Name: Shubbarn Dutta Year : 2 rd Strom: CST Enrollment: 12019009022112 Régistration: 304201900900752 Paper Name Paper Name: Artificial Intelligence & Paper Wide: PCCCS405 Machine Signatione: Shubham Dulta Date: 16th March 2021

Ans wo

ID	Student	Circlet Rating	Actual Probable Out		
1	0	Fair	0	1	FN
2	0	Excellent	0	0	tr
3	0	Fair	1	1	TP
4	11 11 11 11	Excellent	.0	0	TN
5	. (Excellent	1	0	FR
6	Ö	Fair	O	0	TN
7	0	Excellent 1	1	1,	TP
8		Fair	1	0	1/FP
49 4	0	1 Excellent	6	71	J FN

So, Total FN=2 TN=3 FP22 TP=2

SO, Accuracy = TP+ TN TP+FP+TN+FN

= 5 = 0.55 = 55%

:. Precision = TP = 2 = 0.5 TP+EP = = = 50 = . *, Ruall = TP = 2 = 0.5 TP+FN = 2 = 0.5

Hore, TP - True Positive TN - Frui Nyative FR -> Fahe Assitive 2.8) AXX 4025 8075 7225 95 8075 70 6900 | 5600 65 4100 9550 70 3600 | 9200 EY=385 Ex= Enyz 31.15 30,50 To find the value of wefficient we need to minimize the object The for using the derivative B, = hzxy-ExEy カミルー(ミル)~ $= 3 \times 30500 - 390 \times 385$ $5 \times (31, 1500) - (390)$ = (152,500 - 150,150) (155,750 - 152,100) = 2350 = 0.699 Bo = Ey - B, Ex 385-0.6942390

2 6 13.38 7

incar regression y in => y = B, 1x + Bo = 0.619 × + 13.389 : Pearson's wefficient in Hat B, = 0.699 & Bo = 13.389. Overfilling Underfitting i) A satisfical model A satistical model is said to be evertilled on machine is said to have. when we train train it with lot of data. under filting when it cannot capture the underlying herol u') In overfilling, ii) under filt y destroys model stands starts ble accuracy of own machine learning model. learning from the noise & inaccurate data enters in datasd. ii) It has high varian ul) It has high bian & -ce . 8 low bigg low variance iv) It usually happens in) It usually happens when because of non-param we have less data to built methods as these type of an accurate model & also ML algorithm have more when we try to build a bruddh in building model linear model with non-linear

2nd part
Popular Methods of evalutry classifi Cusually 2/3 for train & 1/3 for test) Learn model using train set & measure - Usually used when there is sufficient both train & told data will be a part. k-fold Gross-validation · par Jet Step: - data in split onto ! 2 rd step: - each subset in turn is assel for testing & the remain -dur for braining.

Porton mance measure average alons all folds. 4. A) By the mothod of least requeres,

by given data $\{(x, y_1), (x_2, y_2), \dots (x_n)\}$ y = an + b (0, b are parameter) E(a,b) = { {yn - (.0x, +6)}} $\frac{\partial E}{\partial a} = 0$, $\frac{\partial E}{\partial b} = 0$ $\frac{\partial E}{\partial a} = \sum_{n=1}^{N} 2 (y_n - (\alpha y_n + b)) \cdot (-y_n)$ $\frac{\partial E}{\partial b} = \sum_{n=1}^{N} 2 (y_n - (\alpha y_n + b)) \cdot (-y_n)$ Now the eq. $\frac{1}{2} \left(\frac{\lambda}{2} \times \lambda_n \right) \cdot a + \left(\frac{\lambda}{2} \times \lambda_n \right) \cdot b = \frac{\lambda}{2} \times \lambda_n \cdot \lambda_n$ By minimising evolution $\left[\frac{\lambda}{2} \times \lambda_n \times \lambda_n \right] \left[\frac{\lambda}{2} \times \lambda_n \times \lambda_n \times \lambda_n \right] \left[\frac{\lambda}{2} \times \lambda_n \times \lambda_n \times \lambda_n \right] \left[\frac{\lambda}{2} \times \lambda_n \times \lambda_n \times \lambda_n \right] \left[\frac{\lambda}{2} \times \lambda_n \times \lambda_n \times \lambda_n \right] \left[\frac{\lambda}{2} \times \lambda_n \times \lambda_n \times \lambda_n \right] \left[\frac{\lambda}{2} \times \lambda_n \times \lambda_n \times \lambda_n \right] \left[\frac{\lambda}{2} \times \lambda_n \times \lambda_n \times \lambda_n \times \lambda_n \right] \left[\frac{\lambda}{2} \times \lambda_n \times \lambda_n \times \lambda_n \times \lambda_n \times \lambda_n \right] \left[\frac{\lambda}{2} \times \lambda_n \times \lambda_n \times \lambda_n \times \lambda_n \times \lambda_n \right] \left[\frac{\lambda}{2} \times \lambda_n \times \lambda_n$ where a, 5 are parameter of regression of

5.6) Sigmoid Function - It acts as an activation function in mochine leaving which is used to add non-linearly in ML model. - It duides which value to pan as autom & what not to pan.

- Those are mainly 7 types of Activation
for which are used in ML & Dup learn 6 A) A duision boundary is the region of a problem space in which the output label appear is classified as ambiguous. 000 / 00 0 dan 2 000 000 0000 Hore, dashed time it duision boundary Duinion boundary spor sprake different claves. i) An optimal during boundary is one that minimizes the distance from points on bother classes of data This classification observed by using 2 indextones binary classifican. 8 con states different input features o For birary claubication, one decision boundary in the so swrface in the feature space that separates the test ing. ii) In a statistical clark cation problem, with mor than seed I classes as multiple claner, a decision boundary is hyporo space ento 2 un mone set, one son ad

Composed of 3 no. 7. B) Decission true are ports: i) Decision Nodes ii) Chance Nodes Duision Nodus : - It is a mode in one activity at which the flow branches into several optional =) Chance Nodu: - It is represented by a circle of Shows the Probabilities, artain routes. =) Find Nodur &t show the final outrom

if a decision path. There are 2 yper of decision Trees. They i) Categorical variable duision Tree. - There core 3 popular altribute selection manu gain in chosen as the splitting altibute ii) Opain Ratio - Ratio of information gain to the intrinsic information.

(ii) Gini Index: - Calculated by subtracting
the sum of squand probabilities of each class from one.