- -alternative to batch gradient descent
- more efficient/scalable for large data sets

$$Cost(\theta, (x^{(i)}, y^{(i)})) = \frac{1}{2} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)^{2}$$

$$J_{train}(\theta) = \frac{1}{m} \sum_{i=1}^{m} Cost(\theta, (x^{(i)}, y^{(i)}))$$

- 1) Randomly shuffle dataset
- 2) Repeat { 1 training example @ atime for i = 1 : m { $(n^{(i)}, y^{(i)})$ } $\theta_j := \theta_j \infty \left(h_{\theta}(x^{(i)}) y^{(i)}\right) \cdot x_j^{(i)}$ (for every $j = 0 \rightarrow n$)

Mini-Batch Gradient Descent:

-uses 'b' training examples

$$-\theta_{j} := \theta_{j} - \propto \frac{1}{b} \sum_{k=1}^{i+b} \left(h_{\theta} \left(\chi^{(k)} \right) - y^{(k)} \right) \chi_{j}^{(k)}$$

Stochastic Gradient Descent Convergence

- -plot avg cost vs training examples
- oscillates around global minimum: smaller a may give smaller cost
- Can slowly decrease $\propto \frac{\text{constl}}{\text{iter} \# + \text{const2}}$

Online Learning

Map-reduce & Data Parallelism

- Divide batch gradient descent and dispatch cost function for subset of data to train algorithm in parallel (w/ different machines)

- training set $\rightarrow z$ subsets : $\sum_{i=p}^{q} (h_{\theta}(x^{(i)}) - y^{(i)}) \times_{j}^{(i)}$

Map-Reduce: $\theta_j := \theta_j - \infty \frac{1}{2} \left(temp_j^{(i)} + ... + temp_j^{(2)} \right)$

Map-Reduceable if algorithm can be expressed as computing sums of functions over training set (linear, logistic,...)