import cv2

import numpy as np

import face_recognition

import os

from datetime import datetime

path = 'photo' # this contain known face images

images =[] # list to store the images

classNames = [] # list to store the names of the images

my_list = os.listdir(path) # list of all the images in the path

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print(*my_list) # print the list of images
for cls in my_list:
 curimg = cv2.imread(f'{path}/{cls}') # read the image
 images.append(curimg) # append the image to the list
 classNames.append(os.path.splitext(cls)[0]) # append the name of the image to the list
print(*classNames ) # print the names of the images
def findEncoding(image): # function to find the encoding of the image
 encodelist = []
 for img in images: # loop through the images
   img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB) # convert the image to RGB
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encode = face_recognition.face_encodings(img)[0] # find the encoding of the image
encodelist.append(encode) # append the encoding to the list
return encodelist # return the list of encodings

def markAttendance(name): # function to mark the attendance of the person

with open('attendance.csv', 'r+') as f: # open the attendance file in read and write mode

myDataList = f.readlines() # read the lines of the file

nameList = [] # list to store the names of the people present

for line in myDataList: # loop through the lines of the file

entry = line.split(',') # split the line by comma

nameList.append(entry[0]) # append the name to the list

if name not in nameList: # if the name is not in the list

now = datetime.now() # get the current date and time

dtString = now.strftime('%H:%M:%S') # format the date and time

f.writelines(f'\n{name},{dtString}') # write the name and date and time to the file

encodelistknown = findEncoding(images) # find the encodings of the known images

print(len(encodelistknown), "Encodings found") # print the number of encodings found

cap = cv2.VideoCapture(0) # open the webcam

while True: # loop until the webcam is closed

success, img = cap.read()# read the frame from the webcam

imgS = cv2.resize(img, (0,0),None,0.25,0.25) # resize the frame to 1/4th of the original size

imgS = cv2.cvtColor(imgS,cv2.COLOR_BGR2RGB) # convert the frame to RGB

facesCurFrame = face_recognition.face_locations(imgS) # find the faces in the frame

encodesCurFrame = face_recognition.face_encodings(imgS, facesCurFrame) # find the encodings of the faces in the frame

for encodeFace, faceLoc in zip(encodesCurFrame, facesCurFrame): # loop through the encodings and the face locations

matches = face_recognition.compare_faces(encodelistknown, encodeFace)

faceDistance = face_recognition.face_distance(encodelistknown, encodeFace)

matchesIndex = np.argmin(faceDistance) # find the index of the minimum face distance

if matches[matchesIndex]:

name = classNames[matchesIndex].upper()

y1, x2, y2, x1 = faceLoc # get the face location

y1, x2, y2, x1 = y1*4, x2*4, y2*4, x1*4 # scale the face location back to the original size

cv2.rectangle(img, (x1, y1), (x2, y2), (0, 255, 0), 2)

cv2.rectangle(img, (x1, y2 - 35), (x2, y2), (0, 255,0), cv2.FILLED)

 $cv2.putText(img, name, (x1, y2), cv2.FONT_HERSHEY_COMPLEX, 1, (255, 255, 255), 2) \# draw a rectangle around the face and put the name on the rectangle$

markAttendance(name)

cv2.imshow('Webcam', img) # display the frame with the face locations and names

if cv2.waitKey(1) & 0xFF == ord('d'): # if the 'd' key is pressedd

break