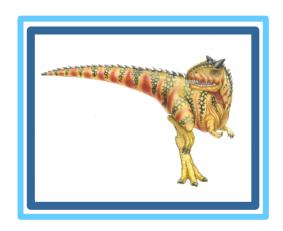
# **Chapter 6: Synchronization Tools**

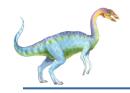




# **Chapter 6: Synchronization Tools**

Background
The Critical-Section Problem
Peterson's Solution
Synchronization Hardware
Mutex Locks
Semaphores





# **Objectives**

To present the concept of process synchronization.

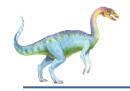
To introduce the critical-section problem, whose solutions can be used to ensure the consistency of shared data

To present both software and hardware solutions of the critical-section problem

To examine several classical process-synchronization problems

To explore several tools that are used to solve process synchronization problems





## **Background**

Cooperating process - Processes that can affect or get affected by other processes executing in the system.

Cooperating processes can be:

Directly sharing a logical address space(both code and data)

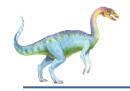
Allowed to share data only through files or messages

Problem: Concurrent access to shared data may result in data

inconsistency

Solution: Process synchronization





# **Background**

Concurrent access to shared data may result in data inconsistency

Maintaining data consistency requires mechanisms to ensure the orderly execution of cooperating processes

Eg: Producer consumer problem

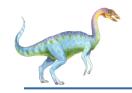
Solution: with the use of shared memory

Buffer: the region in the shared memory that both producer and consumer use

The producer produce one item while the consumer is consuming another item

The producer and consumer should be synchronized





# **Background**

Buffer: the region in the shared memory that both producer and consumer use

Two types of buffer:

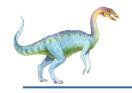
Unbounded — No limit on the size of the buffer. The producer can always produce items, consumer may need to wait for new items

Bounded — Fixed buffer size. Consumer must wait when buffer is empty. Producer must wait when the buffer is full

Illustration of the problem:

Suppose that we wanted to provide a solution to the consumerproducer problem that fills **all** the buffers. We can do so by having an integer **counter** that keeps track of the number of full buffers. Initially, **counter** is set to 0. It is incremented by the producer after it produces a new buffer and is decremented by the consumer after it consumes a buffer.





#### **Race Condition**

counter++ could be implemented as

```
register1 = counter
register1 = register1 + 1
counter = register1
```

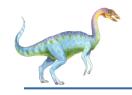
**counter--** could be implemented as

```
register2 = counter
register2 = register2 - 1
counter = register2
```

Consider this execution interleaving with "count = 5" initially:

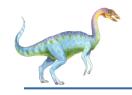
```
S0: producer execute register1 = counter {register1 = 5}
S1: producer execute register1 = register1 + 1 {register1 = 6}
S2: consumer execute register2 = counter {register2 = 5}
S3: consumer execute register2 = register2 - 1 {register2 = 4}
S4: producer execute counter = register1 {counter = 6}
S5: consumer execute counter = register2
```

When several processes access and manipulate the data concurrently and the outcome of the execution depends on the particular order in which the access takes place — Race Condition



#### **Producer**





#### Consumer

```
while (true) {
    while (counter == 0)
        ; /* do nothing */
    next_consumed = buffer[out];
    out = (out + 1) % BUFFER_SIZE;
    counter--;
    /* consume the item in next consumed */
}
```





#### **Critical Section Problem**

Consider system of n processes  $\{p_0, p_1, \dots p_{n-1}\}$ 

Each process has critical section segment of code

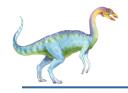
Process may be changing common variables, updating table, writing file, etc

When one process in critical section, no other may be in its critical section

Critical section problem is to design protocol to solve this

Each process must ask permission to enter critical section in entry section, may follow critical section with exit section, then remainder section





## **Critical Section**

#### General structure of process $P_i$

```
do {
     entry section
     critical section

     exit section

remainder section
} while (true);
```



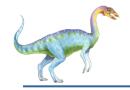


### **Solution to Critical-Section Problem**

- 1. Mutual Exclusion If process  $P_i$  is executing in its critical section, then no other processes can be executing in their critical sections
- 2. Progress If no process is executing in its critical section and there exist some processes that wish to enter their critical section, then the selection of the processes that will enter the critical section next cannot be postponed indefinitely
- 3. **Bounded Waiting** A bound must exist on the number of times that other processes are allowed to enter their critical sections after a process has made a request to enter its critical section and before that request is granted

https://www.youtube.com/watch?v=6x\_XMDCMyAk.





#### **Peterson's Solution**

Good algorithmic description of solving the problem

Two process solution — Peterson's solution is restricted to two processes that alternate the execution between the critical section and remainder section.

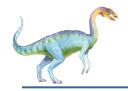
The two processes share two variables:

```
int turn;
Boolean flag[2]
```

The variable turn indicates whose turn it is to enter the critical section

The flag array is used to indicate if a process is ready to enter the critical section. flag[i] = true implies that process  $P_i$  is ready!



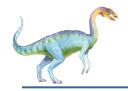


# Algorithm for Process Pi

```
do {
    flag[i] = true;
    turn = j;
    while (flag[j] && turn = = j);
        critical section

    flag[i] = false;
        remainder section
} while (true);
```





# **Peterson's Solution (Cont.)**

Provable that the three CS requirement are met:

1. Mutual exclusion is preserved

```
P<sub>i</sub> enters CS only if:
   either flag[j] = false or turn = i
```

- 2. Progress requirement is satisfied
- 3. Bounded-waiting requirement is met





# **Synchronization Hardware**

Many systems provide hardware support for implementing the critical section code.

All solutions below based on idea of **locking**Protecting critical regions via locks

Uniprocessors – could disable interrupts

Currently running code would execute without preemption





# **Solution to Critical-section Problem Using Locks**



#### Quiz

- 1. What are the two types of processes?
- 2. Which type of processes are in need of synchronization methods?
- 3. Why do we need process synchronization?
- 4. What are the three issues in producer consumer problem?
- 5. What are the two types of buffer?
- 6. What is a critical section?
- 7. What are the 4 sections in a process's structure?
- 8. What are the three criteria to avoid critical section problem?
- 9. What are the counter operations in producer consumer problem?