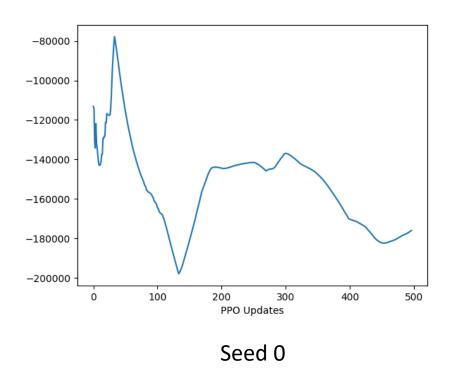
# Meeting 06/20/2020

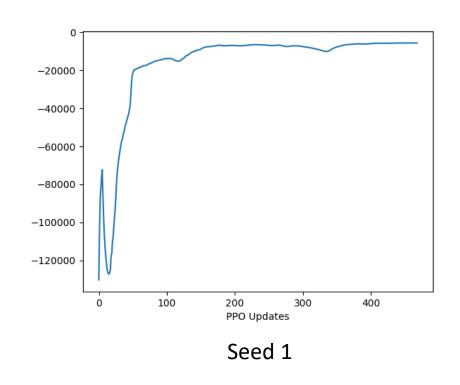
Shuo Zhang

# Adaptive Hand PPO: Goal Loc 7

With terminal + Control reward coefficient 1

When estimate generalized advantage, only take entire episodes (e.g. 2000 steps or 4000 steps)



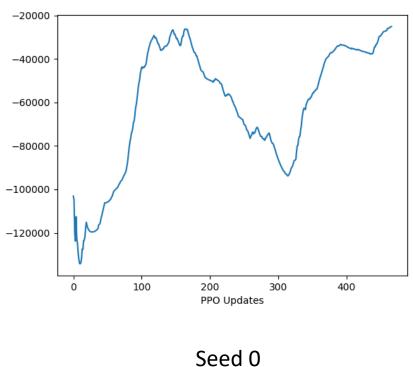


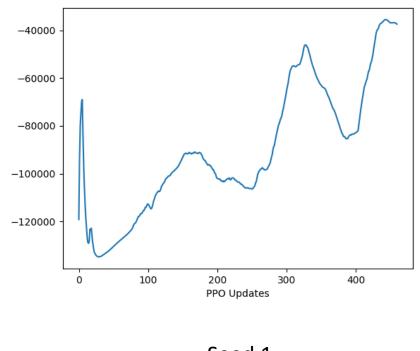
Average return over 100-episodes

# Adaptive Hand PPO: Goal Loc 8

With terminal + Control reward coefficient 1

When estimate generalized advantage, only take entire episodes (e.g. 2000 steps or 4000 steps)



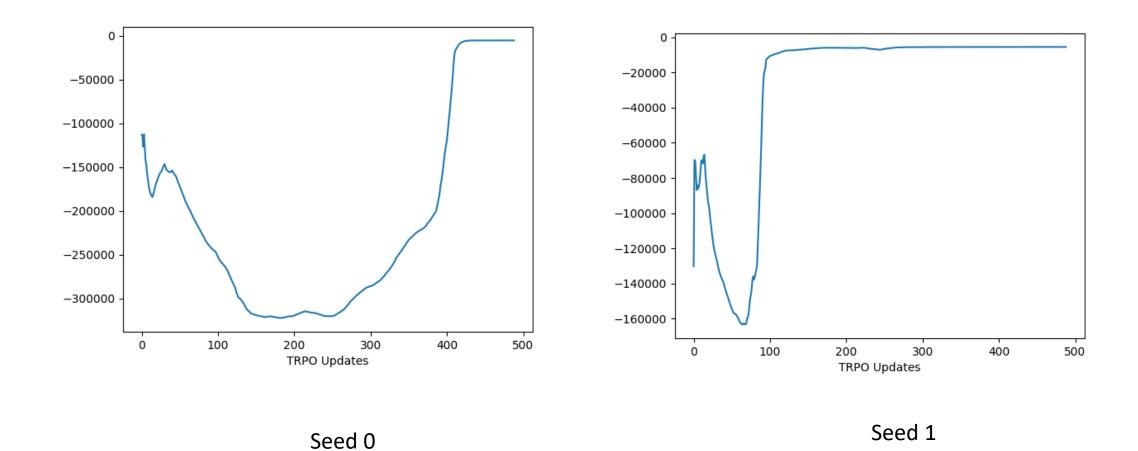


Seed 1

Average return over 100-episodes

# Adaptive Hand TRPO: Goal Loc 7

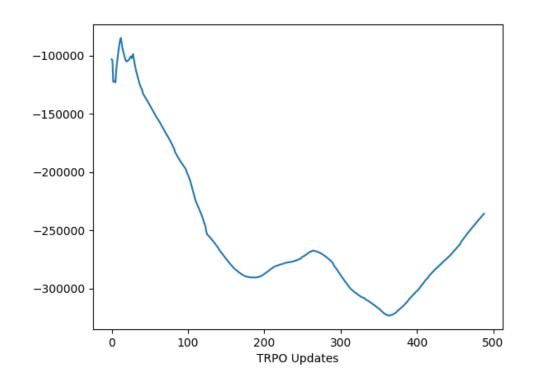
With terminal + Control reward coefficient 1

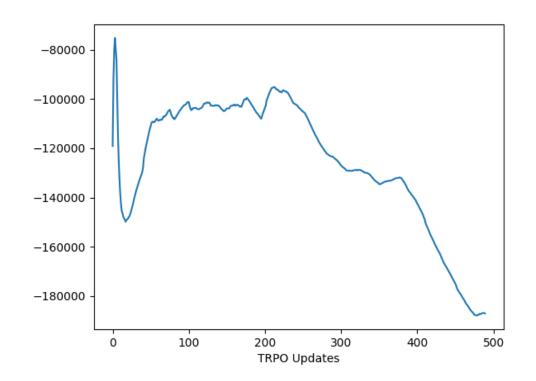


Average return over 100-episodes

# Adaptive Hand TRPO: Goal Loc 8

With terminal + Control reward coefficient 1





Seed 0 Seed 1

#### Average return over 100-episodes