# Fast MRI Reconstruction

From Compressed Sensing to Deep Learning

### **Motivation**

MRI normally takes 15-90 min.

What if the patient could not bear such a long time in the noisy machine? Or what if the condition requires fast diagnosis?

→ Shortening the time of MRI scanning and reconstruction



### **Motivation**

#### Possible solution:

- Subsampling k-space data and then estimate the fully-sampled MRI image without reducing the quality.
- Current methods: GRAPPA/CS noise amplification
- Deep Learning (DL): recognizing patterns and detecting features
- Applying DL to MRI reconstruction

## Theory: Compressed Sensing (CS)

Optimization problem:

$$\min_{u} \mathcal{R}(u) + \frac{\lambda}{2} \left\| Au - f \right\|_{2}^{2}$$

$$A = M \circ \mathcal{F} \circ S$$

Solved by iterative methods such as Gradient Descent

Weakness: low quality of output / reconstruction takes a relatively long time

## Theory: Deep Learning (DL General Info)

End-to-End Variational Network

Same optimization problem as in CS

$$\min_{oldsymbol{u}} \mathcal{R}(oldsymbol{u}) + rac{\lambda}{2} \left\| Aoldsymbol{u} - oldsymbol{f} 
ight\|_2^2$$

Training parameters in Convolutional Neural Network

Unroll iterations (gradient descent) by layer:

$$oldsymbol{u}^{t+1} = oldsymbol{u}^t - \sum_{i=1}^{N_k} (K_i^t)^ op \Phi_i^{t\prime}(K_i^t oldsymbol{u}^t) - \lambda^t A^* (A oldsymbol{u}^t - oldsymbol{f})$$

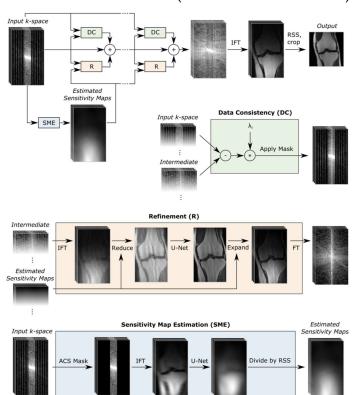
(Knoll, Hammernik, Zhang, Moeller, Pock, Sodickson, & Akcakaya. 2018) <sup>5</sup>

## Theory: Deep Learning Architecture

Input: raw k-space data Output: reconstructed image In one epoch:

- 1. Estimate sensitivity map using the same architecture
- 2. Run VarNetBlock (one cascade) for 12 times

(Johnson et al. 2020)



## Theory: Deep Learning Architecture (Cont'd)

```
k^{t+1} = k^t - \eta^t M(k^t - \tilde{k}) + \mathcal{F} \circ \varepsilon \circ \text{CNN} \left( \mathcal{R} \circ \mathcal{F}^{-1}(k^t) \right)
For each cascade:
   def forward(
        self,
        current_kspage: torch.Tensor,
        ref_kspace: 'torch.Tensor,
        mask: torch. Tensor,
        sens_maps: torch.Tensor,
    ) -> torch Tensor:
        zero \neq torch.zeros(1, 1, 1, 1, 1).to(current_kspace)
        soft'dc = torch.where(mask', current_kspace - ref_kspace, zero) * self.dc_weight
        model_term = self.sens_expand( /
             self.model(self.sens_reduce(current_kspace, sens_maps)), sens_maps
        return current kspace - soft dc - model term
```

### **Dataset**

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fastMRI (http://fastmri.med.nyu.edu/): a public open MRI dataset

Multicoil brain validation dataset is used in this project.

Format: Brain / Multicoil / 2D / Field strength: 1.5 or 3 T

Type: T1 / T1 PRE / T1 POST / T2 / FLAIR

Number of coils: 16 or 20 (probably not accurate; randomly checked)

### Factors & Variables

```
Training:
     #epochs
     # training dataset
     Training with (5 types or only FLAIR, 40 volumes in total)
     Training mask type (Equispaced/Random)
     Training acceleration rate (4/8/4+8)
Reconstruction:
     Reconstruction mask type (Equispaced/Random)
     Reconstruction acceleration rate (4/8/4+8)
```

## Random Subsampling

num cols = shape[-2]center\_fraction, acceleration = self.choose\_acceleration() # create the mask num\_low\_freqs = int(round(num\_cols \* center\_fraction)) prob = (num\_cols / acceleration - num\_low\_freqs) / ( num\_cols - num\_low\_freqs mask = self.rng.uniform(size=num\_cols) < prob</pre> pad = (num\_cols - num\_low\_freqs + 1) // 2 mask[pad : pad + num\_low\_freqs] = True # reshape the mask mask\_shape = [1 for \_ in shape] (https://github.com/facebookresearch/fastMRI)  $mask\_shape[-2] = num\_cols$ mask = torch.from numpy(mask.reshape(\*mask shape).astype(np.float32))

## **Equispaced Subsampling**

```
# determine acceleration rate by adjusting for the number of low frequencies
adjusted accel = (acceleration * (num low freqs - num cols)) / (
    num_low_freqs * acceleration - num_cols
offset = self.rng.randint(0, round(adjusted accel))
accel_samples = np.arange(offset, num_cols - 1, adjusted_accel)
accel samples = np.around(accel samples).astype(np.uint)
mask[accel_samples] = True
4 times acceleration: 8% central lines + 17% others
8 times acceleration: 4% central lines + 8.5% others
```

### **Evaluation Metrics**

Peak Signal-to-Noise Ratio:

$$PSNR(x,y) = 10 \log_{10} \frac{\max(y)^2}{MSE(x,y)}$$

where  $MSE = \frac{1}{n} \|x - y\|_2^2$ 

x is the reconstructed image and y is the ground truth (target)

(Zbontar, Knoll, Sriram, Murrell, Huang, Muckley, Defazio, Stern, Johnson, Bruno. 2018)

#### Structural Similarity:

SSIM
$$(x, y) = \frac{(2\mu_x \mu_y + C_1)(2\sigma_{xy} + C_2)}{(\mu_x^2 + \mu_y^2 + C_1)(\sigma_x^2 + \sigma_y^2 + C_2)}$$

where 
$$\mu_x = \frac{1}{N} \sum_{i=1}^N x_i$$

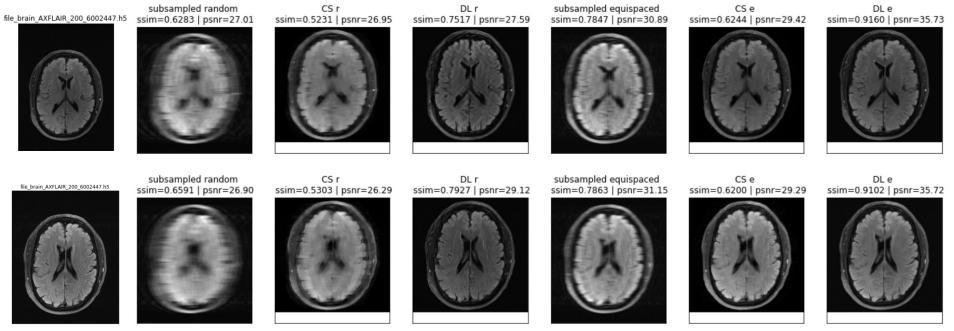
$$\sigma_x = \left(\frac{1}{N-1} \sum_{i=1}^N (x_i - \mu_x)^2\right)^{\frac{1}{2}}$$

$$\sigma_{xy} = \frac{1}{N-1} \sum_{i=1}^N (x_i - \mu_x)(y_i - \mu_y)$$

(Wang, Bovik, Sheikh, Simoncelli. 2004)

### Test 1: CS vs. DL

```
Aim: compare the reconstruction quality
Setting:
CS: BartToolBox
DL: Training:
           #epochs =100
          Training dataset: 8*5 types = 40 volumes
          Training mask type: same as the recon mask type (e-e / r-r)
          Training acceleration rate: 4+8 mixture
     Recon:
           "file_brain_AXFLAIR_200_6002447.h5"
           Recon mask type: same as the training mask type (e-e / r-r)
           Recon acceleration rate: 4
```



Ground truth

CS r	SSIM	PSNR	DLr	SSIM	PSNR
Avg	0.42	27.3	Avg	0.83	30.2
Std	0.13	0.66	Std	0.05	3.12

CS e	SSIM	PSNR	
Avg	0.48	28.8	
Std	0.15	0.68	

DL e	SSIM	PSNR
Avg	0.93	38.1
Std	0.01	1.67

### Test 1: CS vs. DL

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#### Conclusion:

The performance of DL is better than performance of CS.

The gap between CS and DL is smaller in random reconstruction.

#### **Future direction:**

Test random scattered subsampling (here it is random line subsampling).

## Test 2: Mask Type

**Aim:** understand the influence of mask type in the training process

#### Setting:

#### Training:

#epochs =100

Training dataset = 8\*5 types= 40 volumes

Training mask type: equispaced or random

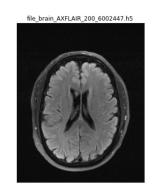
Training acceleration rate = 4+8

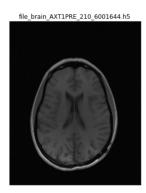
#### Recon:

"file\_brain\_AXFLAIR\_200\_6002447.h5" & "file\_brain\_AXT1PRE\_210\_6001644.h5"

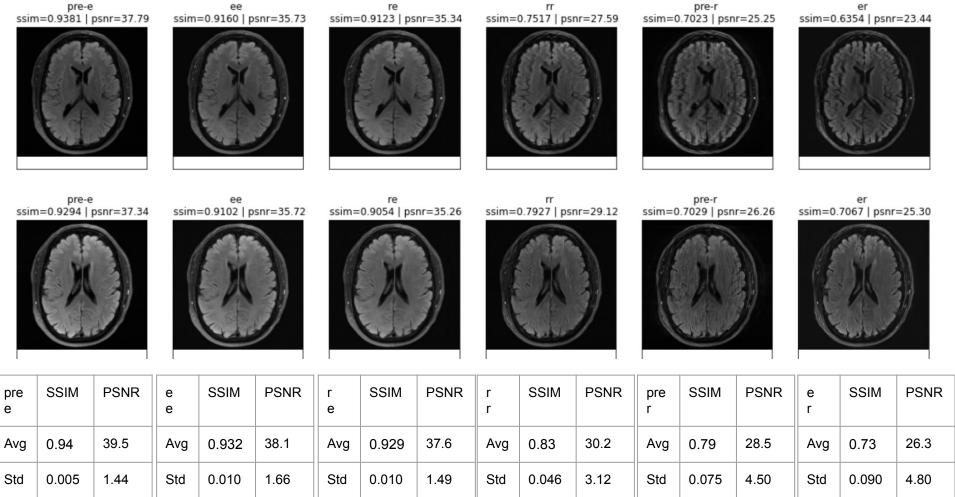
Recon mask type: equispaced or random

Recon Acceleration Rate: 4

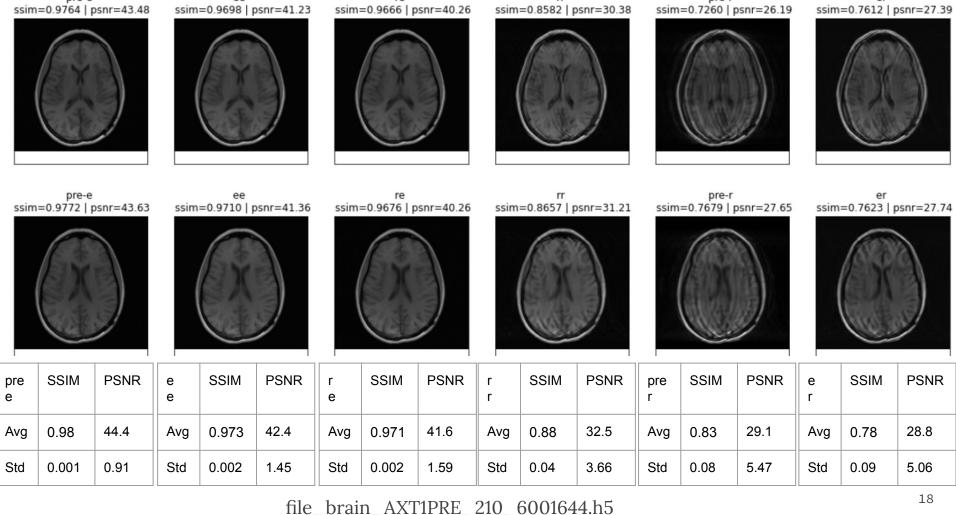




Ground truth



file brain AXFLAIR 200 6002447.h5



pre-r

pre-e

### Test 2: Mask Type

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#### Conclusion:

Recon performance: pre-e > ee > re >> rr > pre-r ~ er

Possible reason: equispaced also contains some randomness and it's easier to infer.

#### **Future direction:**

Further understanding of why re is better than rr.

## **Test 3: Training Acceleration Rate**

**Aim:** understand the influence of acceleration rate in the training process

#### Setting:

```
Training:

#epochs =100

Training dataset = 8*5 types = 40 volumes

Training mask type: equispaced

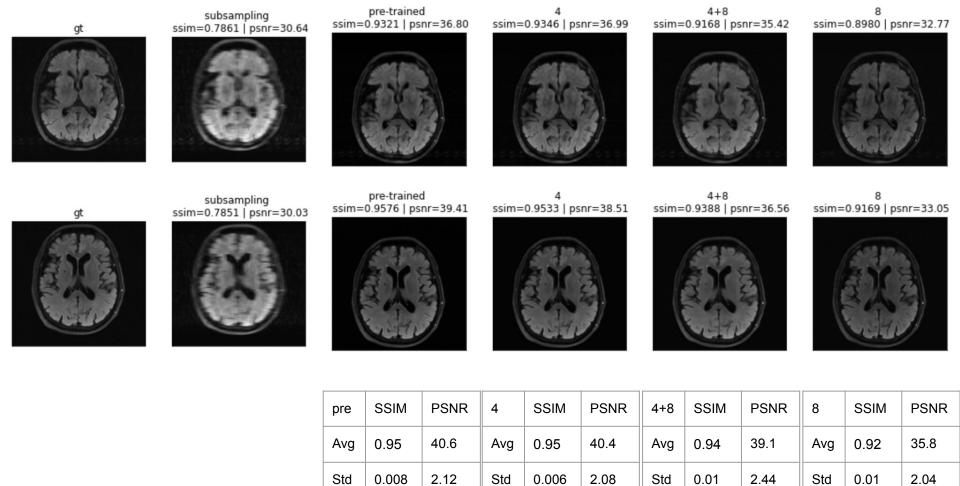
Training acceleration rate = 4+8 / only 4 / only 8

Recon:
```

"file\_brain\_AXFLAIR\_201\_6002868.h5"

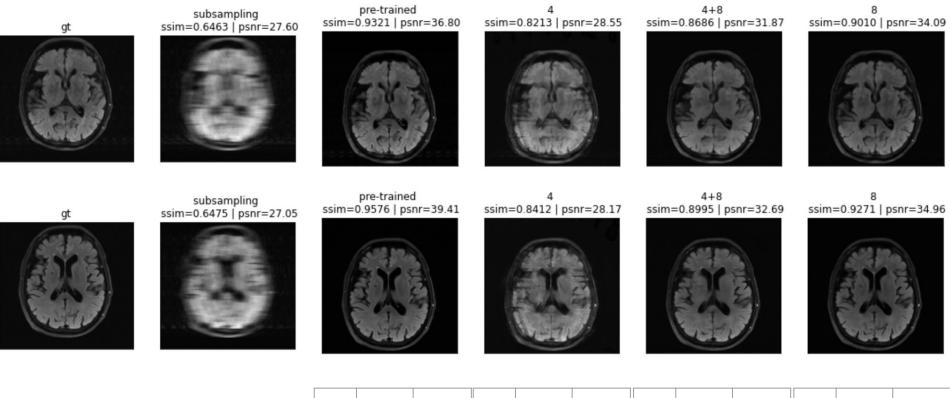
Recon mask type: equispaced

Recon Acceleration Rate: 4 / 8



Std

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_	J



pre	SSIM	PSNR	4	SSIM	PSNR	4+8	SSIM	PSNR	8	SSIM	PSNR
Avg	0.95	40.6	Avg	0.87	31.9	Avg	0.91	35.8	Avg	0.93	38.1
Std	0.008	2.12	Std	0.03	3.40	Std	0.02	3.51	Std	0.01	3.02

## Test 3: Training Acceleration Rate

Conclusion:

Recon 4: pre-trained > 4 > 4+8 > 8

Recon 8: pre-trained  $> 8 \sim 4+8 > 4$ 

#### **Future direction:**

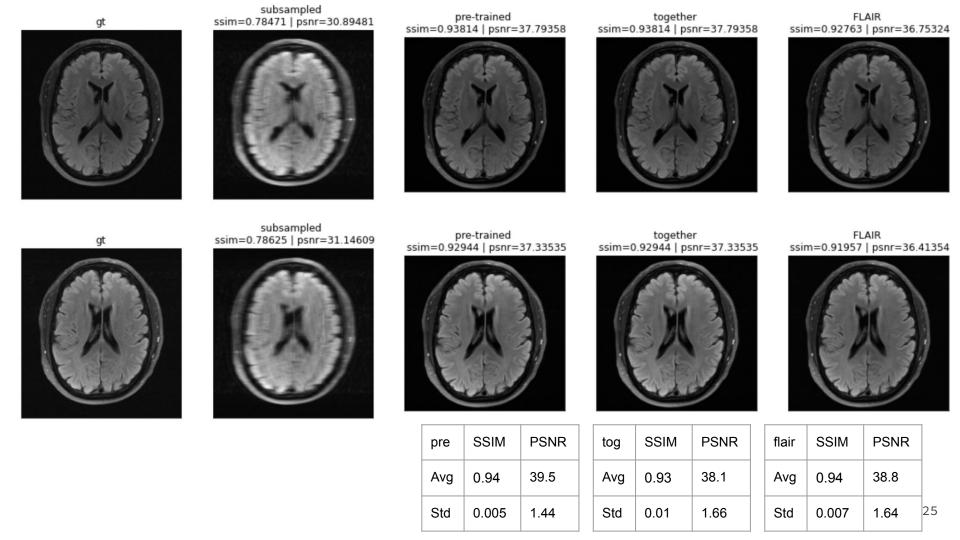
Testing if we want to reconstruct 8 times acceleration, incorporating a certain amount of 4 times acceleration (or even 2 times acceleration) would help improve the results.

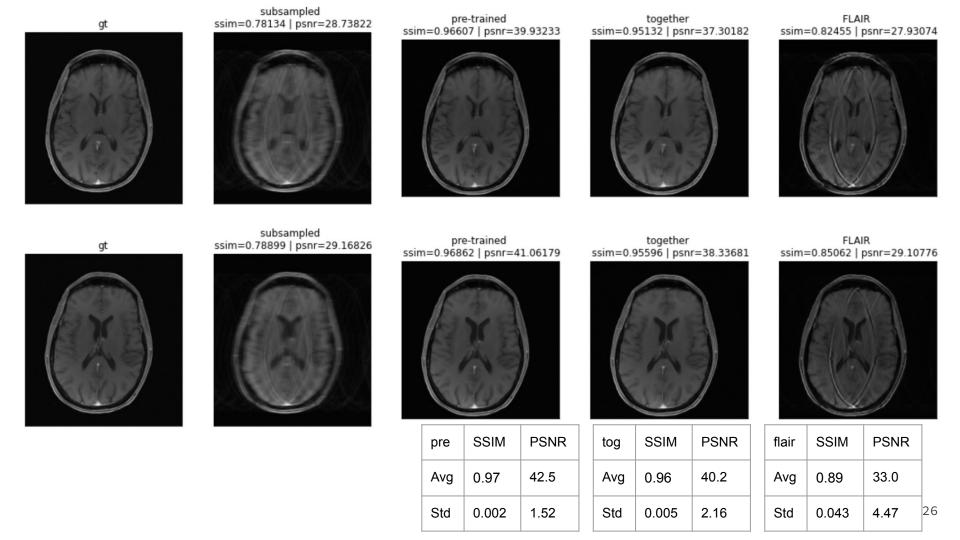
## Test 4: Training Data Type

**Aim:** understand the influence of the type of training dataset

#### Setting:

```
Training:
     #epochs =100
     Training dataset = 8 * 5 types vs. 40 volumes only FLAIR
     Training mask type: equispaced
     Training acceleration rate = 4+8
Recon:
     "file_brain_AXFLAIR_200_6002447.h5" & "file_brain_AXT1POST_201_6002686.h5"
     Recon mask type: equispaced
     Recon Acceleration Rate: 4
```





## Test 4: Training Data Type

#### **Conclusion:**

FLAIR only model to recon FLAIR performs almost the same as together model.

FLAIR only model to recon other types performs worse than together model.

#### **Future direction:**

Further verify this idea.

### **Test 5: Generalization**

**Aim:** if the model is trained on knee dataset, would it perform as good as the model being trained on brain dataset when reconstructing brain images?

#### Setting:

```
Training (pre-trained model): #epochs =100
```

Training dataset = 8\*5 types = 40 volumes

Training mask type: equispaced?

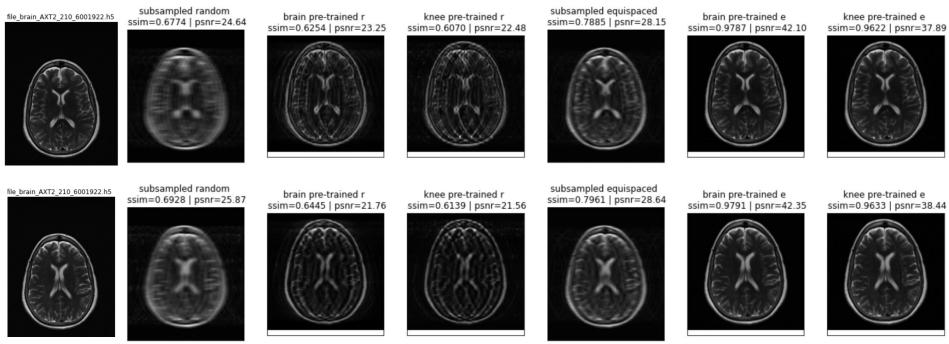
Training acceleration rate = 4+8?

#### Recon:

Brain data: "file\_brain\_AXT2\_210\_6001922.h5" & Knee data: "file1000107.h5"

Recon mask type: equispaced / random

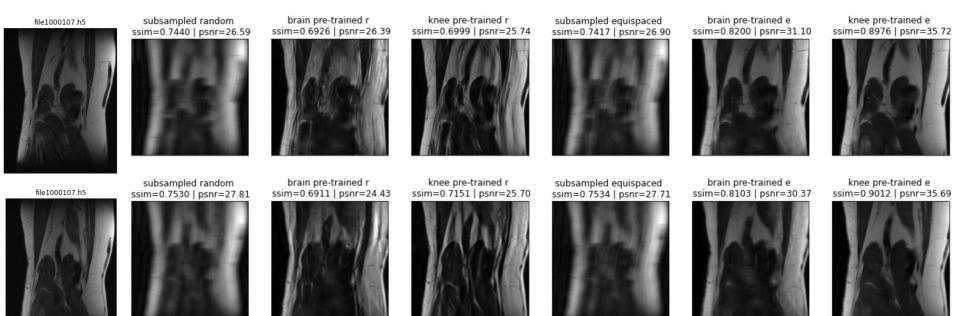
Recon Acceleration Rate: 4



Ground truth

br	SSIM	PSNR	kr	SSIM	PSNR
Avg	0.77	27.13	Avg	0.75	26.2
Std	0.11	6.68	Std	0.12	6.45

bе	SSIM	PSNR	kе	SSIM	PSNR
Avg	0.98	43.8	Avg	0.97	40.6
Std	0.001	1.44	Std	0.004	1.96



Ground	truth

br	SSIM	PSNR	kr	SSIM	PSNR
Avg	0.74	26.65	Avg	0.75	27.1
Std	0.081	3.39	Std	0.089	4.17

b e	SSIM	PSNR	k e	SSIM	PSNR
Avg	0.86	33.2	Avg	0.91	37.0
Std	0.043	2.78	Std	0.016	1.31

Knee data: file1000107.h5

### **Test 5: Generalization**

#### Conclusion:

The generalization of the pre-trained model is not quite good.

Reconstructing one type, training on that type?

Potential Reason? This type of DL is still based on the math model.

#### **Future direction:**

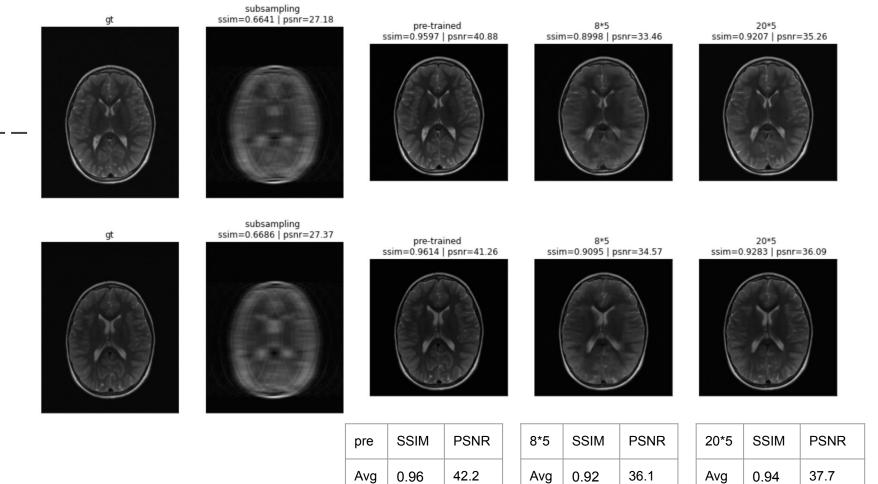
Verify this assumption.

## Test 6: Number of Training Datasets

**Aim:** whether increasing the number of training datasets would increase the performance of the model.

#### Setting:

```
Training:
     #epochs =100
     Training dataset = 8 * 5 types vs. 20 * 5 types
     Training mask type: equispaced
     Training acceleration rate = 4+8
Recon:
     "file_brain_AXT2_202_2020013.h5"
     Recon mask type: equispaced
     Recon Acceleration Rate: 8
```



Std

0.002

0.84

Std

0.013

2.41

Avg 0.94 37.7
Std 0.009 2.43

33

### Test 6: Number of Training Datasets

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#### **Conclusion:**

Increasing number of training datasets could increase the performance of the model.

#### **Future directions:**

Find the bound of the relationship between # training datasets and model performance

Adjust other possible parameters to see the performance.

### What have I done?

"Deep-Learning Methods for Parallel Magnetic Resonance Image Reconstruction" (2020):

"Is it sufficient to train a single model for all types of MR exams, or are separate models required for scans of different anatomical areas, pulse sequences, acquisition trajectories, and acceleration factors as well as scanner manufacturers, field strengths, and receive coils?"

### What have I done?

For E2E-VN model, answers might be:

It's better to train the model on

- 1) all types of MR exams;
- 2) more training datasets;
- 3) a mixture of acceleration rates;
- 4) specific anatomical areas for reconstruction of that particular area;
- 5) equispaced subsampling

### **Future Work**

- Find a suitable metric to evaluate the image quality
- Check the generalization of E2E-VN on different raw datasets
- Modify/Change the model structure such that it would generate more accurate results
- Interprete DL model to have a better understanding
- Would DL method affect the tumor in the reconstructed image?
- ....

## Reference

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