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# decision_tree_model.py
from model_base import ModelBase
from sklearn.tree import DecisionTreeClassifier
from sklearn.model_selection import GridSearchCV
from sklearn.metrics import classification_report, roc_auc_score, precision_recall_curve,confusion_matrix
import numpy as np
class DecisionTreeModel(ModelBase):
      def __init__(self):
    super().__init__()
    self.model = DecisionTreeClassifier(random_state=42)
       def train(self, X_train, y_train):
             print("Training Decision Tree Classifier...")
self.model.fit(X_train, y_train)
       def tune_hyperparameters(self, X_train, y_train):
             print("Tuning hyperparameters for Decision Tree...")
param_grid = {
                    m_grid = {
  'max_depth': [3, 5, 10, None],
  'min_samples_split': [2, 5, 10],
  'criterion': ['gini', 'entropy']
             grid = GridSearchCV(DecisionTreeClassifier(random_state=42),
             param_grid, cv=5, scoring='fl', n_jobs=-1)
grid.fit(X_train, y_train)
print("Best Params:", grid.best_params_)
self.model = grid.best_estimator_
       def evaluate_with_threshold(self, X_test, y_test, threshold=0.5):
             if hasattr(self.model, "predict_proba"):
    y_probs = self.model.predict_proba(X_test)[:, 1]
              else
                    y_probs = self.model.decision_function(X_test)
             y_pred = (y_probs >= threshold).astype(int)
             print(f"Evaluation with Threshold = {threshold}")
print(classification_report(y_test, y_pred))
print("ROC-AUC Score:", roc_auc_score(y_test, y_probs))
cm = confusion_matrix(y_test, y_pred)
print("Confusion Matrix:\n", cm)
return y_pred, y_probs
       def find_best_threshold(self, X_val, y_val):
    y_probs = self.model.predict_proba(X_val)[:, 1]
              precision, recall, thresholds = precision_recall_curve(y_val, y_probs)
              fl_scores = 2 * (precision * recall) / (precision + recall + 1e-8)
             best_index = np.argmax(fl_scores)
best_threshold = thresholds[best_index]
print(f"Best threshold based on F1-score: {best_threshold:.2f}")
return best_threshold
```