# Electronic Countermeasures for Radar

Preliminary Design Review

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# **Project Overview**

- Develop a radar and an ECM module
- Small-scale, low-cost radar and ECM experimentation
- Designed for hobbyists and educators
- Cost: \$805

# **Technical Objectives**

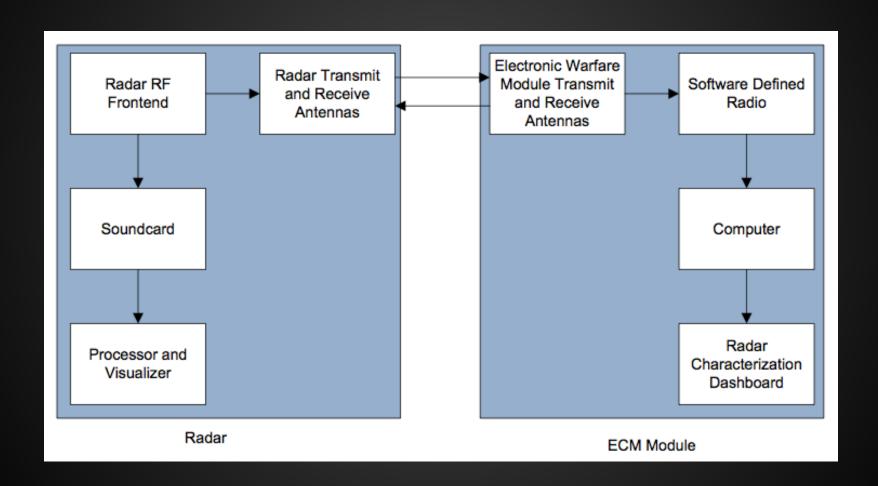
- Low-cost implementations
- Build MIT Cantenna Radar

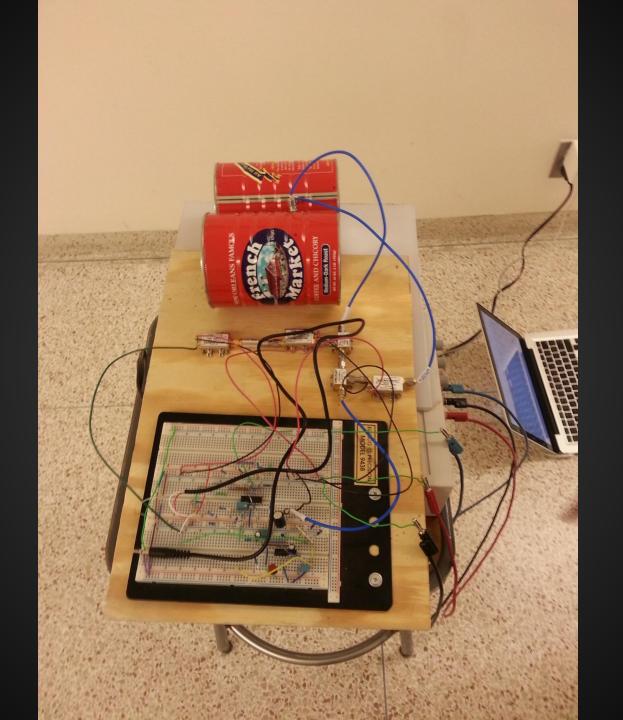
- Program and test countermeasure
- Real-time radar imaging

#### **Current Status**

- Built and tested functioning radar prototype
- In process of programming ECM
- In process of programming real-time imaging

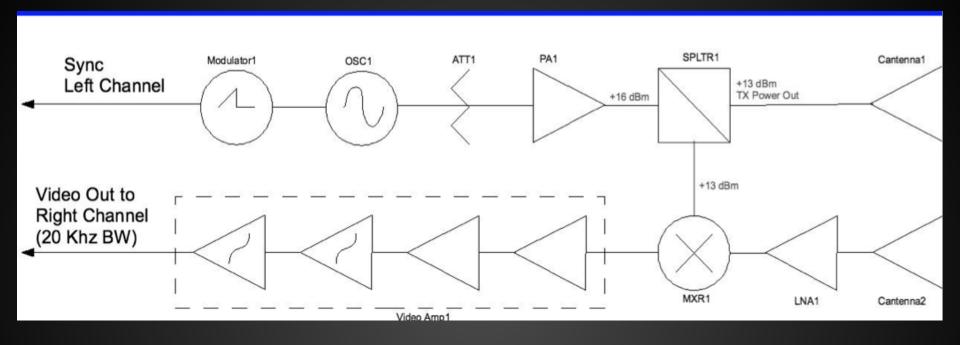
# Design Approach





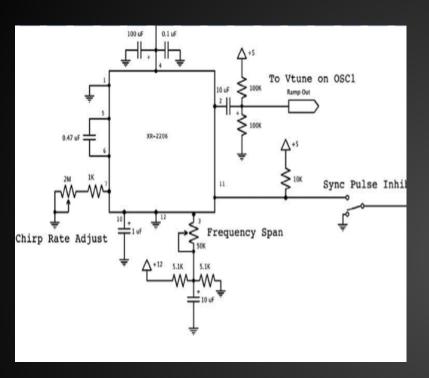


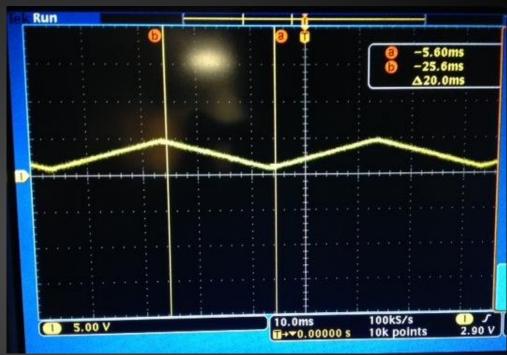
#### Block Diagram of Radar



- Frequency Modulated Continuous Wave Radar
- Operates in the 2.4 Ghz range
- Max Range ~ 1Km for 10dBsm
- Data and signal processing in MATLAB

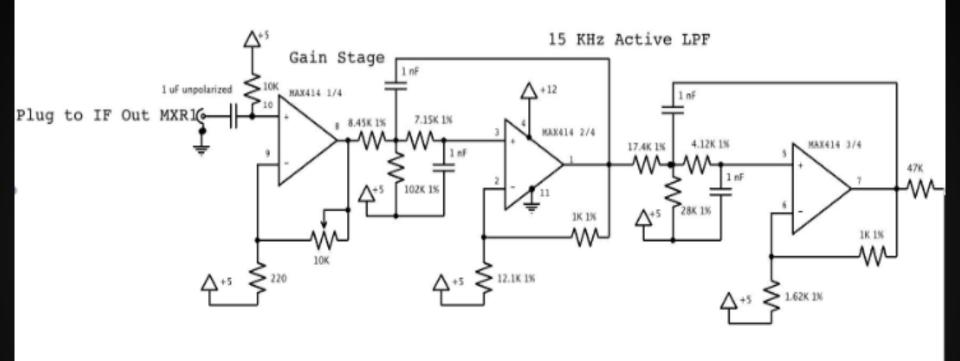
#### Modulator





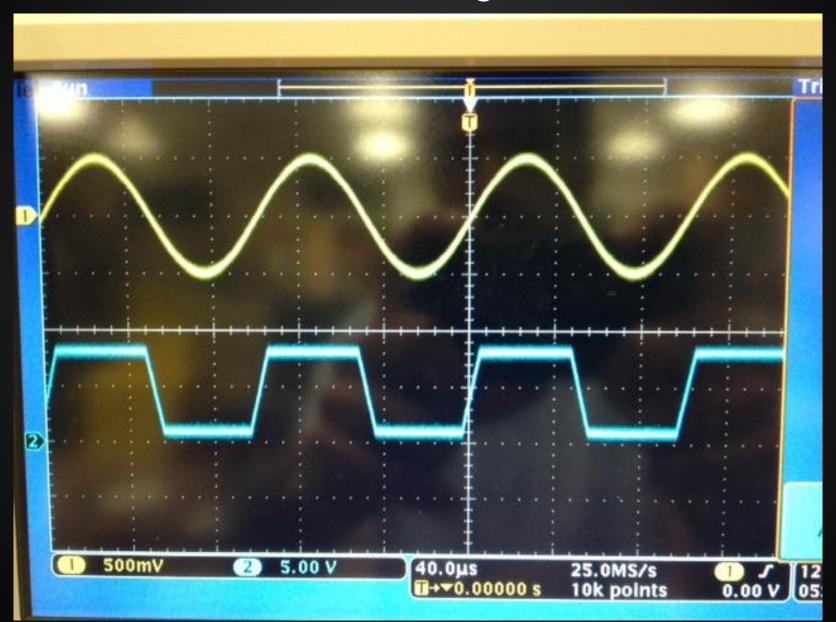
- Modulates the Vtune pin of the Oscillator.
- Vtune pin is proportional to the transmit frequency of the oscillator.
- Linear ramping of Vtune causes the oscillator to produce a linear FM chirp.
- Also connected to left audio input channel to produce a trigger signal synchronized with transmit

#### Video Amplifier

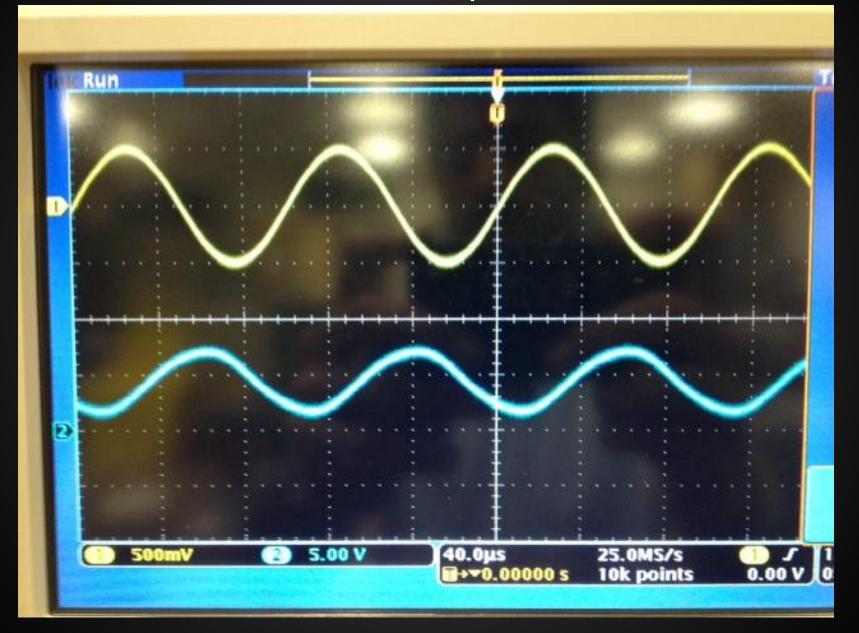


- Consists of Gain Stage and 4th order low pass filter.
- Takes output of mixer; amplifies it.
- Passed through LPF to remove noise and make it compatible with audio port input of computer.

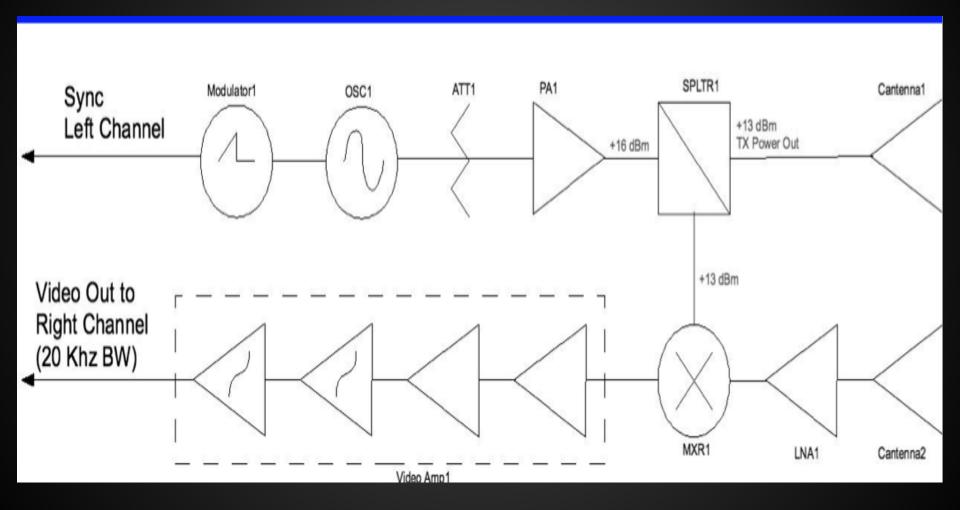
# Gain Stage

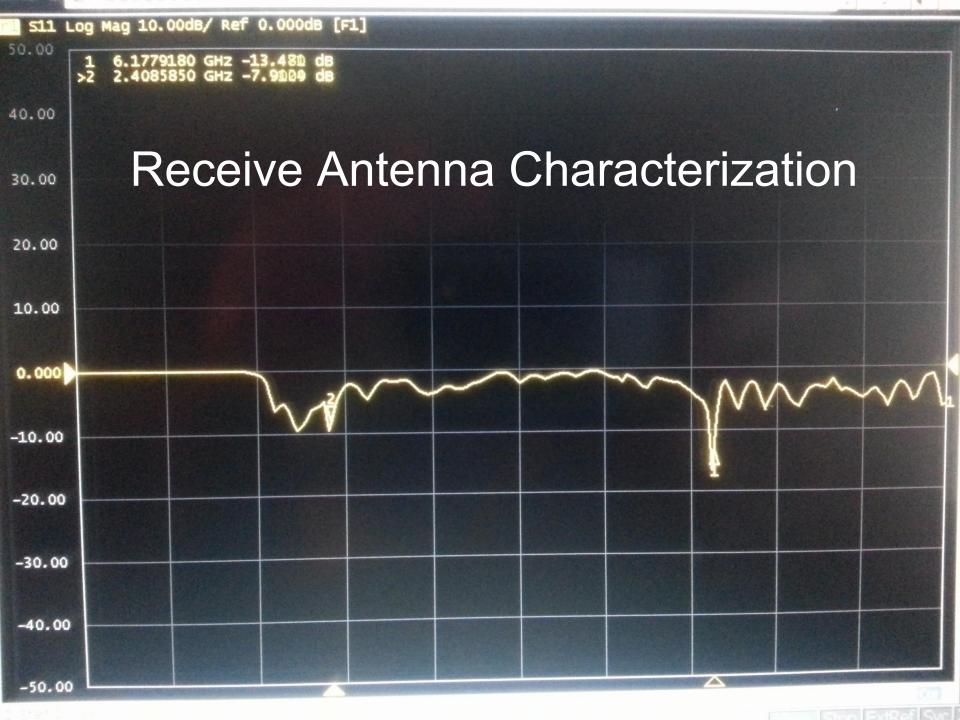


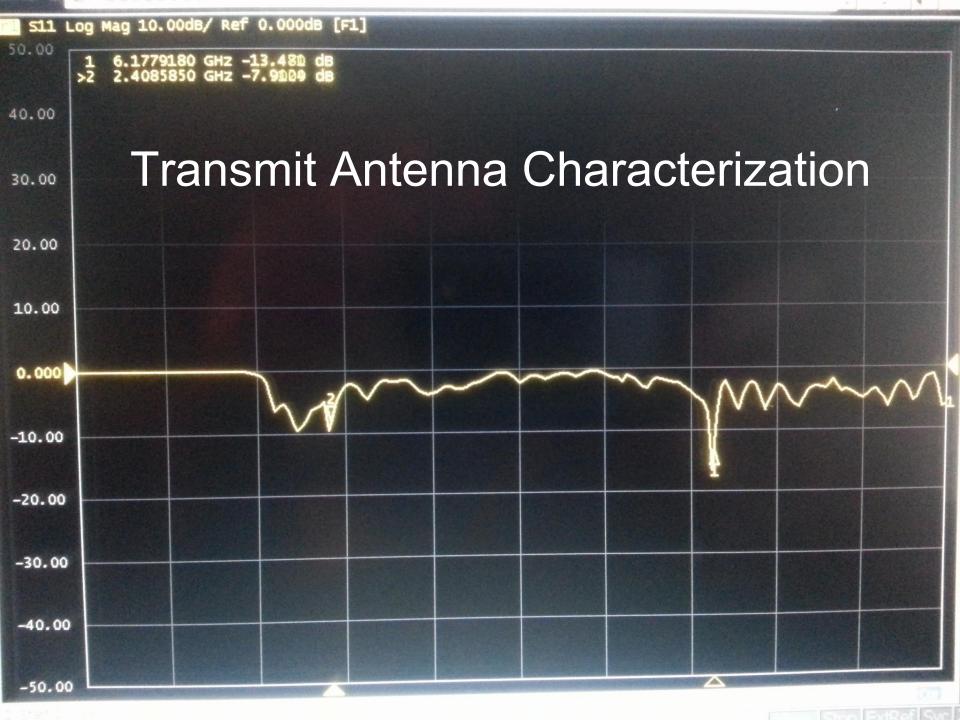
## LPF output

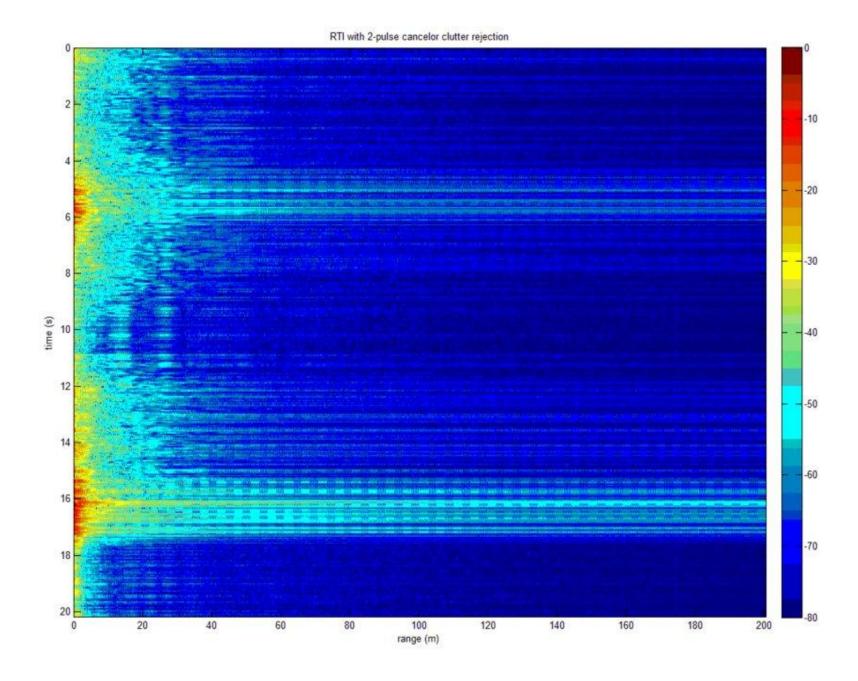


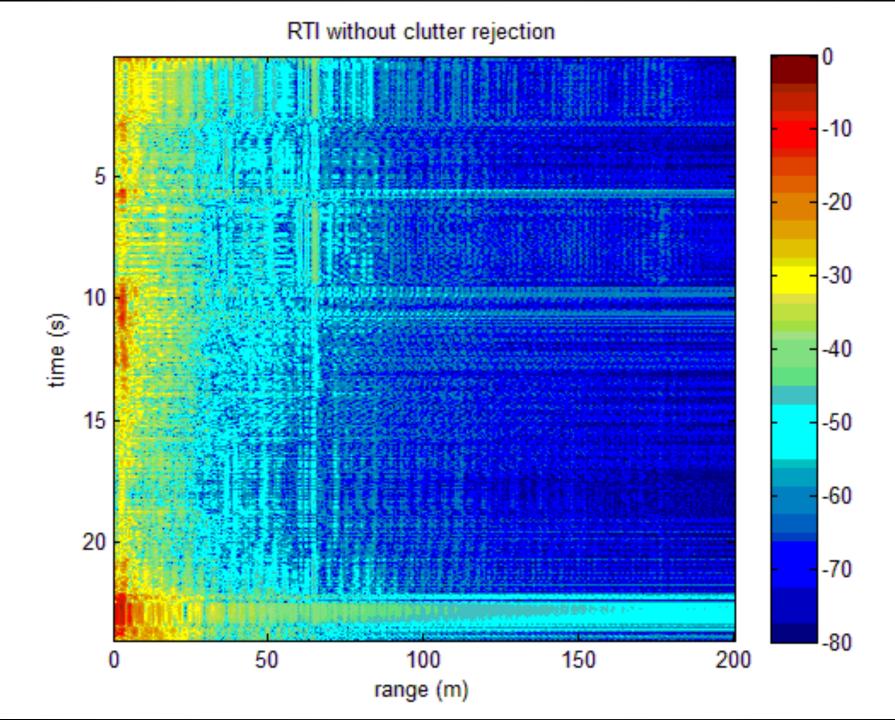
# Ranging and Doppler











RTI with 2-pulse cancelor clutter rejection -10 -20 - - -30 10 time (s) -40 15 -50 -60 20 -70

20

40

60

80

100

range (m)

120

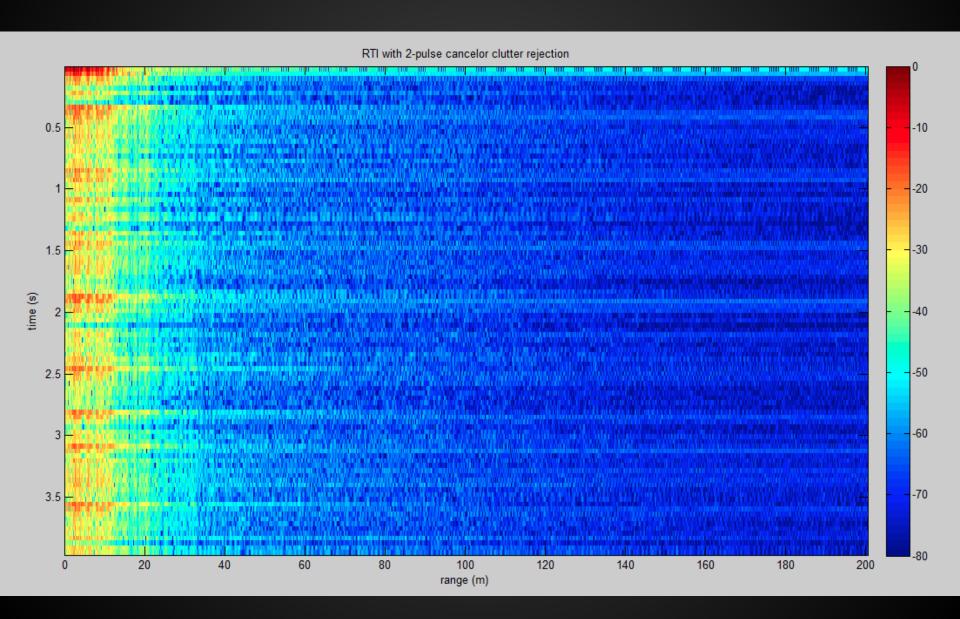
140

160

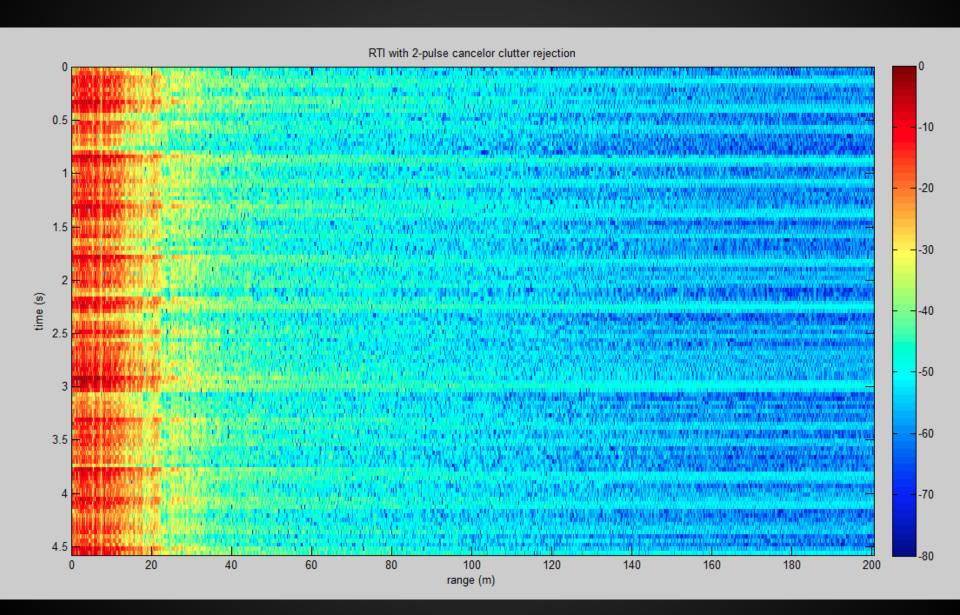
180

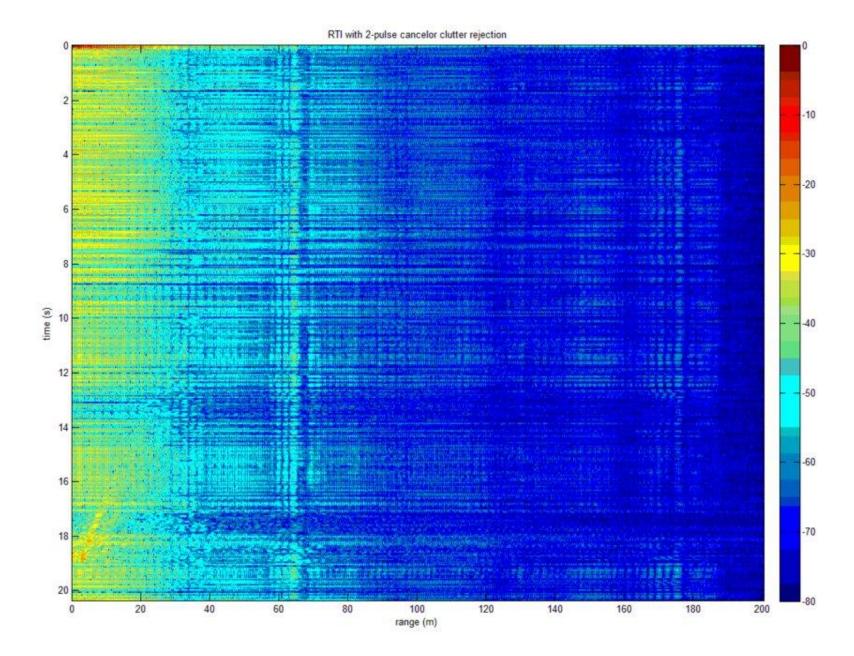
200

### Range without Jamming



### Range with Jamming







#### **Future Work**

 ECM Module Completion 3/28/13

 GUI Development and Testing 4/01/13

 Comprehensive ECM and Radar Test 4/15/13

# **Questions?**