

On seeking *efficient* Pareto optimal points in
multi-player minimum cost flow problems

Shuvomoy Das Gupta
Operations Research Center, MIT

Joint work with Lacra Pavel, University of Toronto

Outline

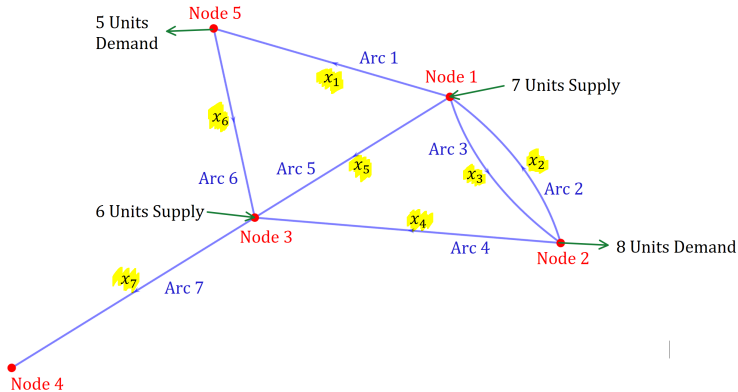
- ▶ what happens if the **minimum cost flow problem** is extended to a multi-player setup
- ▶ what is a good solution concept in such a multi-player setup
⇒ ***efficient* Pareto optimal point**
- ▶ **under what conditions** these good solutions exist
 - one version always exists in any network
 - existence of a stricter version can be checked
- ▶ how to **compute** such solutions

Application



- ▶ E-commerce product transportation systems are dominated by **Amazon, Walmart, Alibaba...**
 - ▶ Amazon uses **FedEx, UPS, AAR** and **other competing organizations** for transportation services
- ⇒ ***multi-player* minimum cost flow problem**

Minimum cost flow problem



- ▶ **Directed connected graph** with nodes and arcs
- ▶ **Integer-valued flow** of some material on each arc
- ▶ Each arc incurs a **cost**
- ▶ **Minimize the total cost** of all flows subject to the network constraints

Minimum cost flow problem

$$\begin{aligned} &\text{minimize}_x \quad \sum_{i \in \{1, \dots, n\}} f_i(x_i) \quad \backslash * \text{ default: } f_i(x_i) = c_i x_i \quad * \backslash \\ &\text{subject to} \quad Ax = b \quad \backslash * \text{ flow conservation constraint } * \backslash \\ &\quad \quad \quad 0 \preceq x \preceq u \quad \backslash * \text{ flow bound constraint } * \backslash \\ &\quad \quad \quad x \in \mathbf{Z}^n \quad \backslash * \text{ flow is integer } * \backslash. \end{aligned}$$

- ▶ The network has n arcs, $m+1$ nodes
- ▶ A : reduced node-arc incidence matrix, dimension $m \times n$
- ▶ b : represents supplies/demands
- ▶ u : upper bound on flow

Meaning of the constraints

- ▶ **The flow conservation constraint:** for any node, the outflow minus inflow must equal the supply/demand of the node
 - must be maintained
- ▶ **The flow bound constraint:** imposes direction and capacity limit on the flow
 - can often be relaxed or omitted in practice
 - in the relaxed case, flow direction is flexible and overflow is allowed

A multi-player extension

- ▶ With **each arc** of the network graph we associate **one player**
- ▶ Each player tries to minimize its **nonconvex cost function**, subject to the network flow constraints
- ▶ Our goal is to seek a **good solution concept** in this multi-player problem

Goal of a player

- ▶ The goal of the i th player for $i = 1, \dots, n$, given other players' strategies $x_{-i} \in \mathbf{Z}^{n-1}$, is to solve:

$$\begin{aligned} & \underset{x_i}{\text{minimize}} && f_i(x_i) && \backslash * \text{ nonconvex } * \backslash \\ & \text{subject to} && A(x_i, x_{-i}) = b && \backslash * \text{ constraints} \\ & && 0 \preceq (x_i, x_{-i}) \preceq u && \text{couple the players } * \backslash \\ & && x \in \mathbf{Z}^n. \end{aligned}$$

Back to the application

- ▶ **Arcs:** transportation links
- ▶ **Nodes:**
 - **Supply nodes:** warehouses
 - **Demand nodes:** retail centers
- ▶ **Players:** transportation organizations (FedEx, UPS, AAR etc)
- ▶ **Flow:** products transported
- ▶ **Each player's goal:**
 - maximize its profit (nonlinear)
 - only controls its own flow

Solution concepts

- ▶ A **solution to the optimization problem** would always favor the dominant player ignoring the rest
- ▶ A **vector optimal solution** is the best social solution
 - It minimizes all the objectives simultaneously
 - **problem:** violates flow conservation
- ▶ The celebrated **Nash equilibrium** is also not very efficient in our setup
- ▶ A better solution solution concept is the **Pareto optimal point**

Pareto optimal point

Pareto optimal point: none of the cost functions can be reduced without increasing some other cost function.

A “feasible” point x^{Pareto} is Pareto optimal if it satisfies the following: there *does not* exist another “feasible” point x such that for all $i = 1, \dots, n$

$$f_i(x_i) \leq f_i(x_i^{\text{Pareto}}),$$

with at least one index j satisfying $f_j(x_j) < f_j(x_j^{\text{Pareto}})$.

Problem: There can be numerous such generic Pareto optimal points, some poor in quality or efficiency.

Efficient Pareto optimal point

- ▶ Finds a balance between **vector optimality** and the **generic Pareto optimality**
- ▶ It is a Pareto optimal point where
 - the maximum possible number of players minimize their cost functions simultaneously
 - flow is conserved
 - flow bound is maintained for the maximum possible number of arcs

The main result

For any multi-player minimum cost flow problem, there exists one efficient Pareto optimal point such that

- ▶ it is **Pareto optimal** and $n - m$ **vector optimal**
 - out of n players, $n - m$ will minimize their cost functions simultaneously
 - the set of $n - m$ vector optimality is maximal (it cannot be made any larger)
- ▶ the flow conservation constraints are maintained
- ▶ at least $n - m$ of the flow bound constraints are maintained (possibly all)

An existence result

- ▶ Out of n flow bound constraints, m of them may not be maintained
- ▶ Can we check in advance if all of the flow bound constraints are maintained?
- ▶ We provide an existence theorem using algebraic geometry

Why need algebraic geometry?

The flow bound constraints over integers can be formulated as polynomials.

Some necessary concepts

- ▶ The **ideal** generated by polynomials f_1, f_2, \dots, f_m is the set

$$\text{ideal}\{f_1, \dots, f_m\} = \left\{ \sum_{i=1}^m h_i f_i \mid h_1, \dots, h_m \text{ are polynomials} \right\}.$$

- analogous to **span of vectors**

- ▶ Given an ideal I , **affine variety** is the set

$$\text{variety}(I) = \{x \mid f(x) = 0, \text{ for all } f \text{ in } I\}$$

- analogous to **null-space of a matrix**

- ▶ **A Groebner basis** G is particular kind of generating set of an ideal I

- analogous to **basis of a span**

- ▶ **Reduced Groebner basis** G_{reduced} is the most compact Groebner basis for an ideal I

- analogous to **orthonormal basis of a span**

Statement of the existence theorem

From the structure of the network (after some pre-calculation), we can generate polynomials

$$q_1, \dots, q_m, r_1, \dots, r_{n-m}$$

Exactly one of the following holds:

(a) There exists an efficient Pareto optimal point, where all the flow bound constraints are maintained.

(b) We have

$$G_{\text{reduced}} = \{1\},$$

where G_{reduced} is the reduced Groebner basis of **ideal** $\{q_1, \dots, q_m, r_1, \dots, r_{n-m}\}$.

There are many computer algebra packages (Maple, Mathematica, FGb) that can compute G_{reduced}

Computing efficient Pareto optimal point

We propose an algorithm to compute efficient Pareto optimal points in two stages:

- ▶ **Stage 1:** We compute a larger set \mathcal{F} , that contains all the efficient Pareto optimal points
- ▶ **Stage 2:** From \mathcal{F} , we compute efficient Pareto optimal points using algebraic elimination theory
 - Need to solve only single-variable optimization problems

Stage 1

- ▶ For $i = 1, 2, \dots, n - m$ calculate

- Compute

$$G_{n-m-i} = G_{\text{reduced}} \cap \mathbf{C}[z_{n-m-i+1}, z_{n-m-i+2}, \dots, z_{n-m}]$$

- Compute **variety**(G_{n-m-i})

- ▶ Each G_{n-m-i} results in a single-variable polynomial system
- ▶ Finding **variety**(G_{n-m-i}) is just finding the roots of a single variable polynomial
- ▶ $\mathcal{F} = \mathbf{variety}(G_0)$

Stage 2

```
for  $i = 1, \dots, m$   
   $X_i := d_i - h_i^T \mathcal{F}$     \* The inverse operator is denoted  $X_i^{-1}$  *\br/>end for  
\* We can compute  $d_i$  and  $h_i$  from  $A$  and  $u$ *\
```

Sort the elements of the $\{X_i\}_{i=1}^m$ s with respect to cardinality of the elements in a descending order.

Denote the index set of the sorted set by $\{s_1, \dots, s_m\}$ such that $|X|_{s_1} \geq \dots \geq |X|_{s_m}$.

```
for  $i = 1, \dots, m$   
   $X_{s_i}^* := \operatorname{argmin}_{x_{s_i} \in X_{s_i}} f_{s_i}(x_{s_i})$     \* Easy to solve single-variable  
optimization problem *\br/>   $\mathcal{F}_{s_i}^* := \bigcup_{x_{s_i} \in X_{s_i}^*} (X_{s_i}^*)^{-1}(x_{s_i})$     \* Lemma. The set  $\mathcal{F}_{s_i}^*$  is nonempty *\br/>  if  $i \leq m$   
     $X_{s_{i+1}} := \{d_{s_{i+1}} - h_{s_{i+1}}^T z \mid z \in \mathcal{F}_{s_i}^*\}$ .  
  end if  
end for  
return  $\mathcal{F}_{s_m}^*$     \* Theorem. Any member of  $\mathcal{F}_{s_m}^*$  is an efficient Pareto  
optimal point *\
```

Concluding Remarks

- ▶ ***Multi-player* minimum cost flow problem**: a natural extension of the minimum cost flow problem
- ▶ ***Efficient* Pareto optimal point** is a desirable solution concept
 - A soft version always exists
 - A strict version can exist: existence can be checked
- ▶ **Algorithms** to compute efficient Pareto optimal points

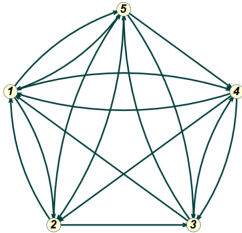
Paper available at

- ▶ <https://shuvomoy.github.io/site/>
- ▶ <https://link.springer.com/article/10.1007/s10898-019-00750-9>

Thank You!

Questions?

Numerical example



A multi-player transportation problem

- 5 nodes, 16 arcs
- Nodes 2, 4 are retail centers
- Nodes 1, 3 are warehouses
- Node 5 transshipment node
- Products need to be shipped from warehouses to retail centers
- Arcs represent different modes of shipment from one node to another and carried out by different organization
- Cost of a certain type of shipment depends on the number of products shipped

$$A = \begin{pmatrix} 1 & 0 & 0 & 0 & -1 & -1 & -1 & 1 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 & 0 & -1 & -1 & -1 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & -1 & -1 & -1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & -1 & -1 & -1 \end{pmatrix}$$

$$b = (9, -13, 15, -11), \quad u = (5, 6, 6, 10, 10, 7, 11, 13, 16, 12, 4, 5, 6, 14, 13, 15)$$

Player	Cost function
1	$-\frac{x_1^4}{30} - \frac{13x_1^3}{15} + \frac{259x_1^2}{30} - \frac{263x_1}{15} + 1$
2	$\frac{77x_2^5}{120} - \frac{247x_2^4}{24} + \frac{471x_2^3}{8} - \frac{3365x_2^2}{24} + \frac{6779x_2}{60} + 1$
3	$\frac{47x_3^4}{24} - \frac{133x_3^3}{4} + \frac{4897x_3^2}{24} - \frac{2123x_3}{4} + 485$
4	$\frac{323x_4^5}{3360} - \frac{2179x_4^4}{1120} + \frac{47393x_4^3}{3360} - \frac{48709x_4^2}{1120} + \frac{7885x_4}{168} + 5$
5	$(x_5 - 1)^2$
6	$-\frac{x_6^4}{8} + \frac{25x_6^3}{12} - \frac{71x_6^2}{8} + \frac{95x_6}{12} + 10$
7	$ x_7 - 5 $
8	$\frac{11x_8^7}{1260} - \frac{7x_8^6}{36} + \frac{119x_8^5}{72} - \frac{479x_8^4}{72} + \frac{4609x_8^3}{360} - \frac{803x_8^2}{72} + \frac{155x_8}{28} + 1$
9	$-\frac{15}{16}x_9^3 + \frac{365x_9^2}{16} - \frac{2865x_9}{16} + \frac{7315}{16}$
10	$(x_{10} - 10)^2$
11	$\frac{5x_{11}^4}{6} - \frac{35x_{11}^3}{3} + \frac{355x_{11}^2}{6} - \frac{370x_{11}}{3} + 90$
12	$\frac{5x_{12}^4}{6} - \frac{25x_{12}^3}{3} + \frac{175x_{12}^2}{6} - \frac{110x_{12}}{3} + 15$
13	$\frac{5x_{13}^4}{6} - 15x_{13}^3 + \frac{595x_{13}^2}{6} - 280x_{13} + 285$
14	$\frac{5x_{14}^4}{6} - \frac{85x_{14}^3}{3} + \frac{2155x_{14}^2}{6} - \frac{6020x_{14}}{3} + 4165$
15	$ x_{15} - 7 $
16	$\begin{cases} x_{16} + 1, & \text{if } 0 \leq x_{16} \leq 3 \\ 0, & \text{if } 4 \leq x_{16} \leq 6 \\ (x_{16} + 1)^3, & \text{if } 7 \leq x_{16} \leq 9 \\ -\frac{x_{16}^3}{6} + \frac{13x_{16}^2}{2} - \frac{244x_{16}}{3} + 330, & \text{else} \end{cases}$

Pareto Optimal Solutions

Our algorithm provides two efficient Pareto optimal points:

$(1, 3, 5, 4, 11, 10, 2, 1, 3, 7, 7, 5)$

and

$(1, 3, 5, 6, 11, 10, 2, 1, 3, 7, 7, 6)$.