

# RANDOM WORLD GENERATION

**EXPLORING ALGORITHMS, VISUAL STYLES,  
AND OPTIMIZATION TECHNIQUES**

NAME:- SHUVRADEEP BERA  
ROLL:- 24IE10042



## What is Procedural Generation?

Procedural generation is the practice of using algorithms to create game content (like maps, characters, items, etc.) automatically instead of manual creation.

## Importance of Procedural Generation

- Enhances replayability and unpredictability in games.
- Procedural generation lowers manual labour, thus reducing development time and costs

## Key Takeaways

- Discussing algorithms like Perlin noise, simplex noise, cellular automata, and Voronoi diagrams.
- Understanding their development, algorithm, applications, limitations and optimization techniques.





# PERLIN NOISE

## Algorithm

### GRID GENERATION

- Perlin noise operates on n-dimensional grid
- Each grid point (or vertex) is assigned a random gradient vector

### DOT PRODUCT

- For any point within a grid cell, calculate the offset vectors from each corner of the cell to the point.
- Dot product of each gradient and offset vector is computed

### INTERPOLATION

- Use these dot products to interpolate between the corners of the grid cell.
- First top left and top right, then bottom left and bottom right
- Then, interpolate these two to get final noise at that point

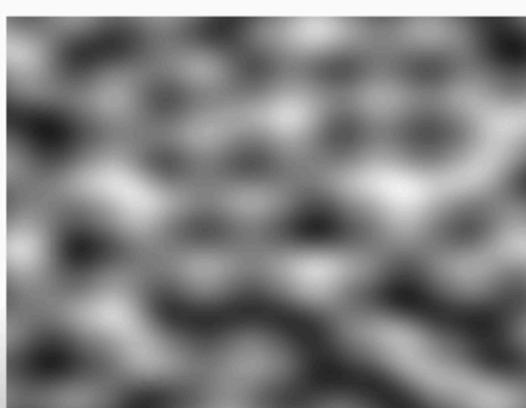
### FADE FUNCTION (EASE CURVE)

- To ensure smooth transitions, an ease curve is used.
- This function, typically  $6t^5 - 15t^4 + 10t^3$ , is applied to interpolation parameters to make transitions more gradual and natural-looking

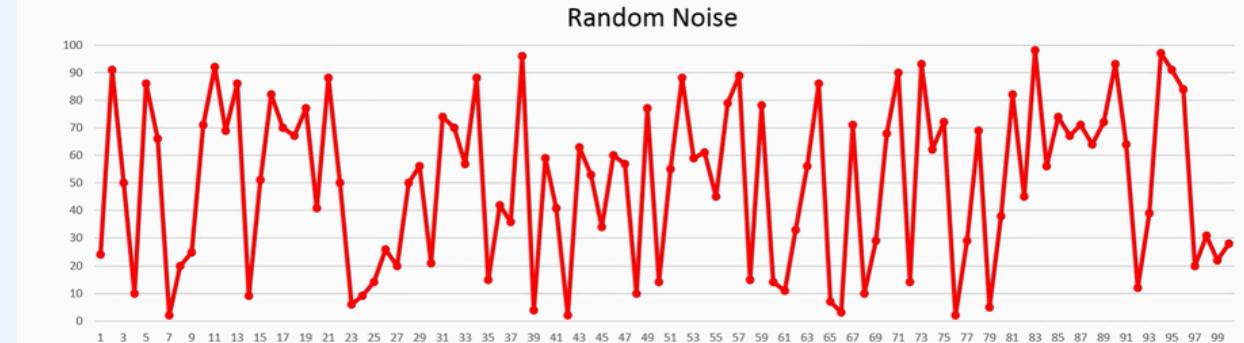
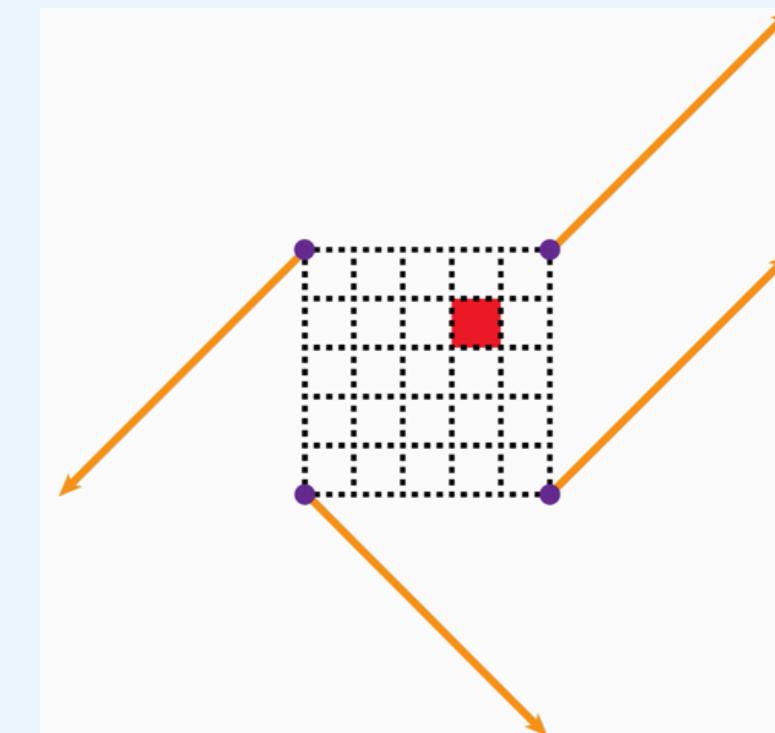
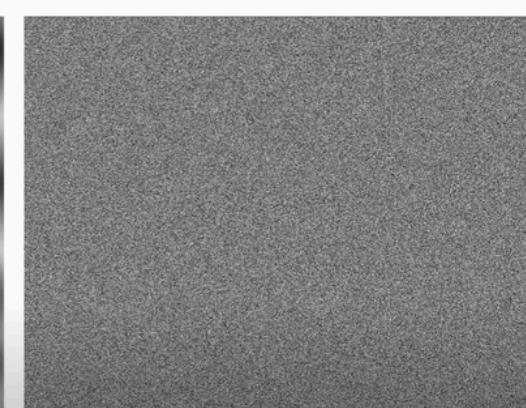
### WHAT IS PERLIN NOISE?

Perlin noise is a gradient-based procedural noise algorithm developed by Ken Perlin in 1983. It generates smooth, natural-looking randomness

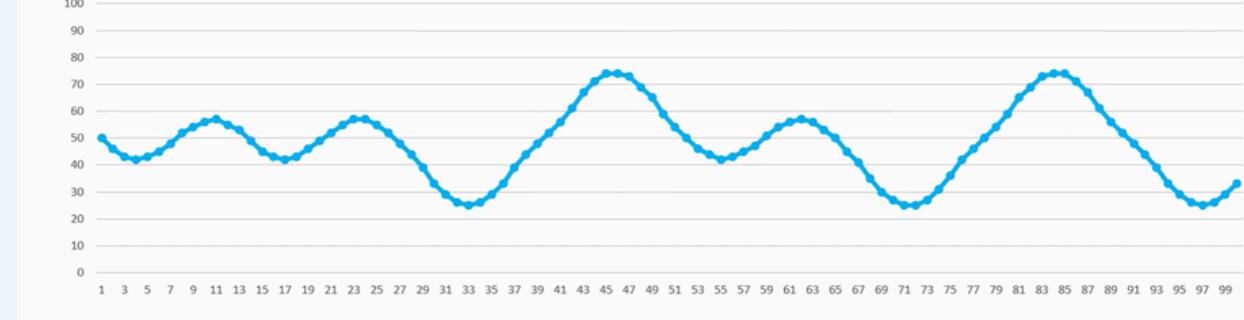
2D Perlin Noise

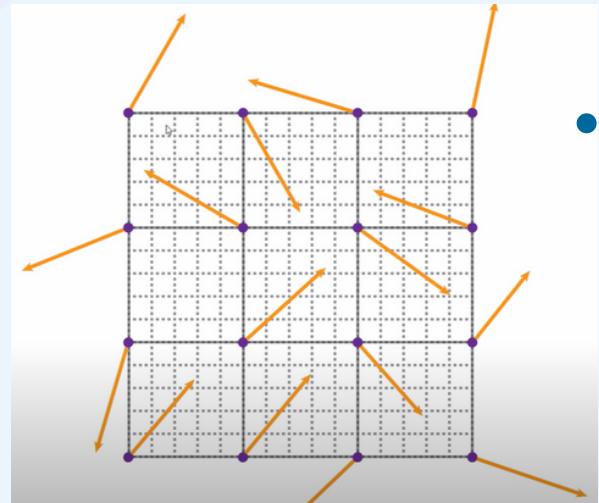


2D Random Noise

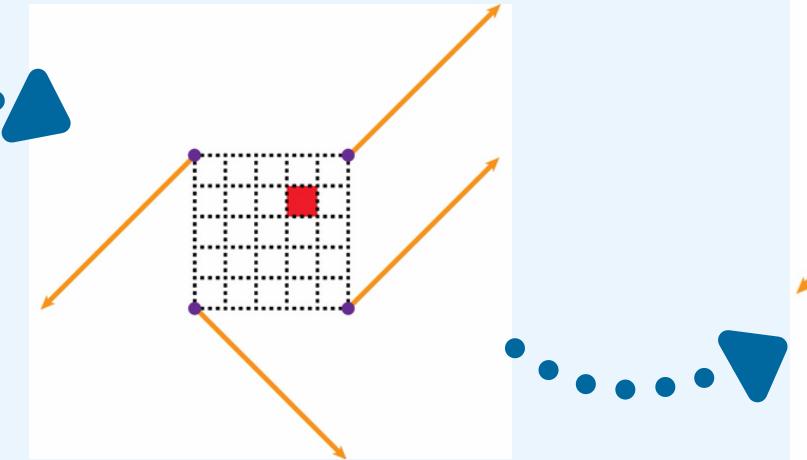


Perlin Noise

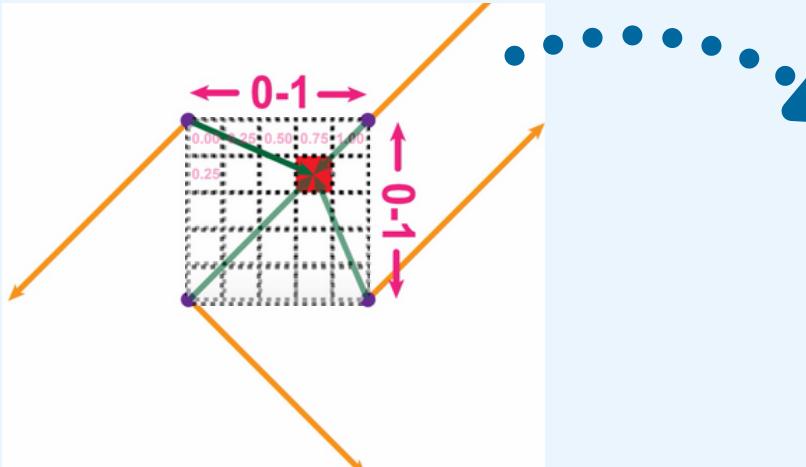




Gradient vectors assigned to various corners



One cell chosen and gradient vectors randomly generated



Distance of each cell from different corners are measured and later used in dot product

Dot product computed gradient vector and pixel distance vector

$$\begin{aligned}D_1 &= \vec{G}(-1, 1) \cdot \vec{D}(0.75, 0.25) = -0.5. \\D_2 &= \vec{G}(1, -1) \cdot \vec{D}(-0.25, 0.25) = -0.5. \\D_3 &= \vec{G}(1, 1) \cdot \vec{D}(-0.75, 0.75) = 0. \\D_4 &= \vec{G}(1, -1) \cdot \vec{D}(-0.25, -0.75) = 0.5.\end{aligned}$$

Now these dot products are used along with fade function parameters  
For eg.-

## Final Result

So, the final Perlin noise value at (0.3, 0.6) is -0.103.

This result tells us that at this point, the Perlin noise function is **negative**, meaning this location corresponds to a **low-intensity area** in a grayscale Perlin noise map.

$$\begin{aligned}N &= (1 - v) \cdot N_x 0 + v \cdot N_x 1 \\&= (1 - 0.683) \cdot (-0.5) + 0.683 \cdot (0.0815) \\&= (0.317 \times -0.5) + (0.683 \times 0.0815) \\&= -0.1585 + 0.0556 \\&= -0.103\end{aligned}$$

Interpolate along y-direction

### Top Row Interpolation ( $y = 1$ , between dot00 and dot01)

$$\begin{aligned}N_x 0 &= (1 - u) \cdot \text{dot00} + u \cdot \text{dot01} \\&= (1 - 0.163) \cdot (-0.5) + 0.163 \cdot (-0.5) \\&= (0.837 \times -0.5) + (0.163 \times -0.5) \\&= -0.4185 - 0.0815 = -0.5\end{aligned}$$

### Bottom Row Interpolation ( $y = 0$ , between dot10 and dot11)

$$\begin{aligned}N_x 1 &= (1 - u) \cdot \text{dot10} + u \cdot \text{dot11} \\&= (1 - 0.163) \cdot (0) + 0.163 \cdot (0.5) \\&= (0.837 \times 0) + (0.163 \times 0.5) \\&= 0 + 0.0815 = 0.0815\end{aligned}$$

Interpolate along x-direction

For  $(x, y) = (2.3, 4.7)$ :

- The bottom-left corner of the grid cell is  $(x_0, y_0) = (2, 4)$
- The top-right corner is  $(x_0+1, y_0+1) = (3, 5)$
- The fractional part of  $(x, y)$  inside this grid cell is:

$$t_x = x - x_0 = 2.3 - 2 = 0.3$$

$$t_y = y - y_0 = 4.7 - 4 = 0.7$$

This means the point  $(2.3, 4.7)$  is 30% of the way from (2,4) to (3,4) in X and 70% of the way from (2,4) to (2,5) in Y.

$$\text{fade}(t) = 6t^5 - 15t^4 + 10t^3$$

$$\text{fade}(0.3) \approx 0.163$$

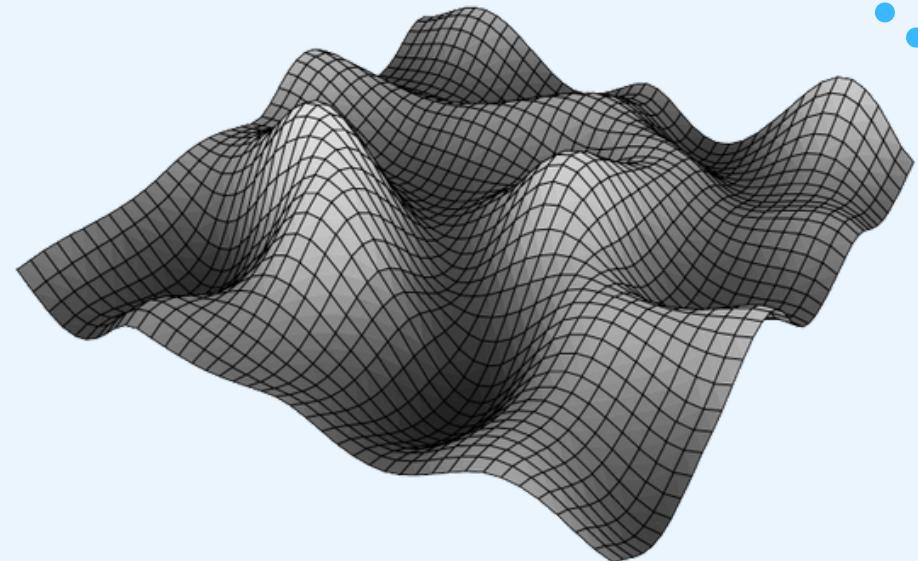
$$\text{fade}(0.7) \approx 0.837$$

# PERLIN NOISE



## KEY FEATURES

- Smooth, continuous gradient noise.
- Smooth and organic appearance that mimics natural textures and patterns

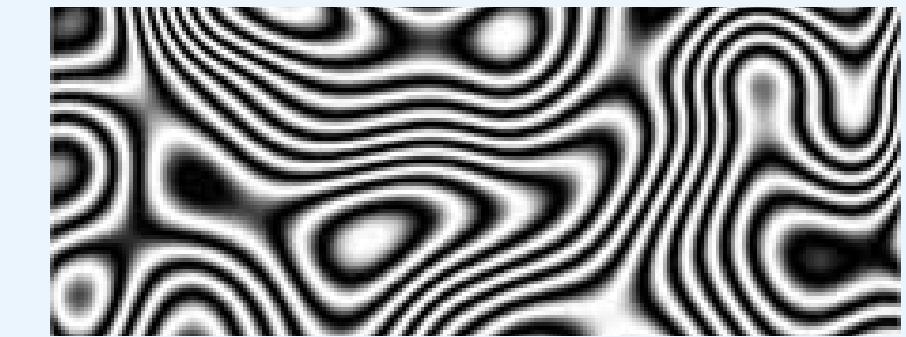


## APPLICATIONS

- Terrain generation (mountains, clouds, water).
- Texture generation (wood, marble).
- Example: Rolling hills or cloud formations.

## DISADVANTAGES

- Can appear "blobby" or lack sharp features.
- Computationally expensive for high dimensions.



## OPTIMISATION

- Use precomputed gradients.
- Limit the number of octaves in fractal noise.
- Use SIMPLEX NOISE.

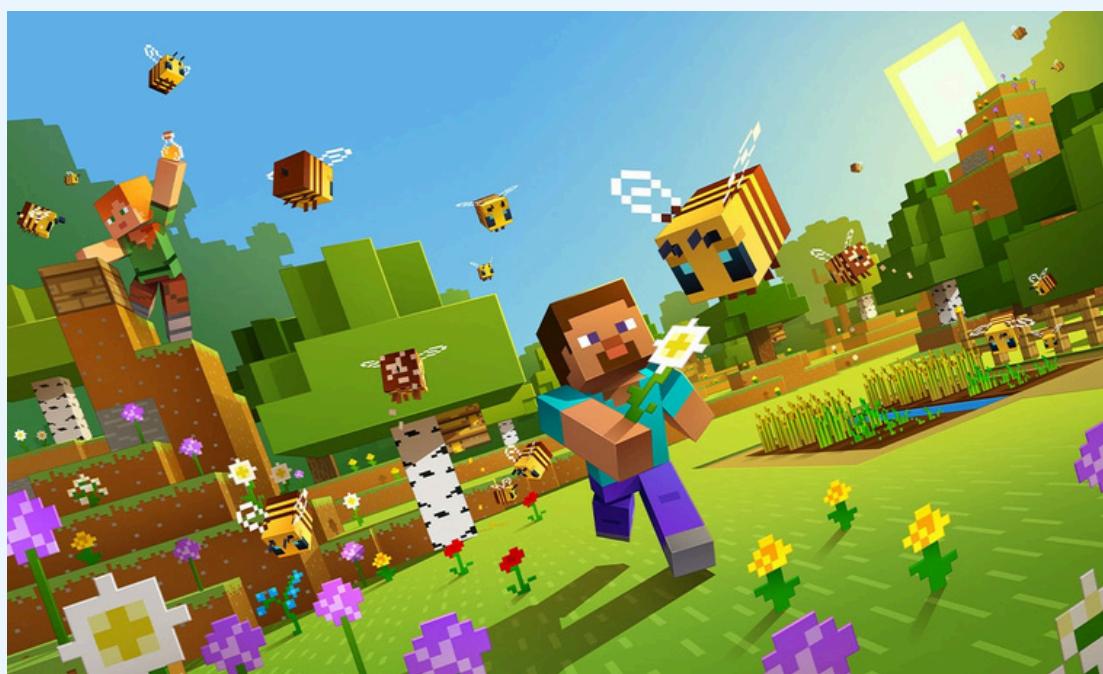
Mother Nature doesn't use a random world generator—she just smudges the pixels until they look right!" 😁



# SIMPLEX NOISE

## HOW IS IT DIFFERENT FROM CLASSIC PERLIN NOISE?

- It has a complexity of  $O(n^2)$  for  $n$  dimensions, compared to  $O(2^n)$  for Perlin noise
- Uses a simplex grid (triangles in 2D, tetrahedrons in 3D).
- Unlike Perlin noise, which can exhibit noticeable grid patterns, simplex noise is visually isotropic



## ALGORITHM

- **Coordinate Skewing:** Transforming the input coordinates to align with a skewed grid, which helps in determining the simplex that contains the point.
- **Simplicial Subdivision:** The space is divided into simplices [triangles, tetrahedrons]
- **Gradient vector selection and noise calculation by kernel summation.**

## WHY IS IT BETTER?

- Reduced computational complexity, hence suitable for higher dimensions.
- Minimized directional artifacts
- Smoother transitions

## WHAT ARE DIMENSIONAL ARTIFACTS?

Dimensional artifacts are unwanted patterns or distortions that arise when generating procedural noise, particularly in multi-dimensional spaces

## GAMES WHICH USE PERNIN AND SIMPLEX NOISE

## FOR RANDOM WORLD GENERATION:-

MINECRAFT, FACTORIO, TERRARIA

# CELLULAR AUTOMATA



## OVERVIEW

- Cells live on a 1D or multidimensional grid.
- Each cell has a state such as 0 or 1 or on and off.
- The on or off state of a cell depends on a set of rules considering the initial states of its neighbouring cells

## VISUAL STYLE:-

- Blocky, grid-like patterns.
- Example: Jagged cave walls or maze-like dungeons.

## APPLICATIONS:-

- Generate organic-looking structures like forests or coral reefs in games.
- Used in Parallel Processing, with each cell processing data individually

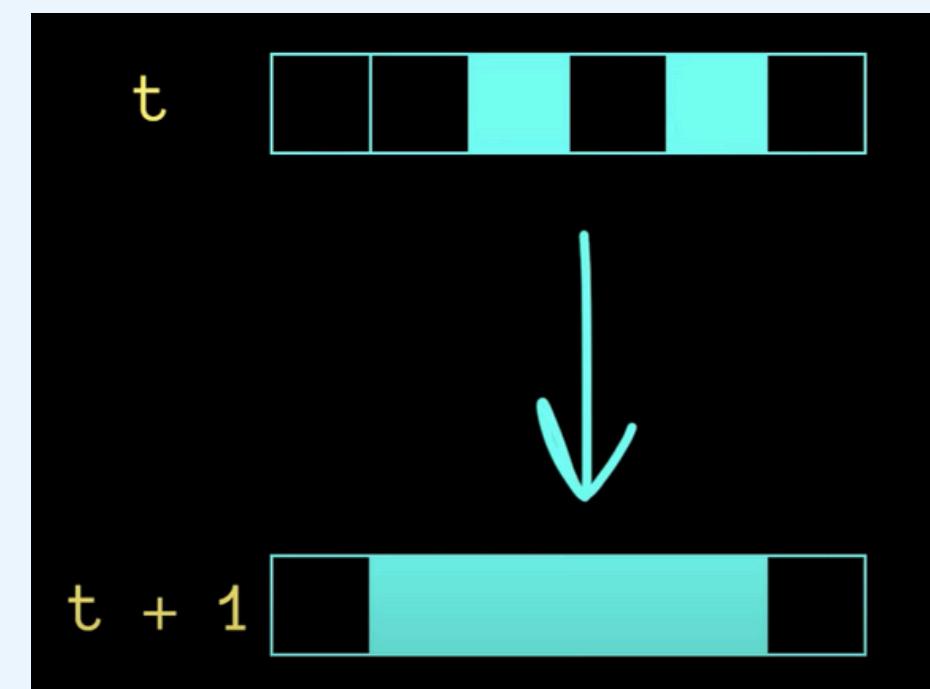
## EXAMPLE TO DEMONSTRATE THE ALGORITHM:-

Let us take RULE 110:-

- If Initial states of cell and neighbours are 1-> Final state =0
- If Initial states of cell and neighbours are 0-> Final state =0
- If cell and right neighbour is 0 but left neighbour is 1-> Final state=0
- Else ->1

INITIAL STATE

FINAL STATE



GAMES WHICH USE CELLULAR AUTOMATA FOR RANDOM WORLD GENERATION:-

GAME OF LIFE, DWARF FORTRESS

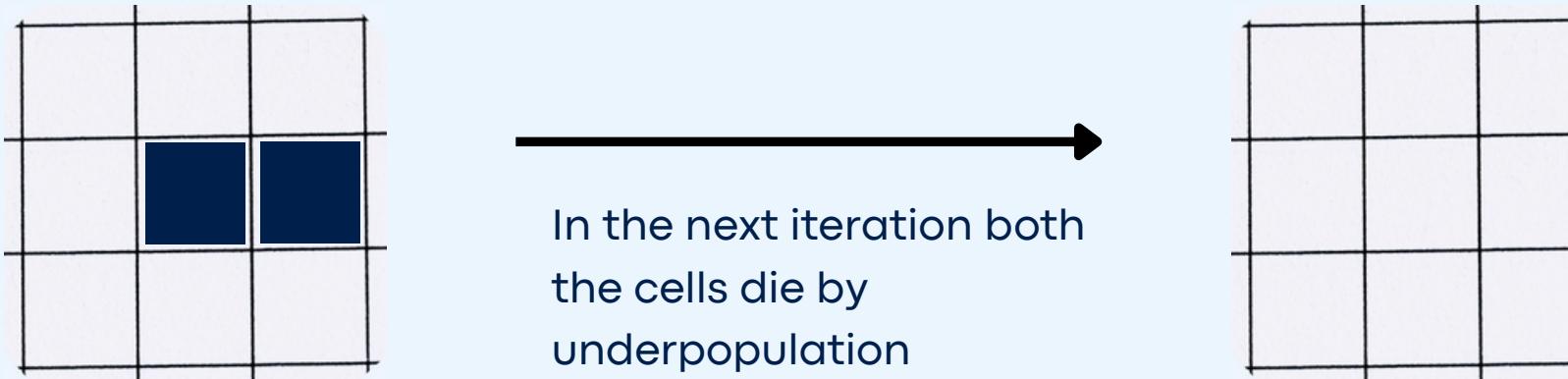


# THE GAME OF LIFE

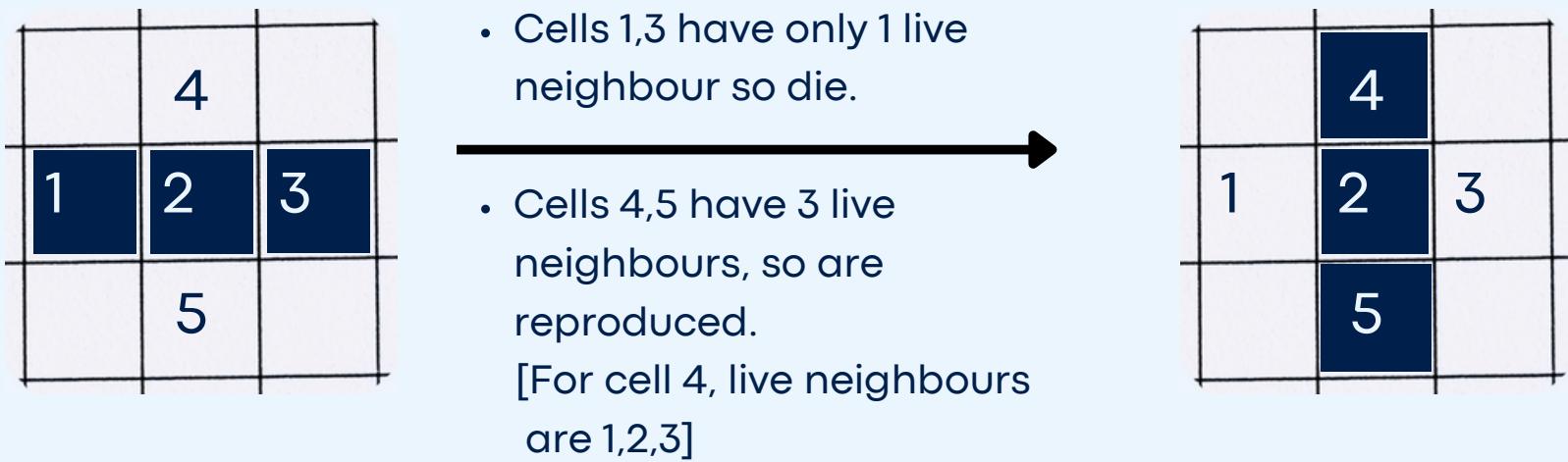
It is a “ZERO PLAYER GAME”, devised by John Horton Conway in 1970. It is built on 2D cellular automaton in which its evolution is determined by its initial state **only**

## EXAMPLE SIMULATION

1. Suppose there are initially 2 live cells



2. If initially there are 3 horizontal live cells



## RULES OF GAME OF LIFE:-

- Any live cell with fewer than two live neighbours dies (underpopulation).
- Any live cell with two or three live neighbours lives on to the next generation.
- Any live cell with more than three live neighbours dies (overpopulation).
- Any dead cell with exactly three live neighbours becomes a live cell (reproduction).

## Cave Generation Example:

- Initial Randomness: Start with a grid of randomly assigned "wall" and "floor" tiles.
- Smoothing: Apply a rule that makes a cell more likely to be a "wall" if it has many "wall" neighbors, and more likely to be a "floor" if it has many "floor" neighbors.
- Iteration: Repeatedly apply the rule to smooth out the random pattern and create cave-like structures.



## 1. Initialize the Grid with Random Noise:

```
import random

# Step 1: Initialize the grid with random noise
def fill_cell_grid_with_noise(width, height, chance_of_wall):
    grid = []
    for y in range(height): # Iterate over height first
        row = []
        for x in range(width): # Iterate over width
            row.append(random.random() >= chance_of_wall)
        grid.append(row)
    return grid
```

## 2. Count no. of neighbors of every cell to apply automata rules

```
# Step 2: Count the number of wall neighbors for a given cell
def count_wall_neighbors(cell_grid, x, y):
    width, height = len(cell_grid[0]), len(cell_grid)
    neighbors = 0
    for dy in [-1, 0, 1]:
        for dx in [-1, 0, 1]:
            if dx == 0 and dy == 0:
                continue
            x1, y1 = x + dx, y + dy
            if 0 <= x1 < width and 0 <= y1 < height and cell_grid[y1][x1]:
                neighbors += 1
    return neighbors
```

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Printing initial noise, where True values are printed with # and false ones with dot(.)

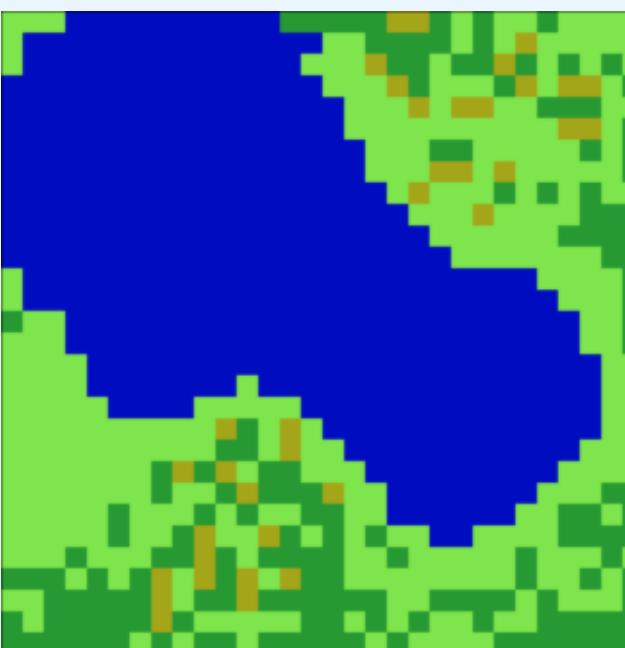
### Initial Grid:

```
#.....#...#....#####..
####...##...#.....#.#
.....#....###..###...#
#.#.#####...#.#.##...#
####.##.##.#.....#.#
#.#.#.#.##..#....#..
#....#.###..###.##..##
.....##.##.#######....#
.#..##..##.##....##...
#######..##.##...##...
```



### 3. Apply Cellular automata rules

```
# Step 3: Apply the cellular automata rules to smooth the grid
def apply_rules(cell_grid):
    width, height = len(cell_grid[0]), len(cell_grid)
    num_wall_neighbors=[]
    for y in range(height):
        row = []
        for x in range(width):
            row.append(count_wall_neighbors(cell_grid, x, y))
        num_wall_neighbors.append(row)
    for y in range(height):
        for x in range(width):
            neighbors = num_wall_neighbors[y][x]
            if cell_grid[y][x] and neighbors < 4:
                cell_grid[y][x] = False
            elif not cell_grid[y][x] and neighbors >= 5:
                cell_grid[y][x] = True
    return cell_grid
```



THESE MAPS CAN BE  
CONVERTED TO COLORED  
PIXELS MAPS BY  
APPLYING ALGORITHMS



FINAL CAVE LAYOUT PRINTED.  
AS SEEN FROM TOP(IN A MAP)

Final Grid:

```
.....##....  
.....####...  
..#...##....#####..  
.#####....#####..  
..#####....#####..  
....#####....#####..  
....#####....#####..  
....#####....#####..  
....##....#####..  
....##....#....  
....#####....  
....#####....  
...##...#####....  
....#####....
```

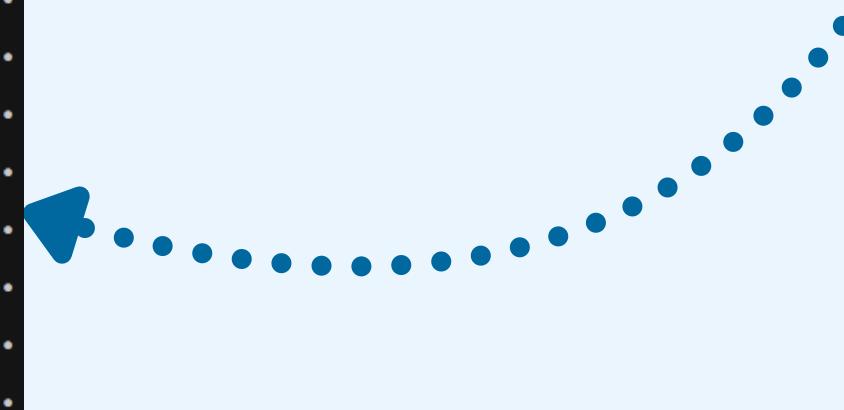
### 4. Writing the print statements with dimension values

```
# Example Usage:
width, height = 25, 15 # Grid dimensions
chance_of_wall = 0.45 # Probability of a cell starting as a wall

# Generate initial grid and apply smoothing rules
cell_grid = fill_cell_grid_with_noise(width, height, chance_of_wall)

# Apply rules multiple times to refine the cave structure
for _ in range(3): # Adjust iterations for better smoothing
    cell_grid = apply_rules(cell_grid)

# Display the generated cave grid
print("\nFinal Grid:")
for row in cell_grid:
    line=""
    for i in row:
        if i==True:
            line+="#"
        else:
            line+="."
    print(line)
```



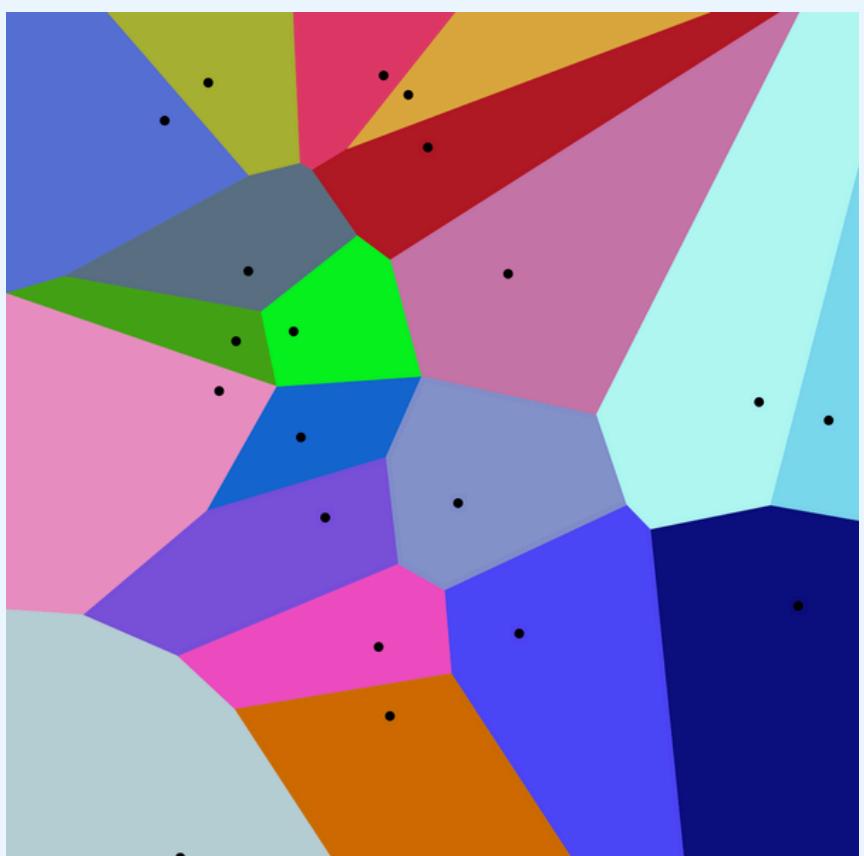


# VORONOI DIAGRAMS

Voronoi diagram is a partitioning of a plane into regions based on the distance to a set of given points. These points, known as seeds, sites, or generators, define the structure of the diagram.

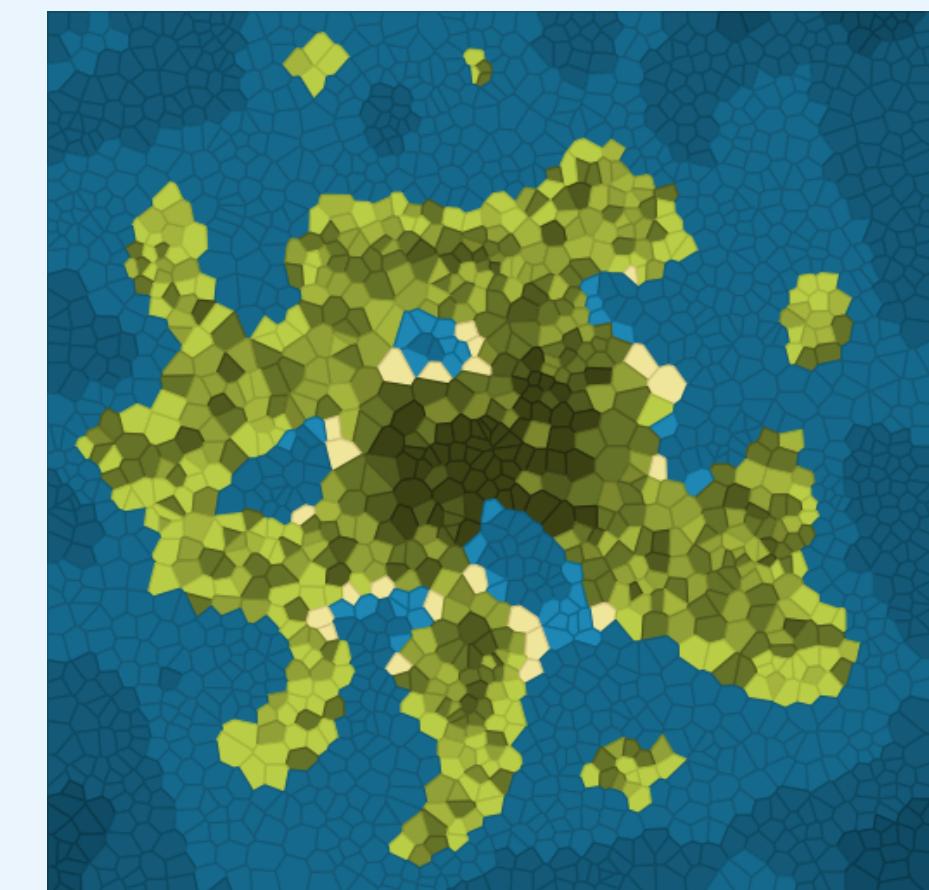
$$V(P_i) = \{x \in \mathbb{R}^2 \mid d(x, P_i) < d(x, P_j) \text{ for all } j \neq i\}$$

Each region consists of all points closer to one seed than to any other.



## VORONOI DIAGRAMS IN WORLD GENERATION:-

- Terrain Generation: Used to create diverse terrain types by assigning different features (e.g., mountains, forests) to each cell based on the seed point's properties.
- Natural patterns like river networks or geological formations
- Used in designing maps in games, with settlements, islands etc.



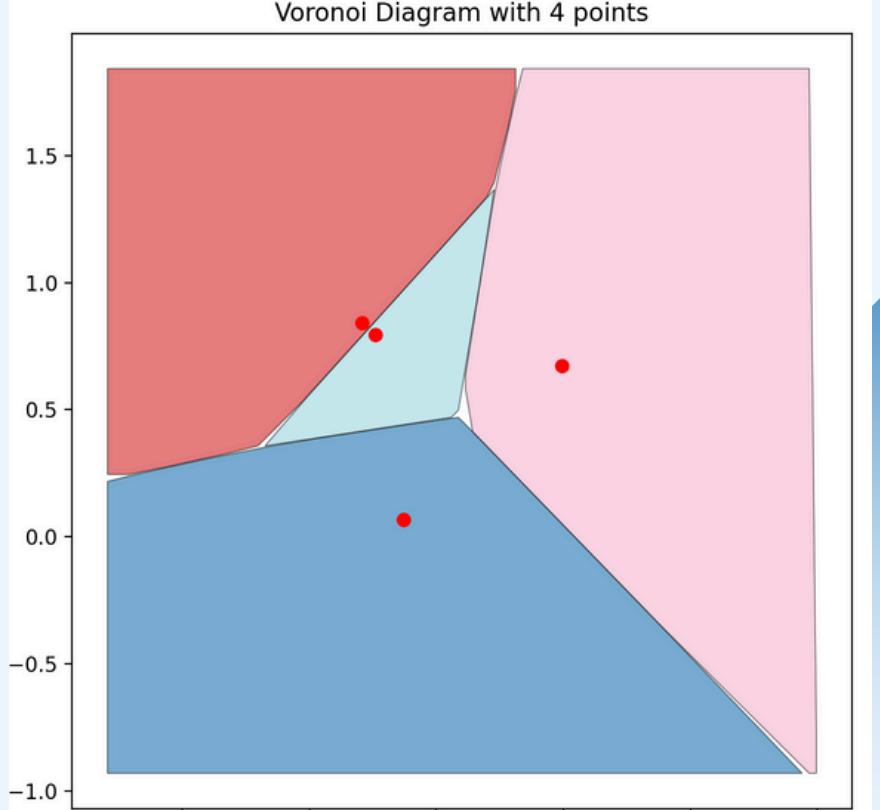
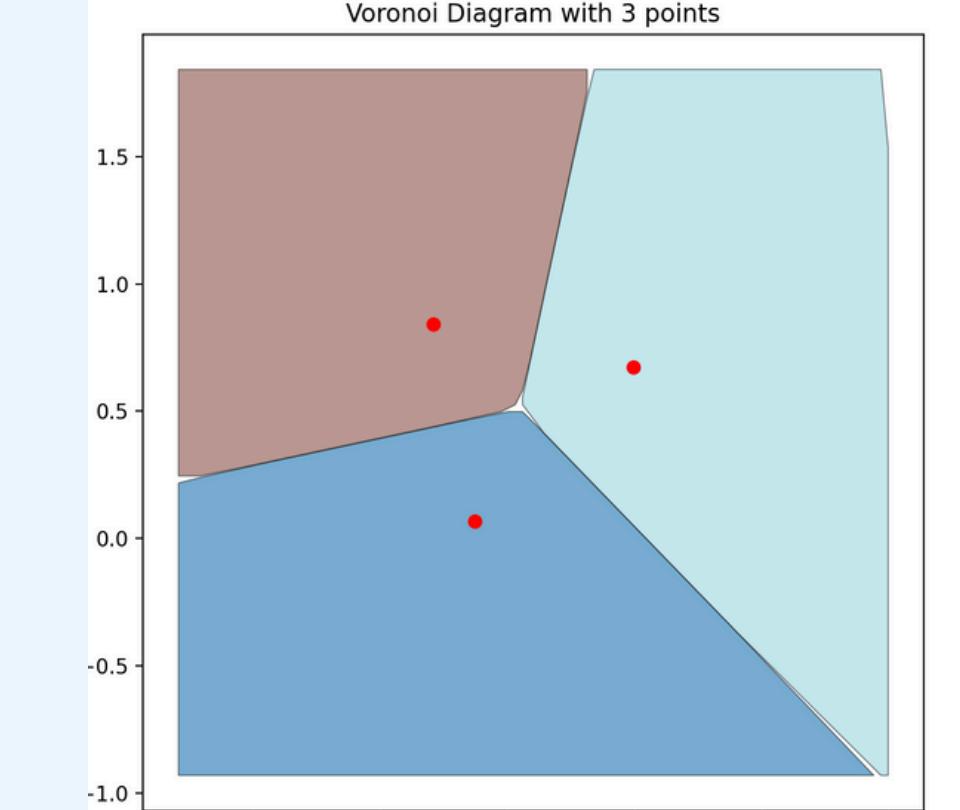
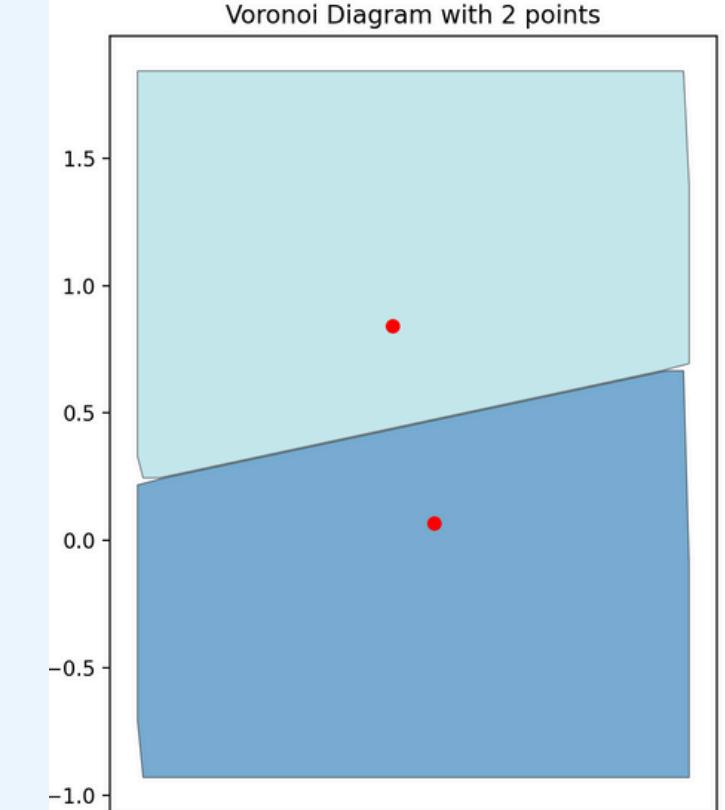
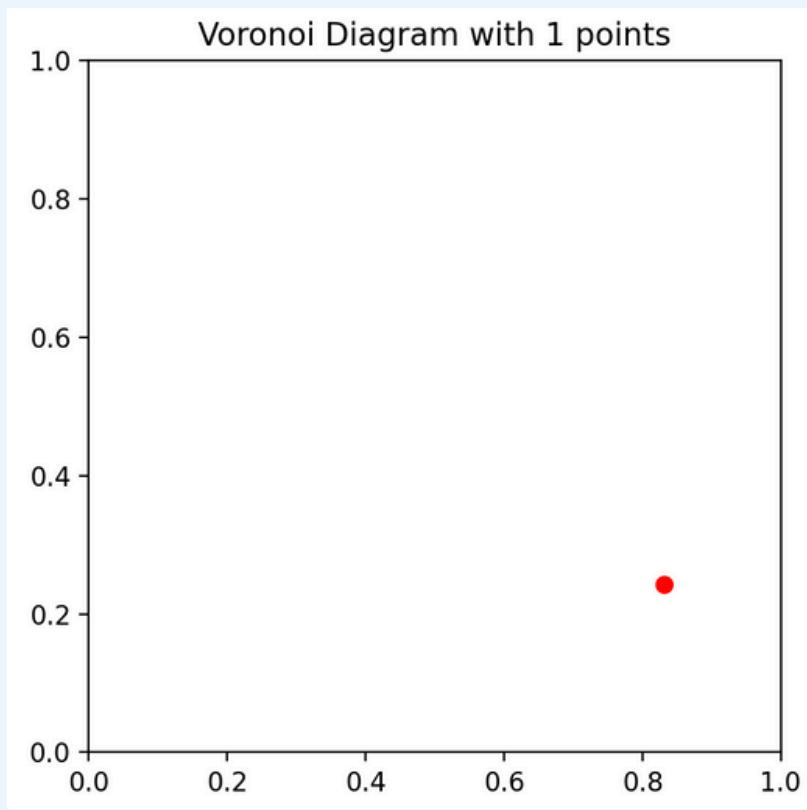
# Algorithm

## 1. Initialize an Empty Diagram

- Begin with an empty plane where no points exist.

## 2. Insert the First Point

- The first point inserted occupies the entire plane as its Voronoi cell.
- Since there are no other points, no edges or boundaries are needed.



## 3. Insert the Second Point

- Compute perpendicular bisector between the two points:
  - a. Find the midpoint between the two points.
  - b. Compute the perpendicular slope.
  - c. Extend the bisector infinitely in both directions.
- This bisector divides the plane into two cells, one for each point.

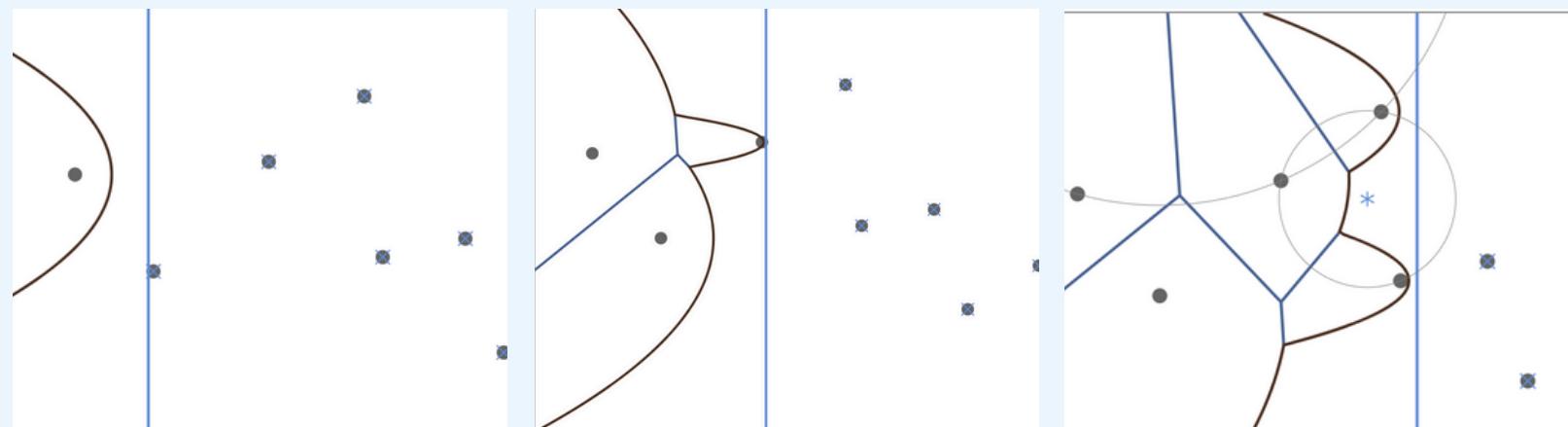
## 4. Insert the Third Point and Beyond

For each new point:

- Locate the nearest neighboring points.
- Compute the midpoint between the new point and each of its neighbors.
- Compute the perpendicular bisector.
- Extend the bisector until it intersects existing edges.
- Remove parts of old Voronoi cells that now belong to the new point.

### DRAWBACKS OF INCREMENTAL INSERTION

- High Cost of Updates:- Voronoi diagrams requires frequent updates to the structure as new sites are added.
- As the number of points increases, the computational overhead grows significantly.
- Special cases such as collinear points or closely spaced points can lead to numerical instability.



- Fortune's Algorithm efficiently constructs Voronoi diagrams in  $O(n \log n)$  time using a sweep-line approach.
- It processes points (site events) from top to bottom while maintaining a beach line of parabolic arcs.
- When arcs disappear (circle events), Voronoi vertices are created, and edges are extended.
- The algorithm completes when all edges are formed and extended to infinity.



## FORTUNE'S ALGORITHM

THUS, WE NEED A BETTER ALGORITHM

---->FORTUNE'S ALGORITHM

### Advantages of Fortune's Algorithm

- Fast: Runs in  $O(n \log n)$  time, making it more efficient than naive approaches.
- Handles Large Datasets: Can compute Voronoi diagrams for thousands of points efficiently.
- Robust: Works well for both finite and infinite Voronoi cells.

### VISUAL CHARACTERISTICS OF VORONOI DIAGRAMS

- Consist of polygonal regions with sharp edges
- Settlement patterns, river and road network and other sharp features.

# DIFFERENCES BETWEEN THE ALGORITHMS

FEATURE	PERLIN NOISE	SIMPLEX NOISE	CELLULAR AUTOMATA	VORONOI DIAGRAMS
<u>TYPE</u>	Gradient Noise	Gradient Noise	Rule-Based Grid Evolution	Space Partitioning
<u>VISUAL STYLE</u>	Smooth and continuous	Smoother and less aliasing	Discrete and abrupt changes	Sharp cell boundaries
<u>EFFICIENCY</u>	Moderate (computationally expensive in higher dimensions)	More efficient than Perlin Noise	Efficient for small grid sizes, can be slow for large worlds	Depends on chosen algorithm. Slow for large no. of seed pts.
<u>OPTIMIZATION TECHNIQUES</u>	<ul style="list-style-type: none"><li>Precompute noise in chunks</li><li>Use octaves for smoother transitions</li></ul>	Use lookup tables for faster computation	<ul style="list-style-type: none"><li>Use multi-threading</li><li>Apply early stopping</li></ul>	Optimize seed distribution to avoid clustering
 <u>USE CASES</u>	Terrain generation, clouds, textures	Terrain generation	Cave systems, map generation	Biomes, city layouts, natural formations



OFTEN THESE ALGORITHMS ARE USED TOGETHER TO OBTAIN THE DESIRED WORLD IN GAMES

#### TERRAIN GENERATION IN GAMES (MINECRAFT-STYLE WORLDS)

- Perlin/Simplex Noise: Used for generating base terrain elevation (hills, mountains, valleys).
- Voronoi Diagrams: Used for dividing the world into distinct areas like forests, deserts, etc.
- Cellular Automata: Used for cave generation, ensuring caves are connected and have natural-looking shapes.

#### CITY GENERATION (SIMCITY-STYLE GAMES)

- VORONOI DIAGRAMS: HELPS CREATE ROAD NETWORKS AND DISTRICT LAYOUTS.
- PERLIN NOISE: USED FOR ELEVATION CHANGES AND TERRAIN SHAPING.
- CELLULAR AUTOMATA: SIMULATES URBAN EXPANSION AND BUILDING PLACEMENT.

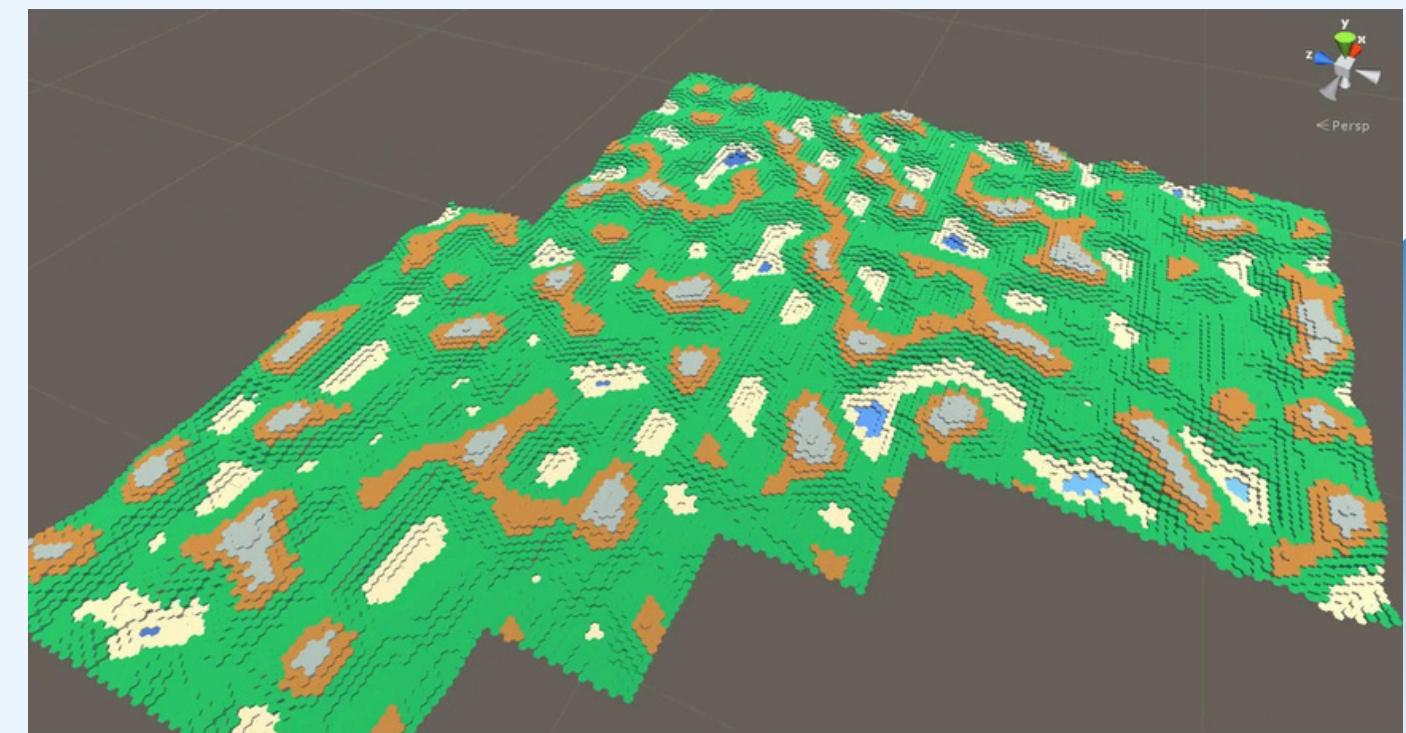
#### Dungeons & Rogue-like Maps

- Perlin Noise: Used for large-scale dungeon layouts with smooth pathways.
- Cellular Automata: Creates cave-like rooms with natural formations.
- Voronoi Diagrams: Used to ensure varied room shapes and sizes.



#### SUMMING-UP

Procedural world generation is a powerful tool that blends multiple algorithms to create rich, dynamic environments. Techniques like Perlin noise, simplex noise, Voronoi diagrams, and cellular automata each bring unique characteristics, and when used together, they enable more realistic and diverse landscapes.





# THANK YOU!