

## Equation of Motions already included

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These are the equations already included the 6DOF model.

$$C_{b/n} = \begin{bmatrix} \cos(\theta)\cos(\psi) & \cos(\theta)\sin(\psi) & -\sin(\theta) \\ -\cos(\phi)\sin(\psi) + \sin(\phi)\sin(\theta)\cos(\psi) & \cos(\phi)\cos(\psi) + \sin(\phi)\sin(\theta)\sin(\psi) & \sin(\phi)\cos(\theta) \\ \sin(\phi)\sin(\psi) + \cos(\phi)\sin(\theta)\cos(\psi) & -\sin(\phi)\cos(\psi) + \cos(\phi)\sin(\theta)\sin(\psi) & \cos(\phi)\cos(\theta) \end{bmatrix}$$

Also represented as:  $C_{b/n} = fn(\Theta)$

$$\Omega = \begin{bmatrix} 0 & -R & Q \\ R & 0 & -P \\ P & -Q & 0 \end{bmatrix}$$

$$\begin{bmatrix} \dot{\phi} \\ \dot{\theta} \\ \dot{\psi} \end{bmatrix} = \begin{bmatrix} 1 & \tan(\theta)\sin(\phi) & \tan(\theta)\cos(\phi) \\ 0 & \cos(\phi) & -\sin(\phi) \\ 0 & \sin(\phi)/\cos(\theta) & \cos(\phi)/\cos(\theta) \end{bmatrix} \times \begin{bmatrix} P \\ Q \\ R \end{bmatrix}$$

Also represented as:  $\dot{\Phi} = H(\Phi)\omega_{b/e}^b$

$${}^b\dot{v}_{CM/e}^b = (\frac{1}{m})F_{A,T}^b + C_{b/n} \times g + \Omega_{b/e}^b \times v_{CM/e}^b$$

$${}^e\dot{p}_{CM/T}^n = C_{n/b} \times v_{CM/e}^b$$

$${}^b\dot{\omega}_{b/e}^b = inv(J^b) \times [M_{A,T}^b - \Omega_{b/e}^b \times J^b \times \omega_{b/e}^b]$$