# Assignment 2

## EE 645 3D Computer Vision

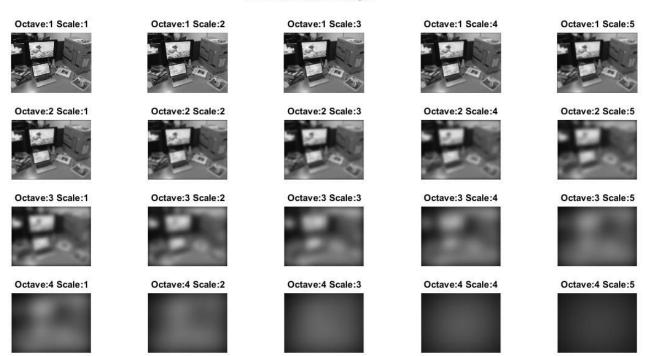
(a) The gaussian scale space has been constructed using the following values of standard deviations.

	1	2	3	4	5
1	0.7071	1	1.4142	2.0000	2.8284
2	1.4142	2.0000	2.8284	4.0000	5.6569
3	2.8284	4.0000	5.6569	8.0000	11.3137
4	5.6569	8.0000	11.3137	16.0000	22.6274

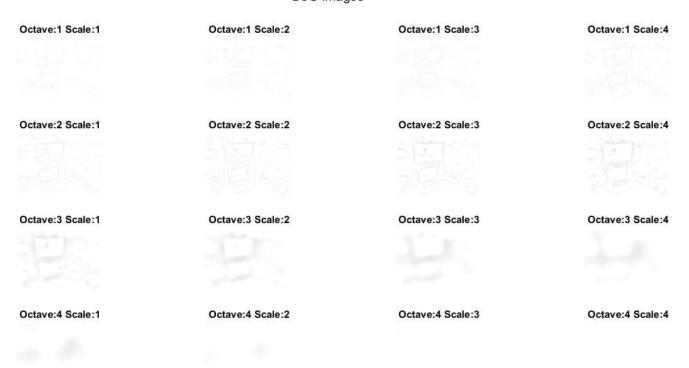
Rows are octaves and columns denote the scale.

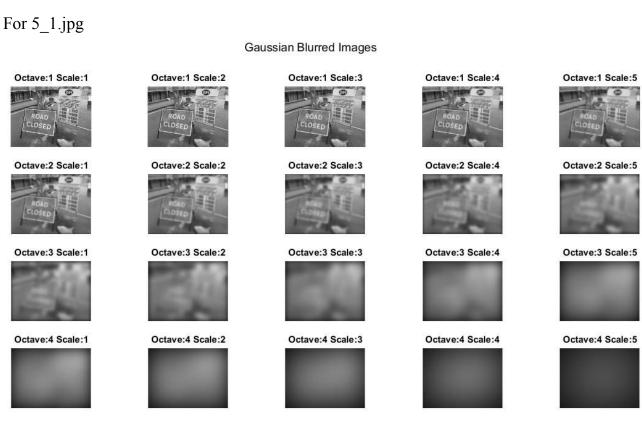
For 3\_1.jpg

#### Gaussian Blurred Images

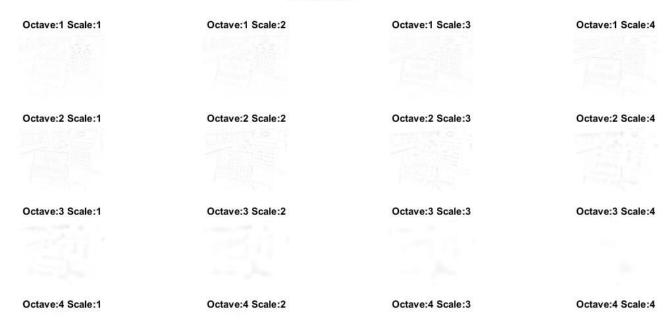


### DoG Images





#### DoG Images



(b) Keypoint Detection. Different colors denote different octaves in which the keypoint was detected.

In 3\_1.jpg



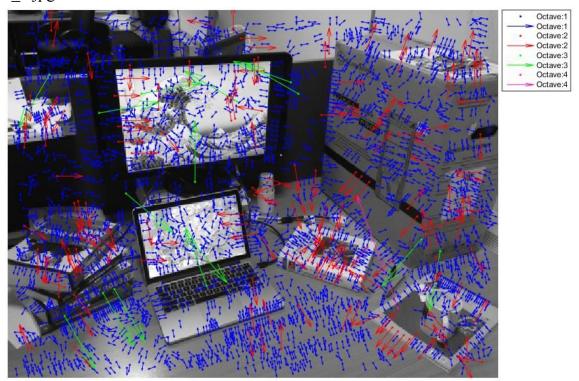
# In 5\_1.jpg



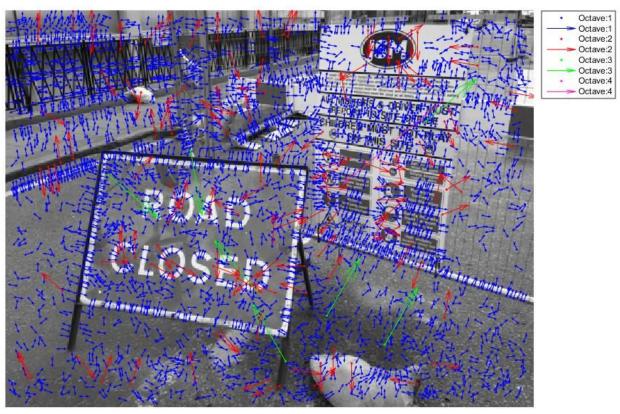
## (c) Orientation Assignment.

Different colors denote different octaves in which the keypoint was detected. The length of vector also denotes the octave of the keypoint.

# 3\_1.jpg



5\_1.jpg

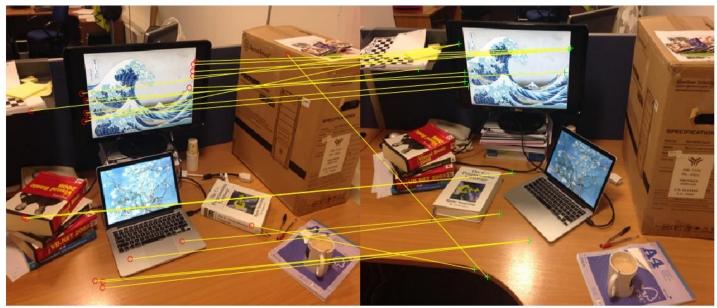


### (d) Keypoint Descriptor

A total of 2793 keypoints in 3\_1.jpg and 3051 keypoints in 5\_1.jpg have been assigned a 128 Dimensional vector. The images were resized so that there were only 512 columns.

(e) Image matching using norm-2 distance. The matching is not quite accurate since accurate keypoint localisation and edge response elimination has not been performed.

Matching between 3\_1.jpg and 3\_2.jpg.



Matching between 5\_1.jpg and 5\_2.jpg.



Some of the manually picked keypoints











