

ANDREW TULLOCH

MATHEMATICS OF OP- ERATIONS RESEARCH EXAMPLES

TRINITY COLLEGE
THE UNIVERSITY OF CAMBRIDGE

Contents

1	<i>Example Sheet 1</i>	5
---	------------------------	---

1

Example Sheet 1

(i) The Lagrangian of the problem is

$$L(x, \lambda) = -2x_1^2 - x_2^2 + x_1x_2 - \lambda(3x_1 + x_2 - 10) \quad (1.1)$$

with partial derivatives

$$\frac{\partial L}{\partial x_1} = -4x_1 + x_2 + 8 - 3\lambda \quad (1.2)$$

$$\frac{\partial L}{\partial x_2} = -2x_2 + x_1 + 3 - \lambda \quad (1.3)$$

$$(1.4)$$

$$\frac{\partial L}{\partial \lambda} = 3x_1 + x_2 - 10 \quad (1.5)$$

and second partial derivatives

$$\frac{\partial^2 L}{\partial x_1^2} = -4 \quad (1.6)$$

$$\frac{\partial^2 L}{\partial x_2^2} = -2 \quad (1.7)$$

$$\frac{\partial^2 L}{\partial x_1 \partial x_2} = 1 \quad (1.8)$$

Setting (1.2), (1.3), (1.5) to zero and solving the set of equations gives

$$x_1 = \frac{69}{28} \quad (1.9)$$

$$x_2 = \frac{73}{28} \quad (1.10)$$

The Hessian matrix is

$$\begin{vmatrix} -4 & 1 \\ 1 & -2 \end{vmatrix} = 7 > 0 \quad (1.11)$$

and $\frac{\partial^2 L}{\partial x_1^2} < 0$, so the solution is the maximizer of L . Thus, by the Lagrangian Sufficiency theorem, the solution is a maximizer of original problem.

(ii)

(iii)

(iv) Let $A \stackrel{*}{\equiv} B$ indicate that A is the dual of B . Then we have

$$\min\{c^T x | Ax \geq b, x \geq 0\} \stackrel{*}{\equiv} \max\{b^T x | A^T x \leq c, x \geq 0\} \quad (1.12)$$

Let a linear program be given in the general form. Then

$$\min\{c^T x | Ax \geq b, x \geq 0\} \stackrel{*}{\equiv} \max\{b^T x | A^T x \leq c, x \geq 0\} \quad (1.13)$$

$$= \min\{(-b)^T x | (-A)^T x \geq (-c), x \geq 0\} \quad (1.14)$$

$$\stackrel{*}{\equiv} \{(-c)^T x | ((-A)^T)^T x \leq -b, x \geq 0\} \quad (1.15)$$

$$= \min\{c^T x | Ax \geq b, x \geq 0\} \quad (1.16)$$

and thus the dual of the dual of a linear program is identical to the linear program.

(v) (i) The general linear program

$$\min\{c^T x | Ax \geq b, x \geq 0\} \stackrel{*}{\equiv} \max\{b^T x | A^T x \leq c, x \geq 0\} \quad (1.17)$$

We then have

$$\max\{0^T x | Ax = b, x \geq 0\} \equiv \min\{(-0)^T x | Ax = b, x \geq 0\} \quad (1.18)$$

$$\stackrel{*}{\equiv} \max\{z^T b | z^T A \leq 0^T\} \quad (1.19)$$

$$\equiv \min\{y^T b | y^T A \geq 0^T\} \quad (1.20)$$

Thus, the dual of (1.18) is (1.20) as required.

- (ii) By weak duality, we have for any feasible solutions y of (1.18) and x of (1.20), that

$$0^T x = 0 \leq y^T b \quad (1.21)$$

If (1.18) is feasible, then by weak duality, (1.20) is bounded below by zero (by (1.21)).

(1.20) is obviously feasible, since $y = 0$ is a feasible solution.

If (1.20) is bounded, we can solve it using the Simplex method, which also gives us an optimal and therefore feasible solution for (1.18).

- (iii) The two cases correspond to the two cases of the above result. (1.18) is feasible if and only if there exists $x \in \mathbb{R}^n$ with $Ax = b$ and $x \geq 0$. (1.18) is infeasible if and only if (1.20) is unbounded if and only if there exists $y \in \mathbb{R}^m$ such that $y^T A \geq 0$ and $y^T b < 0$.

(vi)

(vii)

(viii)

(ix)

(x)

- (xi) (i) Trivial to verify this problem is in NP, as given a certificate, simply follow the path through the nodes, which is linear in the number of nodes.
- (ii) Pretty tricky, just following construction in [HTTP://AMA.epfl.ch/~moustafa/Other/Complexityslides/lec7.pdf](http://ama.epfl.ch/~moustafa/Other/Complexityslides/lec7.pdf).
- (iii) Traveling salesman problem - given an instance of undirected Hamiltonian cycle $G(V, E)$, construct an instance of TSP $T(V', d)$ by placing a city at each $v \in V$ (so $V' = V$), and let

$$d(v_1, v_2) = \begin{cases} 1 & (v_1, v_2) \in E \\ 2 & \text{otherwise} \end{cases} \quad (1.22)$$

There exists a TSP path of length $|V|$ if and only if there exists an undirected Hamiltonian cycle in the original graph.

We now reduce directed Hamiltonian cycle to undirected Hamiltonian cycle. For an instance $G(V, E)$ of the directed problem, construct the undirected graph $G'(V', E')$ where each vertex v_i is replaced by three vertices $v'_{i1}, v'_{i2}, v'_{i3}$, with edges $v'_{i1} \leftrightarrow v'_{i2}, v'_{i2} \leftrightarrow v'_{i3}$, and $v'_{i3} \leftrightarrow v'_{j1}$ if $v_i \rightarrow v_j$.

We then trivially have that any undirected Hamiltonian cycle in G' can be mapped to a directed Hamiltonian cycle in G , as required.