



Evolution/Development of Operating Systems





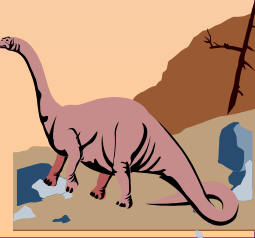
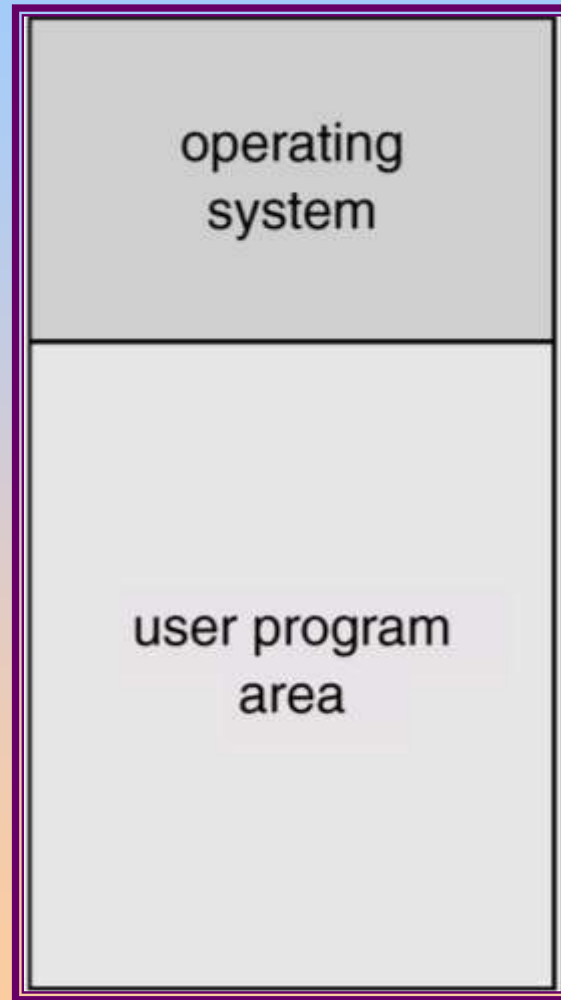
Simple Batch Systems

- Hire an operator
- User \neq operator
- Add a card reader
- Reduce setup time by batching similar jobs
- Automatic job sequencing – automatically transfers control from one job to another. First rudimentary operating system.
- Resident monitor
 - ☞ initial control in monitor
 - ☞ control transfers to job
 - ☞ when job completes control transfers back to monitor





Memory Layout for a Simple Batch System





Control Cards

■ Problems

1. How does the monitor know about the nature of the job (e.g., Fortran versus Assembly) or which program to execute?
2. How does the monitor distinguish
 - (a) job from job?
 - (b) data from program?

■ Solution

- ☞ Introduce control cards





Control Cards (Cont.)

- Parts of resident monitor
 - ☞ Control card interpreter – responsible for reading and carrying out instructions on the cards.
 - ☞ Loader – loads systems programs and applications programs into memory.
 - ☞ Device drivers – know special characteristics and properties for each of the system's I/O devices.
- Problem: Slow Performance – I/O and CPU could not overlap; card reader very slow.
- Solution: Off-line operation – speed up computation by loading jobs into memory from tapes and card reading and line printing done off-line.





Spooling

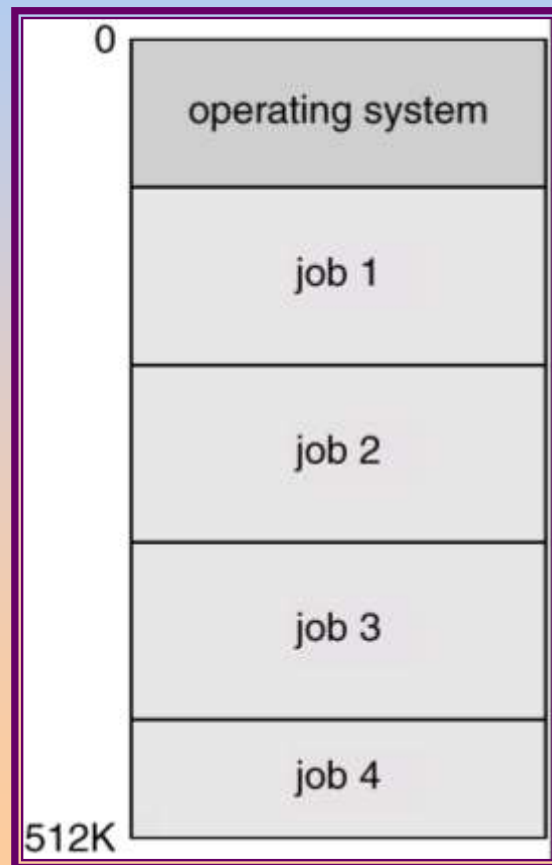
- Overlap I/O of one job with computation of another job. While executing one job, the OS:
 - ☞ Reads next job from card reader into a storage area on the disk (job queue).
 - ☞ Outputs printout of previous job from disk to printer.
- *Job pool* – data structure that allows the OS to select which job to run next in order to increase CPU utilization.
- Acronym for Simultaneous Peripheral Operation On-line.





Multiprogrammed Batch Systems

- Several jobs are kept in main memory at the same time, and the CPU is multiplexed among them.
- *Job pool* – data structure that allows the OS to select which job to run next in order to increase CPU utilization.





Multiprogramming

- Multiprogramming: In-order to increase CPU utilization by organizing jobs such that CPU has always one job to execute.
- CPU burst time & I/O burst time
- CPU does not sit idle, it is executing one or the other job at any given time.
- Job pool to RAM (Job Scheduling)





OS Features Needed for Multiprogramming

- Memory management – the system must allocate the memory to several jobs.
- CPU scheduling – the system must choose among several jobs ready to run.
- Allocation of devices.





Time-Sharing Systems–Interactive Computing

- Multiple jobs are executed by CPU switching b/w them.
- Little CPU time is given to each user.
- Switches occur so frequently that each user is given the impression that he/she owns the system.
- But actually, 1 computer is being shared among multiple users.





Desktop Systems

- *Personal computers* – computer system dedicated to a single user.
- I/O devices – keyboards, mouse, display screens, printers.
- User convenience and responsiveness.
- Often individuals have sole use of computer and do not need advanced CPU utilization or protection features.
- May run several different types of operating systems (Windows, MacOS, UNIX, Linux)





Parallel Systems

- Single processor systems
- Multiprocessor systems with more than one CPU in close communication.
- *Tightly coupled system* – processors share memory and a clock; communication usually takes place through the shared memory.
- Advantages of parallel systems:
 - ☞ Increased *throughput*
 - ☞ Economical
 - ☞ Increased reliability
 - 📄 graceful degradation
 - 📄 fault-tolerant systems





Parallel Systems (Cont.)

■ *Symmetric multiprocessing (SMP)*

- ☞ Each processor runs an identical copy of the operating system.
- ☞ Many processes can run at once without performance deterioration.
- ☞ Most modern operating systems support SMP
- ☞ Jobs & resources are shared dynamically among various processes.
- ☞ Peer to peer computing

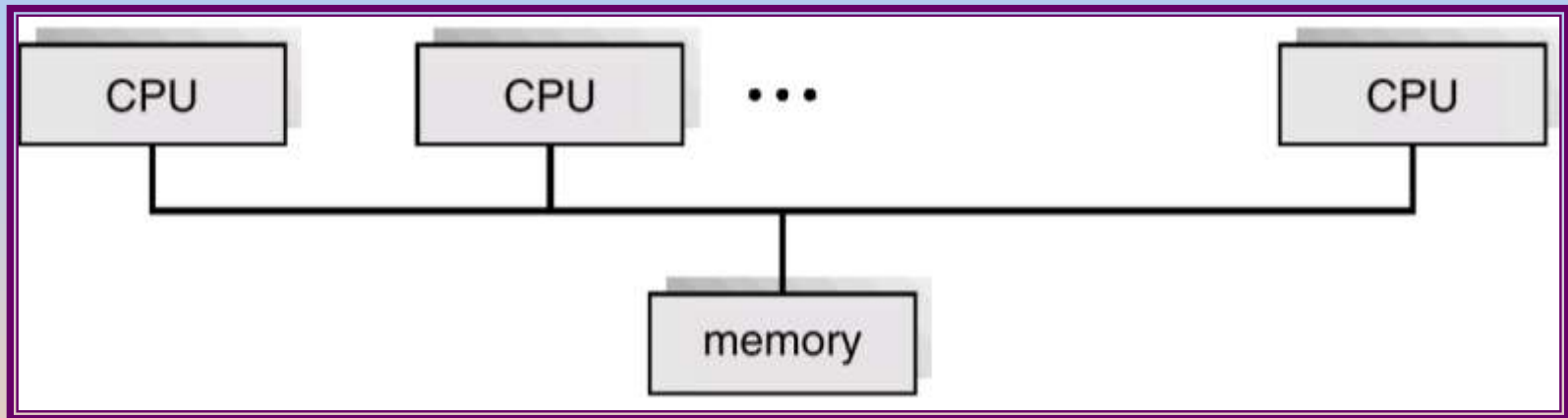
■ *Asymmetric multiprocessing*

- ☞ Each processor is assigned a specific task; master processor schedules and allocates work to slave processors.
- ☞ Master-slave or client-server architecture
- ☞ More common in extremely large systems





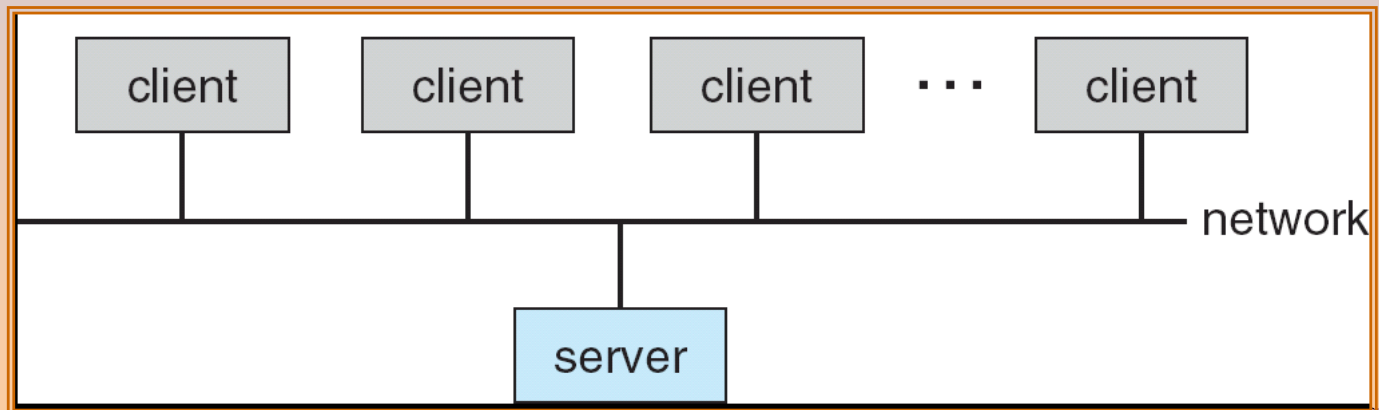
Symmetric Multiprocessing Architecture



Computing Environments

Client-Server Computing

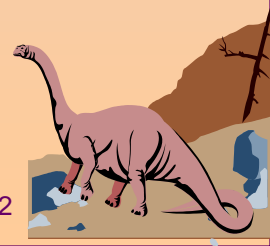
- Many systems now **servers**, responding to requests generated by **clients**
 - ▶ **Compute-server** provides an interface to client to request services (i.e. database)
 - ▶ **File-server** provides interface for clients to store and retrieve files





Peer-to-Peer Computing

- Another model of distributed system
- P2P does not distinguish clients and servers
 - ☞ Instead all nodes are considered peers
 - ☞ May each act as client, server or both





Distributed Systems

- Collection of physically separate, heterogeneous computer systems that are networked to provide the users with access to various resources.
- Distribute the computation among several physical processors.
- *Loosely coupled system* – each processor has its own local memory; processors communicate with one another through various communications lines, such as high-speed buses or telephone lines.
- Wired Network: Cu wires, fibre strands
- Wireless Network: Satellites, Radio frequency, Bluetooth and Wi-Fi.





Distributed Systems (cont)

- Advantages of distributed systems.
 - ☞ Resource Sharing
 - ☞ Computation speed up – load sharing
 - ☞ Reliability
 - ☞ Communication
- Requires networking infrastructure
- Local area networks (LAN) or Wide area networks (WAN) or Metropolitan Area Network (MAN)
- May be either client-server or peer-to-peer systems.





Real-Time Systems

- Used when there are rigid time requirements on the operation of a processor or flow of data.
- Often used as a control device in a dedicated application such as controlling scientific experiments, medical imaging systems, industrial control systems, weapon systems, home appliance controllers and some display systems.
- Well-defined fixed-time constraints.
- Processing must be done within the defined constraints or the system will fail.
- Real-Time systems may be either *hard* or *soft* real-time.





Real-Time Systems (Cont.)

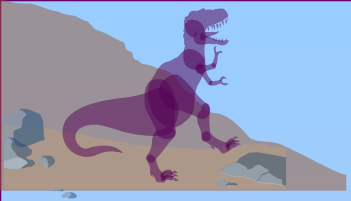
■ Hard real-time:

- ☞ Guarantees that critical tasks should complete on time.
- ☞ All delays in the system be bounded
- ☞ Strict deadlines
- ☞ Conflicts with time-sharing systems, not supported by general-purpose operating systems.

■ Soft real-time

- ☞ Less restrictive than hard RT systems
- ☞ Critical RT tasks get priority over other tasks & retain that priority until that task is complete.
- ☞ Bcoz of their lack of deadline support, they have limited utility in industrial control & robotics
- ☞ Useful in applications like multimedia, virtual reality, scientific projects like undersea exploration & planetary rovers.





Handheld Systems

- Personal Digital Assistants (PDAs)
- Cellular telephones
- Issues:
 - ☞ Limited memory
 - ☞ Slow processors
 - ☞ Small display screens.

