

### □ Simple harmonic motion:

The motion of a particle moving along a straight line with an acceleration whose direction is always towards a fixed point on the line and whose magnitude is proportional to the distance from the fixed point is called simple harmonic motion. A vibrating system that execute simple harmonic motion is sometimes called simple harmonic oscillator.

### □ Characteristics of simple harmonic motion:

1. The motion is periodic motion.
2. The acceleration of the body is proportional to its displacement from its equilibrium position.
3. The acceleration of the body is always directed towards a certain fixed point.
4. The motion is **isochronous** because the expression for the time period ( $T = 2\pi \sqrt{\frac{m}{k}}$ ) is independent of the amplitude of the motion.
5. The equation does not conclude the motion of the particle along the circle.

### □ Differential equation of a simple harmonic oscillator and its solution:

Let us consider a motion of the vibration of a system of mass  $m$ , attached to a spring of negligible mass, as the mass slides on a frictionless surface, as shown in Fig. 1.

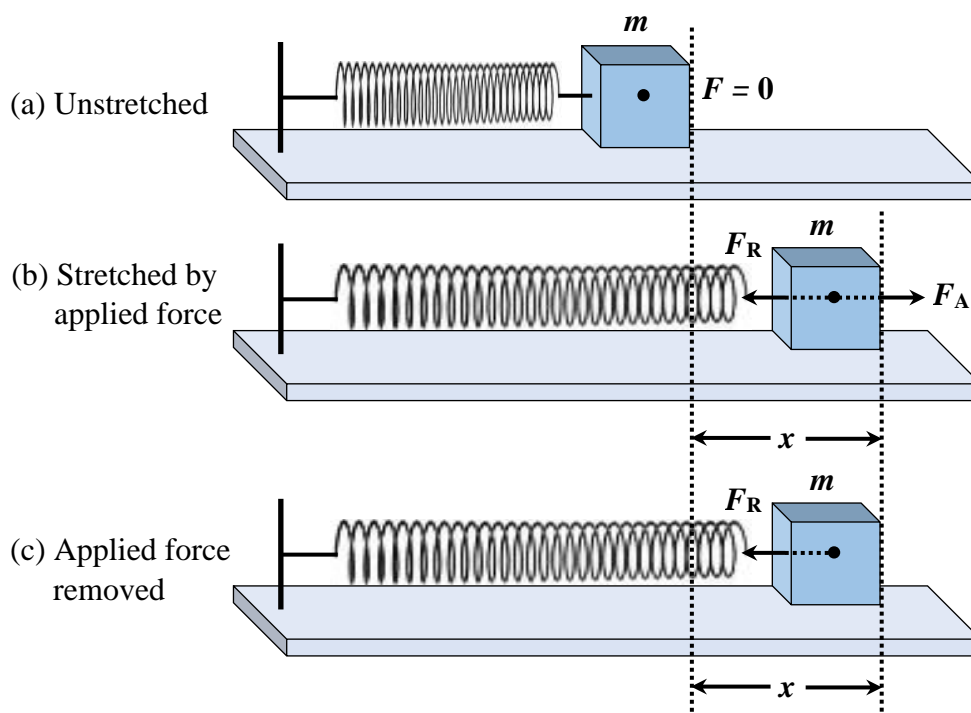


Fig.1. Vibrating spring.

Let us consider that the mass  $m$ , in unstretched position [Fig. 1(a)], is in its equilibrium position. If an applied force  $F_A$  acts on the mass, it will be displaced to the right of its equilibrium position by a distance  $x$  as shown in Fig. 1(b).

From Hook's law

$$F_A = kx \quad \text{where, } k \text{ is the force constant}$$

By Newton's third law, there is an equal but opposite elastic restoring force exerted by the spring on the mass which pulling the mass towards the left.

$$F_R = -F_A$$

$$\text{or, } F_R = -kx \dots \dots \dots (1)$$

When  $F_A$  is removed, the elastic restoring force  $F_R$  is then the only force acting on the mass  $m$  [Fig. 1(c)], and it tries to restore  $m$  to its equilibrium position. We can then find the acceleration of the mass from Newton's second law as

$$ma = F_R$$

$$\text{or, } ma = -kx \dots \dots \dots (2)$$

Since the acceleration  $a = \frac{d^2x}{dt^2}$ , the Eq. (2) can be written as

$$m \frac{d^2x}{dt^2} = -kx$$

$$\text{or, } \frac{d^2x}{dt^2} = -\frac{k}{m}x$$

$$\therefore \frac{d^2x}{dt^2} + \frac{k}{m}x = 0 \dots \dots \dots (3)$$

The Eq. (3) is the required differential equation of a simple harmonic oscillator.

Solving the Eq. (3) produce a solution that is a sinusoidal function

$$x(t) = c_1 \cos \omega t + c_2 \sin \omega t$$

This equation can be written in the form

$$x(t) = A \cos(\omega t + \phi)$$

$$\text{where, } \omega = \sqrt{\frac{k}{m}}, A = \sqrt{c_1^2 + c_2^2}, \tan \phi = \frac{c_2}{c_1}$$

where,  $A$  is the amplitude (maximum displacement from equilibrium),  $\omega = 2\pi f$  is the angular frequency,  $f$  is the frequency, and  $\phi$  is a constant known as phase.

$$\textbf{Velocity } v = \frac{dx}{dt} = -A \sin(\omega t + \phi). \omega = -A \omega \sin(\omega t + \phi)$$

$$\textbf{Acceleration } a = \frac{d^2x}{dt^2} = \frac{dv}{dt} = -A \omega \cos(\omega t + \phi). \omega = -A \omega^2 \cos(\omega t + \phi)$$

$$\text{or, } a = -\omega^2 x, \text{ where, } \omega^2 = \frac{k}{m}$$

$$\text{Since } \omega = 2\pi f$$

$$\therefore \textbf{frequency } f = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

$$\text{and since } \textbf{time period } T = \frac{1}{f}$$

$$\therefore T = 2\pi \sqrt{\frac{m}{k}}$$

#### □ Energy of simple harmonic oscillator:

$$\text{Kinetic energy } K = \frac{1}{2}mv^2 = \frac{1}{2}m[-A\omega \sin(\omega t + \phi)]^2 \quad [\text{since } v = -A\omega \sin(\omega t + \phi)]$$

$$\begin{aligned}
 &= \frac{1}{2} m \omega^2 A^2 \sin^2(\omega t + \phi) = \frac{1}{2} m \frac{k}{m} A^2 \sin^2(\omega t + \phi) \\
 &= \frac{1}{2} k A^2 \sin^2(\omega t + \phi)
 \end{aligned}$$

and potential energy  $U = \frac{1}{2} k x^2$

$$= \frac{1}{2} k A^2 \cos^2(\omega t + \phi) \quad [\text{since } x = A \cos(\omega t + \phi)]$$

The total energy  $E = K + U$

$$\begin{aligned}
 &= \frac{1}{2} k A^2 \sin^2(\omega t + \phi) + \frac{1}{2} k A^2 \cos^2(\omega t + \phi) \\
 &= \frac{1}{2} k A^2 [\sin^2(\omega t + \phi) + \cos^2(\omega t + \phi)] \\
 &= \frac{1}{2} k A^2 \text{ where, } k \text{ and } A \text{ are constant.}
 \end{aligned}$$

Therefore, in the absence of friction and other energy loss, the total mechanical energy of a simple harmonic oscillator is constant.