

For example-

This is the verilog module corresponding to the peripheral:

```
// ***** MY PWM BLOCK ***** //
```

```
wire [15:0] gpio_15_0;
```

```
assign gpio_15_0 = {  
    gpio_15_out,  
    gpio_14_out,  
    io20_cell_out,  
    io19_cell_out,  
    io18_cell_out,  
    io17_cell_out,  
    io16_cell_out,  
    gpio_8_out,  
    gpio_7_out,  
    io13_cell_out,  
    io12_cell_out,  
    gpio_4_out,  
    io10_cell_out,  
    io9_cell_out,  
    io8_cell_out,  
    io7_cell_out  
};
```

```
wire [15:0] gpio_31_16;
```

```
assign gpio_31_16 = {  
    gpio_31_out,  
    gpio_30_out,  
    gpio_29_out,  
    gpio_28_out,  
    gpio_27_out,  
    gpio_26_out,  
    gpio_25_out,  
    gpio_24_out,  
    gpio_23_out,  
    gpio_22_out,  
    gpio_21_out,  
    gpio_20_out,  
    gpio_19_out,  
    gpio_18_out,  
    gpio_17_out,  
    gpio_16_out  
};
```

```
mypwm pwm_gen(
```

```

        .clk(core_clk),
        .max_count(gpio_15_0),
        .cmp_val(gpio_31_16),
        .vout(VOUT)
    );

```

C Code:

```

#include "platform.h"
#include "utils.h"
#include "gpio.h"

```

```

void togglegpio()
{
    //Assumption 1 ---> output, 0 ---> input
    write_word(GPIO_DIRECTION_CNTRL_REG, 0xFFFFEFFF); //GPIO0 to 23-> output

    while (1) {

        write_word(GPIO_DATA_REG, 0x08001000);
        delay_loop(1000, 5000);
        write_word(GPIO_DATA_REG, 0xFFFFFFFF);
        delay_loop(1000, 5000);
    }
}

void main()
{
    togglegpio();
    return 0;
}

```

platform.h:

```

/*!General Purpose Input / Output */
#define GPIO_START 0x00040100 //GPIO Start Address */
#define GPIO_OFFSET 0x08 /*!Generic offset used to access GPIO registers*/
#define PLIC_GPIO_OFFSET 6

```

gpio.h:

```

#define GPIO_DIRECTION_CNTRL_REG (uint32_t*) (GPIO_START + (0 * GPIO_OFFSET ))
#define GPIO_DATA_REG (uint32_t*) (GPIO_START + (1 * GPIO_OFFSET ))

```