

# Shushman Choudhury

Github | Website | Scholar | LinkedIn  
shushman@cs.stanford.edu

## INTERESTS

Multi-Agent Decision-Making; Intelligent Transportation Systems; Digital Policy

## EXPERIENCE

### LACUNA TECHNOLOGIES, INC. | RESEARCH SCIENTIST

Jul 2021 - Ongoing | Palo Alto, CA

- Cutting-edge decision-making for transportation and mobility policies, in partnership with US cities and airports.

### STANFORD INTELLIGENT SYSTEMS LABORATORY (SISL) | RESEARCH ASSISTANT

Sep 2017 - Jun 2021 | Stanford, CA

- Hierarchical allocation, route planning, and control algorithms for large multi-robot networks.
- Work on drone-transit routing featured in VentureBeat, BBC Digital Planet, and IEEE Spectrum (among others)

### MICROSOFT RESEARCH REDMOND (MSR) | AI PHD INTERN

Summer 2020 | Remote

- Multi-task deep reinforcement learning by computing and adapting shared representations.

### CMU PERSONAL ROBOTICS LAB | RESEARCH ASSISTANT

Aug 2015 - Aug 2017 | Pittsburgh, PA

- Efficient anytime motion planning for robot manipulation, validated on the robot HERB.

### STANFORD LAW SCHOOL | TECH POLICY LAB MEMBER

Sep 2018 - Apr 2019 | Stanford, CA

- Advised INTERPOL [Article], the Administrative Conference of the United States [Report], and the US federal government task force on the National Research Cloud [Article].

## EDUCATION

### STANFORD UNIVERSITY | PH.D. IN COMPUTER SCIENCE | SEP 2017 - JUNE 2021

Advisors - Mykel Kochenderfer and Jeannette Bohg

School of Engineering Graduate Fellowship 2017-18 | VMWare Graduate Fellowship 2020-21

### CARNEGIE MELLON UNIVERSITY | M.S. IN ROBOTICS | AUG 2015 - AUG 2017

Advisor - Siddhartha Srinivasa • GPA: 4.00

### IIT KHARAGPUR | B.TECH. IN COMPUTER SCIENCE | JUL 2011 - MAY 2015

Advisor - Partha Pratim Chakrabarti • GPA: 9.47/10

## SELECTED PUBLICATIONS

**Coordinated Multi-Agent Pathfinding for Drones and Trucks over Road Networks** S. Choudhury, K. Solovey, M. J. Kochenderfer, and M. Pavone. International Conference on Autonomous Agents and Multi-Agent Systems 2022 (To Appear)

**Scalable Anytime Planning for Multi-Agent MDPs** S. Choudhury, J. K. Gupta, P. Morales, and M. J. Kochenderfer. Autonomous Agents and Multi-Agent Systems (AAMAS) 2021. **Best Paper**

**Efficient Large Scale Multi-Drone Delivery Using Transit Networks** S. Choudhury, K. Solovey, M. J. Kochenderfer, and M. Pavone. IEEE ICRA 2020 **Best Multi-Robot Paper Finalist** Journal of Artificial Intelligence Research

**Dynamic Multi-Robot Task Allocation under Uncertainty and Temporal Constraints** S. Choudhury, J. K. Gupta, M. J. Kochenderfer, D. Sadigh, and J. Bohg. Robotics Science and Systems (RSS) 2020

## LANGUAGES AND LIBRARIES

• Julia • C++ • Python • POMDPs.jl • Pytorch

## SELECTED OUTREACH

### STANFORD IGNITE PROGRAM 2018 | STUDENT MENTOR

Helped develop a curated set of robotics-inspired math exercises for Sequoia High School, Redwood City.

### ENGINEERS FOR A SUSTAINABLE WORLD | CONTENT COORDINATOR

Co-authored a Springer Book article on the role of STEAM education in a sustainable world.