

Static Noncooperative Infinite Games

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Review - Matrix Games

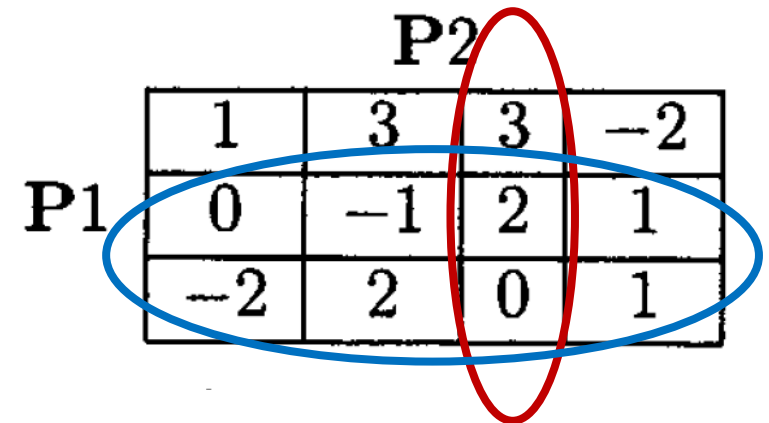
- $A = \{a_{ij}\}$, each entry is an outcome
- i th row: strategies for P1, j th column: strategies for P2
- Target of P1: find i^* th row to minimize the outcomes

$$\bar{V}(A) \triangleq \max_j a_{i^*j} \leq \max_j a_{ij}, \quad i = 1, \dots, m,$$

- $\bar{V}(A)$ -- loss ceiling of P1 (security level for his losses)
- row i^* -- security strategy for P1
- Target of P2: find j^* th column to maximize the outcomes

$$\underline{V}(A) \triangleq \min_i a_{ij^*} \geq \min_i a_{ij}, \quad j = 1, \dots, n.$$

- $\underline{V}(A)$ -- gain-floor of P2 (security level for his gains)
- column j^* -- security strategy for P2



The table represents a matrix game with Player 1 (P1) as rows and Player 2 (P2) as columns. The entries are outcomes. A blue oval highlights the first two rows, representing P1's security strategy. A red oval highlights the third column, representing P2's security strategy.

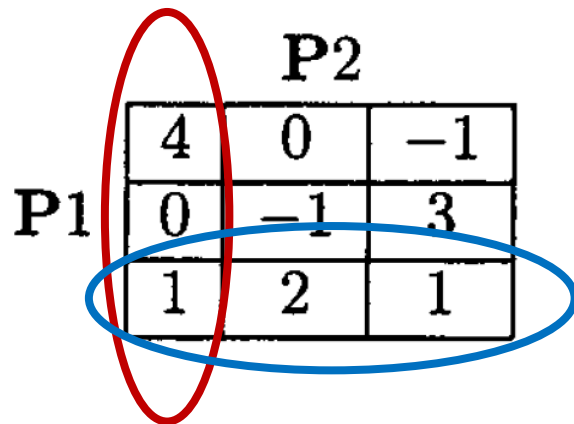
		P2			
		1	3	3	-2
P1		0	-1	2	1
		-2	2	0	1

Review - Saddle-point equilibrium

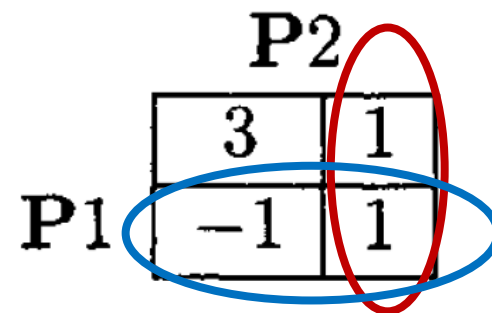
- If the pair of inequalities:

$$a_{i^*j} \leq a_{i^*j^*} \leq a_{ij^*}$$

for all i and j , then the strategies {row i^* , column j^* } are said to constitute a **saddle-point equilibrium**. And the matrix game is said to have a **saddle point** in pure strategies.



	P2		
P1	4	0	-1
	0	-1	3
	1	2	1



	P2	
P1	3	1
	-1	1

Review - Mixed Strategies

- Key idea: enlarge the strategy spaces, allow the players to base their decisions on the outcome of random events.

E.g. $\{row1, row2, row3\}$ —pure strategies space

$\{y_1, y_2, y_3\}$ —a mixed strategy, where $y_1 + y_2 + y_3 = 1$

$Y = \{(y_1, y_2, y_3), (y'_1, y'_2, y'_3) \dots\}$ —the mixed strategy space of P1, comprised of all such probability distributions.

		P2			
		1	3	3	-2
P1	0	0	-1	2	1
	-2	-2	2	0	1

Review - Mixed Strategies

- $\bar{V}_m(A) = \min_Y \max_Z y'Az$
- $\underline{V}_m(A) = \max_Z \min_Y y'Az$

- **The minimax theorem:**

- In any matrix game A , the average security levels of the players in mixed strategies coincide, that is:

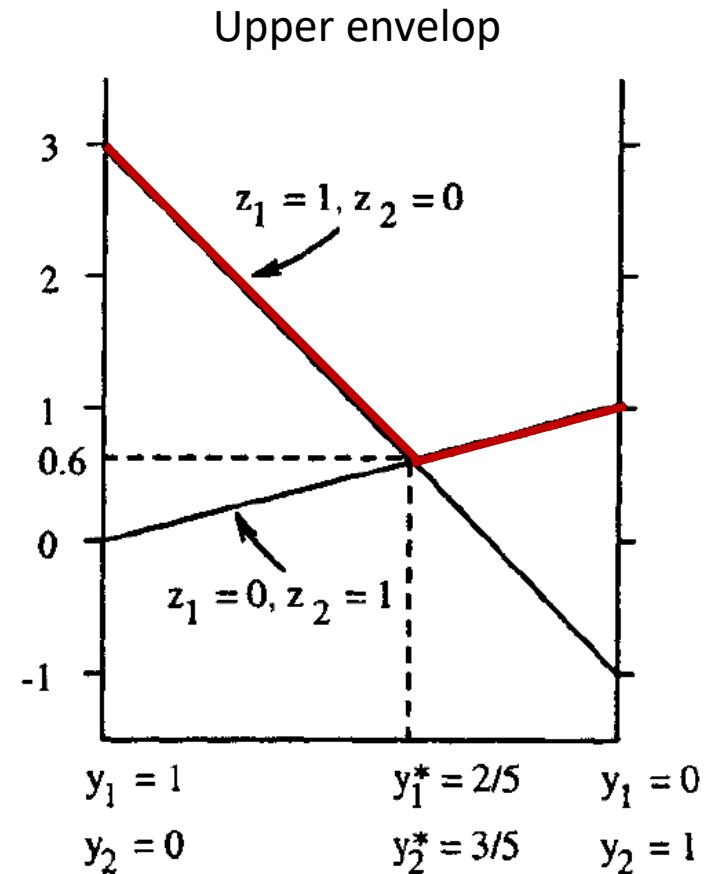
$$\bar{V}_m(A) = \underline{V}_m(A)$$

- We have thus seen that, if the players are allowed to use mixed strategies, **matrix games always admit a saddle-point solution** which, thereby, manifests itself as **the only reasonable equilibrium solution** in zero-sum two-person games of that type

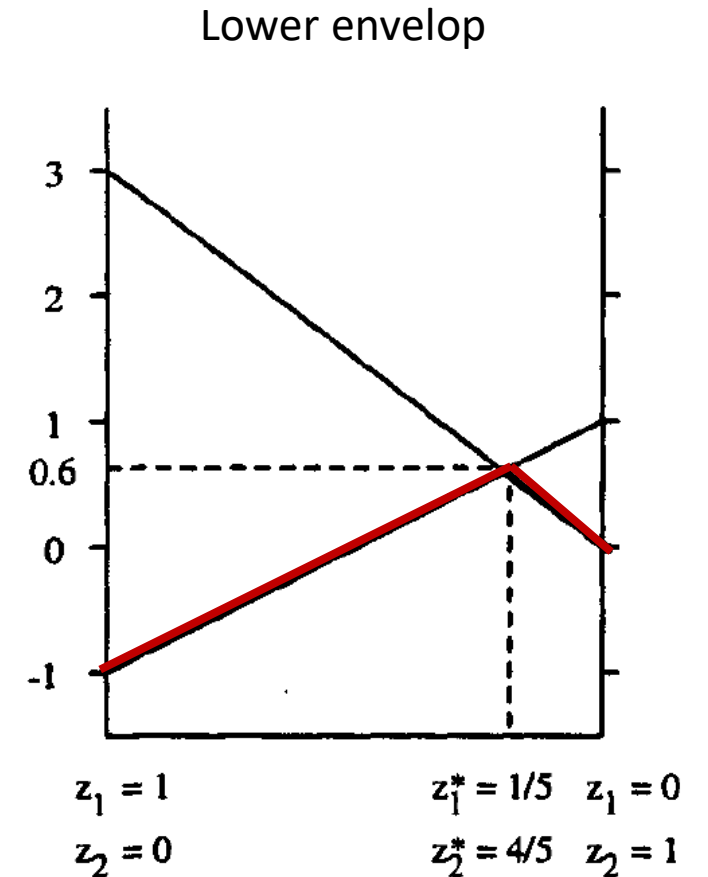
Review - Mixed Equilibrium Strategies

- Graphical solution for (2×2) matrix games

	P2	
P1	3	0
	-1	1



Mixed security strategy of P1



Mixed security strategy of P2

Review - Nash Equilibrium

- A pair of strategies {row i^* , column j^* } is said to constitute a **noncooperative (Nash) equilibrium** solution to a bimatrix game ($A = \{a_{ij}\}, B = \{b_{ij}\}$) if the following pair of inequalities is satisfied for all $i = 1, \dots, m$ and all $j = 1, \dots, n$:

$$\begin{aligned}a_{i^*j^*} &\leq a_{ij^*} \\ b_{i^*j^*} &\leq b_{i^*j}\end{aligned}$$

- Furthermore, the pair $(a_{i^*j^*}, b_{i^*j^*})$ is known as a noncooperative (Nash) equilibrium outcome of the bimatrix game.
- Example: (1,2) and (-1,0) are the equilibrium outcomes.

P2

	1		0
	2		-1

P1

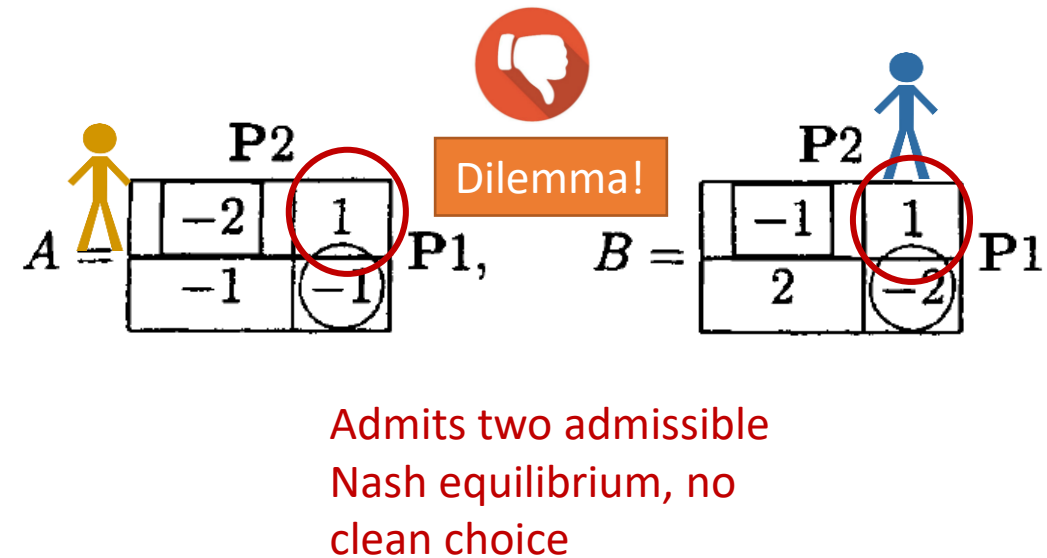
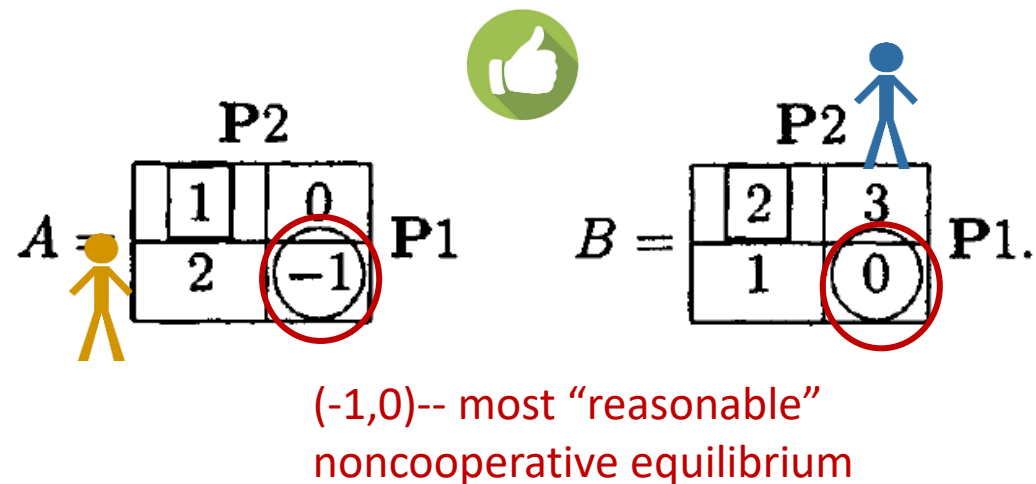
P2

	2		3
	1		0

P1.

Review - Nash Equilibrium

- If a bimatrix game admits more than one admissible Nash equilibrium solution, then the equilibrium outcome of the game becomes rather ill-define.



Review - Stackelberg Equilibrium

- Hierarchical (Stackelberg) equilibrium

A =

<div style="display: flex; flex-direction: column; align-items: center;"> <div style="background-color: yellow; padding: 2px 5px;">1</div> <div style="background-color: yellow; padding: 2px 5px;">2</div> <div style="background-color: yellow; padding: 2px 5px;">3</div> </div>	<i>L</i>	0^{S_1}	2	$3/2^{S_2}$	P1,
	<i>M</i>	1	1^N	3	
	<i>R</i>	-1	2	2	
		<i>L</i>	<i>M</i>	<i>R</i>	

P2

B =

<div style="display: flex; flex-direction: column; align-items: center;"> <div style="background-color: yellow; padding: 2px 5px;">1</div> <div style="background-color: yellow; padding: 2px 5px;">2</div> <div style="background-color: yellow; padding: 2px 5px;">3</div> </div>	<i>L</i>	-1^{S_1}	1	$-2/3^{S_2}$	P1.
	<i>M</i>	2	0^N	1	
	<i>R</i>	0	1	$-1/2$	
		<i>L</i>	<i>M</i>	<i>R</i>	

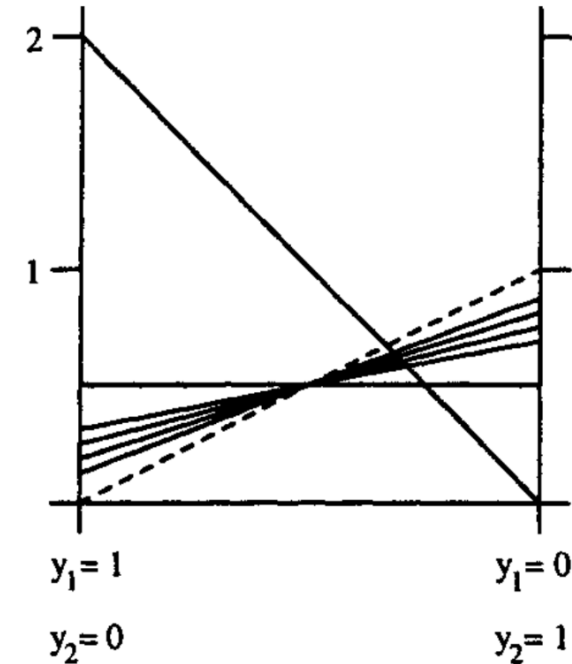
P2

- ➔
- P1 – leader, P2 – follower:
 - (L,L) is the Stackelberg solution, (0,-1) is the Stackelberg outcome with P1 as the leader.
 - P2 – leader, P1 – follower:
 - (L,R) is the Stackelberg solution, (3/2,-2/3) is the Stackelberg outcome with P1 as the leader.

Noncooperative Infinite Games

- **Infinite:** at least one of the players has at his disposal an infinite number of alternatives to choose from.

		P2				
P1	2	$1/2$	$1/3$	$1/4$	$1/5$
	0	$1/2$	$2/3$	$3/4$	$4/5$

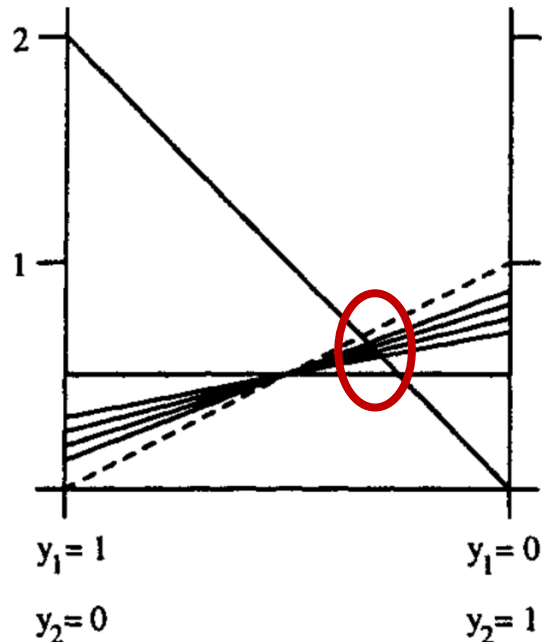


ϵ Equilibrium Solutions

Definition 4.2 For a given $\epsilon \geq 0$, the pair $\{u_\epsilon^{1*}, u_\epsilon^{2*}\} \in U^1 \times U^2$ is called an ϵ saddle point if

$$J(u_\epsilon^{1*}, u^2) - \epsilon \leq J(u_\epsilon^{1*}, u_\epsilon^{2*}) \leq J(u^1, u_\epsilon^{2*}) + \epsilon$$

for all $\{u^1, u^2\} \in U^1 \times U^2$. For $\epsilon = 0$ one simply speaks of a “saddle point”.

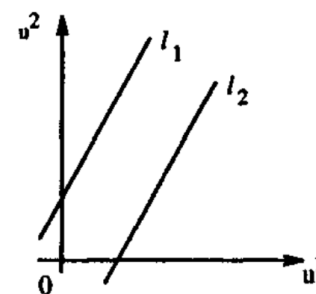
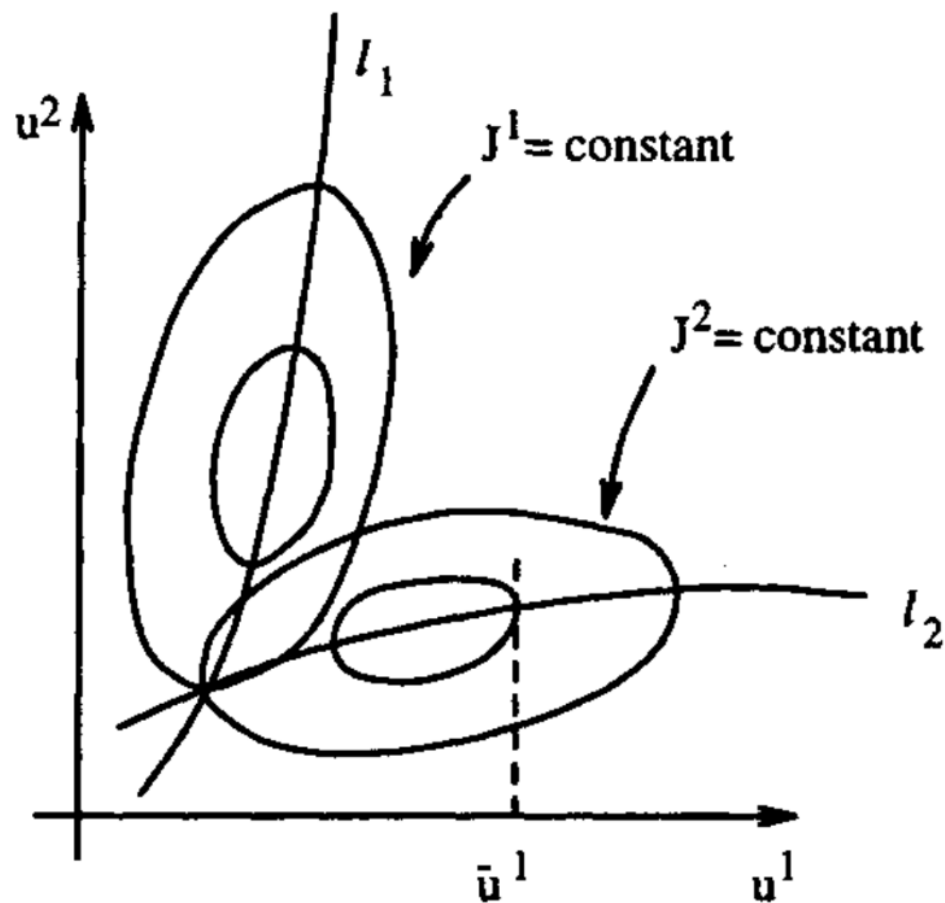


		P2				
P1	2	1/2	1/3	1/4	1/5
	0	1/2	2/3	3/4	4/5

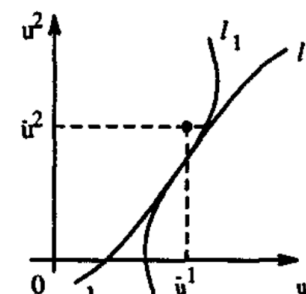
Reaction curves

Definition 4.3 In an N -person nonzero-sum game, let the minimum of the cost function of **P1**, $J^1(u^1, \dots, u^N)$, with respect to $u^1 \in U^1$ be attained for each $u_{-1} \in U_{-1}$, where $u_{-1} \triangleq \{u^2, \dots, u^N\}$ and $U_{-1} \triangleq U^2 \times \dots \times U^N$. Then, the set $R^1(u_{-1}) \subset U^1$ defined by

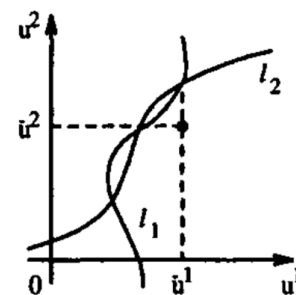
$$R^1(u_{-1}) = \{\xi \in U^1 : J^1(\xi, u_{-1}) \leq J^1(u^1, u_{-1}), \quad \forall u^1 \in U^1\}$$



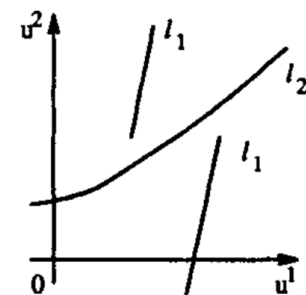
(a)



(b)



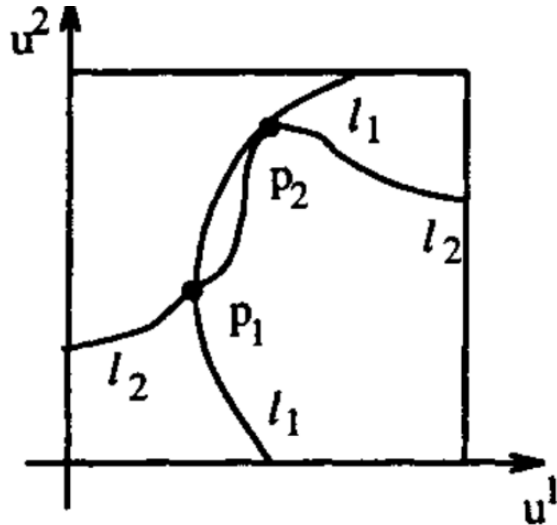
(c)



(d)

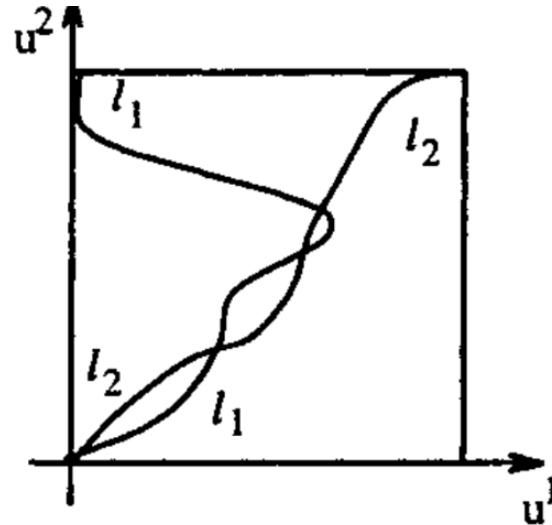
Robust Nash Solution

Definition 4.4 Given two connected curves $u^2 = l_2(u^1)$ and $u^1 = l_1(u^2)$ on the square, denote their weak δ -neighborhoods by N_δ^2 and N_δ^1 , respectively.²⁶ Then, a point P of intersection of these two curves is said to be robust if, given $\epsilon > 0$, there exists a $\delta_0 > 0$ so that every ordered pair selected from $N_{\delta_0}^2$ and $N_{\delta_0}^1$ has an intersection in an ϵ -neighborhood of P .



(a)

P1 is robust
P2 is not robust

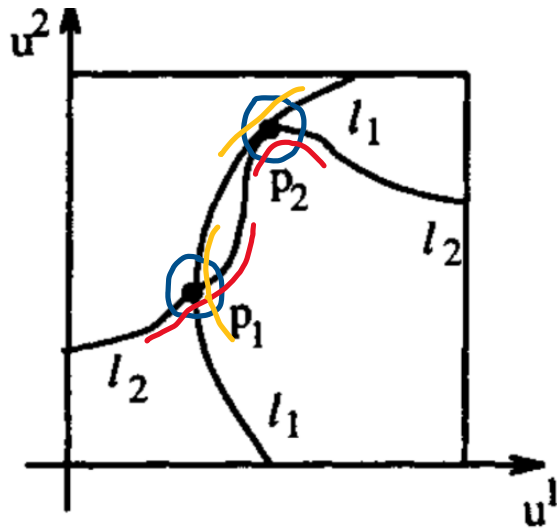


(b)

All points are robust

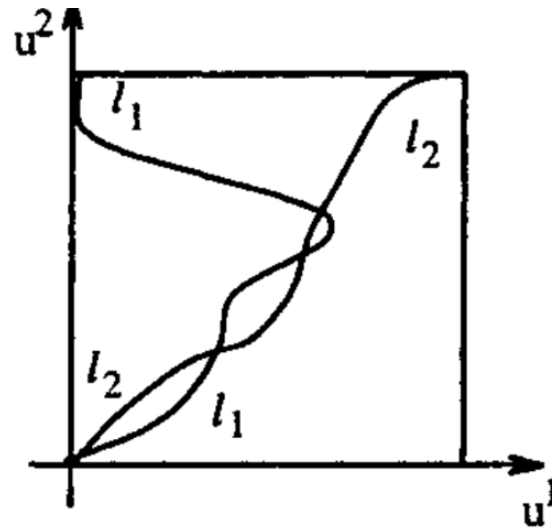
Robust Nash Solution

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(a)

P1 is robust
P2 is not robust



(b)

All points are robust

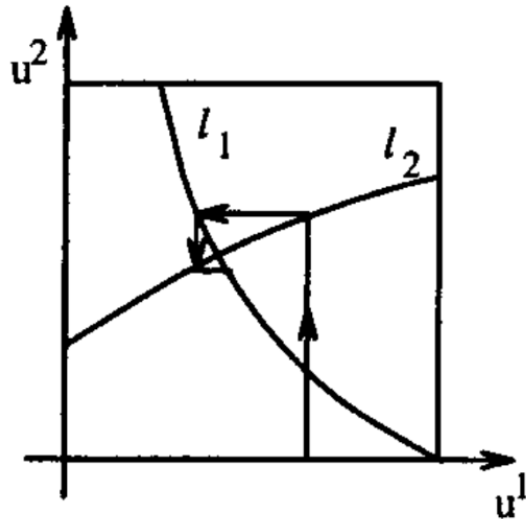
Stable Nash Solution

Definition 4.5 A Nash equilibrium u^{i*} , $i \in \mathbf{N}$, is (globally) stable with respect to an adjustment scheme \mathcal{S} if it can be obtained as the limit of the iteration:

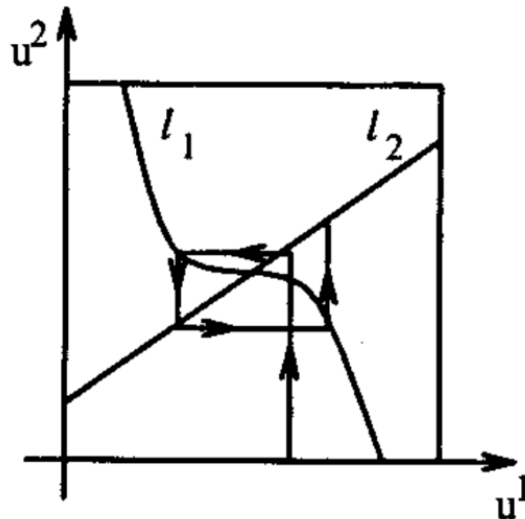
$$u^{i*} = \lim_{k \rightarrow \infty} u^{i(k)}, \quad (4.3)$$

$$u^{i(k+1)} = \arg \min_{u^i \in U^i} J^i(u_{-i}^{(\mathcal{S}_k)}, u^i), \quad u^{i(0)} \in U^i, \quad i \in \mathbf{N}, \quad (4.4)$$

where the superscript \mathcal{S}_k indicates that the precise choice of $u_{-i}^{(\mathcal{S}_k)}$ depends on the readjustment scheme selected.



(a)



(b)



Thanks
Happy Halloween
Hope to meet you soon

