

# Statistical independence measure based on maximum norm and characteristic function decomposition

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## Abstract

In this paper we propose statistical independence measure based on the maximum norm of the absolute value of difference between joint and product-marginal characteristic functions, and its estimation procedure (including open-source repository). We also extend the proposed measure to the reproducing kernel Hilbert spaces (RKHS), which allows to apply it to structured data.

We conduct experiments both with simulated and real data. Our experiments reveal, that the proposed measure can exploit statistical dependence in non-linear data sets, and that it can improve real-data classification accuracy, when applied for feature extraction and regularisation.

## 1 Introduction

Statistical dependence measures plays important role in various statistical and machine learning methods (e.g. hypothesis testing [1], feature selection and extraction [2, 3], information bottleneck methods [4], causal inference [5], self-supervised learning [6], among others). Earliest statistical dependence estimation ideas (e.g. conditional probability) share nearly-common origin with the beginning of formal statistical reasoning itself. During last two centuries ideas of correlation and (relative) entropy (including various generalizations) were proposed and became very popular in numerous applications and theoretical developments. However, with the increasing popularity of statistical machine learning, new statistical dependence estimation methods, that are robust, applicable to noisy, high-dimensional, structured data, and which can be efficiently integrated with modern machine learning methods are helpful for the development both of the theory and application.

In this article we focus on quantitative estimation of statistical independence, using characteristic functions. We begin with the short review of some important previous dependence estimation approaches (Section 2), devoting special

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attention to ones based on characteristic functions (Section 2.1). Afterwards, we formulate the proposed characteristic function-based statistical dependence measure and its empirical estimator (Section 3), including an extension into reproducing kernel Hilbert spaces (RKHS'es), which are the main theoretical contribution of our paper. Section 4 is devoted to experiments with simulated and real data sets, where we apply the proposed dependence measure for feature extraction and deep neural network (DNN) regularisation, and finalizing Section 5 concludes this article.

## 2 Previous Work

During recent years, various approaches have been used in order to construct statistical dependence estimation methods. For example, information theory (mutual information [7] and generalisations), reproducing kernel Hilbert spaces (Hilbert-Schmidt independence criterion [1]), characteristic functions (distance correlation [8, 9]), and other (e.g. [10] copula-based kernel dependence measures, integral-probability-metric-reliant Sobolev independence criterion [11]). Further we will focus on characteristic-function-based methods.

### 2.1 Characteristic-function-based methods

Characteristic function of  $d_X$ -dimensional random vector  $X$  defined in some probability space  $(\Omega_X, \Sigma_X, \mathbb{P}_X)$  is defined as

$$\phi_X(\alpha) = \mathbb{E}_X e^{i\alpha^T X}, \quad (1)$$

where  $i = \sqrt{-1}$ ,  $\alpha \in R^{d_X}$ . Having  $n$  i.i.d. realisations of  $X$ , corresponding empirical characteristic function is defined as

$$\widehat{\phi}_X(\alpha) = \frac{1}{n} \sum_{j=1}^n e^{i\langle \alpha, x_j \rangle}. \quad (2)$$

Having pair of two random vectors  $(X, Y)$  defined in another probability space  $(\Omega_{X,Y}, \Sigma_{X,Y}, \mathbb{P}_{X,Y})$  joint characteristic function is defined as:

$$\phi_{X,Y}(\alpha, \beta) = \mathbb{E}_{X,Y} e^{i(\alpha^T X + \beta^T Y)}, \quad (3)$$

where  $\alpha \in R^{d_X}$  and  $\beta \in R^{d_Y}$ . Similarly, having  $n$  i.i.d. realisations of  $(X, Y)$ , joint empirical characteristic function is defined as

$$\widehat{\phi}_{X,Y}(\alpha, \beta) = \frac{1}{n} \sum_{j=1}^n e^{i(\langle \alpha, x_j \rangle + \langle \beta, y_j \rangle)}. \quad (4)$$

In terms of characteristic functions, statistical independence of  $X$  and  $Y$  is equivalent to  $\forall \alpha \in R^{d_X}, \forall \beta \in R^{d_Y}$ ,

$$\Delta_{X,Y}(\alpha, \beta) := \phi_{X,Y}(\alpha, \beta) - \phi_X(\alpha)\phi_Y(\beta) = 0, \quad (5)$$

where  $d_x$  and  $d_y$  are dimensions of  $X$  and  $Y$ , respectively.

This formulation of statistical independence was used as the basis (first in [8] for one-dimensional case, and afterwards extended and developed by [9] for bivariate multidimensional random vectors) for construction of statistical independence tests and measures. *Distance covariance* and *distance correlation*, proposed by [9] relies on weighted  $L^2$ -norm analysis of (5). They select weighting function in such a way, that dependence measure can be expressed in terms of correlation of data-dependent distances. Study [12] generalises [9] to multivariable case and proposes *distance multivariate* and derivative dependence measure, called *total distance multivariate*. [13] proposed computationally efficient algorithm for estimation of distance correlation measure, reducing computational complexity from  $O(n^2)$  to  $O(n \cdot \log n)$ , where  $n$  is sample size.

Our motivation stems from the fact that evaluation of [9] measures in high dimensional cases may be prone to curse of dimensionality (as mentioned in [14]). Although staying in  $L^p$ -space framework, instead of  $p = 2$  ( $L^2$  space) we take a limit when  $p \rightarrow \infty$ , and thereby avoid direct calculation of norm integral, since norm of  $L^p$  converges to supremum norm when  $p \rightarrow \infty$ . Also, from practical point of view maximization is convenient, because it is already implemented in various deep learning frameworks.

### 3 Proposed Independence Measure

This motivates the construction of a novel dependence measure, which we further refer to as Kac independence measure (KacIM). Let  $X$  and  $Y$  be two standardized random random vectors. The proposed independence measure is defined as

$$\kappa(X, Y) = \max_{\alpha \in \mathbb{R}^{d_X}, \beta \in \mathbb{R}^{d_Y}} |\phi_{X,Y}(\alpha, \beta) - \phi_X(\alpha)\phi_Y(\beta)|. \quad (6)$$

#### 3.1 Properties

**Theorem 1.** *Statistical independence measure (6) has the following properties:*

1.  $\kappa(X, Y) = \kappa(Y, X)$ ,
2.  $0 \leq \kappa(X, Y) \leq 1$ ,
3.  $\kappa(X, Y) = 0$  iff  $X \perp Y$ .
4.  $\kappa(X, Y)$  is scale invariant.

*Proof.* Property 1. is obvious from definition (6) (commutativity of addition and multiplication), and property 2. directly follows from Cauchy inequality

and that absolute value of characteristic function is bounded by 1:

$$\begin{aligned} |\phi_{X,Y}(\alpha, \beta) - \phi_X(\alpha)\phi_Y(\beta)|^2 &= \mathbb{E}_{X,Y} |(e^{i\alpha^T X} - \phi_X(\alpha))(e^{i\beta^T Y} - \phi_Y(\beta))|^2 \leq \\ \mathbb{E}_{X,Y} |e^{i\alpha^T X} - \phi_X(\alpha)|^2 |e^{i\beta^T Y} - \phi_Y(\beta)|^2 &= (1 - |\phi_X(\alpha)|^2)(1 - |\phi_Y(\beta)|^2). \end{aligned}$$

Proof of property 3. directly follows from properties of characteristic functions (see e.g. [15], Corollary 14.1)<sup>1</sup>. Scale invariance (Property 4.) is trivial result of the standartisation requirement for  $X$  and  $Y$ .  $\square$

### 3.2 Estimation

Having i.i.d. standartized data  $(x_j, y_j)$ ,  $j = 1, 2, \dots, n$ , an empirical scale-invariant estimator of (6) is defined via corresponding empirical characteristic functions (4) and (2):

$$\hat{\kappa}(X, Y) = \max_{\alpha, \beta} |\widehat{\phi_{X,Y}}(\alpha, \beta) - \widehat{\phi_X}(\alpha)\widehat{\phi_Y}(\beta)|. \quad (7)$$

Empirical estimator (7) also is symmetric and and bounded (Theorem 1). It can be calculated iteratively by Algorithm 1 (Pytorch [18] implementation can be accessed from [https://github.com/povidanius/kac\\_independence\\_measure](https://github.com/povidanius/kac_independence_measure)).

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#### Algorithm 1 KacIM estimation iteration

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**Require:** data batch  $(x, y)$ , gradient-based optimiser  $GradOpt(loss)$   
 Normalize  $(x, y)$  to zero mean and unit variance (scale invariance).  
 Calculate KacIM estimator  $\hat{\kappa}(x, y)$ , without maximization step (i.e. using current  $\alpha, \beta$ ).  
 Perform one maximization iteration of computed  $\hat{\kappa}(x, y)$  via  $\alpha, \beta \rightarrow GradOpt(\hat{\kappa}(x, y))$ .

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Hence, the estimation of KacIM via Algorithm 1 results in  $O(kn)$  computational complexity, where  $k$  is the number of iterations, and  $n$  is sample size.

It requires to initialise  $\alpha$  and  $\beta$  (we empirically found that uniform initialisation resulted in faster convergence), select stoping criteria (e.g.  $k \in \mathbf{N}$ ), and optimiser. In our implementation we use decoupled weight decay regularization optimizer [19]. We also empirically observed that normalisation of parameters  $\alpha$  and  $\beta$  on to unit sphere increases estimation stability (why?).

Note, that e.g. Shannon and Renyi mutual information [7] are also estimated via transforming them into maximisation problem by Donsker-Varadhan representation [17], in order to avoid density estimation.

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<sup>1</sup>This property also is known as Kac's theorem [16]. Although it is quite simple mathematical fact, this provides the basis of the proposed measure's name.

### 3.3 Kernel version

Having two RKHS'es, defined by feature mapping  $(x, y) \rightarrow (l(x, \cdot), l(y, \cdot))$ , where  $k : \mathbb{R}^{d_x} \times \mathbb{R}^{d_x} \rightarrow \mathbb{R}$  and  $l : \mathbb{R}^{d_y} \times \mathbb{R}^{d_y} \rightarrow \mathbb{R}$  (see [20]). Then, estimation of kernel-*KIM* ( $\hat{\kappa}_{k,l}(X, Y)$ ) can be reformulated as maximization of :

$$\left| \frac{1}{n} \sum_{j=1}^n e^{i(\langle \alpha, k(x_j, \cdot) \rangle + \langle \beta, l(y_j, \cdot) \rangle)} - \frac{1}{n^2} \sum_{j=1}^n e^{i\langle \alpha, k(x_j, \cdot) \rangle} \sum_{k=1}^n e^{i\langle \beta, l(y_k, \cdot) \rangle} \right|, \quad (8)$$

and representer theorem[?] implies

$$\hat{\kappa}_{k,l}(X, Y) = \max_{\|\alpha\|=\|\beta\|=1} \left| \frac{1}{n} 1^T e^{i(\alpha^T K + \beta^T L)} - \frac{1}{n^2} (1^T e^{i(\alpha^T K)}) (1^T e^{i(\beta^T L)}) \right|, \quad (9)$$

where  $K$  and  $L$  are Gram matrices, corresponding to  $x_i$  and  $y_i$ . Note that the number of parameters of  $\hat{\kappa}_{k,l}(X, Y)$  is dimension-independent and is equal to  $2n_b$ , where  $n_b$  is batch size. Also, kernel-*KIM* can be applied for structured data, via corresponding positive defined kernels.

## 4 Experiments

Further we will conduct empirical investigation of KacIM in order to demonstrate that it can measure statistical dependencies in non-linear data sets, and that it can be practically useful as a component of cost functions (in feature selection and extraction, and regularisation problems).

### 4.1 Generated data

**Non-linear statistical dependence detection.** We begin with simple example, which demonstrates the efficiency of KacIM for simulated multivariate data with additive and multiplicative noise.

Figure 1 reflects KacIM values during iterative adaptation (200 iterations). In the case of independent data, both  $x_i$  and  $y_i$  ( $d_x = 512$ ,  $d_y = 4$ ) are sampled from gaussian distribution, independently. In the case of dependent data, an additive noise and multiplicative noise, the dependent variable is generated according to  $y_i = \sin(Px_i) + \cos(Px_i) + \lambda \epsilon_i$  ( $\lambda = 1.00$ ) and  $y_i = (\sin(Px_i) + \cos(Px_i))\epsilon_i$ , respectively, where  $P$  is  $d_x \times d_y$  random projection matrix,  $\epsilon_i \sim N(0, 1)$  and  $\epsilon_i \perp x_i$ .

When data is independent, both in additive and multiplicative cases, due to independence, estimator (7) is resistant to maximisation, and oscillates near zero. On the other hand, when the data is not independent, the condition (5) is violated and maximization of estimator (7) is possible.

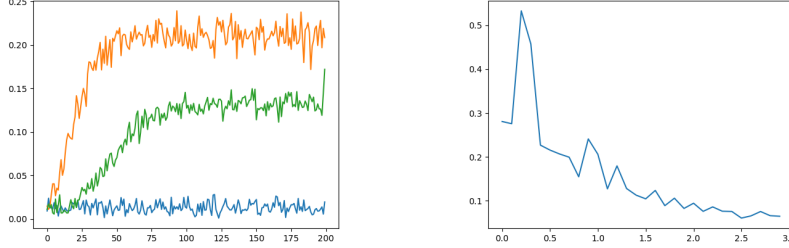


Figure 1: Left figure: Dependence detection in independent data (blue), additive (orange) and multiplicative (green) noise scenarios. Right figure: noise level ( $x$  axis) vs final iteration KacIM value ( $y$  axis). KacIM values for larger noise levels saturates as in tail of graph

**Noise variance effect** In this simulation we use the same additive noise setting as in previous paragraph, but evaluate all noise levels  $\lambda \in [0.1, 3.0]$ , with step 0.1. Figure 1 empirically shows that value of KacIM negatively correlates with noise level, and therefore the proposed measure is able not only to detect whether independence is present, but also to quantitatively evaluate it, which enables to use it to derive cost functions for various learning-based algorithms.

## 4.2 Feature selection

### 4.3 Feature extraction

Let us denote by  $T := (x_i, y_i)_{i=1}^N$  a supervised-learning dataset of  $N$  pairs of  $d_x$ -dimensional inputs  $x_i$ , and  $d_y$ -dimensional one-hot-encoded outputs  $y_i$ .

In feature extraction experiments we will use a set of classification data sets from OpenML [21], which cover different domains. We use *KacIM* in order to conduct supervised linear feature extraction by seeking

$$W^* = \arg \max_W \kappa(Wx, y) - \alpha \text{Tr}\{(W^T W - I)^T (W^T W - I)\}, \quad (10)$$

where the regularisation term, controlled by multiplier  $\alpha \geq 0$ , enforces orthogonality of projection matrix  $W^*$ , and  $\text{Tr}\{\cdot\}$  denotes matrix trace operator.

In all the experiments (10) the cost function is optimised iteratively (250 iterations), simultaneously optimising parameters of KacIM ( $\alpha$  and  $\beta$ ) and projection matrix  $W$ . After the optimisation, the feature extraction is conducted by  $f(x) = W^*x$ , where  $x$  is original input vector, and  $f$  are corresponding feature vector.

We randomly split all the datasets in training and testing sets of equal size, comparing unmodified inputs  $x$ , and features of all possible dimensions up to  $d_x$  with 10% step. In our experiments we set  $\alpha$  to 1.0 to quickly ensure orthogonal projection matrices, and further proceed to dependence maximization stage.

| Dataset                    | $N/d_x/n_c$   | Raw  | KacIMFE | NCA  |
|----------------------------|---------------|------|---------|------|
| micro-mass                 | (360,1300,10) | 0.88 | 0.93    | 0.89 |
| ionosphere                 | (351,34,2)    | 0.88 | 0.92    | 0.94 |
| spambase                   | (4601,57,2)   | 0.69 | 0.83    | 0.87 |
| lsvt                       | (126,310,2)   | 0.67 | 0.68    | 0.78 |
| one-hundred-plants-texture | (1599,64,100) | 0.62 | 0.77    | 0.80 |
| tokyo1                     | (959,44,2)    | 0.72 | 0.89    | 0.91 |
| clean1                     | (476,168,2)   | 0.77 | 0.99    | 0.98 |
| one-hundred-plants-shape   | (1600,64,100) | 0.10 | 0.48    | 0.47 |
| pc4                        | (1458,37,2)   | 0.88 | 0.87    | 0.87 |
| madelon                    | (2600,500,2)  | 0.60 | 0.55    | 0.57 |
| scene                      | (2407,299,2)  | 0.89 | 0.98    | 0.93 |
| gina_agnostic              | (3468,970,2)  | 0.85 | 0.80    | 0.81 |
| isolet                     | (7797,617,26) | 0.93 | 0.95    | 0.95 |

Table 1: Classification accuracies.  $N$  denotes full data set size,  $d_x$  - input dimensionality, and  $n_c$  - number of classes. In this table feature dimension is equal to a half of original input dimension.

In order to quantitatively evaluate features, we use logistic regression-based classification accuracy, measured on the testing set.

We use two baselines: raw features (RAW column in Table 1) and neighborhood component analysis [22] (NCA column in Table 1). The purpose of these experiments is to provide the preliminary evaluation of the applicability of KacIM for feature extraction, hence we use rather basic cost function and comparative baselines.

The classification accuracies, reported in Table 1 demonstrate that KacIM-based feature extraction procedure (KacIMFE column) indeed allows to increase classification accuracy when applied to real data sets from different domains, despite In contrast to our feature extraction approach, NCA explicitly optimises for classification accuracy, rather than more abstract dependency of  $f(x)$  with  $y$ .

#### 4.4 Regularisation

In regularisation experiments we investigate chest x-ray classification task. It is represented as binary classification data set, consisting of x-ray scans (5216 for training, and 642 for testing), which should be classified as pneumonia or normal (e.g. Figure 2). As classifier we use *ResNet18*, trained with batches of 128 elements. We denote classifier as  $f(\phi(x|\theta_0)|\theta_1)$ , where  $\theta_0$  are bottleneck parameters,  $\theta_1$  final (linear) layer parameters, and  $x$  is  $224 \times 224$  input image. For optimisation we use decoupled weight decay regularization optimizer [19] with learning rate set to 0.0002, and weight decay parameter set to 0.00001 (7

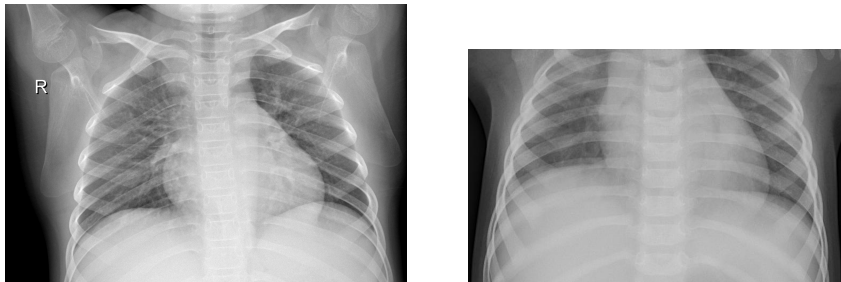


Figure 2: Left figure: example of healthy lung x-ray. Right: pneumonia.

| Mode                   | esting |
|------------------------|--------|
| Without regularisation | 0.8338 |
| With regularisation    | 0.8427 |

Table 2: Classification accuracy comparison of regularised and not regularised model (pneumonia dataset).

epochs). We used the following data augmentations: random horizontal flip, random rotation (up to 10 degrees), color jitter.

We will investigate additive regularizer, which maximises dependency of bottleneck the feature  $\phi(x)$  and target variable  $y$  (one-hot encoding):

$$Cost(\theta_0, \theta_1, W) := CE(f(\phi(x|\theta_0)|\theta_1), y) - \beta \kappa(W\phi(x|\theta_0), y), \quad (11)$$

where  $CE(., .)$  is cross-entropy loss,  $W$  is  $32 \times 512$  projection matrix, and  $\beta \geq 0$  is regularisation parameter (in our experiments  $\beta = 0.1$ ).

The results of classification accuracy without and with aforementioned regularisation is reported in Table 2.

## 5 Conclusion

In this article we propose statistical dependence measure, KacIM, which relies on the  $L^\infty$  norm of the absolute value of difference between joint characteristic function and the product of marginal ones. The proposed measure, in theory can detect both linear and non-linear statistical dependence between a pairs of random variables of possibly different dimension, extended to various known statistical generalisations (e.g. reproducing kernel Hilbert spaces, multivariablity), machine learning scenarios (e.g. feature extraction, regularisation, among others), and is empirically tractable on these problems. On the other side, it raises a corresponding set of unanswered questions, both theoretical and empirical. For example, the interpretability when it approaches its maximal value remains insufficiently clear, however empirical experiments with simulated data reveals, that increasing independence between two random variables is reflected in a



decreasing trend on the estimated values of the proposed dependence measure. In contrary to e.g. HSIC or distance correlation, the estimation of the proposed measure is iterative optimisation process. Therefore, parameter initialization, meta-parameter (e.g. stopping criteria, batch size) selection are needed in order to evaluate it efficiently.

Beside demonstrated applications in Section 4, the proposed measure is differentiable and thereby can be integrated with various modern deep-learning methods, applied to high-dimensional and structured data. From empirical point of view, we see exploration of KacIM in causality, information bottleneck theory, self-supervised learning, and other modern problems, where dependence measures define a criterion of optimisation, as important future work. We also would like to note, that exhaustive survey of measures of statistical dependence, accompanied with open-source code repository, would be helpful both for the theorists and for practitioners.

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