

view\_frames Result

Recorded at time: 13.357

chassis

odom

Broadcaster: /robot\_state\_publisher

Average rate: 10.215 Hz

Most recent transform: 13.301 ( 0.056 sec old)

Buffer length: 4.699 sec

Broadcaster: /robot\_state\_publisher

Average rate: 10.215 Hz

Most recent transform: 13.301 ( 0.056 sec old)

Buffer length: 4.699 sec

Broadcaster: /gazebo

Average rate: 10.213 Hz

Most recent transform: 13.326 ( 0.031 sec old)

Buffer length: 4.700 sec

left\_wheel

right\_wheel

robot\_footprint

