ReadMe

File

Folder	Presentation
/code	含 `probot_gazebo` ROS Package; 其中/src 下包含实验1-5&大作业代码
/img	文档内所需图片
/vedio	验证视频
/doc	md文档

Run

```
1   catkin_make
```

Lab 1 正逆运动学

```
1   roslaunch probot_gazebo probot_anno_position_control_bringup.launch
2   roslaunch probot_gazebo invert.launch
```

Lab 3 Jacobi速度传递

```
1   roslaunch probot_gazebo probot_anno_velocity_control_ring_bringup.launch
2   roslaunch probot_gazebo jacobi.launch
```

Lab 4 轨迹规划

```
1   roslaunch probot_gazebo probot_anno_velocity_control_ring_bringup.launch
2   roslaunch probot_gazebo trajectory.launch
```

Lab 5 定点转动

```
1   roslaunch probot_gazebo probot_anno_velocity_control_ring_bringup.launch
2   roslaunch probot_gazebo fixpoint.launch
```

大作业 Ring

```
1   roslaunch probot_gazebo probot_anno_velocity_control_ring_bringup.launch
2   roslaunch probot_gazebo ring.launch
```

Depends

Eigen 3.3.7