

## 1. DFS and BFS

```
from collections import deque

g = {1:[2,3], 2:[4], 3:[4], 4:[5]}

def dfs(u, goal, v=[], p=[]):
    v.append(u); p.append(u)
    if u==goal: return p
    for x in g.get(u,[]):
        if x not in v:
            r=dfs(x,goal,v,p)
            if r: return r
    p.pop(); return None

def bfs(s, goal):
    q=deque([(s,[s])]); v={s}
    while q:
        n,p=q.popleft()
        if n==goal: return p
        for x in g.get(n,[]):
            if x not in v: v.add(x); q.append((x,p+[x]))

print("DFS:", dfs(1,5))
print("BFS:", bfs(1,5))
```

### OUTPUT:

DFS: [1, 2, 4, 5]

BFS: [1, 2, 4, 5]

## 2. Hill Climbing:

```
import numpy as np

def f(x): return -x**2 + 5

def neigh(x, s=0.1): return [x+s, x-s]

x = 2.0

for i in range(100):

    n = neigh(x)

    best = max(n, key=f)

    if f(best) > f(x):

        x = best

        print(f"Step {i+1}: x={x:.4f}, f(x)={f(x):.4f}")

    else:

        print("Converged"); break

print(f"\nBest x={x:.4f}, f(x)={f(x):.4f}")
```

### OUTPUT:

```
Step 1: x=1.9000, f(x)=1.3900
Step 2: x=1.8000, f(x)=1.7600
Step 3: x=1.7000, f(x)=2.1100
Step 4: x=1.6000, f(x)=2.4400
Step 5: x=1.5000, f(x)=2.7500
Step 6: x=1.4000, f(x)=3.0400
Step 7: x=1.3000, f(x)=3.3100
Step 8: x=1.2000, f(x)=3.5600
Step 9: x=1.1000, f(x)=3.7900
Step 10: x=1.0000, f(x)=4.0000
Step 11: x=0.9000, f(x)=4.1900
Step 12: x=0.8000, f(x)=4.3600
Step 13: x=0.7000, f(x)=4.5100
Step 14: x=0.6000, f(x)=4.6400
Step 15: x=0.5000, f(x)=4.7500
```

Step 16:  $x=0.4000$ ,  $f(x)=4.8400$

Step 17:  $x=0.3000$ ,  $f(x)=4.9100$

Step 18:  $x=0.2000$ ,  $f(x)=4.9600$

Step 19:  $x=0.1000$ ,  $f(x)=4.9900$

Step 20:  $x=-0.0000$ ,  $f(x)=5.0000$

Converged

Best  $x=-0.0000$ ,  $f(x)=5.0000$

### 3. Knowledge Based Agent for Wumpus world

```
class KB:
```

```
    def __init__(s): s.f=set()
```

```
    def tell(s,f): s.f.add(f)
```

```
class WumpusAgent:
```

```
    def __init__(s):
```

```
        s.kb=KB(); s.gold=False
```

```
    def run(s):
```

```
        world={(0,0):["Breeze"],(0,1):["Stench"],(1,0):[],(1,1):["Breeze"]}
```

```
        for loc, percepts in world.items():
```

```
            for p in percepts: s.kb.tell((p,loc))
```

```
            if "Glitter" in percepts: s.gold=True
```

```
        print("Gold found" if s.gold else "Gold not found")
```

```
WumpusAgent().run()
```

### OUTPUT:

Gold not found

## 4. Knowledge Representation schemes

```
facts = {"raining", "cloudy"}

rules = [ (["raining"], "wet_ground"), (["cloudy"], "maybe_rain"), (["raining", "cloudy"], "umbrella_needed") ]

changed = True

while changed:

    changed = False

    for pre, con in rules:

        if con not in facts and all(p in facts for p in pre):

            facts.add(con)

            changed = True

print("All facts:", facts)
```

### OUTPUT:

**All facts: {'cloudy', 'wet\_ground', 'raining', 'umbrella\_needed', 'maybe\_rain'}**

## 5. Forward state space planning alg

```
from collections import deque
```

```
class A:
```

```
    def __init__(s,n,p,a,d=[]): s.n,p,s.a,s.d=n,set(p),set(a),set(d)
```

```
    def apply(s,state): return (state - s.d) | s.a
```

```
def plan(init,acts,goal):
```

```
    q,vis=deque([(init,[])]),{frozenset(init)}
```

```
    while q:
```

```
        s,p=q.popleft()
```

```
        if goal<=s: return p
```

```
        for a in acts:
```

```
            if a.n<=s:
```

```
                ns=frozenset(a.apply(s))
```

```
                if ns not in vis: vis.add(ns); q.append((ns,p+[list(a.a)]))
```

```
    return None
```

```
init=frozenset({"onA_table","clearA","onB_table","clearB"})
```

```
acts=[A(frozenset(["onA_table","clearA"]),["holdingA"],["onA_table","clearA"]),
```

```
      A(frozenset(["holdingA","clearB"]),["onA_B"],["holdingA","clearB"])]
```

```
goal=frozenset(["onA_B"])
```

```
print("Plan:", plan(init,acts,goal))
```

### OUTPUT:

Plan: None

## 6. Simple and polynomial Regression

```
import numpy as np, matplotlib.pyplot as plt
from sklearn.linear_model import LinearRegression
from sklearn.preprocessing import PolynomialFeatures
from sklearn.model_selection import train_test_split
from sklearn.metrics import r2_score

X,y=np.arange(1,11).reshape(-
1,1),np.array([35000,38000,42000,46000,50000,55000,60000,65000,70000,75000])
Xtr,Xte,ytr,yte=train_test_split(X,y,test_size=0.2,random_state=42)

lr=LinearRegression().fit(Xtr,ytr)
poly=PolynomialFeatures(2);
pr=LinearRegression().fit(poly.fit_transform(Xtr),ytr)

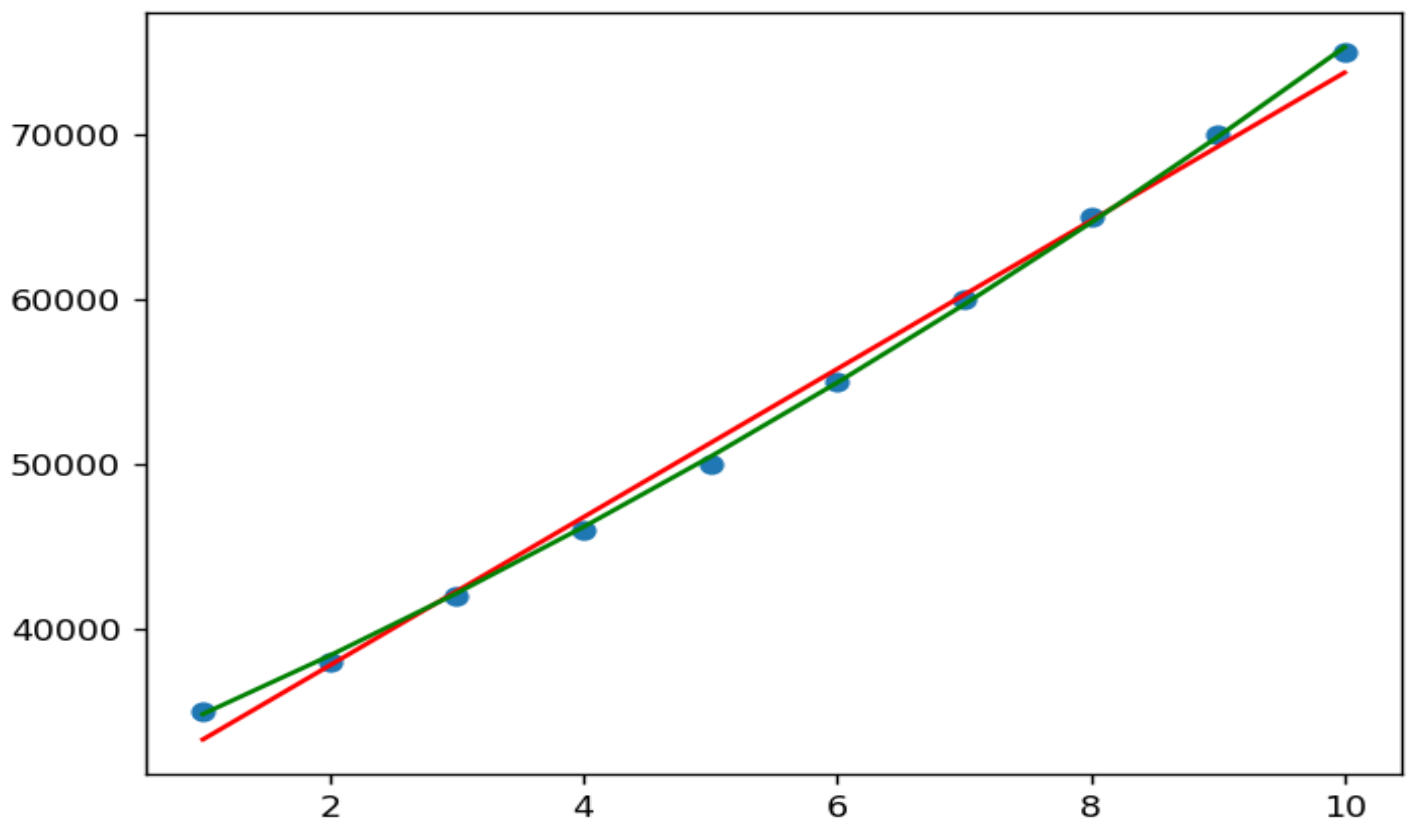
print("R² Linear:", r2_score(yte,lr.predict(Xte)))
print("R² Poly:", r2_score(yte,pr.predict(poly.transform(Xte))))

plt.scatter(X,y)
plt.plot(X,lr.predict(X),'r',X,pr.predict(poly.transform(X)),'g');
plt.show()
```

### OUTPUT:

R² Linear: 0.998779296875

R² Poly: 0.9997211508583043



## 7. KNN On Indian diabetes patient

```
import numpy as np,
matplotlib.pyplot as plt

X=np.array([[2,120,70,20,80,25,0.5,30],[4,150,80,25,90,30,0.7,45],
            [1,85,60,18,60,22,0.3,25],[6,180,90,30,120,35,0.9,50],
            [3,95,65,20,70,23,0.4,28],[5,160,85,28,100,33,0.8,48]])
y=np.array([0,1,0,1,0,1])

X=(X-X.mean(0))/X.std(0)

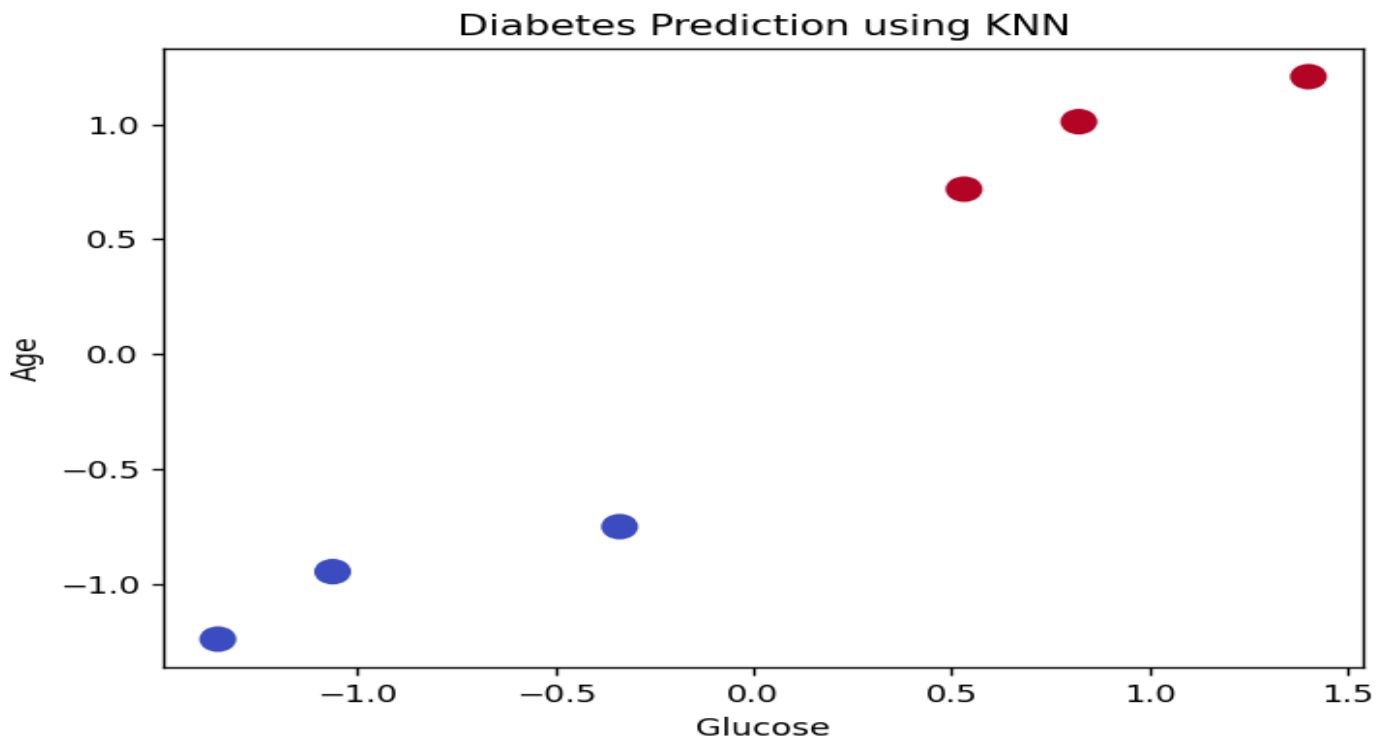
def knn(X,y,q,k=3):
    d=np.sqrt(((X-q)**2).sum(1)); r
    eturn int(round(y[np.argsort(d)[:k]].mean()))

q=np.array([2,130,72,22,85,26,0.6,32]); q=(q-X.mean(0))/X.std(0)
print("Prediction (1=Diabetic,0=Not):", knn(X,y,q))

plt.scatter(X[:,1],X[:,7],c=y,cmap="coolwarm",s=100)
plt.xlabel("Glucose"); plt.ylabel("Age");
plt.title("Diabetes Prediction using KNN");
plt.show()
```

### OUTPUT:

Prediction (1=Diabetic,0=Not): 1



## 8. K-means Clustering mode

```
import pandas as pd, matplotlib.pyplot as plt
```

```
from sklearn.cluster import KMeans
```

```
from sklearn.preprocessing import StandardScaler
```

```
df=pd.DataFrame({'Age':[22,25,47,52,46,56,55,60,28,30],
```

```
                 'Experience':[1,3,20,25,18,30,28,35,5,7],
```

```
                 'Income':[15000,20000,85000,100000,80000,120000,110000,150000,30000,35000]}))
```

```
print("Employee Dataset:\n", df)
```

```
data_scaled = StandardScaler().fit_transform(df)
```

```
df['Cluster'] = KMeans(n_clusters=3, random_state=42).fit_predict(data_scaled)
```

```
plt.scatter(df['Experience'],df['Income'],c=df['Cluster'],cmap='viridis')
```

```
plt.xlabel('Experience'); plt.ylabel('Income'); plt.title('Employee Income Clusters');
```

```
plt.show()
```

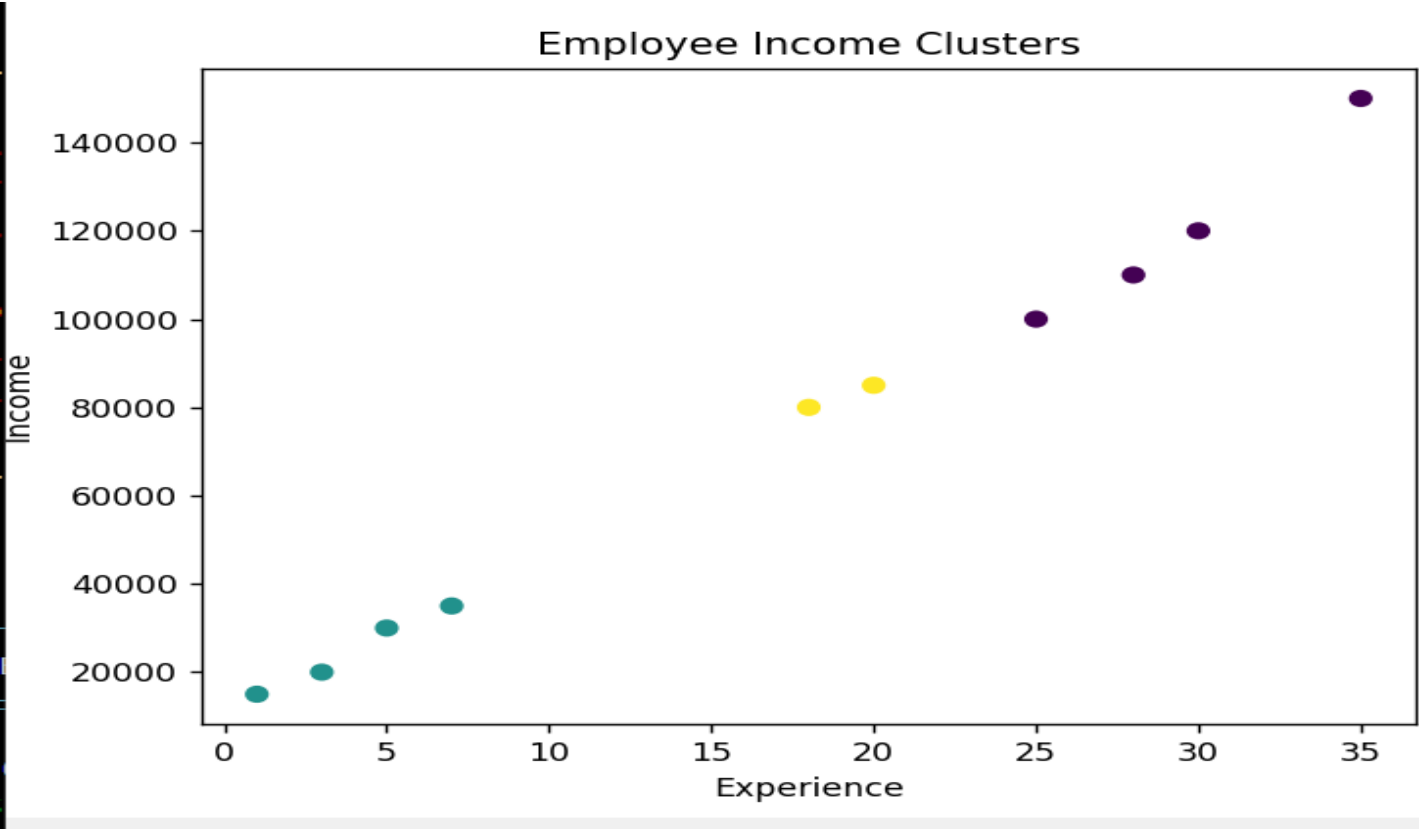
**OUTPUT:**



Employee Dataset:

Age Experience Income

0	22	1	15000
1	25	3	20000
2	47	20	85000
3	52	25	100000
4	46	18	80000
5	56	30	120000
6	55	28	110000
7	60	35	150000
8	28	5	30000
9	30	7	35000



## 9. IRIS Flower

```
import numpy as np

from sklearn.datasets import load_iris

from sklearn.preprocessing import StandardScaler

from sklearn.decomposition import PCA

from sklearn.linear_model import LogisticRegression

from sklearn.model_selection import train_test_split

from sklearn.metrics import accuracy_score


X,y=load_iris(return_X_y=True)

sc=StandardScaler(); X=sc.fit_transform(X)

pca=PCA(1); X=pca.fit_transform(X)

Xtr,Xte,ytr,yte=train_test_split(X,y,test_size=0.2,random_state=42)

model=LogisticRegression().fit(Xtr,ytr)

print("Accuracy:",accuracy_score(yte,model.predict(Xte)))

new=np.array([[5.1,3.5,1.4,0.2]]); new=pca.transform(sc.transform(new))

print("Predicted Species:", load_iris().target_names[model.predict(new)][0])
```

OUTPUT:

Accuracy: 0.9

Predicted Species: setosa

## 10. Q- learning

```
import numpy as np, random
```

```
n_states, n_actions, goal = 5, 2, 4
```

```
Q = np.zeros((n_states, n_actions))
```

```
alpha, gamma, epsilon, episodes = 0.1, 0.9, 0.2, 500
```

```
for _ in range(episodes):
```

```
    s = 0
```

```
    while s != goal:
```

```
        a = random.randint(0,1) if random.random() < epsilon else np.argmax(Q[s])
```

```
        ns = s+1 if a==1 else max(0, s-1)
```

```
        r = 10 if ns==goal else -1
```

```
        Q[s,a] += alpha * (r + gamma * np.max(Q[ns]) - Q[s,a])
```

```
        s = ns
```

```
print("Learned Q-table:")
```

```
print(np.round(Q, 2))
```

### OUTPUT:

Learned Q-table:

```
[[ 3.09  4.58]
```

```
 [ 3.11  6.2 ]
```

```
 [ 4.57  8.  ]
```

```
 [ 6.19 10.  ]
```

```
 [ 0.   0.  ]]
```