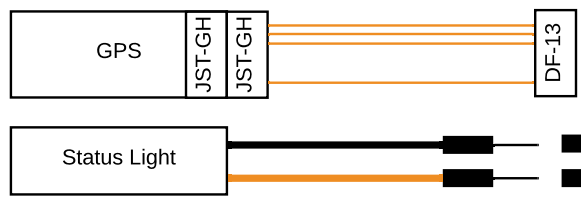


Revision	Notes
1	Initial public releas
2	Added Pixhawk telemetry and Jetson Nano connection
3	Fixed port and starboard ESC pin assignments
4	Added note for Jetson Nano to use barrel connector power.

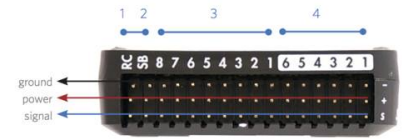
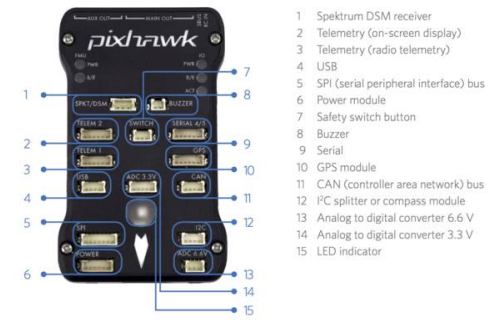


Note:
For Pixhawk 1: only 4 pins are used because I2C line are not required

Part Name	Pixhawk Connection
GPS	10 - GPS Module
Power Sense Module	6 - Power Module
Jetson GPIO (pins 4,6,8,10 - red wire pin 4)	2 - Telem 2

Part Name	Pixhawk Connection
USB to Jetson	Micro-USB port

Part Name	Pixhawk Connection
Port ESC	3 - Main Output 2
Starboard ESC	3 - Main Output 1
Servo Rail Power	2 - S.Bus Output



<https://ardupilot.org/copter/docs/common-pixhawk-overview.html>