# Using the Digital I/O interface of STMicroelectronics STM32 Microcontrollers

#### Corrado Santoro

#### ARSLAB - Autonomous and Robotic Systems Laboratory

Dipartimento di Matematica e Informatica - Università di Catania, Italy

santoro@dmi.unict.it

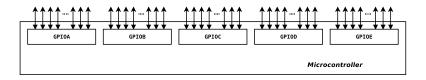


L.A.P. 1 Course

## What is a "digital I/O interface"?

- It is an interface in which each electrical pin may have two states:
  - Logical o (it means 0V);
  - Logical 1 (it means 5V or 3.3V on the basis of the VDD);
- Each line can be programmer as:
  - an output (it "generates" current and can be used, for example, to lit a LED)
  - an input (it "receives" current and can be used, for example, to read a pushbutton)

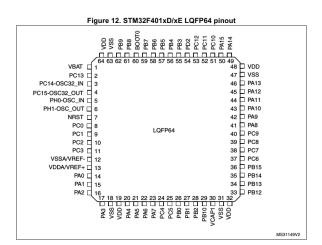
## The General Purpose I/O (GPIO) Interface of STM32



- MCUs of the STM32 family have several digital ports, called GPIOA, GPIOB, GPIOC, ...,
- Each port has 16 bits and thus 16 electrical pins
- Pins are referred as Pxy, where x is the port name (A, B, ..., E) and y is the bit (0, 1, ..., 15).
- As an example, the pin PC3 is the bit 3 of the port C.
- Each PIN has also an alternate function, related to a peripheral e.g. Timer, UART, SPI, etc.
- According to the MCU package, not all bits are mapped to electrical pins. This is a choice "by-design".



# The General Purpose I/O (GPIO) Interface of STM32



## Using the GPIO Interface

 To use a specific GPIO line (pin), the following operations are needed:

### Set-up

- Initialize the whole GPIO port (this operation basically enables the clock line to the GPIO port)
- 2 Set the direction (input or output) of the pin you intend to use

### Operate

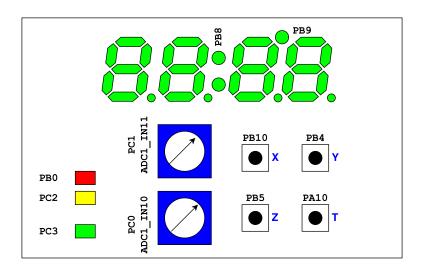
- Read the GPIO pin, if it is programmed as "input", or
- Write the GPIO pin, if it is programmed as "output"
- These operations are made really simple using the stm32\_unict\_lib



## Using the GPIO Interface with stm32\_unict\_lib

- Example: setting PA5 as output and using it
- Set-up
  - Initialize the whole GPIO port (this operation basically enables the clock line to the GPIO port)
    GPIO\_init (GPIOA);
  - Set the direction of the pin you intend to use GPIO\_config\_output (GPIOA, 5);
- Operate
  - Write "0" to PA5: GPIO\_write (GPIOA, 5, 0);
    Write "1" to PA5: GPIO\_write (GPIOA, 5, 1);

## The Nucleo64 Addon Board



## First Example: Flashing a LED

```
#include "stm32 unict lib.h"
int main()
   // initialize port B
   GPIO init (GPIOB);
   // configure pin PA5 as output
   GPIO config output (GPIOB, 8);
   // infinite loop
   for (;;) {
       GPIO_write(GPIOB, 8, 1); // set PB8 to 1
       delay_ms(500); // wait 0.5 secs
       GPIO_write(GPIOB, 8, 0); // set PB8 to 0
       delay_ms(500);
                     // wait 0.5 secs
```

# Using the GPIO Interface with stm32\_unict\_lib

- Example: setting PC3 as input and using it
- Set-up
  - Initialize the whole GPIO port (this operation basically enables the clock line to the GPIO port)
     GPIO\_init(GPIOC);
    - Set the direction of the pin you intend to use GPIO\_config\_input (GPIOC, 3);
- Operate
  - Read PC3 pin: int pinval = GPIO\_read(GPIOC, 3);
  - "pinval" can be "0" or "1"

## First Example: Read a Pushbutton and lit the LED

```
#include "stm32 unict lib.h"
int main()
    // pushbutton on PA10: LED on PB8
    // initialize ports
    GPIO init (GPIOA);
    GPIO init (GPIOB);
    // configure pin PA10 as input
    GPIO_config_input (GPIOA, 10);
    // configure pin PB8 as output
    GPIO config_output(GPIOB, 8);
    // infinite loop
    for (::) {
        int pinval = GPIO read(GPIOA, 10);
        GPIO_write(GPIOB, 8, !pinval);
```

## Inside the code....

- What are the GPIOA, GPIOB, ... variables?
- What are the prototypes of the GPIO functions?
- GPIOA, GPIOB, ... are global variables defined in CMSIS libraries as:
   GPIO\_TypeDef \* GPIOA;

```
GPIO_TypeDef * GPIOB;
...;
```

- GPIO\_TypeDef is a structure whose fields are the special-function-registers (SFRs) of a GPIO port
- Each GPIOA, GPIOB, ... variable is a pointer to a GPIO\_TypeDef and represents the address of the memory holding the SFRs of that port

## The GPIO function prototypes

```
Initialize a GPIO port:
  void GPIO_init(GPIO_TypeDef * port);
Configure a GPIO pin as input:
  void GPIO_configure_input(GPIO_TypeDef * port,
                               int pin_num);
Configure a GPIO pin as output:
  void GPIO_configure_output(GPIO_TypeDef * port,
                               int pin_num);
Write to an output pin:
  void GPIO_write(GPIO_TypeDef * port, int pin_num,
                    int pin_val);
Read from an input pin:
  int GPIO_read(GPIO_TypeDef * port, int pin_num);
Change the state of an output pin:
  void GPIO_toggle(GPIO_TypeDef * port, int pin_num);
```

# Using the Digital I/O interface of STMicroelectronics STM32 Microcontrollers

#### Corrado Santoro

#### ARSLAB - Autonomous and Robotic Systems Laboratory

Dipartimento di Matematica e Informatica - Università di Catania, Italy

santoro@dmi.unict.it



L.A.P. 1 Course