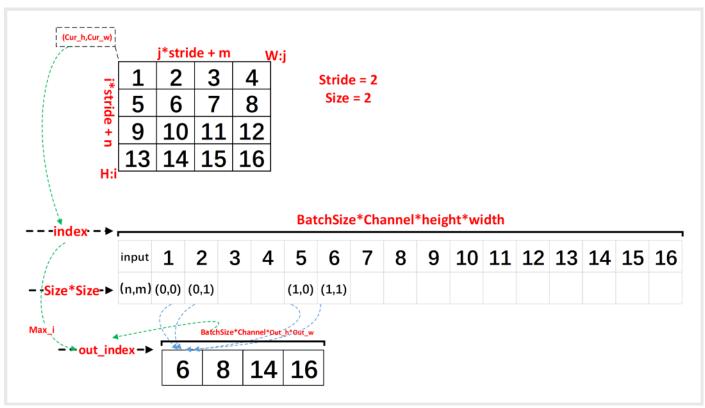
batch-batchsize



maxpool_layer make_maxpool_layer(int batch, int h, int w, int c, int size, int stride, int padding)

```
h-height
w-width
size-kernelSize
Stride-stride
Padding-padding

//计算池化操作后的输出尺寸

//w_out=(w_in + 2*pad - kernel_size) / stride +1;

///h_out =(h_in + 2*pad - kernel_size) / stride +1;

1. out_w = (w + 2*padding)/stride;

1. out_h = (h + 2*padding)/stride;

void forward_maxpool_layer(const maxpool_layer 1, network net)

{
    int b, i, j, k, m, n;
    int w_offset = -1. pad/2;
    int h offset = -1. pad/2;
```

```
int h = 1.out h;
    int w = 1.out_w;
    int c = 1.c;
    //遍历输出元素
    for (b = 0; b < 1. batch; ++b) {
       for (k = 0; k < c; ++k) {
           for (i = 0; i < h; ++i) {
               for (j = 0; j < w; ++j) {
                   int out_index = j + w*(i + h*(k + c*b));//计算输出索引
                   float max = -FLT MAX;
                   int max i = -1;
                    //依次取出kernelSize*kernelSize个元素
                   for (n = 0; n < 1. size; ++n) {
                       for (m = 0; m < 1. size; ++m) {
                             //依次计算当前kernel内部元素的相对坐标
                           int cur_h = h_offset + i*l.stride + n;
                           int cur_w = w_offset + j*l.stride + m;
                             //根据相对坐标计算出一维数组的真实坐标
                           int index = cur w + 1. w*(cur h + 1. h*(k + b*1. c));
                             //边界检查
                           int valid = (cur h \geq 0 && cur h \leq 1.h &&
                                       cur w >= 0 \&\& cur w < 1.w);
                             //取出元素
                           float val = (valid != 0) ? net.input[index] : -FLT_MAX;
                             //确定最大值元素及其角标
                           \max i = (val > max) ? index : max i;
                           \max = (val > max) ? val : max;
                       }
                     //输出kernel内最大元素及其角标
                   1. output[out index] = max;
                   1. indexes[out_index] = max_i;
       }
   }
void backward_maxpool_layer(const maxpool_layer 1, network net)
    int i;
    int h = 1.out h;
    int w = 1.out w;
    int c = 1.c;
```

```
for(i = 0; i < h*w*c*l.batch; ++i){
    //梯度只传给上一层最大值位置的神经元,其余神经元的梯度都是0
    int index = l.indexes[i];
    net.delta[index] += l.delta[i];
}
```