ALU	VERIFICAT	ΓΙΟΝ DO	CUMENT	

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CHAPTER 1: PROJECT OVERVIEW AND OBJECTIVES

1.1 Project Overview:

This project describes the complete testing and validation process for a parameterized Arithmetic Logic Unit (ALU) utilizing an advanced, class-based SystemVerilog verification environment. The core purpose is to confirm the operational accuracy and temporal performance of the ALU implementation through a well-organized and scalable testing methodology.

1.2 Verifcation Objectives:

• Functional Verification:

- 1. Arithmetic Operations.
- 2. Logical Operations.
- 3. Control and Interface:
 - MODE switching between arithmetic and logical modes.
 - INP_VALID combinations (00, 01, 10, 11) impact verification.
 - Clock enable and reset behavior testing.
 - 16-cycle timeout mechanism for missing operands.
- 4. Error Handling:

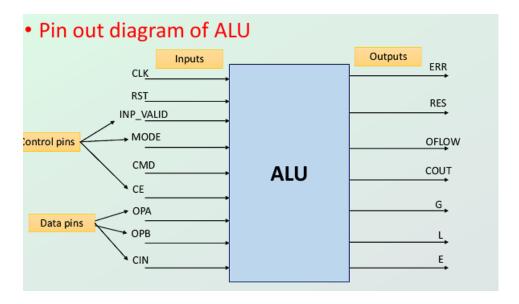
• Functional Coverage:

- 100% command coverage across both modes
- All INP VALID state transitions
- Comprehensive error condition coverage

• Verification Stratergy:

- Constrained random stimulus generation
- Self-checking testbenches with reference models
- Directed tests for corner cases
- Assertion-based protocol verification
- Coverage-driven methodology

1.3 DUT Interface:



• Input Ports

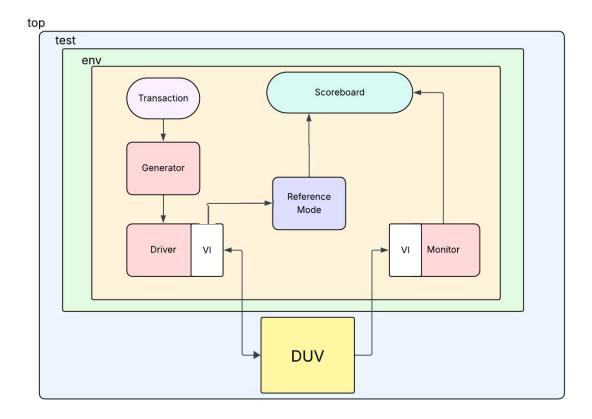
Signal Name	Туре	Width (bits)	Description
INP_VALID	Input	2	Input valid signal - indicates when input data is valid
MODE	Input	1	Mode selection signal - determines ALU operation mode
CMD	Input	4	Command signal - specifies the specific ALU operation
OPA	Input	Parametrized	Operand A - first arithmetic/logic operand
OPB	Input	Parametrized	Operand B - second arithmetic/logic operand
CIN	Input	1	Carry In - input carry for arithmetic operations

2 Output ports:

Signal Name	Type	Width (bits)	Description
ERR	Output	1	Error signal - indicates if an error occurred during operation
RES	Output	Parametrized	Result - the output result of the ALU operation
OFLOW	Output	1	Overflow - indicates arithmetic overflow condition
COUT	Output	1	Carry Out - output carry from arithmetic operations
G	Output	1	Greater than - comparison result flag
L	Output	1	Less than - comparison result flag
Е	Output	1	Equal - comparison result flag

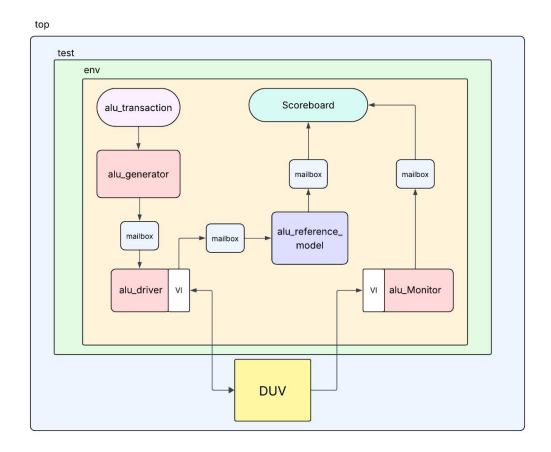
CHAPTER 2 - VERIFICATION ARCHITECTURE

2.1 Verification architecture:



The figure shows general testbench architecture used for verifying digital designs. At the top module is the Design Under Verification (DUV). The test has the testbench environment that includes a transaction generator that creates and manages the input testcases for testing. These transactions are randomized within the generator and then transmitted to the driver, which applies them as signals to the DUV through a virtual interface. Outputs from the DUV are monitored by a monitor, which forwards this data to a scoreboard for checking correctness against expected results calculated by a reference model. The environment block encapsulates all these components, ensuring coordination among them, while the scoreboard oversees the entire verification process to validate the DUV.

2.2 Verification ALU architecture:



The figure illustrates the **Verification Architecture** for an Arithmetic Logic Unit (ALU) using a modular testbench environment.

Key Components:

• alu transaction:

Defines the input and output of transactions (e.g., operands and operations) exchanged between components.

• alu generator:

Randomly creates test scenarios by generating transactions. These are sent to the driver for processing.

• alu_driver:

Receives transactions from the generator and drives them to the DUV and reference model using a virtual interface (VI)

• DUV (Design Under Verification):

The actual ALU design that receives inputs from the driver and generates outputs for validation.

• alu monitor:

Observes and captures the output signals from the DUV through the virtual interface. It converts them back into transaction format and forwards them to the scoreboard.

• alu reference model:

Serves as a golden model that receives the same input as the DUV and produces the expected output for comparison.

Scoreboard:

Compares the output from the DUV (via the monitor) with the expected output from the reference model. Any mismatches are flagged as functional errors.

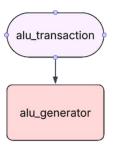
Mailboxes:

Facilitate communication between generator, driver, monitor, reference model, and scoreboard by passing transactions.

2.3 FLOW CHART OF SV COMPONENTS:

1. Transaction Class:

The alu_transaction class encapsulates all ALU input stimuli and output responses for verification purposes.



Components

Randomized Input Stimuli: The transaction contains ALU input signals declared with the rand keyword for automatic randomization:

• INP_VALID, MODE, CMD, OPA, OPB, CIN: Input signals that will be randomized by the generator

Non-Randomized Output Signals

Output signals are declared without rand as they represent the ALU's response:

• ERR, RES, OFLOW, COUT, G, L, E: Output signals monitored for verification

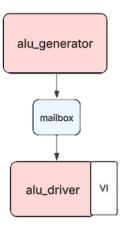
Constraints

The class implements mode-dependent constraints for realistic test scenarios:

Deep Copy Method

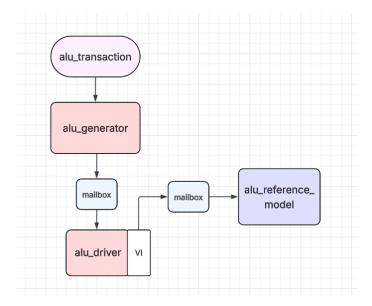
Implements a copy () function following the blueprint pattern for creating independent transaction copies used across testbench components.

2. Generator Class:



The generator consists of the ALU transaction class handle, the mailbox handle which connects to the driver, and the start() task which randomizes transactions and sends the randomized transactions to the driver through the mailbox.

3. Driver Class:



Key Features Implemented:

1. Two Mailboxes

- gen to drv mbox: Transfers transactions from generator to driver
- drv to ref mbox: Sends transactions from driver to reference model

2. Virtual Interface (Dynamic)

- alu_if: SystemVerilog interface with clocking blocks
- valu if: Virtual interface for dynamic access
- Communicates between testbench and DUV with proper synchronization

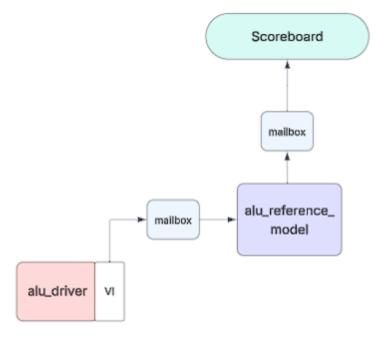
3. Functional Coverage Group

- Covers all input combinations (operands a, b, operation).
- Edge case coverage (zero results, overflow, carry conditions).

4. Drive Task in ALU Driver

• drive_transaction(): Drives stimuli to the DUV.

4. Reference Model:



Serves as a golden model that receives the same input as the DUV and produces the expected output for comparison.

Key Features:

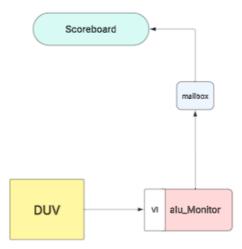
1. Two Mailboxes

- 1. drv to ref mbox: Receives transactions from the driver with input stimuli
- 2. ref to scb mbox: Sends processed transactions with expected results to the scoreboard

2. Functionality

- Task: start(), Continuously gets transactions from driver, computes expected results, and forwards to scoreboard
- Task to permorm operations: task compute_expected_result(): Implements golden reference for all ALU operations (ADD, SUB, MUL, DIV, AND, OR, XOR, NOT)

5. Monitor:



The ALU Monitor captures transactions from the DUV interface and forwards them to the scoreboard for result comparison.

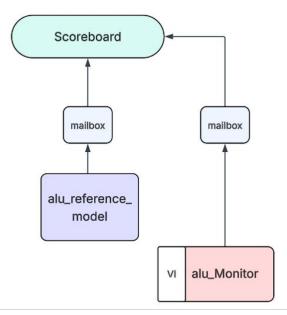
Mailbox Communication

• mon to scb mbox: Sends captured DUV transactions to the scoreboard

Functionality

- start(): Continuously monitors DUV interface and captures completed transactions
- Samples DUV outputs when valid transaction completes and creates transaction objects

6. Scoreboard:



The ALU Scoreboard compares actual DUV results against expected results from the reference model to determine test pass/fail status.

Mailbox Communication

- ref to scb mbox: Receives expected results from the reference model
- mon to scb mbox: Receives actual results from the monitor

Functionality

- compare results (): Compares expected vs actual results and reports mismatches
- report (): Provides final test statistics (pass/fail counts, coverage)

CHAPTER 3: RESULTS AND ANALYSIS

3.1 Design Bugs:

S.No	Test Case Category	Reason for Failure
1	16-Clock Cycle Timeout Logic	Error flag is not set even after waiting for 16 clock cycles when expected timeout condition occurs.
2	Single-Operand Operations	DUT does not perform single-operand operations (increment/decrement) when only the corresponding input valid signal is high; only works when INP_VALID == 2'b11, violating design specification requirements.
3	Carry-Out Logic for Increment Operations	COUT logic is incorrect/missing in increment operations and remains at default value; COUT flag should be asserted when operand reaches maximum value (e.g., 255 incrementing to 256).
4	Increment A Operation	INC_A operation holds the same value as OPA instead of incrementing it, resulting in no change to the operand value.
5	Increment B and Decrement B Operations	INC_B operation incorrectly decrements the value instead of incrementing.
6	Shift operation	Right shift operations on both OPA and OPB fail; Left shift OPB operation fails to execute correctly.

7	Decrement B Operations	DEC_B operation incorrectly increments the value instead of decrementing.
8	Overflow Logic for Decrement Operations	OVER_FLOW logic is incorrect/missing for decrement operations and remains at default value; OVER_FLOW flag should be asserted when operand at minimum value (e.g., 0) is decremented to -1.
9	Carry-In Signal Timing	CIN signal appears with a one-clock-cycle delay in addition with CIN and subtraction with CIN operations, causing timing misalignment.
10	Rotate Right A by B Error Condition	ROR_A_B error condition detection is incorrect and always remains zero even when the error condition occurs, failing to set appropriate error flags.
11	Multiplication Operation	Issues present in the multiplication operation functionality affecting correct arithmetic results.
12	Logical OR	Logical OR operation fails to execute correctly even with valid inputs and proper timing.

3.2 Coverage Report:

• Overall coverage

Coverage Sun	ımary by	Structure:	Coverage Sum	mary 1	b у Тур	e:			
Design Scope ∢	Hits % ∢	Coverage % ∢	Total Coverage:					92.54%	82.69%
top	90.58%	79.23%	Coverage Type ∢	Bins ∢	Hits ∢	Misses ∢	Weight ∢	% Hit ∢	Coverage •
inf	93.47%	85.07%	Covergroups	140	140	0	1	100.00%	100.00%
DUT	89.56%	83.36%	Statements	141	128	13	1	90.78%	90.78%
alu_pkg	100.00%	100.00%	Branches	73	67	6	1	91.78%	91.78%
alu_driver	100.00%	100.00%	FEC Conditions	18	11	7	1	61.11%	61.11%
alu_monitor	100.00%	100.00%	Toggles	294	272	22	1	92.51%	92.51%
			Assertions	5	3	2	1	60.00%	60.00%

• Code coverage:

Local Instance Coverage Details:

Total Coverage:					92.47%	85.87%
Coverage Type ∢	Bins ∢	Hits ∢	Misses ∢	Weight ∢	% Hit ∢	Coverage ◄
<u>Statements</u>	117	113	4	1	96.58%	96.58%
<u>Branches</u>	73	68	5	1	93.15%	93.15%
FEC Conditions	18	11	7	1	61.11%	61.11%
<u>Toggles</u>	204	189	15	1	92.64%	92.64%

• Functional Coverage:

Scope: /alu_pkg/alu_driver

Covergroup type:

drv_cg

Summary	Total Bins	Hits	Hit %
Coverpoints	28	28	100.00%
Crosses	101	101	100.00%

					5	Search:	
CoverPoints	*	Total Bins	Hits 👇	Misses -	Hit % –	Goal % –	Coverage % -
O CIN_CP		2	2	0	100.00%	100.00%	100.00%
OMD_CP		14	14	0	100.00%	100.00%	100.00%
INP_VALID_CP		4	4	0	100.00%	100.00%	100.00%
MODE_CP		2	2	0	100.00%	100.00%	100.00%
OPA_CP		3	3	0	100.00%	100.00%	100.00%
OPB_CP		3	3	0	100.00%	100.00%	100.00%

			Search:			
Crosses	Total Bins 👇	Hits +	Misses -	Hit % 👇	Goal % –	Coverage % -
OCMD_X_IP_V	56	56	0	100.00%	100.00%	100.00%
	28	28	0	100.00%	100.00%	100.00%
■ MODE_X_INP_V	8	8	0	100.00%	100.00%	100.00%
OPA_X_OPB	9	9	0	100.00%	100.00%	100.00%

Scope: /alu_pkg/alu_monitor

Covergroup type:

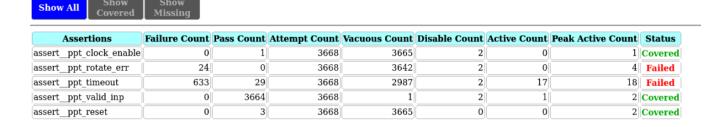
mon_cg

Summary	Total Bins	Hits	Hit %
Coverpoints	11	11	100.00%
Crosses	0	0	0.00%

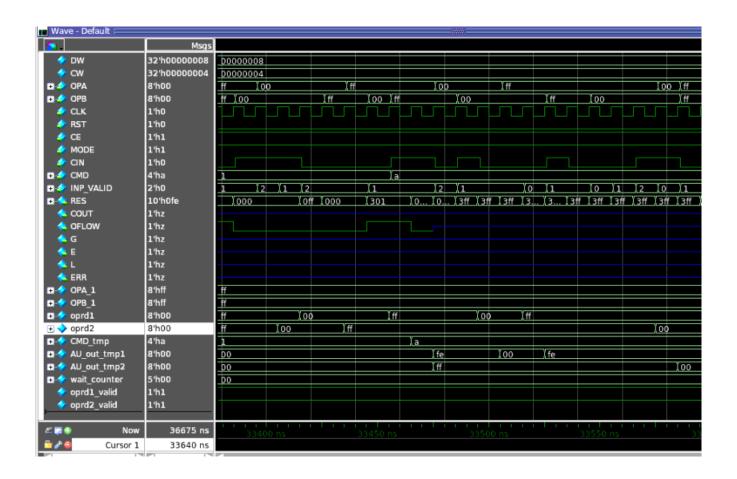
						Search:	
CoverPoints	*	Total Bins	Hits +	Misses -	Hit % +	Goal % 👇	Coverage %
O COUT_CP		2	2	0	100.00%	100.00%	100.00%
<u>■ E_CP</u>		1	1	0	100.00%	100.00%	100.00%
® ERR_CP		2	2	0	100.00%	100.00%	100.00%
 <u>G_CP</u>		1	1	0	100.00%	100.00%	100.00%
<u>U_CP</u>		1	1	0	100.00%	100.00%	100.00%
OV_CP		2	2	0	100.00%	100.00%	100.00%
® RES_CP		2	2	0	100.00%	100.00%	100.00%

• Assertion Coverage:

Questa Assertion Coverage Report



3.3 Output waveform:



3.4 Verification Plan link:

Verification Plan