

Beam test performance of the highly granular SiW-ECAL technological prototype for the ILC.

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Abstract

The technological prototype of the CALICE highly granular silicon-tungsten electromagnetic calorimeter (SiW-ECAL) tested in beam at DESY in 2017. In this test the setup comprised seven layers of 1024 channels and a size of $18 \times 18 \text{ cm}^2$ each. This article presents key performance results in terms of signal over noise ratios at different levels of the readout chain and a study of the uniformity of the detector response.

Keywords: Calorimeter methods, calorimeters, Si and pad detectors

1. Introduction

The International Linear Collider, ILC [1, 2, 3, 4, 5], is a next generation of e^+e^- linear colliders project. It will provide collisions of polarized beams with center-of-mass energies between 250 GeV and 1 TeV. These collisions will be studied by multipurpose detectors. The two proposed projects [5] – the International Large Detector (ILD) and the Silicon Detector (SiD) – are designed for the use of Particle Flow (PF) technique [6, 7], for the reconstruction of the final state particles. The PF techniques rely on single particle separation to allow for the selection of the best information available in the full detector to determine the final states of the collisions.

They allow reducing the impact of the poor resolution of the calorimeter systems (compared with trackers) in the overall reconstruction but require detectors with highly granular, compact and hermetic calorimetric systems. Furthermore, the PF capabilities are enhanced when the calorimeters are placed inside a large magnetic field that favors the separation of charged particles. This in turn calls for a compact design of the calorimeters. Most of the R&D efforts of such calorimeters for future linear colliders are carried out by the CALICE collaboration.

This document reports on the performance in beam test of the technological prototype of the silicon-tungsten electromagnetic calorimeter, the SiW-ECAL. The SiW-ECAL is the baseline choice for the ILD ECAL. It will be placed, together with the hadronic calorimeter of the ILD, inside a magnetic field of at least 3T. Silicon constitutes the active and tungsten the passive material of the detector. The overall thickness is 24 radiation lengths (X_0) or about 1 interaction length.

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The choice of silicon and tungsten makes possible the design of a very compact calorimeter with high granularity in 3 dimensions. The baseline design for the ILD foresees 26-30 layers in the barrel region enclosed in about 23 cm thick structures. The active sensors will be segmented in squared cells of $5 \times 5 \text{ mm}^2$, for a total of ~ 80 million readout channels for the barrel region of the ECAL of the ILD. The dynamic range in each channel will range from 0.5 to 3000 MIPs, where the MIP acronym stands for both the most probable value of the energy deposited by a minimum-ionizing-particle and the particle itself. In order to minimize external services and maximize the hermeticity, the very-front-end (VFE) electronics must be embedded in the calorimeter modules and be cooled only passively. In turn, to reduce overall power consumption, the SiW-ECAL will exploit the particular bunch structure foreseen for the ILC: the e^+e^- bunches trains will arrive within time windows of $\sim 1\text{-}2$ ms width separated by ~ 200 ms. The data acquisition will be gated during these 1-2 ms and the bias currents of the electronics will be shut down to save power during the idle time. This technique is usually denominated as power pulsing. Finally, the calorimeters will operate in self-trigger mode (each channel featuring a discriminator for internal trigger decision) and on-chip zero suppression mode.

2. The SiW-ECAL technological prototype

The first SiW-ECAL prototype was the so-called SiW-ECAL physics prototype [8]. It was extensively tested at DESY, FNAL and CERN [9, 10, 11, 12, 13]. The VFE was placed outside the active area with no particular constraints on power consumption. It consisted of 30 layers of silicon sensors alternated with tungsten plates yielding a total of $24 X_0$. The active layers were made of a matrix of 3×3 silicon sensors of $500 \mu\text{m}$ thickness. Each of these sensors was segmented in matrices of 6×6 squared pixels of $10 \times 10 \text{ mm}^2$.

The new generation prototype dubbed the SiW-ECAL technological prototype addresses the main technological challenges: compactness, power consumption reduction through power pulsing and VFE inside the detector.

A picture showing the SiW-ECAL technological prototype setup tested at DESY (Hamburg) in summer 2017 can be seen in Figure 1. The setup consists of 7 layers housed in a PVC and aluminum structure that can host up to 10 layers in slots with a 15-mm pitch. The first six layers were placed in the first six slots and the 7th in the last one. From now on, the layers will be referenced by their numbers from 1 to 7. The detector was

commissioned in the laboratory and afterwards exposed to a low energy positron beam in the DESY test beam area (line 24) [14] the first layer located at the most upstream on the beam. All results presented here are obtained with the detector running in power pulsing mode and with gated acquisitions of 1 – 3 ms at frequencies of 1-5 Hz.

Each layer consists of a readout module on top of a carbon cradle that protects the sensors and the sides of the module. The readout module is further wrapped by two aluminum plates that provide electromagnetic shielding and mechanical stability. The readout module itself consists of an Active Signal Unit (ASU) and an adapter board to a data acquisition system (DAQ)[15, 16, 17] at the beginning of the module. In the picture, the ASU is covered by an aluminum plate marked by the red number 1. The ASU consist of a $18 \times 18 \text{ cm}^2$ sized printed circuit board, PCB, equipped with 16 VFE ASICs and 4 silicon sensors glued onto the other side. The PCB features 1024 square pads of $5.5 \times 5.5 \text{ mm}^2$ that are readout by the ASICs. Part of the adapter board is also covered by the aluminum plate and the uncovered part is seen over the red number 2 in the picture. The adapter board also holds other services e.g. the super capacitance used for the power pulsing. This decoupling capacitor of 400 mF with 16 m Ω of equivalent serial resistance provides enough local storage of power to assure stable low voltage supply during the power pulsing. This capacitor is seen just above the red number 2. The first component of the DAQ system, the detector interface board described in [15], is identified in the picture by a red number 3. For simplicity, the rest of the DAQ system is not shown.

The VFE ASICs are 16 SKIROC2 [18, 19, 20] (Silicon pin Kalorimeter Integrated ReadOut Chip), that have been designed for the readout of silicon PIN diodes. The SKIROC2 in LFBGA package are bump bonded to the PCB. The version of the ASUs tested in this beam test has a thickness of 2.8 mm including the ASICs in its current packaging. Each of these SKIROC2 comprises 64 readout channels made of a variable-gain preamplifier followed by two branches: a fast line for the self-trigger decision and a slow line for dual-gain charge measurement. The gain on the preamplifier is set by changing the feedback capacitor, C_f . The fast line consists of a high gain variable CRRC shaper followed by a low offset discriminator to make the trigger decision. A common 10-bit DAC provides the threshold of the discriminator. The slow line is made of a low gain and a high gain CRRC shapers to handle a large dynamic range. When a channel triggers, a track and hold cell is used to record the signal at its peaking

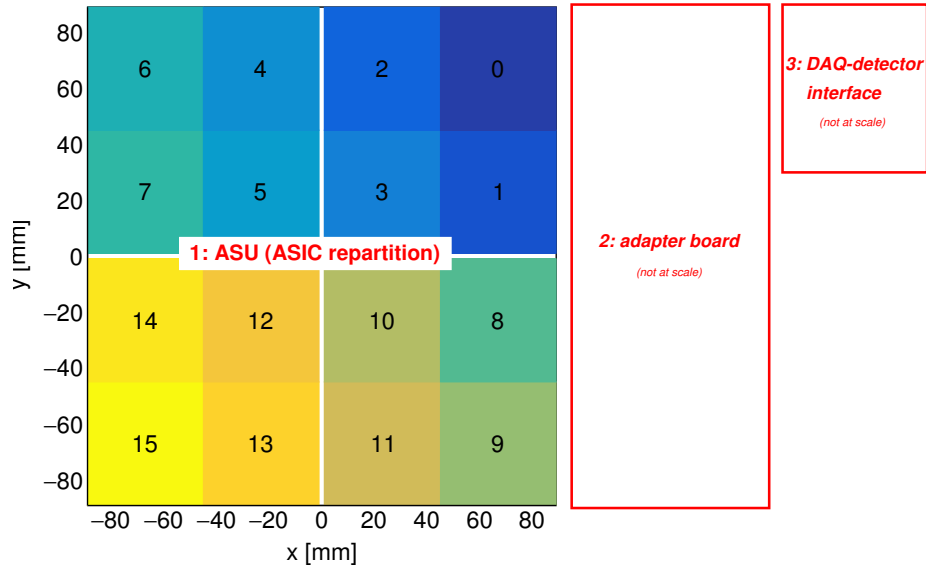
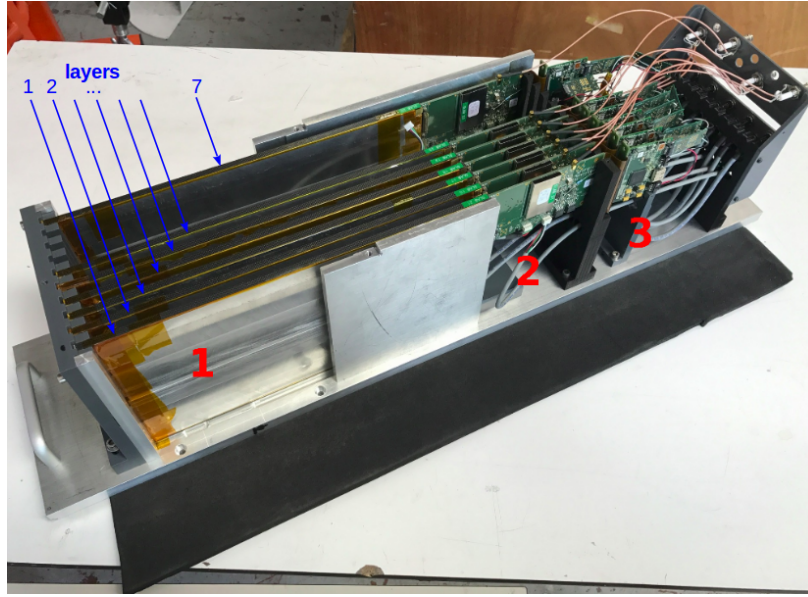


Figure 1: Top: prototype with 7 layers inside the mechanical housing. Bottom: schematic view of the readout modules including the surface repartition readout by each ASIC, numbered from 0 to 15. Notice that the adapter board and DAQ-detector interface drawings are not at scale.

time in the dual gain line. The levels of all the others channels are then also recorded. The triggers are timestamped within each gated acquisition with a slow clock of 5 MHz. The timestamp numbers are called brunch crossing identifiers (BCID). The charges are stored in the buffers of a switched capacitor array, SCA, and later converted by a 12-bit Wilkinson ADC. The ASIC consumes, in the power pulsing conditions as foreseen for the ILC, $27 \mu\text{W}$ per channel.

The four sensors consist of $90 \times 90 \text{ mm}^2$ silicon sensors of $320 \pm 15 \mu\text{m}$ thick with high resistivity (bigger than $5000 \Omega\cdot\text{cm}$). Each sensor is subdivided in an array of 256 PIN diodes of $5.5 \times 5.5 \text{ mm}^2$ connected each to the PCB pads by a dot of conductive glue. The high voltage to deplete the sensors is delivered to the sensors via a $100 \mu\text{m}$ copper foil isolated from the rest of the setup by a kapton sheet. It has been estimated that a MIP traversing the PIN perpendicular to its surface pro-

duces, in average, a signal of 4 fC.

3. Performance at positron beam test at DESY

The beam line at DESY provides continuous positron beams in the energy range of 1 to 6 GeV with rates from a few hundreds of Hz to a few kHz with a maximum of ~ 3 kHz for 2-3 GeV. In addition, DESY gives access to a bore 1 T solenoid.

The physics program of the beam test can be summarized as follows:

1. Calibration without tungsten absorber using 3 GeV positrons interacting, in the first approach, as MIPs. The beam was normally directed to 81 positions equally distributed over the modules surface.
2. Test in a magnetic field up to 1 T using, also without tungsten and with 3 GeV positrons. For this test, a PVC structure was designed and produced to support one single readout module.
3. Response to electrons of different energies with a fully equipped detector, *i.e.* sensitive parts *and* tungsten absorber.

In this paper, we discuss in detail the results of the commissioning of the prototype in Section 3.1 and the results of the pedestal, noise and MIP calibration in Section 3.2. We also show the results on the pedestal and noise stability when the readout modules are placed inside a magnetic field, in Section 3.3.

3.1. Commissioning of the detector

Earlier experience with the SKIROC2 ASIC is been reported in [19, 21, 20]. For the following, the internal SKIROC2 parameters determined in these references are adopted except if otherwise stated. Since most of the data taking program consisted of the recording of MIP level signals, we set a low value of the feedback capacitance of the preamplifier to $C_f = 1.2$ pF to obtain gains of 71.25 mV/fC and 7.125 mV/fC in the dual-gain charge measurement. With the higher of both gains, the SKIROC2 ensures a linearity better than 90% for 0.5-200 MIPs, sufficient for the analysis of electromagnetic showers created by few GeV positrons. All data presented here were taken with the higher of the two gains.

3.1.1. Masking of noisy readout channels

As a very first step channels are disabled that triggered already at a threshold above 1 MIP noise runs. For details the reader is referred to [22]. The disabled channels can be classified into four categories:

- Routing issues: The same channels trigger in all layers. This hints at a issue with the routing of the PCB. Following a conservative approach, we added to this set all channels that were noisy in at least three modules.
- ASIC issues: In case 70% of the channels of an ASIC triggered at, the entire ASIC was disabled.
- Sensor issues: If a wafer showed problems like e.g. high leakage currents, all channels connected to the wafer were disabled.
- Others.

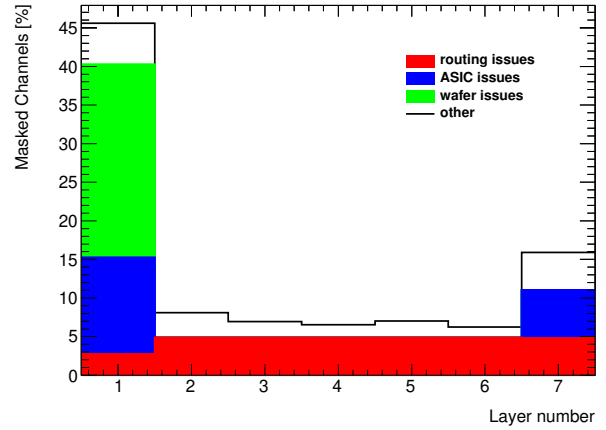


Figure 2: Fraction of channels with counts above one MIP in noise runs and that have been disabled for the data taking.

All these channels have been disabled for the data taking.

3.1.2. Trigger threshold optimization and signal-over-noise ratio for the trigger

The threshold of the internal trigger can be optimized by means of dedicated scans of trigger threshold values with only noise signals or with injected signals of different amplitudes. The trigger thresholds used for data taking of the individual channels are determined by lowering successively the trigger thresholds of the channels and recording the number of counts. The resulting curves can be approximated by an inverted error function. A value of the optimal threshold was calculated for every channel by shifting the threshold from the threshold at the 50% of the curve plus 3 times the width of the curve, with the width defined as half the difference between the thresholds at which the curve is equal to $50 \pm 34\%$. The average of the optimal thresholds for

all channels is used as the optimal global threshold to be used by the ASIC. If the analysis has failed in more than 50% of the channels (*i.e.* because they are masked), an *ad-hoc* high value of the threshold is chosen for the ASIC (250 in DAC units).

Note here that the width of the curve defined before depends on the ratio of the frequency of the white noise of the electronics and the clock speed of the readout. Therefore, the width is not a proper measurement of the detector noise. To achieve this the scan has to be repeated with external signals. These can either be provided by signals generated by beam particles or by injecting signals into the channels. Here we follow the second approach. Amplitudes equivalent to 1 and 2 MIPs were injected into channels of an ASIC mounted on a testboard.

The result of these scans is shown in Figure 3 for several channels of one SKIROCs. These curves allow for the trigger threshold calibration and the estimation of signal-over-noise ratio for the trigger, $(S/N)_{trigger}$, defined as the ratio between the distance of the 1 MIP and 2 MIP threshold curves scans at its 50% of efficiency and the width of the 1 MIP threshold scan curve. From the measurement shown in Figure 3 we extract a $(S/N)_{trigger}$ ratio of about 12.8.

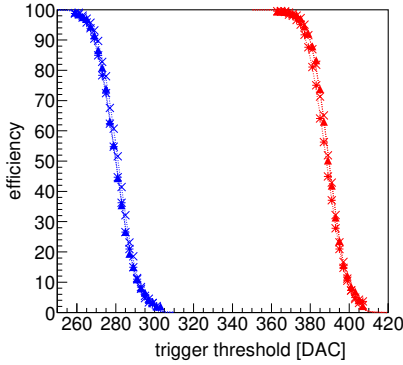


Figure 3: Threshold curves with charge injection (1 MIP in blue and 2 MIPs in red) for different channels in a SKIROC2 testboard. From this plot, we extract a $(S/N)_{trigger}$ of about 12.8 in the trigger line.

The trigger threshold calibration (from DAC units to MIPs) is extracted from these curves following a simple formula:

$$1 - Threshold[MIP] = \frac{DAC_{50\%}(1 \text{ MIP}) - Threshold[DAC]}{DAC_{50\%}(2 \text{ MIP}) - DAC_{50\%}(1 \text{ MIP})} \quad (1)$$

where $DAC_{50\%}(X \text{ MIP})$ stands for the DAC value in

the 50% point of the threshold scan curve obtained with X MIP signals. This calibration has been applied to all readout modules: see Figure 4. Further dedicated data taking runs with particle beams are needed in the future to measure the uncertainty and spread between SKIROCs and modules of the used calibration.

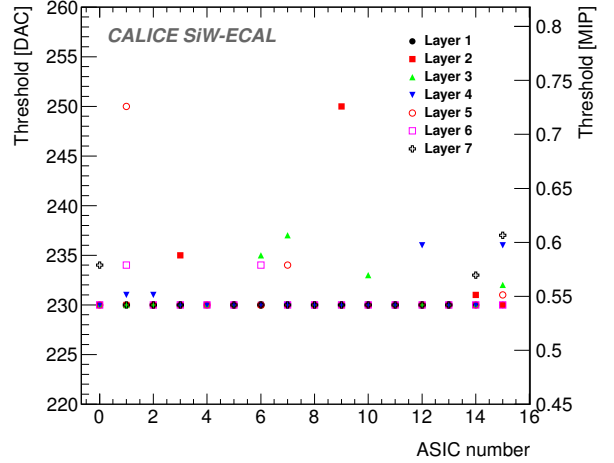


Figure 4: Summary of the trigger threshold settings in the internal DAC units and in MIP units.

3.2. Response to 3 GeV positrons acting as MIPs

All the analyses presented here rely on the selection and identification of tracks-like events. The first step of the reconstruction is the rejection of two types of fake events due to the ASIC design: *a)* triggers in consecutive BCIDs due to the preamplifiers sensitivity to instabilities of the power supply; *b)* an artifact of the event validation logical sequence of the ASIC. These fake events are removed offline using timing information. Residual electromagnetic showers are rejected by requiring less than 5 triggers per module. Tracks are therefore reconstructed by creating clustered events from the seven layers grouped using their time stamp, allowing for a tolerance on the BCID of ± 1 . An event is accepted if at least three of the layers were clustered together in a track traversing the modules in the same position for all modules with a tolerance of ± 5.5 mm per layer.

3.2.1. Pedestal and noise determination

The pedestal distribution for each channel and SCA corresponds to the distribution of ADC counts recorded by the channel when another one was triggered. The distributions are fit by a Gaussian. The mean of the

Gaussian is interpreted as the pedestal position. The width of the pedestal is associated to the standard deviation of the Gaussian. Both values are calculated for all ASICS, channels and SCA under test. Using these calculated pedestal positions, the pedestal subtraction to all measured charges in ADC counts is performed. This process is done in a layer, ASIC, channel and SCA basis. As a summary, all the calculated pedestal positions and widths of the ADC for all non-triggered and non-masked channels and SCAs are shown in Figure 5. The non-gaussian spread of the pedestal position is explained by the fact that each SCA has its own pedestal value. More important is that the width of the distributions is very similar for all channels and SCAs. This is a proof of the homogeneity of the noise levels within the system.

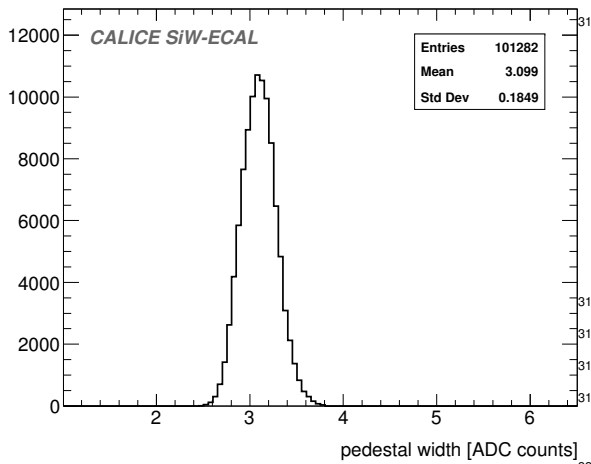
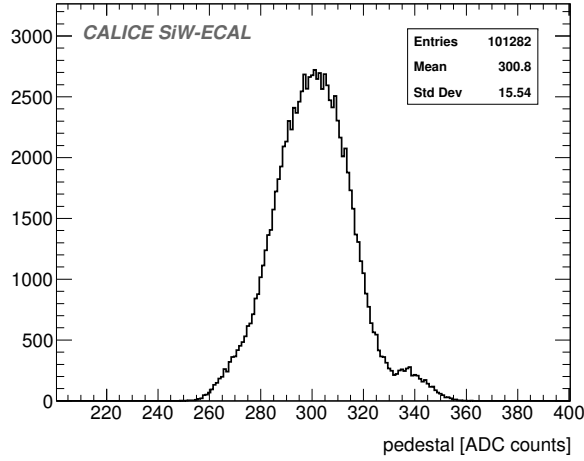


Figure 5: Pedestal mean position (upper) and width (lower) for all channels and all SCAs in the setup.

3.2.2. MIP calibration

For all channels under test, the resulting charge spectrum of the triggered channels after pedestal correction are fit by a Landau function convoluted with a Gaussian if the number of events was larger than 1000. The most-probable-value of the Landau function is taken as the MIP value, allowing thus for a direct conversion from ADC counts to energy in MIP units.

The fit succeeded in 98% of the cases and the spread of the resulting MIP calibration is 5%. The remaining channels are discarded in the following analysis. Results are summarized in Figure 6.

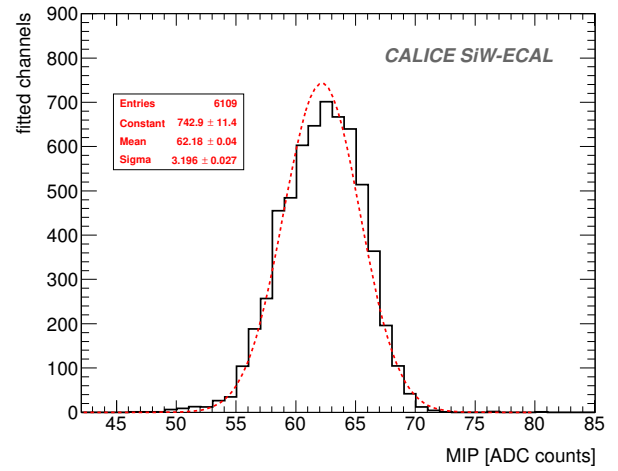


Figure 6: Result of the MIP calibration for all calibrated channels.

3.2.3. Signal-over-noise ratio for the charge measurement of triggered channels

The signal over-noise-ratio for the charge measurement of triggered channels, $(S/N)_{charge}$, is defined as the ratio of the calculated MIP values to the noise (the pedestal width) for each channel and SCA. This quantity has been calculated for all channels under test, giving:

$$(S/N)_{charge} = 20.4 \pm 1.5 \quad (2)$$

The results are summarized in Figure 7. The excellent ratio ensures that low energetic hits just above the trigger threshold can actually be used for the event reconstruction.

3.2.4. MIP detection efficiency

To evaluate the single hit detection efficiency we increased the purity of our tracks sample by requiring tracks with at least 4 layers with a hit in exactly the

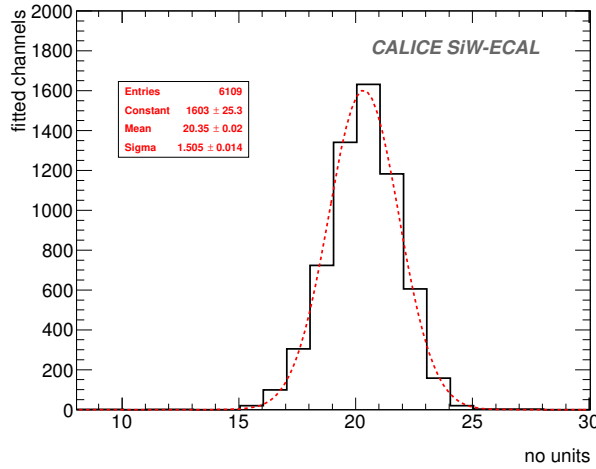


Figure 7: Distribution of the $(S/N)_{charge}$ for all calibrated channels.

same channel. For the remaining three layers the search region is extended to the eight channels surrounding the target channel. Residual spurious signals are filtered by requiring a minimal energy deposition of 0.3 MIP. The averaged results for every ASIC are shown in Figure 8. Except for a few exceptions, the efficiency is compatible with 100%. The low efficiencies in the first layer are related to the presence of noisy channels not spotted during the commissioning. These channels saturate the DAQ in their ASICs earlier than in others. In the last layer we also observe few small deviations which are associated to channels in the periphery, hinting for a small misalignment of the last layer.

3.3. Pedestal and noise stability in a magnetic field

Data were recorded without magnetic field as reference for values of the magnetic field of 0.5 T and 1T, respectively. The beam, 3 GeV positrons, was incident on the area of the PCB readout by the ASIC number 12.

The pedestal position and width of all channels in the readout module inside of the magnetic field are compared with their values obtained in Section 3.2. This is shown in Figure 9. We see that the agreement is perfect within the statistical uncertainties. Due to the lower rates in this beam area, the analysis is only done up to few memory cells and at least 500 entries are required in order to calculate the pedestals for comparison with the default values.

4. Summary and outlook

In this document we present the results on the commissioning in beam of a small but fully equipped SiW-

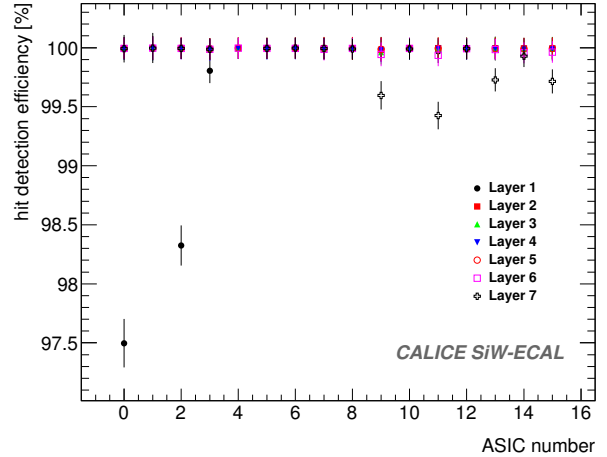


Figure 8: MIP detection efficiency in high purity samples of tracks of MIP-like acting particles for all layers. The average for all readout channels in each ASICs is shown. The error bars correspond to the standard deviation of the efficiency distribution of all channels in the ASIC.

ECAL technological prototype made of readout modules featuring the main characteristics foreseen for future high energy e^+e^- collider detectors. For the first time results are presented for detection units featuring 1024 channels as designed for e.g. the ILD Detector in a setup optimized for a physics program dedicated to the study of electromagnetic showers. The seven layers under study were operated in power pulsed mode. Therefore this article constitutes a first reference for the detector performance in this operation mode. The beam test has allowed for studying in detail the performance of the detector. The detector response is homogeneous with 98% of the non masked channels calibrated at a spread of the 5%. The signal over noise on the trigger has been evaluated to be about 12.8, a value that allows to for setting trigger below the MIP level with high efficiency although new dedicated beam tests are required to know the uncertainty and spread of this value among different modules and ASICs. The signal over noise on the charge measurement for triggered channels is 20.4, which ensures that all channels with a trigger just about noise level can be used in the data analysis. The MIP detection efficiency in tracks has been evaluated to be compatible with the 100% in most of the channels.

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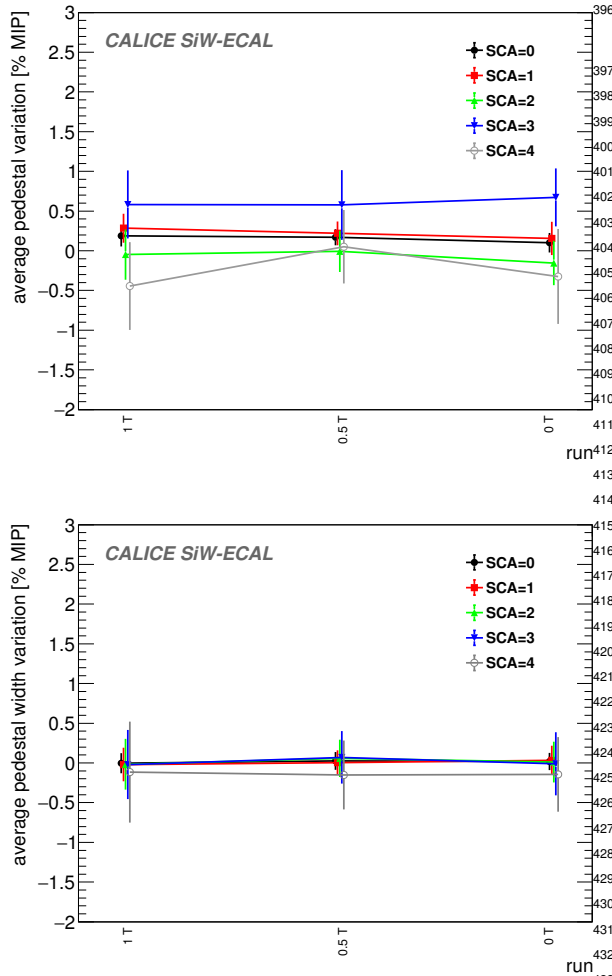


Figure 9: Average deviation of the pedestal mean position (up) and width (down). The error bars correspond to one standard deviation of the averaged values.

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