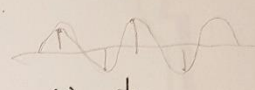


DSP First

Consider $x(t) = \cos(80\pi t + \frac{\pi}{3})$ 40 Hz

- ✓ ① Plot spectrum of $x(t)$ (10%)
- ✓ ② Plot spectrum of $x(t+0.01)$ (10%) 
- ③ Suppose $x[n]$ is obtained from sampling $x(t)$ at sampling rate f_s . Plot the spectrum of $x[n]$ between (15%) -3π and 3π for $f_s = 80$ Hz, 160 Hz and 800 Hz.
- ④ What are the three $\bar{x}(t)$ reconstructed from the three spectra in ③? (15%)
- ⑤ For $f_s = 32$ Hz, plot the spectrum of $x[n]$ in $(-3\pi, 3\pi)$. What is the $\bar{x}(t)$ reconstructed from spectrum of $x[n]$? (15%)
- ⑥ For $f_s = 50$ Hz, plot the spectrum of $x[n]$ in $(-3\pi, 3\pi)$. What is the $\bar{x}(t)$ reconstructed from spectrum of $x[n]$? (15%)

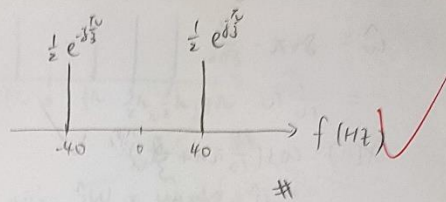
Consider $y[n] = 0.8 y[n] + \frac{1}{3} \{x[n+1] + x[n] + x[n-1]\}$

- ✓ ⑦ Is this a causal system? why? (10%)
- ⑧ Is this system a FIR? why? (10%)

$$x(t) = \cos(80\pi t + \frac{\pi}{3})$$

$$1. \quad x(t) = \frac{e^{j(80\pi t + \frac{\pi}{3})} + e^{-j(80\pi t + \frac{\pi}{3})}}{2}$$

$$= \frac{1}{2} e^{j\frac{\pi}{3}} e^{j80\pi t} + \frac{1}{2} e^{-j\frac{\pi}{3}} e^{-j80\pi t}$$



2. time shift

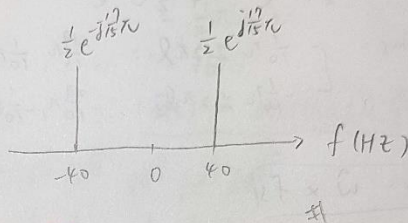
$$b_k = a_k \times e^{-j2\pi f_k z d}$$

$$x(t - zd)$$

$$zd = -0.01$$

$$\frac{1}{2} e^{j\frac{\pi}{3}} \times e^{-j2\pi(40)(-0.01)} = \frac{1}{2} e^{j\frac{17}{15}\pi}$$

$$\frac{1}{2} e^{-j\frac{\pi}{3}} \times e^{-j2\pi(40)(-0.01)} = \frac{1}{2} e^{-j\frac{17}{15}\pi}$$



$x(t)$ function?

$$3. \quad (1) \quad f_s = 80 \text{ Hz}$$

$$\hat{\omega} = \omega \cdot \frac{1}{f_s}$$

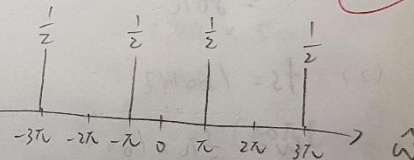
$$= 80\pi \cdot \frac{1}{80}$$

$$= \pi$$

$$\frac{1}{2} e^{j\frac{\pi}{3}} + \frac{1}{2} e^{-j\frac{\pi}{3}}$$

$$= \frac{1}{2}$$

$x(n)$ function?



$$\text{alias: } \begin{cases} \pi \pm 2\pi l & \dots, -\pi, \pi, 3\pi, \dots \\ -\pi \pm 2\pi l & \dots, -3\pi, -\pi, \pi, \dots \end{cases}$$

$$\text{alias: } \begin{cases} \pi \pm 2\pi l \\ -\pi \pm 2\pi l \end{cases}$$

phase?

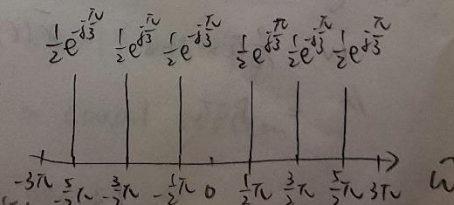
$$(2) \quad f_s = 160 \text{ Hz}$$

$$\hat{\omega} = 80\pi \cdot \frac{1}{160}$$

$$= \frac{1}{2}\pi$$

$$\therefore x(n) = \cos(\frac{1}{2}\pi n + \frac{\pi}{3})$$

$$= \frac{1}{2} e^{j\frac{\pi}{3}} e^{j\frac{1}{2}\pi n} + \frac{1}{2} e^{-j\frac{\pi}{3}} e^{-j\frac{1}{2}\pi n}$$



$$\text{alias: } \begin{cases} \frac{1}{2}\pi \pm 2\pi l & \dots, -\frac{3}{2}\pi, \frac{1}{2}\pi, \frac{5}{2}\pi, \dots \\ -\frac{1}{2}\pi \pm 2\pi l & \dots, -\frac{5}{2}\pi, -\frac{1}{2}\pi, \frac{3}{2}\pi, \dots \end{cases}$$

$$(3) f_s = 800 \text{ Hz}$$

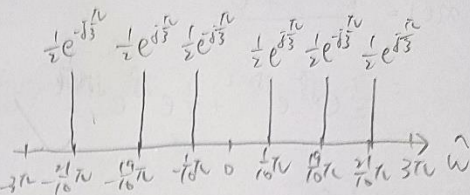
$$\hat{\omega} = 80\pi \cdot \frac{1}{800}$$

$$= \frac{1}{10}\pi$$

$$x(n) = \cos\left(\frac{1}{10}\pi n + \frac{\pi}{3}\right)$$

$$= \frac{1}{2}e^{j\frac{\pi}{10}n}e^{j\frac{\pi}{6}} + \frac{1}{2}e^{-j\frac{\pi}{10}n}e^{-j\frac{\pi}{6}}$$

$$\text{alias: } \begin{cases} \frac{1}{10}\pi \pm 2\pi k = \dots, -\frac{19}{10}\pi, \frac{1}{10}\pi, \frac{21}{10}\pi, \dots \\ -\frac{1}{10}\pi \pm 2\pi k = \dots, -\frac{21}{10}\pi, -\frac{1}{10}\pi, \frac{19}{10}\pi, \dots \end{cases}$$



4.

$$15 \quad \boxed{\omega = \hat{\omega} \times f_s}$$

$$(1) f_s = 80 \text{ Hz}$$

$$\therefore \bar{x}(t) = \cos(80\pi t)$$

$$\omega = \pi \times 80$$

$$= 80\pi$$

$$(2) f_s = 160 \text{ Hz}$$

$$\omega = \frac{1}{2}\pi \times 160$$

$$= 80\pi$$

$$\therefore \bar{x}(t) = \cos(80\pi t + \frac{\pi}{3})$$

$$(3) f_s = 800 \text{ Hz}$$

$$\omega = \frac{1}{10}\pi \times 800$$

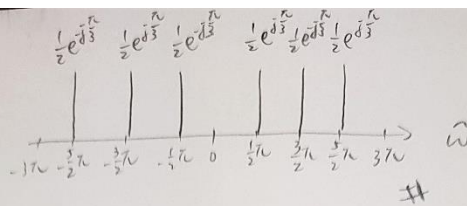
$$= 80\pi$$

$$\therefore \bar{x}(t) = \cos(80\pi t + \frac{\pi}{3})$$

5. $f_s = 32 \text{ Hz}$

15 $\hat{\omega} = \omega \cdot \frac{1}{f_s}$
 $= 80\pi \times \frac{1}{32}$
 $= \frac{5}{2}\pi$

alias: $\left[\begin{array}{l} \frac{5}{2}\pi \pm 2\pi k : \dots, \frac{3}{2}\pi, \frac{1}{2}\pi, \frac{5}{2}\pi, \dots \\ -\frac{5}{2}\pi \pm 2\pi k : \dots, -\frac{5}{2}\pi, -\frac{1}{2}\pi, \frac{3}{2}\pi, \dots \end{array} \right.$



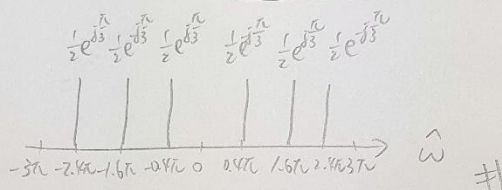
$\omega = \hat{\omega} \times f_s$
 $= \frac{1}{2}\pi \times 32$
 $= 16\pi$

$\therefore \bar{x}(t) = \cos(16\pi t + \frac{\pi}{3})$ #

6. 15 $f_s = 50 \text{ Hz}$

$\hat{\omega} = 80\pi \times \frac{1}{50}$
 $= 1.6\pi$

alias: $\left[\begin{array}{l} 1.6\pi \pm 2\pi k : \dots, -2.4\pi, -0.4\pi, 1.6\pi, \dots \\ -1.6\pi \pm 2\pi k : \dots, -1.6\pi, 0.4\pi, 2.4\pi, \dots \end{array} \right.$



$\omega = \hat{\omega} \times f_s$
 $= 0.4\pi \times 50$
 $= 20\pi$

$\therefore \bar{x}(t) = \cos(20\pi t - \frac{\pi}{3})$ #

$y[n] = 0.8y[n-1] + \frac{1}{3} \{ x[n+1] + x[n] + x[n-1] \}$

7. causal means to use only present or past signals, this system uses future signal ($x[n+1]$)

\therefore No, this is not a causal system. #

8. FIR: $y[n] = \sum_{k=0}^M b_k x[n-k]$

该系统無法歸類成上述形式 #

\therefore No, this system is not a FIR.