

# PATTERN RECOGNITION

## Lab 2, Bayesian Decision Theory Random Number Generation

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# Bayesian decision rule

- Bayesian *decision rule*
  - If  $P(\omega_1) > P(\omega_2)$ , decide  $\omega_1$ ; else decide  $\omega_2$
  - What is the possible error:  $\min(P(\omega_1), P(\omega_2))$
  - More information can be obtained: different fish have obvious lightness measurement  $x$  as a *continuous* variable, its distribution in terms of class  $\omega_1$  is expressed as
    - $p(x/\omega_1)$  – *class-conditional probability density* function
      - probability density function for  $x$ , given class nature is  $\omega_1$
      - is not a probability
      - the distribution of  $x$  depends on it
      - what is the physical meaning?

# Bayesian formula

- *Bayes' formula*

- Probability density of a pattern in  $\omega_j$  and having feature value  $x$ :

- $$p(\omega_j, x) = P(\omega_j | x)p(x) = p(x | \omega_j)P(\omega_j)$$

- $$P(\omega_j | x) = \frac{p(x | \omega_j)P(\omega_j)}{p(x)}$$
 - *Bayes' formula*

- $$p(x) = \sum_{j=1}^2 p(x | \omega_j)P(\omega_j)$$

- $$\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{\text{evidence}}$$

- Converting a prior probability to a posterior probability

- $p(x | \omega_j)$  – *likelihood* of  $\omega_j$  with respect to  $x$

- $p(x)$  is called the *evidence*

# Rewriting Bayes' Decision Rule

- How can we make a decision after observing the value of  $x$ ?

$$\text{Decide } \begin{cases} w_1 & \text{if } P(w_1|x) > P(w_2|x) \\ w_2 & \text{otherwise} \end{cases}$$

- Rewriting the rule gives

$$\text{Decide } \begin{cases} w_1 & \text{if } \frac{p(x|w_1)}{p(x|w_2)} > \frac{P(w_2)}{P(w_1)} \\ w_2 & \text{otherwise} \end{cases}$$

- Note that, at every  $x$ ,  $P(w_1|x) + P(w_2|x) = 1$ .

# Probability error

- Bayes' decision rule (two class classification):  
Decide  $\omega_1$  if  $P(\omega_1/x) > P(\omega_2/x)$ ; otherwise decide  $\omega_2$
- Probability error from the Bayes' decision rule:  
 $P(error/x) = P(\omega_1/x)$  if we decide  $\omega_2$   
 $= P(\omega_2/x)$  if we decide  $\omega_1$ .  
 $\rightarrow P(error/x) = \min [P(\omega_1/x), P(\omega_2/x)]$
- $P(error) = \int_{-\infty}^{\infty} P(error, x) dx = \int_{-\infty}^{\infty} P(error/x) p(x) dx$
- How to minimize this error?

# Random

- Truly Random
  - Exhibiting true randomness
- Pseudorandom
  - Appearance of randomness but having a specific repeatable pattern
- Quasi-random
  - Having a set of non-random numbers in a randomized order

# Seeds

- In your experimentation, you can generate 100 streams each with a different seed point in order to:
  - avoid duplicate streams of random numbers,
  - get a general idea of the behavior of the random number generator on your workstation.
- Seeds can be obtained from:
  - A. M. Law and W. D. Kelton, *Simulation Modeling & Analysis*, 2nd Edition, McGraw-Hill, NewYork, 1991.

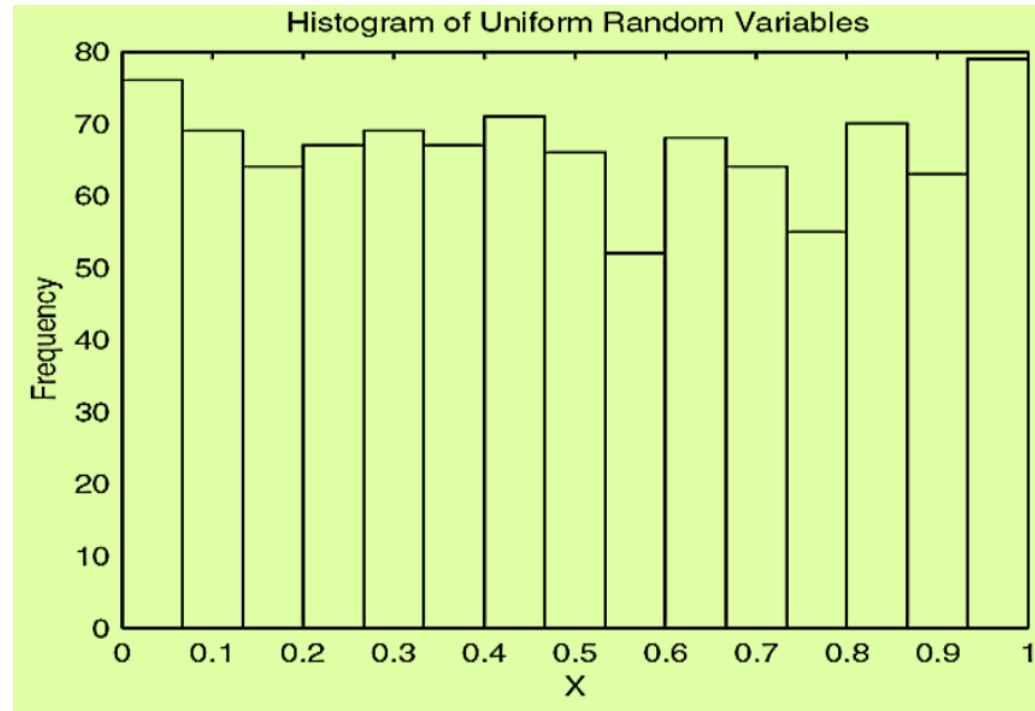
```
Seeds = [ 1, ...
1973272912, 281629770, 20006270,1280689831,2096730329,1933576050,...
913566091, 246780520,1363774876, 604901985,1511192140,1259851944,...
824064364, 150493284, 242708531, 75253171,1964472944,1202299975,...
233217322,1911216000, 726370533, 403498145, 993232223,1103205531,...
762430696,1922803170,1385516923, 76271663, 413682397, 726466604,...
336157058,1432650381,1120463904, 595778810, 877722890,1046574445,...
68911991,2088367019, 748545416, 622401386,2122378830, 640690903,...
1774806513,2132545692,2079249579, 78130110, 852776735,1187867272,...
1351423507,1645973084,1997049139, 922510944,2045512870, 898585771,...
243649545,1004818771, 773686062, 403188473, 372279877,1901633463,...
498067494,2087759558, 493157915, 597104727,1530940798,1814496276,...
536444882,1663153658, 855503735, 67784357,1432404475, 619691088,...
119025595, 880802310, 176192644,1116780070, 277854671,1366580350,...
1142483975,2026948561,1053920743, 786262391,1792203830,1494667770,...
1923011392,1433700034,1244184613,1147297105, 539712780,1545929719,...
190641742,1645390429, 264907697, 620389253,1502074852, 927711160,...
364849192,2049576050, 638580085, 547070247 ];
```

# In Matlab

```
% Obtain a vector of uniform random variables in (0,1) .
x = rand(1,1000);
% Do a histogram to plot.
% First get the height of the bars.
[N,X] = hist(x,15);
% Use the bar function to plot.
bar(X,N,1,'w')
title('Histogram of Uniform Random Variables')
xlabel('X')
ylabel('Frequency')
```

## Notes:

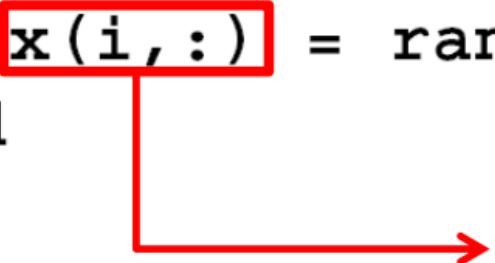
- The function *rand* with no arguments returns a single instance of the random variable *U*.
- To get an array *m* $\times$ *n* of uniform variates, you can use the syntax **rand(m,n)**.
- If you use **rand(n)**, then you get an *n* $\times$ *n* matrix.





- The seed or the state of the generator is reset to the default when Matlab starts up, so the same sequences of random variables are generated whenever you start Matlab.
- If you call the function using **rand('state',0)**, then MATLAB resets the generator to the initial state.
- If you want to specify another state, then use the syntax **rand('state',j)** to set the generator to the  $j$ -th state.
- You can obtain the current state using **S = rand('state')**, where **S** is a 35 element vector. To reset the state to this one, use **rand('state',S)**.

```
% Generate 3 random samples of size 5.  
x = zeros(3,5);    % Allocate the memory.  
for i = 1:3  
    rand('state',i) % set the state  
    x(i,:) = rand(1,5);  
end
```



0.9528	0.7041	0.9539	0.5982	0.8407
0.8752	0.3179	0.2732	0.6765	0.0712
0.5162	0.2252	0.1837	0.2163	0.4272

# Lab Exercise 1 (50%)

## Lab Exercise CH2-1:

- 2-1.1 Using MATLAB to redo  $p(x|\omega_1)$  and  $p(x|\omega_2)$  in Example 1.
- 2-1.2 Find  $P(\omega_1|x)$  and  $P(\omega_2|x)$  for all  $x$  and draw the figure as left using MATLAB.

## Lab Exercise CH2-2

Two exclusive categories  $\omega_1, \omega_2$ :

$P(\omega_1) = 2/3, P(\omega_2) = 1/3, P(x|\omega_1) \Rightarrow N(2, 0.5)$  (normal distribution),

$P(x|\omega_2) \Rightarrow N(1.5, 0.2)$ . Select the optimal decision using MATLAB.

## Lab Exercise CH2-3

Feature space  $\Omega = \{\omega_1, \omega_2\}, P(\omega_1) = 2/3, P(\omega_2) = 1/3, P(x|\omega_1) \Rightarrow N(2, 0.5),$

$P(x|\omega_2) \Rightarrow N(1.5, 0.2)$ .  $\lambda = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ .

Select the optimal decision using MATLAB.

$$N(\mu, \sigma) = \frac{1}{\sqrt{2\pi}\sigma} e^{-1/2((x-\mu)/\sigma)^2}$$

# Lab Exercise 1 (50%)

## Random number generation

- (a) Generate three streams (1D, 2D and 3D) of random numbers with 1,000 samples, you may use the Matlab command `rand`.
- (b) Visualize the generated samples, you may use a scatter plot.
- (c) Compute the histogram of the three streams, then normalize them to become a probability density function (pdf).
- (d) Visualize the pdf's of the three streams. Are the samples uniformly distributed? Do the pdf's represent a standard uniform distributions? Comment.

# OpenCV

- Languages for OpenCV – C, C++, Python, MATLAB, Java
- Operating systems – Windows, Linux, Mac OS, iOS, Android
- Cross platforms – OpenCL, CUDA, OpenGL, VTK, ITK etc. (compatibility is needed or overcome)
- Started from 2000 to now – including almost everything such as CUDA, VTK 3D, Computer Graphics, 2D and 3D calibration, audio and video etc.
- Web sites for questions – [www.stackoverflow.com](http://www.stackoverflow.com); [www.google.com](http://www.google.com); or [www.baidu.com](http://www.baidu.com)

# OpenCV Structure

- Lib indicates the corresponding operations, computing, analysis algorithm
- Closing with d indicates debug version, otherwise release version
  - Core – main module (basic structures, operations, drawing, clustering etc.)
  - Imgproc – image processing module
  - Video – video analysis and analytics module
  - Photo – image computing, restoration, noise reduction
  - Feature2d – 2D feature module
  - Calib3d – camera positioning and 3D reconstruction module
  - Objdetect – object detection module
  - Ml – machine learning module
  - Highgui – high level graphic interface module
  - Gpu – graphic processing unit module (for fast computing)

# OpenCV header files (interface)

- `#ifndef __OPENCV_ALL_HPP__`
- `#define __OPENCV_ALL_HPP__`
- `#include "opencv2/core/core_c.h"`
- `#include "opencv2/core/core.hpp"`
- `#include "opencv2/flann/miniflann.hpp"`
- `#include "opencv2/imgproc/imgproc_c.h"`
- `#include "opencv2/imgproc/imgproc.hpp"`
- `#include "opencv2/photo/photo.hpp"`
- `#include "opencv2/video/video.hpp"`
- `#include "opencv2/features2d/features2d.hpp"`
- `#include "opencv2/objdetect/objdetect.hpp"`
- `#include "opencv2/calib3d/calib3d.hpp"`
- `#include "opencv2/ml/ml.hpp"`
- `#include "opencv2/highgui/highgui_c.h"`
- `#include "opencv2/highgui/highgui.hpp"`
- `#include "opencv2/contrib/contrib.hpp"`
- `#endif`

Or use using namespace cv;

# Installation OpenCV 3.1.0 (VS 2013)

- Download opencv-3.1.0.exe (x64/x86) from the official web site <http://sourceforge.net/projects/opencvlibrary/files/opencv-win/> and extract it to Program Files\opencv310
- Set environment variable (if you have administrator right), otherwise copy all dll files into run time directory (Debug/Release)
  - Press right key on your computer, select
  - Advanced System Setting -> Environment variable -> Create
    - Fill in Path
    - D:\Program Files\opencv310\opencv\build\x64\vc12\bin
- Visual Studio configuration
  - Project->Properties, select Configuration Properties ->C/C++->General
    - Additional Include Directories: xxx\build\include
  - Project->Properties, select Configuration Properties ->Linker -> General
    - Additional Library Directories: xxxx\x64\vc12
  - Project->Properties, select Configuration Properties ->Linker -> Input
    - Copy all opencv libraries into Additional Dependencies such as opencv\_core310d.lib

```
#include "opencv2/imgproc/imgproc.hpp"
#include "opencv2/highgui/highgui.hpp"
// 使用标准的cv库
using namespace cv;

int main( )
{
    // 读取源图像并转化为灰度图像
    Mat srcImage = cv::imread("../images\\flower.jpg");
    // 判断文件是否读入正确
    if( !srcImage.data )
        return 1;
    // 图像显示
    imshow("srcImage", srcImage);
    // 等待键盘键入
    waitKey(0);
    return 0;
}
```