- Using a tapered window causes the height of the sidelobes to diminish, with a corresponding increase in the main lobe width resulting in a wider transition at the discontinuity
- Hann:

$$w[n] = 0.5 + 0.5\cos(\frac{\pi n}{M}), -M \le n \le M$$

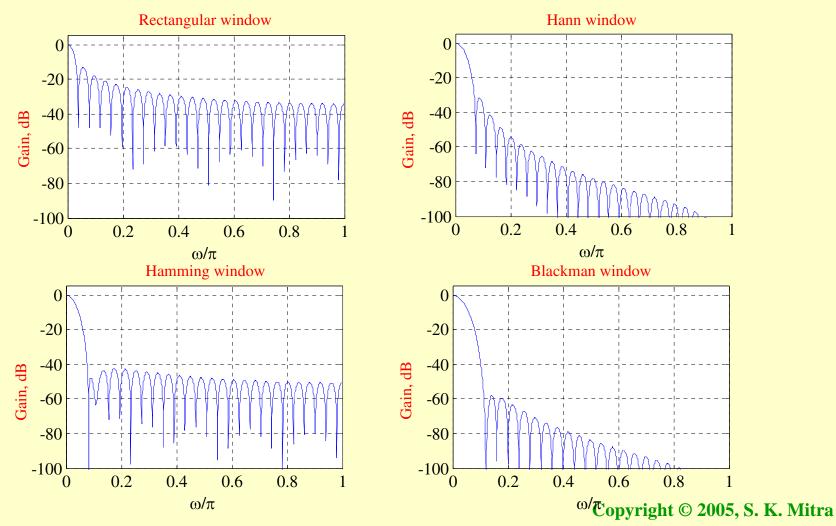
• Hamming:

$$w[n] = 0.54 + 0.46\cos(\frac{\pi n}{M}), -M \le n \le M$$

• Blackman:

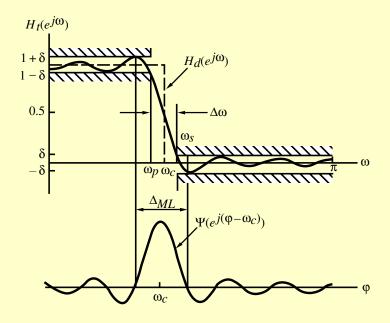
$$w[n] = 0.42 + 0.5\cos(\frac{\pi n}{M}) + 0.08\cos(\frac{2\pi n}{M}) - M \le n \le M$$
Convergebt © 2005, S. K.

• Plots of magnitudes of the DTFTs of these windows for M = 25 are shown below:



- Magnitude spectrum of each window characterized by a main lobe centered at ω = 0 followed by a series of sidelobes with decreasing amplitudes
- Parameters predicting the performance of a window in filter design are:
- Main lobe width
- Relative sidelobe level

- Main lobe width Δ_{ML} given by the distance between zero crossings on both sides of main lobe
- Relative sidelobe level $A_{s\ell}$ given by the difference in dB between amplitudes of largest sidelobe and main lobe



- Observe $H_t(e^{j(\omega_c + \Delta\omega)}) + H_t(e^{j(\omega_c \Delta\omega)}) \cong 1$
- Thus, $H_t(e^{j\omega_c}) \cong 0.5$
- Passband and stopband ripples are the same

• Distance between the locations of the maximum passband deviation and minimum stopband value $\cong \Delta_{ML}$

Width of transition band

$$\Delta \omega = \omega_s - \omega_p < \Delta_{ML}$$

- To ensure a fast transition from passband to stopband, window should have a very small main lobe width
- To reduce the passband and stopband ripple δ, the area under the sidelobes should be very small
- Unfortunately, these two requirements are contradictory

- In the case of rectangular, Hann, Hamming, and Blackman windows, the value of ripple does not depend on filter length or cutoff frequency ω_c , and is essentially constant
- In addition,

$$\Delta \omega \approx \frac{c}{M}$$

where *c* is a constant for most practical purposes

- Rectangular window $\Delta_{ML} = 4\pi/(2M+1)$ $A_{s\ell} = 13.3 \, \text{dB}, \ \alpha_s = 20.9 \, \text{dB}, \ \Delta\omega = 0.92\pi/M$
- Hann window $\Delta_{ML} = 8\pi/(2M + 1)$ $A_{s\ell} = 31.5 \, \text{dB}, \, \alpha_s = 43.9 \, \text{dB}, \, \Delta \omega = 3.11\pi/M$
- Hamming window $\Delta_{ML} = 8\pi/(2M+1)$ $A_{s\ell} = 42.7 \text{ dB}, \ \alpha_s = 54.5 \text{dB}, \ \Delta\omega = 3.32\pi/M$
- Blackman window $\Delta_{ML} = 12\pi/(2M + 1)$ $A_{s\ell} = 58.1 \text{ dB}, \alpha_s = 75.3 \text{ dB}, \Delta\omega = 5.56\pi/M$

- Filter Design Steps -
 - (1) **Set**

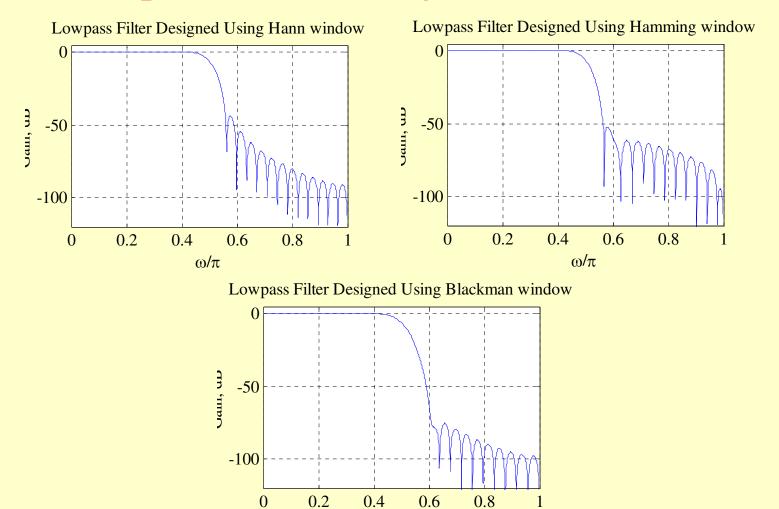
$$\omega_c = (\omega_p + \omega_s)/2$$

- (2) Choose window based on specified α_s
- (3) Estimate M using

$$\Delta \omega \approx \frac{c}{M}$$

FIR Filter Design Example

• Lowpass filter of length 51 and $\omega_c = \pi/2$



 ω/π

FIR Filter Design Example

- An increase in the main lobe width is associated with an increase in the width of the transition band
- A decrease in the sidelobe amplitude results in an increase in the stopband attenuation

• Dolph-Chebyshev Window -

$$w[n] = \frac{1}{2M+1} \left[\frac{1}{\gamma} + 2 \sum_{k=1}^{M} T_k (\beta \cos \frac{k}{2M+1}) \cos \frac{2nk\pi}{2M+1} \right],$$
$$-M \le n \le M$$

where
$$\gamma = \frac{\text{amplitude of sidelobe}}{\text{main lobe amplitude}}$$

$$\beta = \cosh(\frac{1}{2M}\cosh^{-1}\frac{1}{\gamma})$$

and

$$T_{\ell}(x) = \begin{cases} \cos(\ell \cos^{-1} x), & |x| \le 1\\ \cosh(\ell \cosh^{-1} x), & |x| > 1 \end{cases}$$

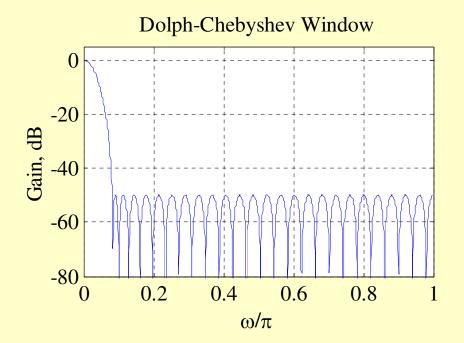
- Dolph-Chebyshev window can be designed with any specified relative sidelobe level while the main lobe width adjusted by choosing length appropriately
- Filter order is estimated using

$$N = \frac{2.056\alpha_s - 16.4}{2.85(\Delta\omega)}$$

where $\Delta\omega$ is the normalized transition bandwidth, e.g, for a lowpass filter

$$\Delta \omega = \omega_s - \omega_p$$

 Gain response of a Dolph-Chebyshev window of length 51 and relative sidelobe level of 50 dB is shown below



Properties of Dolph-Chebyshev window:

- All sidelobes are of equal height
- Stopband approximation error of filters designed have essentially equiripple behavior
- For a given window length, it has the smallest main lobe width compared to other windows resulting in filters with the smallest transition band

Kaiser Window -

$$w[n] = \frac{I_0\{\beta\sqrt{1-(n/M)^2}\}}{I_0(\beta)}, -M \le n \le M$$

where β is an adjustable parameter and $I_0(u)$ is the modified zeroth-order Bessel function of the first kind:

$$I_0(u) = 1 + \sum_{r=1}^{\infty} \left[\frac{(u/2)^r}{r!} \right]^2$$

- Note $I_0(u) > 0$ for u > 0• In practice $I_0(u) \cong 1 + \sum_{r=1}^{20} \left[\frac{(u/2)^r}{r!} \right]^2$

- β controls the minimum stopband attenuation of the windowed filter response
- β is estimated using

$$\beta = \begin{cases} 0.1102(\alpha_s - 8.7), & \text{for } \alpha_s > 50 \\ 0.5842(\alpha_s - 21)^{0.4} + 0.07886(\alpha_s - 21), & \text{for } 21 \le \alpha_s \le 50 \\ 0, & \text{for } \alpha_s < 21 \end{cases}$$

• Filter order is estimated using

$$N = \frac{\alpha_s - 8}{2.285(\Delta\omega)}$$

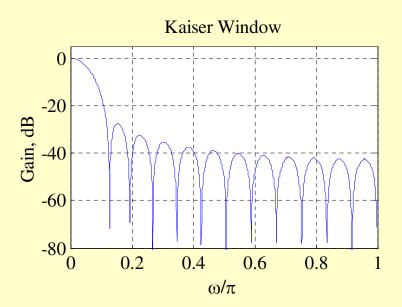
where $\Delta \omega$ is the normalized transition bandwidth

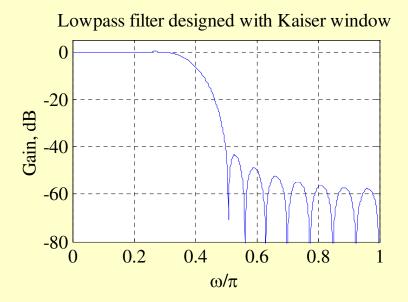
FIR Filter Design Example

- Specifications: $\omega_p = 0.3\pi$, $\omega_s = 0.5\pi$, $\alpha_s = 40 \, \mathrm{dB}$
- Thus $\omega_c = (\omega_p + \omega_s)/2 = 0.4\pi$ $\delta_s = 10^{-\alpha_s/20} = 0.01$ $\beta = 0.5842(19)^{0.4} + 0.07886 \times 19 = 3.3953$ $N = \frac{32}{2.285(0.2\pi)} = 22.2886$
- Choose N = 24 implying M = 12

FIR Filter Design Example

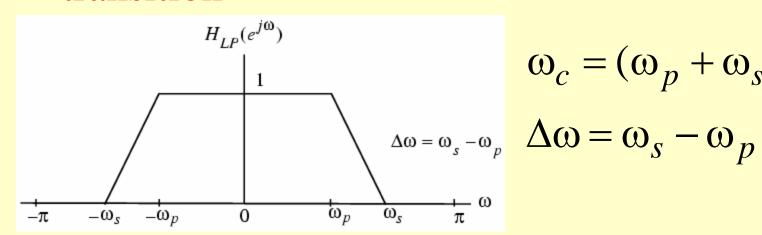
• Hence $h_t[n] = \frac{\sin(0.4\pi n)}{\pi n} \cdot w[n], -12 \le n \le 12$ where w[n] is the n-th coefficient of a length-25 Kaiser window with $\beta = 3.3953$





Impulse Responses of FIR Filters with a Smooth Transition

• First-order spline passband-to-stopband transition



$$\omega_c = (\omega_p + \omega_s)/2$$

$$\Delta \omega = \omega_S - \omega_D$$

$$h_{LP}[n] = \begin{cases} \omega_c / \pi, & n = 0\\ \frac{2\sin(\Delta \omega n / 2)}{\Delta \omega n} \cdot \frac{\sin(\omega_c n)}{\pi n} & |n| > 0 \end{cases}$$

Impulse Responses of FIR Filters with a Smooth Transition

• Pth-order spline passband-to-stopband transition

$$h_{LP}[n] = \begin{cases} \omega_c / \pi, & n = 0\\ \left(\frac{2\sin(\Delta\omega n/2P)}{\Delta\omega n/2P}\right)^P \cdot \frac{\sin(\omega_c n)}{\pi n} & |n| > 0 \end{cases}$$

Lowpass FIR Filter Design Example

Example

