

Javier Irizarry-Delgado

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🌐 github.com/Shxl2

Education

University of Florida <i>BS in Electrical Engineering</i> <ul style="list-style-type: none">◦ GPA: 4.0◦ Benacquisto Scholarship◦ STEPUP 30 Program Scholar◦ Relevant Coursework: Calculus 3, Physics 2	<i>Fall 2024 – Spring 2028</i>
American Heritage Schools – Broward Campus <ul style="list-style-type: none">◦ Engineering and Computer Science track	<i>Fall 2020 – Spring 2024</i>

Skills and Abilities

Programming Languages: Java, C++, Python, LaTeX
3D Modeling: Onshape, Fusion 360, Inventor
Languages: English, Spanish


Experience

Robotics Mentor <i>P.K. Yonge Developmental Research School</i> <ul style="list-style-type: none">◦ FIRST Robotics Competition Team 4118: Roaring Riptide◦ Taught high school students how to write robot programs in Java, and wire FRC robots	<i>Gainesville, FL</i> <i>Fall 2024 -</i>
Robotics Summer Camp Counselor <i>American Heritage Schools - Broward Campus</i> <ul style="list-style-type: none">◦ Taught campers how to code in Java, and wire motors, sensors, and microcontrollers to summer camp robots, for an in-house robotics competition. Fixed electrical issues during competitions.	<i>Plantation, FL</i> <i>Summer 2021 - 2024</i>

Extracurricular Activities

Machine Intelligence Lab - Member <i>University of Florida</i> <ul style="list-style-type: none">◦ Wrote robot programs in robot operating system (ROS) for the Maritime RobotX challenge.	<i>Gainesville, FL</i> <i>Fall 2024 -</i>
Robotics - Electrical Director <i>American Heritage Schools - Broward Campus</i> <ul style="list-style-type: none">◦ FIRST Robotics Competition Team 2383◦ Programmed the robot (Java and C++) using a finite state machine, and wired the components of the robot (motors, motor controllers, microcontrollers, sensors). Fixed electrical issues during competition.	<i>Plantation, FL</i> <i>Fall 2022 - Spring 2024</i>

Projects

Simultaneous Localization and Mapping (SLAM) for FIRST Robotics Competition Robots <ul style="list-style-type: none">◦ In a team of two, developed a program for SLAM in Java using April tags as landmarks, which ran on an external coprocessor (Beelink mini pc).◦ Developed a program to time-sync vision measurements.	github.com/Ninjineers-2383/SLAM-Server 
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