Learning Hand Features for Sign Language Recognition

Course Project: Deep Learning for Perception - Spring 2015

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Abstrac

Our project aims towards learning spatio-temporal features from images. We use 3D convolutional networks to learn such features and use it to recognize words in Amercian Sign Language. We compare our results with a baseline 2D convolutional neural network model to illustrate the advantages of learning spatio-temporal features over spatial features.

1 Introduction

Around 360 million people all over the world suffer from hearing loss and Sign Language, is the most popular means for this group to communicate. However, majority of people without hearing loss do not understand sign language. Thus, a lot of research and effort is put into **translating sign language into spoken language**. However this is a diffcult task as -

- 1. Sign Languages are **not** visual representation of spoken languages.
- 2. Sign languages have their own syntactic and grammatical structures.
- 3. They are both spatial and temporal in nature.
- 4. Gestures are identified by hand position, finger shape, parts of the hand and also facial expressions.
- 5. Data background is ever changing.
- 6. Data occlusion in the signed videos is also a concern.

2 The Dataset and Preprocessing

Dataset

- American Sign Language Lexicon Video Data set (ASLLVD) [1]
- Video sequences in uncompressed raw format for >3,300 words
- Collected using 4 synchronized cameras capturing different views of the signer
- High fidelity in the hand and face regions as they contain most information about the signed word
- Automatic skin segmentation
- Frames cropped to the skin
- Normalized to ensure uniform brightness

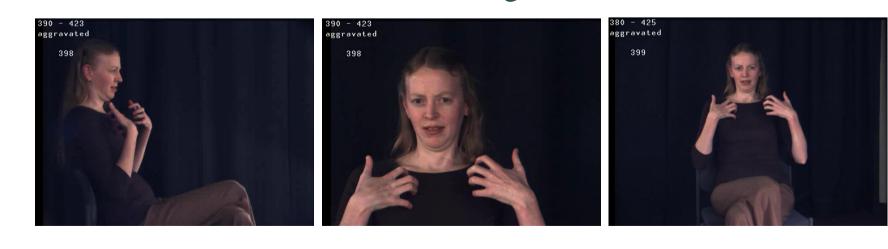


Figure 1: Side, zoomed and front views of the signer as in the ASLLVD dataset In this work:

- A sample of this data set containing 10 classes (words)
- Each word had around **5-6 videos** showing the full resolution **front** view and the side view
- We only use *front views* to ensure training set uniformity.

Preprocessing

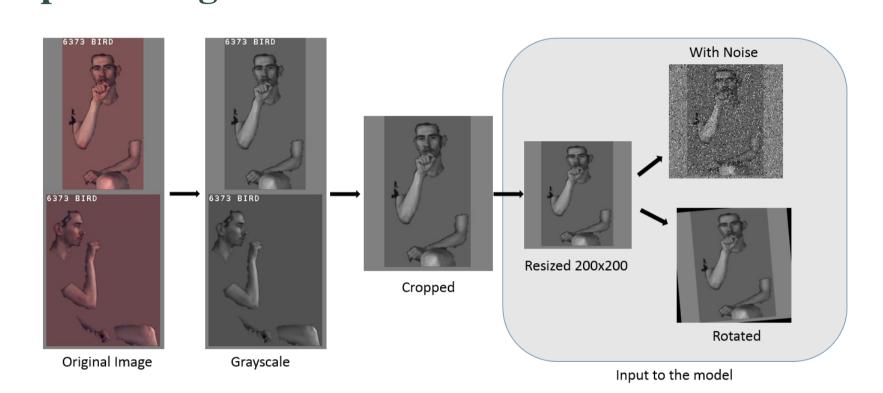


Figure 2: Data Pre-processing flow

3 Model Architecture

3.1 Spatial Model: 2D Convolutional Neural Network (2D-CNN)

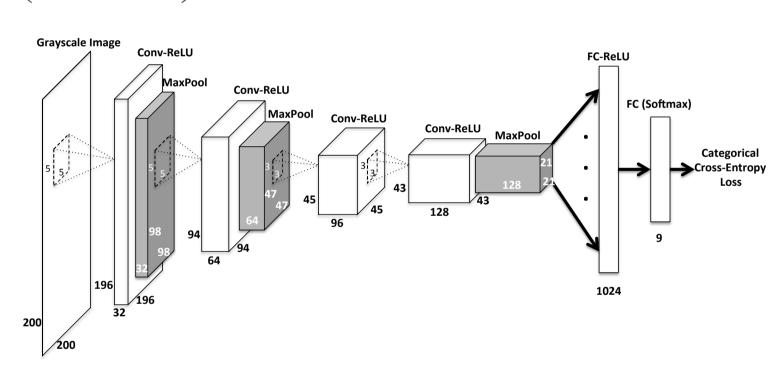
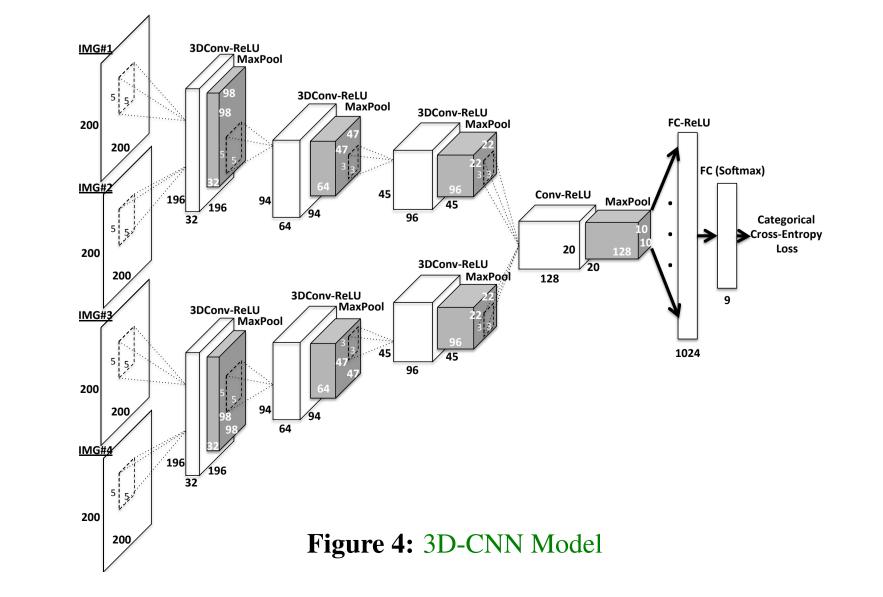


Figure 3: 2D-CNN Model

- Our baseline model:
- -Most common CNN architectures, e.g. [5]: $Input \rightarrow [[CONV \rightarrow ReLU]^N \rightarrow MaxPool]^M \rightarrow [FC->$
- $ReLU]^K \to FC$
- Convolution is only applied across space
- -Softmax is used at the last layer
- Categorical Cross-entropy is the optimization objective
- 3.2 Spatio-Temporal Model: 3D Convolutional Neural Network (3D-CNN)



• Similar to the work in [3], "Slow Fusion" architecture [4]:

- Using cubic kernels to support convolution across time
- Generalization of 2D-CNN, across time
- -Same spatial architecture, class score function and loss as in 2D-CNN

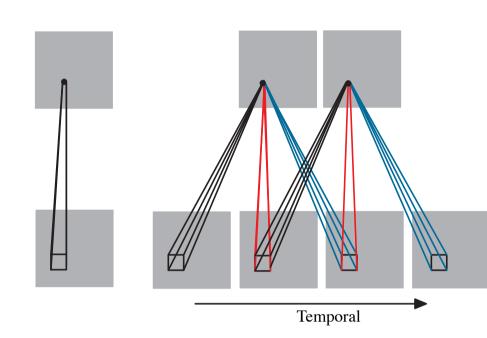


Figure 5: [3]: "2D-Convolution (left) vs. 3D-Convolution. In the right figure, the size of the convolution kernel in the temporal dimension is 3, and the sets of connections are color-coded so that the shared weights are in the same color. In 3D convolution, the same 3D kernel is applied to overlapping 3D cubes in the input video to extract motion features."

4 Experimental Evaluation

4.1 Implementation Details

- Both models trained using **Backpropagation**, incorporating **RM-SProp** [6]
- Implemented in Theano [2]
- Measuring Top-1, Top-3 and Top-5 classification accuracy
- Single-frame classification in 2D-CNN
- Sequence classification in 3D-CNN

4.2 Results

Model	2D CNN	3D CNN
Top-1	0.276	0.211
Top-3	0.4225	0.556
Top-5	0.439	0.556

Table 1: Comparison of classification accuracy of 2D and 3D-CNN models (Best results for each measure)

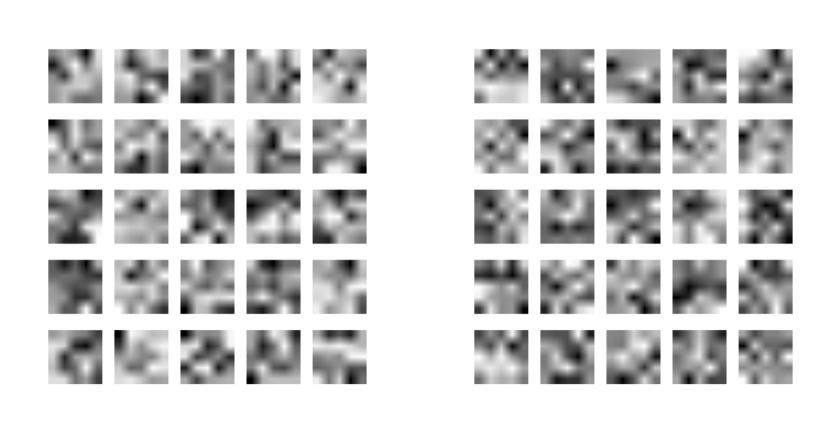


Figure 6: Visualization of Features in 3D CNN

Conclusions and Future Research

- 3D convolutions are able to learn spatio-temporal features but need better initializations. Current initialization schemes involve 2D CNNs learnt from the same data
- Current models do not involve max-pooling across time, this leads to time variant features
- For the particular task, weights can be biased to regions where the hands exist
- Comparison with alternate spatio-temporal learning methods such as CNN-RNN to be carried out

References

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