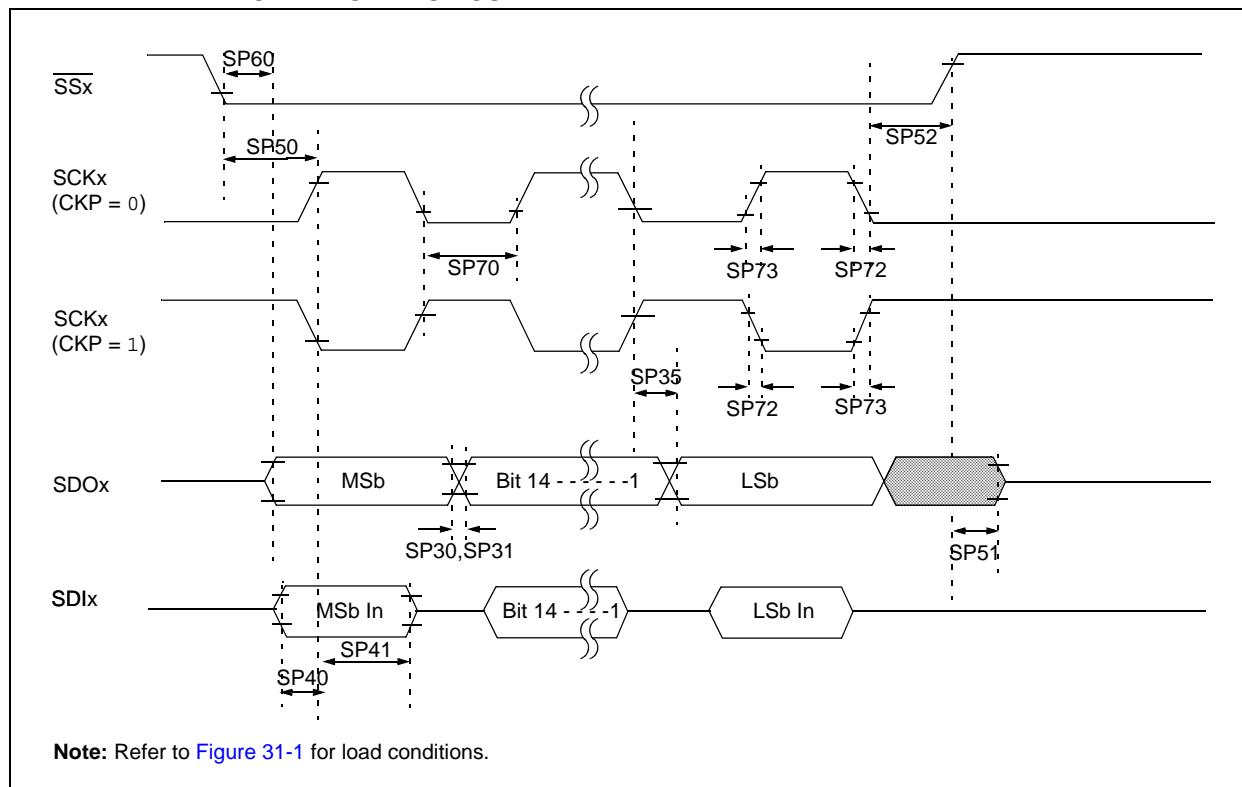
**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCKx is 111 ns. The clock generated in Master mode must not violate this specification.

**4:** Assumes 50 pF load on all SPI<sub>x</sub> pins.

**FIGURE 31-18: SPI<sub>x</sub> SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 0, SMP = 0) TIMING CHARACTERISTICS**



**TABLE 31-36: SPI<sub>x</sub> SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 0, SMP = 0) TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
SP70	TscP	Maximum SCK Input Frequency	—	—	15	MHz	See Note 3
SP72	TscF	SCK <sub>x</sub> Input Fall Time	—	—	—	ns	See parameter DO32 and Note 4
SP73	TscR	SCK <sub>x</sub> Input Rise Time	—	—	—	ns	See parameter DO31 and Note 4
SP30	TdoF	SDO <sub>x</sub> Data Output Fall Time	—	—	—	ns	See parameter DO32 and Note 4
SP31	TdoR	SDO <sub>x</sub> Data Output Rise Time	—	—	—	ns	See parameter DO31 and Note 4
SP35	Tsch2doV, TscL2doV	SDO <sub>x</sub> Data Output Valid after SCK <sub>x</sub> Edge	—	6	20	ns	—
SP36	TdoV2sch, TdoV2scL	SDO <sub>x</sub> Data Output Setup to First SCK <sub>x</sub> Edge	30	—	—	ns	—
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCK <sub>x</sub> Edge	30	—	—	ns	—
SP41	Tsch2diL, TscL2diL	Hold Time of SDIx Data Input to SCK <sub>x</sub> Edge	30	—	—	ns	—
SP50	TssL2scH, TssL2scL	SS <sub>x</sub> ↓ to SCK <sub>x</sub> ↑ or SCK <sub>x</sub> Input	120	—	—	ns	—
SP51	TssH2doZ	SS <sub>x</sub> ↑ to SDO <sub>x</sub> Output High-Impedance <sup>(4)</sup>	10	—	50	ns	—
SP52	TscH2ssH TscL2ssH	SS <sub>x</sub> after SCK <sub>x</sub> Edge	1.5 TCY + 40	—	—	ns	See Note 4
SP60	TssL2doV	SDO <sub>x</sub> Data Output Valid after SS <sub>x</sub> Edge	—	—	50	ns	—

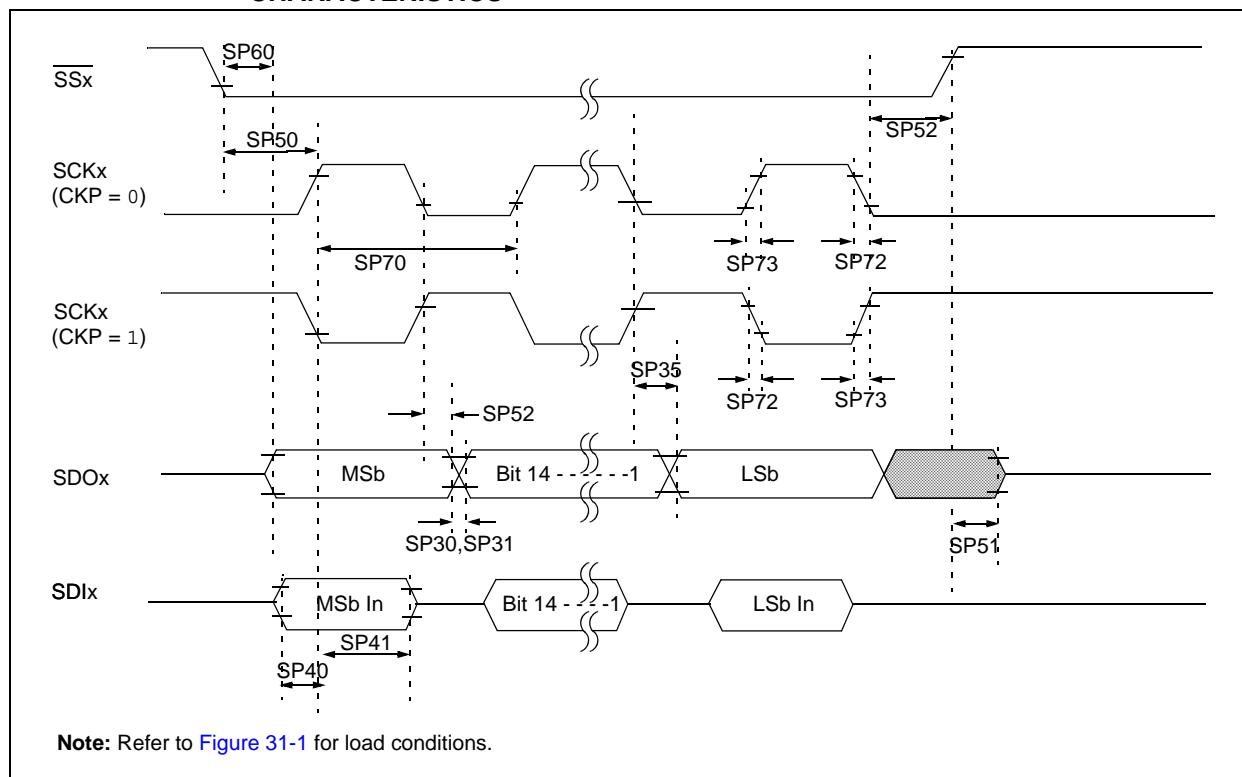
**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCK<sub>x</sub> is 66.7 ns. Therefore, the SCK clock generated by the Master must not violate this specification.

**4:** Assumes 50 pF load on all SPI<sub>x</sub> pins.

**FIGURE 31-19: SPI<sub>x</sub> SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0) TIMING CHARACTERISTICS**



**TABLE 31-37: SPI<sub>x</sub> SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0) TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
SP70	TscP	Maximum SCK Input Frequency	—	—	11	MHz	See Note 3
SP72	TscF	SCK <sub>x</sub> Input Fall Time	—	—	—	ns	See parameter DO32 and Note 4
SP73	TscR	SCK <sub>x</sub> Input Rise Time	—	—	—	ns	See parameter DO31 and Note 4
SP30	TdoF	SDO <sub>x</sub> Data Output Fall Time	—	—	—	ns	See parameter DO32 and Note 4
SP31	TdoR	SDO <sub>x</sub> Data Output Rise Time	—	—	—	ns	See parameter DO31 and Note 4
SP35	TscH2doV, TscL2doV	SDO <sub>x</sub> Data Output Valid after SCK <sub>x</sub> Edge	—	6	20	ns	—
SP36	TdoV2scH, TdoV2scL	SDO <sub>x</sub> Data Output Setup to First SCK <sub>x</sub> Edge	30	—	—	ns	—
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCK <sub>x</sub> Edge	30	—	—	ns	—
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCK <sub>x</sub> Edge	30	—	—	ns	—
SP50	TssL2scH, TssL2scL	SS <sub>x</sub> ↓ to SCK <sub>x</sub> ↑ or SCK <sub>x</sub> Input	120	—	—	ns	—
SP51	TssH2doZ	SS <sub>x</sub> ↑ to SDO <sub>x</sub> Output High-Impedance <sup>(4)</sup>	10	—	50	ns	—
SP52	TscH2ssH TscL2ssH	SS <sub>x</sub> after SCK <sub>x</sub> Edge	1.5 T <sub>CY</sub> + 40	—	—	ns	See Note 4
SP60	TssL2doV	SDO <sub>x</sub> Data Output Valid after SS <sub>x</sub> Edge	—	—	50	ns	—

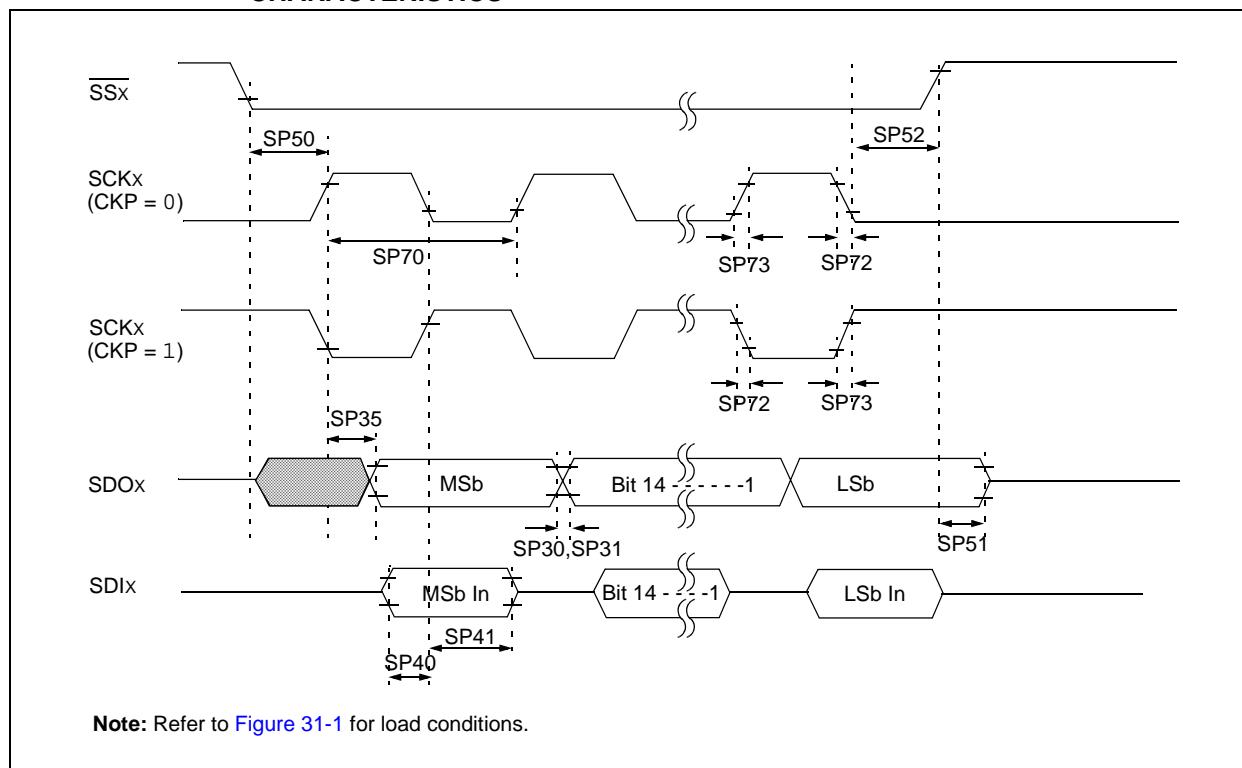
**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCK<sub>x</sub> is 91 ns. Therefore, the SCK clock generated by the Master must not violate this specification.

**4:** Assumes 50 pF load on all SPI<sub>x</sub> pins.

**FIGURE 31-20: SPI<sub>x</sub> SLAVE MODE (FULL-DUPLEX CKE = 0, CKP = 1, SMP = 0) TIMING CHARACTERISTICS**



**TABLE 31-38: SPI<sub>x</sub> SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0) TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
SP70	TscP	Maximum SCK Input Frequency	—	—	15	MHz	See <b>Note 3</b>
SP72	TscF	SCK <sub>x</sub> Input Fall Time	—	—	—	ns	See parameter <a href="#">DO32</a> and <b>Note 4</b>
SP73	TscR	SCK <sub>x</sub> Input Rise Time	—	—	—	ns	See parameter <a href="#">DO31</a> and <b>Note 4</b>
SP30	TdoF	SDO <sub>x</sub> Data Output Fall Time	—	—	—	ns	See parameter <a href="#">DO32</a> and <b>Note 4</b>
SP31	TdoR	SDO <sub>x</sub> Data Output Rise Time	—	—	—	ns	See parameter <a href="#">DO31</a> and <b>Note 4</b>
SP35	TscH2doV, TscL2doV	SDO <sub>x</sub> Data Output Valid after SCK <sub>x</sub> Edge	—	6	20	ns	—
SP36	TdoV2scH, TdoV2scL	SDO <sub>x</sub> Data Output Setup to First SCK <sub>x</sub> Edge	30	—	—	ns	—
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCK <sub>x</sub> Edge	30	—	—	ns	—
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCK <sub>x</sub> Edge	30	—	—	ns	—
SP50	TssL2scH, TssL2scL	SS <sub>x</sub> ↓ to SCK <sub>x</sub> ↑ or SCK <sub>x</sub> Input	120	—	—	ns	—
SP51	TssH2doZ	SS <sub>x</sub> ↑ to SDO <sub>x</sub> Output High-Impedance <sup>(4)</sup>	10	—	50	ns	—
SP52	TscH2ssH TscL2ssH	SS <sub>x</sub> after SCK <sub>x</sub> Edge	1.5 T <sub>CY</sub> + 40	—	—	ns	See <b>Note 4</b>

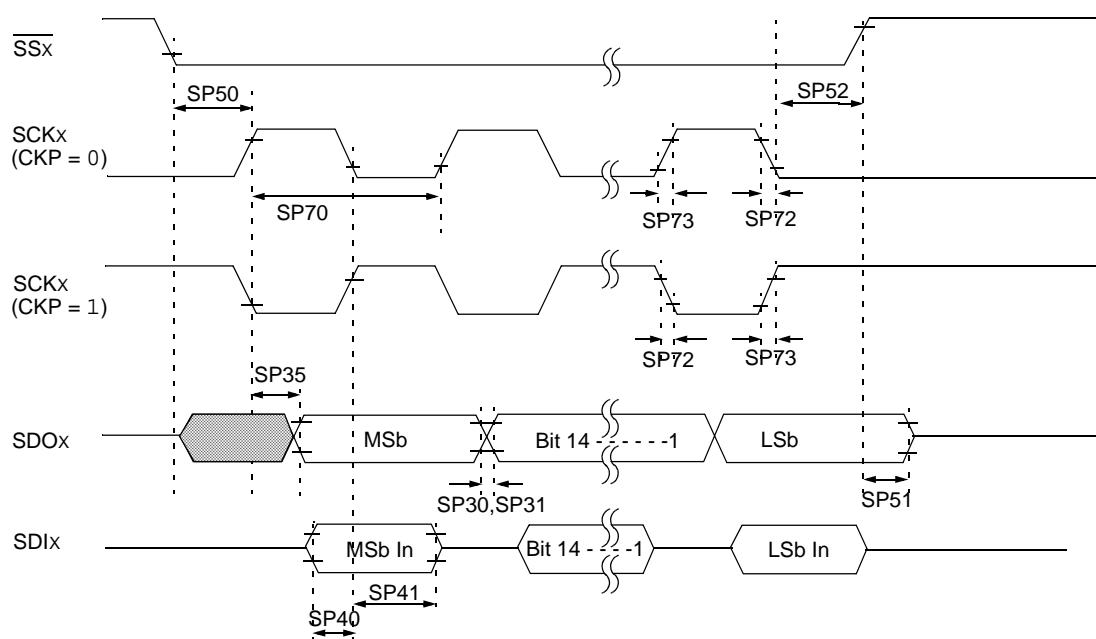
**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCK<sub>x</sub> is 66.7 ns. Therefore, the SCK clock generated by the Master must not violate this specification.

**4:** Assumes 50 pF load on all SPI<sub>x</sub> pins.

**FIGURE 31-21: SPI<sub>x</sub> SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0) TIMING CHARACTERISTICS**



**Note:** Refer to [Figure 31-1](#) for load conditions.

**TABLE 31-39: SPI<sub>x</sub> SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0) TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
SP70	TscP	Maximum SCK Input Frequency	—	—	11	MHz	See <b>Note 3</b>
SP72	TscF	SCK <sub>x</sub> Input Fall Time	—	—	—	ns	See parameter <a href="#">DO32</a> and <b>Note 4</b>
SP73	TscR	SCK <sub>x</sub> Input Rise Time	—	—	—	ns	See parameter <a href="#">DO31</a> and <b>Note 4</b>
SP30	TdoF	SDO <sub>x</sub> Data Output Fall Time	—	—	—	ns	See parameter <a href="#">DO32</a> and <b>Note 4</b>
SP31	TdoR	SDO <sub>x</sub> Data Output Rise Time	—	—	—	ns	See parameter <a href="#">DO31</a> and <b>Note 4</b>
SP35	TscH2doV, TscL2doV	SDO <sub>x</sub> Data Output Valid after SCK <sub>x</sub> Edge	—	6	20	ns	—
SP36	TdoV2scH, TdoV2scL	SDO <sub>x</sub> Data Output Setup to First SCK <sub>x</sub> Edge	30	—	—	ns	—
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCK <sub>x</sub> Edge	30	—	—	ns	—
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCK <sub>x</sub> Edge	30	—	—	ns	—
SP50	TssL2scH, TssL2scL	SS <sub>x</sub> ↓ to SCK <sub>x</sub> ↑ or SCK <sub>x</sub> Input	120	—	—	ns	—
SP51	TssH2doZ	SS <sub>x</sub> ↑ to SDO <sub>x</sub> Output High-Impedance <sup>(4)</sup>	10	—	50	ns	—
SP52	TscH2ssH TscL2ssH	SS <sub>x</sub> after SCK <sub>x</sub> Edge	1.5 T <sub>CY</sub> + 40	—	—	ns	See <b>Note 4</b>

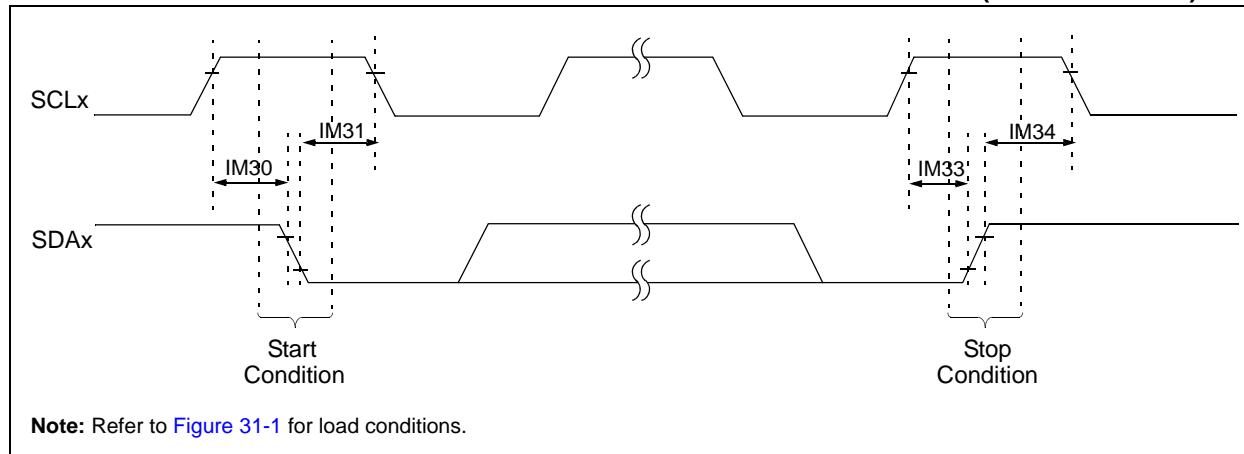
**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCK<sub>x</sub> is 91 ns. Therefore, the SCK clock generated by the Master must not violate this specification.

**4:** Assumes 50 pF load on all SPI<sub>x</sub> pins.

**FIGURE 31-22: I<sup>2</sup>C<sub>x</sub> BUS START/STOP BITS TIMING CHARACTERISTICS (MASTER MODE)**



**FIGURE 31-23: I<sup>2</sup>C<sub>x</sub> BUS DATA TIMING CHARACTERISTICS (MASTER MODE)**

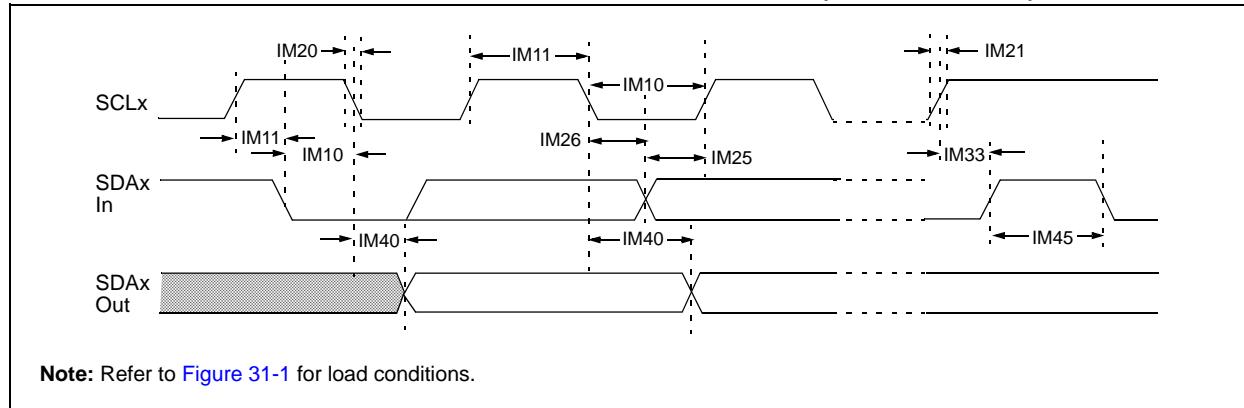


TABLE 31-40: I<sup>2</sup>Cx BUS DATA TIMING REQUIREMENTS (MASTER MODE)

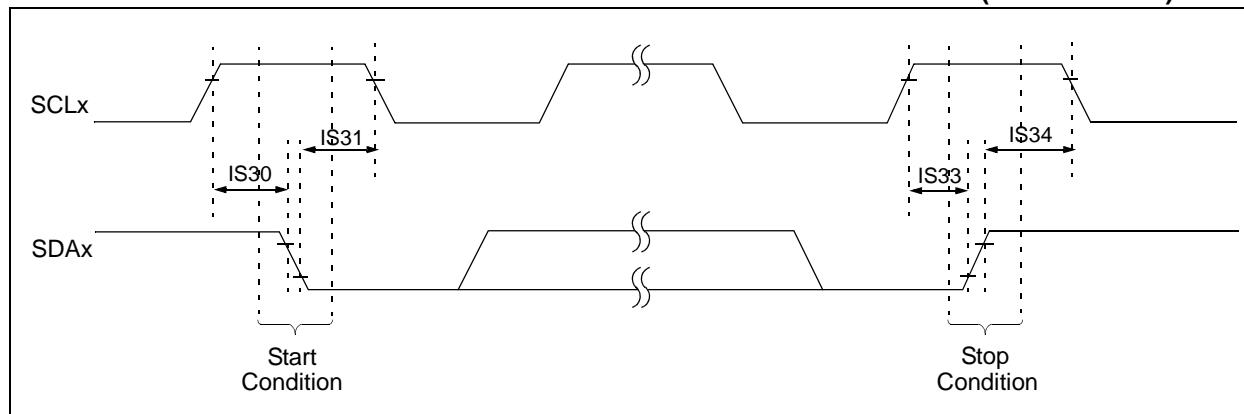
AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Param No.	Symbol	Characteristic	Min <sup>(1)</sup>	Max	Units	Conditions
IM10	TLO:SCL	Clock Low Time	100 kHz mode	T <sub>CY</sub> /2 (BRG + 1)	—	μs
			400 kHz mode	T <sub>CY</sub> /2 (BRG + 1)	—	μs
			1 MHz mode <sup>(2)</sup>	T <sub>CY</sub> /2 (BRG + 1)	—	μs
IM11	THI:SCL	Clock High Time	100 kHz mode	T <sub>CY</sub> /2 (BRG + 1)	—	μs
			400 kHz mode	T <sub>CY</sub> /2 (BRG + 1)	—	μs
			1 MHz mode <sup>(2)</sup>	T <sub>CY</sub> /2 (BRG + 1)	—	μs
IM20	TF:SCL	SDAx and SCLx Fall Time	100 kHz mode	—	300	ns
			400 kHz mode	20 + 0.1 C <sub>B</sub>	300	ns
			1 MHz mode <sup>(2)</sup>	—	100	ns
IM21	TR:SCL	SDAx and SCLx Rise Time	100 kHz mode	—	1000	ns
			400 kHz mode	20 + 0.1 C <sub>B</sub>	300	ns
			1 MHz mode <sup>(2)</sup>	—	300	ns
IM25	TSU:DAT	Data Input Setup Time	100 kHz mode	250	—	ns
			400 kHz mode	100	—	ns
			1 MHz mode <sup>(2)</sup>	40	—	ns
IM26	THD:DAT	Data Input Hold Time	100 kHz mode	0	—	μs
			400 kHz mode	0	0.9	μs
			1 MHz mode <sup>(2)</sup>	0.2	—	μs
IM30	TSU:STA	Start Condition Setup Time	100 kHz mode	T <sub>CY</sub> /2 (BRG + 1)	—	μs
			400 kHz mode	T <sub>CY</sub> /2 (BRG + 1)	—	μs
			1 MHz mode <sup>(2)</sup>	T <sub>CY</sub> /2 (BRG + 1)	—	μs
IM31	THD:STA	Start Condition Hold Time	100 kHz mode	T <sub>CY</sub> /2 (BRG + 1)	—	μs
			400 kHz mode	T <sub>CY</sub> /2 (BRG + 1)	—	μs
			1 MHz mode <sup>(2)</sup>	T <sub>CY</sub> /2 (BRG + 1)	—	μs
IM33	TSU:STO	Stop Condition Setup Time	100 kHz mode	T <sub>CY</sub> /2 (BRG + 1)	—	μs
			400 kHz mode	T <sub>CY</sub> /2 (BRG + 1)	—	μs
			1 MHz mode <sup>(2)</sup>	T <sub>CY</sub> /2 (BRG + 1)	—	μs
IM34	THD:STO	Stop Condition Hold Time	100 kHz mode	T <sub>CY</sub> /2 (BRG + 1)	—	ns
			400 kHz mode	T <sub>CY</sub> /2 (BRG + 1)	—	ns
			1 MHz mode <sup>(2)</sup>	T <sub>CY</sub> /2 (BRG + 1)	—	ns
IM40	TAA:SCL	Output Valid From Clock	100 kHz mode	—	3500	ns
			400 kHz mode	—	1000	ns
			1 MHz mode <sup>(2)</sup>	—	400	ns
IM45	TBF:SDA	Bus Free Time	100 kHz mode	4.7	—	μs
			400 kHz mode	1.3	—	μs
			1 MHz mode <sup>(2)</sup>	0.5	—	μs
IM50	CB	Bus Capacitive Loading	—	400	pF	—
IM51	TPGD	Pulse Gobbler Delay	65	390	ns	See Note 3

**Note 1:** BRG is the value of the I<sup>2</sup>C Baud Rate Generator. Refer to **Section 19. "Inter-Integrated Circuit™ (I<sup>2</sup>C™)"** (DS70195) in the "dsPIC33F/PIC24H Family Reference Manual". Please see the Microchip web site for the latest dsPIC33F/PIC24H Family Reference Manual sections.

**2:** Maximum pin capacitance = 10 pF for all I<sup>2</sup>Cx pins (for 1 MHz mode only).

**3:** Typical value for this parameter is 130 ns.

**FIGURE 31-24: I<sub>2</sub>C<sub>x</sub> BUS START/STOP BITS TIMING CHARACTERISTICS (SLAVE MODE)**



**FIGURE 31-25: I<sub>2</sub>C<sub>x</sub> BUS DATA TIMING CHARACTERISTICS (SLAVE MODE)**

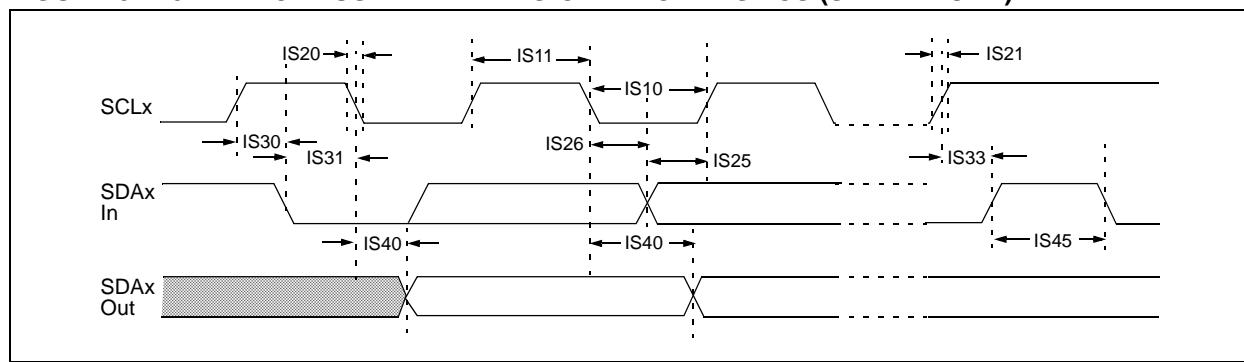
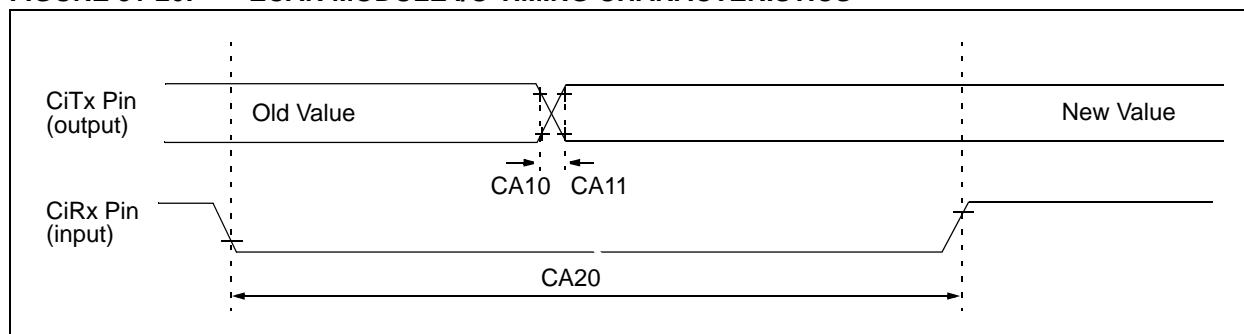


TABLE 31-41: I<sup>2</sup>Cx BUS DATA TIMING REQUIREMENTS (SLAVE MODE)

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic	Min	Max	Units	Conditions	
IS10	T <sub>LO:SCL</sub>	Clock Low Time	100 kHz mode	4.7	—	μs	Device must operate at a minimum of 1.5 MHz
			400 kHz mode	1.3	—	μs	Device must operate at a minimum of 10 MHz
			1 MHz mode <sup>(1)</sup>	0.5	—	μs	—
IS11	T <sub>HI:SCL</sub>	Clock High Time	100 kHz mode	4.0	—	μs	Device must operate at a minimum of 1.5 MHz
			400 kHz mode	0.6	—	μs	Device must operate at a minimum of 10 MHz
			1 MHz mode <sup>(1)</sup>	0.5	—	μs	—
IS20	T <sub>F:SCL</sub>	SDAx and SCLx Fall Time	100 kHz mode	—	300	ns	C <sub>B</sub> is specified to be from 10 to 400 pF
			400 kHz mode	20 + 0.1 C <sub>B</sub>	300	ns	
			1 MHz mode <sup>(1)</sup>	—	100	ns	
IS21	T <sub>R:SCL</sub>	SDAx and SCLx Rise Time	100 kHz mode	—	1000	ns	C <sub>B</sub> is specified to be from 10 to 400 pF
			400 kHz mode	20 + 0.1 C <sub>B</sub>	300	ns	
			1 MHz mode <sup>(1)</sup>	—	300	ns	
IS25	T <sub>SU:DAT</sub>	Data Input Setup Time	100 kHz mode	250	—	ns	—
			400 kHz mode	100	—	ns	
			1 MHz mode <sup>(1)</sup>	100	—	ns	
IS26	T <sub>HD:DAT</sub>	Data Input Hold Time	100 kHz mode	0	—	μs	—
			400 kHz mode	0	0.9	μs	
			1 MHz mode <sup>(1)</sup>	0	0.3	μs	
IS30	T <sub>SU:STA</sub>	Start Condition Setup Time	100 kHz mode	4.7	—	μs	Only relevant for Repeated Start condition
			400 kHz mode	0.6	—	μs	
			1 MHz mode <sup>(1)</sup>	0.25	—	μs	
IS31	T <sub>HD:STA</sub>	Start Condition Hold Time	100 kHz mode	4.0	—	μs	After this period, the first clock pulse is generated
			400 kHz mode	0.6	—	μs	
			1 MHz mode <sup>(1)</sup>	0.25	—	μs	
IS33	T <sub>SU:STO</sub>	Stop Condition Setup Time	100 kHz mode	4.7	—	μs	—
			400 kHz mode	0.6	—	μs	
			1 MHz mode <sup>(1)</sup>	0.6	—	μs	
IS34	T <sub>HD:STO</sub>	Stop Condition Hold Time	100 kHz mode	4000	—	ns	—
			400 kHz mode	600	—	ns	
			1 MHz mode <sup>(1)</sup>	250	—	ns	
IS40	T <sub>A:A:SCL</sub>	Output Valid From Clock	100 kHz mode	0	3500	ns	—
			400 kHz mode	0	1000	ns	
			1 MHz mode <sup>(1)</sup>	0	350	ns	
IS45	T <sub>BF:SDA</sub>	Bus Free Time	100 kHz mode	4.7	—	μs	Time bus must be free before a new transmission can start
			400 kHz mode	1.3	—	μs	
			1 MHz mode <sup>(1)</sup>	0.5	—	μs	
IS50	C <sub>B</sub>	Bus Capacitive Loading	—	400	pF	—	—

**Note 1:** Maximum pin capacitance = 10 pF for all I<sup>2</sup>Cx pins (for 1 MHz mode only).

**FIGURE 31-26: ECAN MODULE I/O TIMING CHARACTERISTICS****TABLE 31-42: ECAN MODULE I/O TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ 85°C				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ <sup>(2)</sup>	Max	Units	Conditions
CA10	TioF	Port Output Fall Time	—	—	—	ns	See parameter D032
CA11	TioR	Port Output Rise Time	—	—	—	ns	See parameter D031
CA20	Tcwf	Pulse Width to Trigger CAN Wake-up Filter	120	—	—	ns	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

TABLE 31-43: ADC MODULE SPECIFICATIONS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
<b>Device Supply</b>							
AD01	AVDD	Module VDD Supply	Greater of VDD – 0.3 or 3.0	—	Lesser of VDD + 0.3 or 3.6	V	—
AD02	AVSS	Module Vss Supply	VSS – 0.3	—	VSS + 0.3	V	—
<b>Reference Inputs</b>							
AD05	VREFH	Reference Voltage High	AVSS + 2.5	—	AVDD	V	
AD05a			3.0	—	3.6	V	VREFH = AVDD VREFL = AVSS = 0
AD06	VREFL	Reference Voltage Low	AVSS	—	AVDD – 2.5	V	
AD06a			0	—	0	V	VREFH = AVDD VREFL = AVSS = 0
AD07	VREF	Absolute Reference Voltage	2.5	—	3.6	V	VREF = VREFH - VREFL
AD08	IREF	Current Drain	—	—	10	µA	ADC off
AD09	IAD	Operating Current	—	7.0	9.0	mA	ADC operating in 10-bit mode, see <b>Note 1</b> ADC operating in 12-bit mode, see <b>Note 1</b>
<b>Analog Input</b>							
AD12	VINH	Input Voltage Range VINH	VINL	—	VREFH	V	This voltage reflects Sample and Hold Channels 0, 1, 2, and 3 (CH0-CH3), positive input
AD13	VINL	Input Voltage Range VINL	VREFL	—	AVSS + 1V	V	This voltage reflects Sample and Hold Channels 0, 1, 2, and 3 (CH0-CH3), negative input
AD17	RIN	Recommended Impedance of Analog Voltage Source	—	—	200 200	Ω	10-bit ADC 12-bit ADC

**Note 1:** These parameters are not characterized or tested in manufacturing.

TABLE 31-44: ADC MODULE SPECIFICATIONS (12-BIT MODE)

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
<b>ADC Accuracy (12-bit Mode) – Measurements with external VREF+/VREF-</b>							
AD20a	Nr	Resolution <sup>(1)</sup>	12 data bits			bits	
AD21a	INL	Integral Nonlinearity	-2	—	+2	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
AD22a	DNL	Differential Nonlinearity	>-1	—	<1	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
AD23a	GERR	Gain Error	—	3.4	10	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
AD24a	E0FF	Offset Error	—	0.9	5	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
AD25a	—	Monotonicity	—	—	—	—	Guaranteed
<b>ADC Accuracy (12-bit Mode) – Measurements with internal VREF+/VREF-</b>							
AD20a	Nr	Resolution <sup>(1)</sup>	12 data bits			bits	
AD21a	INL	Integral Nonlinearity	-2	—	+2	LSb	VINL = AVSS = 0V, AVDD = 3.6V
AD22a	DNL	Differential Nonlinearity	>-1	—	<1	LSb	VINL = AVSS = 0V, AVDD = 3.6V
AD23a	GERR	Gain Error	2	10.5	20	LSb	VINL = AVSS = 0V, AVDD = 3.6V
AD24a	E0FF	Offset Error	2	3.8	10	LSb	VINL = AVSS = 0V, AVDD = 3.6V
AD25a	—	Monotonicity	—	—	—	—	Guaranteed
<b>Dynamic Performance (12-bit Mode)</b>							
AD30a	THD	Total Harmonic Distortion	—	—	-75	dB	—
AD31a	SINAD	Signal to Noise and Distortion	68.5	69.5	—	dB	—
AD32a	SFDR	Spurious Free Dynamic Range	80	—	—	dB	—
AD33a	FNYQ	Input Signal Bandwidth	—	—	250	kHz	—
AD34a	ENOB	Effective Number of Bits	11.09	11.3	—	bits	—

**Note 1:** Injection currents > |0| can affect the ADC results by approximately 4 to 6 counts (i.e., VIH source > (VDD + 0.3V) or Vil source < (Vss - 0.3V).

**TABLE 31-45: ADC MODULE SPECIFICATIONS (10-BIT MODE)**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
<b>ADC Accuracy (10-bit Mode) – Measurements with external VREF+/VREF-</b>							
AD20b	Nr	Resolution <sup>(1)</sup>	10 data bits			bits	
AD21b	INL	Integral Nonlinearity	-1.5	—	+1.5	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
AD22b	DNL	Differential Nonlinearity	>-1	—	<1	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
AD23b	GERR	Gain Error	—	3	6	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
AD24b	E0FF	Offset Error	—	2	5	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
AD25b	—	Monotonicity	—	—	—	—	Guaranteed
<b>ADC Accuracy (10-bit Mode) – Measurements with internal VREF+/VREF-</b>							
AD20b	Nr	Resolution <sup>(1)</sup>	10 data bits			bits	
AD21b	INL	Integral Nonlinearity	-1	—	+1	LSb	VINL = AVSS = 0V, AVDD = 3.6V
AD22b	DNL	Differential Nonlinearity	>-1	—	<1	LSb	VINL = AVSS = 0V, AVDD = 3.6V
AD23b	GERR	Gain Error	3	7	15	LSb	VINL = AVSS = 0V, AVDD = 3.6V
AD24b	E0FF	Offset Error	1.5	3	7	LSb	VINL = AVSS = 0V, AVDD = 3.6V
AD25b	—	Monotonicity	—	—	—	—	Guaranteed
<b>Dynamic Performance (10-bit Mode)</b>							
AD30b	THD	Total Harmonic Distortion	—	—	-64	dB	—
AD31b	SINAD	Signal to Noise and Distortion	57	58.5	—	dB	—
AD32b	SFDR	Spurious Free Dynamic Range	72	—	—	dB	—
AD33b	FNYQ	Input Signal Bandwidth	—	—	550	kHz	—
AD34b	ENOB	Effective Number of Bits	9.16	9.4	—	bits	—

**Note 1:** Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts.

**FIGURE 31-27: ADC CONVERSION (12-BIT MODE) TIMING CHARACTERISTICS  
(ASAM = 0, SSRC<2:0> = 000)**

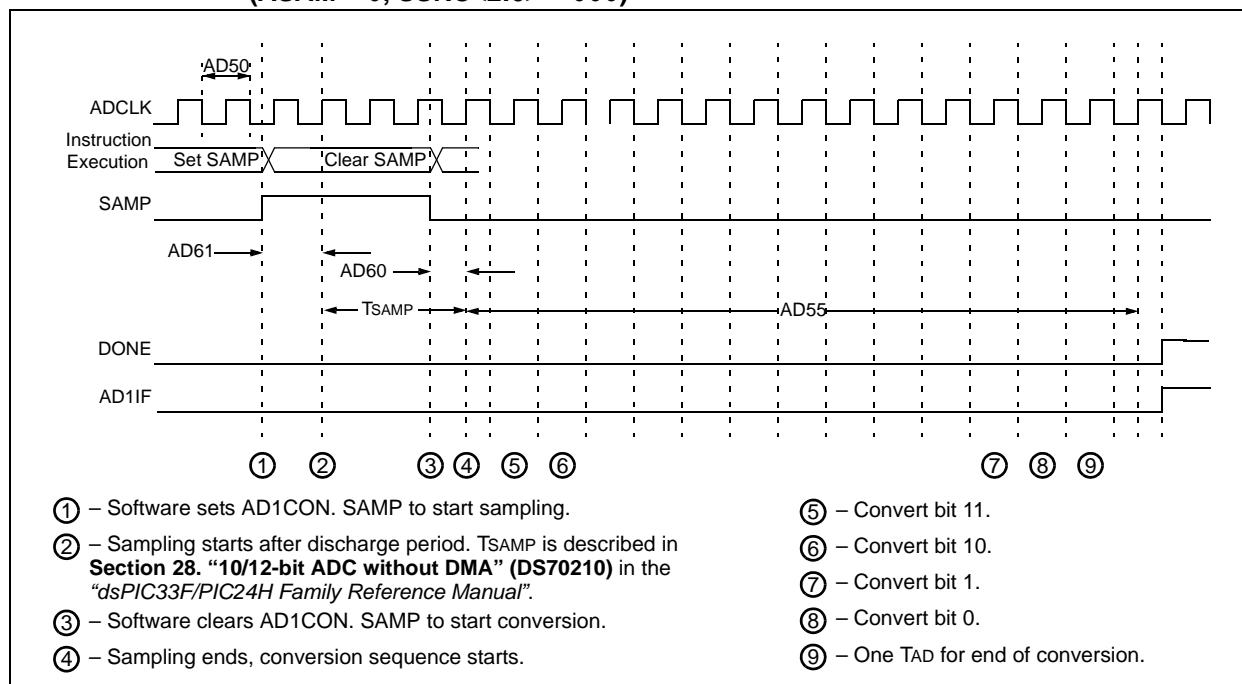


TABLE 31-46: ADC CONVERSION (12-BIT MODE) TIMING REQUIREMENTS

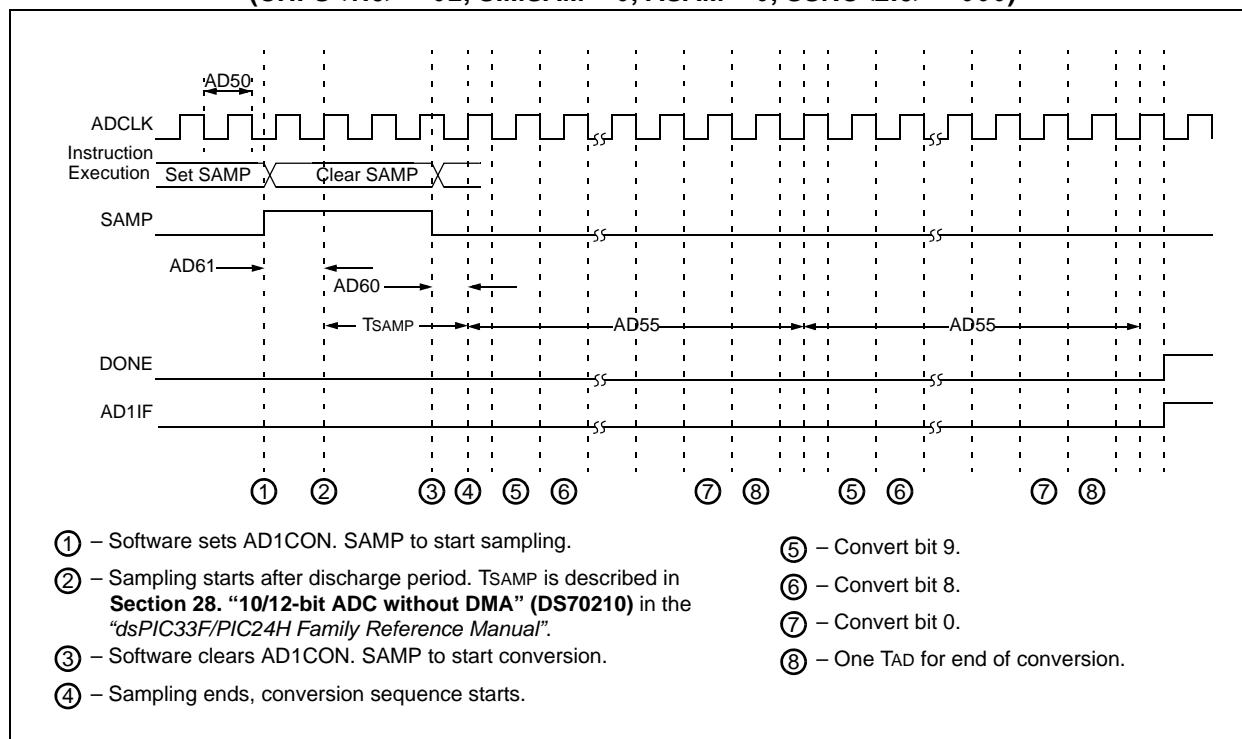
AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
<b>Clock Parameters</b>							
AD50	TAD	ADC Clock Period	117.6	—	—	ns	—
AD51	t <sub>RC</sub>	ADC Internal RC Oscillator Period	—	250	—	ns	—
<b>Conversion Rate</b>							
AD55	t <sub>CONV</sub>	Conversion Time	—	14 TAD	—	ns	—
AD56	F <sub>CNV</sub>	Throughput Rate	—	—	500	Ksps	—
AD57	t <sub>SAMP</sub>	Sample Time	3 TAD	—	—	—	—
<b>Timing Parameters</b>							
AD60	t <sub>PCS</sub>	Conversion Start from Sample Trigger <sup>(2)</sup>	2 TAD	—	3 TAD	—	Auto convert trigger not selected
AD61	t <sub>PSS</sub>	Sample Start from Setting Sample (SAMP) bit <sup>(2)</sup>	2 TAD	—	3 TAD	—	—
AD62	t <sub>CSS</sub>	Conversion Completion to Sample Start (ASAM = 1) <sup>(2)</sup>	—	0.5 TAD	—	—	—
AD63	t <sub>DPU</sub>	Time to Stabilize Analog Stage from ADC Off to ADC On <sup>(2)</sup>	—	—	20	μs	—

**Note 1:** Because the sample caps will eventually lose charge, clock rates below 10 kHz may affect linearity performance, especially at elevated temperatures.

**2:** These parameters are characterized but not tested in manufacturing.

**3:** The t<sub>DPU</sub> is the time required for the ADC module to stabilize at the appropriate level when the module is turned on (AD1CON1<ADON>='1'). During this time, the ADC result is indeterminate.

**FIGURE 31-28: ADC CONVERSION (10-BIT MODE) TIMING CHARACTERISTICS  
(CHPS<1:0> = 01, SIMSAM = 0, ASAM = 0, SSRC<2:0> = 000)**



**FIGURE 31-29: ADC CONVERSION (10-BIT MODE) TIMING CHARACTERISTICS (CHPS<1:0> = 01, SIMSAM = 0, ASAM = 1, SSRC<2:0> = 111, SAMC<4:0> = 00001)**

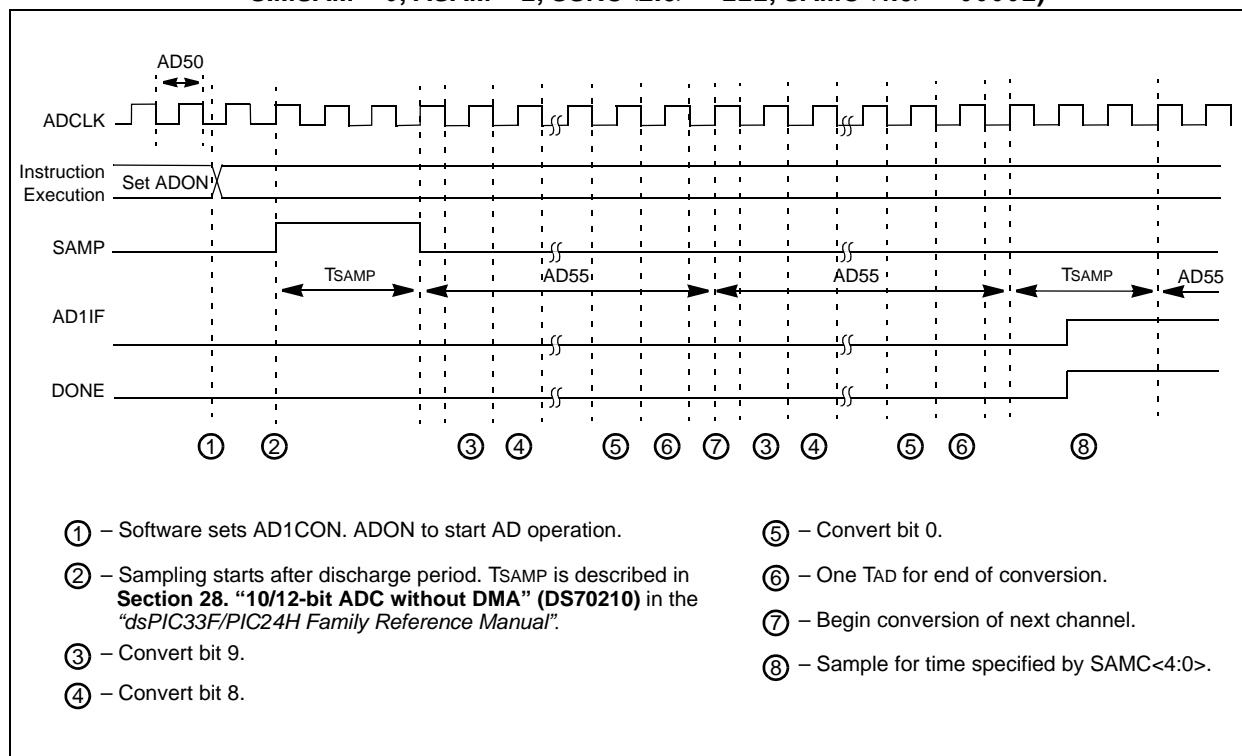


TABLE 31-47: ADC CONVERSION (10-BIT MODE) TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
<b>Clock Parameters</b>							
AD50	TAD	ADC Clock Period	76	—	—	ns	—
AD51	tRC	ADC Internal RC Oscillator Period	—	250	—	ns	—
<b>Conversion Rate</b>							
AD55	tCONV	Conversion Time	—	12 TAD	—	—	—
AD56	Fcnv	Throughput Rate	—	—	1.1	MspS	—
AD57	TsAMP	Sample Time	2 TAD	—	—	—	—
<b>Timing Parameters</b>							
AD60	tPCS	Conversion Start from Sample Trigger <sup>(1)</sup>	2 TAD	—	3 TAD	—	Auto-Convert Trigger not selected
AD61	tPSS	Sample Start from Setting Sample (SAMP) bit <sup>(1)</sup>	2 TAD	—	3 TAD	—	—
AD62	tcss	Conversion Completion to Sample Start (ASAM = 1) <sup>(1)</sup>	—	0.5 TAD	—	—	—
AD63	tDPU	Time to Stabilize Analog Stage from ADC Off to ADC On <sup>(1)</sup>	—	—	20	μs	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

- 2:** Because the sample caps will eventually lose charge, clock rates below 10 kHz may affect linearity performance, especially at elevated temperatures.
- 3:** The tDPU is the time required for the ADC module to stabilize at the appropriate level when the module is turned on (AD1CON1<ADON>='1'). During this time, the ADC result is indeterminate.

TABLE 31-48: AUDIO DAC MODULE SPECIFICATIONS

AC/DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
<b>Clock Parameters</b>							
DA01	VOD+	Positive Output Differential Voltage	1	1.15	2	V	VOD+ = VDACH - VDACL See <b>Note 1,2</b>
DA02	VOD-	Negative Output Differential Voltage	-2	-1.15	-1	V	VOD- = VDACL - VDACH See <b>Note 1,2</b>
DA03	VRES	Resolution	—	16	—	bits	—
DA04	GERR	Gain Error	—	3.1	—	%	—
DA08	FDAC	Clock frequency	—	—	25.6	MHz	—
DA09	FsAMP	Sample Rate	0	—	100	kHz	—
DA10	FINPUT	Input data frequency	0	—	45	kHz	Sampling frequency = 100 kHz
DA11	TINIT	Initialization period	1024	—	—	Clks	Time before first sample
DA12	SNR	Signal-to-Noise Ratio	—	61	—	dB	Sampling frequency = 96 kHz

**Note 1:** Measured VDACH and VDACL output with respect to Vss, with 15 μA load and FORM bit (DACLCON<8>) = 0.

- 2:** This parameter is tested at -40°C ≤ TA ≤ +85°C only.

**TABLE 31-49: COMPARATOR TIMING SPECIFICATIONS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V <b>(unless otherwise stated)</b> Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
300	TRESP	Response Time <sup>(1,2)</sup>	—	150	400	ns	—
301	TMC20V	Comparator Mode Change to Output Valid <sup>(1)</sup>	—	—	10	μs	—

**Note 1:** Parameters are characterized but not tested.

**2:** Response time measured with one comparator input at (VDD - 1.5)/2, while the other input transitions from Vss to VDD.

**TABLE 31-50: COMPARATOR MODULE SPECIFICATIONS**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V <b>(unless otherwise stated)</b> Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
D300	VIOFF	Input Offset Voltage <sup>(1)</sup>	—	±10	—	mV	—
D301	VICM	Input Common Mode Voltage <sup>(1)</sup>	0	—	AVDD-1.5V	V	—
D302	CMRR	Common Mode Rejection Ratio <sup>(1)</sup>	-54	—	—	dB	—

**Note 1:** Parameters are characterized but not tested.

**TABLE 31-51: COMPARATOR REFERENCE VOLTAGE SETTLING TIME SPECIFICATIONS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
VR310	TSET	Settling Time <sup>(1)</sup>	—	—	10	μs	—

Note 1: Setting time measured while CVRR = 1 and CVR3:CVR0 bits transition from '0000' to '1111'.

**TABLE 31-52: COMPARATOR REFERENCE VOLTAGE SPECIFICATIONS**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
VRD310	CVRES	Resolution	CVRSRC/24	—	CVRSRC/32	LSb	—
VRD311	CVRAA	Absolute Accuracy	—	—	0.5	LSb	—
VRD312	CVRUR	Unit Resistor Value (R)	—	2k	—	Ω	—

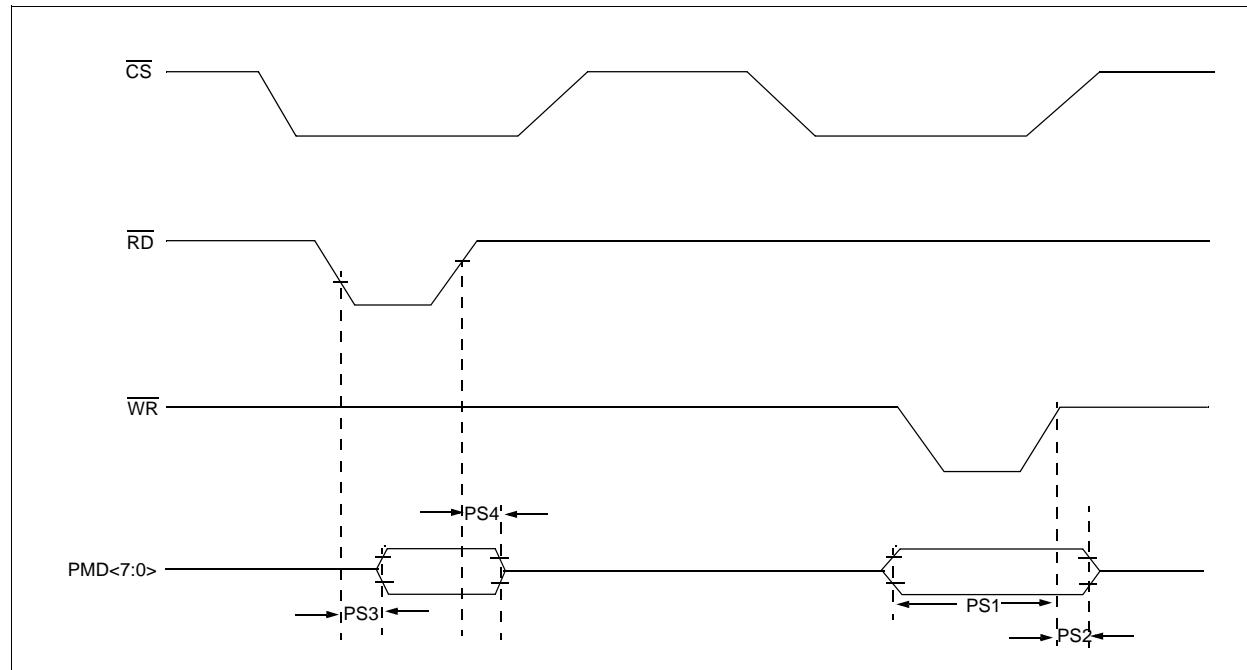
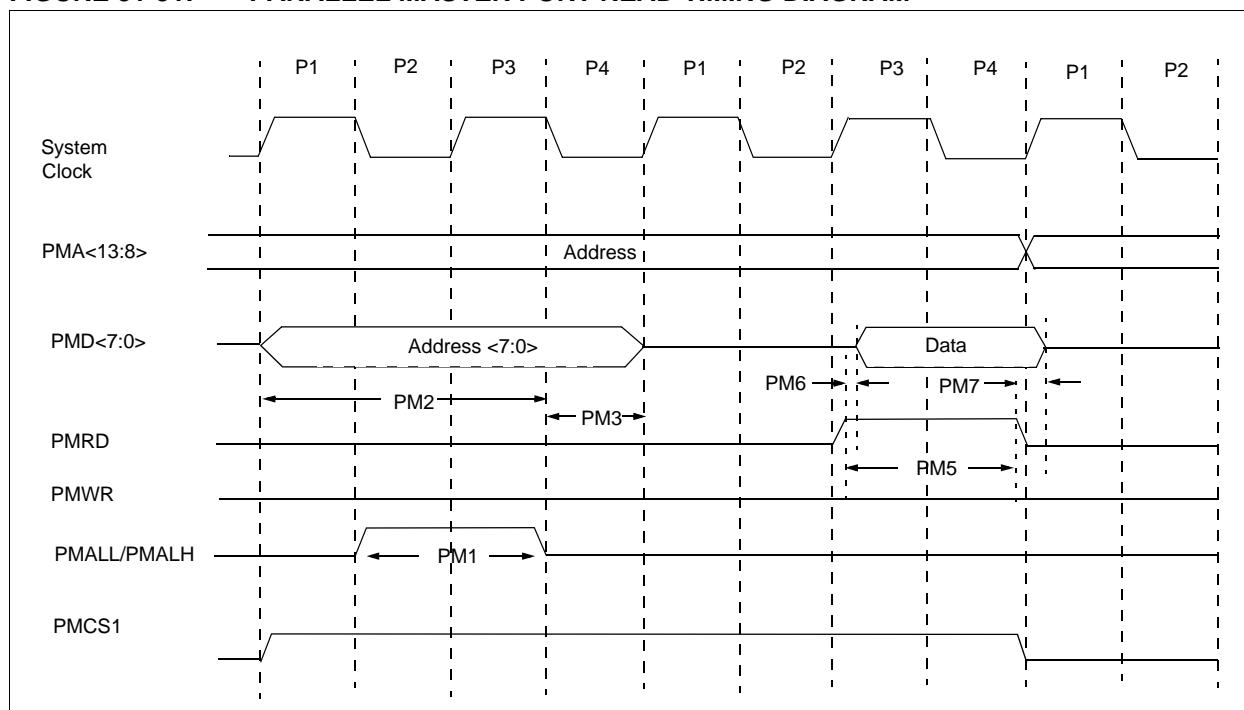
**FIGURE 31-30: PARALLEL SLAVE PORT TIMING DIAGRAM**

TABLE 31-53: SETTING TIME SPECIFICATIONS

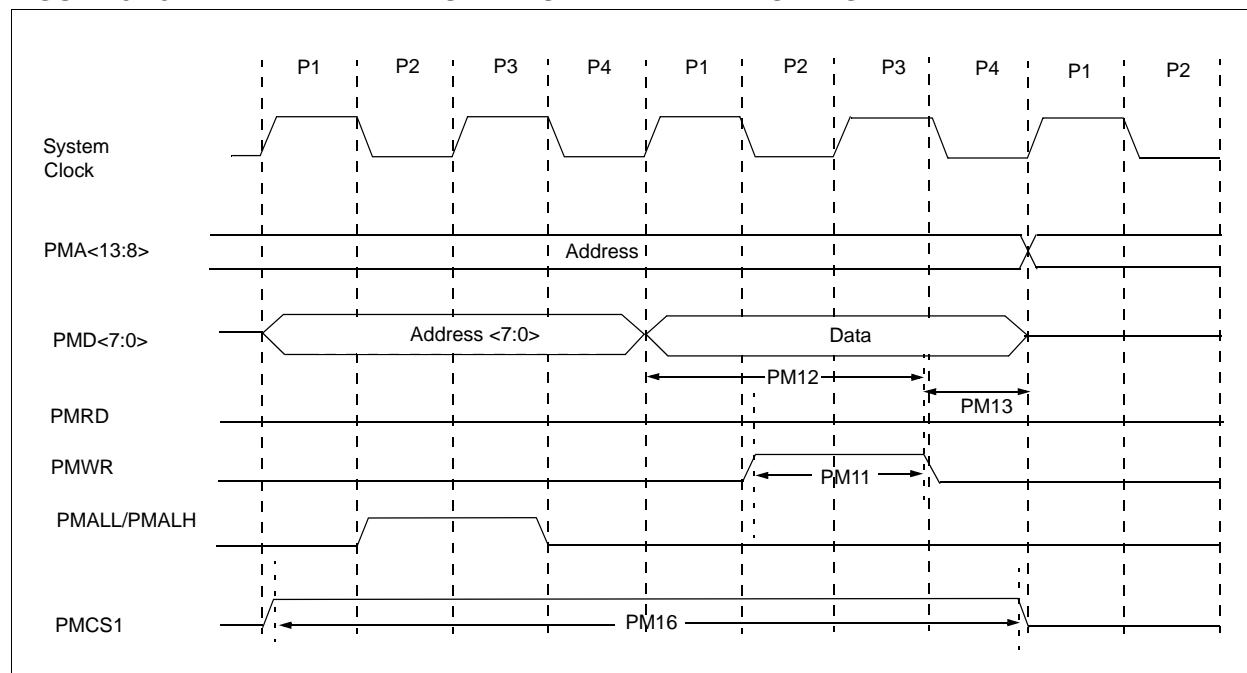
AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
PS1	TdtV2wrH	Data in Valid before WR or CS Inactive (setup time)	20	—	—	ns	—
PS2	TwrH2dtl	WR or CS Inactive to Data-In Invalid (hold time)	20	—	—	ns	—
PS3	TrdL2dtV	RD and CS to Active Data-Out Valid	—	—	80	ns	—
PS4	TrdH2dtl	RD Active or CS Inactive to Data-Out Invalid	10	—	30	ns	—

FIGURE 31-31: PARALLEL MASTER PORT READ TIMING DIAGRAM



**TABLE 31-54: PARALLEL MASTER PORT READ TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Characteristic	Min	Typ	Max	Units	Conditions
PM1	PMALL/PMALH Pulse Width	—	0.5 TCY	—	ns	—
PM2	Address Out Valid to PMALL/PMALH Invalid (address setup time)	—	0.75 TCY	—	ns	—
PM3	PMALL/PMALH Invalid to Address Out Invalid (address hold time)	—	0.25 TCY	—	ns	—
PM5	PMRD Pulse Width	—	0.5 TCY	—	ns	—
PM6	PMRD or PMENB Active to Data In Valid (data setup time)	150	—	—	ns	—
PM7	PMRD or PMENB Inactive to Data In Invalid (data hold time)	—	—	5	ns	—

**FIGURE 31-32: PARALLEL MASTER PORT WRITE TIMING DIAGRAM**

**TABLE 31-55: PARALLEL MASTER PORT WRITE TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Characteristic	Min	Typ	Max	Units	Conditions
PM11	PMWR Pulse Width	—	0.5 TCY	—	ns	—
PM12	Data Out Valid before PMWR or PMENB goes Inactive (data setup time)	—	—	—	ns	—
PM13	PMWR or PMEMB Invalid to Data Out Invalid (data hold time)	—	—	—	ns	—
PM16	PMCSx Pulse Width	TCY - 5	—	—	ns	—

**TABLE 31-56: DMA READ/WRITE TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)				
Param No.	Characteristic	Min	Typ	Max	Units	Conditions
DM1	DMA Read/Write Cycle Time	—	—	1 TCY	ns	—

## 32.0 HIGH TEMPERATURE ELECTRICAL CHARACTERISTICS

This section provides an overview of dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 electrical characteristics for devices operating in an ambient temperature range of -40°C to +150°C.

**Note:** Programming of the Flash memory is not allowed above 125°C.

The specifications between -40°C to +150°C are identical to those shown in [Section 31.0 “Electrical Characteristics”](#) for operation between -40°C to +125°C, with the exception of the parameters listed in this section.

Parameters in this section begin with an H, which denotes High temperature. For example, parameter DC10 in [Section 31.0 “Electrical Characteristics”](#) is the Industrial and Extended temperature equivalent of HDC10.

Absolute maximum ratings for the dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 high temperature devices are listed below. Exposure to these maximum rating conditions for extended periods can affect device reliability. Functional operation of the device at these or any other conditions above the parameters indicated in the operation listings of this specification is not implied.

### Absolute Maximum Ratings<sup>(1)</sup>

Ambient temperature under bias <sup>(4)</sup> .....	-40°C to +150°C
Storage temperature .....	-65°C to +160°C
Voltage on VDD with respect to Vss .....	-0.3V to +4.0V
Voltage on any pin that is not 5V tolerant with respect to Vss <sup>(5)</sup> .....	-0.3V to (VDD + 0.3V)
Voltage on any 5V tolerant pin with respect to Vss when VDD < 3.0V <sup>(5)</sup> .....	-0.3V to (VDD + 0.3V)
Voltage on any 5V tolerant pin with respect to Vss when VDD ≥ 3.0V <sup>(5)</sup> .....	-0.3V to 5.6V
Maximum current out of Vss pin .....	60 mA
Maximum current into VDD pin <sup>(2)</sup> .....	60 mA
Maximum junction temperature .....	+155°C
Maximum output current sunk by any I/O pin <sup>(3)</sup> .....	1 mA
Maximum output current sourced by any I/O pin <sup>(3)</sup> .....	1 mA
Maximum current sunk by all ports combined .....	10 mA
Maximum current sourced by all ports combined <sup>(2)</sup> .....	10 mA

**Note 1:** Stresses above those listed under “Absolute Maximum Ratings” can cause permanent damage to the device. This is a stress rating only, and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods can affect device reliability.

- 2:** Maximum allowable current is a function of device maximum power dissipation (see [Table 32-2](#)).
- 3:** Unlike devices at 125°C and below, the specifications in this section also apply to the CLKOUT, VREF+, VREF-, SCLx, SDAx, PGCx and PGDx pins.
- 4:** AEC-Q100 reliability testing for devices intended to operate at 150°C is 1,000 hours. Any design in which the total operating time from 125°C to 150°C will be greater than 1,000 hours is not warranted without prior written approval from Microchip Technology Inc.
- 5:** Refer to the “[Pin Diagrams](#)” section for 5V tolerant pins.

### 32.1 High Temperature DC Characteristics

TABLE 32-1: OPERATING MIPS VS. VOLTAGE

Characteristic	VDD Range (in Volts)	Temperature Range (in °C)	Max MIPS
			dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04
	3.0V to 3.6V	-40°C to +150°C	20

TABLE 32-2: THERMAL OPERATING CONDITIONS

Rating	Symbol	Min	Typ	Max	Unit
High Temperature Devices					
Operating Junction Temperature Range	T <sub>J</sub>	-40	—	+155	°C
Operating Ambient Temperature Range	T <sub>A</sub>	-40	—	+150	°C
Power Dissipation:					
Internal chip power dissipation: $P_{INT} = V_{DD} \times (I_{DD} - \sum I_{OH})$	P <sub>D</sub>	$P_{INT} + P_{I/O}$			W
I/O Pin Power Dissipation: $I/O = \sum (\{V_{DD} - V_{OH}\} \times I_{OH}) + \sum (V_{OL} \times I_{OL})$					
Maximum Allowed Power Dissipation	P <sub>DMAX</sub>	$(T_J - T_A)/\theta_{JA}$			W

TABLE 32-3: DC TEMPERATURE AND VOLTAGE SPECIFICATIONS

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$ for High Temperature				
Parameter No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
<b>Operating Voltage</b>							
HDC10	Supply Voltage						
	V <sub>DD</sub>	—	3.0	3.3	3.6	V	-40°C to +150°C

TABLE 32-4: DC CHARACTERISTICS: POWER-DOWN CURRENT (IPD)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$ for High Temperature				
Parameter No.	Typical	Max	Units	Conditions			
<b>Power-Down Current (IPD)</b>							
HDC60e	250	2000	μA	+150°C	3.3V	Base Power-Down Current <sup>(1,3)</sup>	
HDC61c	3	5	μA	+150°C	3.3V	Watchdog Timer Current: ΔI <sub>WDT</sub> <sup>(2,4)</sup>	

**Note 1:** Base IPD is measured with all peripherals and clocks shut down. All I/Os are configured as inputs and pulled to V<sub>SS</sub>. WDT, etc., are all switched off, and VREGS (RCON<8>) = 1.

**2:** The Δ current is the additional current consumed when the module is enabled. This current should be added to the base IPD current.

**3:** These currents are measured on the device containing the most memory in this family.

**4:** These parameters are characterized, but are not tested in manufacturing.

**TABLE 32-5: DC CHARACTERISTICS: DOZE CURRENT (IDOZE)**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature				
Parameter No.	Typical <sup>(1)</sup>	Max	Doze Ratio	Units	Conditions		
HDC72a	39	45	1:2	mA	+150°C	3.3V	20 MIPS
HDC72f	18	25	1:64	mA			
HDC72g	18	25	1:128	mA			

**Note 1:** Parameters with Doze ratios of 1:2 and 1:64 are characterized, but are not tested in manufacturing.

**TABLE 32-6: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
HDO10 HDO16	VOL	<b>Output Low Voltage</b> I/O ports OSC2/CLKO	—	—	0.4	V	IOL = 1 mA, VDD = 3.3V
			—	—	0.4	V	IOL = 1 mA, VDD = 3.3V
HDO20 HDO26	VOH	<b>Output High Voltage</b> I/O ports OSC2/CLKO	2.40	—	—	V	IOH = -1 mA, VDD = 3.3V
			2.41	—	—	V	IOH = -1 mA, VDD = 3.3V

**TABLE 32-7: DC CHARACTERISTICS: PROGRAM MEMORY**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
HD130 HD134	EP TRETD	<b>Program Flash Memory</b> Cell Endurance Characteristic Retention	10,000 20	— —	— —	E/W Year	-40°C to +150°C <sup>(2)</sup> 1000 E/W cycles or less and no other specifications are violated

**Note 1:** These parameters are assured by design, but are not characterized or tested in manufacturing.

**2:** Programming of the Flash memory is not allowed above 125°C.

## 32.2 AC Characteristics and Timing Parameters

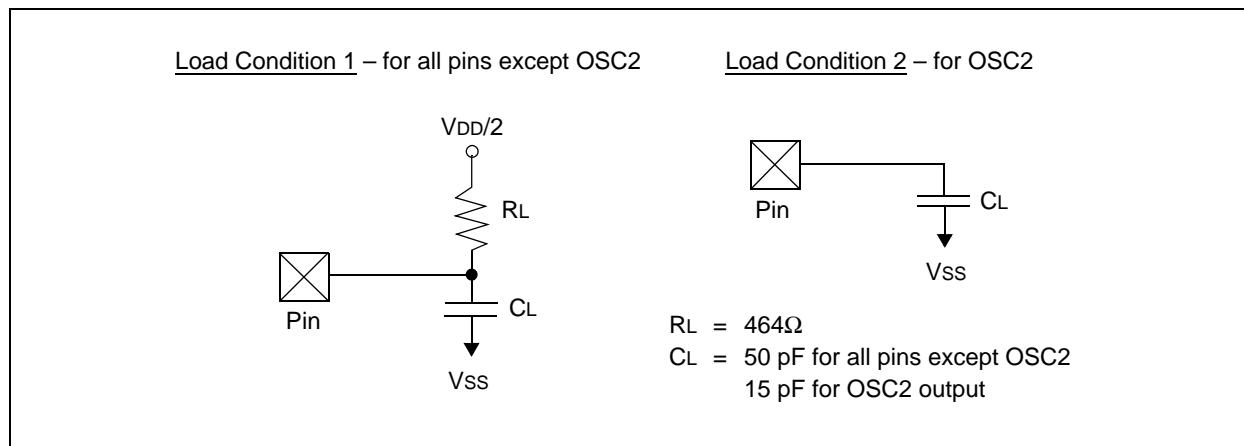
The information contained in this section defines dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 AC characteristics and timing parameters for high temperature devices. However, all AC timing specifications in this section are the same as those in [Section 31.2 “AC Characteristics and Timing Parameters”](#), with the exception of the parameters listed in this section.

Parameters in this section begin with an H, which denotes High temperature. For example, parameter OS53 in [Section 31.2 “AC Characteristics and Timing Parameters”](#) is the Industrial and Extended temperature equivalent of HOS53.

**TABLE 32-8: TEMPERATURE AND VOLTAGE SPECIFICATIONS – AC**

<b>AC CHARACTERISTICS</b>	<b>Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)</b> Operating temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +150^{\circ}\text{C}$ for High Temperature Operating voltage VDD range as described in <a href="#">Table 32-1</a> .
---------------------------	---

**FIGURE 32-1: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS**



**TABLE 32-9: PLL CLOCK TIMING SPECIFICATIONS**

<b>AC CHARACTERISTICS</b>		<b>Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)</b> Operating temperature $-40^{\circ}\text{C} \leq \text{TA} \leq +150^{\circ}\text{C}$ for High Temperature					
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
HOS53	DCLK	CLKO Stability (Jitter) <sup>(1)</sup>	-5	0.5	5	%	Measured over 100 ms period

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**TABLE 32-10: SPI<sub>x</sub> MASTER MODE (CKE = 0) TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
HSP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	10	25	ns	—
HSP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	28	—	—	ns	—
HSP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	35	—	—	ns	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

**TABLE 32-11: SPI<sub>x</sub> MODULE MASTER MODE (CKE = 1) TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
HSP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	10	25	ns	—
HSP36	TdoV2sc, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	35	—	—	ns	—
HSP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	28	—	—	ns	—
HSP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	35	—	—	ns	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

**TABLE 32-12: SPI<sub>x</sub> MODULE SLAVE MODE (CKE = 0) TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
HSP35	TscH2doV, TscL2doV	SDO <sub>x</sub> Data Output Valid after SCK <sub>x</sub> Edge	—	—	35	ns	—
HSP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCK <sub>x</sub> Edge	25	—	—	ns	—
HSP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCK <sub>x</sub> Edge	25	—	—	ns	—
HSP51	TssH2doZ	SS <sub>x</sub> ↑ to SDO <sub>x</sub> Output High-Impedance	15	—	55	ns	See Note 2

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Assumes 50 pF load on all SPI<sub>x</sub> pins.

**TABLE 32-13: SPI<sub>x</sub> MODULE SLAVE MODE (CKE = 1) TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
HSP35	TscH2doV, TscL2doV	SDO <sub>x</sub> Data Output Valid after SCK <sub>x</sub> Edge	—	—	35	ns	—
HSP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCK <sub>x</sub> Edge	25	—	—	ns	—
HSP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCK <sub>x</sub> Edge	25	—	—	ns	—
HSP51	TssH2doZ	SS <sub>x</sub> ↑ to SDO <sub>x</sub> Output High-Impedance	15	—	55	ns	See Note 2
HSP60	TssL2doV	SDO <sub>x</sub> Data Output Valid after SS <sub>x</sub> Edge	—	—	55	ns	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Assumes 50 pF load on all SPI<sub>x</sub> pins.

**TABLE 32-14: ADC MODULE SPECIFICATIONS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature					
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
<b>Reference Inputs</b>							
HAD08	IREF	Current Drain	—	250	600	μA	ADC operating, See <b>Note 1</b>
			—	—	50	μA	ADC off, See <b>Note 1</b>

**Note 1:** These parameters are not characterized or tested in manufacturing.

2: These parameters are characterized, but are not tested in manufacturing.

**TABLE 32-15: ADC MODULE SPECIFICATIONS (12-BIT MODE)**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature					
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
<b>ADC Accuracy (12-bit Mode) – Measurements with External V<sub>REF+</sub>/V<sub>REF-</sub><sup>(1)</sup></b>							
HAD20a	Nr	Resolution <sup>(3)</sup>	12 data bits			bits	—
HAD21a	INL	Integral Nonlinearity	-2	—	+2	Lsb	V <sub>INL</sub> = AVSS = V <sub>REFL</sub> = 0V, AVDD = V <sub>REFH</sub> = 3.6V
HAD22a	DNL	Differential Nonlinearity	> -1	—	< 1	Lsb	V <sub>INL</sub> = AVSS = V <sub>REFL</sub> = 0V, AVDD = V <sub>REFH</sub> = 3.6V
HAD23a	GERR	Gain Error	-2	—	10	Lsb	V <sub>INL</sub> = AVSS = V <sub>REFL</sub> = 0V, AVDD = V <sub>REFH</sub> = 3.6V
HAD24a	E <sub>OFF</sub>	Offset Error	-3	—	5	Lsb	V <sub>INL</sub> = AVSS = V <sub>REFL</sub> = 0V, AVDD = V <sub>REFH</sub> = 3.6V
<b>ADC Accuracy (12-bit Mode) – Measurements with Internal V<sub>REF+</sub>/V<sub>REF-</sub><sup>(1)</sup></b>							
HAD20a	Nr	Resolution <sup>(3)</sup>	12 data bits			bits	—
HAD21a	INL	Integral Nonlinearity	-2	—	+2	Lsb	V <sub>INL</sub> = AVSS = 0V, AVDD = 3.6V
HAD22a	DNL	Differential Nonlinearity	> -1	—	< 1	Lsb	V <sub>INL</sub> = AVSS = 0V, AVDD = 3.6V
HAD23a	GERR	Gain Error	2	—	20	Lsb	V <sub>INL</sub> = AVSS = 0V, AVDD = 3.6V
HAD24a	E <sub>OFF</sub>	Offset Error	2	—	10	Lsb	V <sub>INL</sub> = AVSS = 0V, AVDD = 3.6V
<b>Dynamic Performance (12-bit Mode)<sup>(2)</sup></b>							
HAD33a	F <sub>NYQ</sub>	Input Signal Bandwidth	—	—	200	kHz	—

**Note 1:** These parameters are characterized, but are tested at 20 ksps only.

2: These parameters are characterized by similarity, but are not tested in manufacturing.

3: Injection currents &gt; | 0 | can affect the ADC results by approximately 4-6 counts.

TABLE 32-16: ADC MODULE SPECIFICATIONS (10-BIT MODE)

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature					
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
<b>ADC Accuracy (10-bit Mode) – Measurements with External VREF+/VREF-(<sup>(1)</sup>)</b>							
HAD20b	Nr	Resolution <sup>(3)</sup>	10 data bits			bits	—
HAD21b	INL	Integral Nonlinearity	-3	—	3	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
HAD22b	DNL	Differential Nonlinearity	> -1	—	< 1	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
HAD23b	GERR	Gain Error	-5	—	6	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
HAD24b	Eoff	Offset Error	-1	—	5	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V
<b>ADC Accuracy (10-bit Mode) – Measurements with Internal VREF+/VREF-(<sup>(1)</sup>)</b>							
HAD20b	Nr	Resolution <sup>(3)</sup>	10 data bits			bits	—
HAD21b	INL	Integral Nonlinearity	-2	—	2	LSb	VINL = AVSS = 0V, AVDD = 3.6V
HAD22b	DNL	Differential Nonlinearity	> -1	—	< 1	LSb	VINL = AVSS = 0V, AVDD = 3.6V
HAD23b	GERR	Gain Error	-5	—	15	LSb	VINL = AVSS = 0V, AVDD = 3.6V
HAD24b	Eoff	Offset Error	-1.5	—	7	LSb	VINL = AVss = 0V, AVDD = 3.6V
<b>Dynamic Performance (10-bit Mode)<sup>(2)</sup></b>							
HAD33b	FNYQ	Input Signal Bandwidth	—	—	400	kHz	—

**Note 1:** These parameters are characterized, but are tested at 20 kspS only.

**2:** These parameters are characterized by similarity, but are not tested in manufacturing.

**3:** Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts.

**TABLE 32-17: ADC CONVERSION (12-BIT MODE) TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature					
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
<b>Clock Parameters</b>							
HAD50	TAD	ADC Clock Period <sup>(1)</sup>	147	—	—	ns	—
<b>Conversion Rate</b>							
HAD56	FCNV	Throughput Rate <sup>(1)</sup>	—	—	400	Ksps	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

**TABLE 32-18: ADC CONVERSION (10-BIT MODE) TIMING REQUIREMENTS**

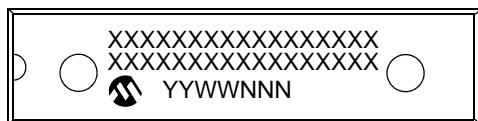
AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature					
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
<b>Clock Parameters</b>							
HAD50	TAD	ADC Clock Period <sup>(1)</sup>	104	—	—	ns	—
<b>Conversion Rate</b>							
HAD56	FCNV	Throughput Rate <sup>(1)</sup>	—	—	800	Ksps	—

**Note 1:** These parameters are characterized but not tested in manufacturing.

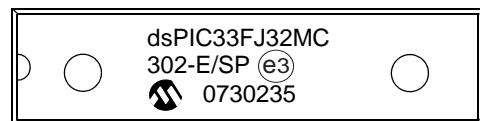
**NOTES:**

### 33.0 PACKAGING INFORMATION

28-Lead SPDIP



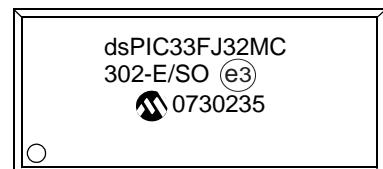
Example



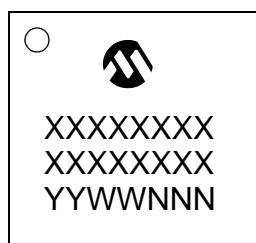
28-Lead SOIC (.300")



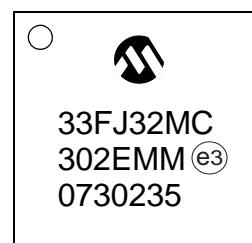
Example



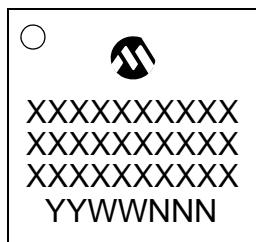
28-Lead QFN-S



Example



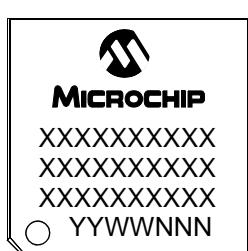
44-Lead QFN



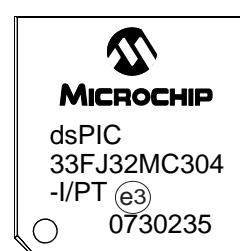
Example



44-Lead TQFP



Example



**Legend:** XX...X Customer-specific information

Y Year code (last digit of calendar year)

YY Year code (last 2 digits of calendar year)

WW Week code (week of January 1 is week '01')

NNN Alphanumeric traceability code

(e3) Pb-free JEDEC designator for Matte Tin (Sn)

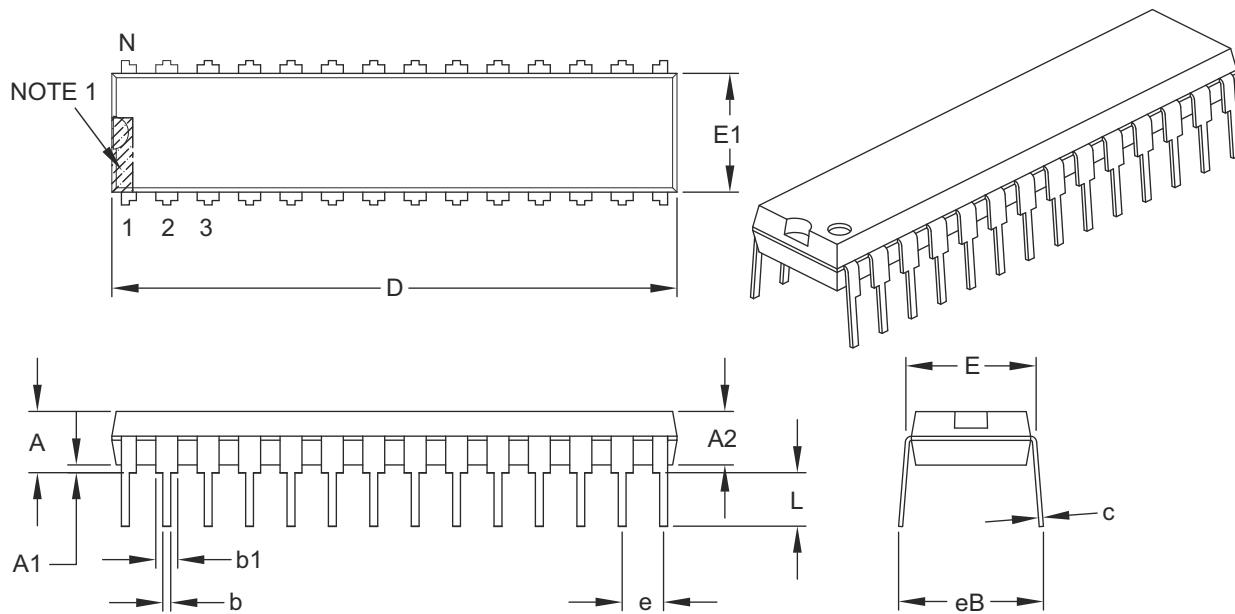
\* This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.

**Note:** If the full Microchip part number cannot be marked on one line, it is carried over to the next line, thus limiting the number of available characters for customer-specific information.

### 33.1 Package Details

#### 28-Lead Skinny Plastic Dual In-Line (SP) – 300 mil Body [SPDIP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		INCHES		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N		28	
Pitch	e		.100 BSC	
Top to Seating Plane	A	—	—	.200
Molded Package Thickness	A2	.120	.135	.150
Base to Seating Plane	A1	.015	—	—
Shoulder to Shoulder Width	E	.290	.310	.335
Molded Package Width	E1	.240	.285	.295
Overall Length	D	1.345	1.365	1.400
Tip to Seating Plane	L	.110	.130	.150
Lead Thickness	c	.008	.010	.015
Upper Lead Width	b1	.040	.050	.070
Lower Lead Width	b	.014	.018	.022
Overall Row Spacing §	eB	—	—	.430

##### Notes:

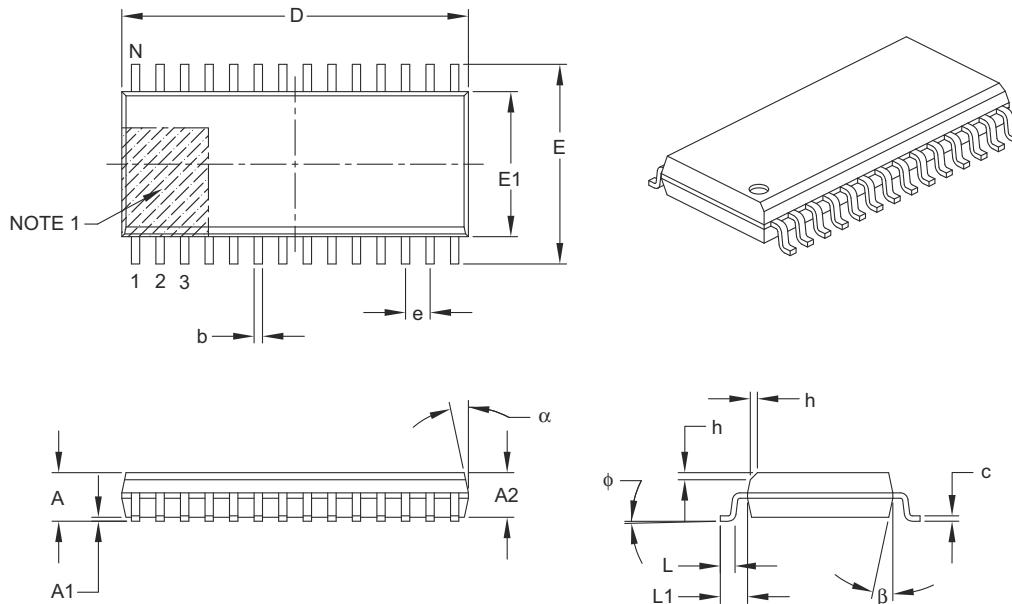
1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic.
3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
4. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-070B

**28-Lead Plastic Small Outline (SO) – Wide, 7.50 mm Body [SOIC]**

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



		Units	MILLIMETERS		
		Dimension Limits	MIN	NOM	MAX
Number of Pins		N	28		
Pitch		e	1.27 BSC		
Overall Height		A	–	–	2.65
Molded Package Thickness		A2	2.05	–	–
Standoff §		A1	0.10	–	0.30
Overall Width		E	10.30 BSC		
Molded Package Width		E1	7.50 BSC		
Overall Length		D	17.90 BSC		
Chamfer (optional)		h	0.25	–	0.75
Foot Length		L	0.40	–	1.27
Footprint		L1	1.40 REF		
Foot Angle Top		phi	0°	–	8°
Lead Thickness		c	0.18	–	0.33
Lead Width		b	0.31	–	0.51
Mold Draft Angle Top		alpha	5°	–	15°
Mold Draft Angle Bottom		beta	5°	–	15°

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic.
3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side.
4. Dimensioning and tolerancing per ASME Y14.5M.

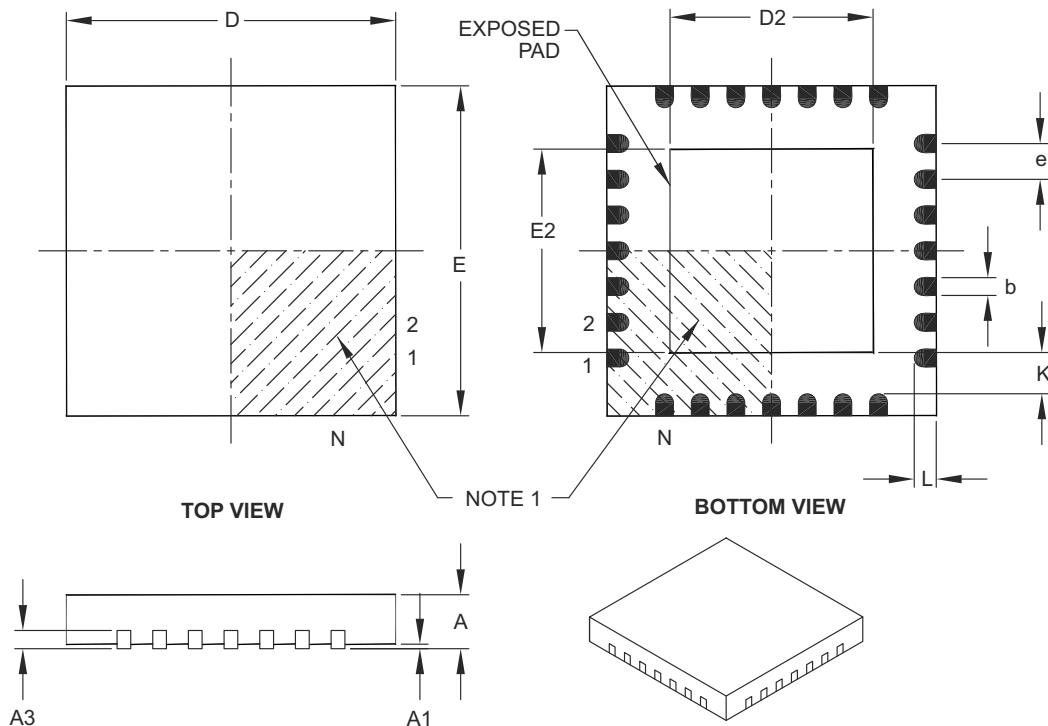
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-052B

**28-Lead Plastic Quad Flat, No Lead Package (MM) – 6x6x0.9 mm Body [QFN-S]  
with 0.40 mm Contact Length**

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



		Units	MILLIMETERS		
Dimension Limits			MIN	NOM	MAX
Number of Pins	N		28		
Pitch	e		0.65	BSC	
Overall Height	A	0.80	0.90	1.00	
Standoff	A1	0.00	0.02	0.05	
Contact Thickness	A3	0.20 REF			
Overall Width	E	6.00 BSC			
Exposed Pad Width	E2	3.65	3.70	4.70	
Overall Length	D	6.00 BSC			
Exposed Pad Length	D2	3.65	3.70	4.70	
Contact Width	b	0.23	0.38	0.43	
Contact Length	L	0.30	0.40	0.50	
Contact-to-Exposed Pad	K	0.20	–	–	

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Package is saw singulated.

3. Dimensioning and tolerancing per ASME Y14.5M.

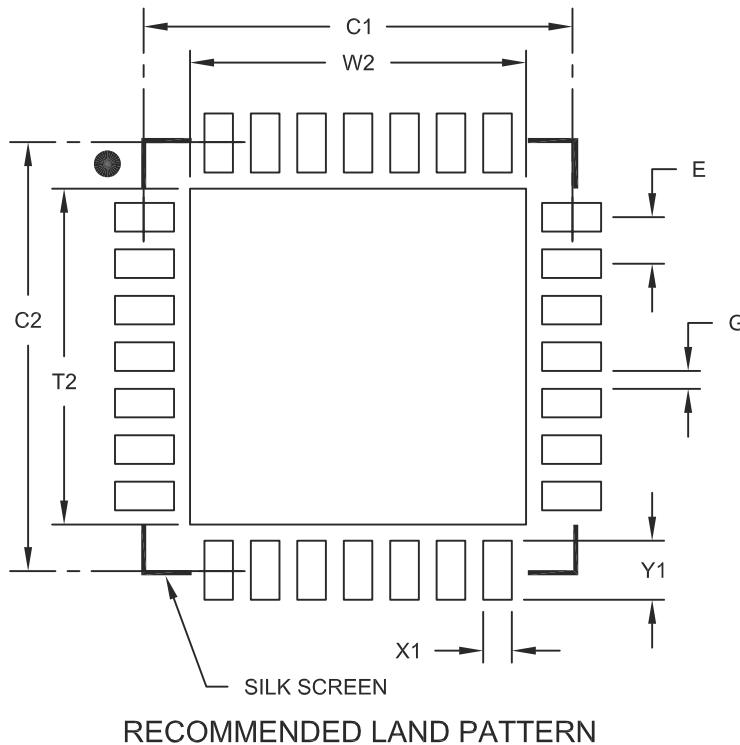
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-124B

**28-Lead Plastic Quad Flat, No Lead Package (MM) – 6x6x0.9 mm Body [QFN-S]  
with 0.40 mm Contact Length**

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		0.65	BSC
Optional Center Pad Width	W2			4.70
Optional Center Pad Length	T2			4.70
Contact Pad Spacing	C1		6.00	
Contact Pad Spacing	C2		6.00	
Contact Pad Width (X28)	X1			0.40
Contact Pad Length (X28)	Y1			0.85
Distance Between Pads	G	0.25		

Notes:

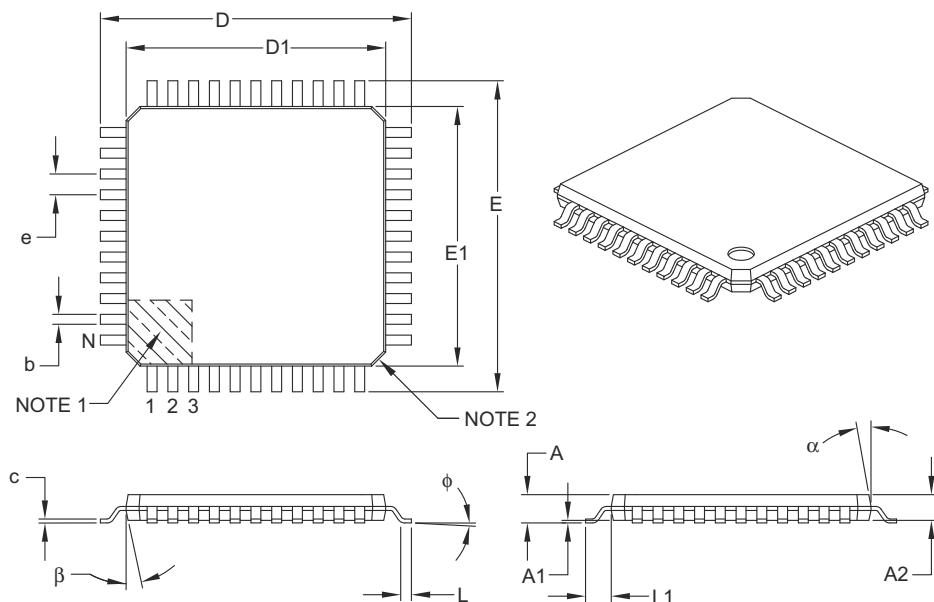
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2124A

**44-Lead Plastic Thin Quad Flatpack (PT) – 10x10x1 mm Body, 2.00 mm [TQFP]**

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



		Units			MILLIMETERS		
		Dimension Limits			MIN	NOM	MAX
Number of Leads	N				44		
Lead Pitch	e				0.80 BSC		
Overall Height	A	—	—	—	—	—	1.20
Molded Package Thickness	A2	0.95	1.00	1.05			
Standoff	A1	0.05	—	0.15			
Foot Length	L	0.45	0.60	0.75			
Footprint	L1	1.00 REF					
Foot Angle	φ	0°	3.5°	7°			
Overall Width	E	12.00 BSC					
Overall Length	D	12.00 BSC					
Molded Package Width	E1	10.00 BSC					
Molded Package Length	D1	10.00 BSC					
Lead Thickness	c	0.09	—	0.20			
Lead Width	b	0.30	0.37	0.45			
Mold Draft Angle Top	α	11°	12°	13°			
Mold Draft Angle Bottom	β	11°	12°	13°			

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Chamfers at corners are optional; size may vary.
3. Dimensions D1 and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25 mm per side.
4. Dimensioning and tolerancing per ASME Y14.5M.

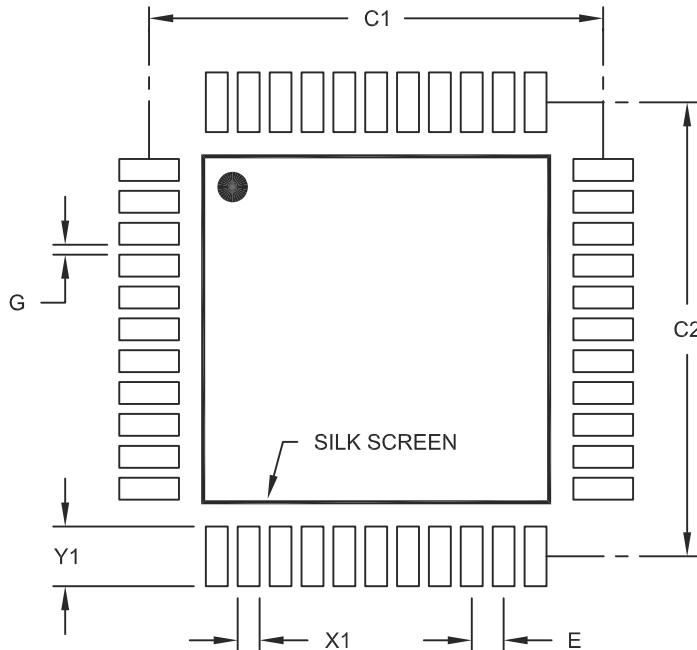
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-076B

**44-Lead Plastic Thin Quad Flatpack (PT) – 10x10x1 mm Body, 2.00 mm [TQFP]**

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Dimension	Limits	UNITS MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E		0.80	BSC
Contact Pad Spacing	C1		11.40	
Contact Pad Spacing	C2		11.40	
Contact Pad Width (X44)	X1			0.55
Contact Pad Length (X44)	Y1			1.50
Distance Between Pads	G	0.25		

Notes:

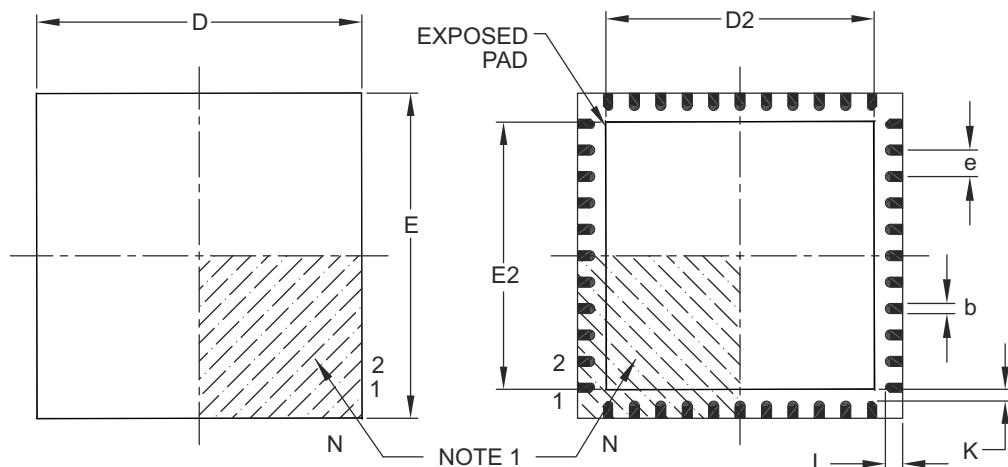
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2076A

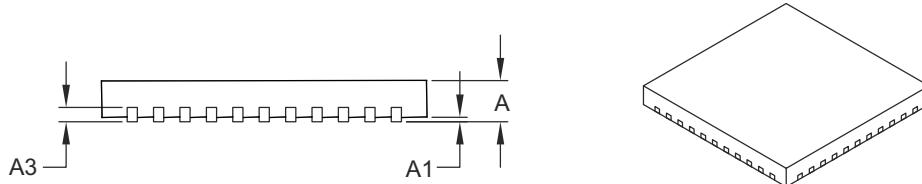
**44-Lead Plastic Quad Flat, No Lead Package (ML) – 8x8 mm Body [QFN]**

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



TOP VIEW

BOTTOM VIEW



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N		44	
Pitch	e		0.65 BSC	
Overall Height	A	0.80	0.90	1.00
Standoff	A1	0.00	0.02	0.05
Contact Thickness	A3		0.20 REF	
Overall Width	E		8.00 BSC	
Exposed Pad Width	E2	6.30	6.45	6.80
Overall Length	D		8.00 BSC	
Exposed Pad Length	D2	6.30	6.45	6.80
Contact Width	b	0.25	0.30	0.38
Contact Length	L	0.30	0.40	0.50
Contact-to-Exposed Pad	K	0.20	–	–

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Package is saw singulated.

3. Dimensioning and tolerancing per ASME Y14.5M.

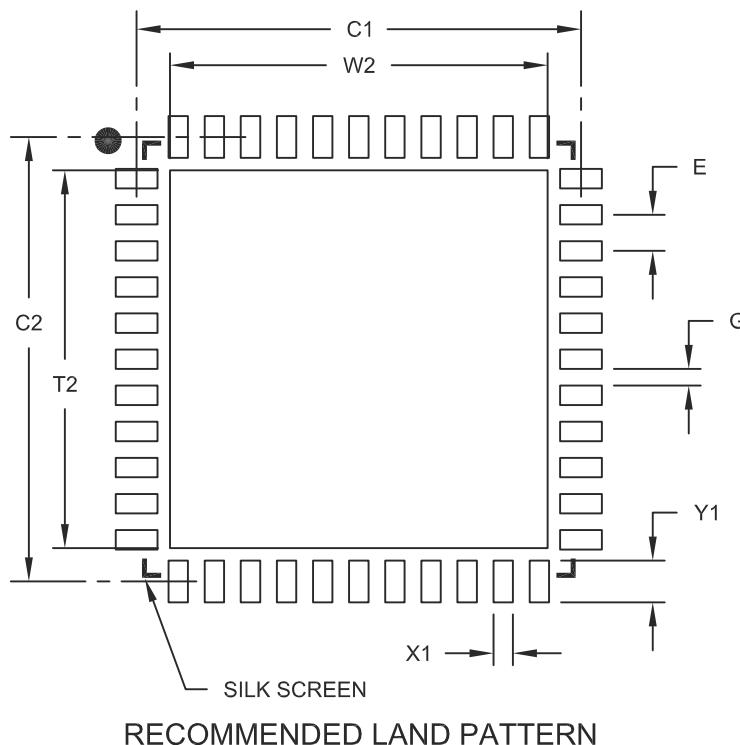
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-103B

**44-Lead Plastic Quad Flat, No Lead Package (ML) – 8x8 mm Body [QFN]**

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.65	BSC	
Optional Center Pad Width	W2			6.80
Optional Center Pad Length	T2			6.80
Contact Pad Spacing	C1	8.00		
Contact Pad Spacing	C2	8.00		
Contact Pad Width (X44)	X1			0.35
Contact Pad Length (X44)	Y1			0.80
Distance Between Pads	G	0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2103A

**NOTES:**

## APPENDIX A: REVISION HISTORY

### Revision A (August 2007)

Initial release of this document.

### Revision B (March 2008)

This revision includes minor typographical and formatting changes throughout the data sheet text. In addition, redundant information was removed that is now available in the respective chapters of the “*dsPIC33F/PIC24H Family Reference Manual*”, which can be obtained from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

The major changes are referenced by their respective section in the following table.

**TABLE A-1: MAJOR SECTION UPDATES**

Section Name	Update Description
“High-Performance, 16-bit Digital Signal Controllers”	Note 1 added to all pin diagrams (see “Pin Diagrams”) Add External Interrupts column and Note 4 to the “ <b>dsPIC33FJ32MC302/304, dsPIC33FJ64MCX02/X04 and dsPIC33FJ128MCX02/X04 Controller Families</b> ” table
Section 1.0 “Device Overview”	Updated parameters PMA0, PMA1 and PMD0 through PMPD7 (Table 1-1)
Section 3.0 “Memory Organization”	Updated FAEN bits in Table 4-8
Section 6.0 “Interrupt Controller”	IFS0-IFS04 changed to IFSx (see <b>Section 6.3.2 “IFSx”</b> ) IEC0-IEC4 changed to IECx (see <b>Section 6.3.3 “IECx”</b> ) IPC0-IPC19 changed to IPCx (see <b>Section 6.3.4 “IPCx”</b> )
Section 7.0 “Direct Memory Access (DMA)”	Updated parameter PMP (see Table 8-1)
Section 8.0 “Oscillator Configuration”	Updated the third clock source item (External Clock) in <b>Section 8.1.1 “System Clock Sources”</b> Updated TUN<5:0> (OSCTUN<5:0>) bit description (see Register 8-4)
Section 21.0 “10-bit/12-bit Analog-to-Digital Converter (ADC1)”	Added Note 2 to Figure 21-3
Section 27.0 “Special Features”	Added Note 2 to Figure 27-1 Added parameter FICD in Table 27-1 Added parameters BKBUG, COE, JTGEN and ICS in Table 27-2 Added Note after second paragraph in <b>Section 27.2 “On-Chip Voltage Regulator”</b>

**TABLE A-1: MAJOR SECTION UPDATES (CONTINUED)**

Section Name	Update Description
<b>Section 30.0 “Electrical Characteristics”</b>	<p>Updated Max MIPS for temperature range of -40°C to +125°C in Table 30-1</p> <p>Updated typical values in Thermal Packaging Characteristics in Table 30-3</p> <p>Added parameters DI11 and DI12 to Table 30-9</p> <p>Updated minimum values for parameters D136 (TRW) and D137 (TPE) and removed typical values in Table 30-12</p> <p>Added Extended temperature range to Table 30-13</p> <p>Updated Note 2 in Table 30-38</p> <p>Updated parameter AD63 and added Note 3 to Table 30-42 and Table 30-43</p>

**Revision C (May 2009)**

This revision includes minor typographical and formatting changes throughout the data sheet text.

Global changes include:

- Changed all instances of OSCI to OSC1 and OSCO to OSC2
- Changed all instances of VDDCORE and VDDCORE/VCAP to VCAP/VDDCORE

The other changes are referenced by their respective section in the following table.

**TABLE A-2: MAJOR SECTION UPDATES**

Section Name	Update Description
“High-Performance, 16-bit Digital Signal Controllers”	Updated all pin diagrams to denote the pin voltage tolerance (see “Pin Diagrams”). Added Note 2 to the 28-Pin QFN-S and 44-Pin QFN pin diagrams, which references pin connections to Vss.
Section 1.0 “Device Overview”	Updated AVDD in the PINOUT I/O Descriptions (see Table 1-1).
Section 2.0 “Guidelines for Getting Started with 16-bit Digital Signal Controllers”	Added new section to the data sheet that provides guidelines on getting started with 16-bit Digital Signal Controllers.
Section 3.0 “CPU”	Updated CPU Core Block Diagram with a connection from the DSP Engine to the Y Data Bus (see Figure 3-1). Vertically extended the X and Y Data Bus lines in the DSP Engine Block Diagram (see Figure 3-3).
Section 4.0 “Memory Organization”	Updated Reset value for CORCON in the CPU Core Register Map (see Table 4-1). Removed the FLTA1IE bit (IEC3) from the Interrupt Controller Register Map (see Table 4-4). Updated bit locations for RPINR25 in the Peripheral Pin Select Input Register Map (see Table 4-24). Updated the Reset value for CLKDIV in the System Control Register Map (see Table 4-36).
Section 5.0 “Flash Program Memory”	Updated <b>Section 5.3 “Programming Operations”</b> with programming time formula.
Section 9.0 “Oscillator Configuration”	Updated the Oscillator System Diagram and added Note 2 (see Figure 9-1). Updated default bit values for DOZE<2:0> and FRCDIV<2:0> in the Clock Divisor (CLKDIV) Register (see Register 9-2). Added a paragraph regarding FRC accuracy at the end of <b>Section 9.1.1 “System Clock Sources”</b> . Added Note 3 to <b>Section 9.2.2 “Oscillator Switching Sequence”</b> . Added Note 1 to the FRC Oscillator Tuning (OSCTUN) Register (see Register 9-4).
Section 10.0 “Power-Saving Features”	Added the following registers: <ul style="list-style-type: none"> <li>• PMD1: Peripheral Module Disable Control Register 1 (Register 10-1)</li> <li>• PMD2: Peripheral Module Disable Control Register 2 (Register 10-2)</li> <li>• PMD3: Peripheral Module Disable Control Register 3 (Register 10-3)</li> </ul>

**TABLE A-2: MAJOR SECTION UPDATES (CONTINUED)**

Section Name	Update Description
<b>Section 11.0 “I/O Ports”</b>	Removed Table 11-1 and added reference to pin diagrams for I/O pin availability and functionality.  Added paragraph on ADPCFG register default values to <b>Section 11.3 “Configuring Analog Port Pins”</b> .  Added Note box regarding PPS functionality with input mapping to <b>Section 11.6.2.1 “Input Mapping”</b> .
<b>Section 18.0 “Serial Peripheral Interface (SPI)”</b>	Added Note 2 and 3 to the SPIxCON1 register (see Register 18-2).
<b>Section 20.0 “Universal Asynchronous Receiver Transmitter (UART)”</b>	Updated the Notes in the UxMODE register (see Register 20-1).  Updated the UTXINV bit settings in the UxSTA register and added Note 1 (see Register 20-2).
<b>Section 21.0 “Enhanced CAN (ECAN™) Module”</b>	Changed bit 11 in the ECAN Control Register 1 (CiCTRL1) to Reserved (see Register 21-1).
<b>Section 22.0 “10-bit/12-bit Analog-to-Digital Converter (ADC1)”</b>	Replaced the ADC1 Module Block Diagrams with new diagrams (see Figure 22-1 and Figure 22-2).  Updated bit values for ADCS<7:0> and added Notes 1 and 2 to the ADC1 Control Register 3 (AD1CON3) (see Register 22-3).  Added Note 2 to the ADC1 Input Scan Select Register Low (AD1CSSL) (see Register 22-7).  Added Note 2 to the ADC1 Port Configuration Register Low (AD1PCFGL) (see Register 22-8).
<b>Section 23.0 “Audio Digital-to-Analog Converter (DAC)”</b>	Updated the midpoint voltage in the last sentence of the first paragraph.  Updated the voltage swing values in the last sentence of the last paragraph in <b>Section 23.3 “DAC Output Format”</b> .
<b>Section 24.0 “Comparator Module”</b>	Updated the Comparator Voltage Reference Block Diagram (see Figure 24-2).
<b>Section 25.0 “Real-Time Clock and Calendar (RTCC)”</b>	Updated the minimum positive adjust value for CAL<7:0> in the RTCC Calibration and Configuration (RCFGCAL) Register (see Register 25-1).
<b>Section 28.0 “Special Features”</b>	Added Note 1 to the Device Configuration Register Map (see Table 28-1).  Updated Note 1 in the dsPIC33F Configuration Bits Description (see Table 28-2).

**TABLE A-2: MAJOR SECTION UPDATES (CONTINUED)**

Section Name	Update Description
<b>Section 31.0 “Electrical Characteristics”</b>	<p>Updated Typical values for Thermal Packaging Characteristics (see Table 31-3).</p> <p>Updated Min and Max values for parameter DC12 (RAM Data Retention Voltage) and added Note 4 (see Table 31-4).</p> <p>Updated Power-Down Current Max values for parameters DC60b and DC60c (see Table 31-7).</p> <p>Updated Characteristics for I/O Pin Input Specifications (see Table 31-9).</p> <p>Updated Program Memory values for parameters 136, 137 and 138 (renamed to 136a, 137a and 138a), added parameters 136b, 137b and 138b, and added Note 2 (see Table 31-12).</p> <p>Added parameter OS42 (GM) to the External Clock Timing Requirements (see Table 31-16).</p> <p>Updated Watchdog Timer Time-out Period parameter SY20 (see Table 31-21).</p> <p>Removed VOMIN, renamed VOMAX to VO, and updated the Min and Max values in the Audio DAC Module Specifications (see Table 31-44).</p>

## Revision D (November 2009)

The revision includes the following global update:

- Added Note 2 to the shaded table that appears at the beginning of each chapter. This new note provides information regarding the availability of registers and their associated bits

This revision also includes minor typographical and formatting changes throughout the data sheet text.

All other major changes are referenced by their respective section in the following table.

**TABLE A-3: MAJOR SECTION UPDATES**

Section Name	Update Description
<b>"High-Performance, 16-bit Digital Signal Controllers"</b>	Added information on high temperature operation (see " <b>Operating Range:</b> ").
<b>Section 11.0 "I/O Ports"</b>	Changed the reference to digital-only pins to 5V tolerant pins in the second paragraph of <b>Section 11.2 "Open-Drain Configuration"</b> .
<b>Section 20.0 "Universal Asynchronous Receiver Transmitter (UART)"</b>	Updated the two baud rate range features to: 10 Mbps to 38 bps at 40 MIPS.
<b>Section 22.0 "10-bit/12-bit Analog-to-Digital Converter (ADC1)"</b>	Updated the ADC block diagrams (see Figure 22-1 and Figure 22-2).
<b>Section 23.0 "Audio Digital-to-Analog Converter (DAC)"</b>	Removed last sentence of the first paragraph in the section. Added a shaded note to <b>Section 23.2 "DAC Module Operation"</b> . Updated Figure 23-2: "Audio DAC Output for Ramp Input (Unsigned)".
<b>Section 28.0 "Special Features"</b>	Updated the second paragraph and removed the fourth paragraph in <b>Section 28.1 "Configuration Bits"</b> . Updated the Device Configuration Register Map (see Table 28-1).
<b>Section 31.0 "Electrical Characteristics"</b>	Updated the Absolute Maximum Ratings for high temperature and added Note 4. Removed parameters DI26, DI28 and DI29 from the I/O Pin Input Specifications (see Table 31-9). Updated the SPIx Module Slave Mode (CKE = 1) Timing Characteristics (see Figure 31-17). Removed Table 31-45: Audio DAC Module Specifications. Original contents were updated and combined with Table 31-44 of the same name.
<b>Section 32.0 "High Temperature Electrical Characteristics"</b>	Added new chapter with high temperature specifications.
<b>"Product Identification System"</b>	Added the "H" definition for high temperature.

**Revision E (January 2011)**

This revision includes typographical and formatting changes throughout the data sheet text. In addition, the Preliminary marking in the footer was removed.

All instances of VDDCORE have been removed.

All other major changes are referenced by their respective section in the following table.

**TABLE A-4: MAJOR SECTION UPDATES**

Section Name	Update Description
<b>“High-Performance, 16-bit Digital Signal Controllers”</b>	The high temperature end range was updated to +150°C (see “Operating Range:”).
<b>Section 2.0 “Guidelines for Getting Started with 16-bit Digital Signal Controllers”</b>	Updated the title of <b>Section 2.3 “CPU Logic Filter Capacitor Connection (VCAP)”</b> .  The frequency limitation for device PLL start-up conditions was updated in <b>Section 2.7 “Oscillator Value Conditions on Device Start-up”</b> .  The second paragraph in <b>Section 2.9 “Unused I/Os”</b> was updated.
<b>Section 4.0 “Memory Organization”</b>	The All Resets values for the following SFRs in the Timer Register Map were changed (see Table 4-5): <ul style="list-style-type: none"> <li>• TMR1</li> <li>• TMR2</li> <li>• TMR3</li> <li>• TMR4</li> <li>• TMR5</li> </ul>
<b>Section 9.0 “Oscillator Configuration”</b>	Added Note 3 to the OSCCON: Oscillator Control Register (see Register 9-1).  Added Note 2 to the CLKDIV: Clock Divisor Register (see Register 9-2).  Added Note 1 to the PLLFBD: PLL Feedback Divisor Register (see Register 9-3).  Added Note 2 to the OSCTUN: FRC Oscillator Tuning Register (see Register 9-4).  Added Note 1 to the ACLKCON: Auxiliary Control Register (see Register 9-5).
<b>Section 22.0 “10-bit/12-bit Analog-to-Digital Converter (ADC1)”</b>	Updated the VREFL references in the ADC1 module block diagrams (see Figure 22-1 and Figure 22-2).
<b>Section 28.0 “Special Features”</b>	Added a new paragraph and removed the third paragraph in <b>Section 28.1 “Configuration Bits”</b> .  Added the column “RTSP Effects” to the dsPIC33F Configuration Bits Descriptions (see Table 28-2).

**TABLE A-4: MAJOR SECTION UPDATES (CONTINUED)**

Section Name	Update Description
<b>Section 31.0 “Electrical Characteristics”</b>	<p>Updated the maximum value for Extended Temperature Devices in the Thermal Operating Conditions (see Table 31-2).</p> <p>Removed Note 4 from the DC Temperature and Voltage Specifications (see Table 31-4).</p> <p>Updated all typical and maximum Operating Current (IDD) values (see Table 31-5).</p> <p>Updated all typical and maximum Idle Current (IDLE) values (see Table 31-6).</p> <p>Updated the maximum Power-Down Current (IPD) values for parameters DC60d, DC60a, and DC60b (see Table 31-7).</p> <p>Updated all typical Doze Current (Idoze) values (see Table 31-8).</p> <p>Updated the maximum value for parameter DI19 and added parameters DI28, DI29, DI60a, DI60b, and DI60c to the I/O Pin Input Specifications (see Table 31-9).</p> <p>Added Note 2 to the PLL Clock Timing Specifications (see Table 31-17)</p> <p>Removed Note 2 from the AC Characteristics: Internal RC Accuracy (see Table 31-18).</p> <p>Updated the Internal RC Accuracy minimum and maximum values for parameter F21b (see Table 31-19).</p> <p>Updated the characteristic description for parameter DI35 in the I/O Timing Requirements (see Table 31-20).</p> <p>Updated <i>all</i> SPI specifications (see Table 31-32 through Table 31-39 and Figure 31-14 through Figure 31-21)</p> <p>Updated the ADC Module Specification minimum values for parameters AD05 and AD07, and updated the maximum value for parameter AD06 (see Table 31-43).</p> <p>Updated the ADC Module Specifications (12-bit Mode) minimum and maximum values for parameter AD21a (see Table 31-44).</p> <p>Updated all ADC Module Specifications (10-bit Mode) values, with the exception of Dynamic Performance (see Table 31-45).</p> <p>Updated the minimum value for parameter PM6 and the maximum value for parameter PM7 in the Parallel Master Port Read Timing Requirements (see Table 31-54).</p> <p>Added DMA Read/Write Timing Requirements (see Table 31-56).</p>

**TABLE A-4: MAJOR SECTION UPDATES (CONTINUED)**

Section Name	Update Description
<b>Section 32.0 “High Temperature Electrical Characteristics”</b>	Updated all ambient temperature end range values to +150°C throughout the chapter. Updated the storage temperature end range to +160°C. Updated the maximum junction temperature from +145°C to +155°C. Updated the maximum values for High Temperature Devices in the Thermal Operating Conditions (see Table 32-2). Updated the ADC Module Specifications (12-bit Mode) (see Table 32-14). Updated the ADC Module Specifications (10-bit Mode) (see Table 32-15).
<b>“Product Identification System”</b>	Updated the end range temperature value for H (High) devices.

**Revision F (August 2011)**

This revision includes typographical and formatting changes throughout the data sheet text.

All other major changes are referenced by their respective section in the following table.

**TABLE A-5: MAJOR SECTION UPDATES**

Section Name	Update Description
<b>Section 28.0 “Special Features”</b>	Added Note 3 to the Connections for the On-chip Voltage Regulator diagram (see <a href="#">Figure 28-1</a> ).
<b>Section 31.0 “Electrical Characteristics”</b>	Removed Voltage on VCAP with respect to Vss from the Absolute Maximum Ratings. Removed Note 3 and parameter DC10 (VCORE) from the DC Temperature and Voltage Specifications (see <a href="#">Table 31-4</a> ). Updated the Characteristics definition and Conditions for parameter BO10 in the Electrical Characteristics: BOR (see <a href="#">Table 31-11</a> ). Added Note 1 to the Internal Voltage Regulator Specifications (see <a href="#">Table 31-13</a> ).

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Device: dsPIC33FJ32MC302/X04, dsPIC33FJ64MCX02/X04 and Literature Number: DS70291F  
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dsPIC 33 FJ 32 MC3 02 T E / SP - XXX		
Microchip Trademark	_____	
Architecture	_____	
Flash Memory Family	_____	
Program Memory Size (KB)	_____	
Product Group	_____	
Pin Count	_____	
Tape and Reel Flag (if applicable)	_____	
Temperature Range	_____	
Package	_____	
Pattern	_____	

Architecture:	33	=	16-bit Digital Signal Controller
Flash Memory Family:	FJ	=	Flash program memory, 3.3V
Product Group:	MC2	=	Motor Control family
	MC3	=	Motor Control family
	MC8	=	Motor Control family
Pin Count:	02	=	28-pin
	04	=	44-pin
Temperature Range:	I	=	-40°C to +85°C (Industrial)
	E	=	-40°C to +125°C (Extended)
	H	=	-40°C to +150°C (High)
Package:	SP	=	Skinny Plastic Dual In-Line - 300 mil body (SPDIP)
	SO	=	Plastic Small Outline - Wide - 300 mil body (SOIC)
	ML	=	Plastic Quad, No Lead Package - 8x8 mm body (QFN)
	MM	=	Plastic Quad, No Lead Package - 6x6x0.9 body (QFN-S)
	PT	=	Plastic Thin Quad Flatpack - 10x10x1 mm body (TQFP)

**Examples:**

- a) dsPIC33FJ32MC302-E/SP:  
Motor Control dsPIC33, 32 KB program  
memory, 28-pin, Extended temperature,  
SPDIP package.



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