Hands on

Deep Learning

VVV17 Winter School on Humanoid Robot Programming
Santa Margherita Ligure
Feb. 7 2017

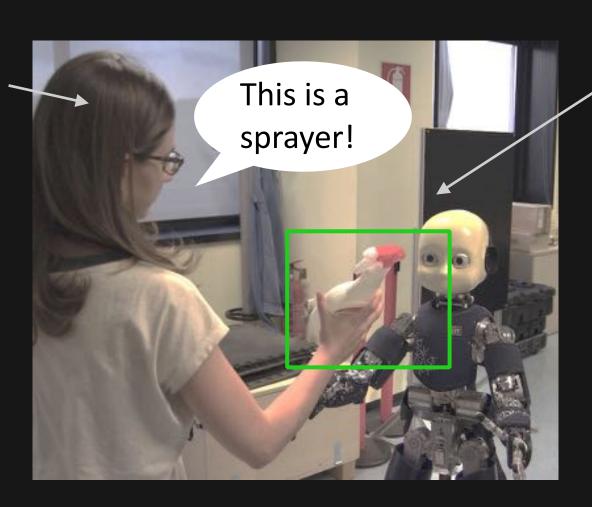
Outline

1. The iCubWorld Project

2. Deep Learning using Caffe

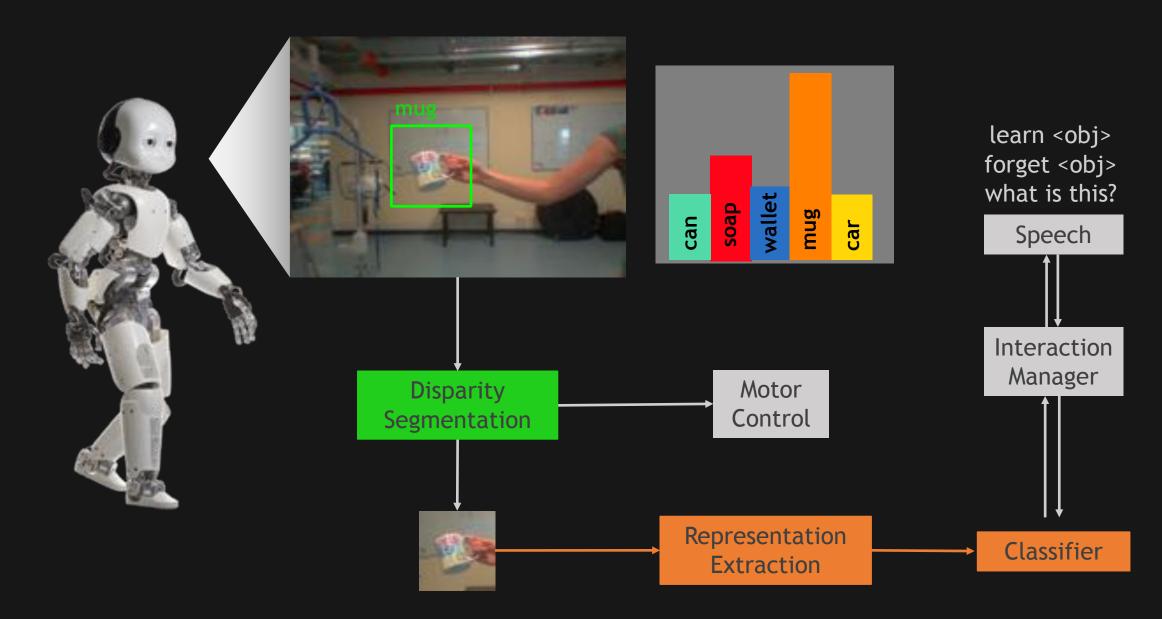
Teaching iCub to See: HRI Framework

Verbal instructions of a "teacher"



iCub learning the object

On the Fly Object Recognition



The Need for an iCubWorld Dataset

What is the Visual World of a Robot?

not so many object/instances



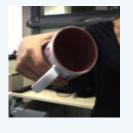
http://image-net.org/



The Need for an iCubWorld Dataset

What is the Visual World of a Robot?

- not so many object/instances
- lots of viewpoint changes















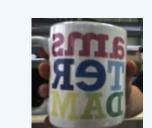




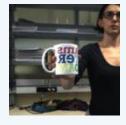


















The Need for an iCubWorld Dataset

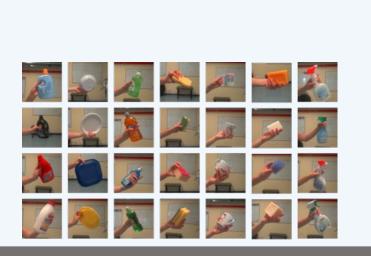
What is the Visual World of a Robot?

- not so many object/instances
- lots of viewpoint changes
- ...
- uninformative background
- self supervised
- ...

→ Different from usual vision tasks!!

iCubWorld Datasets

https://robotology.github.io/iCubWorld/

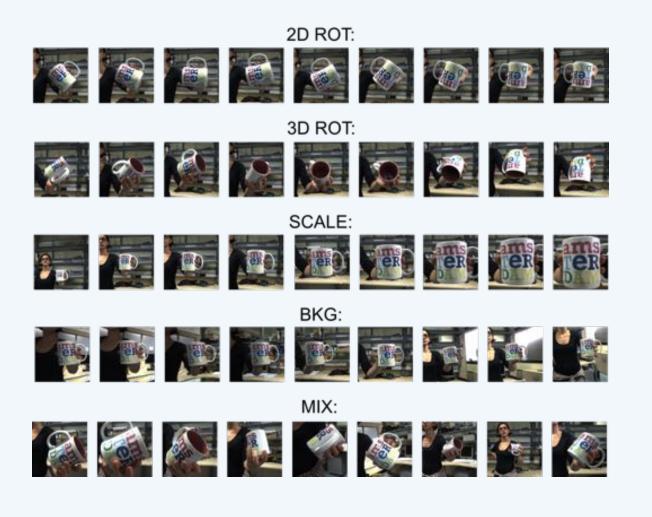


2012-13 1st and 2nd iCW Releases 2014-15 iCubWorld28 2016 iCubWorld - Transformations

Latest Release: iCubWorld - Transformations



Latest Release: iCubWorld - Transformations

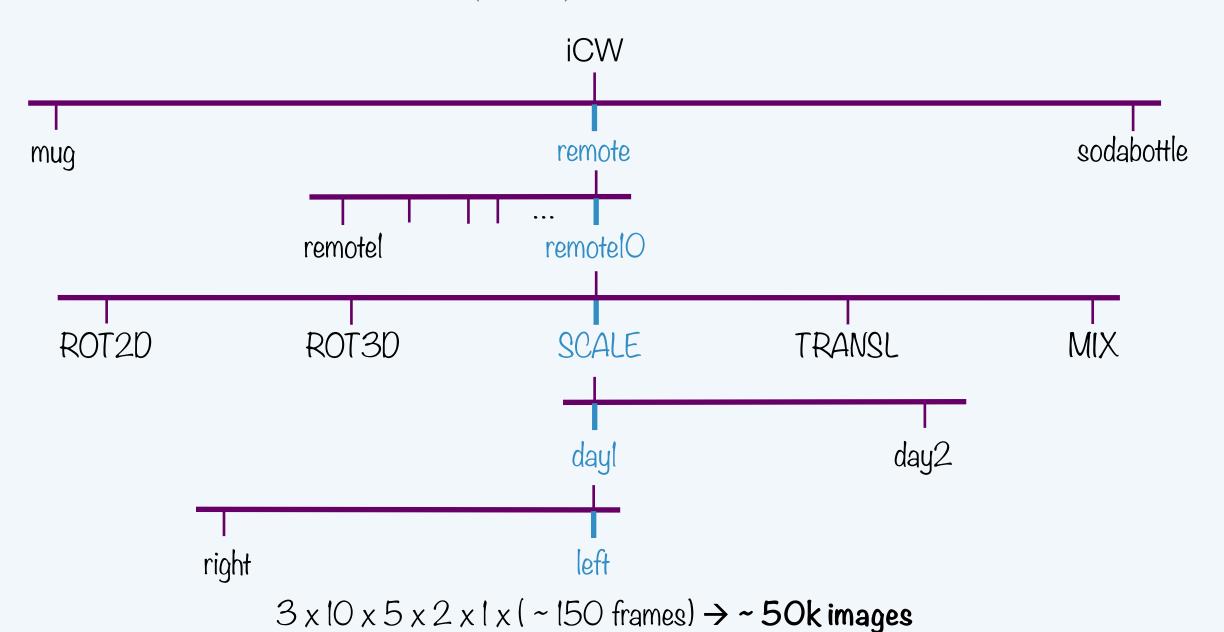


20 categories 10 object instances per category

10 sequences per object:
5 transformations
2 days

stereo sequences

iCubWorld (iCW): subset for the labs



Outline

1. The iCubWorld Project

2. Deep Learning using Caffe

Caffe (Convolutional Architecture for Fast Feature Embedding)

C++ framework command-line, Python and Matlab interfaces

to define and train (Convolutional) Neural Networks (on CPUs/CUDA GPUs)

Web: http://caffe.berkeleyvision.org/

GitHub: https://github.com/BVLC/caffe

Community: <u>Caffe Users - Google Groups</u>

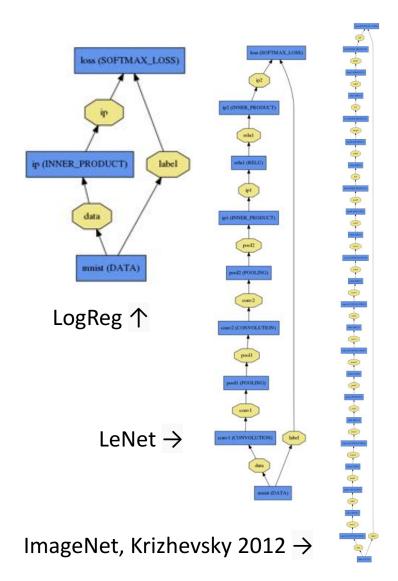
Caffe

(Convolutional Architecture for Fast Feature Embedding)

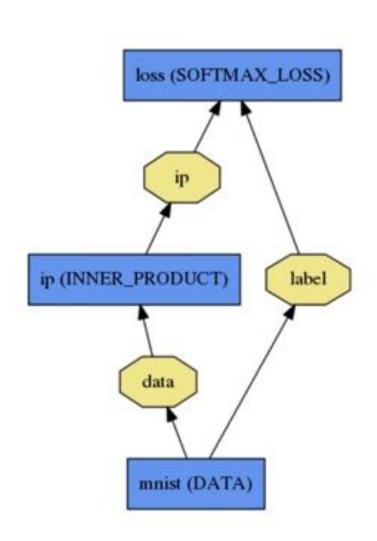
Nets

Layers

Blobs



Net

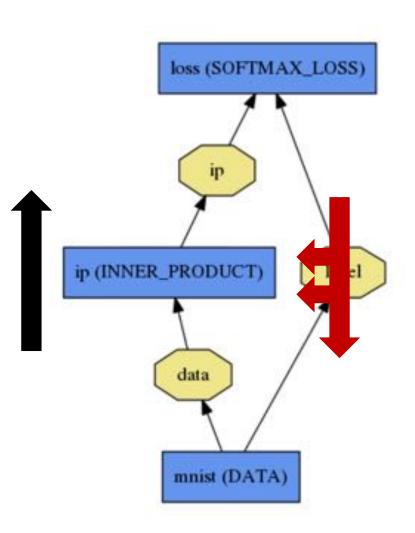


A network is a set of Layers and their connections.

Data and derivatives flow through the net as **Blobs** (an array interface).

Forward/Backward are the essential Net computations.

Layers



Defined by **setup**, **forward** and **backward** computations:

setup: run once for initialization

forward: make output given input

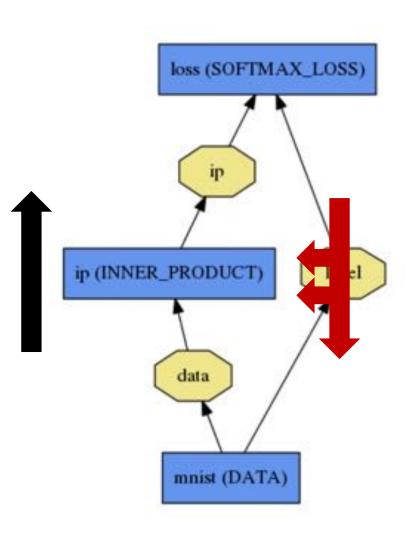
backward: make gradient of output

- w.r.t. bottom

- w.r.t. parameters

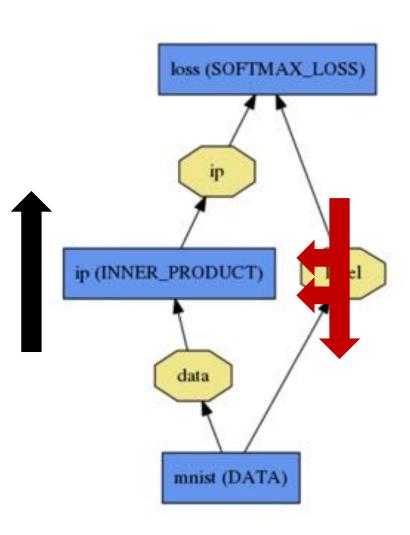
The Net's **Forward** and **Backward** passes are composed of the layers' steps (*Compositional Modeling*)

LAYER CATALOGUE (on Caffe website)



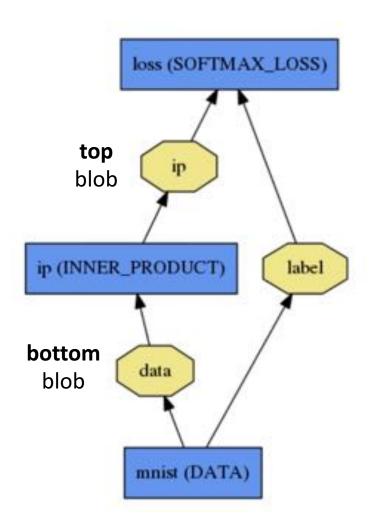
- √ "Convolution"
- ✓ "Pooling"
- ✓ "LRN" (normalization)
- ✓ "InnerProduct"
- ✓ "ReLU" (non linearity)
- **√** ...
- ✓ DATA layers (include image pre-processing steps):
 - √ database ("Data")
 - ✓ in-memory ("MemoryData")
 - ✓ image list ("ImageData")
- ✓ LOSS layers
 - ✓ softmax ("SoftmaxWithLoss")
 - ✓ accuracy ("Accuracy")

(Common) Image Preprocessing Steps



- √ "Convolution"
- ✓ "Pooling"
- ✓ "LRN" (normalization)
- ✓ "InnerProduct"
- ✓ "ReLU" (non linearity)
- **√** ...
- ✓ DATA layers (include image pre-processing steps):
 - 1. Subtract mean image of the training set (or mean pixel)
 - 2. Crop of expected size (e.g. 227x227x3)
- ✓ LOSS layers
 - ✓ softmax ("SoftmaxWithLoss")
 - ✓ accuracy ("Accuracy")

Blobs

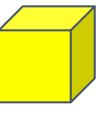


4-dimensional array stored in a C-contiguous fashion:

number N x channel C x height H x width W

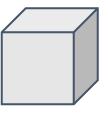
Hides the overhead of CPU/GPU computation by synchronizing as needed and allocating memory on host/device lazily.

Provides a unified memory interface:



Data

Number x Channel x Height x Width 256 x 3 x 227 x 227 for CaffeNet train input



Parameter: Convolution Weight

N Output x K Input x Height x Width 96 x 3 x 11 x 11 for CaffeNet conv1



Parameter: Convolution Bias

96 x 1 x 1 x 1 for CaffeNet conv1

Solver (Optimizer)

Initializes the model and the training.

At each iteration:

forward → output and loss backward → gradients parameter updates solver state update

Periodic validation.

Periodic snapshots of the model and solver state.

Many different kinds implemented in Caffe, e.g.:

- SGD
- Nesterov Accelerated Gradient
- Adam
- ...

Hands On

1. Warm Up

- running out-of-the-box
- opening the box

2. Assignment

- change configuration files and run different fine-tuning protocols
- [optional] suggestions for deeper exploration

Hands On

1. Warm Up

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Running out-of-the-box

Follow instructions here: https://github.com/vvv-school/tutorial_dl-tuning

- run the tester train_and_test_net_tester.sh
 (you should already have done this)
- 2. run the example train_and_test_net.sh

Opening the box

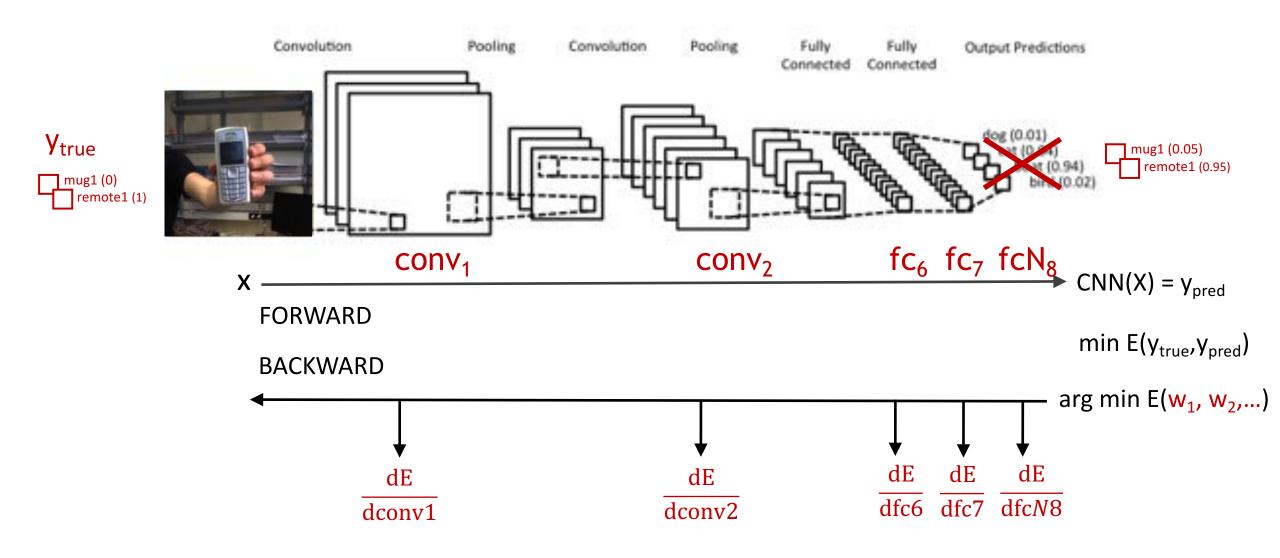
Look at the content of the example:

```
$ cd $LAB_DIR/tutorial_dl-tuning/id_2objects_caffenet
```

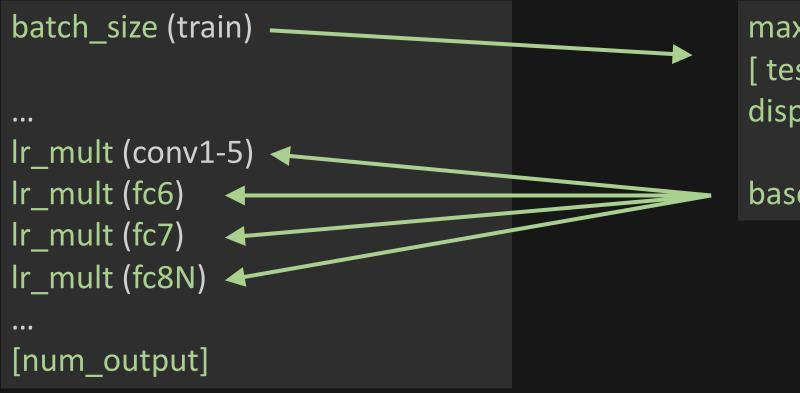
- all-0/train_val.prototxt
- all-0/deploy.prototxt
- all-0/solver.prototxt
- images_lists/train.txt
- images lists/val.txt
- images lists/test.txt
- images_lists/labels.txt

```
train_and_test_net.sh
```

What's happening? Fine-tuning CaffeNet on a 2-class identification task



train_val.prototxt

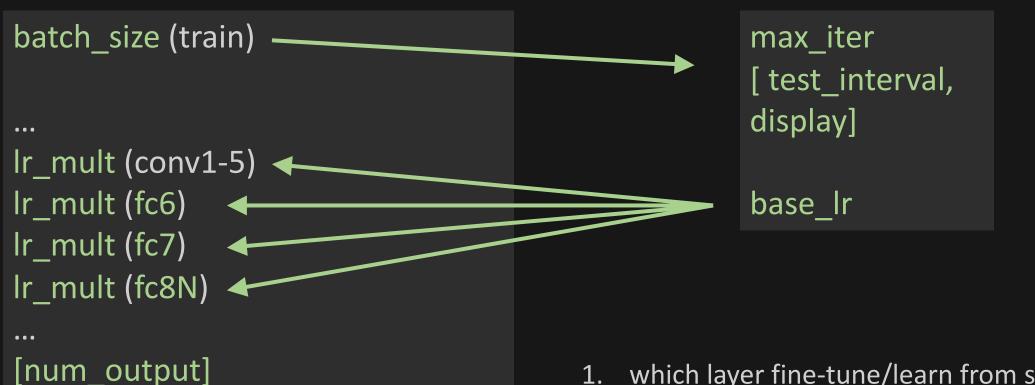


solver.prototxt

```
max_iter
[ test_interval,
display]
base_lr
```

train_val.prototxt

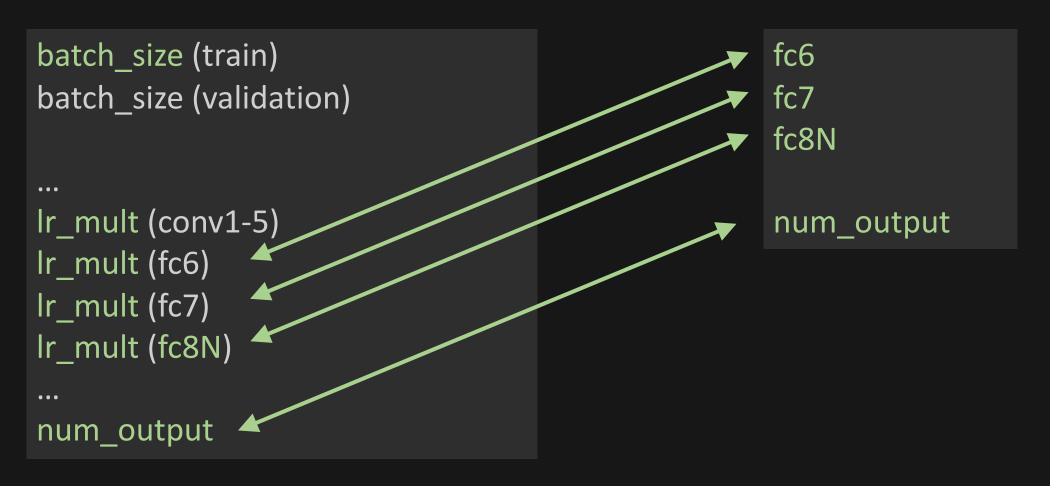
solver.prototxt



- 1. which layer fine-tune/learn from scratch
- 2. with which learning rate(s)
- varying batch size

train_val.prototxt

deploy.prototxt



train_and_test_net.sh

```
First defines paths (to caffe executables, to images, etc.), then:
   create databases (train & val LMDBs and mean.binaryproto):
       ${Caffe ROOT}/build/tools/convert imageset \
              --resize width=256 --resize height=256 --shuffle \
              ${IMAGES DIR} ${FILELIST TRAIN} ${LMDB TRAIN}
       → Imdb train (Imdb val)
       ${Caffe ROOT}/build/tools/compute image mean \
              ${LMDB TRAIN} ${BINARYPROTO MEAN}
       → mean.binaryproto
```

train_and_test_net.sh

```
2. train:
       ${Caffe ROOT}/build/tools/caffe \
               train -solver ${SOLVER FILE} -weights ${WEIGHTS FILE} \
               --log dir=${TUTORIAL DIR}/${EX}/${PROTOCOL}
       → icw_iter_*.caffemodel, icw_iter_*.solverstate, caffe.INFO
   parse caffe.INFO:
       ${TUTORIAL_DIR}/scripts/parse_caffe_log.sh \
               ${TUTORIAL DIR}/${EX}/${PROTOCOL}/caffe.INFO
       → caffeINFOtrain.txt, caffeINFOval.txt (tables)
```

train and test net.sh

train_and_test_net.sh

```
5. eventually choose best (or last) epoch:
       snap_list=(`ls -t icw_iter*.caffemodel`)
       FINAL_SNAP=${TUTORIAL_DIR}/${EX}/${PROTOCOL}/${snap_list[0]}
       FINAL MODEL=${TUTORIAL DIR}/${EX}/${PROTOCOL}/final.caffemodel
       mv ${FINAL SNAP} ${FINAL MODEL}
       rm ${TUTORIAL DIR}/${EX}/${PROTOCOL}/icw iter *.solverstate
       rm ${TUTORIAL DIR}/${EX}/${PROTOCOL}/icw iter *.caffemodel
   test final.caffemodel:
       $\{TUTORIAL DIR\}\/scripts\/src\/build\/classify_image_list_vvv17\
              ${DEPLOY FILE} ${FINAL MODEL} ${BINARYPROTO MEAN} \
              ${LABELS FILE} ${IMAGES DIR} ${FILELIST TEST} \
              ${TUTORIAL DIR}/${EX}/${PROTOCOL}/test acc day1.txt
               ${PRINT PREDICTIONS} ${IMG DELAY}
       → test acc day1.txt
```

Hands On

1. Warm Up

- running out-of-the-box
- opening the box

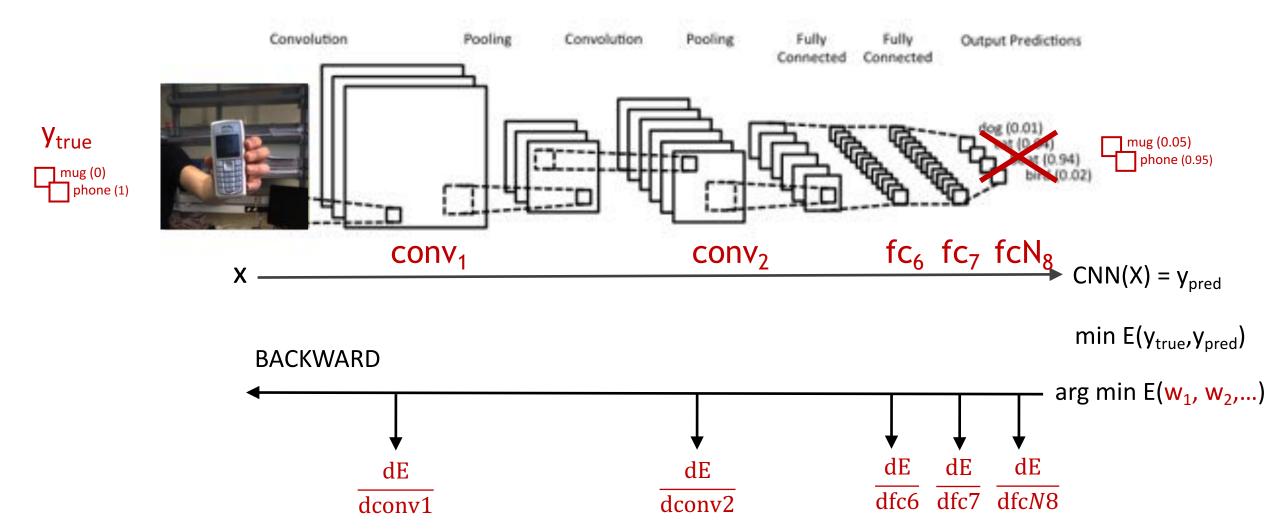
2. Assignment

- change configuration files and run different fine-tuning protocols
- [optional] suggestions for deeper exploration

Assignment

- 1. Apply the protocol we have used in the tutorial on a different task
- 2. Try fine-tuning also fc7, fc6
- 3. Try fine-tuning all layers
- 4. Try learning fc7, fc6 from scratch
- 5. Vary the batch size

name	batch size (train)	conv layers	fc6	fc7	fc8	# epochs	acc day1	acc day2
all-0	32	lr: 0	lr: 0	lr: 0	lr: 1e-2 from scratch	6	?	?



name	batch size (train)	conv layers	fc6	fc7	fc8	# epochs	acc day1	acc day2
all-0	32	lr: 0	lr: 0	lr: 0	lr: 1e-2 from scratch	6	?	?
conv-0_fc6-2_fc7-2	32	lr: 0	lr: 1e-2	lr: 1e-2	lr: 1e-2 from scratch	6	?	?
conv-0_fc6-3_fc7-3	32	lr: 0	lr: 1e-3	lr: 1e-3	lr: 1e-2 from scratch	6	?	?
all-3	32	lr: 1e-3	lr: 1e-3	lr: 1e-3	lr: 1e-2 from scratch	6	?	?
conv-0_fc6N-2_fc7N-2	32	lr: 0	lr: 1e-2 from scratch	lr: 1e-2 from scratch	lr: 1e-2 from scratch	18	?	?
conv-0_fc6N-4_fc7N-4	32	lr: 0	lr: 1e-4 from scratch	lr: 1e-4 from scratch	lr: 1e-2 from scratch	36	?	?
all-3_batch-8	8	lr: 1e-3	lr: 1e-3	lr: 1e-3	lr: 1e-2 from scratch	6	?	?
all-0_batch-1	1	lr: 0	lr: 0	lr: 0	lr: 1e-2 from scratch	6	?	?

name	batch size (train)	conv layers	fc6	fc7	fc8	# epochs	acc day1	acc day2
all-0	32	lr: 0	lr: 0	lr: 0	lr: 1e-2 from scratch	6	?	?
conv-0_fc6-2_fc7_2	າາ	?	?					
conv-0_fc6-3		?	?					
all-3	h+	?	?					
conv-0_fc6N-2	<u>ht</u>	?	?					
conv-0_fc6N-4		?	?					
all-3_batch-8	8	lr: 1e-3	lr: 1e-3	lr: 1e-3	lr: 1e-2 from scratch	6	?	?
all-0_batch-1	1	lr: 0	lr: 0	lr: 0	lr: 1e-2 from scratch	6	?	?

Things you may want to try...

Try changing the task reducing the number of example frames per object in the training set:

- create a new exercise folder (call it e.g. id_10objects_less_frames)
 by copying id_10objects_caffenet
- 2. open id_10objects.m in the new folder and change setlist.max_frames.train (try e.g. 20, or 10, or 5)
- 3. open example_task_generation.m and modify the paths to
 - (i) use the configuration file at point 2)
 - (ii) create training, validation and test sets in the new folder
 - > run the script to generate the new training set
- 4. implement the protocols all-0 and all-3 on this new task and run them
- → how much does the recognition accuracy decrease? is there a better protocol?

Things you may want to try...

Try to perform an object categorization task:

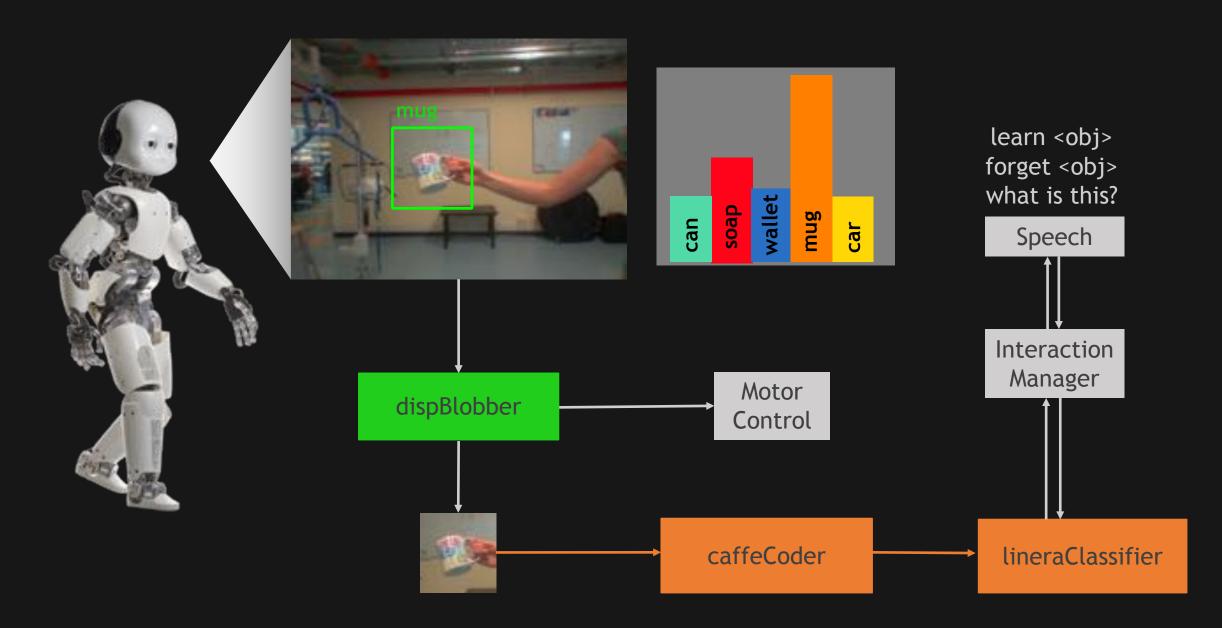
- create a new exercise folder (call it e.g. cat_3categories)
 by copying id_10objects_caffenet
- 2. open id_10objects.m in the new folder (you may rename it to match the new task) and change it to generate a task of discrimination between the 3 categories in iCW (e.g. by training on 7 objects/cat, validating on 2, and testing one the remaining 1)
- 3. open example_task_generation.m and modify the paths to
 - (i) use the configuration file at point 2)
 - (ii) create training, validation and test sets in the new folder
 - → run the script to generate the new training set
- 4. implement the protocols all-0 and all-3 on this new task and run them
- → how much does the recognition accuracy change? is there a better protocol?
- → is this task more or less difficult? why?

Things you may want to try...

Deploy the fine-tuned model in the recognition pipeline on the iCub!

- create a folder with your surname
- put inside the final.caffemodel and mean.binaryproto
- together with a test.prototxt (see next for how to create this file...)

On the Fly Object Recognition Demo on iCub



Pointers to GitHub Repositories

DEMO: robotology/onthefly-recognition

- → manager
- → speech
- → tracking

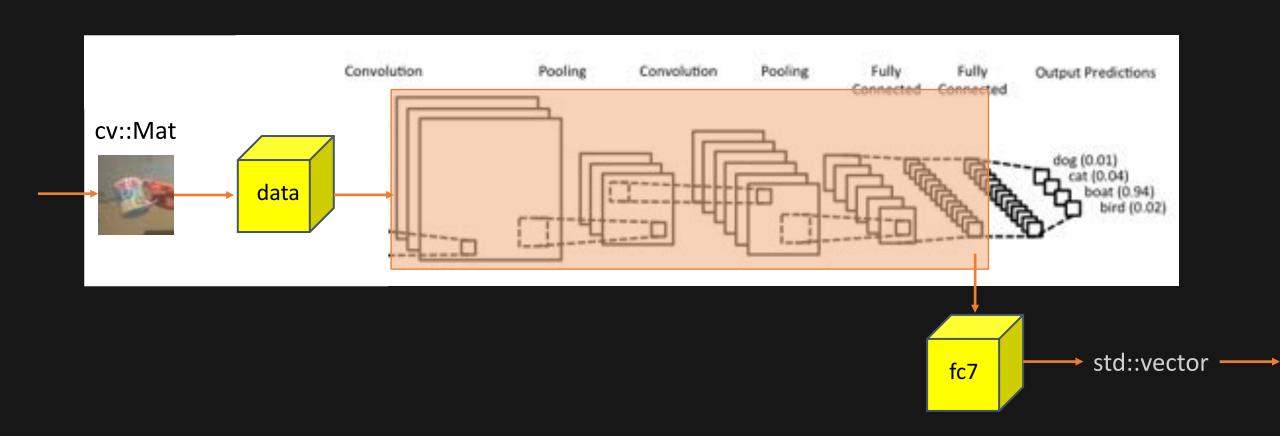
SEGMENTATION: robotology/segmentation

→ dispBlobber

RECOGNITION PIPELINE: robotology/himrep

- → caffeCoder
- → linearClassifier

caffeCoder: (YARP) wrapper for caffe



caffeCoder: call with your own files

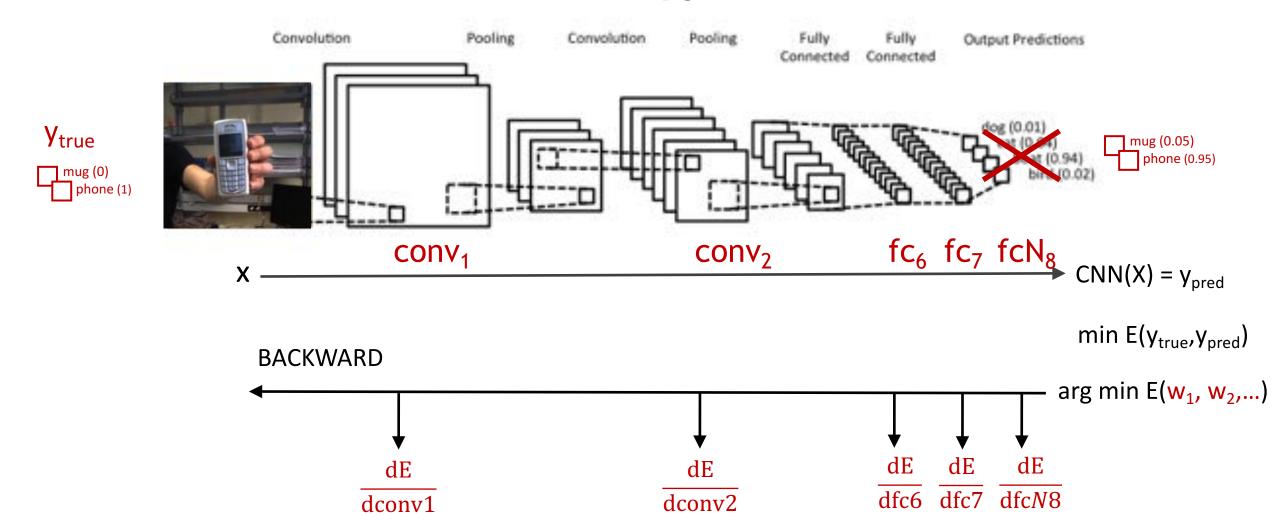
```
provided that you have:
/home/icub/.local/share/yarp/contexts/himrep/pasquale/final.caffemodel
/home/icub/.local/share/yarp/contexts/himrep/pasquale/mean.binaryproto
/home/icub/.local/share/yarp/contexts/himrep/pasquale/test.prototxt

call (you can try also on the VM):

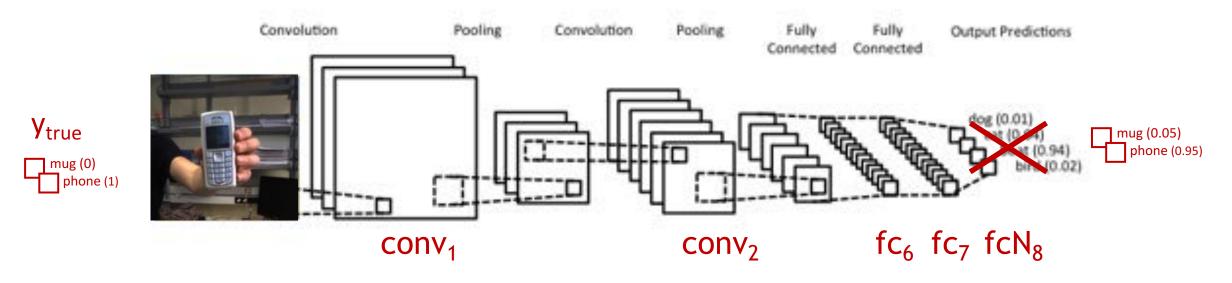
caffeCoder --pretrained_binary_proto_file
/home/icub/.local/share/yarp/contexts/himrep/pasquale/final.caffemodel
--feature_extraction_proto_file pasquale/test.prototxt --extract_features_blob_names fc6N
```

More details on assignment...

1. Fine-tuning CaffeNet on a 2-class identification task 10

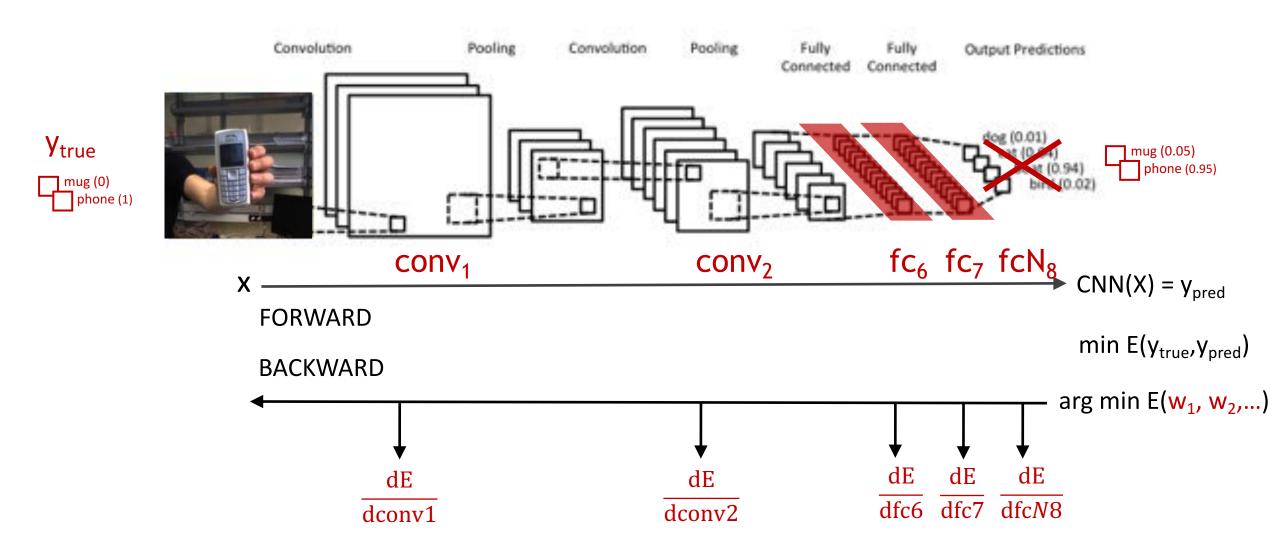


1. Fine-tuning CaffeNet on a 2-class identification task 10

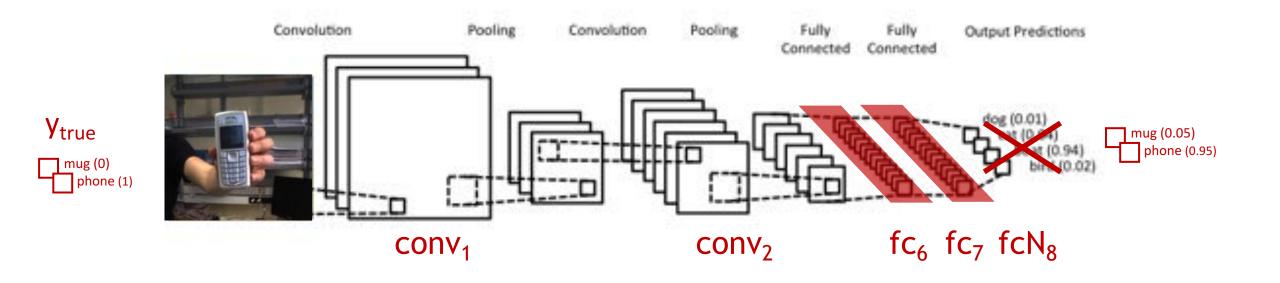


name	batch size (train)	conv layers	fc6	fc7	fc8	# epochs	acc day1	acc day2	
all-0	32	lr: 0	lr: 0	lr: 0	lr: 1e-2 from scratch	6	?	?	

2. Try fine-tuning fc7,fc6

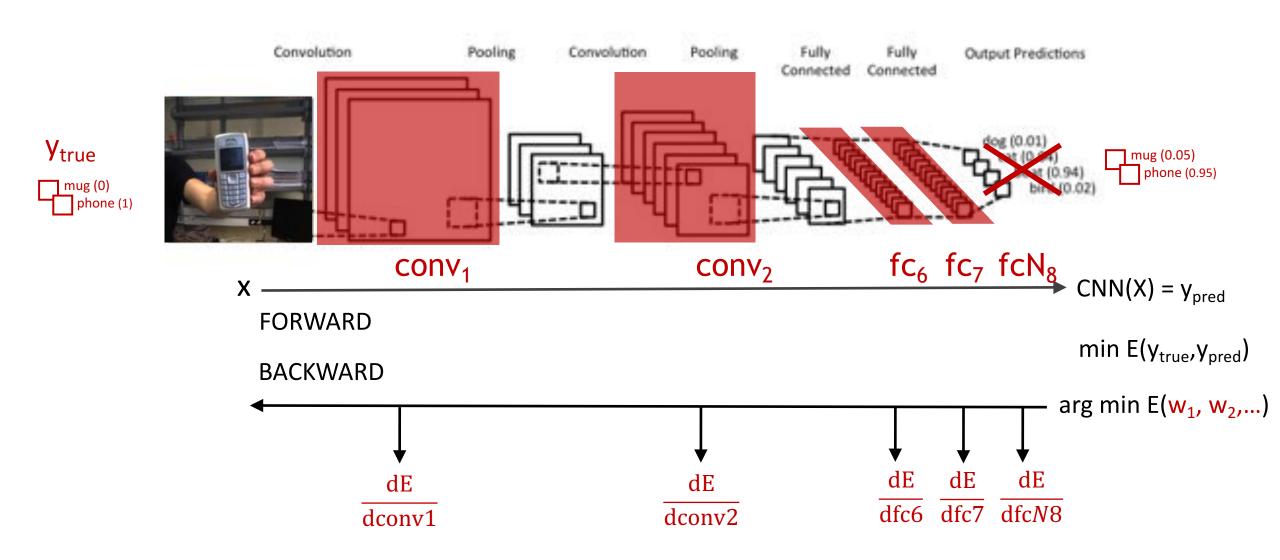


2. Try fine-tuning fc7,fc6

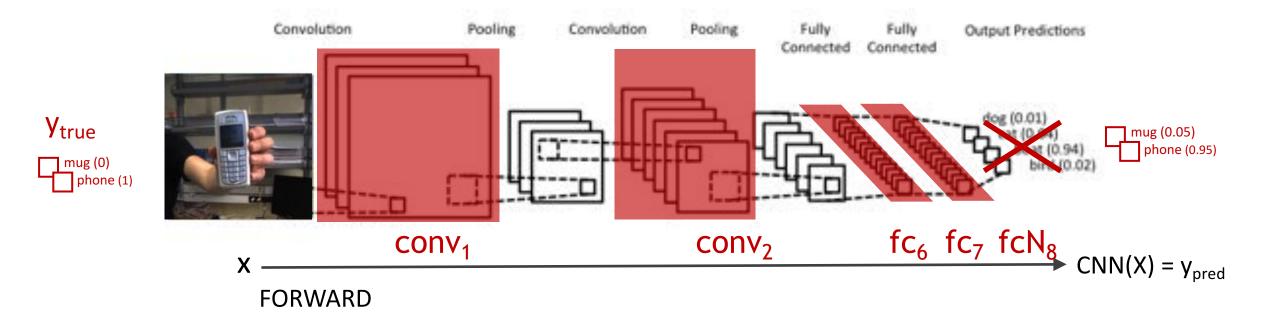


name	batch size (train)	conv layers	fc6	fc7	fc8	# epochs	acc day1	acc day2
conv-0_fc6-2_fc7-2	32	lr: 0	lr: 1e-2	lr: 1e-2	lr: 1e-2 from scratch	6	?	?
conv-0_fc6-3_fc7-3	32	lr: 0	lr: 1e-3	lr: 1e-3	lr: 1e-2 from scratch	6	?	?

3. Try fine-tuning all layers

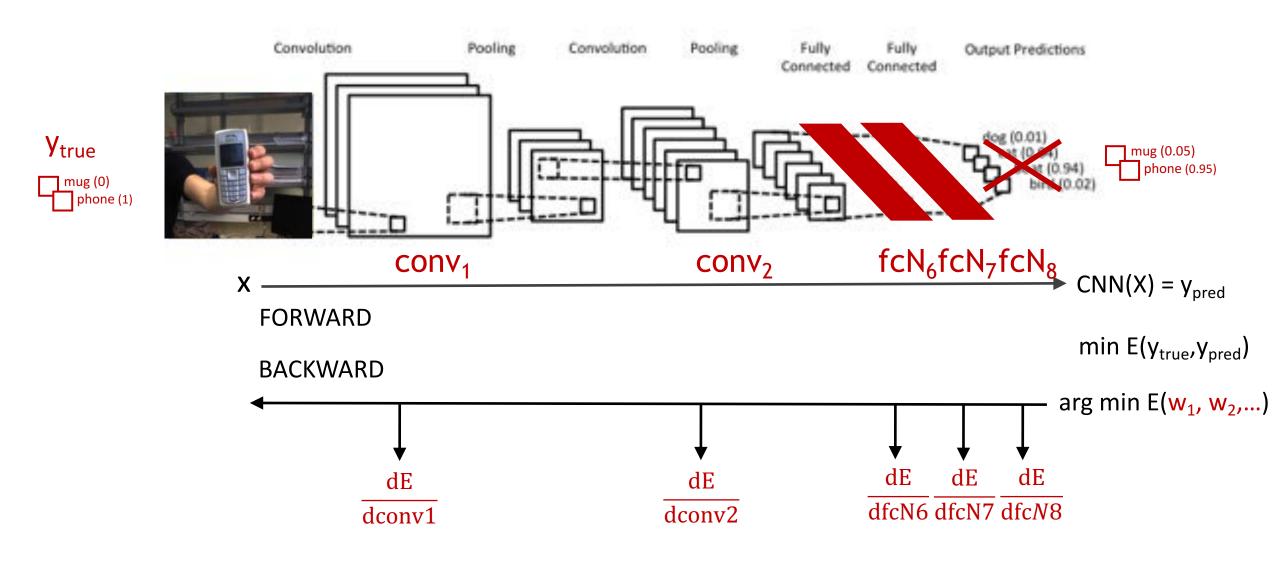


3. Try fine-tuning all layers

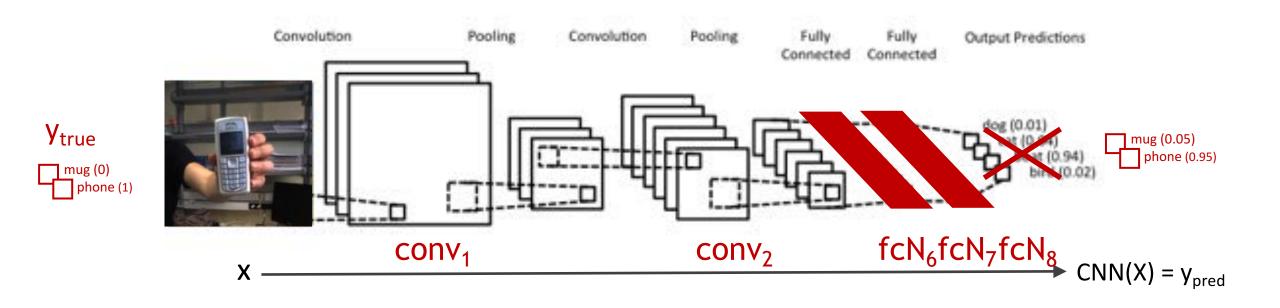


name	batch size (train)	conv layers	fc6	fc7	fc8	# epochs	acc day1	acc day2
all-3	32	lr: 1e-3	lr: 1e-3	lr: 1e-3	lr: 1e-2 from scratch	6 (12)	?	?

4. Is it possible to learn from scratch fc7,fc6?



4. Is it possible to learn from scratch fc7,fc6?



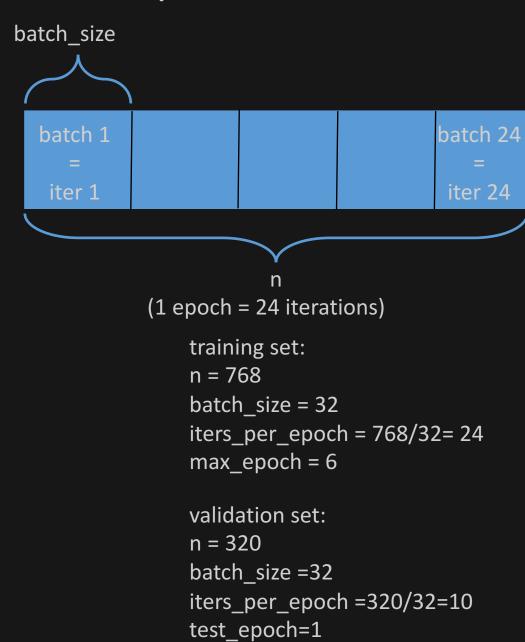
name	batch size (train)	conv layers	fc6	fc7	fc8	# epochs	acc day1	acc day2
conv-0_fc6N-2_fc7N-2	32	lr: 0	lr: 1e-2 from scratch	lr: 1e-2 from scratch	lr: 1e-2 from scratch	18	?	?
conv-0_fc6N-4_fc7N-4	32	lr: 0	lr: 1e-4 from scratch	lr: 1e-4 from scratch	lr: 1e-2 from scratch	18 (36)	?	?

5. Vary the batch size

name	batch size (train)	conv layers	fc6	fc7	fc8	# epochs	acc day1	acc day2
all-3_batch-8	8	lr: 1e-3	lr: 1e-3	lr: 1e-3	lr: 1e-2 from scratch	6	?	?
all-0_batch-1	1	lr: 0	lr: 0	lr: 0	lr: 1e-2 from scratch	6	?	?

solver.prototxt: hot to set batch-related parameters

```
net: "train_val.prototxt"
solver_mode: CPU
# carry out <max iter> training iterations
max iter: 144 (6 x 24)
## the validation will carry out <test_iter> iterations
test_iter: 10
## carry out validation every <test interval> training iterations
test interval: 24
## display every <display> iterations
display: 24
## save model every <snapshot> iterations
snapshot: 0
snapshot_prefix: "icw"
```



train_val.prototxt: set the batch size

```
layer {
  name: "data"
  type: "Data"
  top: "data"
  top: "label"
  include {
    phase: TRAIN
  transform_param {
    mirror: true
    crop_size: 227
    mean_file: "../mean.binaryproto"
  data_param {
    source: "../lmdb_train"
    batch_size: 32
    backend: LMDB
```

```
layer {
  name: "data"
  type: "Data"
  top: "data"
  top: "label"
  include {
    phase: TEST
  transform_param {
    mirror: false
    crop_size: 227
    mean_file: "../mean.binaryproto"
  data_param {
    source: "../Imdb_val"
    batch_size: 32
    backend: LMDB
```

train_val.prototxt: set lr_mult for conv and fc layers

```
layer {
                                         ... ...
                                           convolution_param {
  name: "conv1"
  type: "Convolution"
                                             num_output: 96
  bottom: "data"
                                             kernel_size: 11
  top: "conv1"
                                             stride: 4
                                             weight_filler {
  param {
    lr_mult: <x> [1,10,0.1...]
                                               type: "gaussian"
    decay_mult: 1
                                               std: 0.01
                                             bias_filler {
  param {
    lr_mult: <2x> [2,20,0.2...]
                                               type: "constant"
    decay_mult: 0
                                               value: 0
```

train_val.prototxt: set lr_mult for conv and fc layers

```
layer {
                                         ... ...
  name: "fc6"
                                           inner_product_param {
  type: "InnerProduct"
                                              num_output: 4096
  bottom: "pool5"
                                             weight_filler {
  top: "fc6"
                                                type: "gaussian"
                                                std: 0.005
  param {
    lr_mult: <x> [e.g.: 1,10,0.1...]
    decay_mult: 1
                                              bias filler {
                                                type: "constant"
                                                value: 1
  param {
    lr_mult: <2x> [e.g.: 2,20,0.2...]
    decay_mult: 0
```

train_val.prototxt: rename layers (and related output blobs) that you learn from scratch

```
layer {
                                        ... ...
  name: "fc8N"
                                           inner product param {
  type: "InnerProduct"
                                             num_output: 2
  bottom: "fc7"
                                             weight_filler {
  top: "fc8N"
                                               type: "gaussian"
                                               std: 0.01
  param {
    Ir mult: 1
   decay_mult: 1
                                             bias filler {
                                               type: "constant"
                                               value: 0
  param {
    Ir mult: 2
    decay_mult: 0
```

train_val.prototxt: rename layers (and related output blobs) that you learn from scratch

```
layer {
    name: "accuracy"
    type: "Accuracy"
    bottom: "fc8N"
    bottom: "label"
    top: "accuracy"
}
```

```
layer {
    name: "loss"
    type: "SoftmaxWithLoss"
    bottom: "fc8N"
    bottom: "label"
    top: "loss"
}
```

deploy.prototxt

```
✓ same structure as train_val.protoxt, but
   no DATA layer
   no learning parameters (lr_mult...)
✓ pay attention to:
       \rightarrow rename the layers which you learned from scratch (fc8 \rightarrow fc8N)
       > set num_output (fc8N) accordingly to the task (num_output=2)
```

test.prototxt: you have to create it

✓ same structure as train_val.protoxt, but "MemoryData" DATA layer (see next slide) no learning parameters ✓ pay attention to: \rightarrow rename the layers which you learned from scratch (fc8 \rightarrow fc8N) → set num output (fc8N) accordingly to the task (num output=2) (you can copy the deploy.prototxt)

test.prototxt: example "MemoryData" layer

```
layer {
  name: "data"
  type: "MemoryData"
  top: "data"
  top: "label"
  transform_param {
    mirror: false
    crop_size: 227
    mean_file: "/home/icub/.local/share/yarp/contexts/himrep/pasquale/mean.binaryproto "
  memory_data_param {
    batch_size: 1
    channels: 3
    height: 227
    width: 227
```