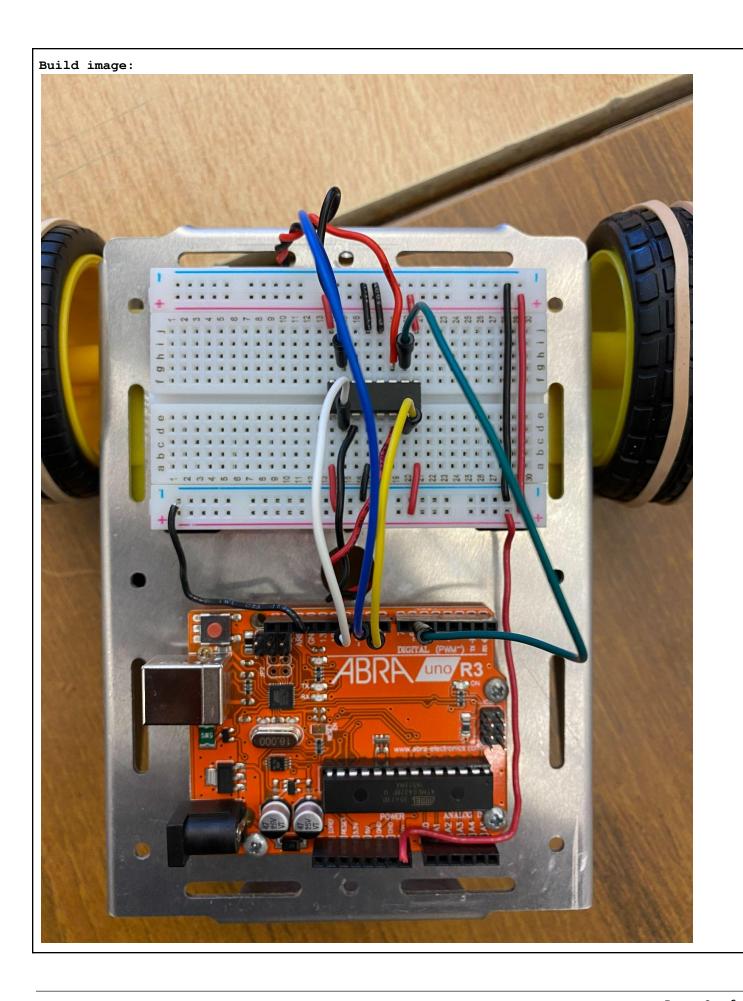
LVL	Criteria
R	
1	
2	
3	
4	"build and wire"[3]
	<pre>□ code commenting is accurate and complete (including title)[½] □ program structure and spacing is logical and demonstrates organization[½] □ code text submission is courier new font and is coloured to allow easier identification of comments[½]  "inspection questions"[1]</pre>
	demonstrates full understanding of circuit and interfacing concepts in conversation with teacher
4+	<pre>"enhancements"[1]</pre>



```
code:
Names: Siddarth & Mostafa
Dates: May 11, 2022
Description: Code for interfacing lab 12 - Motors
const int motors[2][2] = \{\{6,10\}, \{9,11\}\}; setting constant 2d array for motor pins
//function for straight movement (also controls if the motors stop)
void straight(bool forward = true, int time = 3000, bool off = false) {
    int forVar = forward ? 255 : 0; //one line if statement that controls direction;
    //inline one lined if statements used to halt vehicle if off is true
   analogWrite(motor[0][0], (off ? 0 : forVar)); // right motor forward
   analogWrite(motor[0][1], (off ? 0 : 255-forVar)); // right motor back
   analogWrite(motor[1][0], (off ? 0 : forVar)); // left motor forward
   analogWrite(motor[1][1], (off ? 0 : 255-forVar)); // left motor back
   delay(time); // delay (usually 3 seconds by default)
//function for side movement
void side(bool forward = true, bool right = true, int time = 3000) {
    int leftVar = right ? 75 : 255; //sets the speed for left motor
   int rightVar = right ? 255 : 75; //sets the speed for right motor
    int forVar = forward ? 1 : 0; //controls direction (sets which motor pin is on)
   analogWrite(motor[0][1-forVar], rightVar); //the side that is on for right motor
   analogWrite(motor[0][forVar], 0); //the side that is off for right motor
    analogWrite(motor[1][1-forVar], leftVar); //the side that is on for left motor
   analogWrite(motor[1][forVar], 0); //the side that is off for left motor
   delay(time); //delay
void setup() { //setup
   pinMode(motor[0][0], OUTPUT); //sets right motor first pin as output
   pinMode(motor[0][1], OUTPUT); //sets right motor second pin as output
   pinMode(motor[1][0], OUTPUT); //sets left motor first pin as output
   pinMode(motor[1][1], OUTPUT); //sets left motor second pin as output
    straight(); // forward
    straight(false); // backwards
```

```
side(); //forward + right
side(false); //backward + right
side(false, false); // backward + left
side(true, false); // forward + left
straight(true, 1, true); //stop
}
void loop() {} //loop (empty, thus does nothing as it loops)
```