# SIDDHARTH VISWANATH

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### **EDUCATION**

#### University of Waterloo

September 2022 – April 2027

Bachelor of Applied Sciences in Computer Engineering - Freshman

Waterloo, ON

Dean's Honours List (Top 5% standing in a cohort of 300 students)

Relevant Courses: Fundamentals of Programming (C++), Digital Circuits, Linear Circuits

Term Average: 91.58% (4.0 GPA)

# TECHNICAL SKILLS

Languages: C++, Python, HTML, CSS, JavaScript

Frameworks & Tools: Pandas, NumPy, Matplotlib, Jupyter Notebook, Anaconda, React, Node.js, Bootstrap, Git

Hardware & Design: Arduino, SketchUp, AutoCAD, Fritzing PCB Design, 3D-Printing, Soldering

Communication Protocols: UART, I2C, SPI

# **PROJECTS**

#### SumoBot | Python (MicroPython), Microbit, SketchUp, Cura

- Designed and programmed a **fully autonomous**, competitive robot using **Microbit & Python** that pushes other robots out of a 36-inch diameter black ring with a 1-inch white edge.
- Leveraged ultrasonic & infrared sensors to locate and eliminate nearby opposing robots with a precision of  $\pm 3$ cm.
- Utilized QTI sensors on the front of the bot to ensure that it stays within the rink to prevent self-knockout.
- Employed Cura to 3D print a custom bumper designed & optimized on SketchUp, to effectively overturn incoming robots.

## **Q** V8 Roomba | Arduino, C++, Fritzing, TinkerCAD, AutoCAD, Git

- Working in a team of 4 to assemble a fully **autonomous** vacuuming robot with a remote docking station.
- Designed a 4-wheel omni-drive system incorporating 2 Arduinos connected via I2C to provide adequate PWM pins.
- Devised **test cases** in code files to implement the prototype's **2.4 GHz** radio transceivers and utilize wireless **RF communication** between the robot and its docking station.
- Applied integration within code to convert raw acceleration data into precise position data sets.

#### • Weather Display | React, Node, JavaScript, bootstrap, HTML, CSS, Git

- Developed and hosted a web app that fetches data from the **OpenWeatherMap** API given a city & country input.
- Enabled a dark mode feature and used conditional mapping to display backgrounds based on weather output.

# O Data Analytics | Python, Jupyter Notebook, Pandas, Matplotlib, NumPy, Scikit-learn

- · Applied supervised & unsupervised ML models to visualize data frames, make predictions, and measure output accuracy.
- Utilized train-test split from scikit-learn and applied simple decision trees on large datasets with a 95% prediction accuracy.
- Leveraged edge detection and computer vision to accurately identify road lanes in images with a success rate of 98%.
- Implemented models trained using 900+ data points, applying techniques such as linear & logistic regression.

# EXTRACURRICULAR EXPERIENCE

#### President

September 2021 – June 2022

John Fraser Secondary School

Engineering Club, Math Club

- Conducted workshops AI/ML, CAD, Arduino & circuitry throughout the year, resulting in the growth of both clubs by 55%.
- Organized **weekly meetings** to finalize workshop agendas throughout the year, improving our team's conflict resolution, collaboration, and time management capabilities.
- Prepared & delivered weekly lessons to 130+ students and hosted bi-monthly panels to increase student engagement.
- Planned a **district-wide** robotics competition, collaborating with various supervisors across the school board, to invite **15+** schools, accommodating for **100+** students however, this event was unfortunately canceled due to COVID.

#### Founder & Head Scholar

September 2021 – June 2022

Senior Scholars

John Fraser Secondary School

- Managed a team of 40+ academic tutors and provided weekly updates to 8-10 supervisors, ensuring successful operation of the school's peer-tutoring service throughout the year.
- Mentored & guided 90+ students over the school year, resulting in assessment scores improving by as much as 35%.
- Tutored 12+ students on a weekly basis in subjects including Algebra I/II, Calculus, Chemistry, Physics, Biology, and English to strengthen their understanding of fundamental concepts.