

# Junction Tree Algorithm<sup>1</sup>

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<sup>1</sup>These slides accompany the book *Bayesian Reasoning and Machine Learning*. The book and demos can be downloaded from [www.cs.ucl.ac.uk/staff/D.Barber/brrml](http://www.cs.ucl.ac.uk/staff/D.Barber/brrml). Feedback and corrections are also available on the site. Feel free to adapt these slides for your own purposes, but please include a link the above website.

# A general purpose inference algorithm (?)

## Applicability

- The JTA deals with 'marginal' inference in multiply-connected structures.
  - The JTA can handle both Belief and Markov Networks.
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## Efficiency

- The complexity of the JTA can be very high if the graph is multiply connected.
- Provides an upper bound on the computational complexity.
- May be that there are some problems for which much more efficient algorithms exist than the JTA.

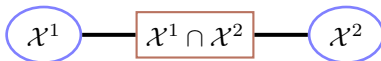
# Clique Graph

A clique graph consists of a set of potentials,  $\phi_1(\mathcal{X}^1), \dots, \phi_n(\mathcal{X}^n)$  each defined on a set of variables  $\mathcal{X}^i$ . For neighbouring cliques on the graph, defined on sets of variables  $\mathcal{X}^i$  and  $\mathcal{X}^j$ , the intersection  $\mathcal{X}^s = \mathcal{X}^i \cap \mathcal{X}^j$  is called the separator and has a corresponding potential  $\phi_s(\mathcal{X}^s)$ . A clique graph represents the function

$$\frac{\prod_c \phi_c(\mathcal{X}^c)}{\prod_s \phi_s(\mathcal{X}^s)}$$

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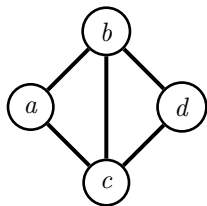
## Example



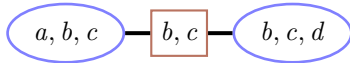
$$\frac{\phi(\mathcal{X}^1)\phi(\mathcal{X}^2)}{\phi(\mathcal{X}^1 \cap \mathcal{X}^2)}$$

# Markov Net $\rightarrow$ Clique Graph

$$p(a, b, c, d) = \frac{\phi(a, b, c)\phi(b, c, d)}{Z}$$



(a)



(b)

**Figure:** (a) Markov network  $\phi(a, b, c)\phi(b, c, d)$ . (b) Clique graph representation of (a).

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## Clique potential assignments

- The separator potential may be set to the normalisation constant  $Z$ .
- Cliques have potentials  $\phi(a, b, c)$  and  $\phi(b, c, d)$ .

# Transformation

$$p(a, b, c, d) = \frac{\phi(a, b, c)\phi(b, c, d)}{Z}$$

By summing we have

$$Zp(a, b, c) = \phi(a, b, c) \sum_d \phi(b, c, d), \quad Zp(b, c, d) = \phi(b, c, d) \sum_a \phi(a, b, c)$$

Multiplying the two expressions, we have

$$\begin{aligned} Z^2 p(a, b, c) p(b, c, d) &= \left( \phi(a, b, c) \sum_d \phi(b, c, d) \right) \left( \phi(b, c, d) \sum_a \phi(a, b, c) \right) \\ &= Z^2 p(a, b, c, d) \sum_{a, d} p(a, b, c, d) \end{aligned}$$

In other words

$$p(a, b, c, d) = \frac{p(a, b, c)p(b, c, d)}{p(c, b)}$$

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## Clique potential assignments

- The separator potential may be set to  $p(b, c)$ .
- Cliques have potentials  $p(a, b, c)$  and  $p(b, c, d)$ .

The cliques and separators contain the marginal distributions.

# Markov $\rightarrow$ Clique Graph

## The transformation

$$\phi(a, b, c) \rightarrow p(a, b, c)$$

$$\phi(b, c, d) \rightarrow p(b, c, d)$$

$$Z \rightarrow p(c, b)$$

The usefulness of this representation is that if we are interested in the marginal  $p(a, b, c)$ , this can be read off from the transformed clique potential.

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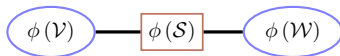
## JTA

- The JTA is a systematic way of transforming the clique graph potentials so that at the end of the transformation the new potentials contain the marginals of the distribution.
- The JTA will work by a sequence of local transformations
- Each local transformation will leave the Clique representation invariant.

# Absorption

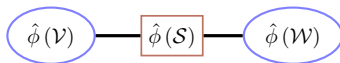
Consider neighbouring cliques  $\mathcal{V}$  and  $\mathcal{W}$ , sharing the variables  $\mathcal{S}$  in common. In this case, the distribution on the variables  $\mathcal{X} = \mathcal{V} \cup \mathcal{W}$  is

$$p(\mathcal{X}) = \frac{\phi(\mathcal{V})\phi(\mathcal{W})}{\phi(\mathcal{S})}$$



and our aim is to find a new representation

$$p(\mathcal{X}) = \frac{\hat{\phi}(\mathcal{V})\hat{\phi}(\mathcal{W})}{\hat{\phi}(\mathcal{S})}$$



in which the potentials are given by

$$\hat{\phi}(\mathcal{V}) = p(\mathcal{V}), \quad \hat{\phi}(\mathcal{W}) = p(\mathcal{W}), \quad \hat{\phi}(\mathcal{S}) = p(\mathcal{S})$$

We can explicitly work out the new potentials as function of the old potentials:

$$p(\mathcal{W}) = \sum_{\mathcal{V} \setminus \mathcal{S}} p(\mathcal{X}) = \sum_{\mathcal{V} \setminus \mathcal{S}} \frac{\phi(\mathcal{V})\phi(\mathcal{W})}{\phi(\mathcal{S})} = \phi(\mathcal{W}) \frac{\sum_{\mathcal{V} \setminus \mathcal{S}} \phi(\mathcal{V})}{\phi(\mathcal{S})}$$

and

$$p(\mathcal{V}) = \sum_{\mathcal{W} \setminus \mathcal{S}} p(\mathcal{X}) = \sum_{\mathcal{W} \setminus \mathcal{S}} \frac{\phi(\mathcal{V})\phi(\mathcal{W})}{\phi(\mathcal{S})} = \phi(\mathcal{V}) \frac{\sum_{\mathcal{W} \setminus \mathcal{S}} \phi(\mathcal{W})}{\phi(\mathcal{S})}$$

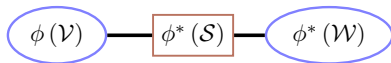
# Absorption

We say that the clique  $\mathcal{W}$  ‘absorbs’ information from clique  $\mathcal{V}$ . First we define a new separator

$$\phi^*(\mathcal{S}) = \sum_{\mathcal{V} \setminus \mathcal{S}} \phi(\mathcal{V})$$

and refine the  $\mathcal{W}$  potential using

$$\phi^*(\mathcal{W}) = \phi(\mathcal{W}) \frac{\phi^*(\mathcal{S})}{\phi(\mathcal{S})}$$



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## Invariance

The advantage of this interpretation is that the new representation is still a valid clique graph representation of the distribution since

$$\frac{\phi(\mathcal{V})\phi^*(\mathcal{W})}{\phi^*(\mathcal{S})} = \frac{\phi(\mathcal{V})\phi(\mathcal{W})\frac{\phi^*(\mathcal{S})}{\phi(\mathcal{S})}}{\phi^*(\mathcal{S})} = \frac{\phi(\mathcal{V})\phi(\mathcal{W})}{\phi(\mathcal{S})} = p(\mathcal{X})$$



# Absorption

After  $\mathcal{W}$  absorbs information from  $\mathcal{V}$  then  $\phi^*(\mathcal{W})$  contains the marginal  $p(\mathcal{W})$ . Similarly, after  $\mathcal{V}$  absorbs information from  $\mathcal{W}$  then  $\phi^*(\mathcal{V})$  contains the marginal  $p(\mathcal{V})$ . After the separator  $\mathcal{S}$  has participated in absorption along both directions, then the separator potential will contain  $p(\mathcal{S})$ .

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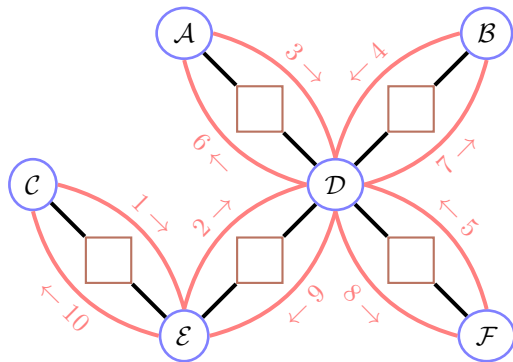
## Proof

$$\phi^{**}(\mathcal{S}) = \sum_{\mathcal{W} \setminus \mathcal{S}} \phi^*(\mathcal{W}) = \sum_{\mathcal{W} \setminus \mathcal{S}} \frac{\phi(\mathcal{W})\phi^*(\mathcal{S})}{\phi(\mathcal{S})} = \sum_{\{\mathcal{W} \cup \mathcal{V}\} \setminus \mathcal{S}} \frac{\phi(\mathcal{W})\phi(\mathcal{V})}{\phi(\mathcal{S})} = p(\mathcal{S})$$

Continuing, we have the new potential  $\phi^*(\mathcal{V})$  given by

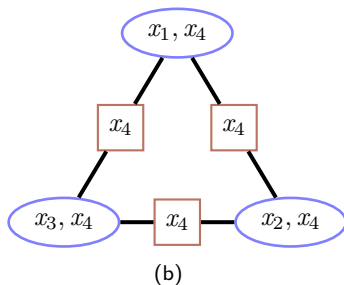
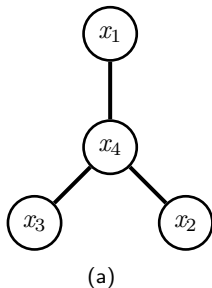
$$\begin{aligned}\phi^*(\mathcal{V}) &= \frac{\phi(\mathcal{V})\phi^{**}(\mathcal{S})}{\phi^*(\mathcal{S})} = \frac{\phi(\mathcal{V}) \sum_{\mathcal{W} \setminus \mathcal{S}} \phi(\mathcal{W})\phi^*(\mathcal{S})/\phi(\mathcal{S})}{\phi^*(\mathcal{S})} \\ &= \frac{\sum_{\mathcal{W} \setminus \mathcal{S}} \phi(\mathcal{V})\phi(\mathcal{W})}{\phi(\mathcal{S})} = p(\mathcal{V})\end{aligned}$$

# Absorption Schedule on a Clique Tree



- For a valid schedule, messages can only be passed to a neighbour when all other messages have been received.
- More than one valid schedule may exist.

# Forming a Clique Tree



$$p(x_1, x_2, x_3, x_4) = \phi(x_1, x_4)\phi(x_2, x_4)\phi(x_3, x_4)$$

- The clique graph of this singly-connected Markov network is multiply-connected, where the separator potentials are all set to unity.
- For absorption to work, we need a singly-connected clique graph.

# Forming a Clique Tree

$$p(x_1, x_2, x_3, x_4) = \phi(x_1, x_4)\phi(x_2, x_4)\phi(x_3, x_4)$$

Reexpress the Markov network in terms of marginals. First we have the relations

$$p(x_1, x_4) = \sum_{x_2, x_3} p(x_1, x_2, x_3, x_4) = \phi(x_1, x_4) \sum_{x_2} \phi(x_2, x_4) \sum_{x_3} \phi(x_3, x_4)$$

$$p(x_2, x_4) = \sum_{x_1, x_3} p(x_1, x_2, x_3, x_4) = \phi(x_2, x_4) \sum_{x_1} \phi(x_1, x_4) \sum_{x_3} \phi(x_3, x_4)$$

$$p(x_3, x_4) = \sum_{x_1, x_2} p(x_1, x_2, x_3, x_4) = \phi(x_3, x_4) \sum_{x_1} \phi(x_1, x_4) \sum_{x_2} \phi(x_2, x_4)$$

Taking the product of the three marginals, we have

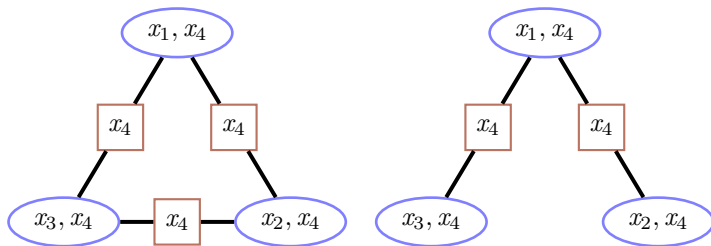
$$\begin{aligned} & p(x_1, x_4)p(x_2, x_4)p(x_3, x_4) \\ &= \phi(x_1, x_4)\phi(x_2, x_4)\phi(x_3, x_4) \underbrace{\left( \sum_{x_1} \phi(x_1, x_4) \sum_{x_2} \phi(x_2, x_4) \sum_{x_3} \phi(x_3, x_4) \right)^2}_{p(x_4)^2} \end{aligned}$$

# Forming a Clique Tree

This means that the Markov network can be expressed in terms of marginals as

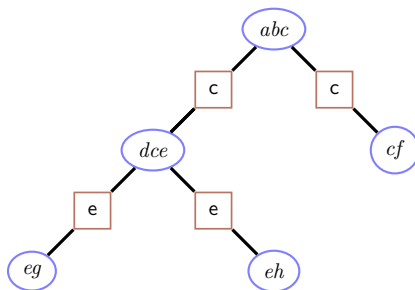
$$p(x_1, x_2, x_3, x_4) = \frac{p(x_1, x_4)p(x_2, x_4)p(x_3, x_4)}{p(x_4)p(x_4)}$$

Hence a valid clique graph is also given by



- If a variable (here  $x_4$ ) occurs on every separator in a clique graph loop, one can remove that variable from an arbitrarily chosen separator in the loop.
- Provided that the original Markov network is singly-connected, one can always form a clique tree in this manner.

# Junction Tree

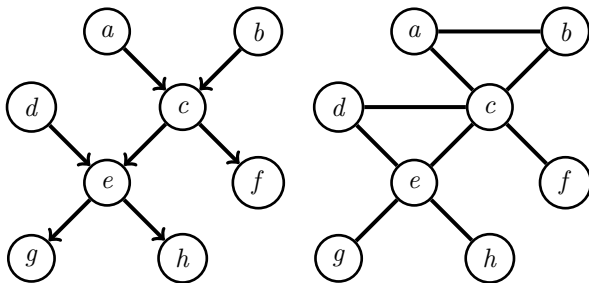


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## Running Intersection Property

- A Clique Tree is a Junction Tree if, for each pair of nodes,  $\mathcal{V}$  and  $\mathcal{W}$ , all nodes on the path between  $\mathcal{V}$  and  $\mathcal{W}$  contain the intersection  $\mathcal{V} \cap \mathcal{W}$ .
- Any singly-connected Markov Network can be transformed into a Junction Tree.
- Thanks to the running intersection property, local consistency of marginals propagates to global marginal consistency.

## Belief Net $\rightarrow$ Markov Net

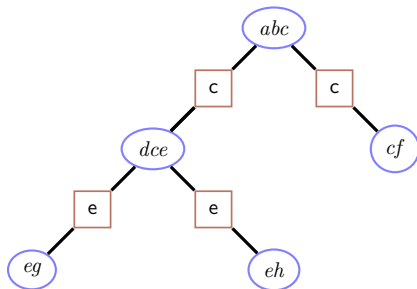
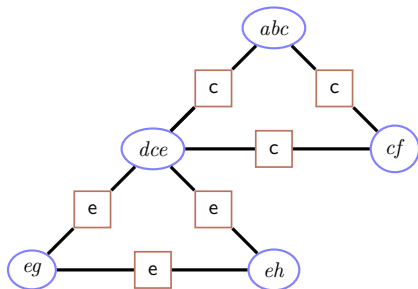


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### Moralisation

Form a link between all unmarried parents.

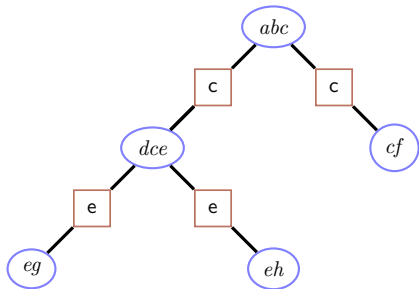
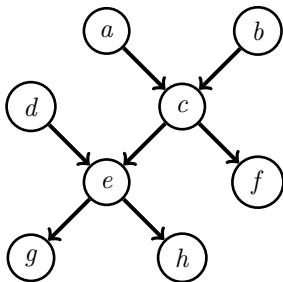
# Markov Net $\rightarrow$ Junction Tree



- Form the clique graph
- Identify a maximal weight spanning tree of the clique graph. (The weight of the edge is the number of variables in the separator)



# Absorption



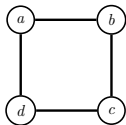
- Assign potentials to JT cliques.

$$\begin{aligned}\phi(abc) &= p(a)p(b)p(c|a, b), & \phi(dce) &= p(d)p(e|d, c) \\ \phi(cf) &= p(f|c), & \phi(eg) &= p(g|e), & \phi(eh) &= p(h|e)\end{aligned}$$

All separator potentials are initialised to unity. Note that in some instances it can be that a junction tree clique is assigned to unity.

- Carry out absorption using a valid schedule.
- Marginals can then be read off the transformed potentials.

# Multiply-Connected Markov Nets



$$p(a, b, c, d) = \phi(a, b)\phi(b, c)\phi(c, d)\phi(d, a)$$

Let's first try to make a clique graph. We have a choice about which variable first to marginalise over. Let's choose  $d$ :

$$p(a, b, c) = \phi(a, b)\phi(b, c) \sum_d \phi(c, d)\phi(d, a)$$

We can express the joint in terms of the marginals using

$$p(a, b, c, d) = \frac{p(a, b, c)}{\sum_d \phi(c, d)\phi(d, a)} \phi(c, d)\phi(d, a)$$

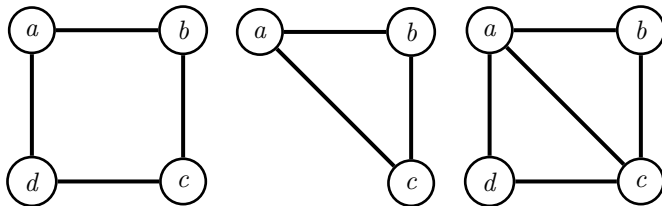
Furthermore,

$$p(a, c, d) = \phi(c, d)\phi(d, a) \sum_b \phi(a, b)\phi(b, c)$$

Plugging this into the above equation, we have

$$p(a, b, c, d) = \frac{p(a, b, c)p(a, c, d)}{\sum_d \phi(c, d)\phi(d, a) \sum_b \phi(a, b)\phi(b, c)} = \frac{p(a, b, c)p(a, c, d)}{p(a, c)}.$$

# Induced representation

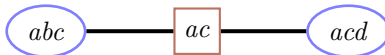


**left** An undirected graph with a loop.

**middle** Eliminating node  $d$  adds a link between  $a$  and  $c$  in the marginal subgraph.

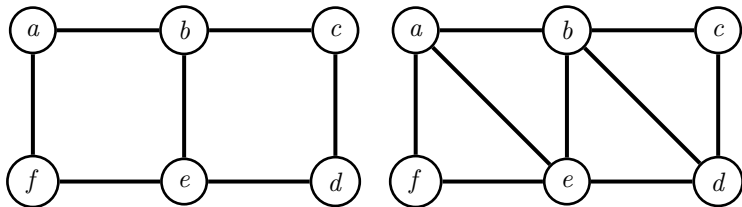
**right** Induced representation of the joint.

**below** Junction tree.



# Triangulation

In a triangulated graph, every loop of length 4 or more must have a chord (a shortcut). Such graphs are called decomposable.



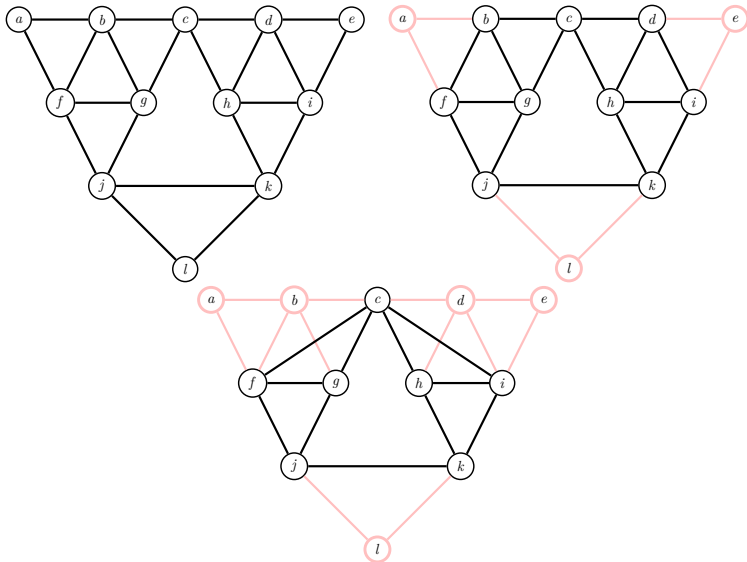
Left: a non-decomposable graph. Right: triangulated version.

# Triangulation via Variable Elimination

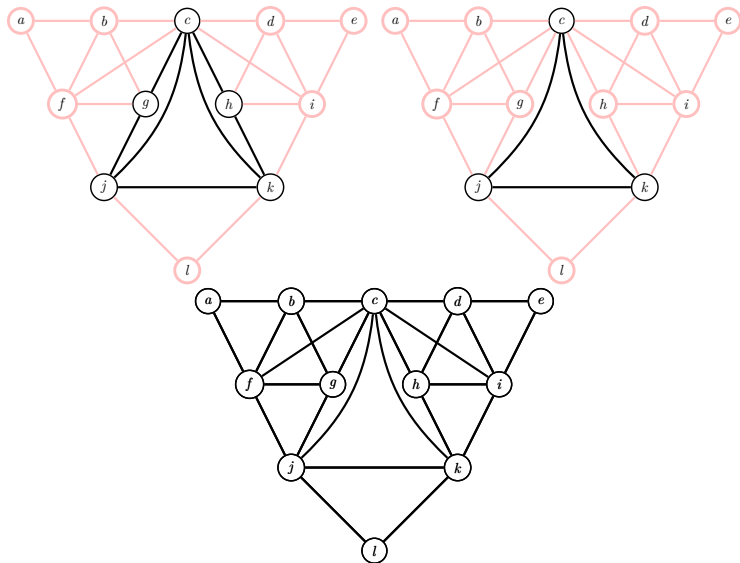
- Repeat:
- Select any non-deleted node  $x$  in the graph
- Add links to all the neighbours of  $x$ .
- Node  $x$  is then deleted.
- Until all nodes have been deleted

This procedure guarantees a triangulated graph. There are many other triangulation algorithms. No known efficient way to find the 'best' triangulation (the one with the smallest cliques).

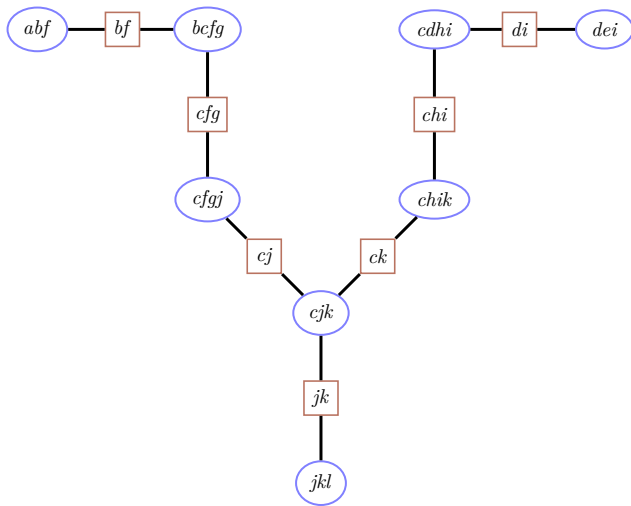
# Triangulation via Variable Elimination



# Triangulation via Variable Elimination



# The Junction Tree



This satisfies the running intersection property.



# The JTA

**Moralisation** Marry the parents. This is required only for directed distributions. Note that all the parents of a variable are married together – a common error is to marry only the ‘neighbouring’ parents.

**Triangulation** Ensure that every loop of length 4 or more has a chord.

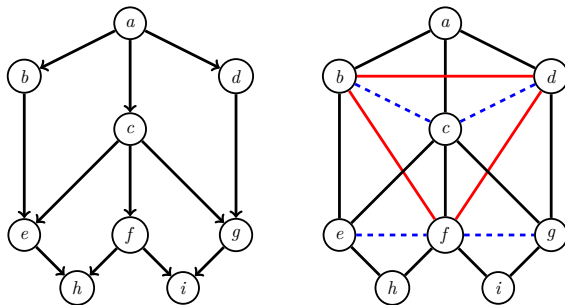
**Junction Tree** Form a junction tree from cliques of the triangulated graph, removing any unnecessary links in a loop on the clique graph. Algorithmically, this can be achieved by finding a tree with maximal spanning weight with weight  $w_{ij}$  given by the number of variables in the separator between cliques  $i$  and  $j$ .

**Potential Assignment** Assign potentials to junction tree cliques and set the separator potentials to unity.

**Message Propagation** Carry out absorption until updates have been passed along both directions of every link on the JT.

The clique marginals can then be read off from the JT.

## Example



Left: Original loopy Belief Network.

Right: The moralisation links (dashed) are between nodes  $e$  and  $f$  and between nodes  $f$  and  $g$ . The other additional links come from triangulation. The clique size of the resulting clique tree (not shown) is four.

See also [demoJTree.m](#) for an example with the famous 'chest clinic' network.

# Remarks

- For discrete variables, the computational complexity of the JTA is exponential in the largest clique size.
- There may exist more efficient algorithms in particular cases. One particular special case is that of marginal inference for a binary variable MRF on a two-dimensional lattice containing only pure quadratic interactions. In this case the complexity of computing a marginal inference is  $O(n^3)$  where  $n$  is the number of variables in the distribution. This is in contrast to the pessimistic exponential complexity suggested by the JTA.
- One might think that the only class of distributions for which essentially a linear time algorithm is available are singly-connected distributions. However, there are decomposable graphs for which the cliques have limited size meaning that inference is tractable. For example an extended version of the 'ladder' graph has a simple induced decomposable representation. These structures are hyper trees.
- By replacing summation with maximisation, we can perform max-absorption to compute the most likely joint state – this is the union of the most likely clique states.