

## Machine Learning Worksheet 12

### Variational Inference

---

#### 1 KL divergence

**Problem 1:** Compute the KL divergence between two Gaussian distributions  $\mathcal{N}(\boldsymbol{\mu}_1, \boldsymbol{\Sigma}_1)$  and  $\mathcal{N}(\boldsymbol{\mu}_2, \boldsymbol{\Sigma}_2)$  with diagonal covariance matrices.

*Hint: If you use the facts you know about normal distribution, you can save yourself a lot of work before taking the straightforward path.*

**Problem 2:** Consider that  $p(\mathbf{x})$  is some arbitrary fixed distribution that we wish to approximate using an isotropic Gaussian distribution  $q(\mathbf{x}) = \mathcal{N}(\mathbf{x} \mid \boldsymbol{\mu}, \mathbf{I})$  (covariance matrix is identity matrix).

By writing down the KL divergence  $\mathbb{KL}(p\|q)$  and then differentiating w.r.t.  $\boldsymbol{\mu}$ , show that the optimal setting of the parameter is

$$\boldsymbol{\mu}^* = \arg \min_{\boldsymbol{\mu}} \mathbb{KL}(p\|q) = \mathbb{E}_p[\mathbf{x}]$$

#### 2 Mean-field variational inference

Consider a very simple probabilistic model with a 2-D latent variable  $\mathbf{z} \in \mathbb{R}^2$  and an observed variable  $x \in \mathbb{R}$ .

The prior over the latent variable is

$$p(\mathbf{z}) = \mathcal{N}(\mathbf{z} \mid \mathbf{0}, \mathbf{I}) = \mathcal{N}(z_1 \mid 0, 1) \cdot \mathcal{N}(z_2 \mid 0, 1),$$

and the likelihood is

$$p(x \mid \mathbf{z}) = \mathcal{N}(x \mid \boldsymbol{\theta}^T \mathbf{z}, 1),$$

where  $\boldsymbol{\theta} \in \mathbb{R}^2$  is a known and fixed parameter.

**Problem 3:** Write down the true posterior distribution  $p(\mathbf{z} \mid x)$ .

Can the posterior be factorized over  $z_1$  and  $z_2$ ? (i.e. can it be expressed as  $p(z_1 \mid x)p(z_2 \mid x)$ ?)

**Problem 4:** We approximate the true posterior using a mean-field variational distribution

$$q(\mathbf{z}) = q_1(z_1)q_2(z_2) = \mathcal{N}(z_1 \mid m_1, s_1^2) \cdot \mathcal{N}(z_2 \mid m_2, s_2^2)$$

Your task is to derive the optimal updates for  $q_1$  and  $q_2$ .

Is  $q(\mathbf{z})$  able to match the true posterior  $p(\mathbf{z} \mid x)$ ?