



深度學習TensorFlow實務

循環神經網路

Lab4

-TA-

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1. 循環神經網路介紹

循環神經網路

- 全名: Recurrent Neural Networks, RNN
- 與前饋神經網路、卷機神經網路最大的不同為 - 記憶暫存功能
- 在自然語言處理 (natural language processing, NLP) 應用廣泛

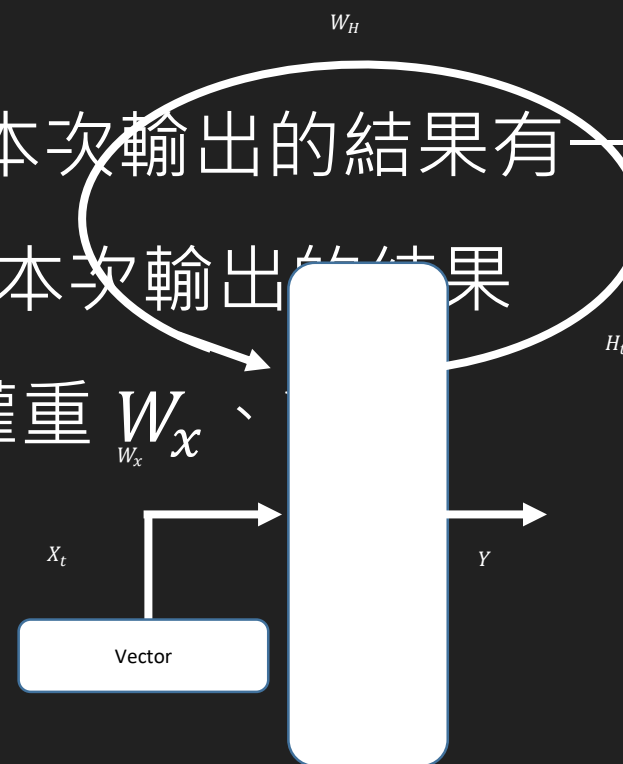
隱馬可夫模型

■ 馬可夫鏈的核心是:

- 給定當前知識、資訊的情況下，觀察對象過去的歷史狀態對於將來的預測來說是無關的
- 一個系統變化時，它下一個狀態 (第 $n+1$ 狀態) 如何的機率只需觀察和統計當前狀態 (第 n 個狀態) 即可以正確得出
- 隱馬可夫鏈是一個雙重的隨機過程，不僅狀態轉移之間是個隨機事件，狀態和輸出之間也是一個隨機過程

RNN結構

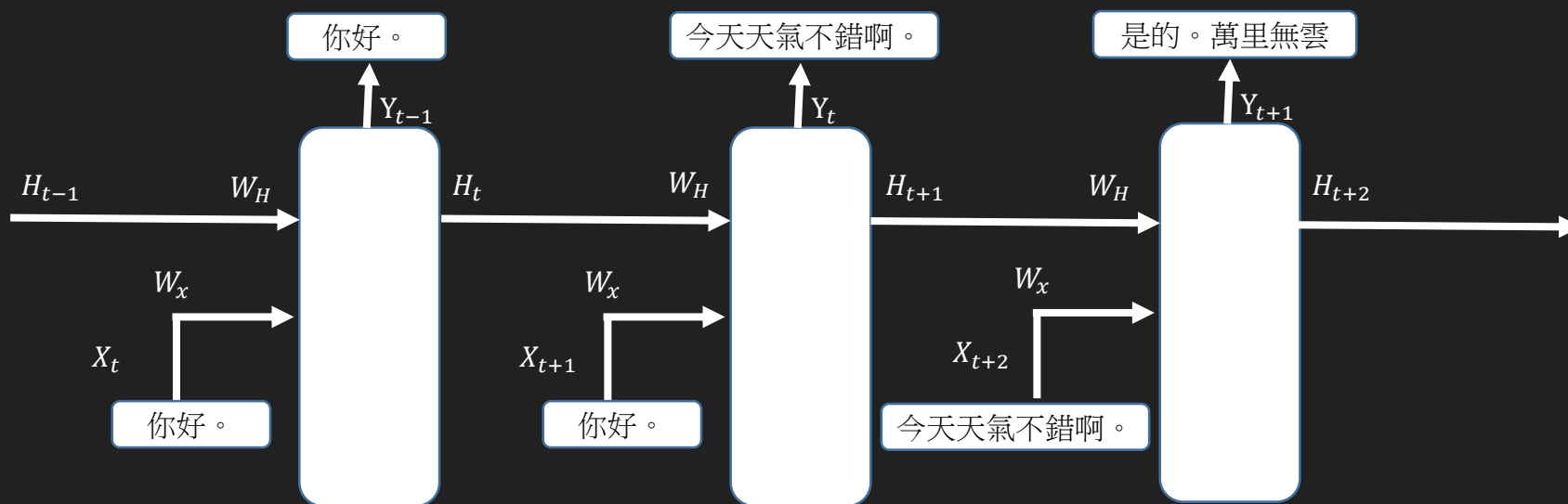
- 兩個特定係數 W_x 、 W_H ， W_x 與 X_t 向量做乘積，作為輸入
- 向量 Y 由前一次輸出的 H_{t-1} (暫存起來) 和 W_H 相乘產生的向量和 W_x 與 X_t 相乘產生的向量做 Softmax 得到
- 前一次輸入的向量 X_{T-1} 所產生的結果對於本次輸出的結果有一定的影響，甚至 X_{T-2} 、 X_{T-3} 都有可能影響本次輸出的結果
- 中間具體量化的邏輯關係需透過訓練得到權重 W_x 、



RNN訓練過程

- W_x 、 W_H 矩陣被初始化後，在 Y 側必有輸出，也就會有殘差產生 E_i
- 放入第一句和第二句後產生 E_1 ，加上第二句和第三句後產生 E_2 ，加到倒數第二句和最後一句後產生 E_{n-1} ，因此可簡寫成

$$LOSS = \sum_{i=1}^{n-1} E_i$$



RNN艱難的誤差傳遞

- W_X 、 W_H 是我們最終要學習的內容
 - $LOSS = \alpha E_X + \beta E_H$
- E_X 、 E_H 表示由 W_X 、 W_H 引起的誤差， α 、 β 表示由樣本產生的係數
 - $H_T = W_H f(H_{t-1}) + W_X X_t$
 - $Y_T = SOFTMAX(f(H_T))$
- 如果只有 X_t 、 Y_t ，那殘差就成了
 - $H_1^o = W_H f() + W_X X_1$
 - $E_1 = \frac{1}{2} (SOFTMAX(f(H_1^o)) - Y_1)^2 \Rightarrow E_1 = \frac{1}{2} (W_S(f(H_1^o)) - Y_1)^2$
- 其中 W_S 是指 Softmax 中的 W_S 矩陣

RNN艱難的誤差傳遞

- 根據 E_1 這個殘差分別來求出 W_X 、 W_H 的偏導數來得到梯度大小

- W_X 的偏導數： $\frac{\partial E_1}{\partial W_X} \Rightarrow \frac{\partial W_s f(H_1^o)}{\partial W_X} \Rightarrow W_s \frac{\partial f(H_1^o)}{\partial W_X} \Rightarrow W_s \frac{\partial f(H_1^o)}{\partial (H_1^o)} \frac{\partial (W_H f() + W_X X_1)}{\partial W_X} \Rightarrow W_s X_1 \frac{\partial f(H_1^o)}{\partial (H_1^o)}$

- 當僅有 1 個樣本對輸入，殘差在 W_X 的斜率僅僅和 X_1 向量有關，若有 2 個樣本對，就與 X_1 、 X_2 有關

- W_H 的偏導數： $\frac{\partial E_1}{\partial W_H} \Rightarrow \frac{\partial W_s f(H_1^o)}{\partial W_H} \Rightarrow W_s \frac{\partial f(H_1^o)}{\partial W_H} \Rightarrow W_s \frac{\partial f(H_1^o)}{\partial (H_1^o)} \frac{\partial (W_H f() + W_X X_1)}{\partial W_H} \Rightarrow W_s \frac{\partial f(H_1^o)}{\partial (H_1^o)} \frac{\partial W_H f()}{\partial W_H}$

- 最後一個 $\frac{\partial W_H f()}{\partial W_H}$ 簡化後成了 $f()$ ，第一次代入一對輸入和輸出值時，這部分值為初始化給的 H_0 值，寫成 $f()$ 問題不大

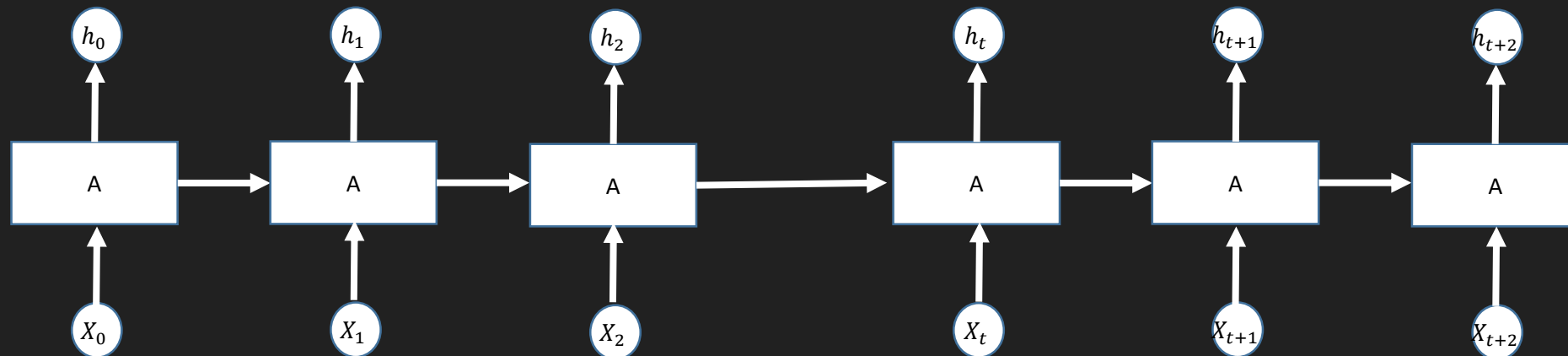
RNN艱難的誤差傳遞

- 如果是第 3 對輸入的值 $\frac{\partial W_H f(H_2^0)}{\partial W_H}$ ， $H_2 = W_H f(H_1) + W_X X_1$
- 這仍是一個 W_H 函數，要繼續求導求出 $\frac{\partial H_2}{\partial W_H}$
- 如果有 1000 對，就要求這一系列的導數並連乘起來
 - $\frac{\partial H_{1000}}{\partial W_H} \frac{\partial H_{999}}{\partial W_H} \frac{\partial H_{998}}{\partial W_H} \cdots \frac{\partial H_2}{\partial W_H} \frac{\partial H_1}{\partial W_H}$
- 將會加大運算的時間複雜度，引發梯度消失、梯度爆炸
- 後人對 RNN 改造發展 LSTM 演算法代替遞歸累積時間演算法

LSTM演算法

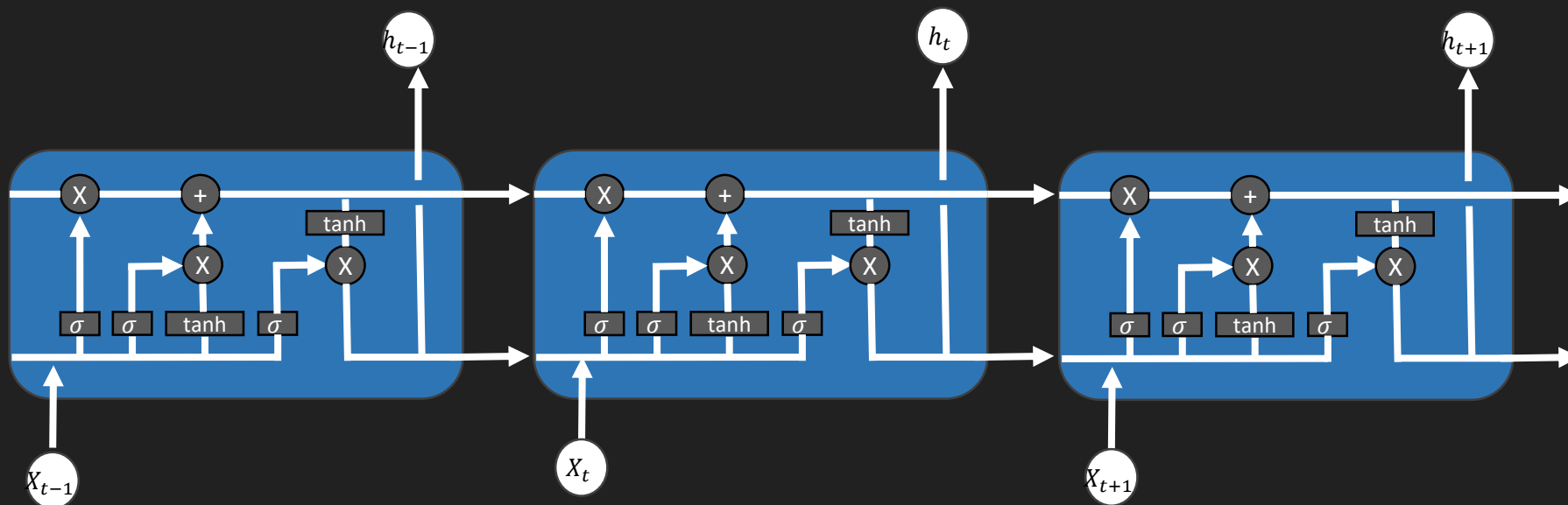
- 全名: long short-term memory，簡稱為：LSTM
- 規避了RNN的梯度爆炸和梯度消失問題，學習速度更快
- 多了遺忘閘 (forget gate) 機制
- 對於一個輸入序列 x_i ，某一個 x 值會影響一個在時間上或者空間上較遠的 H_j 輸出

間上較遠的 H_j 輸出



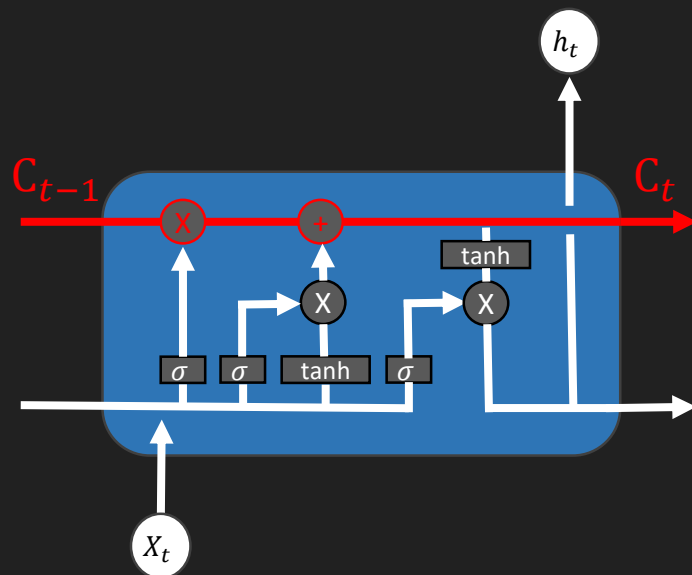
LSTM演算法

- LSTM 輸入層為 X_t ，輸出層為 h_t ，中間部分為一個個的 LSTM 單元
- LSTM 單元一個一個首尾相接，前一層輸出會作為後一層輸入



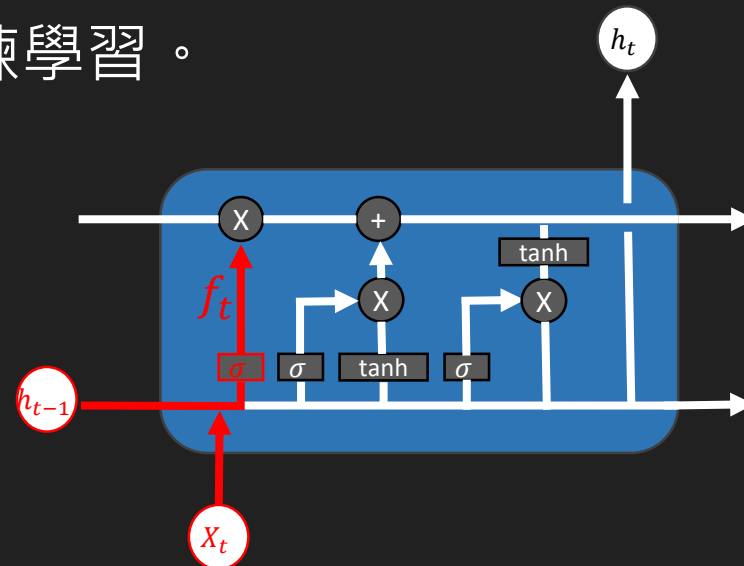
LSTM演算法

- 首先從左到右進行一個向量傳輸，左側的 C_{t-1} 進入單元後，先被一個乘法器乘以一個係數後，再線性疊加一個數值從右側輸出



LSTM演算法

- 左側 h_{t-1} 和下方輸入 x_t 經過連接操作，接著透過一個線性單元 $\sigma(\text{sigmoid})$ 函數之後產生一個 $0 \sim 1$ 之間的數字作為係數輸出
- $f_t = \sigma(W_f \cdot [h_{t-1}, x_t] + b_f)$
- 這就是一個遺忘閘，所謂遺忘就是指相乘的過程，如果 *Sigmoid* 函數輸出是1，那就是完全記住；如果是 0，那就是完全忘記，中間的 W_f 、 b_f 作為待定係數需進行訓練學習。



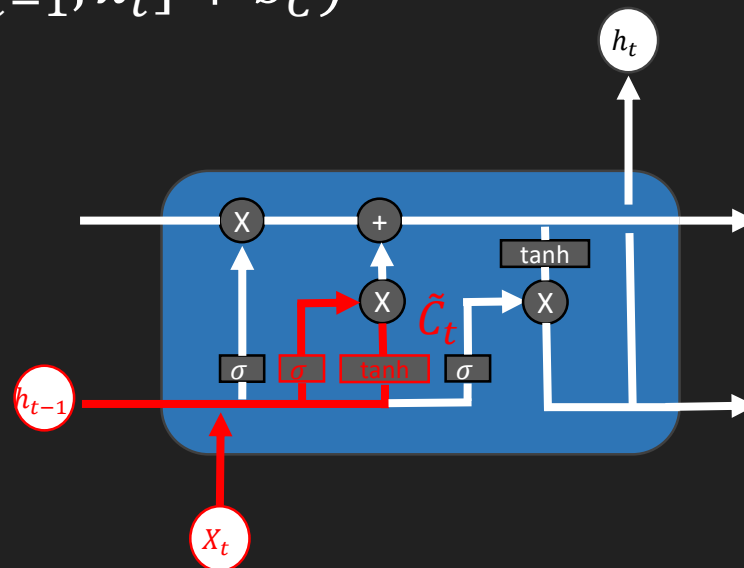
LSTM演算法

■ 這裡有兩個神經網路層一個是 σ ，表達式為：

- $i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$

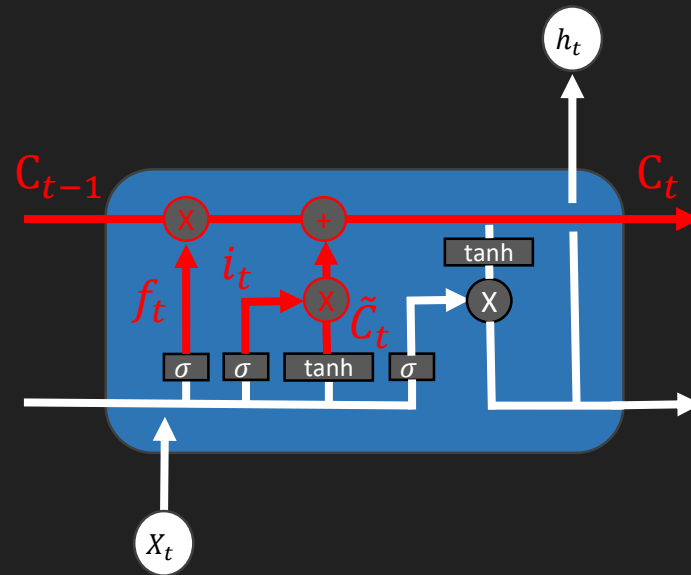
■ 一個是 \tanh ，表達式為：

- $\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$



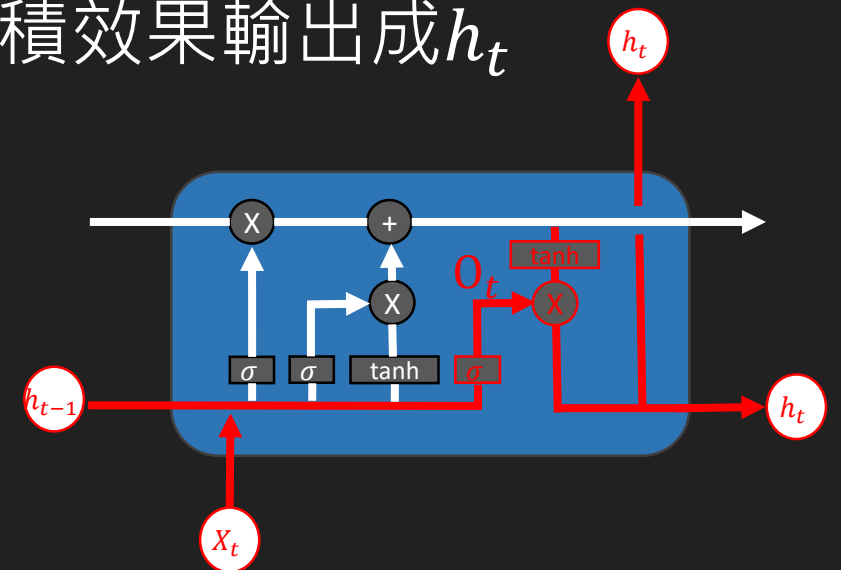
LSTM演算法

- 前一次傳遞過來的 C_{t-1} 向量會和 \tilde{C}_t 線性疊加
 - $C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$
- 那輸出的 C_t 究竟有多少採納本次輸入的訊息？有多少採納上一次遺留下來的訊息呢？



LSTM演算法

- 最後輸出有兩個 h_t ，一個輸出到同層下一個單元，一個輸出到下一層單元上
 - $O_t = \sigma(W_0 \cdot [h_{t-1}, x_t] + b_0)$
 - $h_t = O_t * \tanh(C_t)$
- 輸出的 C_t 向量又經過一個 O_t 遺忘閘的乘積效果輸出成 h_t



2. 應用情境

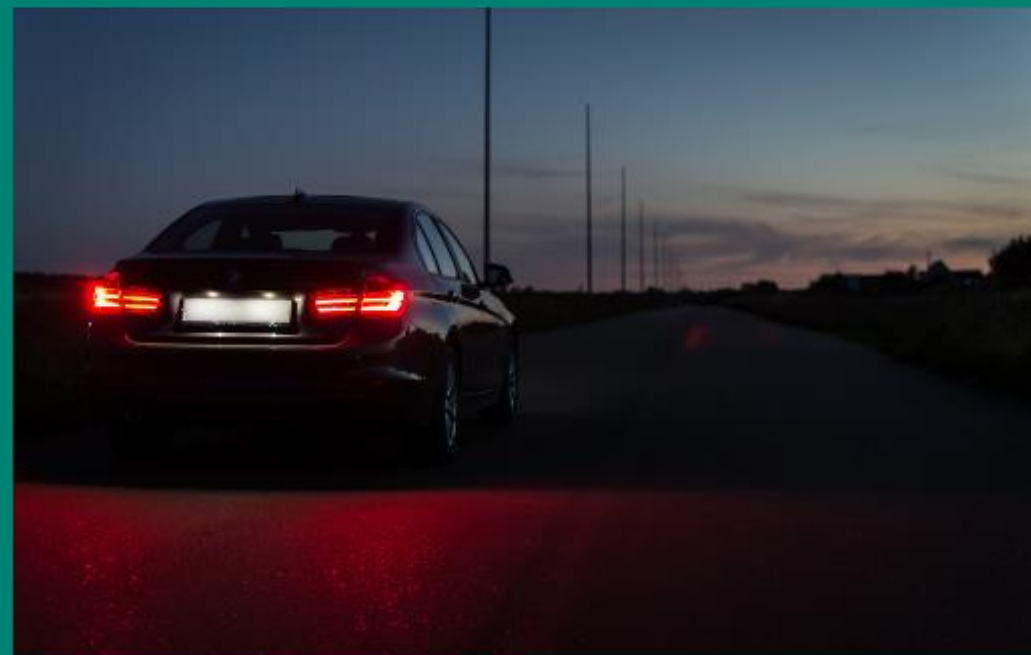
微軟的識圖機器人CaptionBot

- 是一種單一向量輸入，多向量輸出的情境(描述一張圖上的訊息)

I think it's a group of men playing a game of basketball and they seem 🤔 😐.



I think it's a car stopped at a red light at sunset.



圖像字幕模型開源碼

- Github 上的開源專案 CNN + RNN 模型
- CNN 用來提取特徵，RNN 用特徵的向量和描述向量來訓練
- 這種模型能夠標示下面這些圖片中有什麼物體(人物)，以及他們的狀態或者動作



<https://github.com/karpathy/neuraltalk2>

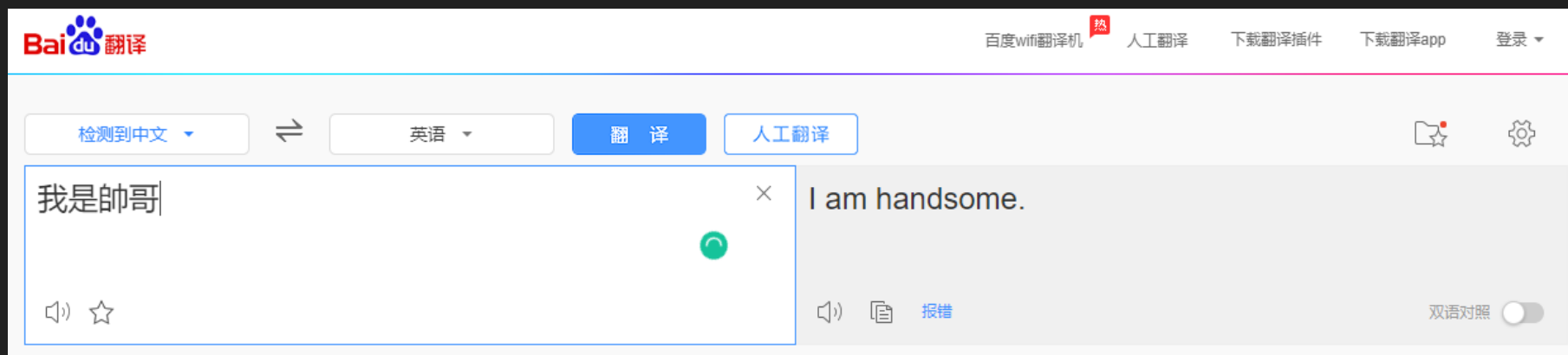
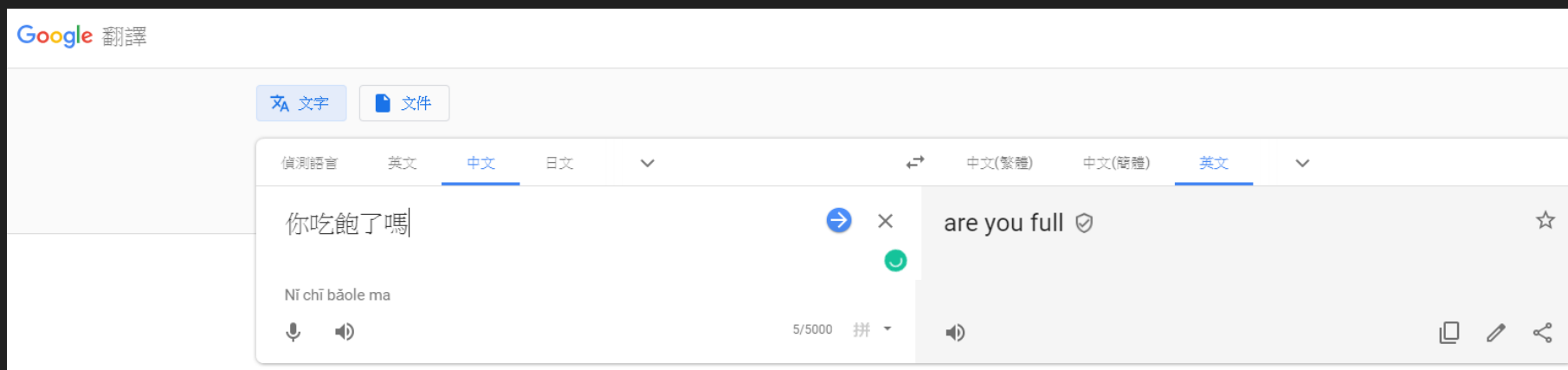
識別影片主題分類

- 專案 C3D: Generic Features for Video Analysis 可以實作主題的識別
- 目前多對撥放的體育競技內容進行分類識別



自動翻譯、聊天機器人

- 在客服、問訊系統等情境下應用，減少人工投入
- Google 翻譯、百度翻譯



描述影片段訊息開源碼

- Github 上的開源專案 RNN 模型
- Demo 影片中，網路能正確識別途中有一群人站在綠色的草坪

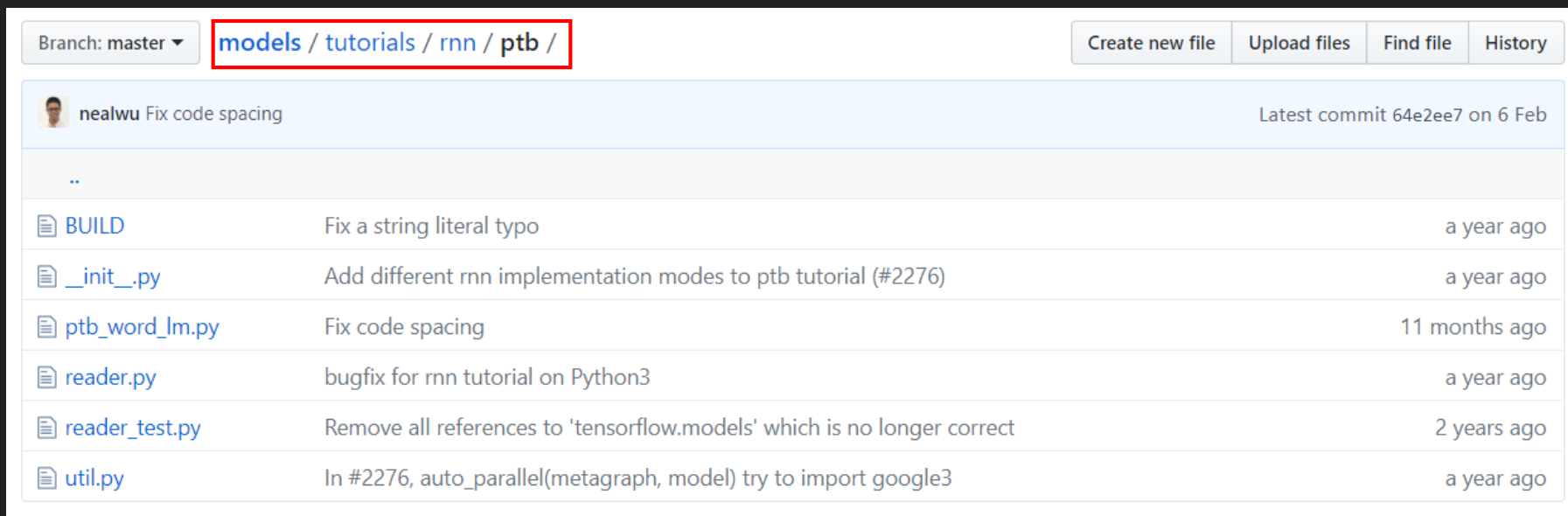


<https://github.com/samim23/NeuralTalkAnimator>

2. 使用TensorFlow完成實驗

使用 TensorFlow 完成實驗

- 採用循環神經網路 (Recurrent Neural Networks) 完成自動文字生成的小工程
- 使用 TensorFlow 官方提供最為經典的 RNN 入門案例
- <https://github.com/tensorflow/models/tree/master/tutorials/rnn/ptb>

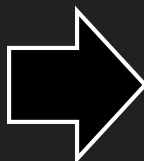
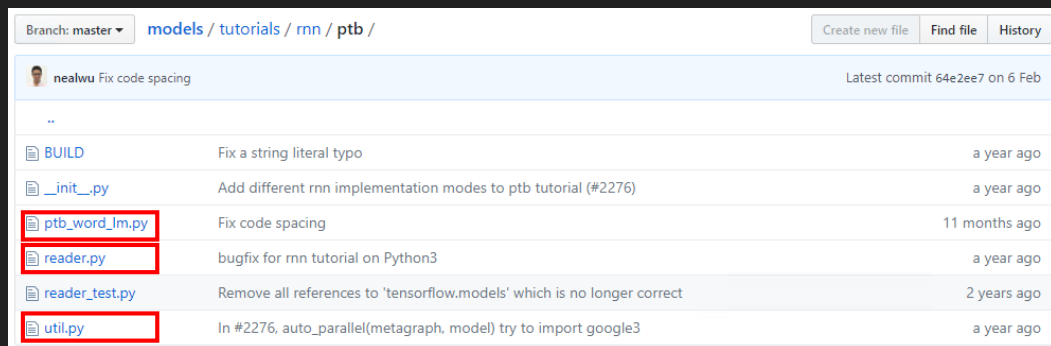


The screenshot shows the GitHub interface for the `models / tutorials / rnn / ptb` directory. The breadcrumb navigation path is highlighted with a red box. Below the navigation bar, a commit by `nealwu` is shown with the message "Fix code spacing". The latest commit hash is `64e2ee7` on Feb 6. A table of files in the directory is displayed below.

File	Description	Time
..		
<code>BUILD</code>	Fix a string literal typo	a year ago
<code>__init__.py</code>	Add different rnn implementation modes to ptb tutorial (#2276)	a year ago
<code>ptb_word_lm.py</code>	Fix code spacing	11 months ago
<code>reader.py</code>	bugfix for rnn tutorial on Python3	a year ago
<code>reader_test.py</code>	Remove all references to 'tensorflow.models' which is no longer correct	2 years ago
<code>util.py</code>	In #2276, <code>auto_parallel(metagraph, model)</code> try to import <code>google3</code>	a year ago

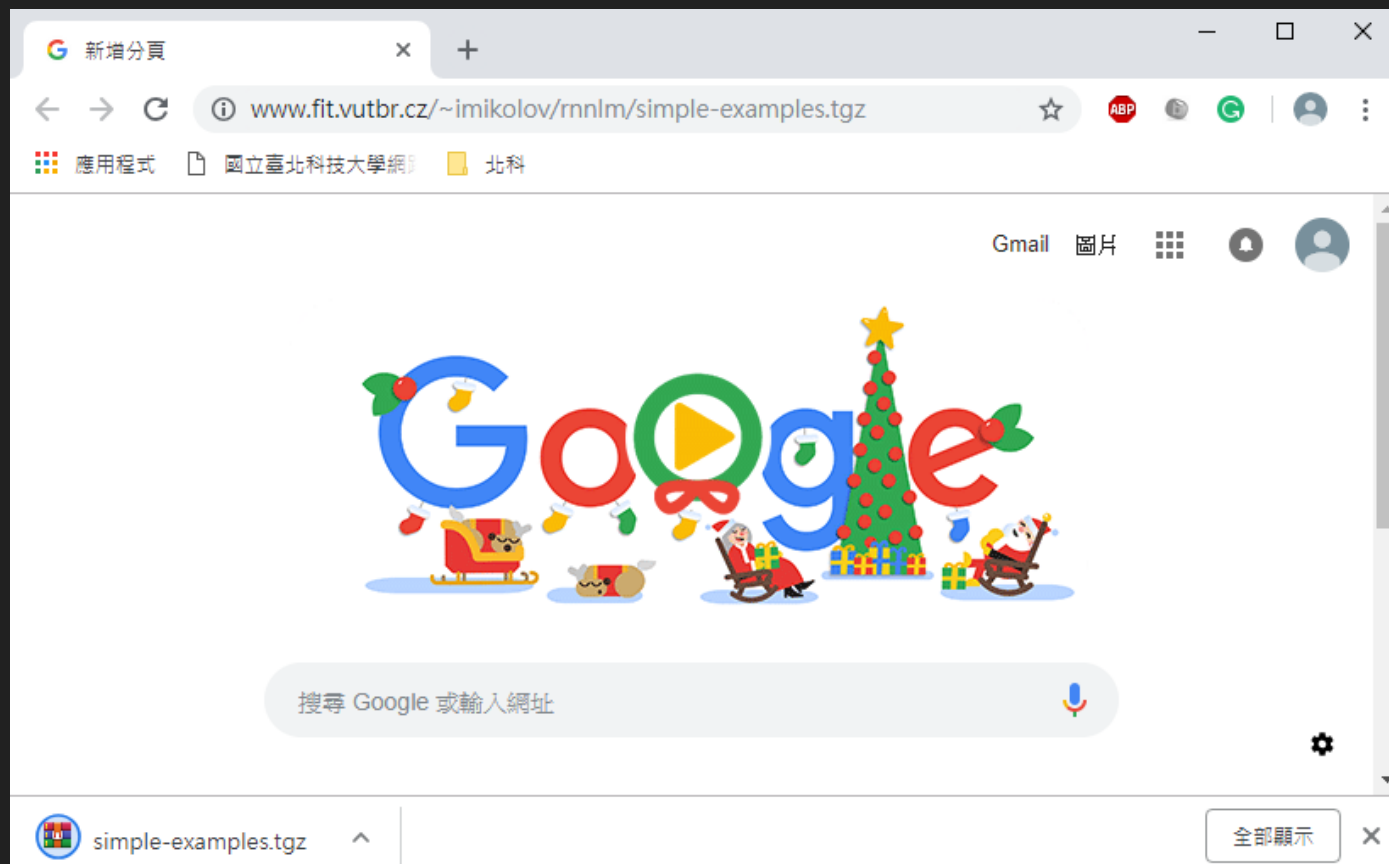
使用 TensorFlow 完成實驗

- 下載檔案 ptb_word_lm.py、reader.py、util.py 至 C:\ 目錄之下



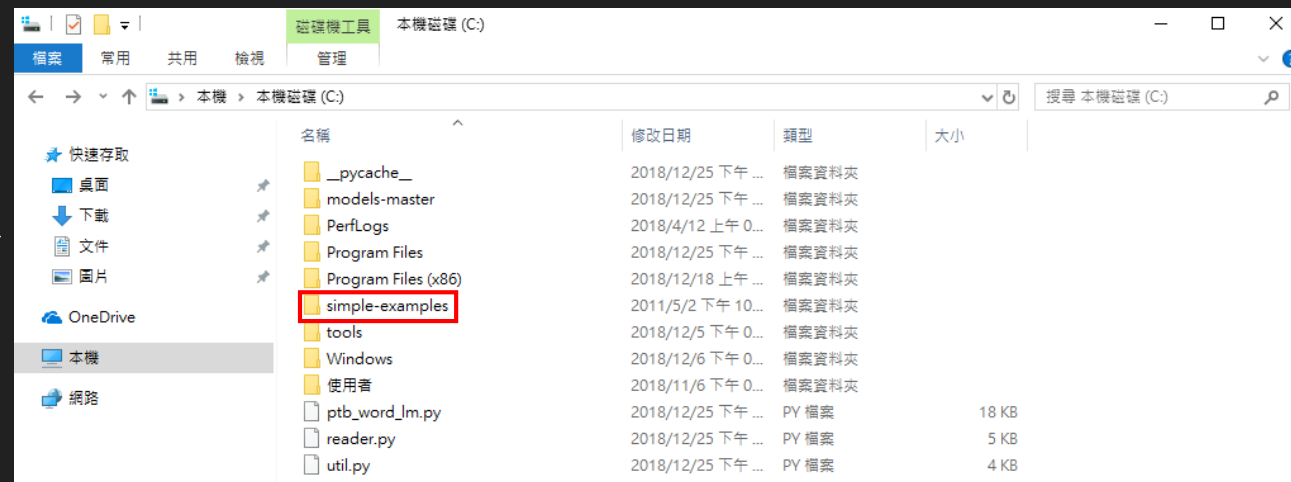
使用 TensorFlow 完成實驗

- 下載 simple-examples
- <http://www.fit.vutbr.cz/~imikolov/rnnlm/simple-examples.tgz>



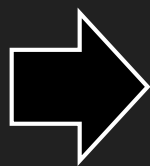
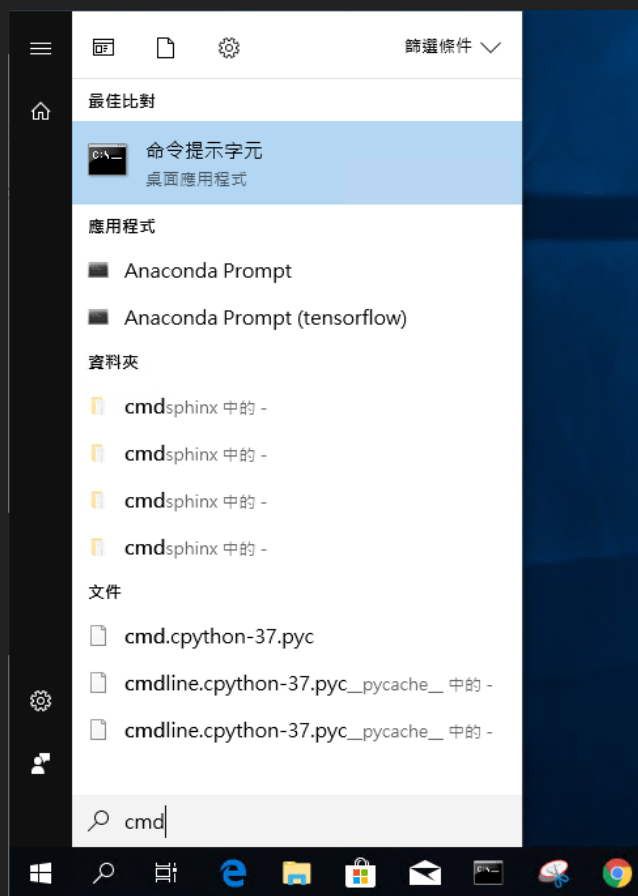
使用 TensorFlow 完成實驗

- 將 simple-examples.tgz 解壓縮至 C:\ 目錄之下



使用 TensorFlow 完成實驗

- 在搜尋輸入 cmd，開啟命令提示字元

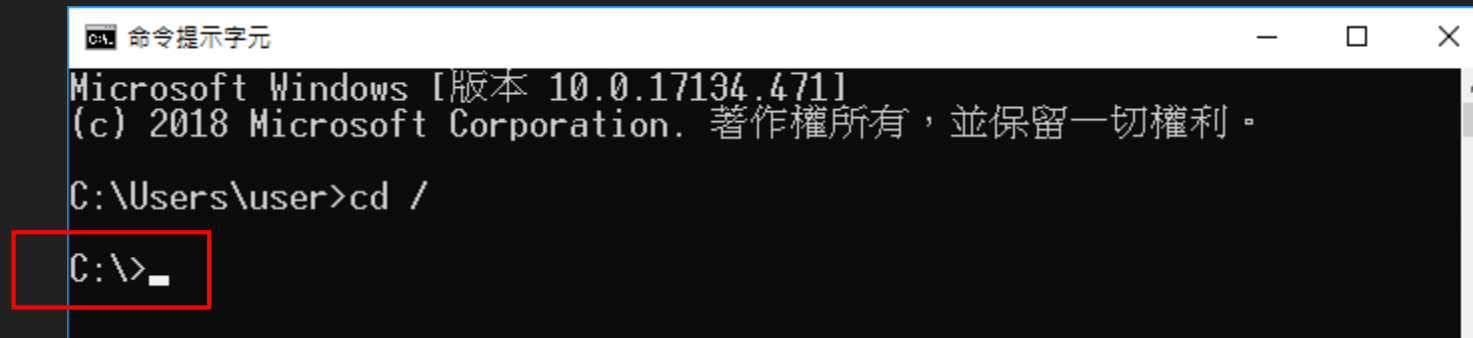


使用 TensorFlow 完成實驗

- 在 cmd 視窗，輸入以下指令

```
> cd /
```

- 工作路徑由 C:\Users\user 變成 C:\



A screenshot of a Windows Command Prompt window. The title bar reads "命令提示字元". The window content shows the following text: "Microsoft Windows [版本 10.0.17134.471]", "(c) 2018 Microsoft Corporation. 著作權所有，並保留一切權利。", "C:\Users\user>cd /", and "C:\>". The "C:\>" line is highlighted with a red rectangular box.

使用 TensorFlow 完成實驗

- 在 cmd 視窗，輸入以下指令

> **Activate tensorflow** # 之前已經建立該虛擬環境

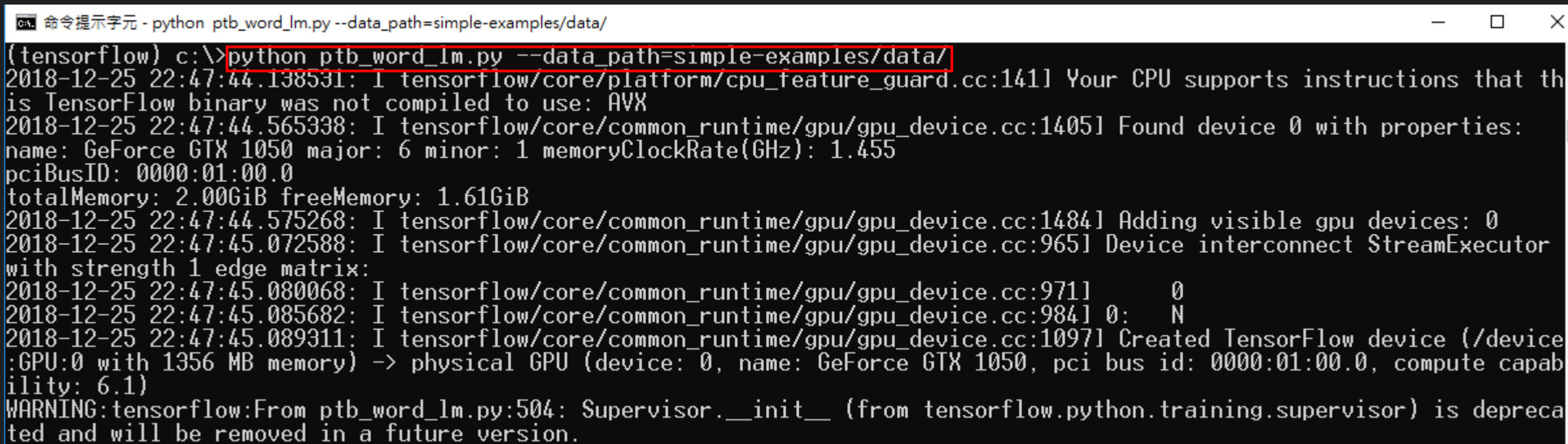


```
命令提示字元
C:\>activate tensorflow
(tensorflow) C:\>
```

使用 TensorFlow 完成實驗

- 在 cmd 視窗，輸入以下指令

> `python ptb_word_lm.py --data_path=simple-examples/data/`



```
命令提示字元 - python ptb_word_lm.py --data_path=simple-examples/data/
(tensorflow) c:\>python ptb_word_lm.py --data_path=simple-examples/data/
2018-12-25 22:47:44.138531: I tensorflow/core/platform/cpu_feature_guard.cc:141] Your CPU supports instructions that this TensorFlow binary was not compiled to use: AVX
2018-12-25 22:47:44.565338: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1405] Found device 0 with properties:
name: GeForce GTX 1050 major: 6 minor: 1 memoryClockRate(GHz): 1.455
pciBusID: 0000:01:00.0
totalMemory: 2.00GiB freeMemory: 1.61GiB
2018-12-25 22:47:44.575268: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1484] Adding visible gpu devices: 0
2018-12-25 22:47:45.072588: I tensorflow/core/common_runtime/gpu/gpu_device.cc:965] Device interconnect StreamExecutor with strength 1 edge matrix:
2018-12-25 22:47:45.080068: I tensorflow/core/common_runtime/gpu/gpu_device.cc:971]      0
2018-12-25 22:47:45.085682: I tensorflow/core/common_runtime/gpu/gpu_device.cc:984] 0:    N
2018-12-25 22:47:45.089311: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1097] Created TensorFlow device (/device:GPU:0 with 1356 MB memory) -> physical GPU (device: 0, name: GeForce GTX 1050, pci bus id: 0000:01:00.0, compute capability: 6.1)
WARNING:tensorflow:From ptb_word_lm.py:504: Supervisor.__init__ (from tensorflow.python.training.supervisor) is deprecated and will be removed in a future version.
```

使用 TensorFlow 完成實驗

- 出現這個畫面~成功
- Epoch = 13
- 困惑度 (Perplexity)

```
命令提示字元
0.903 perplexity: 41.805 speed: 15583 wps
Epoch: 11 Train Perplexity: 40.901
Epoch: 11 Valid Perplexity: 120.685
Epoch: 12 Learning rate: 0.004
0.004 perplexity: 59.853 speed: 15186 wps
0.104 perplexity: 45.295 speed: 15606 wps
0.204 perplexity: 49.544 speed: 15589 wps
0.304 perplexity: 47.502 speed: 15608 wps
0.404 perplexity: 46.690 speed: 15671 wps
0.504 perplexity: 45.908 speed: 15650 wps
0.604 perplexity: 44.384 speed: 15582 wps
0.703 perplexity: 43.727 speed: 15603 wps
0.803 perplexity: 42.981 speed: 15660 wps
0.903 perplexity: 41.523 speed: 15695 wps
Epoch: 12 Train Perplexity: 40.625
Epoch: 12 Valid Perplexity: 120.372
Epoch: 13 Learning rate: 0.002
0.004 perplexity: 59.583 speed: 15785 wps
0.104 perplexity: 45.086 speed: 15938 wps
0.204 perplexity: 49.330 speed: 15926 wps
0.304 perplexity: 47.309 speed: 15943 wps
0.404 perplexity: 46.509 speed: 15833 wps
0.504 perplexity: 45.736 speed: 15883 wps
0.604 perplexity: 44.221 speed: 15748 wps
0.703 perplexity: 43.566 speed: 15725 wps
0.803 perplexity: 42.824 speed: 15746 wps
0.903 perplexity: 41.371 speed: 15755 wps
Epoch: 13 Train Perplexity: 40.476
Epoch: 13 Valid Perplexity: 120.182
Test Perplexity: 113.936

(tensorflow) c:\>_
```


Ptb_world_lm.py 程式碼解析

```
def _get_lstm_cell(self, config, is_training):
    if config.rnn_mode == BASIC:
        return tf.contrib.rnn.BasicLSTMCell(
            config.hidden_size, forget_bias=0.0, state_is_tuple=True,
            reuse=not is_training)
    if config.rnn_mode == BLOCK:
        return tf.contrib.rnn.LSTMBlockCell(
            config.hidden_size, forget_bias=0.0)
    raise ValueError("rnn_mode %s not supported" % config.rnn_mode)
```

建立LSTM單元

```
def _build_rnn_graph_lstm(self, inputs, config, is_training):
    """Build the inference graph using canonical LSTM cells."""
    # Slightly better results can be obtained with forget gate biases
    # initialized to 1 but the hyperparameters of the model would need to be
    # different than reported in the paper.
```

```
    def make_cell():
        cell = self._get_lstm_cell(config, is_training)
        if is_training and config.keep_prob < 1:
            cell = tf.contrib.rnn.DropoutWrapper(
                cell, output_keep_prob=config.keep_prob)
        return cell
```

給lstm單元添加dropout

```
    cell = tf.contrib.rnn.MultiRNNCell(
        [make_cell() for _ in range(config.num_layers)], state_is_tuple=True)
```

建立多層lstm

```
    self._initial_state = cell.zero_state(config.batch_size, data_type())
    state = self._initial_state
    # Simplified version of tf.nn.static_rnn().
    # This builds an unrolled LSTM for tutorial purposes only.
    # In general, use tf.nn.static_rnn() or tf.nn.static_state_saving_rnn().
```

Ptb_world_lm.py 程式碼解析

```
with tf.device("/cpu:0"):
    embedding = tf.get_variable(
        "embedding", [vocab_size, size], dtype=data_type())
    inputs = tf.nn.embedding_lookup(embedding, input_.input_data)
```

每個單詞使用一個唯一向量
表示，word_embedding

```
if is_training and config.keep_prob < 1:
    inputs = tf.nn.dropout(inputs, config.keep_prob)
```

給輸出層添
加dropout

```
output, state = self._build_rnn_graph(inputs, config, is_training)
```

```
softmax_w = tf.get_variable(
    "softmax_w", [size, vocab_size], dtype=data_type())
softmax_b = tf.get_variable("softmax_b", [vocab_size], dtype=data_type())
logits = tf.nn.xw_plus_b(output, softmax_w, softmax_b)
# Reshape logits to be a 3-D tensor for sequence loss
logits = tf.reshape(logits, [self.batch_size, self.num_steps, vocab_size])
```

過一層全連接

```
# Use the contrib sequence loss and average over the batches
loss = tf.contrib.seq2seq.sequence_loss(
    logits,
    input_.targets,
    tf.ones([self.batch_size, self.num_steps], dtype=data_type()),
    average_across_timesteps=False,
    average_across_batch=True)
```

運算loss

```
# Update the cost
self._cost = tf.reduce_sum(loss)
self._final_state = state
```

Ptb_world_lm.py 程式碼解析

```
outputs = []
with tf.variable_scope("RNN"):
    for time_step in range(self.num_steps):
        if time_step > 0: tf.get_variable_scope().reuse_variables()
        (cell_output, state) = cell(inputs[:, time_step, :], state)
        outputs.append(cell_output)
    output = tf.reshape(tf.concat(outputs, 1), [-1, config.hidden_size])
```

開始訓練循環

```
self._lr = tf.Variable(0.0, trainable=False)
tvars = tf.trainable_variables()
grads, _ = tf.clip_by_global_norm(tf.gradients(self._cost, tvars),
                                   config.max_grad_norm)
optimizer = tf.train.GradientDescentOptimizer(self._lr)
self._train_op = optimizer.apply_gradients(
    zip(grads, tvars),
    global_step=tf.train.get_or_create_global_step())

self._new_lr = tf.placeholder(
    tf.float32, shape=[], name="new_learning_rate")
self._lr_update = tf.assign(self._lr, self._new_lr)
```

使用梯度下降最佳化演算法運算
梯度，更新降低
learning rate，
擷取一下梯度值

Ptb_world_lm.py 程式碼解析

```
sv = tf.train.Supervisor(logdir=FLAGS.save_path)
config_proto = tf.ConfigProto(allow_soft_placement=soft_placement)
with sv.managed_session(config=config_proto) as session:
```

```
    for i in range(config.max_max_epoch):
```

```
        lr_decay = config.lr_decay ** max(i + 1 - config.max_epoch, 0.0)
        m.assign_lr(session, config.learning_rate * lr_decay)
```

-----> 降低更新learning rate

```
        print("Epoch: %d Learning rate: %.3f" % (i + 1, session.run(m.lr)))
```

```
        train_perplexity = run_epoch(session, m, eval_op=m.train_op,
                                     verbose=True)
```

```
        print("Epoch: %d Train Perplexity: %.3f" % (i + 1, train_perplexity))
```

```
        valid_perplexity = run_epoch(session, mvalid)
```

```
        print("Epoch: %d Valid Perplexity: %.3f" % (i + 1, valid_perplexity))
```

分別使用訓練資料
和驗證資料執行一
個epoch

```
test_perplexity = run_epoch(session, mtest)
```

```
print("Test Perplexity: %.3f" % test_perplexity)
```

-----> 使用測試資料直接一個epoch

```
if FLAGS.save_path:
```

```
    print("Saving model to %s." % FLAGS.save_path)
```

```
    sv.saver.save(session, FLAGS.save_path, global_step=sv.global_step)
```

-----> 儲存模型

Ptb_world_lm.py 程式碼解析

```
def main(_): -----> 使用TensorFlow後首先調用main函數
    if not FLAGS.data_path:
        raise ValueError("Must set --data_path to PTB data directory")
    gpus = [
        x.name for x in device_lib.list_local_devices() if x.device_type == "GPU"
    ]
    if FLAGS.num_gpus > len(gpus):
        raise ValueError(
            "Your machine has only %d gpus "
            "which is less than the requested --num_gpus=%d."
            % (len(gpus), FLAGS.num_gpus))

    raw_data = reader.ptb_raw_data(FLAGS.data_path)
    train_data, valid_data, test_data, _ = raw_data -----> 準備訓練、驗證和測試資料集

    config = get_config()
    eval_config = get_config()
    eval_config.batch_size = 1
    eval_config.num_steps = 1 -----> 獲取訓練參數和驗證相關參數
```

Ptb_world_lm.py 程式碼解析

```
class SmallConfig(object):  
    """Small config."""  
    init_scale = 0.1  
    learning_rate = 1.0  
    max_grad_norm = 5  
    num_layers = 2  
    num_steps = 20  
    hidden_size = 200  
    max_epoch = 4  
    max_max_epoch = 13  
    keep_prob = 1.0  
    lr_decay = 0.5  
    batch_size = 20  
    vocab_size = 10000  
    rnn_mode = BLOCK
```

```
class MediumConfig(object):  
    """Medium config."""  
    init_scale = 0.05  
    learning_rate = 1.0  
    max_grad_norm = 5  
    num_layers = 2  
    num_steps = 35  
    hidden_size = 650  
    max_epoch = 6  
    max_max_epoch = 39  
    keep_prob = 0.5  
    lr_decay = 0.8  
    batch_size = 20  
    vocab_size = 10000  
    rnn_mode = BLOCK
```

```
class LargeConfig(object):  
    """Large config."""  
    init_scale = 0.04  
    learning_rate = 1.0  
    max_grad_norm = 10  
    num_layers = 2  
    num_steps = 35  
    hidden_size = 1500  
    max_epoch = 14  
    max_max_epoch = 55  
    keep_prob = 0.35  
    lr_decay = 1 / 1.15  
    batch_size = 20  
    vocab_size = 10000  
    rnn_mode = BLOCK
```

```
class TestConfig(object):  
    """Tiny config, for testing."""  
    init_scale = 0.1  
    learning_rate = 1.0  
    max_grad_norm = 1  
    num_layers = 1  
    num_steps = 2  
    hidden_size = 2  
    max_epoch = 1  
    max_max_epoch = 1  
    keep_prob = 1.0  
    lr_decay = 0.5  
    batch_size = 20  
    vocab_size = 10000  
    rnn_mode = BLOCK
```

四組不同的訓練參數設定

reader.py 程式碼解析

```
def _read_words(filename):  
    with tf.gfile.GFile(filename, "r") as f:  
        if Py3:  
            return f.read().replace("\n", "<eos>").split()  
        else:  
            return f.read().decode("utf-8").replace("\n", "<eos>").split()
```

讀檔案裡的資料，把“\n”換行符換成“<eos>”，返回所有出現的單詞列表

```
def _build_vocab(filename):  
    data = _read_words(filename)  
    counter = collections.Counter(data)  
    count_pairs = sorted(counter.items(), key=lambda x: (-x[1], x[0]))  
    words, _ = list(zip(*count_pairs))  
    word_to_id = dict(zip(words, range(len(words))))  
    return word_to_id
```

把每個單詞對應一個唯一id

```
def _file_to_word_ids(filename, word_to_id):  
    data = _read_words(filename)  
    return [word_to_id[word] for word in data if word in word_to_id]
```

把檔案裡的單詞變成對應的id

```
def ptb_raw_data(data_path=None):  
    train_path = os.path.join(data_path, "ptb.train.txt")  
    valid_path = os.path.join(data_path, "ptb.valid.txt")  
    test_path = os.path.join(data_path, "ptb.test.txt")  
  
    word_to_id = _build_vocab(train_path)  
    train_data = _file_to_word_ids(train_path, word_to_id)  
    valid_data = _file_to_word_ids(valid_path, word_to_id)  
    test_data = _file_to_word_ids(test_path, word_to_id)  
    vocabulary = len(word_to_id)  
    return train_data, valid_data, test_data, vocabulary
```

返回訓練、驗證、測試資料集(單詞變成對應id之後的結果)和檔案裡出現的詞彙總數

reader.py 程式碼解析

```
def ptb_producer(raw_data, batch_size, num_steps, name=None):
    with tf.name_scope(name, "PTBProducer", [raw_data, batch_size, num_steps]):
        raw_data = tf.convert_to_tensor(raw_data, name="raw_data", dtype=tf.int32)

        data_len = tf.size(raw_data)
        batch_len = data_len // batch_size
        data = tf.reshape(raw_data[0 : batch_size * batch_len],
                           [batch_size, batch_len])

        epoch_size = (batch_len - 1) // num_steps
        assertion = tf.assert_positive(
            epoch_size,
            message="epoch_size == 0, decrease batch_size or num_steps")
        with tf.control_dependencies([assertion]):
            epoch_size = tf.identity(epoch_size, name="epoch_size")

        i = tf.train.range_input_producer(epoch_size, shuffle=False).dequeue()
        x = tf.strided_slice(data, [0, i * num_steps],
                             [batch_size, (i + 1) * num_steps])
        x.set_shape([batch_size, num_steps])
        y = tf.strided_slice(data, [0, i * num_steps + 1],
                             [batch_size, (i + 1) * num_steps + 1])
        y.set_shape([batch_size, num_steps])
        return x, y
```

把資料和其對應的標籤
分為若干個batch返回

-END-