

Exact characterization for subdifferentials of a special optimal value function

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Abstract For a closed set S and a bounded closed convex set U in a real normed vector space, we give exact subdifferential formulas of an optimal value function $\Pi_{S|U}$ whose definition is based on the Minkowski function of U . $\Pi_{S|U}$ covers distance function and indicator function as special cases. The main contribution is dropping two important assumptions of some main results in the literature.

Keywords Subdifferential · Normal cone · Optimal value function

1 Introduction

Let X be a real normed vector space and U be a bounded closed convex subset of X . The Minkowski function ρ_U of U is defined by

$$\rho_U(u) := \inf\{t > 0 : t^{-1}u \in U\}, \quad \text{for all } u \in X.$$

Let S be a closed subset of X . The function $\Pi_{S|U}$ is defined by

$$\Pi_{S|U}(x) := \inf_{s \in S} \rho_U(s - x), \quad \text{for all } x \in X. \quad (1.1)$$

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The definitions yield directly the following equality

$$\mathbb{I}_{S|U}(x) = \inf \{t > 0 : S \cap (x + tU) \neq \emptyset\}. \quad (1.2)$$

$\mathbb{I}_{S|U}$ is a minimal time function of a control system with constant dynamics; see [3]. In view of Proposition 2.1 of [7] and (1.2), one has for point $x \notin S$,

$$\mathbb{I}_{S|U}(x) = \inf \{t \geq 0 : S \cap (x + tU) \neq \emptyset\}. \quad (1.3)$$

When U is the closed unit ball, $\rho_U(x) = \|x\|$, and hence $\mathbb{I}_{S|U}(x)$ reduces to the usual distance function

$$\mathbf{d}_S(x) := \inf_{s \in S} \|s - x\|, \quad \text{for all } x \in X.$$

When $U = \{0\}$, $\mathbb{I}_{S|U}$ reduces to the indicator function

$$I_S(x) := \begin{cases} 0, & x \in S \\ +\infty, & x \notin S, \end{cases}$$

which can be seen from (1.2).

Various properties of $\mathbb{I}_{S|U}$ have been studied in the literature. If S is convex, the function $\mathbb{I}_{S|U}$ is convex. However, if S is not convex, $\mathbb{I}_{S|U}$ is not necessarily convex. Li and Ni [9] studied the relationships between the existence of minimizers of the minimization problem in (1.1) and directional derivatives of the function $\mathbb{I}_{S|U}(x)$. De Blasi and Myjak [5] and Li [8] studied the well-posedness of the minimization problem in (1.1).

Observe that $\mathbb{I}_{S|U}$ is an optimal value function. Thibault [13] gave upper estimate of subdifferential of optimal value function for an abstract optimization model

$$m(x) := \inf \{f(x, y) : y \in M(x) \cap A\}, \quad (1.4)$$

where M is a set-valued mapping from Banach space X to Banach space Y , $f : X \times Y \rightarrow \mathbb{R} \cup \{+\infty\}$, and A is a subset of Y . Taking $A = S$, $M(x) \equiv Y$, and $f(x, y) = \rho_U(y - x)$, one has

$$m(x) = \mathbb{I}_{S|U}(x).$$

Thus one can apply the main results in [13] to establish subdifferential formula of $\mathbb{I}_{S|U}$. However, this way can only yield upper estimate of subdifferential of $\mathbb{I}_{S|U}$.

Utilizing the special structure of $\mathbb{I}_{S|U}$, one can establish an exact equality of subdifferential of $\mathbb{I}_{S|U}$ in place of upper estimate, and hence improve the subdifferential formula in [13] from upper estimate to exact equality for a special optimal value function $\mathbb{I}_{S|U}$. We review some related work in the following, one can refer to [1, 3, 6, 7, 10–12, 14] for related discussions.

Assume that the origin is an interior point of U , [3,4] gave the formulas for the Fréchet and the proximal subdifferentials of $\Pi_{S|U}$ in Hilbert spaces. It is proved that the Fréchet subdifferential of $\Pi_{S|U}$ at $x \in S$ can be characterized in terms of Fréchet normal cone of S at x and a sublevel set of the support function of U , while the Fréchet subdifferential of $\Pi_{S|U}$ for points outside S can be characterized in terms of Fréchet normal cone of an enlarged set of S and a level set of the support function of U . Similar results hold for proximal subdifferential.

Removing the key assumption that the origin is an interior point of U , [7] presented the same formulas for the Fréchet and the proximal subdifferentials of $\Pi_{S|U}$. However, for subdifferential formulas at $x \notin S$, a calmness condition is required in [7], which plays an important role; see Theorems 3.2 and 4.2 therein. It is noted that calmness condition, also called center-Lipschitz condition in [12], is weaker than locally Lipschitz. When the origin is an interior point of U , $\Pi_{S|U}$ is globally Lipschitz, and hence calmness condition holds naturally. Thus [7] improved the main results in [3,4].

So far, subdifferential formulas at points inside S are complete. This paper considers subdifferential formulas at points outside S . Our results improve known ones by removing both the assumptions that the origin is an interior point of U and the calmness condition, using a new argument.

We organize this paper as follows. Section 2 contains some related concepts and preliminary results. Sections 3 and 4 are devoted to give the formulas for the Fréchet and the proximal subdifferentials of $\Pi_{S|U}$ at $x \notin S$ respectively.

2 Preliminaries

In this section, we recall some definitions and notations and most of them are derived from [2].

Unless otherwise stated, throughout this paper, X is a real normed vector space with norm denoted by $\|\cdot\|$ and X^* denotes the topological dual of X . The canonical pairing $\langle \cdot, \cdot \rangle$ is between X^* and X . Let S be a nonempty closed subset of X and $U \subset X$ a bounded closed convex subset. $M > 0$ satisfies

$$M \geq \sup \{\|u\| : u \in U\}.$$

The support function $\mathfrak{S}_U : X^* \rightarrow (-\infty, \infty]$ of U is defined by

$$\mathfrak{S}_U(\xi) := \sup_{u \in U} \langle \xi, u \rangle, \quad \text{for all } \xi \in X^*.$$

Let $\mathbb{B}(x; \delta)$ denote the open ball centered at x with radius $\delta > 0$ and let $\mathbb{B}^\circ(x; \delta) := \mathbb{B}(x; \delta) \setminus \{x\}$. Suppose that $f : X \rightarrow (-\infty, \infty]$ is a lower semicontinuous function. For $x \in \text{dom } f := \{x \in X : f(x) < \infty\}$, the proximal subdifferential of f at x is the set

$$\partial^P f(x) := \left\{ \xi \in X^* : \liminf_{v \rightarrow 0} \frac{f(x+v) - f(x) - \langle \xi, v \rangle}{\|v\|^2} > -\infty \right\}.$$

Equivalently, there exist $\sigma, \delta > 0$ such that

$$f(y) - f(x) \geq \langle \xi, y - x \rangle - \sigma \|y - x\|^2, \text{ for all } y \in \mathbb{B}(x; \delta).$$

Moreover, the Fréchet subdifferential of f at x is the set

$$\partial^F f(x) := \left\{ \xi \in X^* : \liminf_{v \rightarrow 0} \frac{f(x+v) - f(x) - \langle \xi, v \rangle}{\|v\|} \geq 0 \right\}.$$

The proximal normal cone N_S^P to S at $x \in S$ is the set of all $\xi \in X^*$ for which there exist $\sigma, \delta > 0$ such that

$$\langle \xi, y - x \rangle \leq \sigma \|y - x\|^2, \text{ for all } y \in S \cap \mathbb{B}(x; \delta),$$

and the Fréchet normal cone N_S^F to S at $x \in S$ is the set of all $\xi \in X^*$ for which for arbitrary $\sigma > 0$, there exists $\delta > 0$ such that

$$\langle \xi, y - x \rangle \leq \sigma \|y - x\|, \text{ for all } y \in S \cap \mathbb{B}(x; \delta).$$

The proximal normal cone and the Fréchet normal cone of S at x are actually the corresponding subdifferential of the indicator function of S at x ; see [2].

Define

$$S(r) := \{x \in X : \Pi_{S|U}(x) \leq r\}, \text{ where } r \geq 0.$$

Lemma 2.1 *Let $v \in U$ and $t \geq 0$. Then*

$$\Pi_{S|U}(x - tv) \leq \Pi_{S|U}(x) + t, \text{ for all } x \in X. \quad (2.1)$$

Proof Fix any $x \in X$. If $\Pi_{S|U}(x) = \infty$, the inequality holds obviously. If $\Pi_{S|U}(x) < \infty$, it has been proved in [12, Lemma 5.2]. \square

Lemma 2.2 *Let $\delta > 0$. Suppose $x \notin S$ and $y \in \mathbb{B}(x; \delta/2)$ with $r := \Pi_{S|U}(x) < \infty$ and $q := \Pi_{S|U}(y)$. If $q < r$, $v \in U$, and $0 < t < \min \left\{ \frac{\delta}{2\|v\|+1}, r - q \right\}$, then*

$$y - tv \in S(r) \cap \mathbb{B}^\circ(x; \delta).$$

Proof Let $z_t := y - tv$. By virtue of (2.1) and the fact of $t < r - q$, we have

$$\Pi_{S|U}(z_t) \leq \Pi_{S|U}(y) + t < q + r - q = r, \quad (2.2)$$

and thus $z_t \in S(r)$. By the choice of t ,

$$\|z_t - x\| = \|y - tv - x\| \leq \|y - x\| + t\|v\| < \delta,$$

it follows that $z_t \in \mathbb{B}(x; \delta)$. $z_t \neq x$ is a direct consequence of (2.2), as $\Pi_{S|U}(z_t) < r$ and $\Pi_{S|U}(x) = r$. \square

3 Fréchet subdifferential of the minimal time function

In this section, we characterize the Fréchet subdifferential of $\Pi_{S|U}$ at points outside S without additional assumptions. Let us firstly establish a lemma.

Lemma 3.1 *Suppose that $m, n, \sigma > 0$. Let*

$$p := \frac{(n + \sigma)(1 + mn) - \sqrt{(n + \sigma)^2(1 + mn)^2 - 4n\sigma}}{2n},$$

$$0 < \sigma_0 < \min \left\{ \frac{1}{1 + mn}, p \right\}, \quad (3.1)$$

and let

$$k := \frac{(\sigma_0 + 1)n}{1 - \sigma_0(1 + mn)}.$$

Then

$$\sigma_0 n(mk + 1) < \sigma \text{ and } k > n.$$

Proof $k > n$ is obvious as $\frac{\sigma_0 + 1}{1 - \sigma_0(1 + mn)} > 1$. Now we show

$$\sigma_0 n(mk + 1) - \sigma < 0.$$

Observe that

$$\begin{aligned} \sigma_0 n(mk + 1) - \sigma &= \sigma_0 n \left(\frac{m(\sigma_0 + 1)n}{1 - \sigma_0(1 + mn)} + 1 \right) - \sigma \\ &= a\sigma_0^2 + b\sigma_0 + c, \end{aligned}$$

where

$$\begin{aligned} a &:= -\frac{n}{1 - \sigma_0(1 + mn)}, \\ b &:= \frac{(1 + mn)(n + \sigma)}{1 - \sigma_0(1 + mn)}, \\ c &:= -\frac{\sigma}{1 - \sigma_0(1 + mn)}. \end{aligned}$$

It remains to prove $a\sigma_0^2 + b\sigma_0 + c < 0$. By virtue of (3.1), $a < 0$, $b > 0$, $c < 0$. Moreover, it can be checked that $b^2 - 4ac > 0$. Since $p = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$ and $0 < \sigma_0 < p$, it follows that $a\sigma_0^2 + b\sigma_0 + c < 0$. \square

Now we present a Fréchet subdifferential formula for $\Pi_{S|U}$ at points outside S , which improves main result in [7, Section 4] by removing an important assumption.

Theorem 3.1 Let $x \notin S$ and $r := \Pi_{S|U}(x) < \infty$. Then

$$\partial^F \Pi_{S|U}(x) = N_{S(r)}^F(x) \cap \{\xi \in X^* : \mathfrak{S}_U(-\xi) = 1\}.$$

Proof Theorem 4.2(a) of [7] shows that the left-hand side is contained in the right-hand side. Now we need only to prove the converse inclusion.

Let $\xi \in N_{S(r)}^F(x) \cap \{\xi \in X^* : \mathfrak{S}_U(-\xi) = 1\}$. Then

$$\xi \neq 0, \quad (3.2)$$

as ξ satisfies $\mathfrak{S}_U(-\xi) = 1$.

For any $\sigma > 0$, let

$$0 < \sigma_0 < \min \left\{ \frac{1}{1 + M\|\xi\|}, p \right\}, \quad (3.3)$$

where

$$p := \frac{(\|\xi\| + \sigma)(1 + M\|\xi\|) - \sqrt{(\|\xi\| + \sigma)^2(1 + M\|\xi\|)^2 - 4\|\xi\|\sigma}}{2\|\xi\|},$$

and let

$$k := \frac{(\sigma_0 + 1)\|\xi\|}{1 - \sigma_0(1 + M\|\xi\|)}.$$

Replacing m and n by M and $\|\xi\|$ respectively, one can apply Lemma 3.1 to obtain that

$$\sigma_0\|\xi\|(Mk + 1) < \sigma \text{ and } k > \|\xi\|. \quad (3.4)$$

Since $\xi \in N_{S(r)}^F(x)$ and $\xi \neq 0$, there exists $\delta > 0$ such that

$$\langle \xi, y - x \rangle < \sigma_0\|\xi\|\|y - x\|, \text{ for every } y \in S(r) \cap \mathbb{B}^\circ(x; \delta). \quad (3.5)$$

Let $\delta_1 := \frac{\delta}{2(1+Mk)}$. In order to prove the conclusion, we only need to verify that

$$\Pi_{S|U}(y) - \Pi_{S|U}(x) \geq \langle \xi, y - x \rangle - \sigma\|y - x\|, \text{ for every } y \in \mathbb{B}^\circ(x; \delta_1).$$

Fix any $y \in \mathbb{B}^\circ(x; \delta_1)$ and let $q := \Pi_{S|U}(y)$. Since $\delta_1 < \delta$, we have

$$y \in \mathbb{B}^\circ(x; \delta). \quad (3.6)$$

In the following, we divide the discussion into three cases.

(i) $\Pi_{S|U}(y) = r$. Then $y \in S(r)$. It follows from (3.5) that

$$\begin{aligned}\Pi_{S|U}(y) - \Pi_{S|U}(x) &= 0 > \langle \xi, y - x \rangle - \sigma_0 \|\xi\| \|y - x\| \\ &\geq \langle \xi, y - x \rangle - \sigma_0 \|\xi\| (1 + Mk) \|y - x\| \\ &> \langle \xi, y - x \rangle - \sigma \|y - x\|,\end{aligned}$$

where the last inequality follows from (3.4).

(ii) $\Pi_{S|U}(y) > r$. Recall $q = \Pi_{S|U}(y)$. By the definition of $\Pi_{S|U}(y)$, for any $\varepsilon \in (0, \frac{\delta}{2M})$, there exists $q_\varepsilon \in [q, q + \varepsilon]$ such that

$$S \cap (y + q_\varepsilon U) \neq \emptyset.$$

Take $u_1 \in U$ satisfying $y + q_\varepsilon u_1 \in S$.

Define $z_1 := y + q_\varepsilon u_1 - ru_1$. Then $z_1 + ru_1 \in S$ and hence

$$\Pi_{S|U}(z_1) \leq r.$$

If $q - r \leq k\|y - x\|$, then

$$\begin{aligned}\|z_1 - x\| &\leq \|z_1 - y\| + \|y - x\| \\ &= (q_\varepsilon - r)\|u_1\| + \|y - x\| \\ &\leq M(q_\varepsilon - r) + \|y - x\| \\ &\leq M(q - r + \varepsilon) + \|y - x\| \leq (Mk + 1)\|y - x\| + M\varepsilon \\ &< \delta.\end{aligned}\tag{3.7}$$

This verifies that

$$z_1 \in S(r) \cap \mathbb{B}(x; \delta),$$

and hence (3.5) implies

$$\langle \xi, z_1 - x \rangle \leq \sigma_0 \|\xi\| \|z_1 - x\|.$$

Therefore,

$$\begin{aligned}\Pi_{S|U}(y) - \Pi_{S|U}(x) - \langle \xi, y - x \rangle &= q - r - \langle \xi, y - z_1 \rangle - \langle \xi, z_1 - x \rangle \\ &= q - r - (r - q_\varepsilon) \langle \xi, u_1 \rangle - \langle \xi, z_1 - x \rangle \\ &\geq q - r + r - q_\varepsilon - \langle \xi, z_1 - x \rangle \\ &= q - q_\varepsilon - \langle \xi, z_1 - x \rangle \\ &\geq q - q_\varepsilon - \sigma_0 \|\xi\| \|z_1 - x\| \\ &\geq -\varepsilon - \sigma_0 \|\xi\| ((Mk + 1)\|y - x\| + M\varepsilon),\end{aligned}$$

where the last inequality follows from (3.7).

As $\varepsilon > 0$ is arbitrary, letting $\varepsilon \rightarrow 0+$ yields that

$$\Pi_{S|U}(y) - \Pi_{S|U}(x) - \langle \xi, y - x \rangle \geq -\sigma_0 \|\xi\| (Mk + 1) \|y - x\| > -\sigma \|y - x\|,$$

where the last inequality follows from (3.4).

If $q - r > k \|y - x\|$, it follows from $k > \|\xi\|$ that

$$\begin{aligned} \Pi_{S|U}(y) - \Pi_{S|U}(x) - \langle \xi, y - x \rangle &\geq q - r - \|\xi\| \|y - x\| \\ &> q - r - k \|y - x\| \\ &> 0 \geq -\sigma \|y - x\|. \end{aligned}$$

(iii) $\Pi_{S|U}(y) < r$. Since $\mathfrak{I}_U(-\xi) = 1$ and $\sigma_0 < 1$, there exists $\bar{v} \in U$ such that

$$1 \geq \langle -\xi, \bar{v} \rangle > 1 - \sigma_0. \quad (3.8)$$

Take $z_t := y - t\bar{v}$ for $t > 0$. We claim that there exists \hat{t} such that

$$\Pi_{S|U}(z_{\hat{t}}) \geq r \text{ and } 0 < \hat{t} \leq k \|y - x\|. \quad (3.9)$$

Indeed, if $0 < t < \min \left\{ \frac{\delta}{2M+1}, r - q \right\}$, Lemma 2.2 implies that

$$z_t \in S(r) \cap \mathbb{B}^\circ(x; \delta),$$

and thus we obtain from (3.5) that

$$\langle \xi, z_t - x \rangle < \sigma_0 \|\xi\| \|z_t - x\|. \quad (3.10)$$

On the other hand, noting that

$$\begin{aligned} \lim_{t \rightarrow +\infty} \frac{\langle \xi, z_t - x \rangle}{t} &= \langle -\xi, \bar{v} \rangle > 1 - \sigma_0 > \sigma_0 \|\xi\| M \geq \sigma_0 \|\xi\| \|\bar{v}\| \\ &= \lim_{t \rightarrow +\infty} \frac{\sigma_0 \|\xi\| \|z_t - x\|}{t}, \end{aligned}$$

where the second inequality follows from (3.3), we obtain for large enough t ,

$$\langle \xi, z_t - x \rangle > \sigma_0 \|\xi\| \|z_t - x\|. \quad (3.11)$$

Combing (3.11) with (3.10) yields that there exists $\hat{t} > 0$ such that

$$\langle \xi, z_{\hat{t}} - x \rangle = \sigma_0 \|\xi\| \|z_{\hat{t}} - x\|, \quad (3.12)$$

which, together with (3.10), implies that

$$z_{\hat{t}} \notin S(r) \cap \mathbb{B}^\circ(x; \delta). \quad (3.13)$$

By (3.8) and (3.12), one has

$$\begin{aligned} -\|\xi\|\|y-x\| + \widehat{t}(1-\sigma_0) &\leq \langle \xi, y-x \rangle + \widehat{t}(1-\sigma_0) \leq \langle \xi, y-x \rangle + \widehat{t}\langle \xi, -\bar{v} \rangle \\ &= \langle \xi, z_{\widehat{t}}-x \rangle = \sigma_0 \|\xi\| \|z_{\widehat{t}}-x\| \leq \sigma_0 \|\xi\| (\|y-x\| + \widehat{t}\|\bar{v}\|) \\ &\leq \sigma_0 \|\xi\| \|y-x\| + \sigma_0 \|\xi\| \widehat{t}M, \end{aligned}$$

and hence

$$0 < \widehat{t} \leq \frac{(\sigma_0 + 1)\|\xi\|}{1 - \sigma_0(1 + M\|\xi\|)} \cdot \|y-x\| \equiv k\|y-x\|.$$

Since $y \in \mathbb{B}^\circ(x; \delta_1)$, that is, $\|y-x\| < \frac{\delta}{2(Mk+1)}$, then

$$\|z_{\widehat{t}}-x\| \leq \|y-x\| + \widehat{t}M \leq (kM+1)\|y-x\| < \delta/2 < \delta.$$

and thus by virtue of (3.13),

$$z_{\widehat{t}} \notin S(r) \text{ or } z_{\widehat{t}} = x,$$

which implies $\Pi_{S|U}(z_{\widehat{t}}) \geq r$. We have therefore established the claim (3.9).

By Lemma 2.1, we have

$$\Pi_{S|U}(z_{\widehat{t}}) - \Pi_{S|U}(y) = \Pi_{S|U}(y - \widehat{t}\bar{v}) - \Pi_{S|U}(y) \leq \widehat{t}.$$

Hence, it follows from (3.9) that

$$\Pi_{S|U}(x) - \Pi_{S|U}(y) = r - \Pi_{S|U}(y) \leq \Pi_{S|U}(z_{\widehat{t}}) - \Pi_{S|U}(y) \leq \widehat{t} \leq k\|y-x\|. \quad (3.14)$$

For any $\varepsilon \in (0, r-q)$, the definition of $\Pi_{S|U}$ implies the existence of $q_\varepsilon \in [q, q+\varepsilon)$ such that

$$S \cap (y + q_\varepsilon U) \neq \emptyset. \quad (3.15)$$

Since $\sup_{u \in U} \langle -\xi, u \rangle = 1$, there exists $u_2 \in U$ such that

$$\langle -\xi, u_2 \rangle > 1 - \varepsilon. \quad (3.16)$$

Let $z_2 := y + q_\varepsilon u_2 - ru_2$. By the convexity of U , $(r - q_\varepsilon)U + q_\varepsilon U \subset rU$, and then

$$\begin{aligned} y + q_\varepsilon U &= z_2 - q_\varepsilon u_2 + ru_2 + q_\varepsilon U \\ &\subset z_2 + (r - q_\varepsilon)U + q_\varepsilon U \subset z_2 + rU. \end{aligned}$$

From (3.15), we obtain $S \cap (z_2 + rU) \neq \emptyset$ and hence

$$z_2 \in S(r). \quad (3.17)$$

Moreover, (3.14) implies that

$$\begin{aligned}
 \|z_2 - x\| &\leq \|z_2 - y\| + \|y - x\| \\
 &= (r - q_\varepsilon)\|u_2\| + \|y - x\| \\
 &< M(r - q) + \|y - x\| \\
 &\leq (Mk + 1)\|y - x\| < \delta.
 \end{aligned} \tag{3.18}$$

Combining (3.17) with (3.18), we have

$$z_2 \in S(r) \cap \mathbb{B}(x; \delta).$$

It follows from (3.5) that

$$\langle \xi, z_2 - x \rangle \leq \sigma_0 \|\xi\| \|z_2 - x\|. \tag{3.19}$$

Applying (3.16), (3.18) and (3.19), we obtain

$$\begin{aligned}
 \Pi_{S|U}(y) - \Pi_{S|U}(x) - \langle \xi, y - x \rangle &= q - r - \langle \xi, y - z_2 \rangle - \langle \xi, z_2 - x \rangle \\
 &= q - r - \langle \xi, (r - q_\varepsilon)u_2 \rangle - \langle \xi, z_2 - x \rangle \\
 &\geq q - r + (r - q_\varepsilon)(1 - \varepsilon) - \langle \xi, z_2 - x \rangle \\
 &= q - q_\varepsilon - (r - q_\varepsilon)\varepsilon - \langle \xi, z_2 - x \rangle \\
 &\geq -\varepsilon(1 + r - q_\varepsilon) - \langle \xi, z_2 - x \rangle \\
 &\geq -\varepsilon(1 + r - q_\varepsilon) - \sigma_0 \|\xi\| \|z_2 - x\| \\
 &\geq -\varepsilon(1 + r - q_\varepsilon) - \sigma_0 \|\xi\| (Mk + 1)\|y - x\|.
 \end{aligned} \tag{3.20}$$

As $\varepsilon > 0$ is arbitrary in (3.20), we have

$$\Pi_{S|U}(y) - \Pi_{S|U}(x) - \langle \xi, y - x \rangle \geq -\sigma_0 \|\xi\| (Mk + 1)\|y - x\| > -\sigma \|y - x\|,$$

where the last inequality is due to (3.4). \square

4 Proximal subdifferential of the minimal time function

Now, we present a proximal subdifferential formula for $\Pi_{S|U}$ at points outside S , which improves main result in [7, Section 3] by removing calmness assumption.

Theorem 4.1 *Let $x \notin S$ and $r := \Pi_{S|U}(x) < \infty$. Then*

$$\partial^P \Pi_{S|U}(x) = N_{S(r)}^P(x) \cap \{\xi \in X^* : \mathfrak{I}_U(-\xi) = 1\}.$$

Proof Note that Theorem 3.2(a) in [7] implies that

$$\partial^P \Pi_{S|U}(x) \subset N_{S(r)}^P(x) \cap \{\xi \in X^* : \mathfrak{I}_U(-\xi) = 1\}.$$

Now we prove the converse inclusion.

Let $\xi \in N_{S(r)}^P(x) \cap \{\xi \in X^* : \mathfrak{S}_U(-\xi) = 1\}$. It follows from $\mathfrak{S}_U(-\xi) = 1$ that

$$\xi \neq 0, \quad (4.1)$$

which, together with $\xi \in N_{S(r)}^P(x)$, implies that there exist $\sigma, \delta > 0$ such that

$$\langle \xi, y - x \rangle \leq \sigma \|\xi\| \|y - x\|^2, \text{ for every } y \in S(r) \cap \mathbb{B}(x; \delta). \quad (4.2)$$

Let $k := 4(1 + \sigma)^2 \|\xi\|$. Then

$$\|\xi\| < k. \quad (4.3)$$

Let

$$\delta_1 := \min \left\{ \frac{\delta}{2(1 + Mk)}, 1, \frac{1}{(4M\sigma \|\xi\| + 1)(1 + \sigma)}, \frac{1}{16\sigma \|\xi\|^2 M^2(1 + \sigma)^3} \right\} \quad (4.4)$$

and

$$\sigma_1 := \sigma \|\xi\| (Mk + 1)^2. \quad (4.5)$$

It suffices to show that

$$\Pi_{S|U}(y) - \Pi_{S|U}(x) \geq \langle \xi, y - x \rangle - \sigma_1 \|y - x\|^2, \text{ for every } y \in \mathbb{B}(x; \delta_1).$$

Fix an arbitrary $y \in \mathbb{B}(x; \delta_1)$. Since $\delta_1 < \delta$, we have

$$y \in \mathbb{B}^\circ(x; \delta). \quad (4.6)$$

In the following, let $q := \Pi_{S|U}(y)$, and we divide the argument into three cases.

(i) $\Pi_{S|U}(y) = r$. Then $y \in S(r)$. It follows from (4.6) that

$$\begin{aligned} \Pi_{S|U}(y) - \Pi_{S|U}(x) = 0 &\geq \langle \xi, y - x \rangle - \sigma \|\xi\| \|y - x\|^2 \\ &\geq \langle \xi, y - x \rangle - \sigma_1 \|y - x\|^2, \end{aligned}$$

where the first inequality is due to (4.2) and the second inequality is due to (4.5).

(ii) $\Pi_{S|U}(y) > r$. If $q - r > \|\xi\| \|y - x\|$, then

$$\begin{aligned} \Pi_{S|U}(y) - \Pi_{S|U}(x) - \langle \xi, y - x \rangle &\geq \Pi_{S|U}(y) - \Pi_{S|U}(x) - \|\xi\| \|y - x\| \\ &= q - r - \|\xi\| \|y - x\| \\ &> 0 \geq -\sigma_1 \|y - x\|^2. \end{aligned}$$

Now, we assume that $q - r \leq \|\xi\| \|y - x\|$. By the definition of $\Pi_{S|U}$, for any $\varepsilon \in (0, \frac{\delta}{2M})$, there exists $q_\varepsilon \in [q, q + \varepsilon]$ such that

$$S \cap (y + q_\varepsilon U) \neq \emptyset.$$

Take $u_1 \in U$ satisfying $y + q_\varepsilon u_1 \in S$.

Set $z_1 := y + q_\varepsilon u_1 - r u_1$. Then $z_1 + r u_1 = y + q_\varepsilon u_1 \in S$ and hence

$$\Pi_{S|U}(z_1) \leq r.$$

As $q - r \leq \|\xi\| \|y - x\|$, one has

$$\begin{aligned} \|z_1 - x\| &\leq \|z_1 - y\| + \|y - x\| \\ &= (q_\varepsilon - r)\|u_1\| + \|y - x\| \\ &\leq M(q_\varepsilon - r) + \|y - x\| \\ &\leq M(q - r + \varepsilon) + \|y - x\| \leq (M\|\xi\| + 1)\|y - x\| + M\varepsilon \\ &< \delta. \end{aligned} \quad (4.7)$$

This verifies that

$$z_1 \in S(r) \cap \mathbb{B}(x; \delta),$$

and thus (4.2) implies

$$\langle \xi, z_1 - x \rangle \leq \sigma \|\xi\| \|z_1 - x\|^2.$$

Since $u_1 \in U$ and $\mathfrak{I}_U(-\xi) = 1$, it follows that

$$\begin{aligned} \Pi_{S|U}(y) - \Pi_{S|U}(x) - \langle \xi, y - x \rangle &= q - r - \langle \xi, y - z_1 \rangle - \langle \xi, z_1 - x \rangle \\ &= q - r - (r - q_\varepsilon)\langle \xi, u_1 \rangle - \langle \xi, z_1 - x \rangle \\ &\geq q - r + r - q_\varepsilon - \langle \xi, z_1 - x \rangle \\ &= q - q_\varepsilon - \langle \xi, z_1 - x \rangle \\ &\geq q - q_\varepsilon - \sigma \|\xi\| \|z_1 - x\|^2 \\ &\geq -\varepsilon - \sigma \|\xi\| ((M\|\xi\| + 1)\|y - x\| + M\varepsilon)^2, \end{aligned}$$

where the last inequality is due to (4.7).

Letting $\varepsilon \rightarrow 0+$ yields that

$$\Pi_{S|U}(y) - \Pi_{S|U}(x) - \langle \xi, y - x \rangle \geq -\sigma \|\xi\| (M\|\xi\| + 1)^2 \|y - x\|^2 \geq -\sigma_1 \|y - x\|^2,$$

where the last inequality follows from (4.3) and (4.5).

(iii) $\Pi_{S|U}(y) < r$. As $\mathfrak{I}_U(-\xi) = 1$, let $\bar{v} \in U$ be such that

$$1 \geq \langle -\xi, \bar{v} \rangle > \frac{1}{1 + \sigma}. \quad (4.8)$$

Take $z_t := y - t\bar{v}$ for $t > 0$. We claim that there exists \widehat{t} such that

$$\Pi_{S|U}(z_{\widehat{t}}) > r \text{ and } 0 < \widehat{t} \leq k\|y - x\|. \quad (4.9)$$

Now, we find $t > 0$ such that

$$\langle \xi, z_t - x \rangle > \sigma \|\xi\| \|z_t - x\|^2. \quad (4.10)$$

Note that

$$\langle \xi, z_t - x \rangle = \langle \xi, y - x \rangle + t \langle \xi, -\bar{v} \rangle > \langle \xi, y - x \rangle + \frac{t}{1 + \sigma}$$

and

$$\sigma \|\xi\| \|z_t - x\|^2 \leq \sigma \|\xi\| (\|y - x\| + t\|\bar{v}\|)^2 \leq \sigma \|\xi\| (\|y - x\| + tM)^2.$$

In order to verify (4.10), it remains to find $t > 0$ satisfying

$$\sigma \|\xi\| (\|y - x\| + tM)^2 - \langle \xi, y - x \rangle - \frac{t}{1 + \sigma} \leq at^2 + bt + c \leq 0, \quad (4.11)$$

where

$$\begin{aligned} a &:= \sigma M^2 \|\xi\|, \\ b &:= 2M\sigma \|\xi\| \|y - x\| - \frac{1}{1 + \sigma}, \\ c &:= \sigma \|\xi\| \|y - x\|^2 + \|\xi\| \|y - x\|. \end{aligned}$$

By virtue of (4.1), $a > 0$. It can be checked by (4.1) and (4.6) that $c > 0$. Since $y \in \mathbb{B}(x; \delta_1)$, we deduce from (4.4) that

$$\|y - x\| < \frac{1}{4M(1 + \sigma)\sigma \|\xi\|}, \quad (4.12)$$

$$\|y - x\| < \min \left\{ 1, \frac{1}{16\sigma \|\xi\|^2 M^2 (1 + \sigma)^3} \right\}. \quad (4.13)$$

(4.12) implies

$$b < -\frac{1}{2(1 + \sigma)},$$

which, together with (4.13), implies

$$\begin{aligned} 4ac &= 4\sigma M^2 \|\xi\| (\sigma \|\xi\| \|y - x\|^2 + \|\xi\| \|y - x\|) \\ &= 4\sigma M^2 \|\xi\|^2 (1 + \sigma) \|y - x\| < \frac{1}{4(1 + \sigma)^2} < b^2. \end{aligned}$$

Thus

$$\frac{-b - \sqrt{b^2 - 4ac}}{2a} > 0,$$

as $a > 0$, $b < 0$, and $c > 0$.

By the property of quadratic polynomial with respect to t , if t satisfies

$$\frac{-b - \sqrt{b^2 - 4ac}}{2a} \leq t \leq \frac{-b + \sqrt{b^2 - 4ac}}{2a}, \quad (4.14)$$

then (4.11) holds, so does (4.10). In particular, for $\hat{t} := \frac{-b - \sqrt{b^2 - 4ac}}{2a}$, (4.10) holds. As a consequence of (4.2),

$$z_{\hat{t}} \notin S(r) \cap \mathbb{B}(x; \delta). \quad (4.15)$$

Note that

$$\begin{aligned} \hat{t} &= \frac{2c}{-b + \sqrt{b^2 - 4ac}} \\ &\leq -\frac{2c}{b} \leq 4c(1 + \sigma) \\ &\leq 4(1 + \sigma)^2 \|\xi\| \|y - x\| \\ &= k \|y - x\|. \end{aligned} \quad (4.16)$$

Since $y \in \mathbb{B}^\circ(x; \delta_1)$, it follows from (4.4) that $\|y - x\| < \frac{\delta}{2(Mk+1)}$. Then

$$\|z_{\hat{t}} - x\| \leq \|y - x\| + \hat{t}M \leq (1 + kM)\|y - x\| \leq \delta,$$

where the second inequality is due to (4.16). Combing this with (4.15), we deduce

$$z_{\hat{t}} \notin S(r),$$

which implies

$$\Pi_{S|U}(z_{\hat{t}}) > r, \quad (4.17)$$

and thus the claim (4.9) is verified.

By Lemma 2.1, we have

$$\Pi_{S|U}(z_{\hat{t}}) - \Pi_{S|U}(y) = \Pi_{S|U}(y - \hat{t}\hat{v}) - \Pi_{S|U}(y) \leq \hat{t}.$$

It follows from (4.16) and (4.17) that

$$\Pi_{S|U}(x) - \Pi_{S|U}(y) = r - \Pi_{S|U}(y) \leq \Pi_{S|U}(z_{\hat{t}}) - \Pi_{S|U}(y) \leq \hat{t} \leq k\|y - x\|. \quad (4.18)$$

Note that $q < r$. For any $\varepsilon \in (0, r - q)$, the definition of $\Pi_{S|U}$ implies the existence of $q_\varepsilon \in [q, q + \varepsilon)$ such that

$$S \cap (y + q_\varepsilon U) \neq \emptyset. \quad (4.19)$$

Since $\sup_{u \in U} \langle -\xi, u \rangle = 1$, there exists $u_2 \in U$ such that

$$\langle -\xi, u_2 \rangle > 1 - \varepsilon. \quad (4.20)$$

Let $z_2 := y - (r - q_\varepsilon)u_2$. By the convexity of U , $(r - q_\varepsilon)U + q_\varepsilon U \subset rU$. Therefore,

$$\begin{aligned} y + q_\varepsilon U &= z_2 - (r - q_\varepsilon)u_2 + q_\varepsilon U \\ &\subset z_2 + (r - q_\varepsilon)U + q_\varepsilon U \subset z_2 + rU. \end{aligned}$$

From (4.19), we obtain $S \cap (z_2 + rU) \neq \emptyset$, and hence $\Pi_{S|U}(z_2) \leq r$, that is,

$$z_2 \in S(r). \quad (4.21)$$

Moreover, (4.18) and (4.4) imply that

$$\begin{aligned} \|z_2 - x\| &\leq \|z_2 - y\| + \|y - x\| \\ &= (r - q_\varepsilon)\|u_2\| + \|y - x\| \\ &< M(r - q) + \|y - x\| \leq (Mk + 1)\|y - x\| \end{aligned} \quad (4.22)$$

$$< \delta. \quad (4.23)$$

Therefore, (4.21) and (4.23) imply that

$$z_2 \in S(r) \cap \mathbb{B}(x; \delta).$$

By virtue of (4.2),

$$\langle \xi, z_2 - x \rangle \leq \sigma \|\xi\| \|z_2 - x\|^2. \quad (4.24)$$

It follows that

$$\begin{aligned} \Pi_{S|U}(y) - \Pi_{S|U}(x) - \langle \xi, y - x \rangle &= q - r - \langle \xi, y - z_2 \rangle - \langle \xi, z_2 - x \rangle \\ &= q - r - \langle \xi, (r - q_\varepsilon)u_2 \rangle - \langle \xi, z_2 - x \rangle \\ &\geq q - r + (r - q_\varepsilon)(1 - \varepsilon) - \langle \xi, z_2 - x \rangle \\ &= q - q_\varepsilon - (r - q_\varepsilon)\varepsilon - \langle \xi, z_2 - x \rangle \\ &\geq -\varepsilon(1 + r - q_\varepsilon) - \langle \xi, z_2 - x \rangle \\ &\geq -\varepsilon(1 + r - q_\varepsilon) - \sigma \|\xi\| \|z_2 - x\|^2 \\ &\geq -\varepsilon(1 + r - q_\varepsilon) - \sigma \|\xi\| (Mk + 1)^2 \|y - x\|^2, \end{aligned} \quad (4.25)$$

where the first, the third, and the last inequality are respectively due to (4.20), (4.24), and (4.22).

Letting $\varepsilon \rightarrow 0+$ in (4.25), one has

$$\Pi_{S|U}(y) - \Pi_{S|U}(x) - \langle \xi, y - x \rangle \geq -\sigma \|\xi\| (Mk + 1)^2 \|y - x\|^2 = -\sigma_1 \|y - x\|^2,$$

where the last equality follows from (4.5). \square

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