

SIDDARTH BRAMARAMBIKA SHANKAR

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About Me

- Enthusiastic Robotics and Automation Engineer with a robust background in designing and implementing advanced mobile and articulated robotic systems, as well as industrial automated solutions. My expertise spans machine learning domains, including machine vision and multi-agent systems, alongside industrial specialties such as control systems, modeling, simulation, and optimization of physical systems.
- Experienced Quality Engineer in the electric vehicle manufacturing industry, having successfully led the company to achieve ISO 9001:2015 certification.

Work Experience

Wien Work, (TU Vienna)

Mar 2024 - Present

Master Thesis

Vienna, Austria

- Work is aimed at creating instructive assistive systems coupled with an Intuitive user interface for inclusive production systems and improving user experience.
- User interface: Developing an intuitive web-based application using Django and incorporating WCAG and considering usability heuristics.
- Assistive systems: Developing an assistive system with user-centric design considerations, and ethical and safety considerations to achieve a high-quality production environment with improved user satisfaction.

Starya Mobility Pvt. Ltd

September 2021 - Aug 2022

Quality Engineer

Bangalore, India

- ISO Certification: Successfully led the quality team to achieve ISO 9001:2015 certification through meticulous documentation and effective quality improvement strategies.
- Statistical Process Analysis: Implemented SPC, Regression Analysis, CAPA analysis Documentation formulation for 5 subsystems of Electrical Retrofit kits improving 30% Quality
- Product Procurement: Managed the procurement and maintenance of products and instruments, including measuring instruments and between-centers balancing machines, significantly enhancing company valuation.

Projects

Robot design and Machine Vision

September 2023 - February 2024

- Joint designing, product selection, path planning, kinematic and dynamic load analysis of ARM and legged mobile robot.
- Feature detection, Image Stitching, Visual Odometry, deep learning Image classification, Camera Calibration using OpenCV and Python Programming.

Haptic Interface and Human-Robot Interaction

September 2022 – December 2022

- Haptic device (3D Systems Touch X) interfacing with UR3e Cobot and Pybullet (Physics Robot Simulation package) using API and Parallelizing Python programs for Human-Robot Interaction
- Designed the experiment and evaluated the user experience of a robotic teleoperation system across varying task complexities.
- Designed and conducted a scientific study on user experience also using ROS and Unity.

Ergonomics Evaluation and Improvement

November 2023 - May 2023

 Analysed and made improvements to the ergonomics of a work process of fan haul assembly using RULA and EAWS ergonomic analysis methods. Further validated it using Ema-imk and Seimens Technomatix software.

Education - Master's Degree

European Institute of Technology - Manufacturing

Dual Masters Degree program - People and Robots of Sustainable Work

Sept 2022 - Present

 $Switzerland\ \ \ \ Austria$

Sept 2023 - Present

Vienna, Austria

Pursuing a dual degree master's program in Automation and Robotics Systems offered by the European Institute of Technology - Manufacturing. This program, conducted at two different universities, is designed to meet the evolving needs of the industry and workforce.

Exit University - Technical University of Vienna.

Entry University - University of Applied Sciences and Arts of Southern Switzerland.

Technical University of Vienna

Master of Science in Manufacturing and Robotics

- Assistance systems in Manufacturing
- Digital Simulations of Ergonomics and Robotics
- Machine vision
- Robot Challenge
- Cobot Studio
- Machine Vision

University of Applied Sciences and Arts of Southern Switzerland - SUPSI

Master of Science in Mechatronics and Automation - Grade: 5.07/6

- Integrated Automation
- Industrial Control
- Multi-agent systems
- Applied Statistics and Data Analysis
- Advanced Robotics
- Industrial Robotics
- Autonomous Planning and Acting for Robots
- Sept 2022 Sept 2023 Lugano, Switzerland
- Modeling, Simulation and optimisation

Education - Bachelor's Degree

BMS Institute of Technology

Bachelor of Engineering in Mechanical Engineering - CGPA: 8.21/10

- Control Engineering
- Applied electronics
- Artificial Intelligence (AI)
- Kinematics of Machines

Aug 2017 - Aug 2021

Bangalore, India

- Basics of Robotics
- Mechatronics
- Strength of Materials
- Design of Machines

Achievements

1st place, CirculoDev - Circular Economy, UCD Dublin

CircularDev Summer School - University College Dublin

Jul 2023 - Aug 2023

Dublin, Ireland

* Circular Thinking and Market Penetration Strategies for Digital Product Passport for Mondragon cooperation.

Top 10, Brain Computer Interaction

Neuro TechX global hackathon 2023

December 2023

Vienna, Austria

* Designed and conducted a study for the automatic detection of damaged products using Gtec's Unicorn BCI headset for secondary segregation using labeling and classification of EEG brain signals data sets.

Skills

- Robotics: ROS 1.0 / 2.0, Pybullet, Matlab, Robot design, Pytorch, OpenCV, Unity
- Programming: Python, MATLAB, MS Office, CNC programming, PLC programming, Arduino IDE.
- Process Simulation: Siemens Technomatix, EMA imk, Robo-DK
- Machine Vision: OpenCV, Visual Odometry, Deep Learning Classification.
- Industrial: PLC programming, Functional Safety, Risk Analysis, Lean Processes, Basics of PID.
- Languages: English (C1: Working Proficiency), German (B1: intermediate Proficiency), Hindi (C1: Working Proficiency), Kannada (Native).