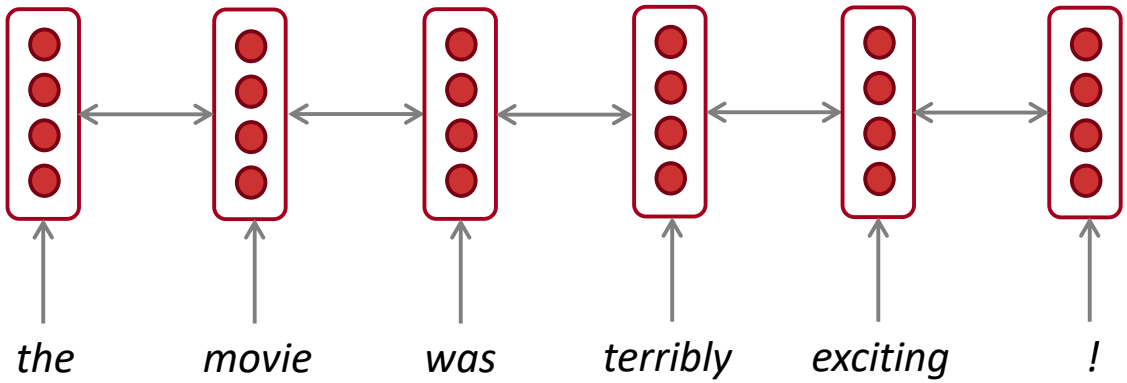
Bidirectional RNNs: simplified diagram



The two-way arrows indicate bidirectionality and the depicted hidden states are assumed to be the concatenated forwards+backwards states.

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Bidirectional RNNs

- Note: bidirectional RNNs are only applicable if you have access to the entire input sequence.
  - They are **not** applicable to Language Modeling, because in LM you *only* have left context available.

- If you do have entire input sequence (e.g. any kind of encoding), bidirectionality is powerful (you should use it by default).

- For example, BERT (**Bidirectional** Encoder Representations from Transformers) is a powerful pretrained contextual representation system built on bidirectionality.
  - You will learn more about BERT later in the course!

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Multi-layer RNNs

- RNNs are already "deep" on one dimension (they unroll over many timesteps)
- We can also make them "deep" in another dimension by applying multiple RNNs – this is a multi-layer RNN.
- This allows the network to compute more complex representations
  - The lower RNNs should compute lower-level features and the higher RNNs should compute higher-level features.
- Multi-layer RNNs are also called *stacked RNNs*.

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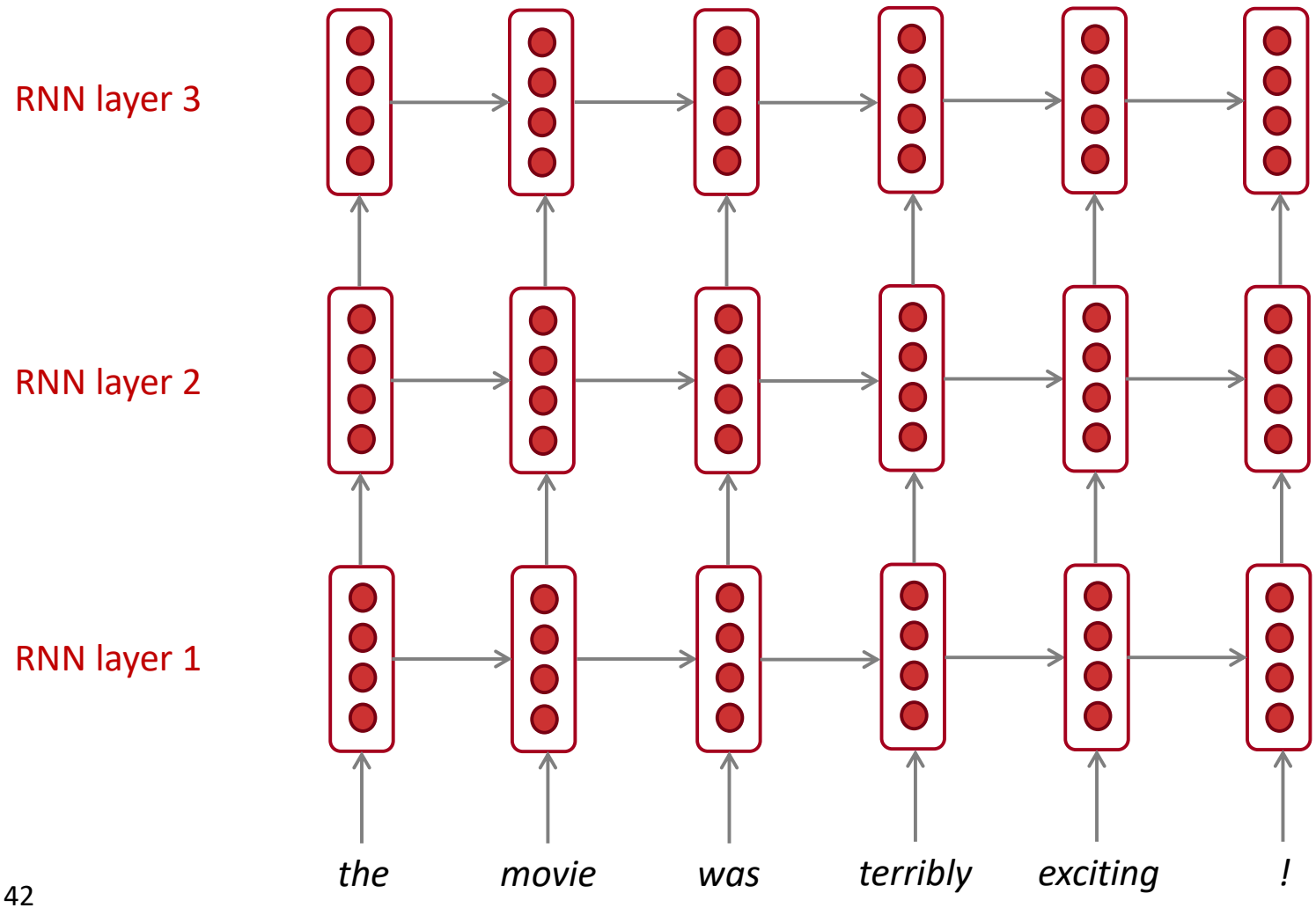
Multi-layer RNNs

The hidden states from RNN layer *i* are the inputs to RNN layer *i+1*



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Multi-layer RNNs in practice

- High-performing RNNs are often multi-layer (but aren't as deep as convolutional or feed-forward networks)
- For example: In a 2017 paper, Britz et al find that for Neural Machine Translation, 2 to 4 layers is best for the encoder RNN, and 4 layers is best for the decoder RNN
  - However, skip-connections/dense-connections are needed to train deeper RNNs (e.g. 8 layers)
- Transformer-based networks (e.g. BERT) can be up to 24 layers
  - You will learn about Transformers later; they have a lot of skipping-like connections

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"Massive Exploration of Neural Machine Translation Architecutres", Britz et al, 2017. https://arxiv.org/pdf/1703.03906.pdf

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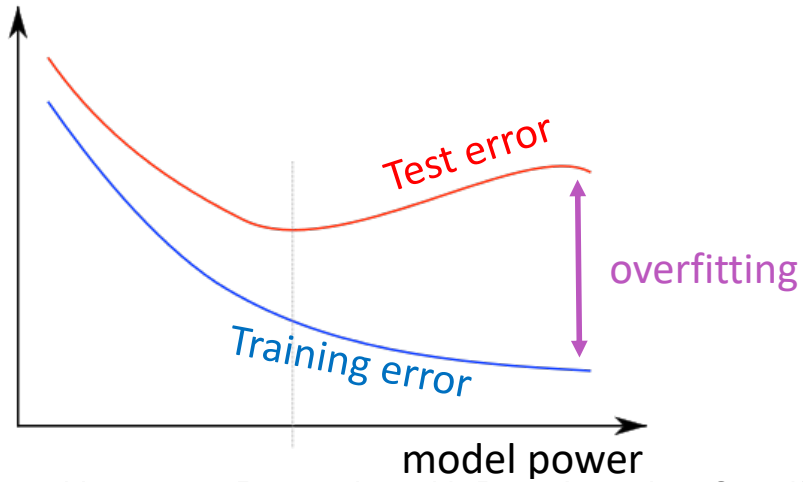
Content

We have models with many params! Regularization!

- Really a full loss function in practice includes **regularization** over all parameters θ, e.g., L2 regularization:

$$J(\theta) = \frac{1}{N}\sum_{i=1}^{N} -\log\left(\frac{e^{f_{y_i}}}{\sum_{c=1}^{C} e^{f_c}}\right) + \lambda \sum_{k} \theta_k^2$$

- Regularization works to prevent overfitting when we have a lot of features (or later a very powerful/deep model, ++)



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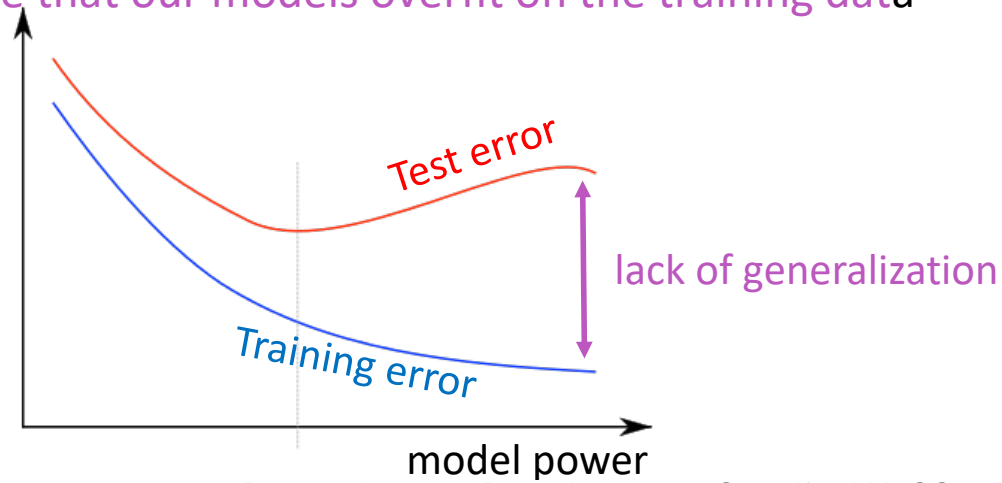
- Regularization produces models that generalize well when we have a lot of features (or later a very powerful/deep model, ++)
  - We do not care that our models overfit on the training data



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Dropout

(Srivastava, Hinton, Krizhevsky, Sutskever, & Salakhutdinov 2012/JMLR 2014)

Preventing Feature Co-adaptation = Regularization

- Training time: at each instance of evaluation (in online SGD-training), randomly set 50% of the inputs to each neuron to 0
- Test time: halve the model weights (now twice as many)
- This prevents feature co-adaptation: A feature cannot only be useful in the presence of particular other features
- In a single layer: A kind of middle-ground between Naïve Bayes (where all feature weights are set independently) and logistic regression models (where weights are set in the context of all others)
- Can be thought of as a form of model bagging
- Nowadays usually thought of as strong, feature-dependent regularizer [Wager, Wang, & Liang 2013]

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"Vectorization"

- E.g., looping over word vectors versus concatenating them all into one large matrix and then multiplying the softmax weights with that matrix

```
from numpy import random
N = 500 # number of windows to classify
d = 300 # dimensionality of each window
C = 5 # number of classes
W = random.rand(C,d)
wordvectors_list = [random.rand(d,1) for i in range(N)]
wordvectors_one_matrix = random.rand(d,N)

%timeit [W.dot(wordvectors_list[i]) for i in range(N)]
%timeit W.dot(wordvectors_one_matrix)
```

- 1000 loops, best of 3: **639 µs** per loop
  10000 loops, best of 3: **53.8 µs** per loop

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"Vectorization"

```
from numpy import random
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d = 300 # dimensionality of each window
C = 5 # number of classes
W = random.rand(C,d)
wordvectors_list = [random.rand(d,1) for i in range(N)]
wordvectors_one_matrix = random.rand(d,N)

%timeit [W.dot(wordvectors_list[i]) for i in range(N)]
%timeit W.dot(wordvectors_one_matrix)
```

- The (10x) faster method is using a C x N matrix
- Always try to use vectors and matrices rather than for loops!
- You should speed-test your code a lot too!!
- These differences go from 1 to 2 orders of magnitude with GPUs
- tl;dr: Matrices are awesome!!!

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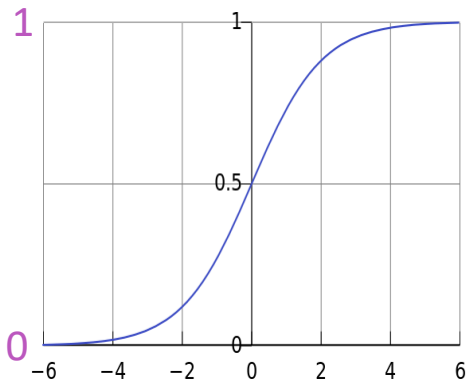
Non-linearities: The starting points

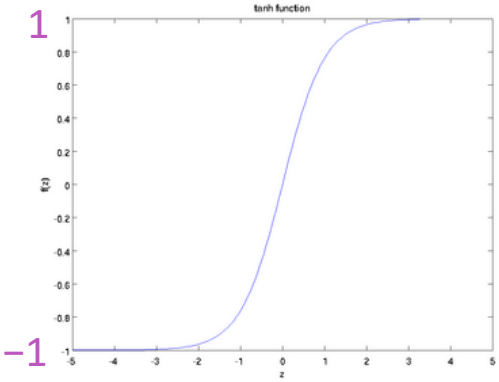
logistic ("sigmoid")

$$f(z) = \frac{1}{1 + \exp(-z)}.$$



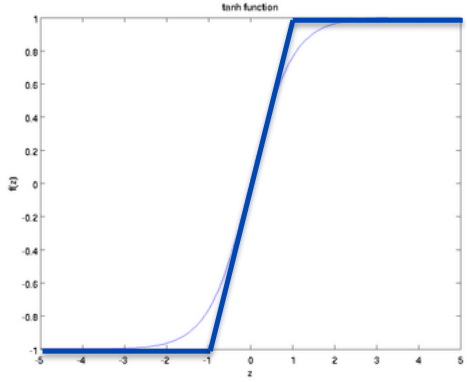
tanh

$$f(z) = \tanh(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}},$$



hard tanh

$$\text{HardTanh}(x) = \begin{cases} -1 & \text{if } x < -1 \\ x & \text{if } -1 <= x <= 1 \\ 1 & \text{if } x > 1 \end{cases}$$



tanh is just a rescaled and shifted sigmoid (2 × as steep, [−1,1]):

$$\tanh(z) = 2\text{logistic}(2z) - 1$$

Both logistic and tanh are still used in particular uses, but are no longer the defaults for making deep networks

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Non-linearities: The new world order

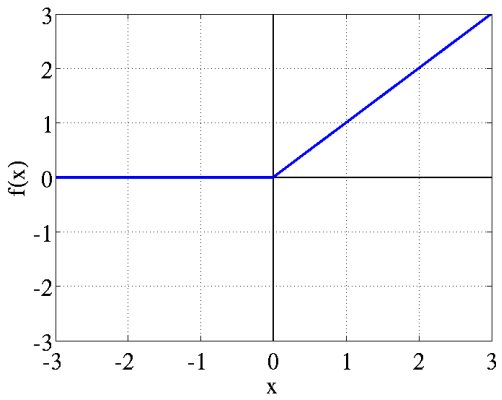
ReLU (rectified linear unit) hard tanh

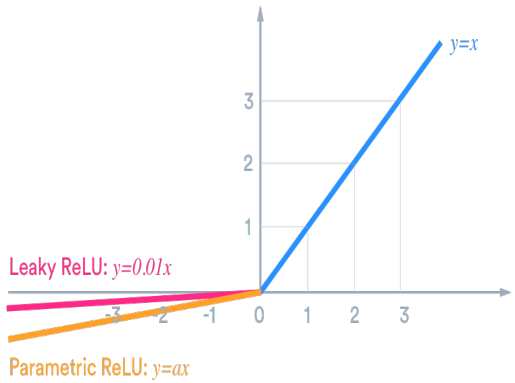
Leaky ReLU / Parametric ReLU

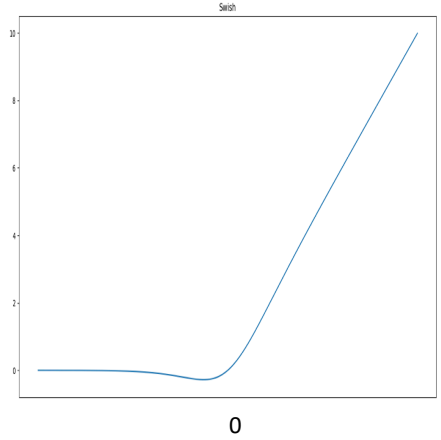
Swish

[Ramachandran, Zoph & Le 2017]

$$\text{rect}(z) = \max(z, 0)$$







- For building a deep feed-forward network, the first thing you should try is ReLU — it trains quickly and performs well due to good gradient backflow

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Parameter Initialization

- You normally must initialize weights to small random values
  - To avoid symmetries that prevent learning/specialization
- Initialize hidden layer biases to 0 and output (or reconstruction) biases to optimal value if weights were 0 (e.g., mean target or inverse sigmoid of mean target)
- Initialize **all other weights** ~ Uniform(–*r*, *r*), with *r* chosen so numbers get neither too big or too small
- Xavier initialization has variance inversely proportional to fan-in n_{in} (previous layer size) and fan-out n_{out} (next layer size):

$$\mathrm{Var}(W_i) = \frac{2}{n_{\mathrm{in}} + n_{\mathrm{out}}}$$

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Optimizers

- Usually, plain SGD will work just fine
  - However, getting good results will often require hand-tuning the learning rate (next slide)
- For more complex nets and situations, or just to avoid worry, you often do better with one of a family of more sophisticated "adaptive" optimizers that scale the parameter adjustment by an accumulated gradient.
  - These models give differentiak per-parameter learning rates
    - Adagrad
    - RMSprop
    - Adam ← A fairly good, safe place to begin in many cases
    - SparseAdam
    - …

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Learning Rates

- You can just use a constant learning rate. Start around *lr* = 0.001?
  - It must be order of magnitude right – try powers of 10
    - Too big: model may diverge or not converge
    - Too small: your model may not have trained by the deadline
- Better results can generally be obtained by allowing learning rates to decrease as you train
  - By hand: halve the learning rate every *k* epochs
    - An epoch = a pass through the data (shuffled or sampled)
  - By a formula: $lr = lr_0 e^{-kt}$, for epoch t
  - There are fancier methods like cyclic learning rates (q.v.)
- Fancier optimizers still use a learning rate but it may be an initial rate that the optimizer shrinks – so may need to start high

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Content