

Probability Background

- Probability spaces
- Random variables
- Expectation
- Basic facts from analysis

• Probability space = (Ω, \mathcal{F}, P)

↑ ↑ ↑
 Sample space σ -field prob measure
 (or σ -algebra) (or function)

- Ω = set of all possible outcomes of an expt
- \mathcal{F} = collection of subsets of Ω with 3 prop -
 - i) $\Omega \in \mathcal{F}$
 - ii) $A \in \mathcal{F} \Rightarrow \bar{A} \in \mathcal{F}$
 - iii) $A_1, A_2, \dots \in \mathcal{F} \Rightarrow \bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$
- Eg - (Ω, \emptyset) , $(\Omega, \emptyset, A, \bar{A})$, 2^Ω for discrete Ω
- Propⁿ - For any collection G of subsets of Ω , \exists a **smallest σ -field** $\sigma(G)$ that contains G
- Defn - For any metric space Ω (e.g. \mathbb{R}^n), let \mathcal{O} denote the collection of all open subsets of Ω . Then the **Borel σ -field** $B(\Omega) = \sigma(\mathcal{O})$

- In particular, for \mathbb{R} , let $\mathcal{I} = \{[-\infty, a] \mid a \in \mathbb{R}\}$ be the set of closed intervals. Then

$$\mathcal{B}(\mathbb{R}) = \sigma(\mathcal{I})$$

i.e., $\mathcal{B}(\mathbb{R})$ is the smallest σ -field containing all closed intervals (works also for open intervals)

- Note: This is a non-constructive definition. However, one can construct sets which are not in $\mathcal{B}(\mathbb{R})$!
(See wikipedia \rightarrow Vitali set)

- $P : \mathcal{F} \rightarrow [0, 1]$ is a probability measure on σ -field \mathcal{F} if
 - $P[\Omega] = 1$
 - $P[A] \in [0, 1] \quad \forall A \in \mathcal{F}$
 - For $A_1, A_2, \dots \in \mathcal{F}$ s.t $A_i \cap A_j = \emptyset \quad \forall i, j$ incompatible / disjoint / mutually exclusive
$$P\left[\bigcup_{i=1}^{\infty} A_i\right] = \sum_{i=1}^{\infty} P[A_i]$$

(KOLMOGOROV'S AXIOMS)

• The above axioms imply the foll^g

i) $P[\emptyset] = 0$

ii) If $A \subseteq B$, then $P[A] \leq P[B]$

iii) $P[\bar{A}] = 1 - P[A]$

iv) For any $A_1, A_2, \dots \in \mathcal{F}$

(Union bound) $P\left[\bigcup_{i=1}^{\infty} A_i\right] \leq \sum_{i=1}^{\infty} P[A_i]$

v) Given $A_1, A_2, \dots \in \mathcal{F}$ st $P[A_i] = 0 \forall i$,

then $P\left[\bigcup_{i=1}^{\infty} A_i\right] = 0$ (0-measure or negligible sets)

vi) Given $A_1, A_2, \dots \in \mathcal{F}$ st $A_i \subseteq A_{i+1} \forall i$

then $P\left[\bigcup_{i=1}^{\infty} A_i\right] = \lim_{i \rightarrow \infty} P[A_i]$

(Sequential continuity)

Try proving
these/ read up

- Random variable \equiv 'measurable' fn on Ω
- A fn $f: (\Omega, \mathcal{F}) \rightarrow (\mathbb{R}, \mathcal{B})$ is **measurable**
if $\forall A \in \mathcal{B}$, we have $f^{-1}(A) \in \mathcal{F}$
- (In this course, we will mostly ignore measurability - however in more complex settings, one needs to be careful...)
- Defn - A random variable X on a probability space (Ω, \mathcal{F}, P) is a measurable fn $X: \Omega \rightarrow \mathbb{R}$

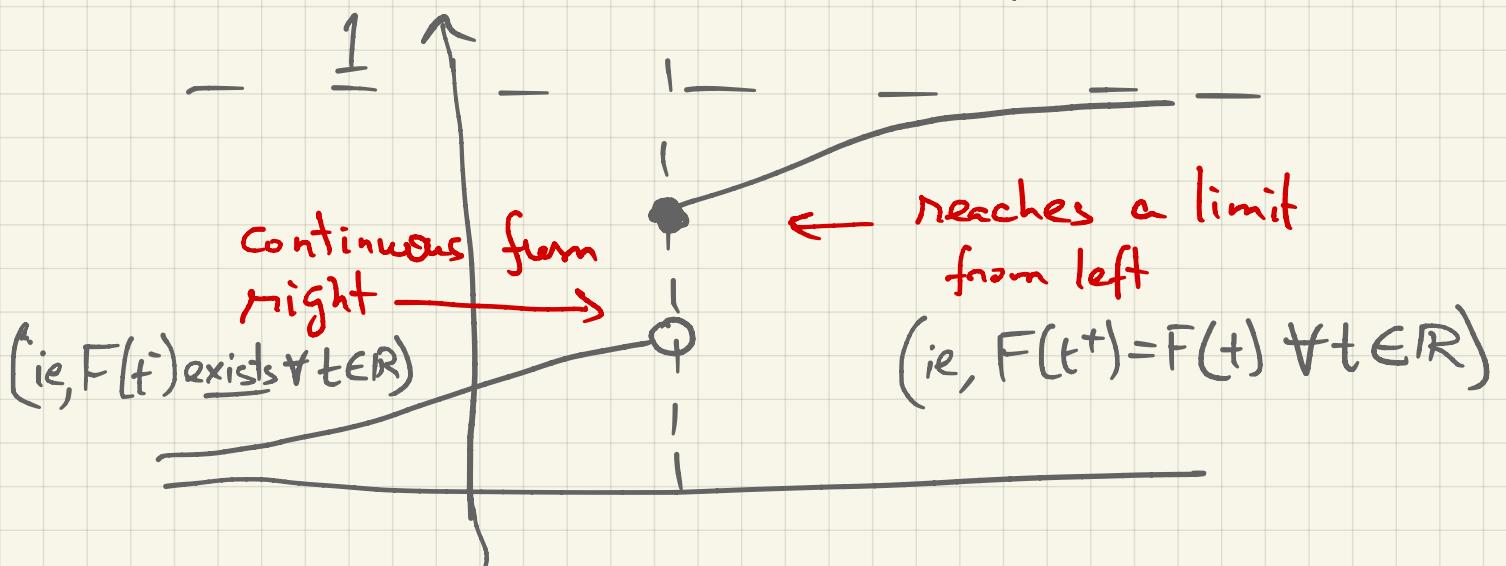
Almost Sure

- We are interested in all events which are non-negligible (i.e., all A s.t $P[A] > 0$).
- Defn - For given (Ω, \mathcal{F}, P) , a property P holds almost surely if $P[\{\omega | \omega \text{ satisfies } P\}] = 1$
- Similarly for r.o.s X, Y , we say $X = Y$ almost surely (or $X = Y$ a.s.) if $P[\{\omega | X(\omega) \neq Y(\omega)\}] = 0$

- The signature feature of a random variable X is its cumulative distribution fn $F: \mathbb{R} \rightarrow [0,1]$, $F(t) = P[X \leq t]$
 - recall the Borel σ -field $\mathcal{B}(\mathbb{R})$ was constructed using only (closed) intervals $(-\infty, t]$
 - the \leq is a convention; we could have as well defined it as $P[X < t]$. This would correspond to constructing $\mathcal{B}(\mathbb{R})$ using open intervals ...
 - CDFs are awesome! All random variables have one.

Properties of CDFs

- $\lim_{t \rightarrow -\infty} F(t) = 0, \lim_{t \rightarrow \infty} F(t) = 1$
- F is non-decreasing
- F is RCLL (Right continuous
Left limits)



This is a consequence of \leq convention

- Every non-decreasing, RCLL fn from 0 to 1 is a CDF for some X ...

- Random variables can be discrete or continuous

Discrete

- $\exists x_1, x_2, \dots \in \mathbb{R}$ s.t.

$$\sum_{i=1}^{\infty} \mathbb{P}[X=x_i] = 1$$

- $P(x_i) = \mathbb{P}[X=x_i]$

Probability mass fn (pmf)

- $F(t) = \sum_{x_i \leq t} P(x_i)$

(Absolutely) Continuous

- $\exists f_h f: \mathbb{R} \rightarrow \mathbb{R}^+$ s.t.

$$F(t) = \int_{-\infty}^t f(x) dx$$

probability density fn (pdf)

- $\mathbb{P}[X=x] = 0 \quad \forall x \in \mathbb{R}$

- See Ch 2.1 of Brémaud (DiscProb) for examples of distributions

Discrete: Bernoulli(p), Binomial(n, p), Geometric(p), Poisson(λ)
 $\text{Multinomial}(m, p_1, p_2, \dots, p_n) = \binom{m \text{ balls in}}{n \text{ bins}}$

Continuous: Uniform(a, b), Gaussian $N(\mu, \sigma^2)$, Exponential(λ)

(for the last two, see Brémaud - Markov Chains)

• Random Vectors = Collection of random variables $(X_i)_{i \in I}$ on prob space (Ω, \mathcal{F}, P)

- Joint distribution fn $F: \mathbb{R}^n \rightarrow [0,1]$
- $$F(t_1, t_2, \dots, t_n) = P[X_1 \leq t_1] \wedge [X_2 \leq t_2] \wedge \dots \wedge [X_n \leq t_n]$$
-

- In dependence - 2 events $A, B \in \mathcal{F}$ are indep if $P[A \cap B] = P[A]P[B]$
 - Different from mutually exclusive/disjoint

- For events A_1, A_2, \dots, A_n
 - $P[A_i \cap A_j] = P[A_i]P[A_j] \forall i, j$
 $\Rightarrow A_i$'s are pairwise independent
 - $P[\bigcap_{i=1}^n A_i] = \prod_{i=1}^n P[A_i]$
 $\Rightarrow A_i$'s are mutually independent

• 2 random variables X, Y are independent if $\forall x, y \in \Omega$

$$P[X=x, Y=y] = P[X=x] P[Y=y]$$

• R.G.s X, Y are said to be conditionally independent given Z if $\forall x, y, z$, we have

$$P[X=x, Y=y | Z=z] = P[X=x | Z=z] P[Y=y | Z=z]$$

(see Brémaud for conditional probability)

• Notation - X, Y independent is written as $X \perp\!\!\!\perp Y$

Expectation

- We will focus first on discrete R.V.

Defn - For R.V. X taking values

in countable set E , and function $g: E \rightarrow \mathbb{R}$ st either g is

non-negative or $\sum_{x \in E} |g(x)| p(x) < \infty$,
'integrable'

then

$$E[g(x)] = \sum_{x \in E} p(x) g(x)$$

pmf $P[X=x]$

An important example

- For any $A \in \mathcal{F}$, $E[1_{\mathbb{I}_A}] = P[A]$
 where $1_{\mathbb{I}_A} \equiv$ indicator R.V. $\begin{cases} 1 & \text{if } A \text{ true} \\ 0 & \text{else} \end{cases}$

- Indicator R.V. are very useful for computations !!

For continuous distributions

- Suppose X has pdf f (ie, continuous) (absolute)

then

$$E[g(x)] = \int_{-\infty}^{\infty} g(x) f(x) dx$$

for any g s.t $\int_{-\infty}^{\infty} |g(z)| f(z) dz < \alpha$

- More generally, X could be discrete + continuous
 - FACT - Any CDF F has only a countable number of jumps
 - Let $\{d_n\}_{n \geq 1}$ be the discontinuity

points for a given CDF F

$$F_d(t) \triangleq \sum_{d_n \leq t} (F(d_n) - F(\bar{d_n})), \quad F_c(t) = F(t) - F_d(t)$$

'jumps' 'continuous part'

then $E[g(x)] = \int_{-\infty}^{\infty} g(x) dF(x)$

$\int_{-\infty}^{\infty}$

‘The Lebesgue integral
of g w.r.t measure F ’

$$= \sum_{n=1}^{\infty} g(d_n)(F(d_n) - F(d_n^-))$$

$$+ \int_{-\infty}^{\infty} g(x) f_c(x) dx$$

where $f_c(x)$ is a function such

that $F_c(t) = \int_{-\infty}^t f_c(x) dx$

(i.e., $f_c(x) = \frac{d}{dx} F_c(x)$)

Properties of $E[X]$

i) Linearity of Expectation

$$E[\lambda_1 g_1(x) + \lambda_2 g_2(x)] = \lambda_1 E[g_1(x)] + \lambda_2 E[g_2(x)]$$

for any $\lambda_1, \lambda_2 \in \mathbb{R}$, g_1, g_2 integrable

ii) For g_1, g_2 s.t $g_1(x) \leq g_2(x) \forall x \in \mathbb{R}$

$$\Rightarrow E[g_1(x)] \leq E[g_2(x)] \quad (\text{monotonicity})$$

iii) If $X \perp\!\!\!\perp Y \Rightarrow E[g(x)h(y)] = E[g(x)]E[h(y)]$

iv) For $X \geq 0$ (i.e., $P[X < 0] = 0$)

$$E[X] = \int_0^\infty (1 - F(t)) dt$$

In particular, if $X \in \mathbb{N}$, then

$$E[X] = \sum_{n=1}^{\infty} P[X \geq n]$$

Mean, Variance, moments

- Mean $\mu = E[X]$

Variance $\sigma^2 = E[(X-\mu)^2]$

$$= E[X^2] - (E[X])^2$$

- Raw moments - $m_k = E[X^k]$

Centered moments - $\tau_k = E[(X-\mu)^k]$

- If $X_1 \perp\!\!\! \perp X_2$, $Y = X_1 + X_2$

then $\tau_k(Y) = \tau_k(X_1) + \tau_k(X_2)$

(However, for mean, this is always true thanks to linearity!)

Some useful facts about integration

- An important part of analysis / measure theory is to formalize the notion of the integral. For our class, we will just need some important results that come out of this formalism
- Consider a sequence of random variables X_1, X_2, \dots

i) If $X_n(\omega) \geq 0$ a.s. and $X_n(\omega) \leq X_{n+1}(\omega)$ a.s. for all n , then

$$\lim_{n \rightarrow \infty} E[X_n] = E\left[\lim_{n \rightarrow \infty} X_n\right]$$

(Monotone convergence)

ii) If $|X_n(\omega)| \leq Y(\omega)$ a.s. for all n ,

and $E[Y] < \infty$, then (dominated convergence)

$$\lim_{n \rightarrow \infty} E[X_n] = E\left[\lim_{n \rightarrow \infty} X_n\right]$$

iii) If $|X_n(\omega)| \leq C$ a.s for all n , then

$$\lim_{n \rightarrow \infty} E[X_n] = E\left[\lim_{n \rightarrow \infty} X_n\right]$$
 (bounded convergence)

iv) If $X_n \geq Y$ a.s for all n , and

$E[Y] < \infty$, then

$$E\left[\liminf_{n \rightarrow \infty} X_n\right] \leq \liminf_{n \rightarrow \infty} E[X_n]$$

(Fatou's Lemma)

All the above hold for discrete
 no (and series) as well - See
 chapter 4.1.3 of Bremaud DP.
 (Also see Appendix A1 for proofs)

- Interchanging sums and integrals

- If $X_n \geq 0$ then $\mathbb{E}\left[\sum_{n=1}^{\infty} X_n\right] = \sum_{n=1}^{\infty} \mathbb{E}[X_n]$

- If $X(t) \geq 0$ then $\mathbb{E}\left[\int_{-\infty}^{\infty} X(t) dt\right] = \int_{-\infty}^{\infty} \mathbb{E}[X(t)] dt$

(Tonelli's Thm)

- If $\mathbb{E}\left[\sum_{n=1}^{\infty} |X_n|\right] < \infty$, then $\mathbb{E}\left[\sum X_n\right] = \sum \mathbb{E}[X_n]$

- If $\mathbb{E}\left[\int_{-\infty}^{\infty} |X(t)| dt\right] < \infty$, then $\mathbb{E}\left[\int X(t) dt\right] = \int \mathbb{E}[X(t)] dt$

(Fubini's Thm)