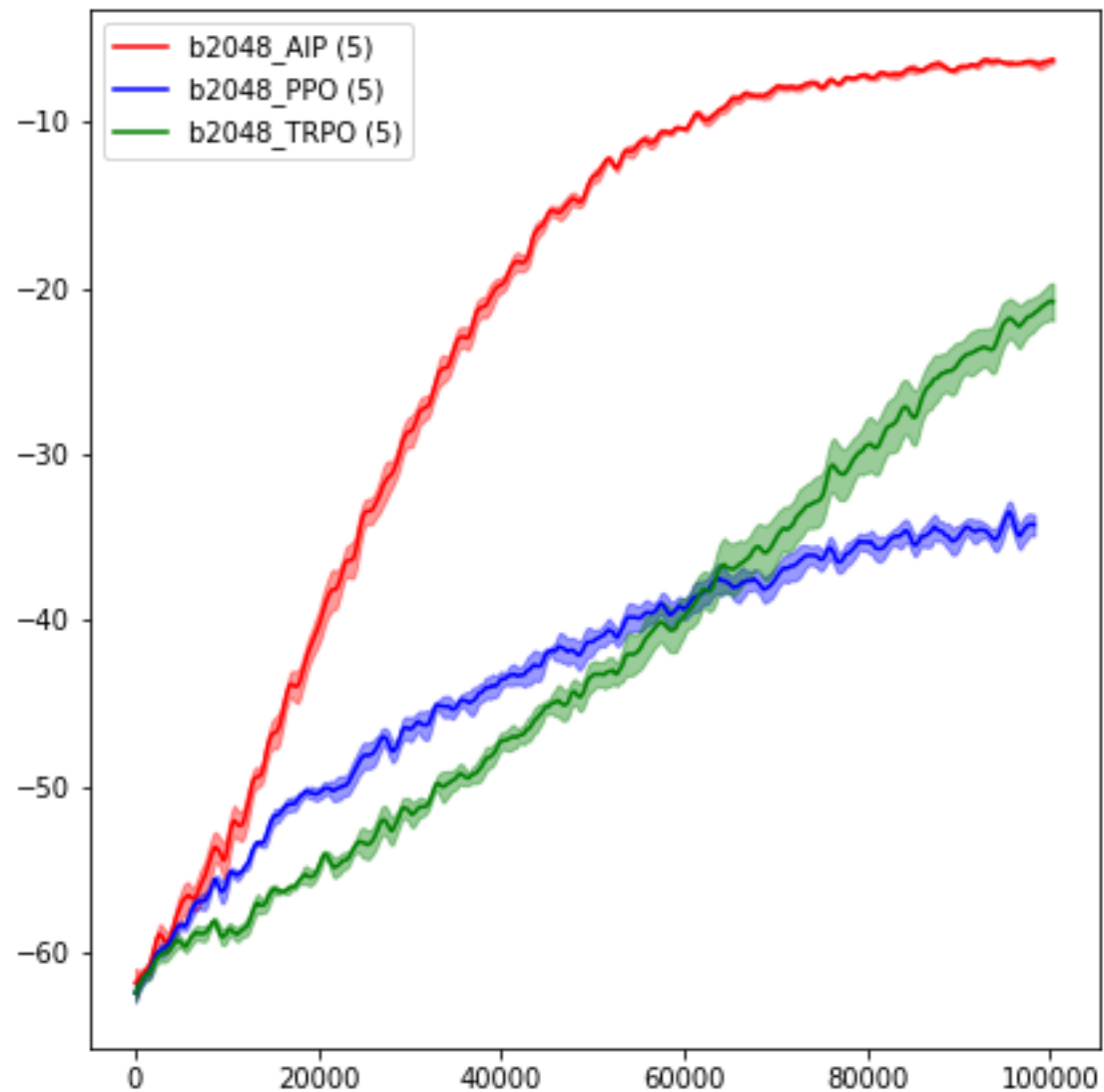


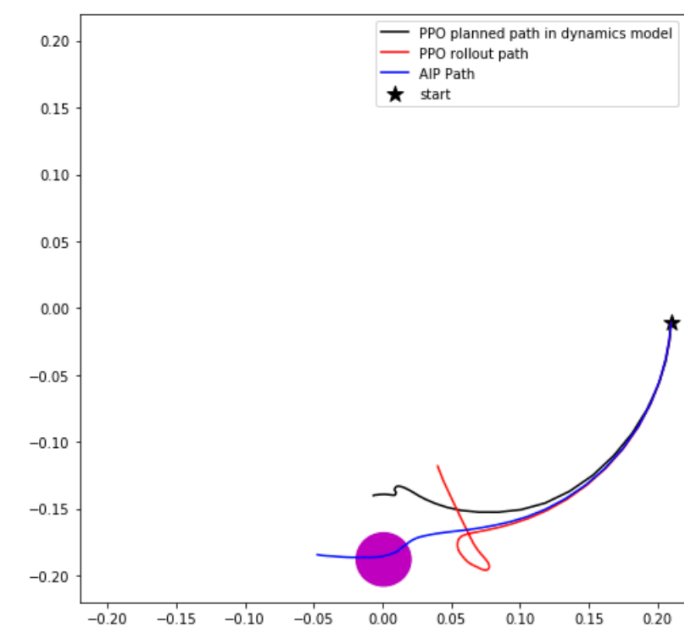
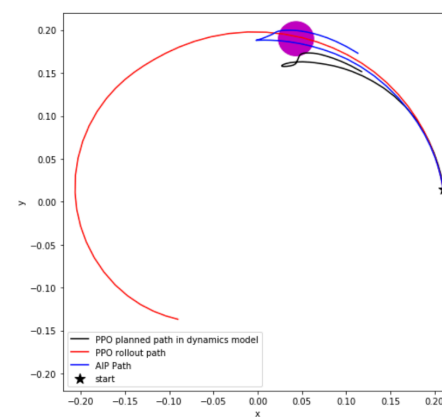
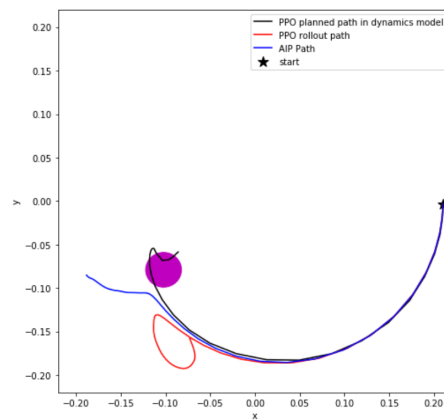
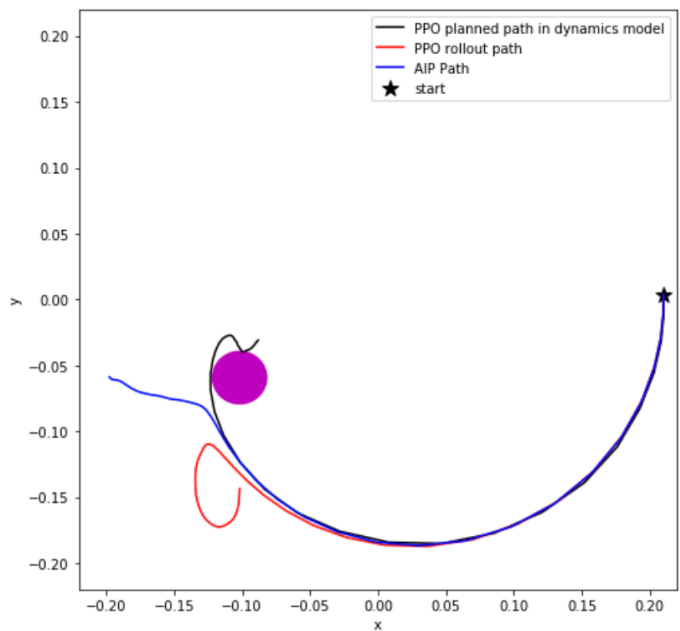
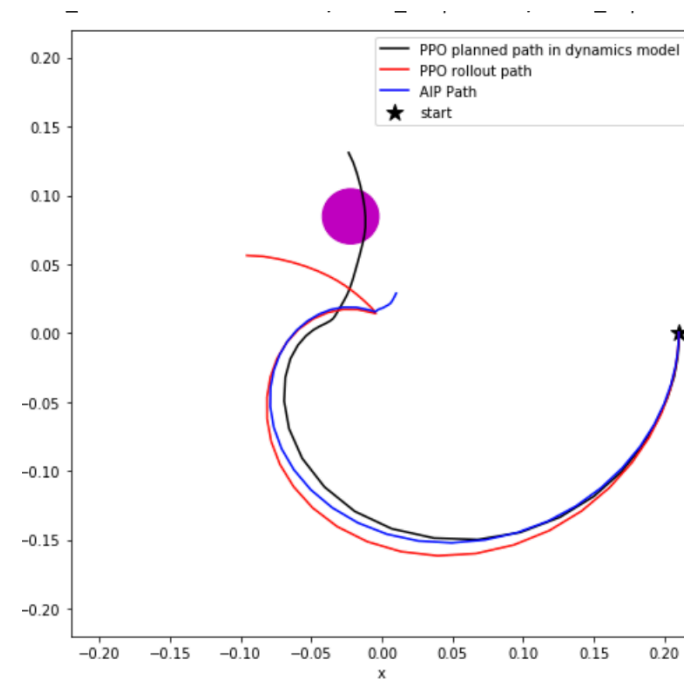
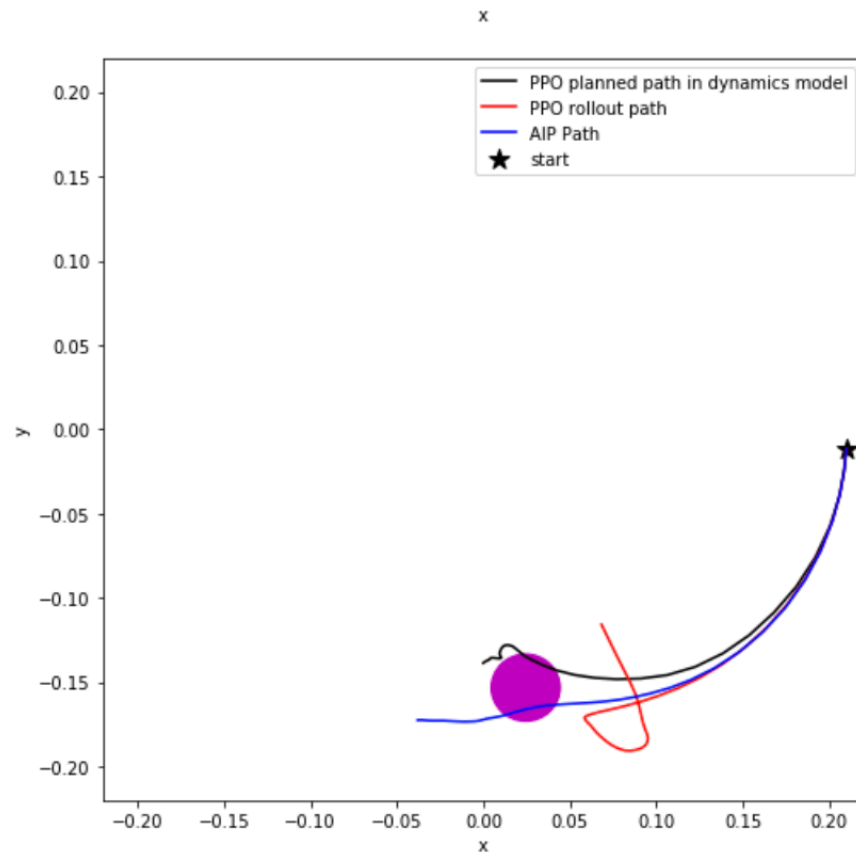
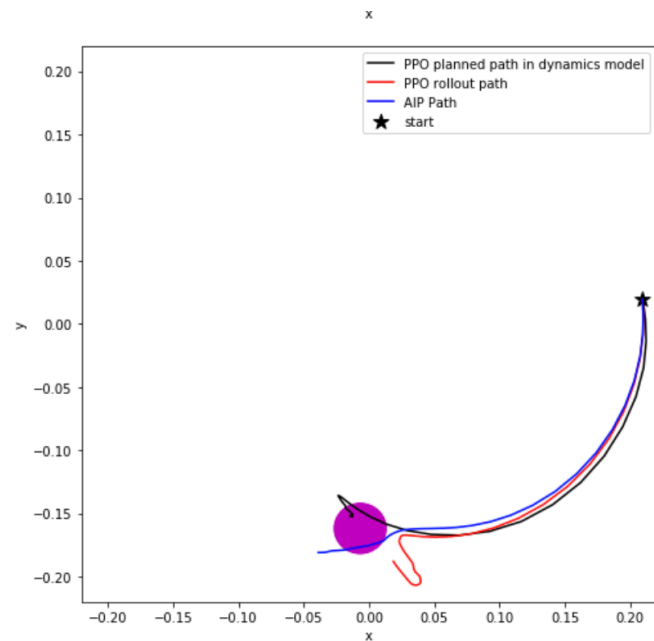
Meeting

09/30/2020

Shuo Zhang

AIP (Mujoco)





Questions and Plans

- Next experiments: Gazebo Hand
- For real hand, no automatic restart?
- For Acrobot, sparse reward -1, adapt r_{diff} in terms of one-step $Q=r+V(s')$?