



DESIGN & ANALYSIS OF ALGORITHM

PCC-CS501



DESIGN & ANALYSIS OF ALGORITHM

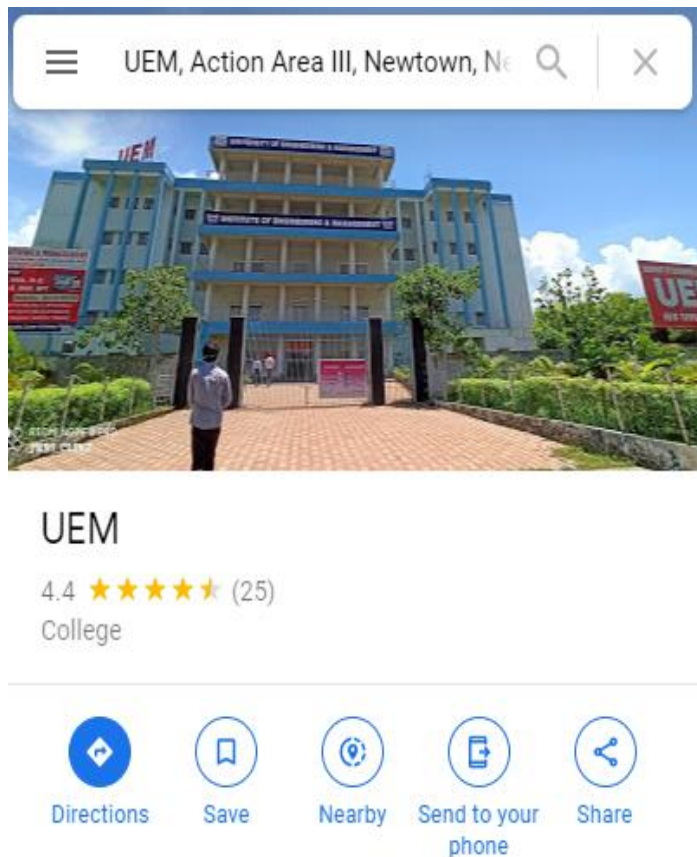
SCHEDULE ----TOPIC WISE

	Topic	Sub Topic
1	INTRODUCTION	DESIGN OF ALGORITHM ,ANALYSIS OF ALGORITHM, ALGORITHM PROPERTIES
2	FRAMEWORK FOR ALGORITHM ANALYSIS	HOW TO COUNT EXECUTION TIME OF ALGORITHM,INPUT INSTANCES
3	ASYMPTOTIC NOTATION	BEST CASE,AVERAGE CASE, WORST CASE
4	SOLVING RECURRENCE RELATION	SUBSTITUTION METHOD, MASTER THEOREM
5	ALGORITHM DESIGN TECHNIQUES	DIVIDE & CONQUER, GREEDY,DYNAMIC PROGRAMMING, BACKTRACKING,
6	DISJOINT SET MANIPULATION	UNION FIND
7	NETWORK FLOW PROBLEM	FORD FULKERSON ALGORITHM
8	NP COMPLETENESS	NP,NP HARD.....ALGORITHM
9	APPROXIMATION ALGORITHM	COMPLEXITY ANALYSIS OF NP COMPETE PROBLEM

DIJKSTRA ALGORITHM

- **SINGLE SOURCE SHORTEST PATH ALGORITHM**

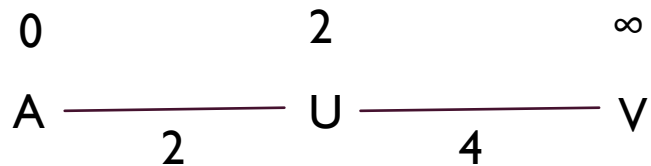
SINGLE SOURCE SHORTEST PATH ALGORITHM



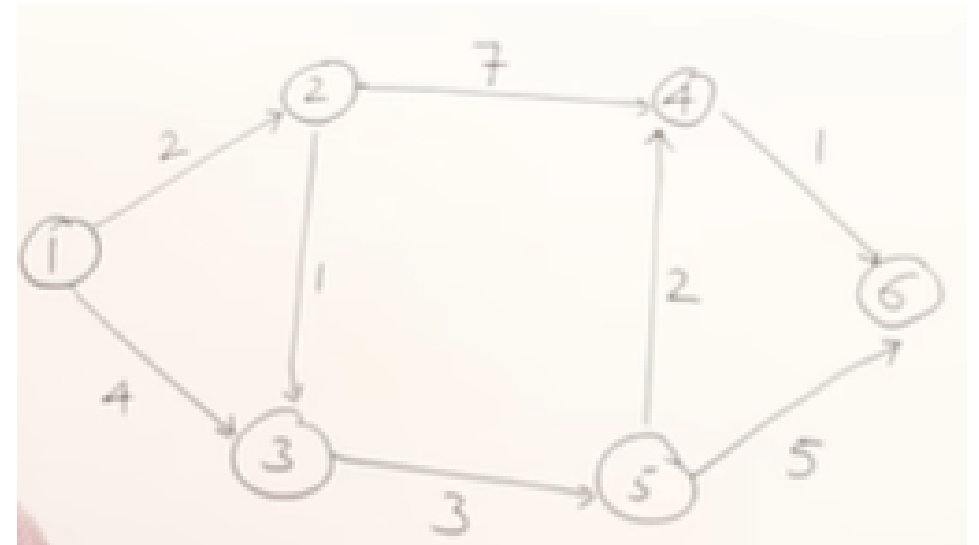
DIJKSTRA ALGORITHM

RULE OF RELAXATION

- Applicable on directed / undirected graph
- Optimization Problem
- Rule of Relaxation

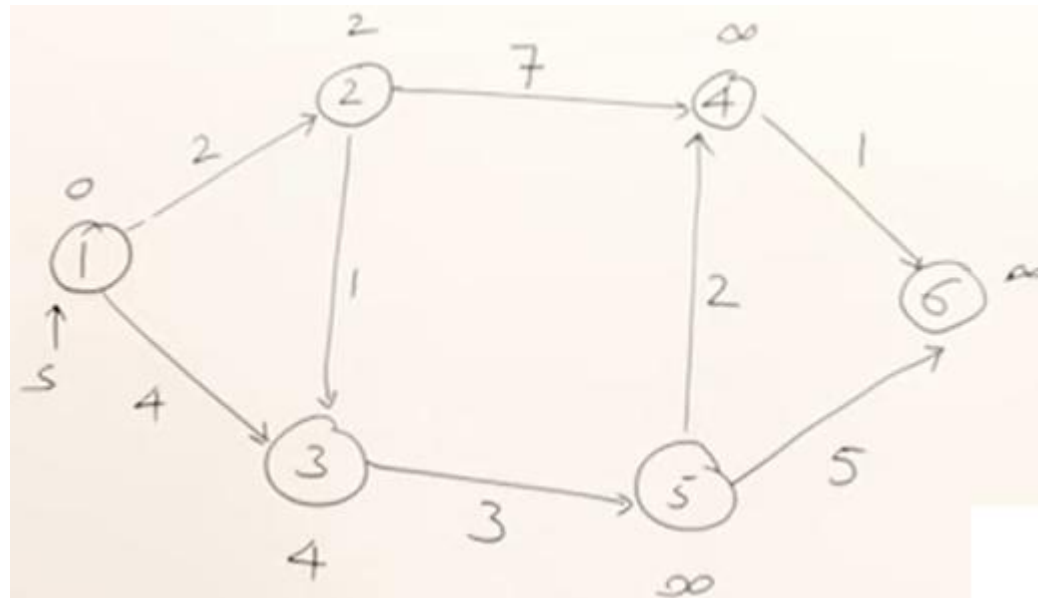


IF $(d[U] + C[U, V]) < d[V]$ THEN
SET $d[V] \leftarrow d[U] + C[U, V]$



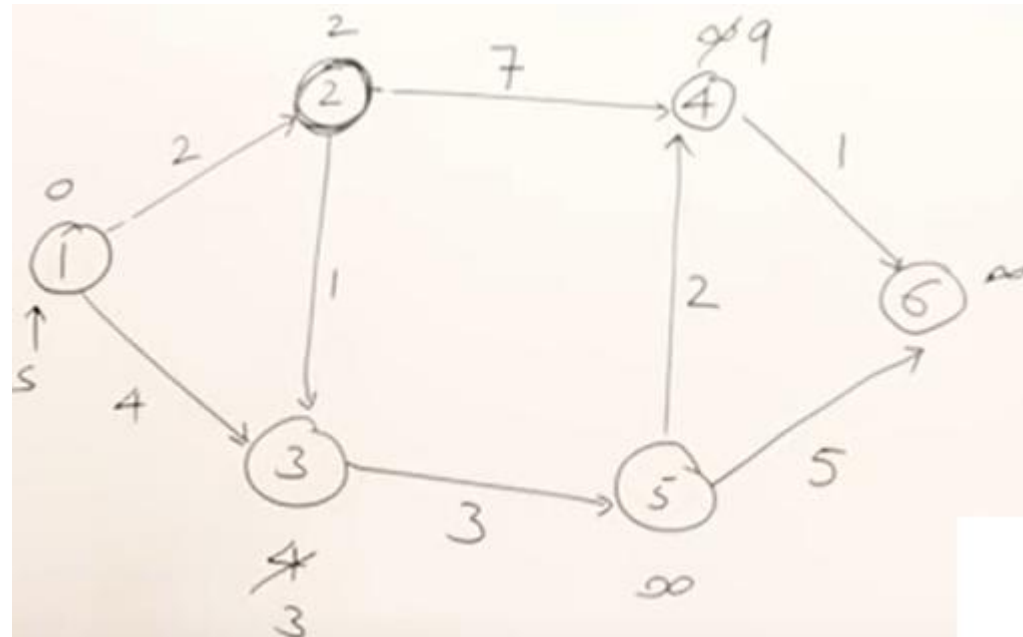
DIJKSTRA ALGORITHM

- Start vertex : 1



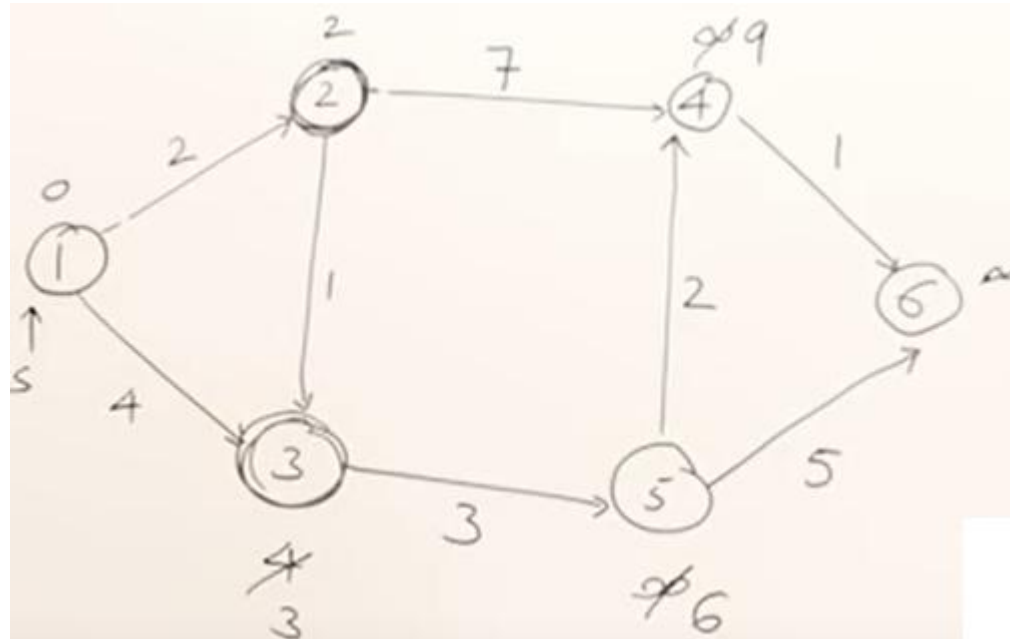
DIJKSTRA ALGORITHM

■ 1 → 2



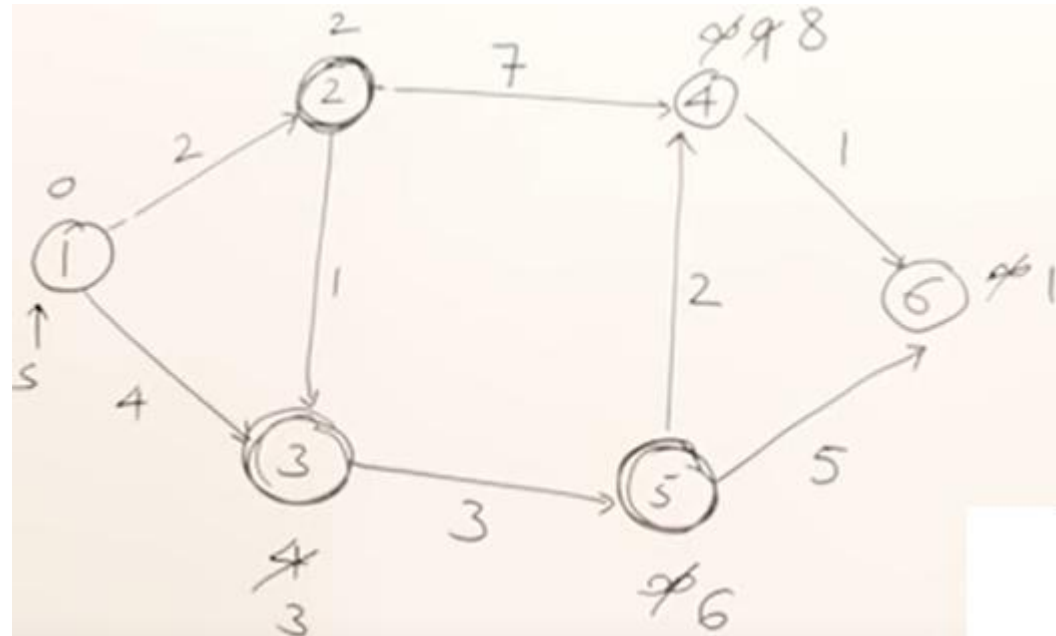
DIJKSTRA ALGORITHM

1 → 2 → 3



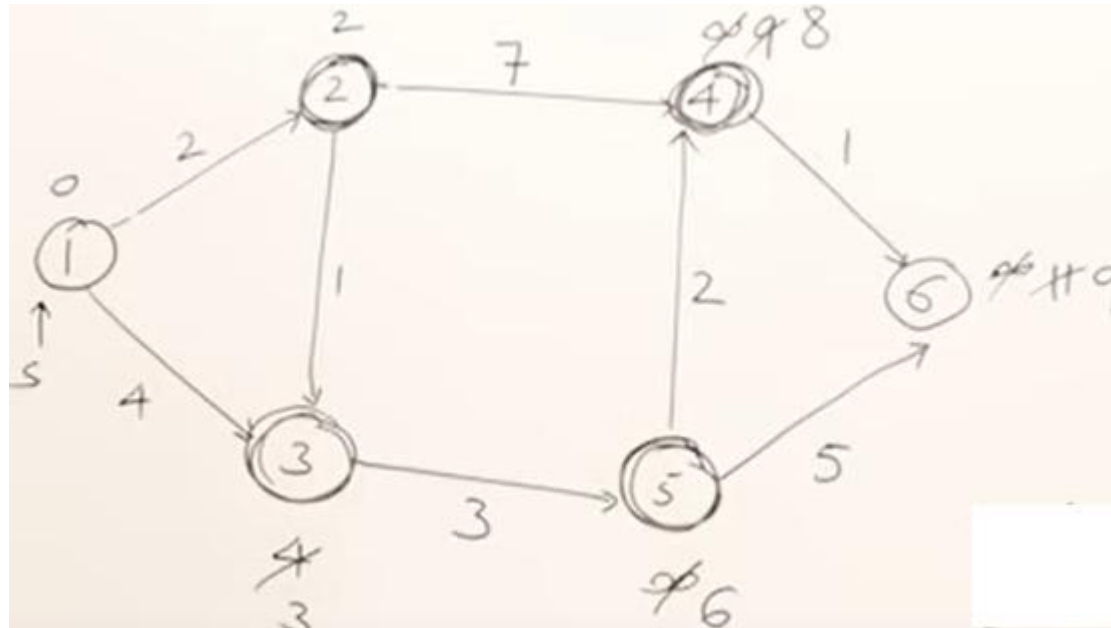
DIJKSTRA ALGORITHM

1 → 2 → 3 → 5



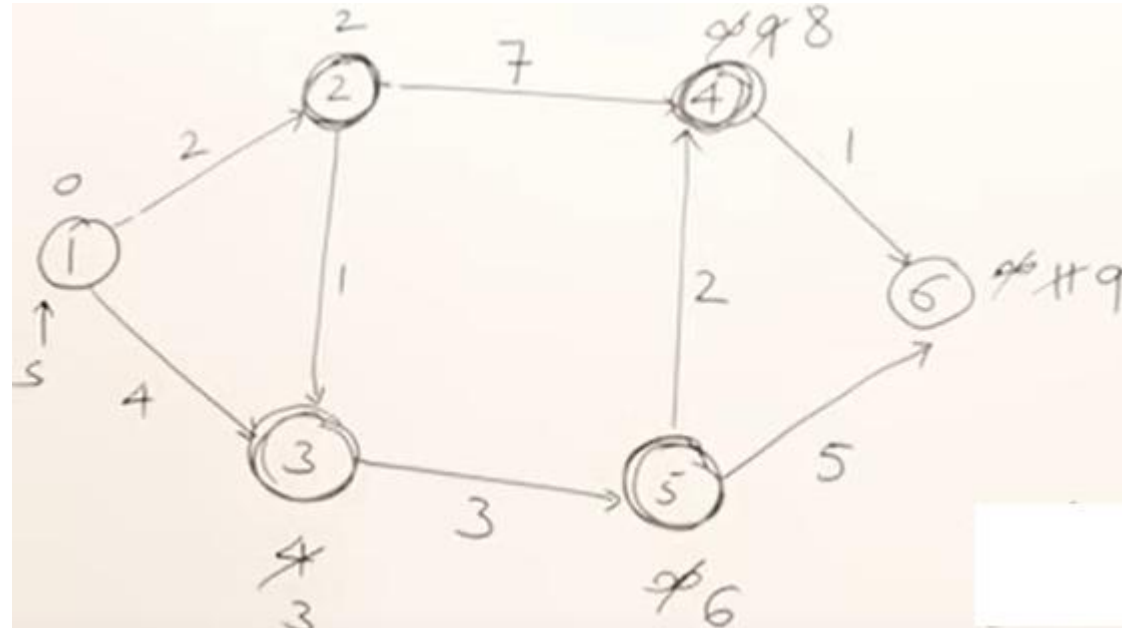
DIJKSTRA ALGORITHM

■ $1 \rightarrow 2 \rightarrow 3 \rightarrow 5 \rightarrow 4$



DIJKSTRA ALGORITHM

1 → 2 → 3 → 5 → 4 → 6



	2	3	5	4	6
Shortest Distances	2	3	6	8	9

TIME COMPLEXITY

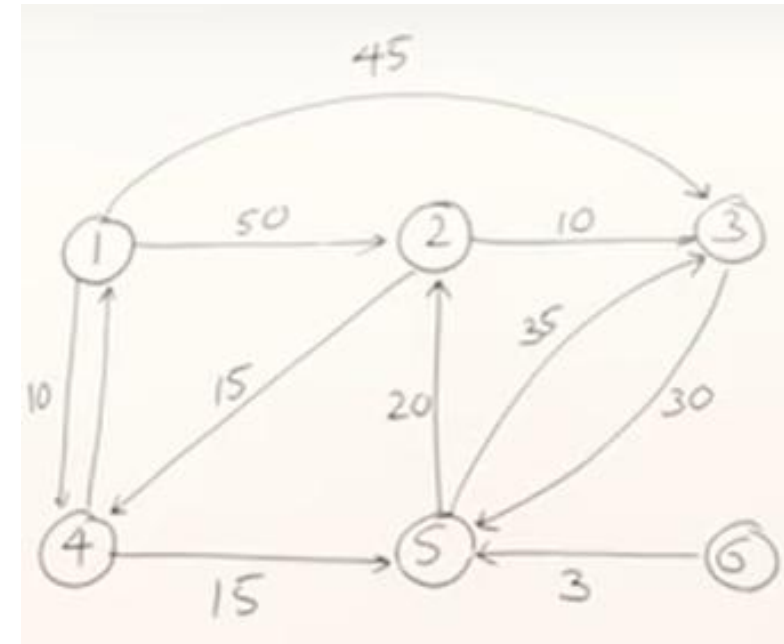
DIJKSTRA ALGORITHM

- $O(V^2)$ or $O(n^2)$

[relaxation w.r.t all the adjacent vertices in case of complete graph]

DIJKSTRA ALGORITHM

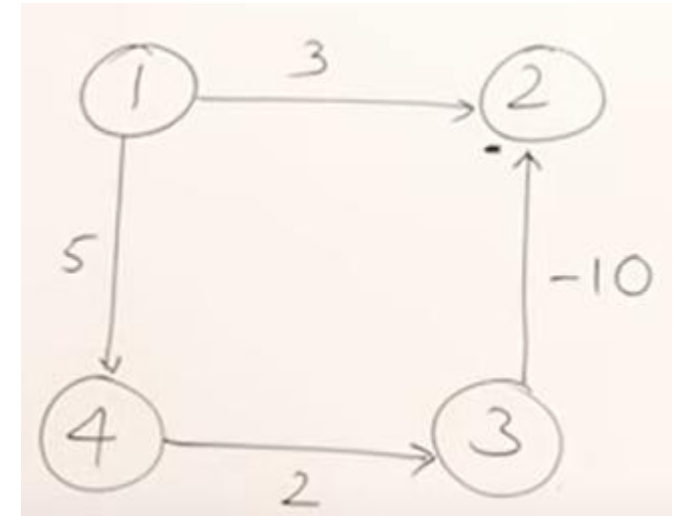
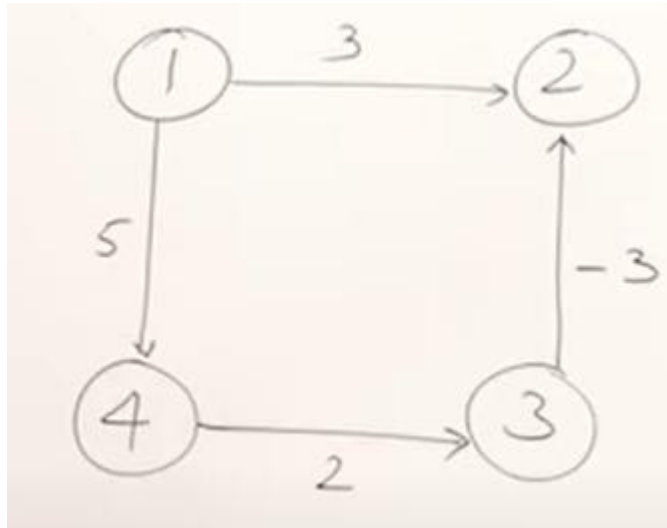
Selected virtex	2	3	4	5	6
4	50	45	10	∞	∞
5	50	45	10	25	∞
2	45	45	10	25	∞
3	45	45	10	25	∞
6	45	45	10	25	∞



DRAWBACK

DIJKSTRA ALGORITHM

- May or May not Support Negative weight edge.



NEXT CLASS

- DYNAMIC PROGRAMMING